

# Tax avoidance and evasion in a dynamic setting

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# Intro

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- Tax avoidance and evasion alter effective tax rates
- Tax systems differentiate between (legal) avoidance and (illegal) evasion but they both reduce revenues collected
- Evasion leads to sizeable revenue losses: 20% of GDP in Europe (Murphy 2019) (13% in Italy, Albarea et al. 2020) under-reporting is  $\approx$  18% in US with a tax gap of 500 billion
- Avoidance also significant: 4% of GDP in Europe (EPRS, 2015), latest IRS and Treasury claim figures up to 500 billion
- We develop a model to study the optimal evasion and avoidance decision in an inter-temporal setting

- Contributions in a static framework (joint avoidance/evasion):
  - Cross and Shaw (1981; 1982) point out importance of joint analysis of avoidance-evasion
  - Alm (1988) and Alm and McCallin (1990) study the case of risk-less and risky avoidance
  - Cowell (1990) investigates distributional impacts
  - Neck (1990) studies interactions with labour supply
  - Gamannossi and Rablen (2016;2017) explore the cases of bounded rationality and optimal enforcement
- Contributions in a dynamic framework (only evasion):
  - Wen-Zhung and Yang (2001) and Dzhumashev and Gahramanov (2011) first models considering just evasion
  - Levaggi and Menoncin (2012; 2013) identify determinants of Yitzhaki puzzle
  - Bernasconi et al. (2015; 2019) study roles of uncertainty and habit

- Characterize optimal avoidance and evasion
- Analyze how deterrence instruments affect compliance and revenues
- Characterize optimal fiscal parameters for the government under various objectives
  - minimizing evasion
  - minimizing non-compliance
  - maximizing revenues
  - maximizing growth

# Model

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# Modelling features and assumptions

Avoidance and evasion differ in their level of sophistication

- **Evasion is cost-less** and carries a fine  $\eta$  if detected
- **Avoidance costs**  $f(a)$  but entails a reduced fine  $\eta(1 - \beta)$  if detected
  - $f(a)$  increasing, convex and  $f(0) = 0$
  - We call the fine reduction  $\beta$  the **avoidance premium**

Both  $f$  and  $\beta$  depend on the fiscal and tax administration specifics

- High avoidance cost and low avoidance premium when:
  - Tax code is simpler and less-ambiguous
  - Legal/investigatory resources of tax authorities are higher
  - Courts have higher effectiveness

Avoidance and evasion are **both correctly detected** upon audit

The agent suffers from **fiscal illusion**

- The effect of compliance on revenues is overlooked



# Consumer's preferences

The agent's utility increases in the consumption of a **privately produced** good  $c_t$  and a **publicly produced** good  $g_t$

The agent utility function is:

$$U = \frac{(c_t - c_m)^{1-\delta}}{1-\delta} + v(g_t)$$

- $c_m$  is a minimum consumption level
- $\delta$  drives concavity of utility from  $c_t$
- $v(\bullet)$  is an increasing and concave function

Absolute risk-aversion  $\frac{\delta}{c_t - c_m}$

- Lower risk aversion when  $c_t$  is higher (DARA)
- Higher risk aversion when either  $\delta$  or  $c_m$  is higher

# Capital Accumulation

The capital accumulated  $dk_t$  is equal to production minus expenses:

$$dk_t = [y_t - c_t - \tau y_t (1 - e_t - a_t) - f(a_t) y_t] dt - \eta \tau y_t [e_t + (1 - \beta) a_t] d\Pi_t$$

Production,  $y_t$

- Deterministic function  $y_t = Ak_t$ ,  $0 < A < 1$  TFP

Expenses:

- Consumption,  $c_t$
- Linear taxes on declared income  $\tau y_t (1 - e_t - a_t)$ 
  - Share of income avoided  $a_t$  and evaded  $e_t$
- Avoidance costs  $f(a_t)$
- Fine costs
  - Fine in case of detection is  $\eta \tau y_t [e_t + (1 - \beta) a_t]$
  - Audits follow a Poisson jump process  $d\Pi_t$  with frequency  $\lambda$

