

git clone https://github.com/raspberrypi/openocd.git --recursive --branch rp2040 --depth=1 cd openocd/

git log

commit 610f137d2b91b794dc9a8999b1e6631a99fcddc7 (grafted, HEAD -> rp2040, origin/rp2040, origin/HEAD)

Author: Rene Kita <git@rkta.de>

Date: Fri Mar 12 18:38:02 2021 +0100

build: remove warnings with gcc 11

This removes some warnings which prevent a successful build with -Werror which is enabled by default. I'm using gcc 11, so maybe others are not getting this warnings yet.

In src/flash/nor/numicro.c the debug messages were misleadingly indented. In src/target/arm920t.c the array size where smaller than expected from the receiving function.

Change-Id: I66f5c6a63beb9f9416e73b726299297476c884d8

Signed-off-by: Rene Kita <git@rkta.de>
Reviewed-on: http://openocd.zylin.com/6104

Reviewed-by: Jonathan McDowell <noodles-openocd@earth.li>

Tested-by: jenkins

Reviewed-by: Tomas Vanek <vanekt@fbl.cz>

ls -la ./bootstrap

ls ../

ls ../installed-openocd

mkdir ../installed-openocd

./configure --enable-sysfsgpio --enable-bcm2835gpio --prefix=/home/devel/installed-openocd/

make -j4 make install

sudo mksquashfs openocd openocd050322-610f137.img

sudo mksquashfs installed-openocd installed-openocd050322-610f137.img

openocd -v

Open On-Chip Debugger 0.11.0-g610f137-dirty (2022-05-03-08:59)

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For bug reports, read

http://openocd.org/doc/doxygen/bugs.html

The information for this document was found at "https://www.electronicshub.org/programming-raspberry-pi-pico-with-swd/"

Testing a new installation method using a prefix in the configure and creating a squashfs img that can install bin & share in "/home/devel/local/openocd". Using this method it can be installed on my other RPi4 without having to rebuild from source. A 2nd "openocd081421-71510a.img" is the source compiled to be installed at "/home/devel/local/openocd"

"export PATH=/home/devel/local/openocd/bin:\$PATH"

The build was done on PI400 and the with the **"installed-openocd081421-71510a.img"** it was installed on a RPi4B 4Gb.

sudo apt install gdb-multiarch

dpkg -l | grep gdb-multiarch

gdb-multiarch 8.2.1-2

armhf GNU Debugger (with

support for multiple architectures)

git clone https://github.com/raspberrypi/openocd.git --recursive --branch rp2040 --depth=1

commit 71510a77a61c6eb2b1266e00010f8f258785a54b (grafted, HEAD -> rp2040, origin/rp2040, origin/HEAD)

Author: Peter Lawrence <12226419+majbthrd@users.noreply.github.com>

Date: Thu Jun 3 14:06:09 2021 -0500

tcl/boards: add pico-debug.cfg

cd openocd/

./bootstrap

- + aclocal --warnings=all
- + libtoolize --automake --copy
- + autoconf --warnings=all
- + autoheader --warnings=all
- + automake --warnings=all --gnu --add-missing --copy

configure.ac:26: installing './compile'

configure.ac:37: installing './config.guess'

configure.ac:37: installing './config.sub'

configure.ac:16: installing './install-sh'

configure.ac:16: installing './missing'

Makefile.am:46: warning: wildcard \$(srcdir: non-POSIX variable name

Makefile.am:46: (probably a GNU make extension)

Makefile.am: installing './INSTALL'

Makefile.am: installing './depcomp'

Makefile.am:23: installing './mdate-sh'

Makefile.am:23: installing './texinfo.tex'

Setting up submodules

Generating build system...

libtoolize: putting auxiliary files in AC_CONFIG_AUX_DIR, 'build-aux'.

libtoolize: copying file 'build-aux/config.guess' libtoolize: copying file 'build-aux/config.sub' libtoolize: copying file 'build-aux/install-sh' libtoolize: copying file 'build-aux/ltmain.sh'

libtoolize: putting macros in AC_CONFIG_MACRO_DIRS, 'm4'.

libtoolize: copying file 'm4/libtool.m4' libtoolize: copying file 'm4/ltoptions.m4' libtoolize: copying file 'm4/ltsugar.m4' libtoolize: copying file 'm4/ltversion.m4' libtoolize: copying file 'm4/ltversion.m4' configure.ac:43: installing 'build-aux/ar-lib' configure.ac:37: installing 'build-aux/compile' configure.ac:30: installing 'build-aux/missing'

libjaylink/Makefile.am: installing 'build-aux/depcomp'

Bootstrap complete. Quick build instructions:

Use the –help to see what the options provide.

