Theory Assignment 2

CSE222: Algorithm Design & Analysis

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Problem-1

The police department in the city of Computopia has made all the streets one-way.

- (a) The mayor of the city claims that it is possible to legally drive from an intersection to any other intersection. Formulate this problem as a graph theoretic problem and explain why it can be solved in linear time.
- (b) Suppose the mayor's claim was found to be wrong. She has now made a weaker claim: "If you start driving from the town-hall, navigating one-way streets, then no matter where you reach, there is always a way to drive legally back to the town-hall." Formulate this weaker property as a graph theoretic problem and explain how it can be solved in linear time.

Input

A directed graph $G = (V, E)^*$ representing the layout of the city. V is the set of all intersections and E is the set of all one-way streets in Computopia.

Note: Formulation of the problem as a graph theoretic problem is given in the subsequent subsection.

Output

- (a) A boolean value *True* if the mayor's claim is true, else *False*.
- (b) A boolean value True the mayor's weaker claim is true, else False.

Solution

- (a) Check if G is strongly connected in linear time using Kosaraju's algorithm.
- (b) Check the townhall is a part of a strongly connected component in G.

Problem-2

Assume that n is the number of vertices in a graph. Then, given an edge-weighted connected undirected graph G = (V, E) with n + 20 edges, design an algorithm that runs in O(n) time and outputs an edge with the smallest weight, connected in a cycle of G. You must give a justification why your algorithm works correctly.

Input

An edge-weighted connected undirected graph G = (V, E) such that |V| = n and |E| = n + 20.

Output

An edge (u, v) with the smallest weight, connected in a cycle of G.

Solution

Terminologies and Definitions

Definition 1 (Cut-Edge) An edge $(u, v) \in E$ is a cut-edge iff removing it from the graph G = (V, E) disconnects G.

The complete Algorithm

- 1. Maintain a hash table $C[(u,v) \in E] \leftarrow 0$ to mark the cut-edges.
- 2. Find all the cut-edges in G, which takes O(|V| + |E|) time.
- 3. While finding the cut-edges, mark the edges that are cut-edges as 1 in C.
- 4. Find the edge with the smallest weight in E such that $C[e] \neq 1$.

Problem3

Suppose that G is a directed acyclic graph with the following features:

- G has a single source s and several sinks t_1, t_2, \ldots, t_k .
- Each edge $(v \to w)$ (i.e. an edge directed from v to w) has an associated weight $P[v \to w]$ between 0 and 1.
- For each non-sink vertex v, the total weight of all the edges leaving v is 1, i.e.

$$\sum_{(v \to w) \in E} P[v \to w] = 1 \tag{1}$$

The weights $P[v \to w]$ define a random walk in G from s to some sink t_i . After reaching any non-sink vertex v, the walk follows the edge $(v \to w)$ with probability $P[v \to w]$. All the probabilities are mutually independent.

Describe and analyze an algorithm to compute the probability that this random walk reaches sink $t_i \forall i \in \{1, 2, ..., k\}$.

Input

A weighted directed acyclic graph G = (V, E) having the above properties.

Output

A sequence of probabilities $P[t_1], P[t_2], \ldots, P[t_k]$, where $P[t_i]$ is the probability that the random walk reaches sink $t_i \, \forall i \in \{1, 2, \ldots, k\}$.

Solution

The given problem can be efficiently solved by applying dynamic programming on the topologically sorted graph G. It allows for the calculation of the probability of reaching every edge $v \in V$ starting from s.

Notations Used

Notation 1 ($P[v \to w]$) The weight of the edge $(v \to w) \in E$. This is also the probability of following the edge $(v \to w)$ for the random walk from v.

Notation 2 (P[v]) The total probability of reaching vertex v from the source s. It also denotes the entry for vertex v in the dynamic programming table.

Preprocessing

We first obtain a total ordering of the given graph G by topologically sorting it. This can be done using the TOPOLOGICAL-SORT(G) routine covered in class. The sorting step can be achieved in $\Theta(|V| + |E|)$ time.