# The optimization problem

$$\max_{\{c_t, e_t, a_t\}_{t \in [t_0, \infty[}} \mathbb{E}_{t_0} \left[ \int_{t_0}^{\infty} \frac{(c_t - c_m)^{1-\delta}}{1-\delta} e^{-\rho(t-t_0)} dt \right]$$

under the capital dynamics:

$$dk_t = [y_t - c_t - \tau y_t (1 - e_t - a_t) - f(a_t) y_t] dt - \\ \eta \tau y_t [e_t + (1 - \beta) a_t] d\Pi_t$$

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# Analysis

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# Optimal solution

$$a^* = (f')^{-1} \tau \beta,$$

$$e_t^* = \frac{k_t - H}{\tau \eta A k_t} \left[ 1 - (\lambda \eta)^{\frac{1}{\delta}} \right] - (1 - \beta) a^*,$$

$$c_t^* = c_m + (k_t - H) \left( \frac{\rho + \lambda}{\delta} + \frac{\delta - 1}{\delta} \left\{ \frac{1}{\eta} + A [(1 - \tau) + \tau \beta a^* - f(a^*)] \right\} - \frac{1}{\eta} (\lambda \eta)^{\frac{1}{\delta}} \right)$$

Where:

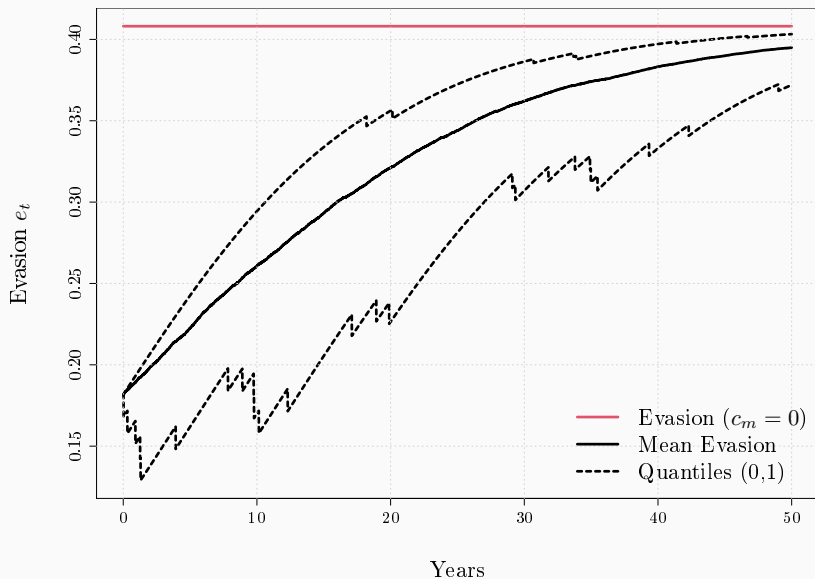
$$(f')^{-1}$$

Inverse of the marginal cost of avoidance

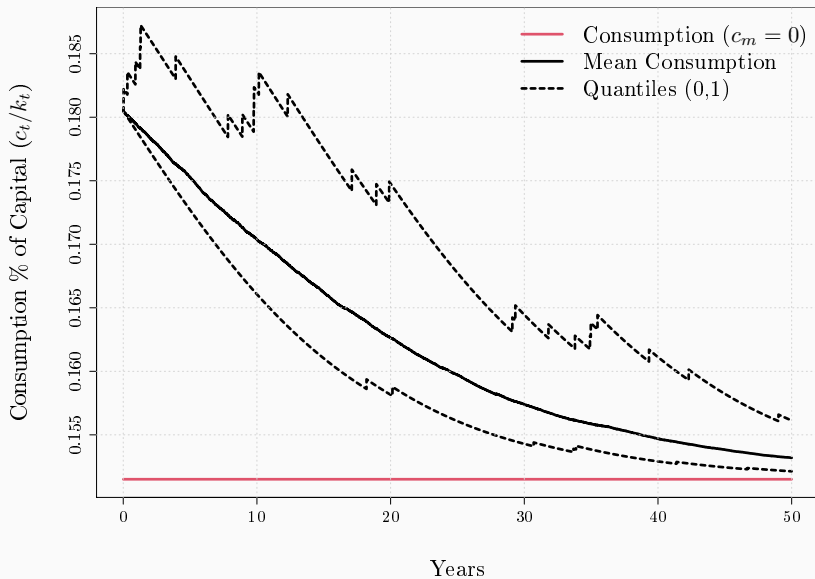
$$H := \frac{c_m}{A[\tau \beta a^* - f(a^*) + (1 - \tau)]}$$

PDV of future  $c_m$  discounted by  
