

# PocketBeagle Walk Through



# PocketBeagle walk-through

Friendly to novices and experts alike, the Beagle experience tracks mainline u-boot, Linux and Debian development, while augmenting it to enable development to start as quickly as possible. Attendees will get started interacting with the hardware via the command-line, shell scripts,

Python and JavaScript. Attendees will be walked through the configuration details for the boot configuration, pin multiplexing, USB networking and other helper scripts they should get to know. Support and development processes within the BeagleBoard.org community will be covered. Exercises will pave the way for the other workshops to dive into their topic without needing to backtrack excessively on PocketBeagle-specific details.

# Author and license

- Author
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Co-founder BeagleBoard.org, Texas Instruments Sitara apps  
<https://beagleboard.org/about>
- License
  - Creative Commons Attribution – Share Alike 4.0  
<https://creativecommons.org/licenses/by-sa/4.0/>

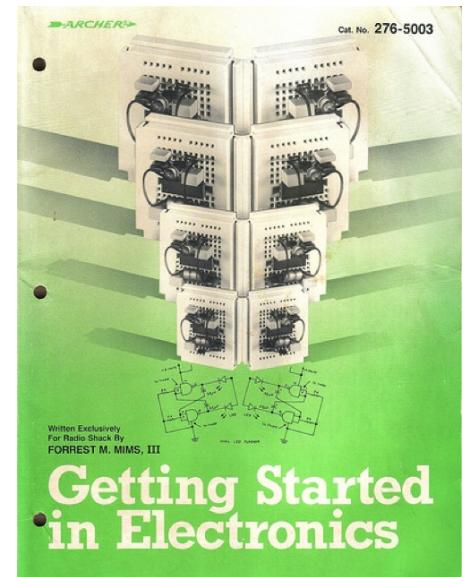
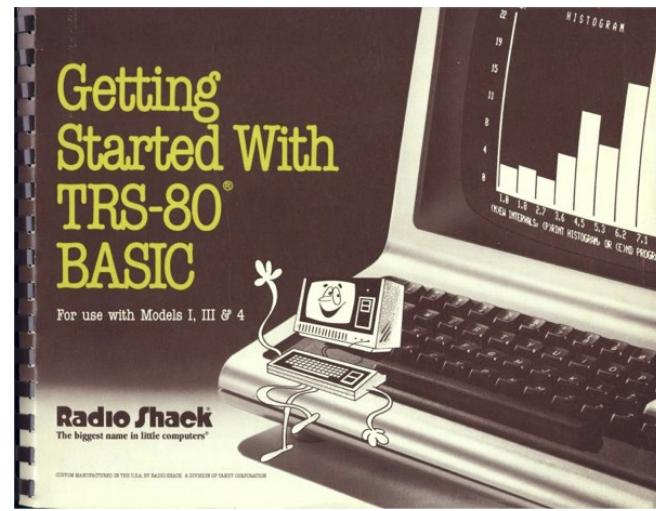
# Outline

- BeagleBoard.org, PocketBeagle and BaconBits
- Developer experience
  - Command-line and shell script
  - JavaScript and Python
  - C/C++
  - C on PRUs
- Project examples
- Labs

# BeagleBoard.org's objectives

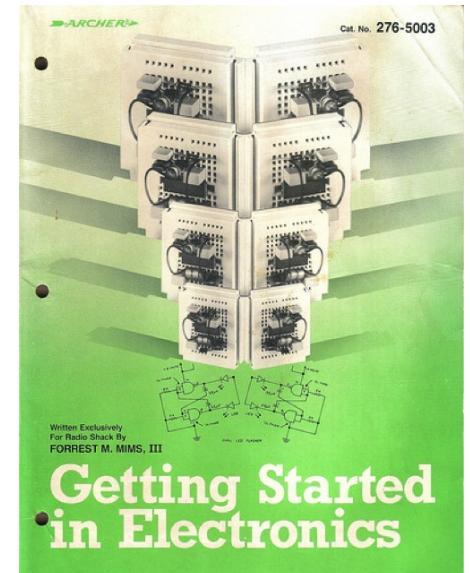
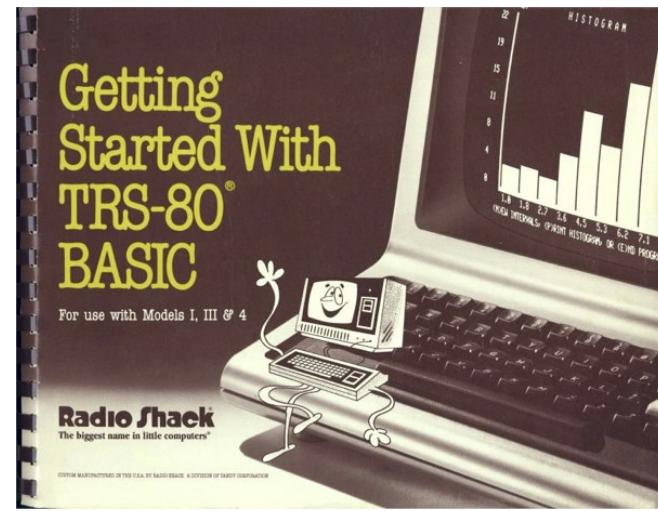
- Education
  - Design and use of open source SW/HW
  - Embedded computing
- Collaboration
  - Physical computing
  - Robotics
  - Industrial/machine controls

# Inspiration from early PCs



# Inspiration from early PCs

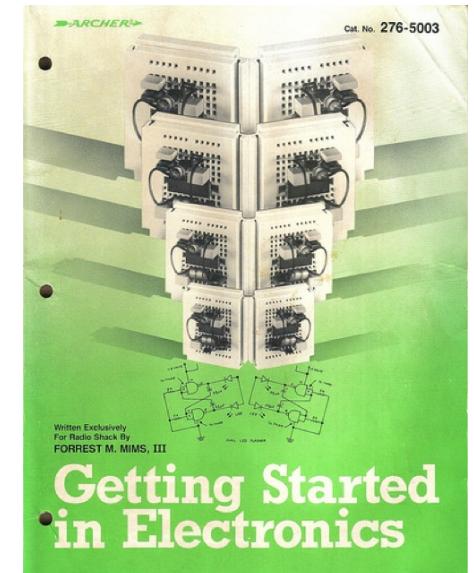
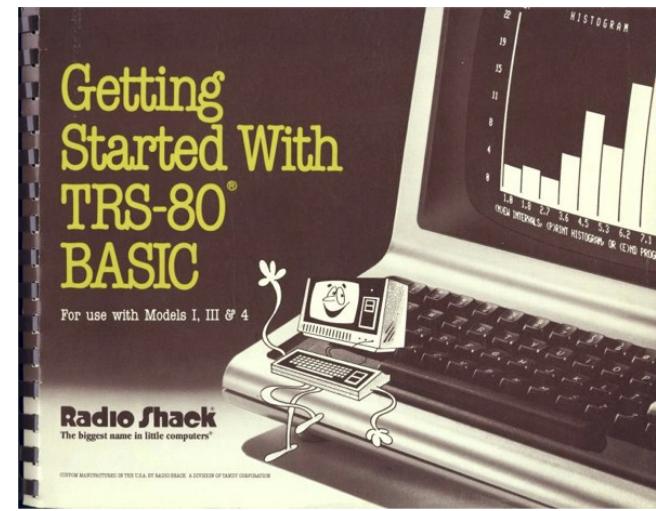
- How do people learn about embedded computers with so much ground to cover?



# Inspiration from early PCs

- How do people learn about embedded computers with so much ground to cover?

- Linux keeps history
- Affordable -> hackable
- Open from boot
- High-level languages
- Motivate with hardware



# Vision

- Creating with electronics should be as easy as creating a web page



# Vision

- Creating with electronics should be as easy as creating a web page
- Appliances are better than applications



# Vision

- Creating with electronics should be as easy as creating a web page
- Appliances are better than applications
- Open source software and hardware enable
  - Collaboration on the problem
  - Ability to understand and improve the fundamentals

# Reality

- Boot-to-browser feels too limiting → booting to Debian distro
- Collaborative programming still complex → collaborate at the kernel
- Many possible development environments
  - command-line/ssh, Cloud9 IDE, node-red, pureData, SuperCollider, LabView, Matlab, Eclipse, Visual Studio, Scratch, Blockly
- Domain specific approaches
  - Machinekit/LinuxCNC, PLC, many IoT toolkits
  - Many rapid sensor approaches: capes, mikroBus, Grove/Grove Zero, PMOD
  - Many rapid build approaches: LEGO, printing/milling, Makeblock, Vex, various other aluminum kits

# Approach

- Don't try to boil the ocean
  - We seek to engage the open source community
- Help where we can
  - Blue supports Grove cables
  - PocketBeagle supports mikroBus click pinout
  - Many “BeagleBoard Compatible” devices targeting specific application areas

# Board history

Fanless open computer  
(BeagleBoard)



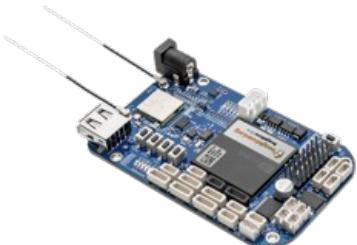
\$249

Mint tin sized with industrial  
peripherals (BeagleBone)



