Scalable k-means++

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Agenda

- The selected paper
- What is k-means?
- What is k-means++?
- What is k-means|| and how does it work?
- Runtime, tradeoff of quality with runtime
- Comparing the three algorithms via trials

Paper: Scalable K-Means++

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- Date: Thursday, March 29, 2012
- Venue: Proceedings of the VLDB Endowment (PVLDB), Vol. 5, No. 7, pp. 622-633 (2012)
- Problem Addressed: How to drastically reduce the number of passes needed to obtain, in parallel, a good initialization for the K-means algorithm.

What is k-means? - The Foundations and Motivations

- A solution to a problem in unsupervised learning
- Unsupervised learning: A preprocessor to organize the data for supervised learning
- The problem: clustering
 - O How can we group data points?

What do we need to figure out, to cluster data?

- How many clusters? k
- What makes a clustering algorithm good?
 - The points in a cluster should be close to each other.
 - Each cluster should be far apart.
 - Efficiency
- How are we going to cluster?
 - Lloyd's Algorithm

Lloyd's Algorithm

Algorithm 1 Lloyd's Algorithm $\mu_1, \ldots, \mu_k \leftarrow \text{randomly chosen centers}$ while Objective function still improves do $S_1,\ldots,S_k \leftarrow \phi$ for $i \in 1, \ldots, n$ do $j \leftarrow \arg\min_{j'} \|x_i - \mu_{j'}\|^2 \}$ add i to S_i end for for $j \in 1, \ldots, k$ do $\mu_j = \frac{1}{|S_i|} \sum_{i \in S_j} x_i$ end for end while

Visually, we have an idea of a clustering.



For example:



Now let's try clustering using Lloyd's algorithm.



First, we randomly select k centers. Here, we are using Google's random number generator.







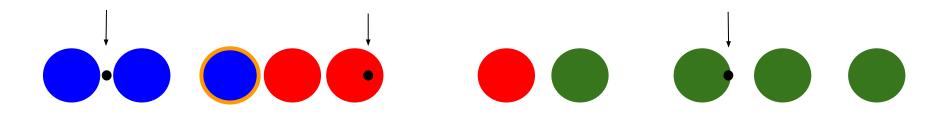




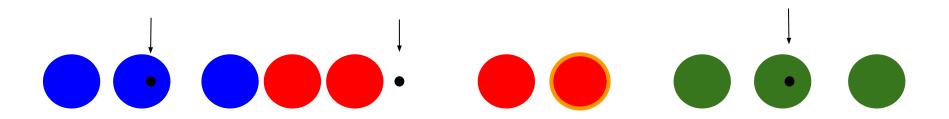
Next, we group the data points into k clusters, based on their distances to the centers.



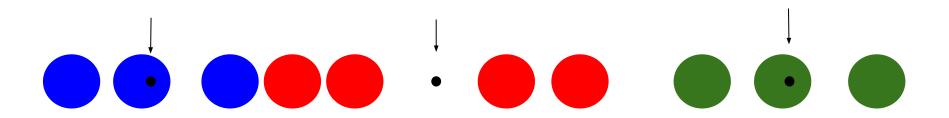
Then we calculate the mean of each cluster, make it the center, and recluster.



The clusters were modified, so we repeat the process. Here are the new means and clusters.

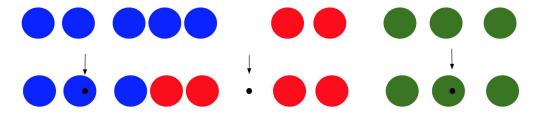


In this iteration, however, no updates were made. Therefore, we are done with the algorithm.



The Problems with k-means

Different (and worse) clusterings can result, as seen in the previous example.



- Due to randomization, it is likely that we initialize multiple centers in the same cluster.
- It can take a while to converge, especially with large datasets.
- Lloyd's Algorithm is NP-hard
- Assuming fixed dimensions, the runtime is O(nkdi), where n is the number of vectors of dimension d,
 k is the number of clusters, and i is the number of iterations until convergence.
- What would a better algorithm accomplish?