TFP corrected by tax and avoidance

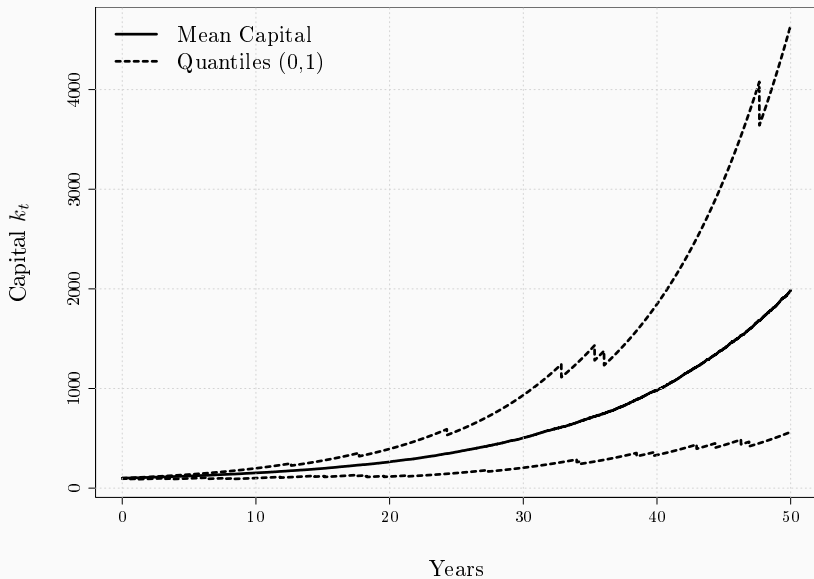
# Evasion dynamics



# Consumption dynamics



# Capital dynamics





# Comparative Statics

|           | $a^*$ | $e_t^*$ | $E_t^* = a^* + e_t^*$ | $\mathbb{E}[dT_t]$ |
|-----------|-------|---------|-----------------------|--------------------|
| $\lambda$ | 0     | —       | —                     | +                  |
| $\eta$    | 0     | —       | —                     | +                  |
| $\beta$   | +     | +/-     | +                     | —                  |
| $\tau$    | +     | —       | +/-                   | +/-                |

$\frac{\partial \text{Col}}{\partial \text{Row}}$  Derivatives of column with respect to row

Where:

$$\mathbb{E}[dT_t] = \tau y_t (1 - e_t^* - a_t^*) dt + \lambda \eta \tau y_t [e_t^* + (1 - \beta) a_t^*] dt$$

are expected revenues collected:

- Revenues from declaration
- Expected revenues from enforcement

# Comparative Statics - Remarks on $\beta$

The sign of  $\frac{\partial e_t^*}{\partial \beta}$  is complex to study when  $c_m > 0$