\$69

Application focused BeagleBones



\$79

Smalls mint tin sized with super-  
flexible design - PocketBeagle



\$25

# PocketBeagle objectives

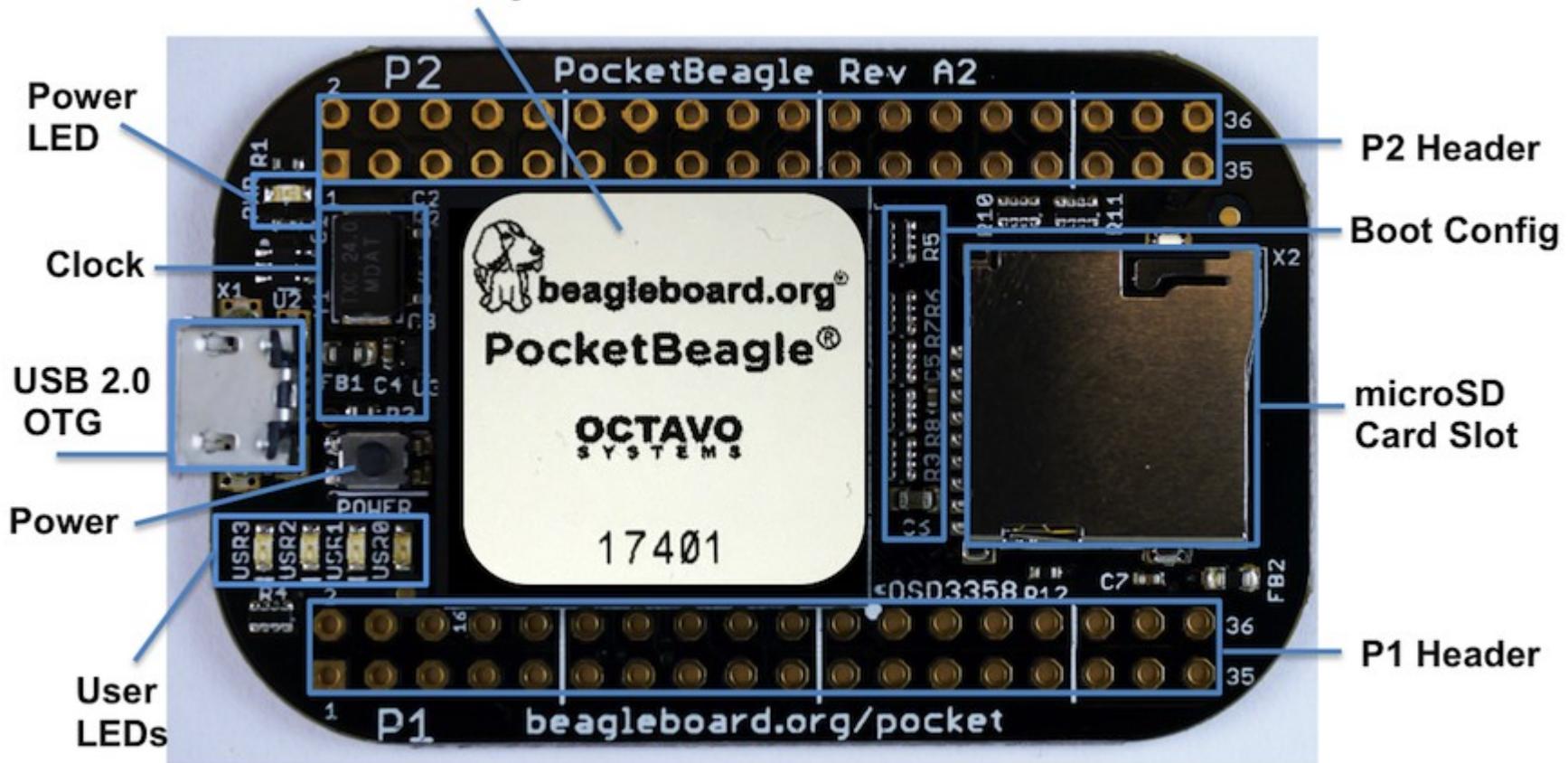
- Get simple
  - 4-layer PCB done in both Kicad and EAGLE
  - Every expansion header pin has a useful predefined mode
- Get flexible
  - USB to holes, no on-board pin consumption, no header soldered
  - Support for 2 mikroBus Click boards (over 300 already exist)
- Get small
  - Stick with mint-tin survival-kit theme, but go to “smalls” (35mm x 55mm)
- Get low cost
  - System-in-package approach has can lower build costs
  - Launched/sustainable at \$25

# PocketBeagle key features

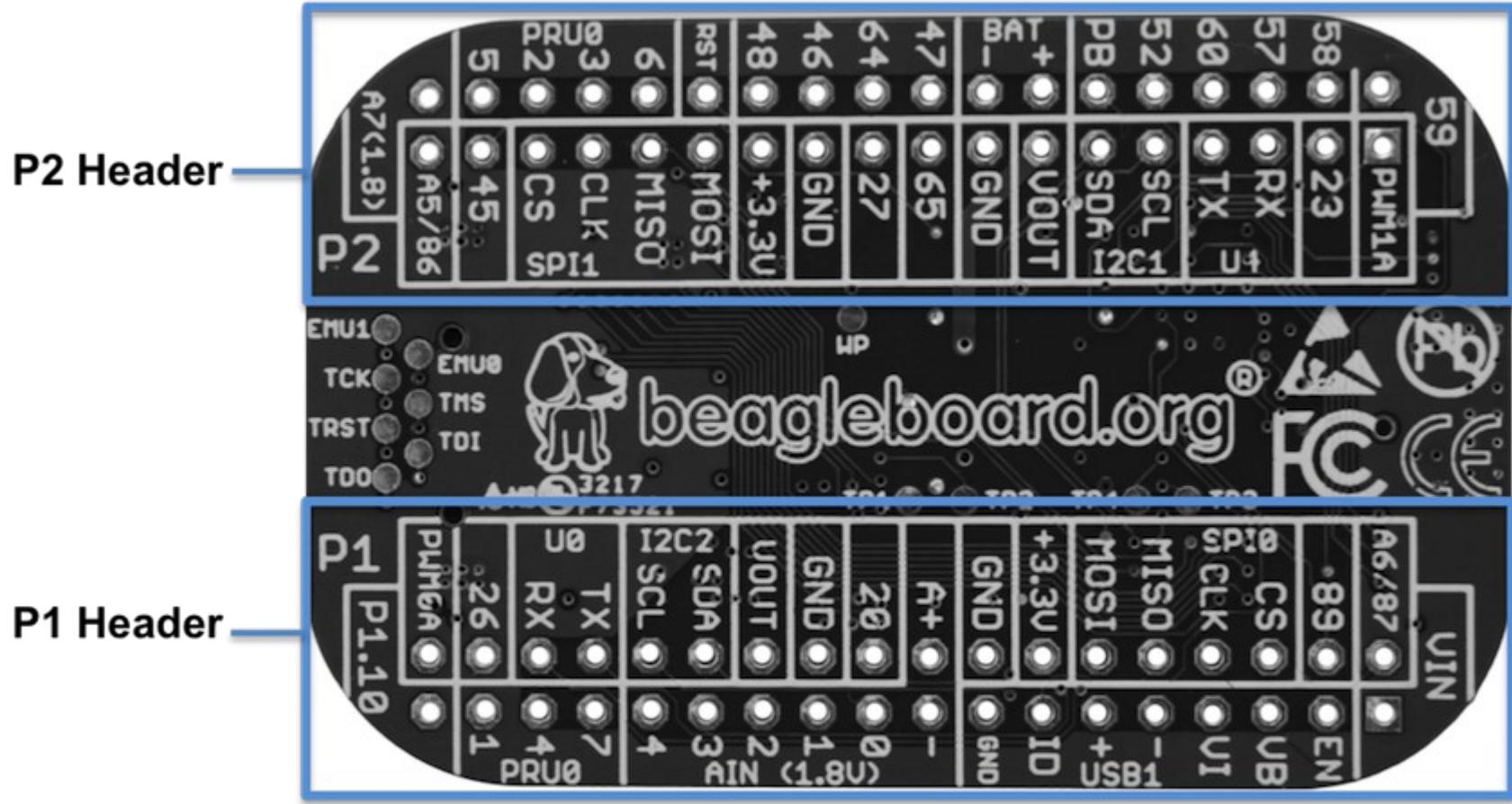
- Processing
  - 1-GHz ARM Cortex-A8 processor
  - 2x200-MHz programmable real-time units (PRUs)
  - ARM Cortex-M3 microcontroller for power and security
  - SGX530 graphics processor (OpenGL ES)
- Memory
  - 512-MB DDR3
  - 4-KB I2C EEPROM
- Interfaces
  - USB 2.0 OTG
  - microSD
- 72 expansion header pins
  - 8 analog inputs (6@1.8V, 2@3.3V)
  - 44 digital I/Os (18 enabled)
  - 3 UARTs (2 enabled)
  - 2 I2C ports
  - 2 SPI ports
  - 2 quadrature encoders accessible
  - 2 CAN bus controllers accessible
  - USB, power/reset buttons, battery/DC

# PocketBeagle top

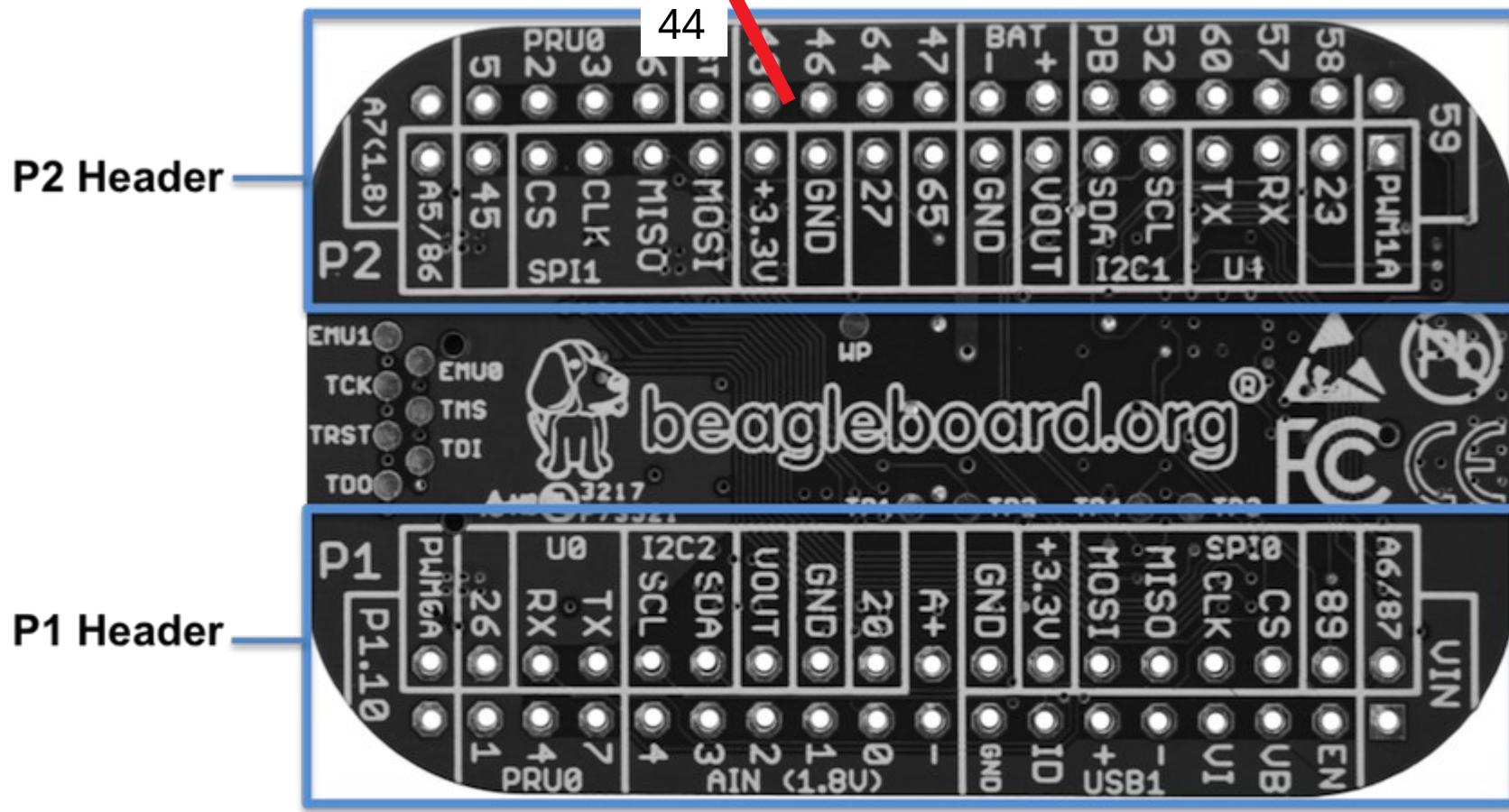
Octavo Systems OSD3358-SM



# PocketBeagle bottom



# PocketBeagle bottom



# PocketBeagle expansion

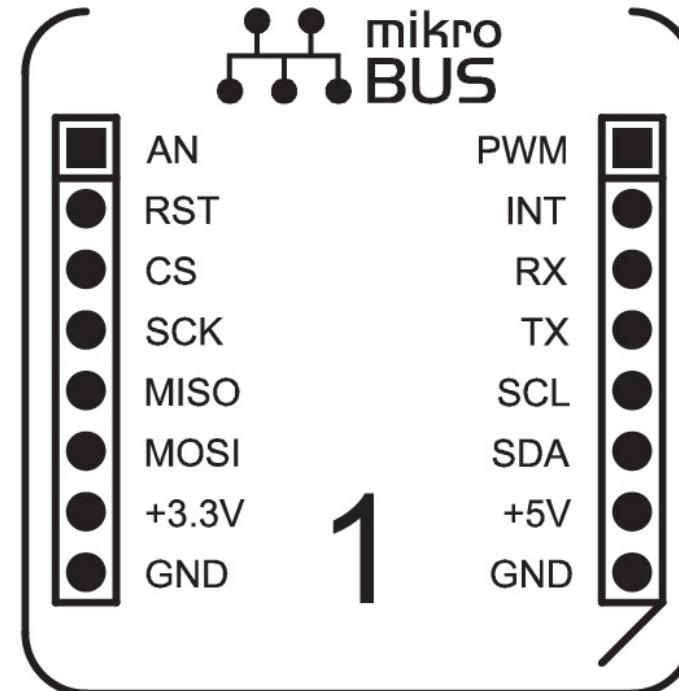
PocketBeagle Expansion Headers (Rev A2a)