An improvement on k-means: k-means++

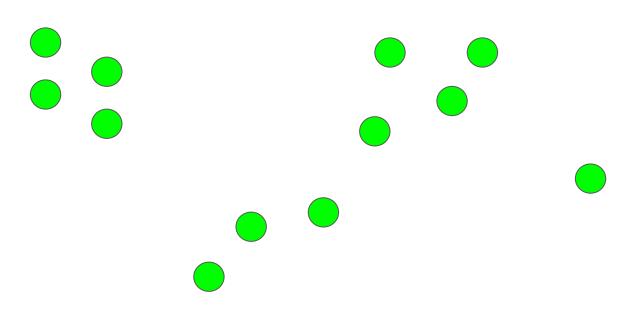
- What does it do?
 - Clusters points based off distance to all current clusters
 - o Points are chosen with probabilities proportional to their distances from other centers
 - Guarantees clusters are far away
- Is this better than Lloyd's algorithm?
 - Significantly more accurate
 - Scales better than Lloyd's (but still not scalable)
 - O(nkd) initialization

K-means++ Initialization Algorithm

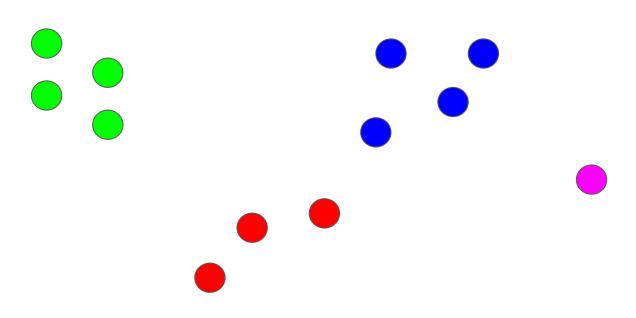
Algorithm 1 k-means++(k) initialization.

- 1: $\mathcal{C} \leftarrow$ sample a point uniformly at random from X
- 2: while $|\mathcal{C}| < k$ do
- 3: Sample $x \in X$ with probability $\frac{d^2(x,C)}{\phi_X(C)}$
- 4: $\mathcal{C} \leftarrow \mathcal{C} \cup \{x\}$
- 5: end while

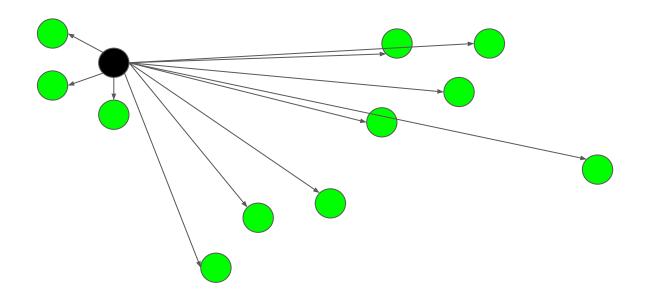
Now let's try clustering in two dimensions



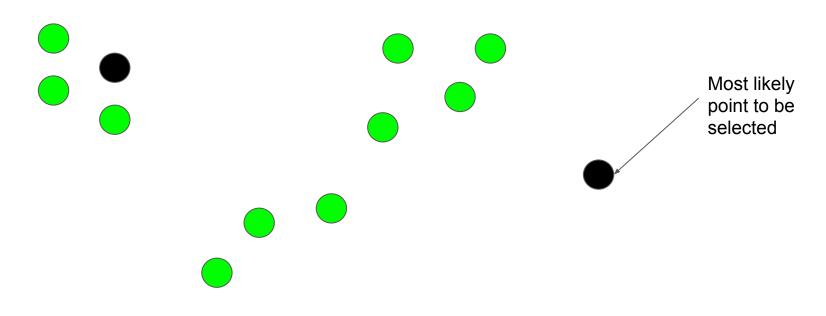
Potential clustering of the data



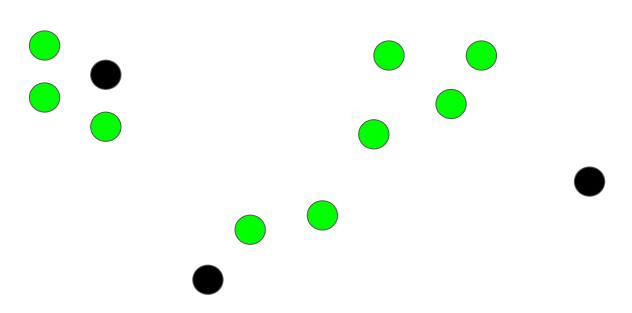
K-means++ starts by picking a random center, then calculates distances