Reason for Sorting:

When G is sorted in the aforementioned fashion, then the vertices are ordered such that v appears before w if $(v \to w) \in E$. This allows us to calculate P[w] by using the probabilities $P[v] \forall (v \to w) \in E$. This is possible because of equation (1) and the fact that the probabilities are mutually independent.

Decomposition into Sub-Problems

The given problem of finding $P[t_i] \ \forall \ 1 \leq i \leq k$ is broken down into overlapping subproblems of the form P[v], where v is not a sink. For each problem P[v], we intend to find the probability of reaching v from s.

Each probability P[v] can be found by adding the probabilities of reaching v from all vertices having an edge directed to v. The existence of $P[u] \forall (u \to v) \in E$ is guaranteed by the topological ordering.

Hence, this decomposition of the given problem into smaller sub-problems guarantees substructure optimality. This is because at any step, we can find the optimal solution using the optimzal solutions obtained in the previous steps.

Recurrence Relation

Let P[v] be the total probability of reaching any vertex v from the source s. Then, the following recurrence relation can be defined:

$$P[v] = \begin{cases} 1 & \text{if } v = s \\ \sum_{(u \to v) \in E} P[u] \times P[u \to v] & \text{otherwise} \end{cases}$$
 (2)

Using the above recurrence relation, we can find $P[v] \forall v \in V$ and maintain it in a $|V| \times 1$ dynamic programming table.

Base Case and Solvable Sub-Problems

The base case for the above recurrence relation is P[s] = 1. This is because the probability of reaching s from the source is 1, as the random walk starts from s.

The sub-problems that solve the original problem are $P[t_i] \ \forall \ 1 \leq i \leq k$, the probabilities of reaching the sinks t_i from s.

The complete Algorithm and Pseudocode

The complete algorithm consists of the following steps:

- 1. Topologically sort the graph G to get a total ordering of V.
- 2. Initialize the dynamic programming table P following the base case.
- 3. Iterate over the vertices in their topological order and tabulate P using the above recurrence relation.
- 4. Return $P[t_1], P[t_2], \ldots, P[t_k]$, the total probabilities of reaching the sinks from s.

The pseudocode for the complete algorithm is given in Algorithm (1). ¹

Algorithm 1 An algorithm to find the probabilities of reaching the sinks from s.

```
1: procedure Sink-probability (G = (V, E)):
        V_T = \text{Topological-sort}(G)
 2:
        P[v \in V_T] \leftarrow 0
 3:
        P[s] \leftarrow 1
 4:
        for v \in V_T do
 5:
            for (u \to v) \in E do
 6:
                P[v] \leftarrow P[v] + P[u] \times P[u \rightarrow v]
 7:
            end for
 8:
        end for
 9:
        return P[t_1], P[t_2], ..., P[t_k]
10:
11: end procedure
```

Runtime Analysis of the Algorithm

The following operations are performed in the algorithm:

- 1. TOPOLOGICAL-SORT(G): This step takes $\Theta(|V| + |E|)$ time.
- 2. Initialization of the dynamic programming table P, which takes $\Theta(|V|)$ time.
- 3. The dynamic programming step takes $\Theta(|V| + |E|)$ time, as it iterates over all vertices, while accessing the edges incident on each vertex. Analogous to a BFS traversal, the total number of iterations of the outer loop is |V| and the inner loop is |E|.

Dominated by the sorting step and the dynamic programming step, the time complexity of the algorithm is $\Theta(|V| + |E|)$.

¹The pseudocode of the algorithm makes use of notations introduced in the section **Notations** Used. Here, $P[v \in V_T]$ denotes a $|V_T| \times 1$ table ordered in the same way as V_T .

Bibliography

- 1. OpenGenius IQ: How to find cut-edges in a Graph
- 2. USCB Math173A: (Lemma 1) Cut-edges are not contained in cycles