Towards Decentralized Proof-of-Location

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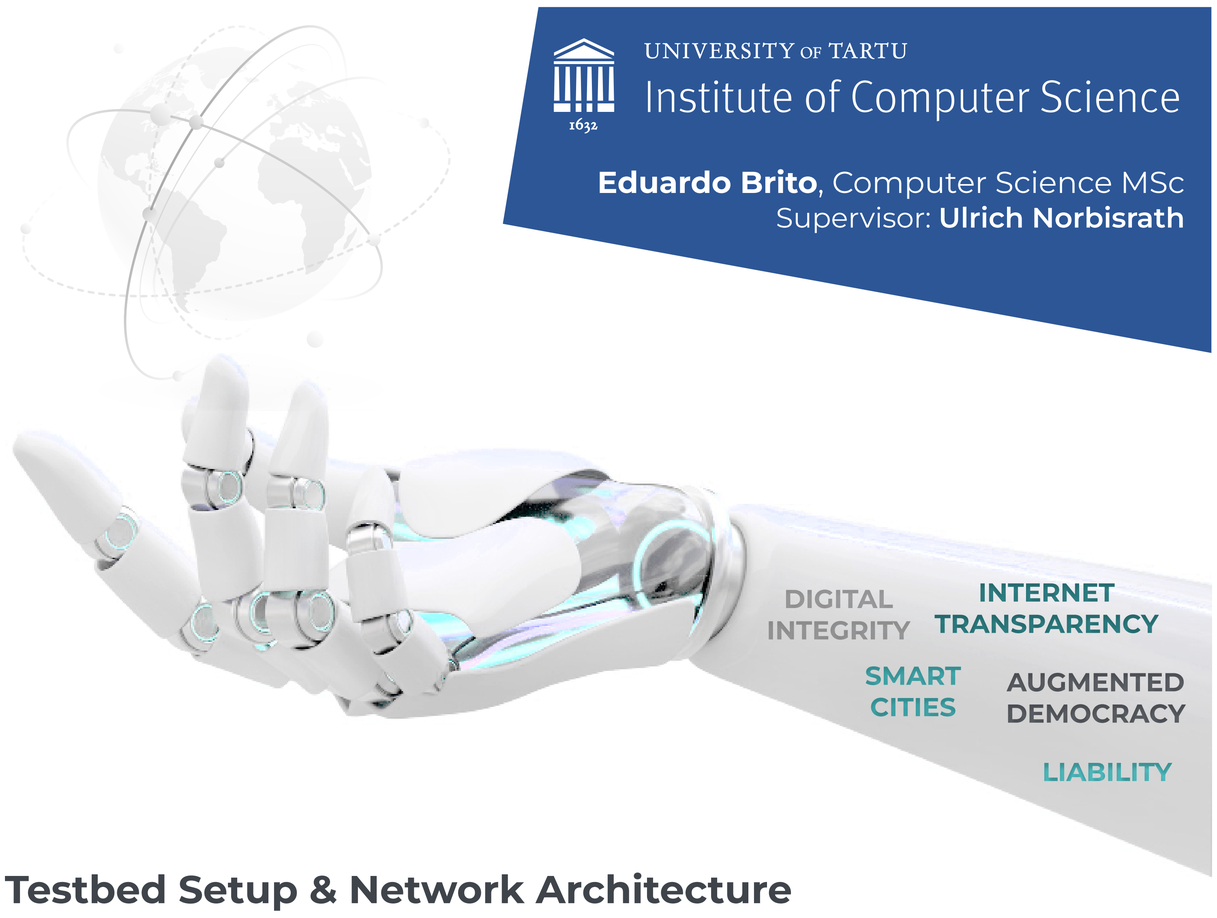
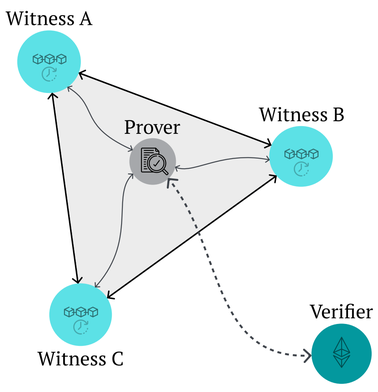
Making use of **mesh network technologies** and **permissionless consensus mechanisms**, we present a novel **decentralized Proof-of-Location protocol** and the implementation of a **proof-of-concept**, showing the achievement of **space and time synchronization** and the generation of **complete, verifiable, and spatio-temporally sound** location proofs.