./configure --help

--enable-sysfsgpio Enable building support for programming driven via sysfs gpios.

--enable-bcm2835gpio Enable building support for bitbanging on BCM2835

The folder where

sudo mkdir /media/devel/03ba8473-3445-4a49-8e7b-1876b5d543d2/installed-openocd

./configure --enable-sysfsgpio --enable-bcm2835gpio --prefix=/media/devel/03ba8473-3445-4a49-8e7b-1876b5d543d2/installed-openocd

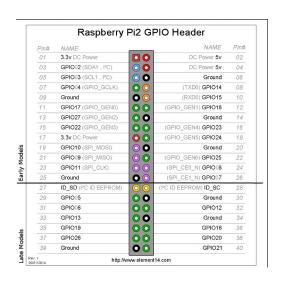
make -j4

sudo make install

top

swclk grd swdio x x x X

GPIO24 pin 18 swdio GRD pin 20 GRD GPI025 pin 22 swclk



~/local/openocd/bin/openocd --version

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local/openocd/bin/openocd: invalid option -- 'e'

local/openocd/bin/openocd --help

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Open On-Chip Debugger

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--help | -h display this help

--version | -vdisplay OpenOCD version

--file | -f use configuration file <name>

--search | -s dir to search for config files and scripts

--debug | -dset debug level to 3

| -d<n> set debug level to <level>

--log_output | -l redirect log output to file <name>

--command | -c run <command>

cd /opt/pico-examples/build/

sudo ~/local/openocd/bin/openocd -f interface/raspberrypi-swd.cfg -f target/rp2040.cfg -c "program blink/blink.elf verify reset exit" [sudo] password for devel:

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adapter speed: 1000 kHz

Info: Hardware thread awareness created Info: Hardware thread awareness created Info: RP2040 Flash Bank Command

Info: BCM2835 GPIO JTAG/SWD bitbang driver

Info: clock speed 1001 kHz

Info: Read incorrect DLIPDR 00000000 (possibly CTRL/STAT value) when selecting coreid 0

Info: DAP init failed in procedure 'program' ** OpenOCD init failed ** shutdown command invoked

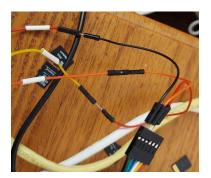
Info: Read incorrect DLIPDR 00000000 (possibly CTRL/STAT value) when selecting coreid 0

Wiring Raspberry Pi and Raspberry Pi Pico

On RPi4B 4Gb red GPIO24 pin 18 black jumper black swdio orange GRD pin 20 orange jumper green GRD yellow GPI025 pin 22 red jumper blue swclk



red GPIO24 pin 18 red SWDIO black jumper black orange GRD pin 20 orange GRD orange jumper green yellow GPI025 pin 22 yellow SWCLK red jumper blue





RPi4B 4Gb Pico Pi GPIO24 pin 18 SWDIO black GRD pin 20 GRD green GPI025 pin 22 **SWCLK** blue



Testing the OpenOCD

cd /opt/pico-examples/build sudo su [sudo] password for devel:

export PATH=/home/devel/local/openocd/bin:\$PATH echo \$PATH which openocd /home/devel/local/openocd/bin/openocd

Now the blink progran is loaded with the need to remove the usb cable and hold the boot sel button pico.

root@mypi3-20:/opt/pico-examples/build# openocd -f interface/raspberrypi-swd.cfg -f target/rp2040.cfg -c "program blink/blink.elf verify reset exit" Open On-Chip Debugger 0.10.0+dev-g71510a7-dirty (2021-08-15-17:08) Licensed under GNU GPL v2

