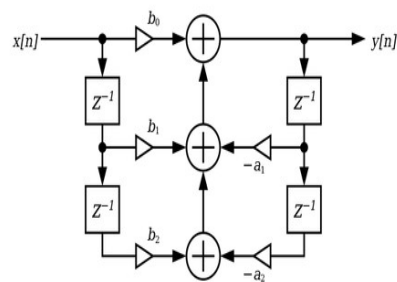


Goal: To determine the time domain response of the transfer function

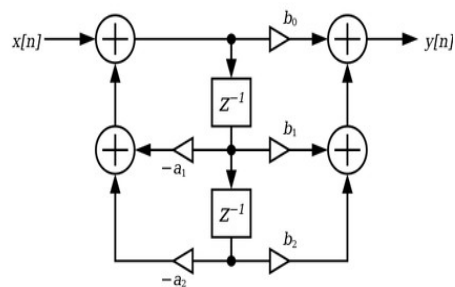
The [transfer function](#) for a linear, time-invariant, digital filter can be expressed as a transfer function in the [Z-domain](#); if it is causal, then it has the form:^[1]

$$H(z) = \frac{B(z)}{A(z)} = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2} + \dots + b_N z^{-N}}{1 + a_1 z^{-1} + a_2 z^{-2} + \dots + a_M z^{-M}}$$