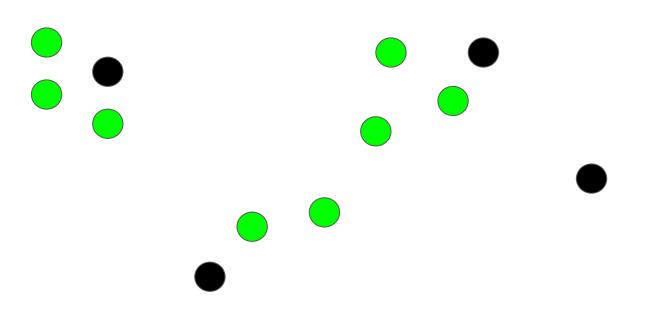
Then it picks another center with probability proportional to distance



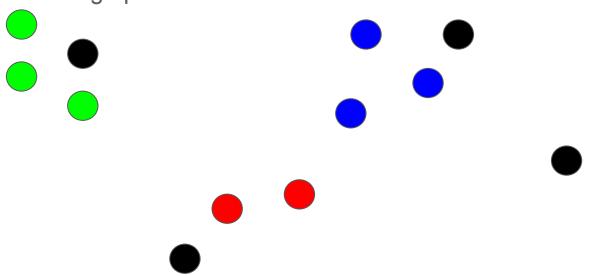
Recalculates distances, and picks new center



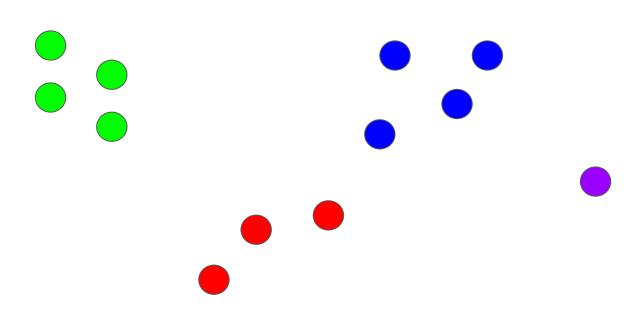
Recalculates the distances to all points from these 3 centers, then picks 4th center



Now that we have k centers we calculate the distance from each point to each center and assign points to cluster with their nearest center.



Now k-means++ has finished!



Problems with k-means++

- 1. K-means++ needs to pass over the data k times
 - a. Picks only one center at each iteration
- K-means++ is sensitive to outliers
 - a. Outliers have higher probability of being chosen

How can we fix these problems?



Possible first center

Most likely third center

The fix: Scalable k-means, or k-means||

Essential changes:

- 1. Oversampling factor *l*
 - a. *l* determines the number of points we pick in each round
- 2. $(log \psi)$ iterations
 - a. Depends on the clustering time of the first initialization
 - b. $(log \psi) \ll k$
 - c. $O(ndlog(\psi))$ initialization