For bug reports, read

http://openocd.org/doc/doxygen/bugs.html

adapter speed: 1000 kHz

Info: Hardware thread awareness created Info: Hardware thread awareness created Info: RP2040 Flash Bank Command

Info: BCM2835 GPIO JTAG/SWD bitbang driver

Info: clock speed 1001 kHz Info: SWD DPIDR 0x0bc12477 Info: SWD DLPIDR 0x00000001 Info: SWD DPIDR 0x0bc12477 Info: SWD DLPIDR 0x10000001

Info: rp2040.core0: hardware has 4 breakpoints, 2 watchpoints Info: rp2040.core1: hardware has 4 breakpoints, 2 watchpoints

Info: starting gdb server for rp2040.core0 on 3333 Info: Listening on port 3333 for gdb connections target halted due to debug-request, current mode: Thread xPSR: 0xf1000000 pc: 0x000000ee msp: 0x20041f00

target halted due to debug-request, current mode: Thread

xPSR: 0xf1000000 pc: 0x000000ee msp: 0x20041f00

** Programming Started **

Info: RP2040 B0 Flash Probe: 2097152 bytes @10000000, in 512 sectors

target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 Info: Writing 12288 bytes starting at 0x0 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 ** Programming Finished ** ** Verify Started ** target halted due to debug-request, current mode: Thread

xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00

** Verified OK **

** Resetting Target ** shutdown command invoked

Now the hellow usb is loaded.

openocd -f interface/raspberrypi-swd.cfg -f target/rp2040.cfg -c "program hello world/usb/hello usb.elf verify reset exit"

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For bug reports, read

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adapter speed: 1000 kHz

Info: Hardware thread awareness created Info: Hardware thread awareness created Info: RP2040 Flash Bank Command

Info: BCM2835 GPIO JTAG/SWD bitbang driver

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Info: rp2040.core0: hardware has 4 breakpoints, 2 watchpoints Info: rp2040.core1: hardware has 4 breakpoints, 2 watchpoints

Info: starting gdb server for rp2040.core0 on 3333 Info: Listening on port 3333 for gdb connections

target halted due to debug-request, current mode: Thread xPSR: 0xf1000000 pc: 0x000000ee msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0xf1000000 pc: 0x000000ee msp: 0x20041f00

** Programming Started **

Info: RP2040 B0 Flash Probe: 2097152 bytes @10000000, in 512 sectors

target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 Info: Writing 24576 bytes starting at 0x0 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 target halted due to debug-request, current mode: Thread xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00 ** Programming Finished ** ** Verify Started ** target halted due to debug-request, current mode: Thread

```
xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00
target halted due to debug-request, current mode: Thread
xPSR: 0x01000000 pc: 0x00000178 msp: 0x20041f00
** Verified OK **
** Resetting Target **
shutdown command invoked
cd /opt/pico-examples/
rm -rf build
mkdir build
cd build
cmake -DCMAKE_BUILD_TYPE=Debug ..
cd hello world/serial/
make -j4
ls -la
total 1028
drwxr-xr-x 3 devel devel 4096 Aug 17 05:47.
drwxr-xr-x 5 devel devel 4096 Aug 17 05:43 ..
drwxr-xr-x 3 devel devel 4096 Aug 17 05:44 CMakeFiles
-rw-r--r-- 1 devel devel 992 Aug 17 05:43 cmake_install.cmake
-rwxr-xr-x 1 devel devel 21496 Aug 17 05:47 hello_serial.bin
-rw-r--r-- 1 devel devel 348298 Aug 17 05:47 hello_serial.dis
-rwxr-xr-x 1 devel devel 360616 Aug 17 05:47 hello serial.elf
-rw-r--r-- 1 devel devel 215933 Aug 17 05:47 hello_serial.elf.map
-rw-r--r-- 1 devel devel 60515 Aug 17 05:47 hello_serial.hex
-rw-r--r-- 1 devel devel 43008 Aug 17 05:47 hello_serial.uf2
```

-rw-r--r-- 1 devel devel 72357 Aug 17 05:43 Makefile