		P1			
USB1	SYS	VIN	1	2	87
	USB1	V_EN	GPIO	109	3
				4	89
		VBUS	5	6	5
		VIN	7	8	2
		DN	9	10	3
		DP	11	12	4
		ID	13	14	3.3V
		GND	15	16	GND
		REF-	17	18	REF+ AIN 1.8V
AIN 1.8V	0	19	20	20	GPIO
	1	21	22	GND	SYS
	2	23	24	VOUT	SYS
	3	25	26	12	
	4	27	28	13	
PRU0	7	QEP0	STRB	A	GPIO
	4				
	1	PWM0	B		
	10				
		117	29	30	43
		114	31	32	42
		111	33	34	26
		88	35	36	110

		P2			
GPIO	PWM1	A	50	1	2
	PWM2	B	23	3	4
	UART4	RX TX	30	5	6
	CAN1	RX TX	31	7	8
	I2C1	SCL SDA	15	9	10
			14	11	12
			13	14	VIN
			15	16	TEMP BAT
			65	17	18
			27	19	20
GPIO	CAN1	RX TX	41	25	26
	I2C2	SDA SCL	40	27	28
	UART0	TX RX	7	29	30
			19	31	32
			45	33	34
			86	35	36
SYS	16(in)				
	15(out)	QEP2 B			
	14(in)				
	14(out)				
GPIO	NRST	SYS			
	IDX	QEP2			
	A				
	15i				
	PRU0				
SYS	3.3V				
	2.3V				
	1.8V				
	1.3V				
	1.0V				
GPIO	115				
	112				
	113				
	116				
	117				
SYS	112				
	113				
	116				
	117				
	118				
GPIO	5				
	2				
	3				
	6				
	7				
PRU0	115				
	112				
	113				
	116				
	117				
PRU0	5				
	2				
	3				
	6				
	7				
PRU0	115				
	112				
	113				
	116				
	117				
PRU0	5				
	2				
	3				
	6				
	7				

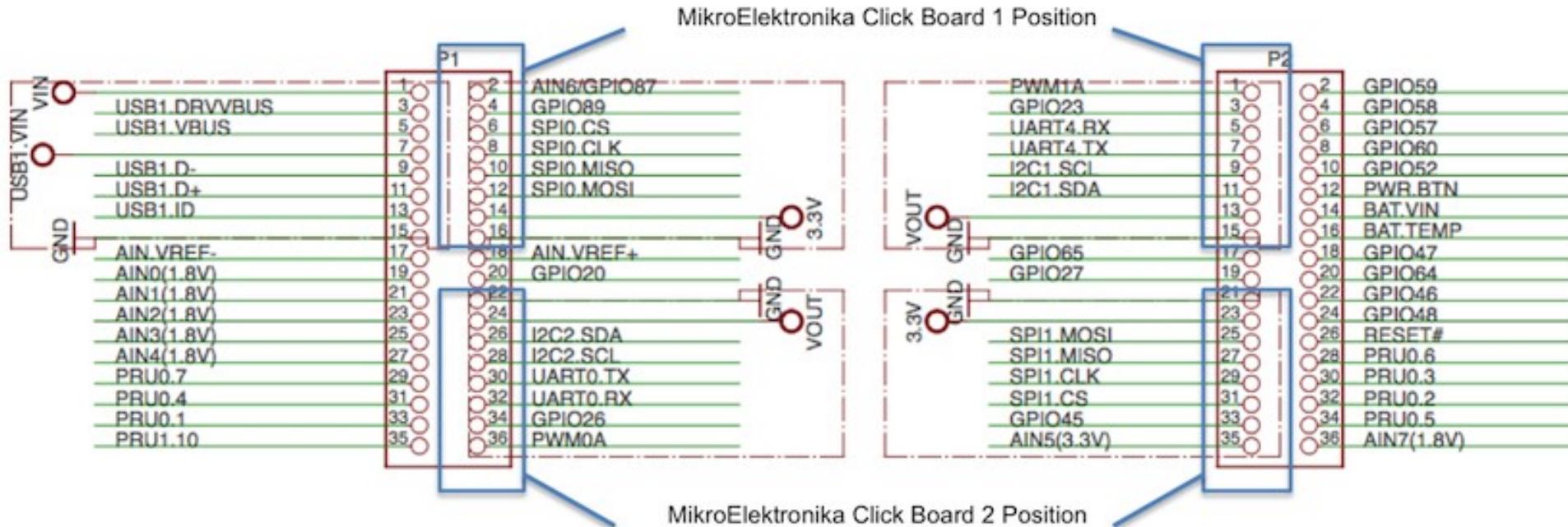
# mikroBus Click

Analog - **AN**  
Reset - **RST**  
SPI Chip Select - **CS**  
SPI Clock - **SCK**  
SPI Master Input Slave Output - **MISO**  
SPI Master Output Slave Input - **MOSI**  
VCC-3.3V power - **+3.3V**  
Reference Ground - **GND**



**PWM** - PWM output  
**INT** - Hardware Interrupt  
**RX** - UART Receive  
**TX** - UART Transmit  
**SCL** - I<sup>2</sup>C Clock  
**SDA** - I<sup>2</sup>C Data  
**+5V** - VCC-5V power  
**GND** - Reference Ground

# Connecting mikroBus Clicks



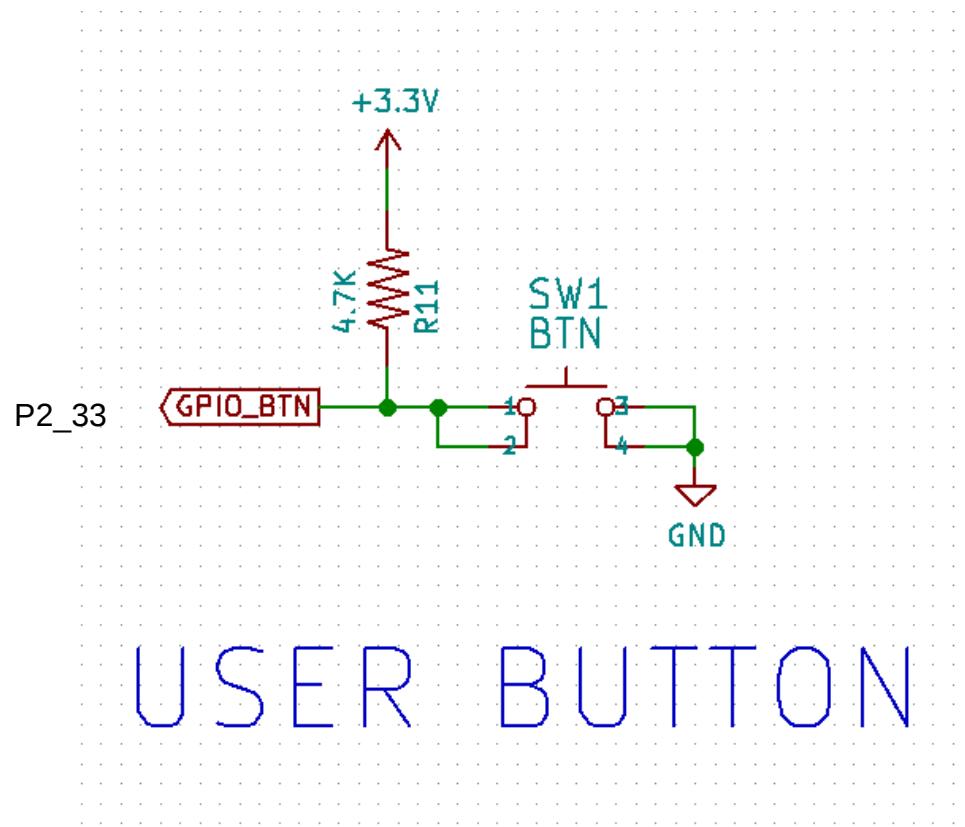
# BaconBits objectives

- Designed specifically for e-ale training
- Inspired by “Bacon Cape” by Dave Anders
  - Designed for similar purpose on BeagleBone
- Provides target for common embedded interfaces
  - SPI, I2C, GPIO, PWM, ADC, USB, serial
- Avoided buying several modules

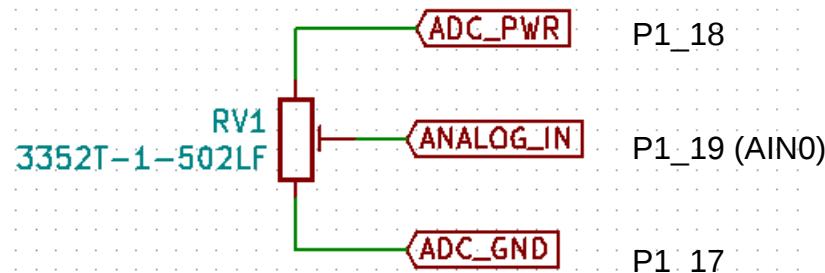
# BaconBits features

- USB-to-Serial micro B
- USB Host A with power
- Power and Reset buttons
- GPIO push button
- ADC potentiometer thumbwheel
- PWM tri-color LED
- SPI 2-digit 7-segment display
- I2C accelerometer