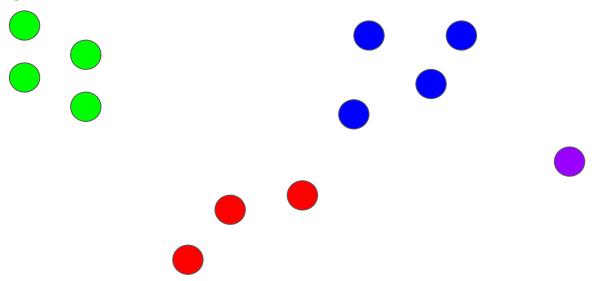


K-means|| algorithm

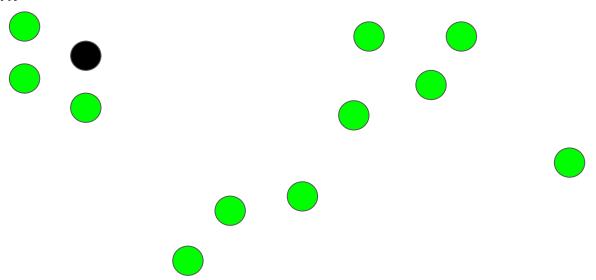
Algorithm 2 k-means $||(k, \ell)|$ initialization.

- 1: $\mathcal{C} \leftarrow$ sample a point uniformly at random from X
- 2: $\psi \leftarrow \phi_X(\mathcal{C})$
- 3: for $O(\log \psi)$ times do
- 4: $C' \leftarrow \text{sample each point } x \in X \text{ independently with probability } p_x = \frac{\ell \cdot d^2(x,C)}{\phi_X(C)}$
- 5: $\mathcal{C} \leftarrow \mathcal{C} \cup \mathcal{C}'$
- 6: end for
- 7: For $x \in \mathcal{C}$, set w_x to be the number of points in X closer to x than any other point in \mathcal{C}
- 8: Recluster the weighted points in \mathcal{C} into k clusters

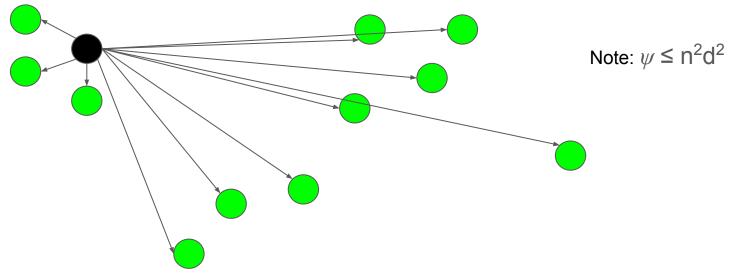
Let's use a familiar example to show the difference between k-means|| and k-means++.



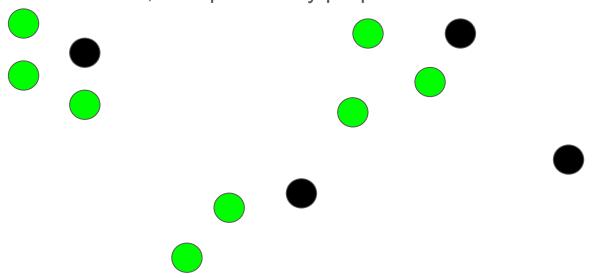
Similar to k-means++, k-means|| randomly selects the first center uniformly at random.



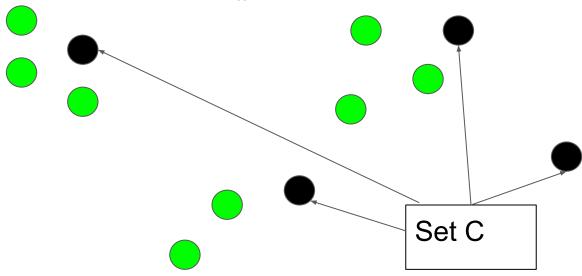
Next we compute the distances to all other points and save the cost of this computation in ψ , which determines the number of iterations we perform.



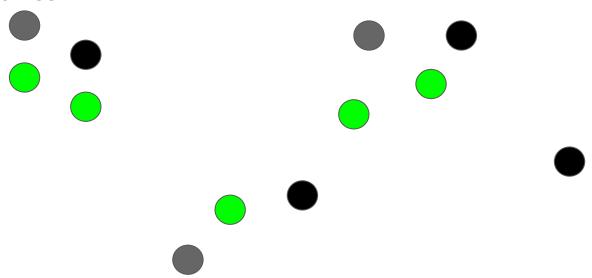
Now we do not pick 1 new center (as k-means++ would), but we rather pick *l* points, in this case 3, with probability proportional to distance.