With the present surge of highly realistic generative AI tools, how would Joe Biden **prove the authenticity** of his review of that pizza place, or the Pope, after buying that brand new fancy jacket? How would a reporter **certify the integrity** of his pictures and videos, or a service provider prove the delivery or supply of goods, at a **specific location**?

How would you prove you are here, right now, reading this poster?

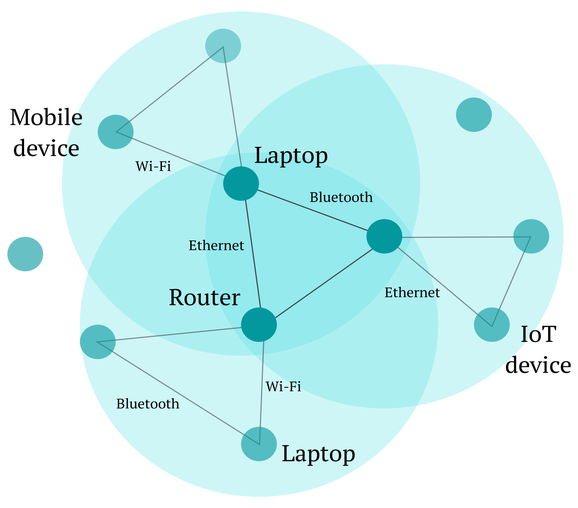


A digital Proof-of-Location

is an electronic certificate that attests one's position in both space and time.

A **prover** engages in a short-range communication protocol with nearby participants, the **witnesses**, with the goal of gathering a verifiable Proof-of-Location claim, to be later presented to a **verifier**, therefore convincing it of one's existence within a geographical area, at a given moment.

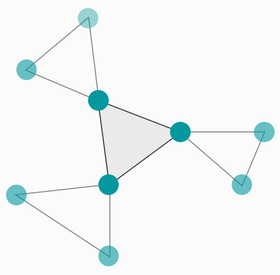
Dynamic Mesh Networks



In mesh topologies, nodes are directly and dynamically connected, in a **non-hierarchical** way. This trait allows for peer-to-peer communication between devices, to efficiently route the data. The mesh nodes are expected to **dynamically** self-organize and self-configure.

Mesh networks enable decentralized and short-range exchange of messages, leading to space synchronization.

Space Synchronization



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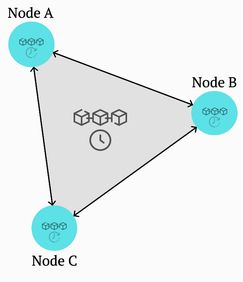
Time Synchronization



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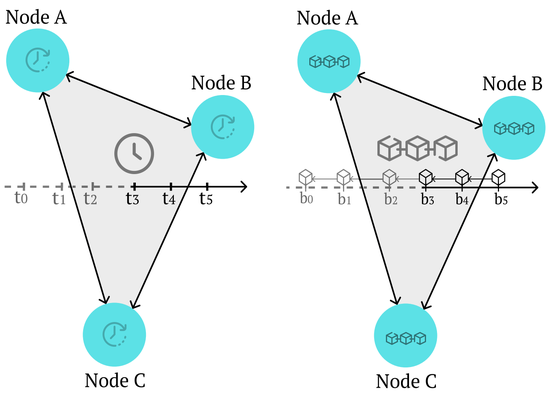
Trustless Proof-of-Location

Turing-Complete Clock Synchronization

In **decentralized and trustless** environments, achieving time synchronization

is the problem of achieving permissionless consensus, and the need for **ordering and synchronizing** events at the same pace, when participants are **not necessarily trusted**. Permissionless consensus with a Turing Complete system enables the decentralized and **time-conscious** agreement on the execution of arbitrary logic.