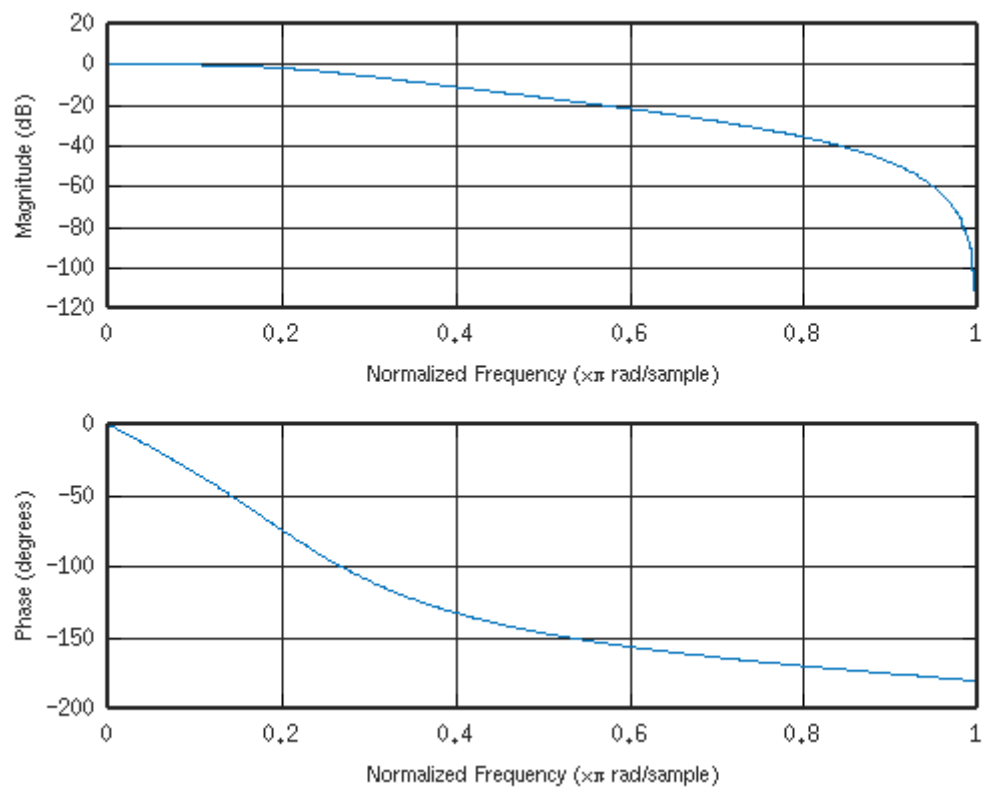
Direct Form 1



Direct Form II



Octave filter



-0.167980, -265.000

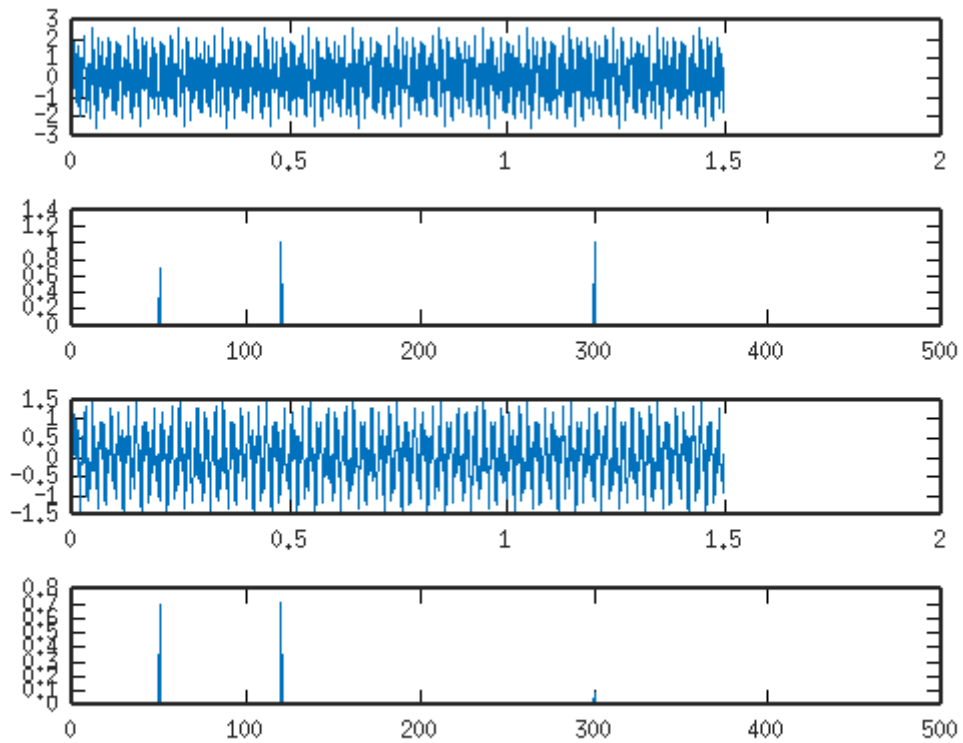
Testcase

The first signal x is 3 sine waves 50, 120, and 300 Hz

The 2nd is the FFT of the signal x .

The 3rd is the filterd with the Butterworth filter.

The 4th show that only the 50 & 120 Hz are present.



421.525, 4.77541

Starting first with order 2

a = 1.00000 -0.98241 0.34767

b = 0.091315 0.182630 0.091315

[A,B,C,D] = tf2ss(b,a);

A =

5.5511e-17 3.4767e-01
-1.0000e+00 9.8241e-01

B =

-0.059568
0.272338

C =

0 1

D = 0.091315

butt6120lp

normalize freq

nf = 0.24000

zeros

ans =

-1
-1
-1
-1
-1
-1

poles
ans =

0.61925 + 0.56170i
0.49120 + 0.32617i
0.43881 + 0.10665i
0.43881 - 0.10665i
0.49120 - 0.32617i
0.61925 - 0.56170i

theta =

0.73670
0.58617
0.23842
-0.23842
-0.58617
-0.73670

b
b =

Columns 1 through 6:

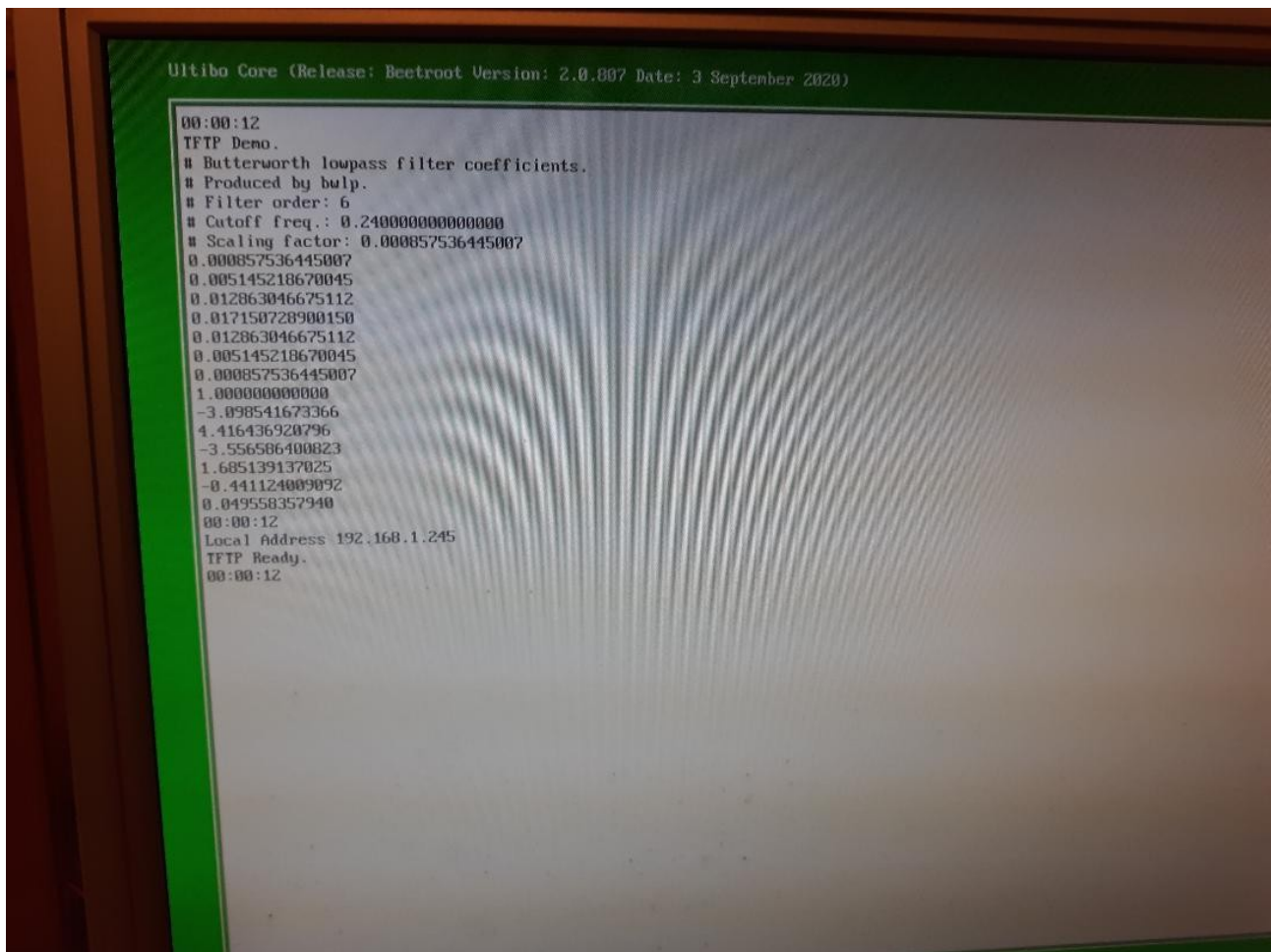
0.00085754 0.00514522 0.01286305 0.01715073 0.01286305 0.00514522

Column 7:

0.00085754

a
a =

1.000000 -3.098542 4.416437 -3.556586 1.685139 -0.441124 0.049558

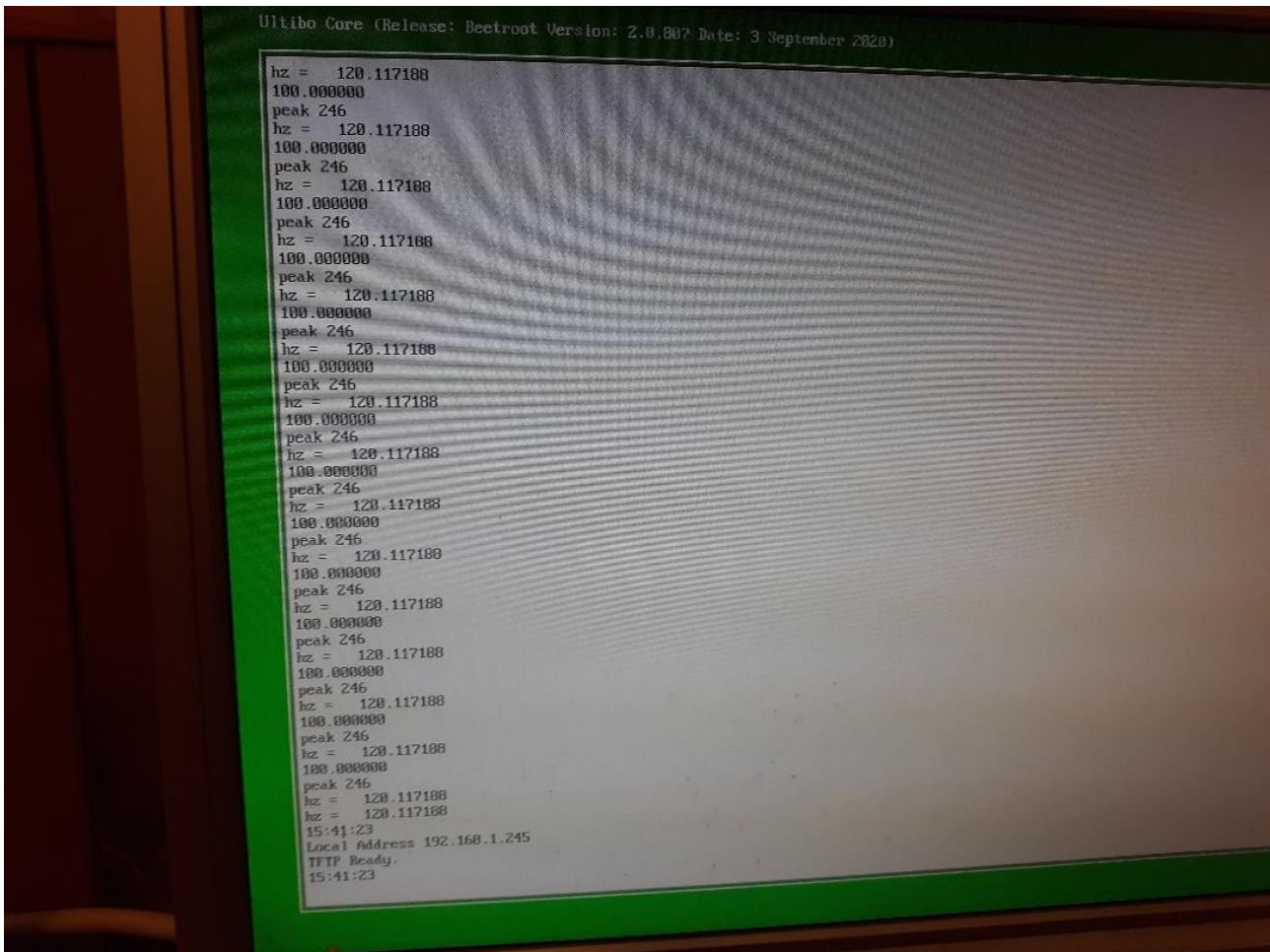


FFT 50 120 300

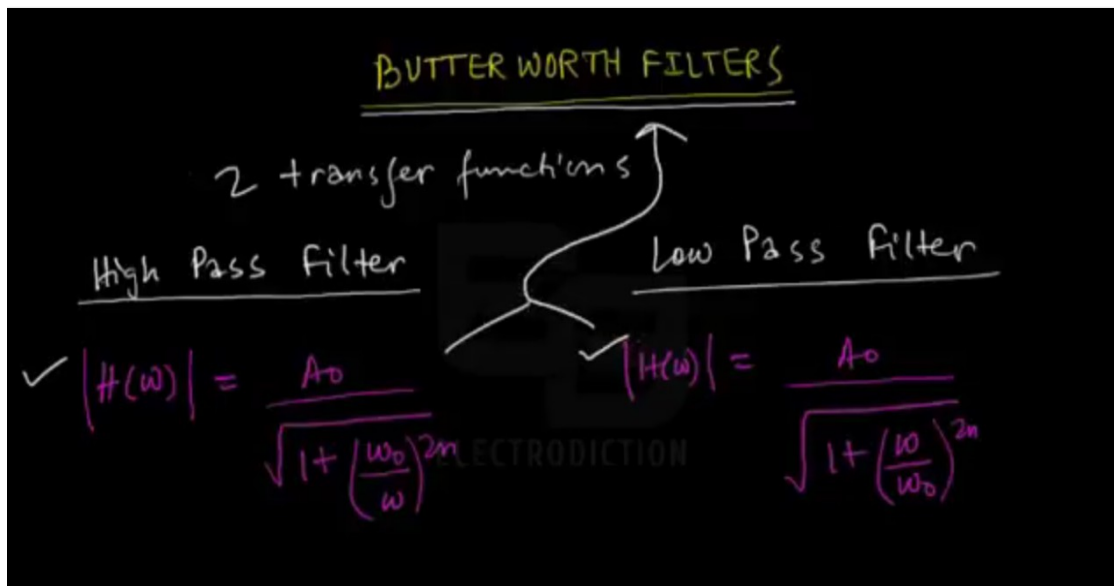
delta f 0.48828125 samples 2048 fs 1000

sample = 10*(sin(2*pi*50*t[i]) + sin(2*pi*120*t[i]) + sin(2*pi*300*t[i])); //no DC

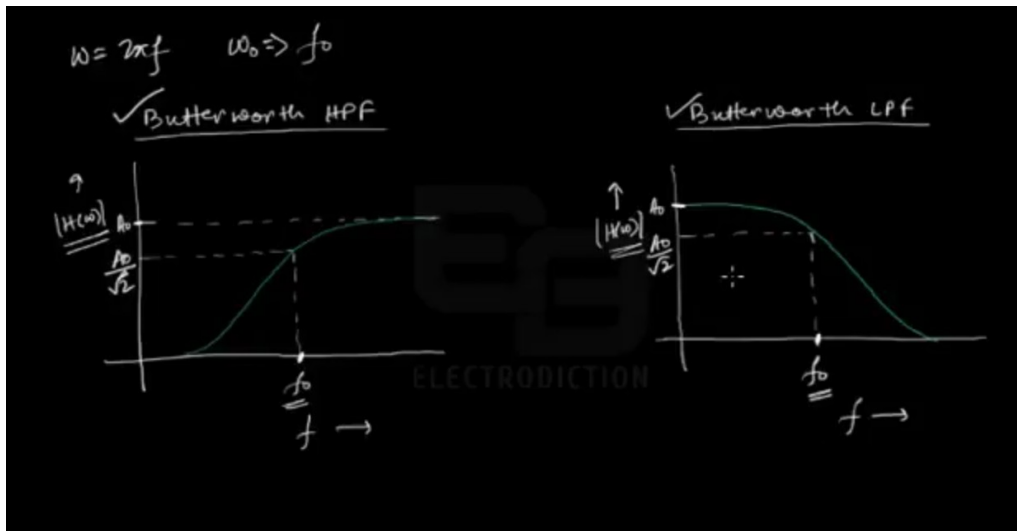