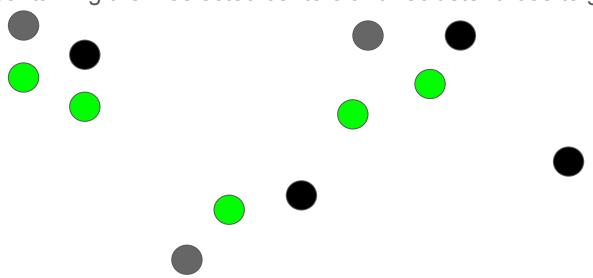
Then we compute the distances between all points and these centers. K-means++ would stop here but k-means|| will often calculate more than k centers.



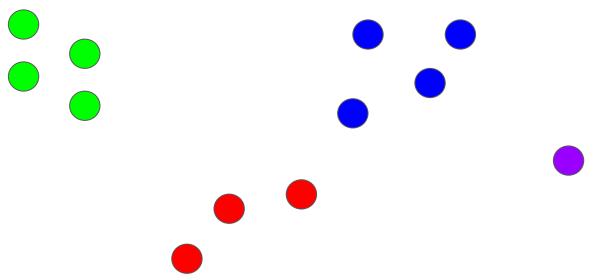
So now we pick l more centers and we repeat the process until we have iterated $log(\psi)$ times.



Let's say $log(\psi) = 2$ and that we are done picking centers, we know evaluate the set C containing the 7 selected centers and recluster those to get k centers.



We can use Lloyd's algorithm or k-means++ to recluster the 7 centers and get these clusters.



Differences

K-means++	K-means
K iterations over the dataset	$\log(\psi)$ iterations where $\psi \le n^2 d^2$, scales well
Adds one center per iteration	Adds multiple centers (<i>l</i> centers) per iteration
Calculates exactly k centers	Calculates more than k centers due to oversampling of the data

These runtime differences are nice but with so few iterations being run, can we expect accurate results?

To Do

According to https://www.cs.rpi.edu/~gittea/teaching/fall2020/project.html

- What is the main result of the paper?
- Describe the result or algorithm and motivate it intuitively.
- What is the cost (time, space, or some other metric) of this algorithm, and how does it compare to prior algorithms for the same problem? (and similarly, for non-algorithmic results)
- What performance guarantees, if any, are provided for the algorithm?
- Give an accurate description of the analysis given in the paper: in simple cases this may be a tour through the entire argument; when this is not possible, focus on explaining a core lemma/theorem that supports the claim of the paper.
- Provide an empirical evaluation of the algorithm: compare its performance to reasonable baselines, and explore relevant aspects of the algorithm (its variability, sensitivity to relevant properties of the input, etc.). If presenting a non-algorithmic result and it is possible, provide some experimental evidence of its sharpness or lack thereof.

Experiments

Conclusion/Big Picture

- K-means|| and k-means++ are accurate
 - a. Both find centroids that are better than random initialization
 - b. The selected centers are much less likely to be part of the same cluster
- 2. K-means|| scales well with its few iterations
 - a. Scales down the number of iterations on large data sets (i.e., $n > 10^9$) to be magnitudes smaller than k-means++
 - b. By decreasing the size of the data, through distribution, problems can be solved more quickly
- 3. K-means|| is applicable in many real-world unsupervised learning situations.
 - a. Whether it's credit fraud detection, organizing featureless data (or data with very few features), or any sort of data analysis, k-means|| can be a useful way for preprocessing the data for supervised learning.

Sources

- Bahmani, Moseley, Vattani, Kumar, Vassilvitskii, Scalable K-Means++, arXiv:1203.6402 [cs.DB] -- The paper that inspired this presentation
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- Seif, The 5 Clustering Algorithms Data Scientists Need to Know, Towards Data Science
- Professor Edo Liberty, Lecture 10: k-means clustering, Algorithms in Data Mining, Yale University
- Arthur, Vassilvitskii, K-means++: The Advantages of Careful Seeding, SODA
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