# BaconBits GPIO button

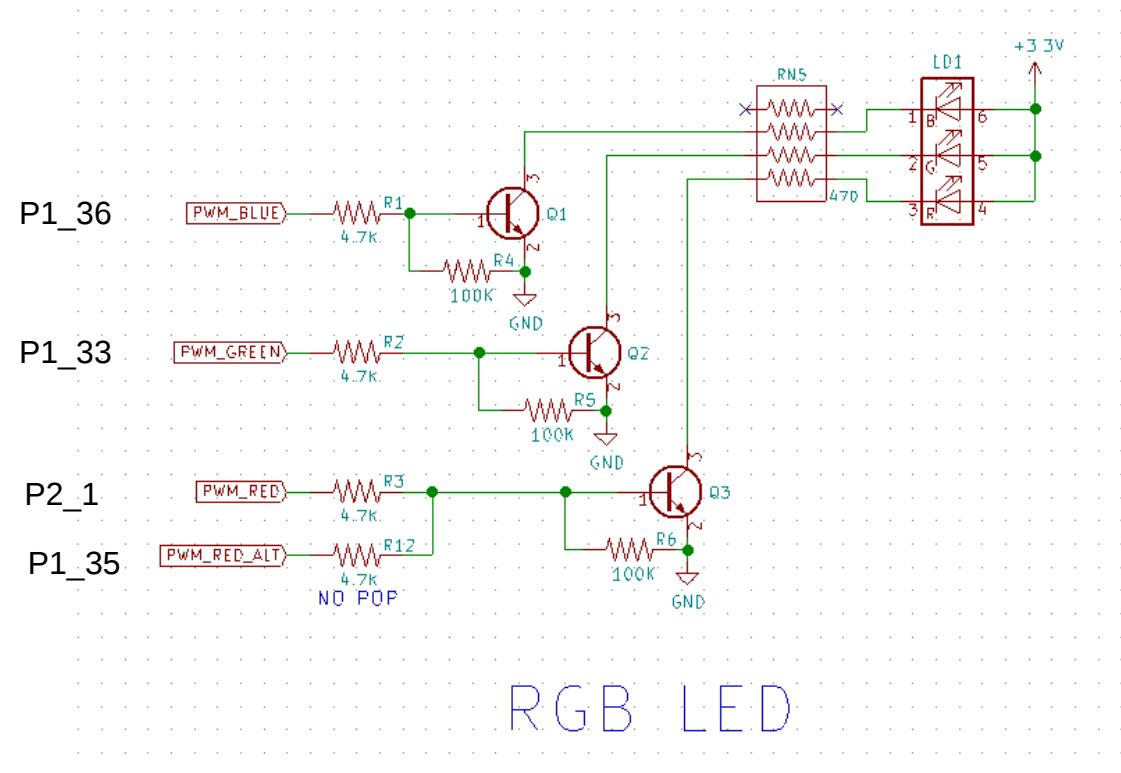


# BaconBits ADC thumbwheel

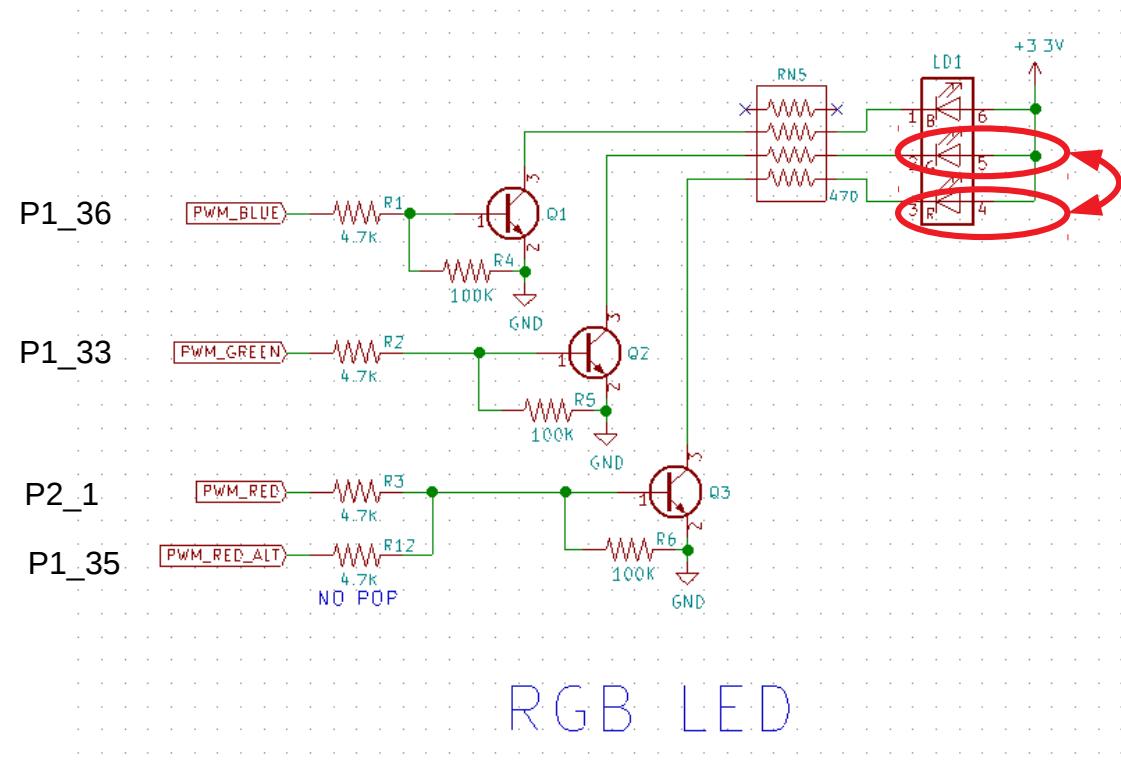


THUMBWHEEL

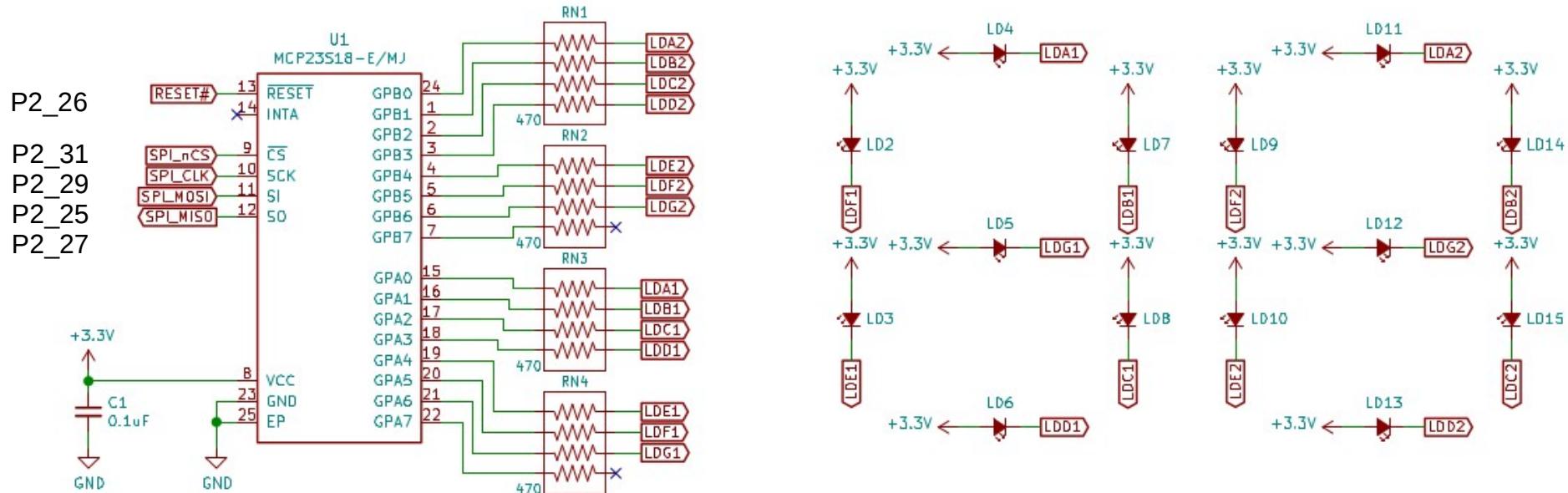
# BaconBits RGB LED



# BaconBits RGB LED

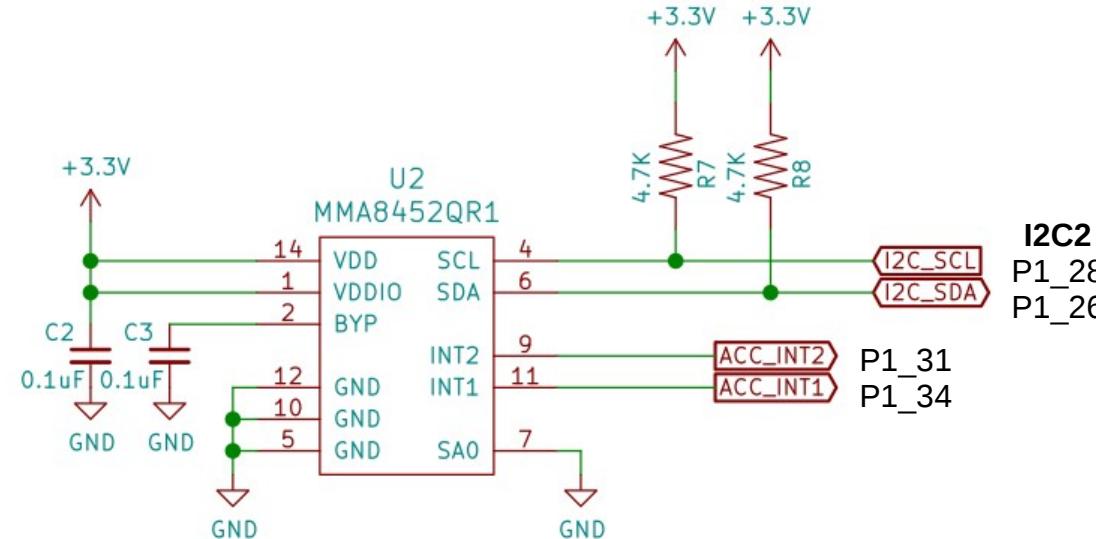


# BaconBits SPI 7-segment display



EMULATED 7 SEGMENTS

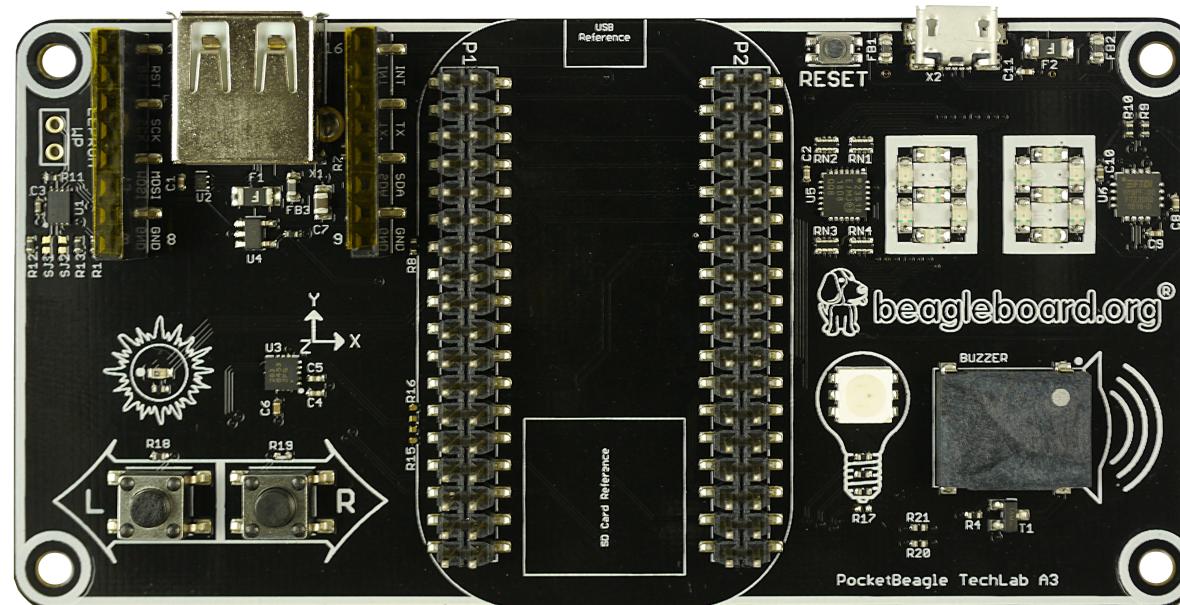
# BaconBits I2C accelerometer



ACCELEROMETER

# PocketBeagle TechLab Cape

- Designed to be compatible with BaconBits
- [beagleboard.org/techlab](http://beagleboard.org/techlab)