(2.104689,	0.000000)	102	49.8046875
(7.311564,	0.000000)	103	
(4.836622,	0.000000)	104	
(2.750056,	0.000000)	246	120.1171875
(8.715654,	0.000000)	247	
(1.689716,	0.000000)	248	
(2.071553,	0.000000)	614	299.8046875
(7.257226,	0.000000)	615	
(4.845451,	0.000000)	616	



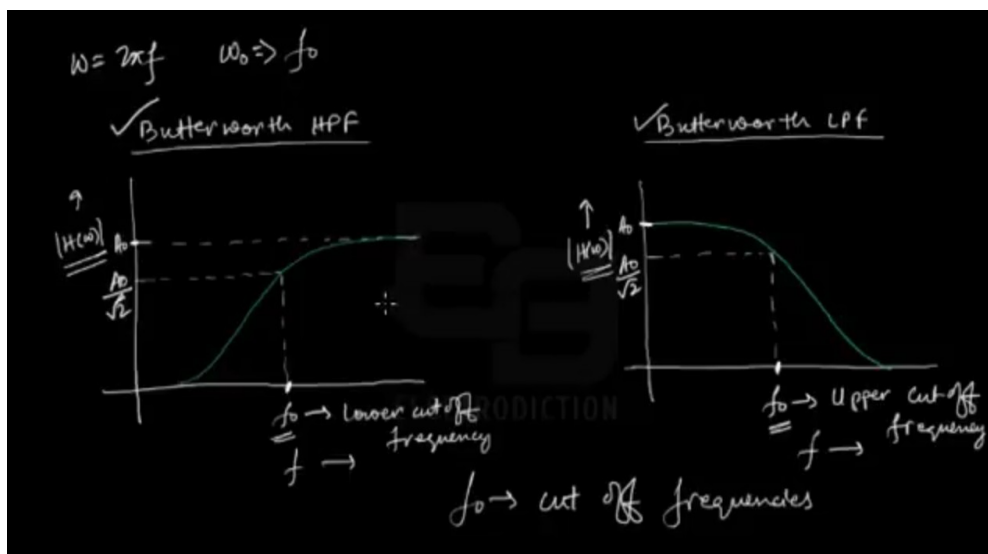
<https://www.youtube.com/watch?v=vikFFw6Hn0o>