The case  $c_m = 0$  offers some insights:

$$\frac{\partial e_t^*}{\partial \beta} \begin{matrix} \geq \\ \leq \end{matrix} 0 \iff \frac{\partial a^*}{\partial \beta} \frac{1}{a^*} \begin{matrix} \leq \\ \geq \end{matrix} \frac{1}{1 - \beta}.$$

- The sign of the derivative depends on the semi-elasticity  $\frac{\partial a^*}{\partial \beta} \frac{1}{a^*}$ 
  - If the semi-elasticity is higher than a threshold,  $e$  is decreasing in  $\beta$
- The semi-elasticity is higher when  $\beta$  is bigger

**Avoidance deterrence increases evasion in economies with higher avoidance premium**

- When  $c_m > 0$  the increase in evasion is more likely than if  $c_m = 0$

Also for the sign of  $\frac{1}{dt} \frac{\partial \mathbb{E}_t[dT_t]}{\partial \tau}$  assuming  $c_m = 0$  provides some insights:

$$\frac{1}{dt} \frac{\partial \mathbb{E}_t[dT_t]}{\partial \tau} \gtrless 0 \iff \tau \lesseqgtr \frac{1 - \beta a_t^*}{\beta \frac{\partial a_t^*}{\partial \tau}}.$$

## Tax revenues display a Laffer curve behaviour

- When  $\tau$  is low, raising  $\tau$  increases revenues
- When  $\tau$  is high, raising  $\tau$  decreases revenues
- The higher the  $\beta$ , the lower the revenue-maximizing tax rate

An increase of  $\tau$  has three impacts on revenues:

1. **Positive** - Marginal tax increase
2. **Positive** - Reduction of evasion
3. **Negative** - Increase in avoidance

## Conclusion

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# Tax avoidance deterrence

Fines and audits are ineffective against tax avoidance  $\Rightarrow$  focus on  $f, \beta, \tau$

## Avoidance costs $f$

- Increasing both  $f'$  and  $f$  lowers avoidance and evasion
- Two components of avoidance costs:
  - **Knowledge costs:** Effort/Expertise to identify the “loophole” to exploit
  - **Set-up costs:** To meet law requirements (e.g., creation of legal entities)
    - Cannot be told apart from those of “intended” economic activities

Avoidance deterrence need to focus on knowledge costs alone

Measures to deter avoidance through  $\beta$  and  $f$

- Simplifying the tax system
  - Reducing the extent of variation of tax treatments
    - deductions, exemptions and preferential treatments
- Increasing the litigation budget of the tax administration
- Implementing anti-avoidance reforms at (multi)national level

# Tax avoidance deterrence

Avoidance deterrence might increase evasion:

1. **Avoidance premium:**

- Decreasing a low  $\beta$  reduces both avoidance and evasion
- Decreasing a high  $\beta$  entails an increase of evasion
- Evasion increase is more likely when  $c_m > 0$

2. **Tax rate:**

Decreasing  $\tau$  reduces avoidance but the increasing effect on evasion eventually lowers compliance and revenues

Negative effects can be sterilized using audit probability or fines

$$a^* = (f')^{-1} \tau \beta,$$

$$e_t^* = \frac{k_t - H}{\tau \eta A k_t} \left[ 1 - (\lambda \eta)^{\frac{1}{\delta}} \right] - (1 - \beta) a^*.$$

# Concluding Remarks

We develop the first dynamic model with joint avoidance/evasion

Interaction of avoidance and evasion is of crucial importance:

- Lead to the emergence of a Laffer curve
- Provide a possible interpretation for the Yitzhaki puzzle

Avoidance deterrence requires specific policies:

- Reduction of  $\beta$  or increase of  $f$ 
  - Long-run: Fiscal/judiciary reforms
  - Short-run: Increase of tax administration resources (legal)
    - Recent investments in data collection/analytics likely effective on evasion
    - Reduction of evasion might bolster avoidance
    - Need to balance deterrence activities
- Reduction of  $\tau$

Avoidance deterrence might entail unintended consequences

Thank you!

Questions?