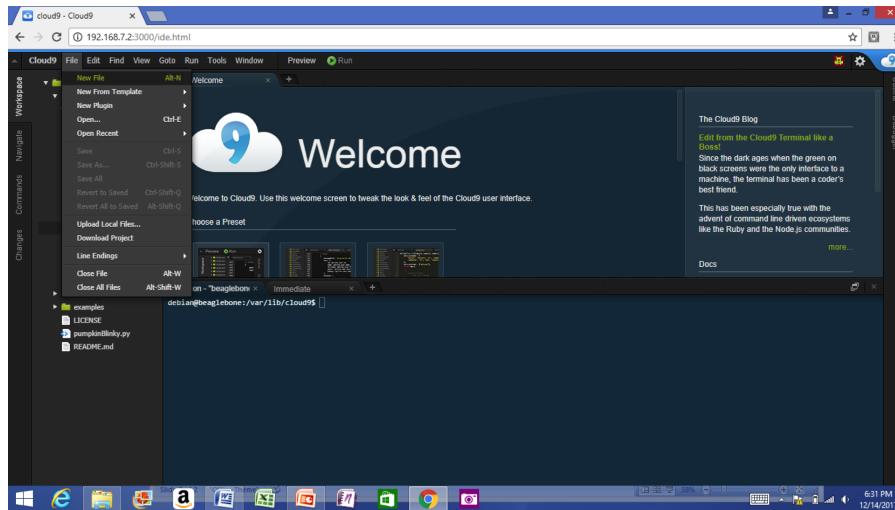


# Developer experience

- Customized Debian images – [bbb.io/latest](https://bbb.io/latest)
- Self-hosted tools for ARMs and PRU
- Libraries for various high-level languages
- Scripts for common tasks
- Sources for bootloader, device tree, etc.
- Servers for network-based development

# Single cable development

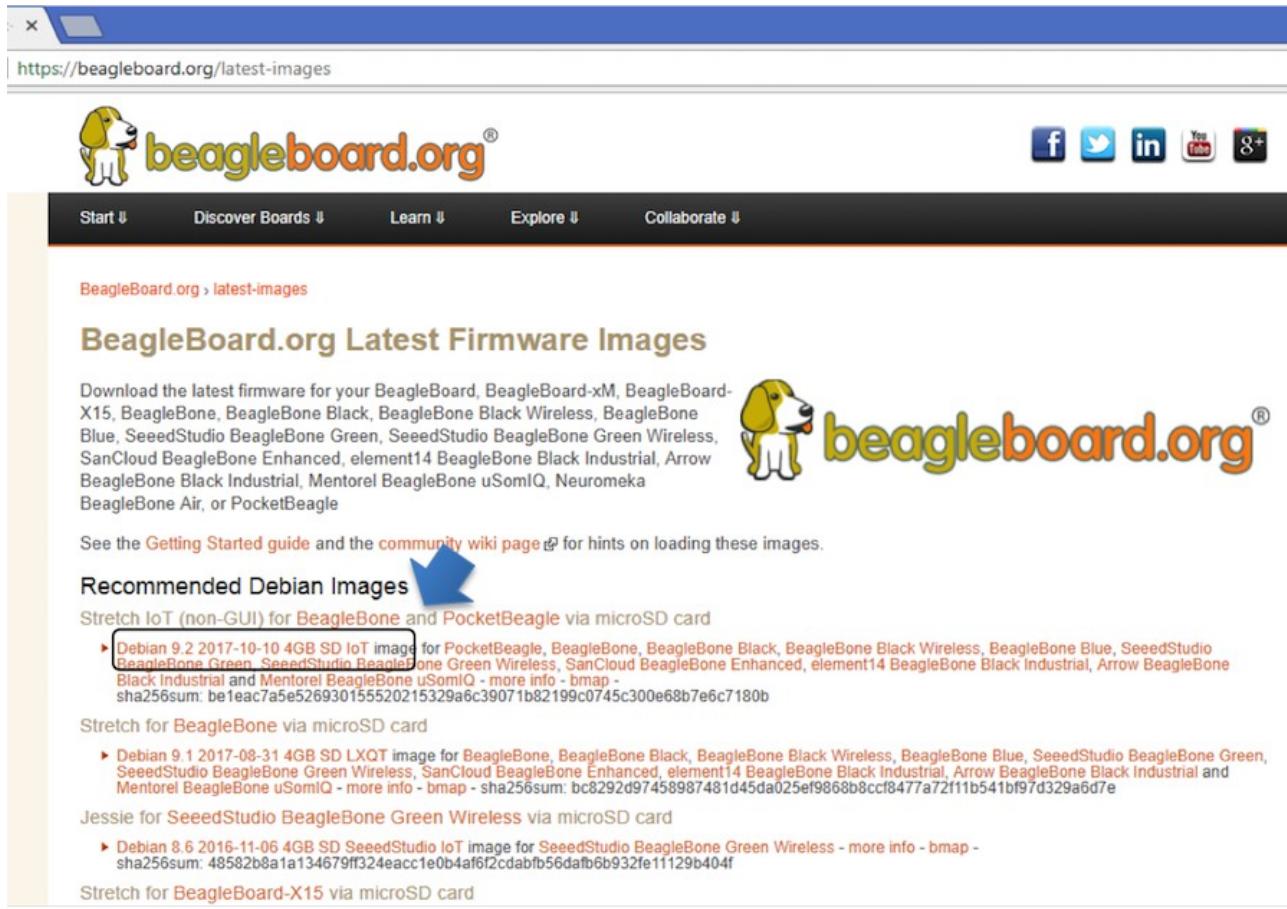
- Power, network, develop
- You can add a network and power many other ways



# Some work in progress

- Add proxy for various services (in Buster IoT images today)
- Integrate common web-based WiFi provisioning
  - SeeedStudio BeagleBone Green Wireless ships with ‘wifidog’ → we will unify approach
- Cross-platform distro installer app
  - See USB NETCONSOLE presentation
- Support for Grove modules and mikroBus clicks
  - Focus on device-tree overlays and kernel patches
- Integration alignment with complete domain solutions
  - Intelligent Agent Replicape/Revolve, Bela Mini, BeagleLogic, etc.
- Improved and integrated PRU examples
- Move to distro friendly approaches for customizations

# Download image



The screenshot shows a web browser displaying the <https://beagleboard.org/latest-images> page. The page features the BeagleBoard.org logo at the top left, followed by social media sharing icons. A navigation bar includes links for Start, Discover Boards, Learn, Explore, and Collaborate. The main content area is titled "BeagleBoard.org Latest Firmware Images". It contains a list of supported boards and a section for "Recommended Debian Images". A blue arrow points from the text "See the Getting Started guide and the community wiki page" to the "Recommended Debian Images" section. The "Recommended Debian Images" section lists several options, with the first one highlighted in a box:

Stretch IoT (non-GUI) for BeagleBone and PocketBeagle via microSD card

- ▶ **Debian 9.2 2017-10-10 4GB SD IoT image for PocketBeagle, BeagleBone, BeagleBone Black, BeagleBone Black Wireless, BeagleBone Blue, SeeedStudio BeagleBone Green, SeeedStudio BeagleBone Green Wireless, SanCloud BeagleBone Enhanced, element14 BeagleBone Black Industrial, Arrow BeagleBone Black Industrial and Mentorel BeagleBone uSomIQ - more info - bmap - sha256sum: bfeac7a5e526930155520215329a6c39071b82199c0745c300e68b7e6c7180b**

Stretch for BeagleBone via microSD card

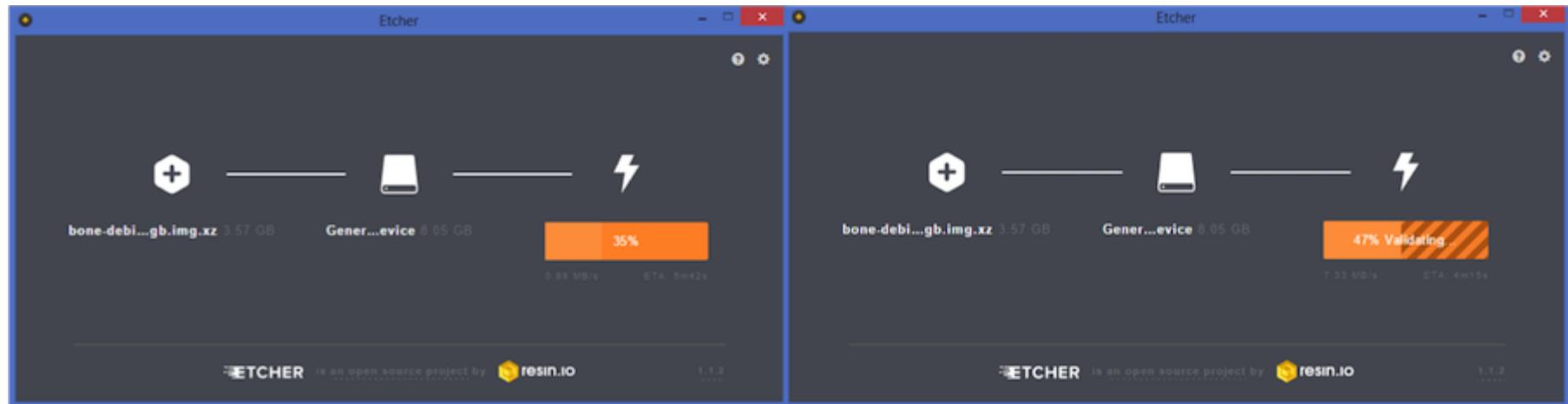
- ▶ **Debian 9.1 2017-08-31 4GB SD LXQT image for BeagleBone, BeagleBone Black, BeagleBone Black Wireless, BeagleBone Blue, SeeedStudio BeagleBone Green, SeeedStudio BeagleBone Green Wireless, SanCloud BeagleBone Enhanced, element14 BeagleBone Black Industrial, Arrow BeagleBone Black Industrial and Mentorel BeagleBone uSomIQ - more info - bmap - sha256sum: bc8292d97458987481d45da025e19868b8ccf8477a72f11b541bf97d329a6d7e**