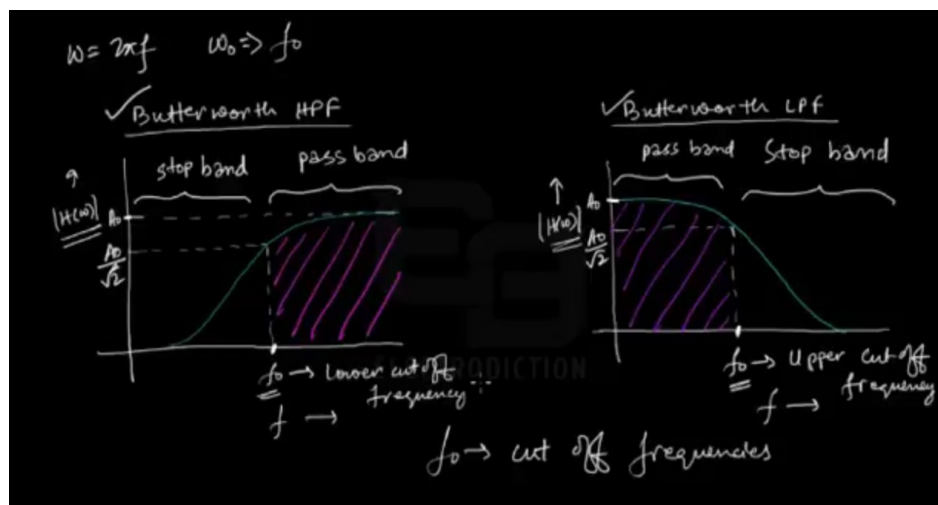
A_o Maximum gain in passbands
 $|H(w)|$ normalized gain $w = 2\pi f$ $w_o = f_o$
 w_o Lower cutoff angular frequency (HPF)
 upper cutoff angular frequency (LPF)
 angular frequency of input signal
 n order(interger 1,2,3...)



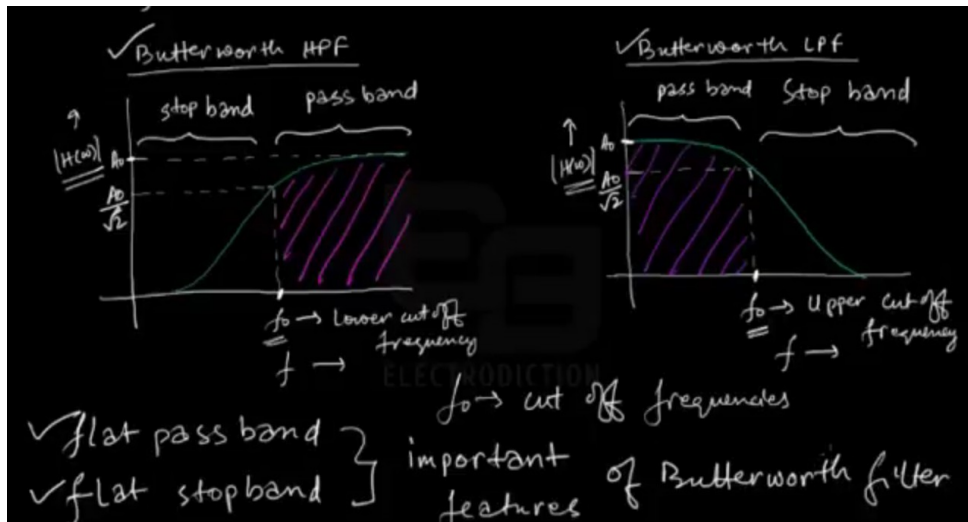
bw2.png



bw3.png



bw4.png



bw5.png