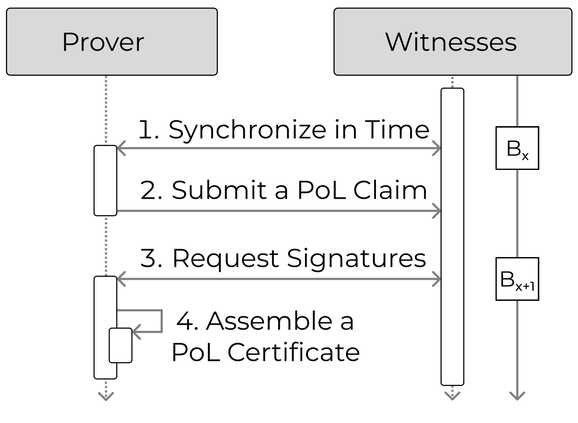


With the establishment of short-range communication and internal clock synchronization, one can now generate

complete, verifiable and spatio-temporally sound location claims, achieving decentralized Proof-of-Location.

The verification process requires the nodes' public keys and the Proof-of-Location certificate, just like any **digital signature verification**, integrated with applications of all kinds.

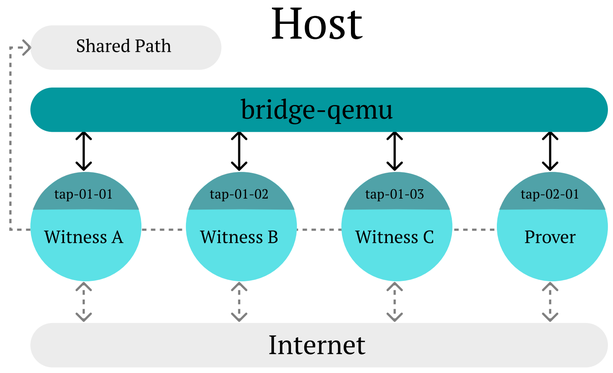
Verifiable Proof-of-Location



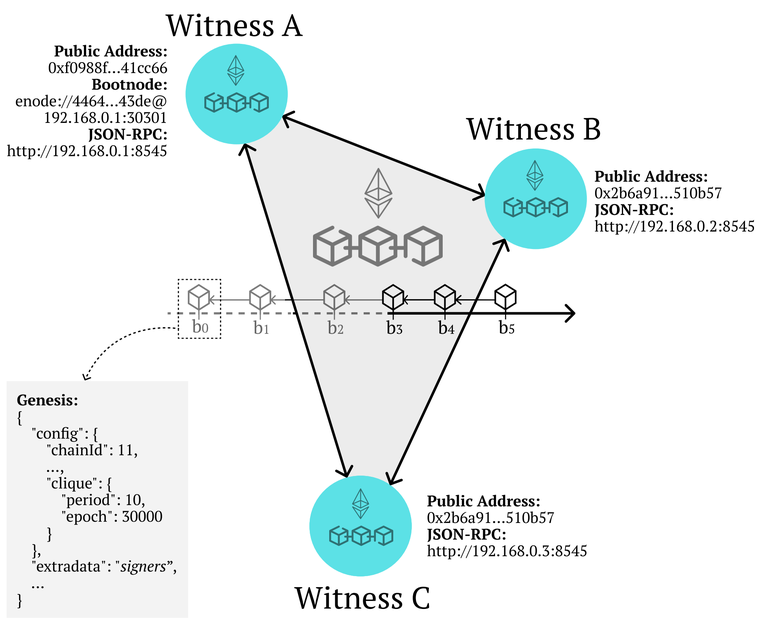
Testbed Setup & Network Architecture

The setup was emulated using **QEMU**. Each node ran **OpenWrt** as the OS, and **batman-adv** as layer 2 routing protocol for mesh networking.