Jessie for SeeedStudio BeagleBone Green Wireless via microSD card

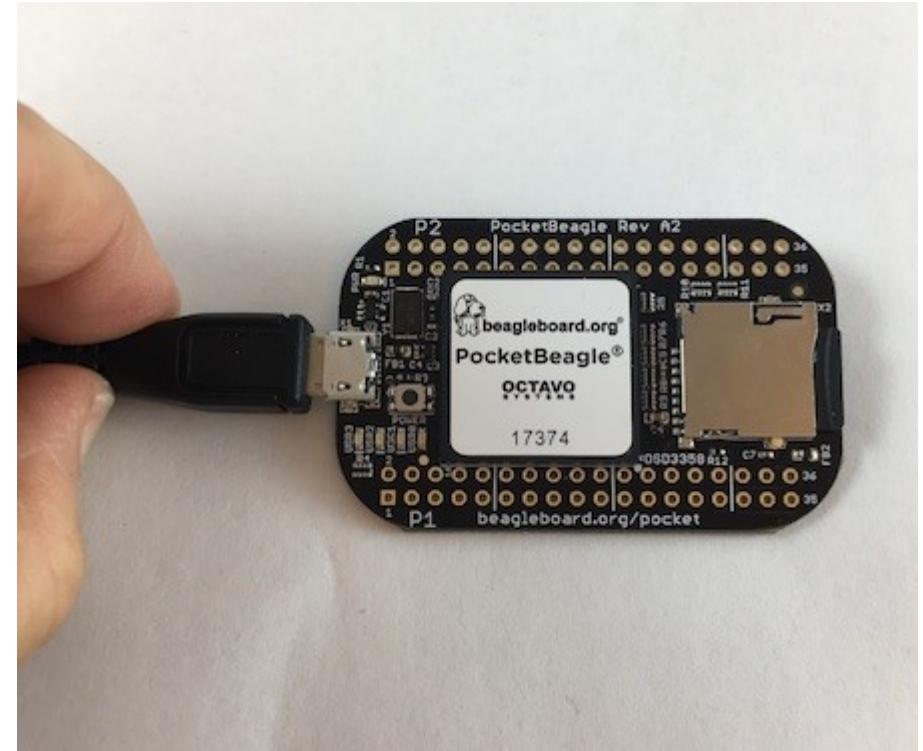
- ▶ **Debian 8.6 2016-11-06 4GB SD SeeedStudio IoT image for SeeedStudio BeagleBone Green Wireless - more info - bmap - sha256sum: 48582b8a1a134679f324eacc1e0b4af6f2cdabfb56dafb6b932fe11129b404f**

Stretch for BeagleBoard-X15 via microSD card

# Write image to microSD with Etcher



# Insert microSD and boot



# Connect to the USB network

Getting started with Beagle X

file:///Volumes/BEAGLEBONE/START.htm



**Start your Beagle**

Beagles are tiny computers with the capability of modern systems, without the bulk, expense, or noise. Read the step-by-step getting started tutorial below to begin developing with your Beagle in minutes.

For user supplied tips on getting started, visit the eLinux (or other) community wiki pages:

- BeagleBoard
- BeagleBoard-X15
- BeagleBone
- BeagleBone Black
- BeagleBone Green
- BeagleBone Green Wireless
- BeagleBone Blue
- SeedStudio BeagleBone Green
- SeedStudio BeagleBone Green Wireless
- SanCloud BeagleBone Enhanced
- NeuroMeka BeagleBone Air

If any step fails, it is recommended to update to the [latest software image](#) to use the instructions below.

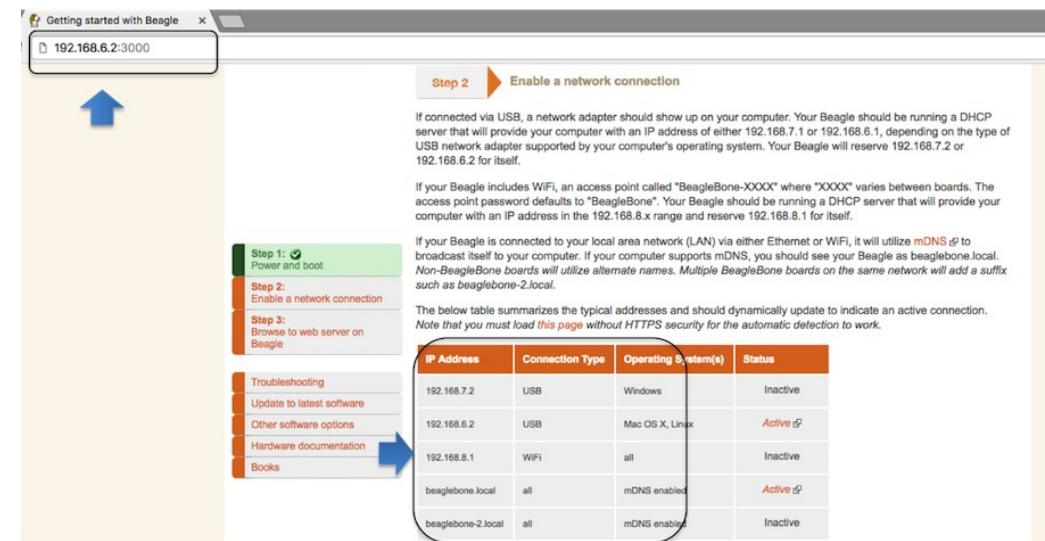
**Step 1** Power and boot

Most Beagles include a USB cable, providing a convenient way to provide both power to your Beagle and connectivity to your computer. If you provide your own, ensure it is of good quality. You'll connect the ["type-B" plug](#) of the USB cable to your Beagle and the ["type-A"](#) plug to your computer. Note that BeagleBoard-X15 must always be powered instead by a 12V adapter with a barrel jack.

Alternatively, for Beagles other than BeagleBoard-X15 and BeagleBone Blue that require 12V, you can utilize a 5V adapter connected to the barrel jack.

Getting started with Beagle X

192.168.6.2:3000



**Step 2** Enable a network connection

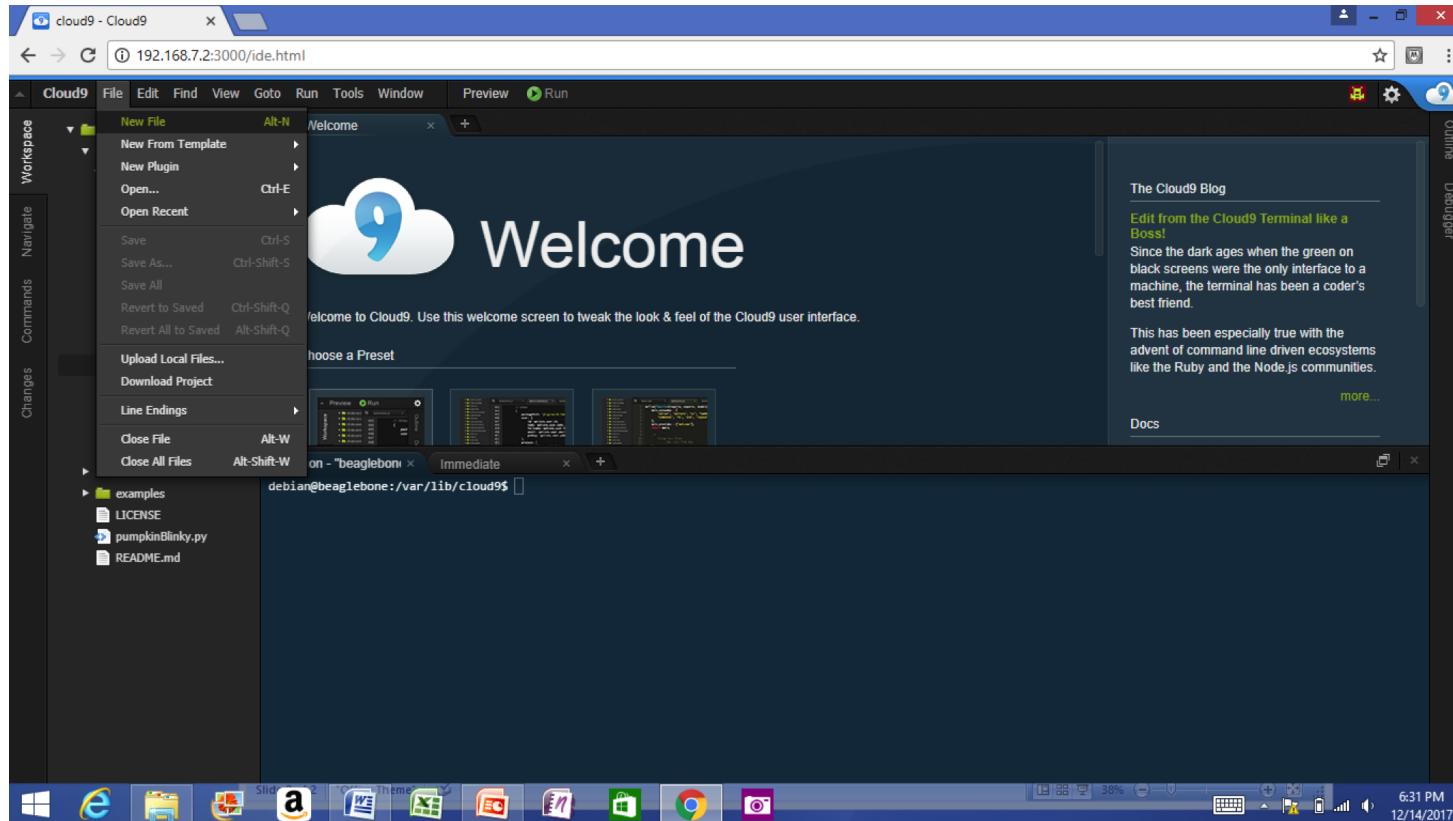
If connected via USB, a network adapter should show up on your computer. Your Beagle should be running a DHCP server that will provide your computer with an IP address of either 192.168.7.1 or 192.168.6.1, depending on the type of USB network adapter supported by your computer's operating system. Your Beagle will reserve 192.168.7.2 or 192.168.6.2 for itself.

If your Beagle includes WiFi, an access point called "BeagleBone-XXXX" where "XXXX" varies between boards. The access point password defaults to "BeagleBone". Your Beagle should be running a DHCP server that will provide your computer with an IP address in the 192.168.8.x range and reserve 192.168.8.1 for itself.

The below table summarizes the typical addresses and should dynamically update to indicate an active connection. Note that you must load [this page](#) without HTTPS security for the automatic detection to work.