The instances are connected to a **bridge interface**, pooling all the raw mesh traffic, simulating the physical medium. Each interface gets a **MAC address** and batman-adv is set up for the discovery of nodes, peer-to-peer connections, and the **formation of a witnessing zone**. Taking advantage of the TCP/IP suite of protocols and by **subnetting**, the typical Internet connections are enabled on top of the peer-to-peer mesh network topology.



Practical Permissionless Consensus



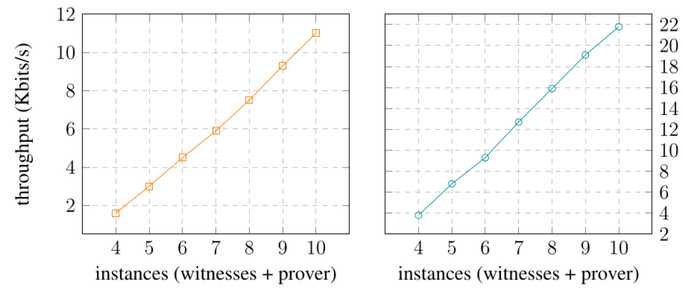
Ethereum was the chosen **blockchain** framework. The ad-hoc network was configured via the Genesis file, choosing a **consensus protocol** and some network rules, f.e., the **block time**. The nodes exposed API endpoints for the discovery of neighbors and peer-to-peer connections.

The Ethereum nodes started producing new blocks, achieving **time synchronization**.

The proof generation and verification processes were automated via **smart contracts**, written in Solidity and running in the EVM.

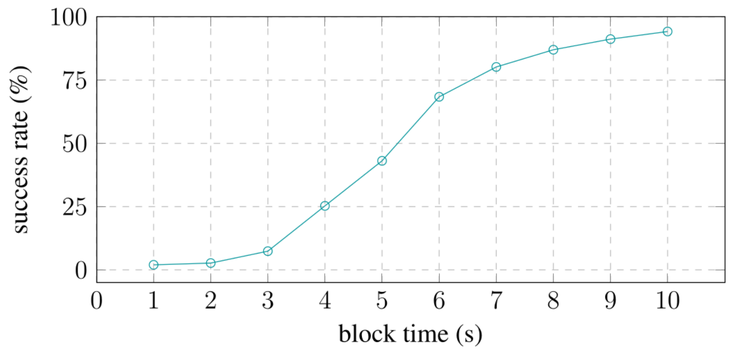
Performance Measurements

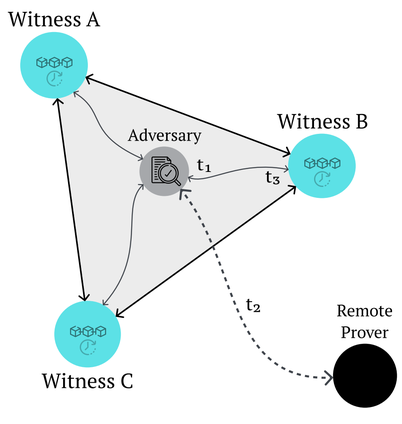
Both the **batman-adv** and the **IPv4** related protocols showed a seemingly **linear increase of the average throughput** with the increase in the number of witnesses. The blockchain traffic had low impact on the network overhead. CPU, RAM and Disk usages also showed **low resource consumption**, demonstrating the adaptability and suitability of the protocol to **resource-constrained environments**.



(a) Batman-adv traffic throughput. (b) IPv4 traffic throughput.

Attack Vectors





A more **permissive block time** allows for a **larger success rate**, but opens the possibility for the so-called **proxy attacks**: when an adversary has enough time to fetch the latest block, ask a remote prover for a signature, and submit a transaction. This allows to conclude that

the **block time** plays a crucial role in the soundness of the protocol.

Public repository:
https://github.com/edurbrito/proof-of-location