IP Address	Connection Type	Operating System(s)	Status
192.168.7.2	USB	Windows	Inactive
192.168.8.2	USB	Mac OS X, Linux	Active
192.168.8.1	WiFi	all	Inactive
beaglebone.local	all	mDNS enabled	Active
beaglebone-2.local	all	mDNS enabled	Inactive

# Open the IDE



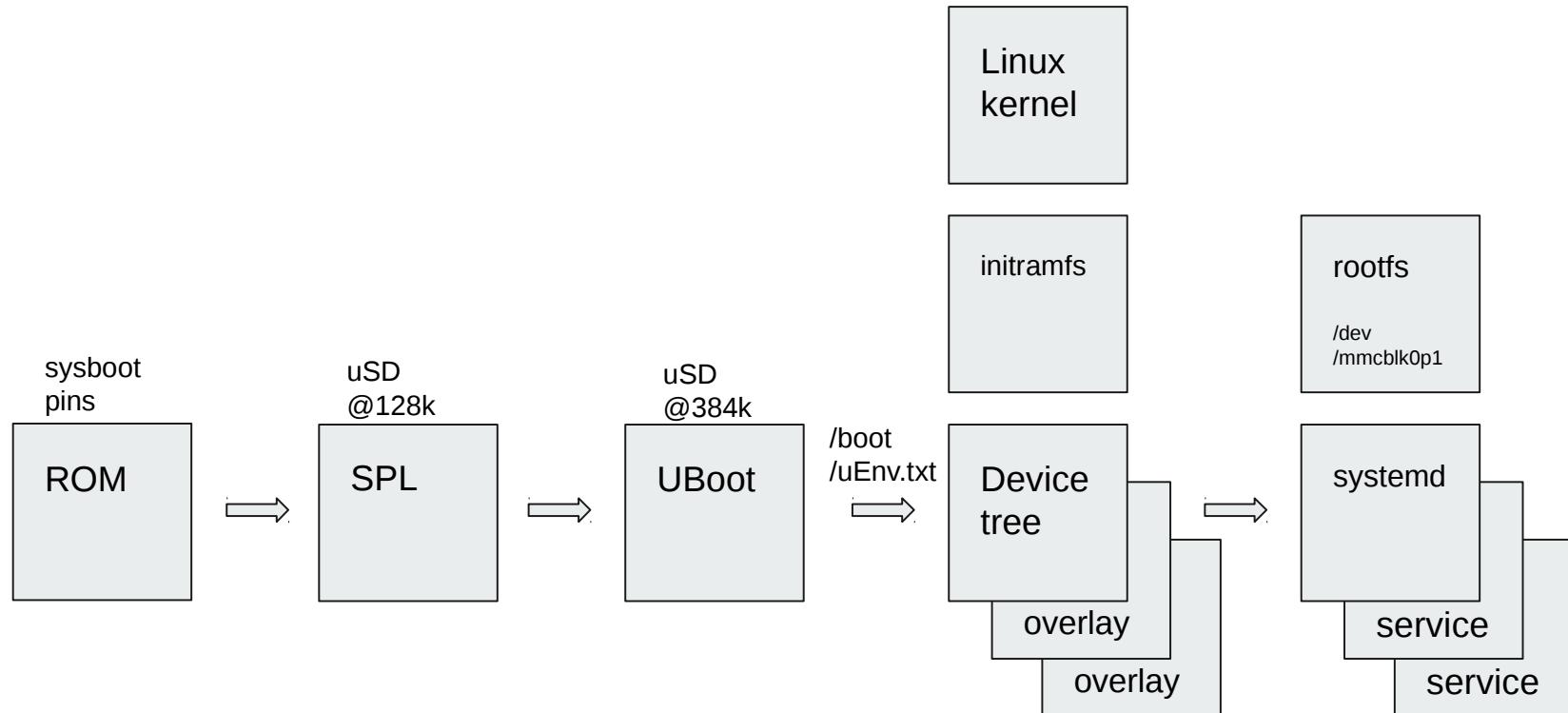
# USB gadgets

- Linux name for device/slave drivers
  - ie., when not host
- USB devices have “classes”
  - Mass storage
  - Camera
  - Audio
  - Printer
  - “HID” or human-interface device like mouse and keyboard
  - Communications

# USB gadgets

- Default image USB gadgets
  - Virtual mass storage
    - Serves you up README.htm
  - Virtual serial
    - Provides access to console after kernel boot
  - Virtual network
    - Enables access to ssh and web servers

# Boot summary



# In Linux, everything becomes a file

- Much to learn
  - I'm used to microcontrollers: just give me the datasheet with register definitions and set me free!
- Training on boot & device drivers useful
  - Often geared more at system bring-up
  - What about the everyday user?
  - Where is that abstraction benefit?
- Let's just walk a working system!

# What is the baseline?

<http://refspecs.linuxfoundation.org/lsb.shtml>

- Every Linux system may be customized
  - This is the nature of open source
  - Stuff still needs to work together
- The Linux Standard Base
  - Umbrella for various Linux Foundation groups
  - A specification and a testkit
  - Documents typical libraries, functions and files expected to be found by the developer

# lsb\_release

```
debian@beaglebone:~$ sudo apt install -y lsb
debian@beaglebone:~$ lsb_release -a
No LSB modules are available.
Distributor ID: Debian
Description:      Debian GNU/Linux 9.5 (stretch)
Release:          9.5
Codename:         stretch
```

# Filesystem Hierarchy Standard

<http://www.pathname.com/fhs/>

- /tmp: temporary files
- /var: data that changes at run-time
- /proc: "information from processes" (virtual)
- /sys: "system filesystem" (virtual)
- /dev: device files
- /media: mount point for removable media
- /lost+found: data without directory entry
- /mnt: mount point for temporary mounted file systems
- /opt: add-on application software packages

# /proc

```
debian@beaglebone:~$ ls /proc
 1      1692   22    3354   878   990          fb       misc           sysvipc
 10     17      23    3362   89     90        filesystems  modules        thread-self
 11     18      2370   34      9     asound        fs       mounts        timer_list
 1110   1857   2375   4      90    buddyinfo        interrupts  mtd          tty
 1112   19      2377   6      91     bus          iomem        net          uptime
 1119   1951   2379   69    913    cgroups        ioports      pagetypeinfo  version
 1150   1964   24      7    918    cmdline        irq         partitions  vmallocinfo
 1151     2      25    70    92    config.gz      kallsyms      pvr          vmstat
 1152   20      26    71    93    consoles        keys        sched_debug  zoneinfo
 12      21      27    72    945    cpu          key-users      schedstat
 1215   2107   28      73    951    cpuinfo        kmsq        self
 1247   2120   29      74    959    crypto        kpagecgroun  slabinfo
 13      2149   30      8    973    devices        kpagecount    softirqs
 1440   2152   31    800    977  device-tree      kpageflags    stat
 15      2153   32    820    980  diskstats      loadavg        swaps
 159     2155   33    821    983    driver        locks          sys
 16      2173  3353   858    984  execdomains      meminfo      sysrq-trigger
```

# /proc/cpuinfo

```
debian@beaglebone:~$ cat /proc/cpuinfo
processor      : 0
model name    : ARMv7 Processor rev 2 (v7l)
BogoMIPS       : 995.32
Features       : half thumb fastmult vfp edsp thumbee neon vfpv3
tls vfpd32
CPU implementer : 0x41
CPU architecture: 7
CPU variant    : 0x3
CPU part       : 0xc08
CPU revision   : 2

Hardware      : Generic AM33XX (Flattened Device Tree)
Revision      : 0000
Serial        : 1741GPB42934
```

# The file interface abstraction

- What can I do with files?
  - open, read, write, close, delete
  - What is an "ioctl"?
  - What is "mmap"?
- What is a virtual file system?
  - Looks like a file, but executes code in the kernel
  - Not really storing anything to media
  - A bit like a "ram disk"

# Kernel.org documentation

<http://www.kernel.org/doc/>

- Documentation extracted from the Linux kernel and mirrored on the web where Google can find it:
  - Documentation - Text files in the kernel source tarball's Documentation subdirectory
  - htmldocs - Kernel Documentation maintained in docbook format (output of "make htmldocs")
  - Menuconfig - help text for each kernel configuration option (from kconfig source)
  - README various README files scattered around Linux kernel source
  - RFC - List of IETF RFCs referred to by kernel source files. Links to both the text of the RFC and the source files that refer to it
  - Output of kernel's "make help"
- Standards documents applicable to the Linux kernel
- Other web pages containing kernel documentation
- Translations to other languages
- Documentation on memory management
- Miscellaneous

# Kernel Application Binary Interface

<http://www.kernel.org/doc/Documentation/ABI/>

- Low-level kernel interface from "userland"
- Status of interface
  - Stable
    - Encouraged to use freely
    - Guaranteed for at least two years
  - Testing
    - Mostly complete, but might change
    - Let developers know how you are using
    - Where you'll find most of the good stuff
  - Obsolete
    - Scheduled for removal
  - Removed

# Kernel Application Binary Interface

<http://www.kernel.org/doc/Documentation/ABI/>

- Types of interfaces
  - Syscalls
    - Trap interface with IDs
    - May be possible to have a direct entry
  - SYSFS
    - Virtual file system
    - See also DEBUGFS and CONFIGFS

# Syscalls

<http://www.kernel.org/doc/man-pages/online/pages/man2/syscalls.2.html>

- open/read/write/lseek/close/unlink
- ioctl
- mknod
- fork/select/poll/...
- mkdir/...
- mount/umount
- mmap

# What is SYSFS?

- Virtual file system that exposes drivers to userspace
- `mount | grep sysfs`
  - sysfs on /sys type sysfs (rw, nosuid, nodev, noexec, relatime)
- /sys/devices - driver hierarchy
- /sys/bus - symbolic links to bus owners
- /sys/class - common interfaces
- /sys/block - block interface
- How about some examples?

# /sys/module

<http://www.kernel.org/doc/Documentation/ABI/stable/sysfs-module>

- /sys/module/MODULENAME
  - .../parameters: options you can provide
  - .../refcnt: number of times in use

```
debian@beaglebone:~$ ls /sys/module
8250          fb           lockd          pruss        sysrq        usb_f_ecm
apparmor      firmware_class mma8452       pruss_intc   tcp_cubic   usb_f_mass_storage
auth_rpcgss   fscrypto     mmcblk       pruss_soc_bus tda18271   usb_f_rndis
block         fuse         module        pvrsvkm    tda827x    usbhid
bone_capemgr hid          mt20xx       r8188eu    tda8290    usb_storage
can           hid_logitech nf_conntrack random      tea5761    u_serial
cec           hid_logitech_hidpp nf_conntrack_ipv4 rc_core    tea5767    vt
cfg80211     i2c_algo_bit  nf_defrag_ipv4  rcupdate   rcutree    ti_cpsw
configfs      ima          nf_nat       rfkill     tpm
cpufreq       iptable_filter nf_nat_ipv4  rng_core   tuner_simple
cpuidle       iptable_mangle nf_layout_nfsv41_files sdhci     ubi
cryptomgr     iptable_nat  nfs          snd        ubifs
dns_resolver  ip_tables    nfsv4       omapdrm    snd_pcm
drm           ipv6         onenand     omap_mailbox snd_timer
drm_kms_helper ir_kbd_i2c overlay    pinctrl_mcp23s08 spidev
dvb_core      kernel      onenand     printk    spurious
dynamic_debug keyboard    overlay    pru_rproc
eeprom_93cx6  leds_pwm    onenand
ehci_hcd     libahci      overlay
etnaviv      libata      onenand
evdev         libcomposite overlay
```

# /sys/class/leds

<https://www.kernel.org/doc/Documentation/ABI/testing/sysfs-class-led>

- /sys/class/leds/LED
  - .../brightness: 0-max\_brightness, >0 = on
  - .../max\_brightness: default is 255
  - .../trigger: triggers available from kernel
  - .../inverted: invert on/off state

```
debian@beaglebone:~$ ls /sys/class/leds
beaglebone:green:usr0  techlab::blue    techlab::seg1    techlab::seg13   techlab::seg3  techlab::seg7
beaglebone:green:usr1  techlab::green   techlab::seg10   techlab::seg14   techlab::seg4  techlab::seg8
beaglebone:green:usr2  techlab::red     techlab::seg11   techlab::seg15   techlab::seg5  techlab::seg9
beaglebone:green:usr3  techlab::seg0    techlab::seg12   techlab::seg2    techlab::seg6
```

# /sys/class/gpio

<http://www.kernel.org/doc/Documentation/ABI/testing/sysfs-gpio>

- Must be explicitly exported to userspace and not claimed by kernel code
- /sys/class/gpio
  - .../export: asks the kernel to export a GPIO to userspace
  - .../unexport: to return a GPIO to the kernel
  - .../gpioN: for each exported GPIO #N
    - .../value: always readable, writes fail for input GPIOs
    - .../direction: r/w as: in, out (low); write: high, low
    - .../edge: r/w as: none, falling, rising, both
  - .../gpiochipN: for each gpiochip; #N is its first GPIO
    - .../base: (r/o) same as N
    - .../label: (r/o) descriptive, not necessarily unique
    - .../ngpio: (r/o) number of GPIOs; numbered N to N + (ngpio - 1)

```
debian@beaglebone:~$ ls /sys/class/gpio
export  gpio114  gpio13  gpio20  gpio30  gpio42  gpio47  gpio58  gpio7   gpiochip0  unexport
gpio110  gpio115  gpio14  gpio23  gpio31  gpio43  gpio5   gpio59  gpio86  gpiochip32
gpio111  gpio116  gpio15  gpio26  gpio4   gpio44  gpio50  gpio60  gpio87  gpiochip496
gpio112  gpio117  gpio19  gpio27  gpio40  gpio45  gpio52  gpio64  gpio88  gpiochip64
gpio113  gpio12   gpio2   gpio3   gpio41  gpio46  gpio57  gpio65  gpio89  gpiochip96
```

# On-chip peripherals (OCP)

```
debian@beaglebone:~$ ls /sys/devices/platform/ocp
40300000.ocmcram 480c8000.mailbox      53100000.sham          ocp:P1_32_pinmux  ocp:P2_20_pinmux
44e07000 gpio     480ca000.spinlock    53500000.aes          ocp:P1_33_pinmux  ocp:P2_22_pinmux
44e09000.serial   4819c000.i2c       driver_override        ocp:P1_34_pinmux  ocp:P2_24_pinmux
44e0b000.i2c     481a0000.spi      modalias              ocp:P1_35_pinmux  ocp:P2_25_pinmux
44e0d000.tscadc  481a8000.serial    ocp:cape-universal   ocp:P1_36_pinmux  ocp:P2_27_pinmux
44e35000.wdt     481ac000 gpio     ocp:14_wkup@44c00000  ocp:P2_01_pinmux  ocp:P2_28_pinmux
44e3e000.rtc     481ae000 gpio     ocp:P1_02_pinmux      ocp:P2_02_pinmux  ocp:P2_29_pinmux
47400000.usb    481cc000.can      ocp:P1_04_pinmux      ocp:P2_03_pinmux  ocp:P2_30_pinmux
48022000.serial 481d0000.can      ocp:P1_06_pinmux      ocp:P2_04_pinmux  ocp:P2_31_pinmux
48024000.serial 48300000.epwmss   ocp:P1_08_pinmux      ocp:P2_05_pinmux  ocp:P2_32_pinmux
4802a000.i2c    48302000.epwmss   ocp:P1_10_pinmux      ocp:P2_06_pinmux  ocp:P2_33_pinmux
48030000.spi    48304000.epwmss   ocp:P1_12_pinmux      ocp:P2_07_pinmux  ocp:P2_34_pinmux
48042000.timer   48310000.rng     ocp:P1_20_pinmux      ocp:P2_08_pinmux  ocp:P2_35_pinmux
48044000.timer   49000000.edma    ocp:P1_26_pinmux      ocp:P2_09_pinmux  of_node
48046000.timer   49800000.tptc    ocp:P1_28_pinmux      ocp:P2_10_pinmux  power
48048000.timer   49900000.tptc    ocp:P1_29_pinmux      ocp:P2_11_pinmux  subsystem
4804a000.timer   49a00000.tptc    ocp:P1_30_pinmux      ocp:P2_17_pinmux  uevent
4804c000 gpio    4a326004.pruss-soc-bus ocp:P1_31_pinmux      ocp:P2_18_pinmux
48060000 mmc     4c000000.emif    ocp:P2_19_pinmux
```

# Reading events

- TBD

# Instantiating a device: .dts example

Phandle  
(reference  
to label)

```
&i2c0 {  
    pinctrl-names = "default";  
    pinctrl-0 = <&i2c0_pins>;  
    status = "okay";  
    clock-frequency = <400000>;  
  
    tps: tps@24 {  
        reg = <0x24>;  
    };  
  
    baseboard_eeprom: baseboard_eeprom@50 {  
        compatible = "at,24c256";  
        reg = <0x50>;  
        #address-cells = <1>;  
        #size-cells = <1>;  
        baseboard_data: baseboard_data@0 {  
            reg = <0 0x100>;  
        };  
    };  
};
```

↳ Pin muxing configuration  
(routing to external package pins)

↳ Enabling this device, otherwise ignored

↳ Node property: frequency

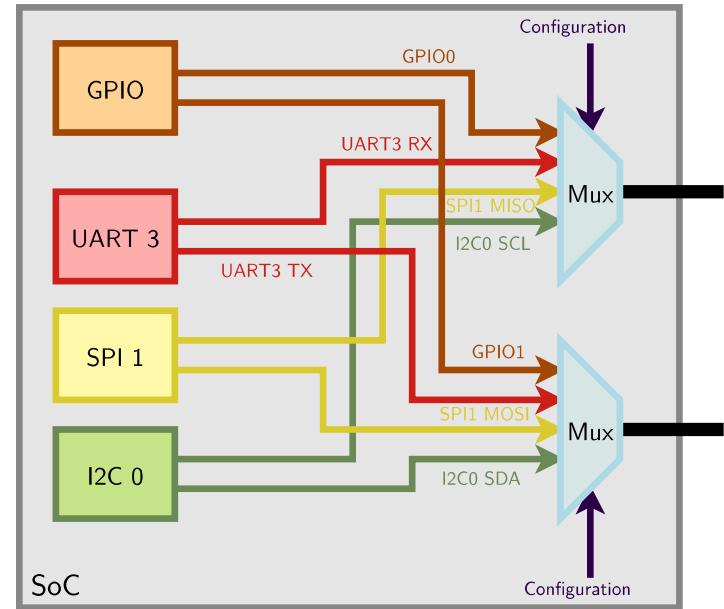
↳ I2C bus identifier

↳ List of devices on i2c0

From arch/arm/boot/dts/am335x-boneblue.dts

# Pin multiplexing

- Modern SoCs have too many hardware blocks compared to physical pins exposed on the chip package.
- Therefore, pins have to be multiplexed
- Pin configurations are defined in the Device Tree
- Correct pin multiplexing is mandatory to make a device work from an electronic point of view.



# Device Tree

- See kernel documentation for bindings
  - [devicetree/bindings/eeprom/eeprom.txt](#)
- Local copies enable you to extend on the fly
  - [/opt/source/dtb-4.9-ti](#)
  - [/opt/source/bb.org-overlays](#)
- Overlays loaded in u-boot, but also possible via kernel configfs

# DT pin definitions

```
&am33xx_pinmux {  
    ...  
    i2c0_pins: pinmux_i2c0_pins {  
        pinctrl-single,pins = <  
            AM33XX_IOPAD(0x988, PIN_INPUT_PULLUP | MUX_MODE0) /* (C17) I2C0_SDA.I2C0_SDA */  
            AM33XX_IOPAD(0x98c, PIN_INPUT_PULLUP | MUX_MODE0) /* (C16) I2C0_SCL.I2C0_SCL */  
        >;  
    };  
    ...  
};  
...  
  
&i2c0 {  
    pinctrl-names = "default";  
    pinctrl-0 = <&i2c0_pins>;  
  
    status = "okay";  
    clock-frequency = <400000>;  
    ...  
};
```

Register offset corresponding to a given package pin  
Allows to select a given SoC signal  
Configures the pin:  
input, output, drive strength, pull up/down...  
Package pin name  
SoC signal name

From arch/arm/boot/dts/am335x-boneblue.dts

# DT: matching devices and drivers

Platform drivers are matched with platform devices that have the same compatible property.

```
static const struct of_device_id omap_i2c_of_match[] = {
    {
        .compatible = "ti,omap4-i2c",
        .data = &omap4_pdata,
    },
    {
        ...
    };
    ...
    static struct platform_driver omap_i2c_driver = {
        .probe          = omap_i2c_probe,
        .remove         = omap_i2c_remove,
        .driver         = {
            .name      = "omap_i2c",
            .pm        = OMAP_I2C_PM_OPS,
            .of_match_table = of_match_ptr(omap_i2c_of_match),
        },
    };
};
```

From drivers/i2c/busses/i2c-omap.c

# config-pin

<https://github.com/beagleboard/bb.org-overlays - tools/beaglebone-universal-io>

```
debian@beaglebone:~$ config-pin -i p1.36
Pin name: P1_36
Function if no cape loaded: pwm
Function if cape loaded: default gpio gpio_pu gpio_pd
gpio_input spi_sclk pwm pruout pruin
Function information: ehrpwm0a default gpio3_14 gpio3_14
gpio3_14 gpio3_14 spi1_sclk ehrpwm0a pru0_out0 pru0_in0
Kernel GPIO id: 110
PRU GPIO id: 142
debian@beaglebone:~$ config-pin -q p1.36
P1_36 Mode: default Direction: in Value: 0
debian@beaglebone:~$ config-pin p1.36 pruout
debian@beaglebone:~$ config-pin -q p1.36
P1_36 Mode: pruout
```

# show-pins.pl

- perl /opt/scripts/device/bone/show-pins.pl -v

# Enabling PRU

- 2 possible drivers: remoteproc or uio
- Enabled via device tree at boot
  - Different systems might have different defaults

# mikroBus Click usage

- See [bbb.io/pbmb](http://bbb.io/pbmb)
- Supported with device-tree overlays loaded in u-boot

# Demonstrations

- BaconBits demo
-

# Some current projects

- Bela Mini
- PocketPilot

# Contributions and issues

- Cape/add-on support
  - <https://github.com/beagleboard/bb.org-overlays>
- Image deltas
  - <https://github.com/beagleboard/image-builder>
- In-system examples
  - <https://github.com/beagleboard/bone101>



# Questions?

# Thank you!

