

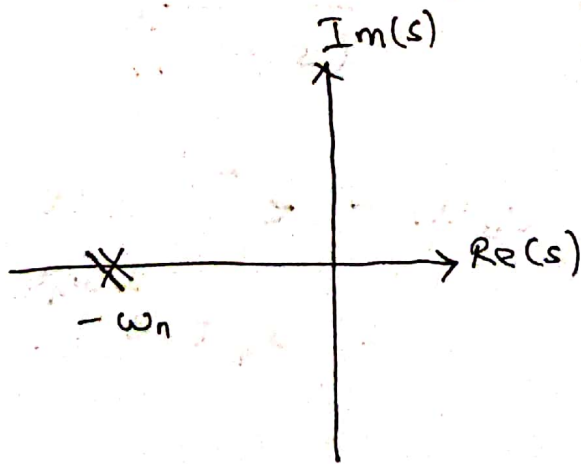
Case III $\zeta = 1$ Critically Damped

$$G(s) = \frac{\omega_n^2}{s^2 + 2\omega_n s + \omega_n^2}$$

$$= \frac{\omega_n^2}{(s + \omega_n)^2}$$

Poles of system \Rightarrow Roots of $(s + \omega_n)^2 = 0$

Two Poles are at $p_{1,2} = -\omega_n$
on Real Axis.



Impulse Response of the system

$$g(t) = \omega_n^2 t \cdot e^{-\omega_n t} \quad \text{for } t \geq 0.$$

$$g(t) \rightarrow 0 \quad \text{as } t \rightarrow \infty.$$

Step Response of SSOs when $\zeta = 1$

$$Y(s) = G(s) \cdot U(s)$$

$$= \frac{1}{s} \cdot \frac{\omega_n^2}{(s^2 + 2\omega_n s + \omega_n^2)}$$

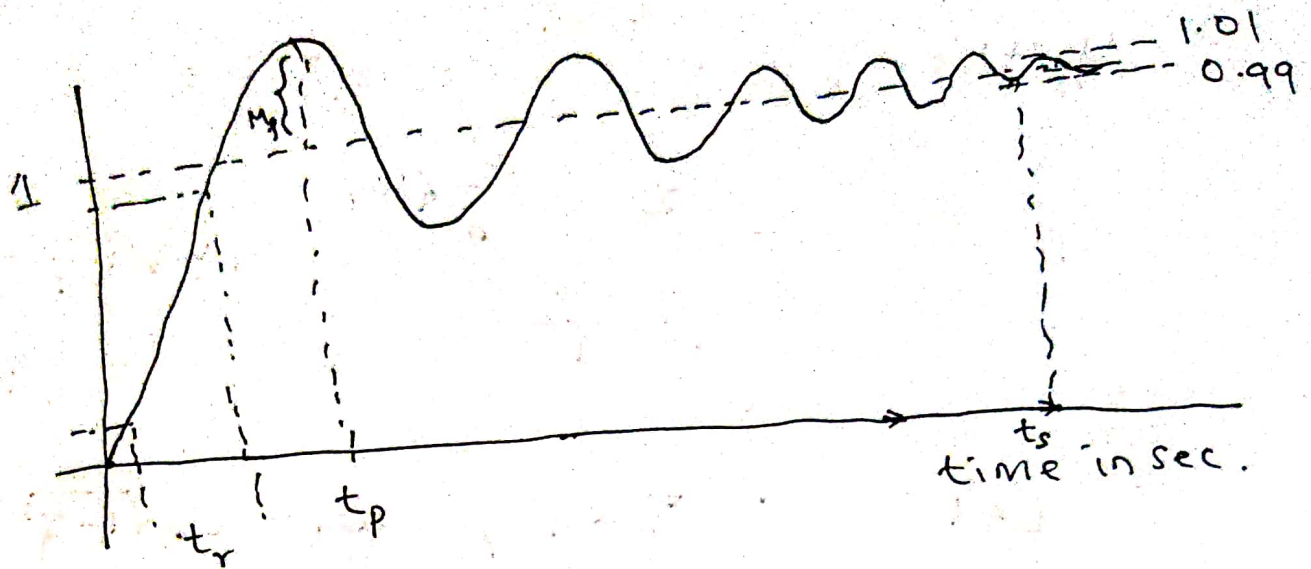
$$= \frac{A}{s} + \frac{Bs + C}{(s^2 + 2\omega_n s + \omega_n^2)}$$

$$A = 1 \quad B = -1 \quad C = -2\omega_n$$

$$Y(s) = \frac{1}{s} - \frac{(s + \omega_n)}{(s + \omega_n)^2} - \frac{\omega_n}{(s + \omega_n)^2}$$

$$\therefore y_s(t) = u_s(t) - e^{-\omega_n t} u_s(t) - \omega_n t e^{-\omega_n t} \cdot u_s(t)$$

Time Domain Specifications:



Rise Time: t_r Time taken by the step response to rise from 5% of steady state value to 95% of steady state value.

$$t_r \approx \frac{1.8}{\omega_n}$$

Peak Time: t_p Time at which step response of the system is maximum value.

$$y_s(t_p) = y_{\max}$$

$$y_s(t) = 1 - e^{-\zeta \omega_n t} \cos \omega_n \sqrt{1-\zeta^2} t - \frac{\zeta}{\sqrt{1-\zeta^2}} e^{-\zeta \omega_n t} \sin \omega_n \sqrt{1-\zeta^2} t \quad \text{for } t \geq 0.$$

$$\text{Let } \sigma = \zeta \omega_n, \quad \omega_d = \omega_n \sqrt{1-\zeta^2}$$

$$y_s(t) = 1 - e^{-\sigma t} \cos \omega_d t - \frac{\sigma}{\omega_d} e^{-\sigma t} \sin \omega_d t$$

$$\frac{dy_s(t)}{dt} = 0 \quad \text{when } t = t_p.$$

$$\therefore 0 = 0 - \left\{ e^{-\sigma t} (-\sin \omega_d t) \omega_d - \sigma e^{-\sigma t} \cos \omega_d t - \frac{\sigma}{\omega_d} \left\{ e^{-\sigma t} \cos \omega_d t \omega_d - \sigma e^{-\sigma t} \sin \omega_d t \right\} \right.$$

$$0 = \sin \omega_d t \left\{ e^{-\sigma t} \right\} \left\{ 1 + \frac{\sigma^2}{\omega_d^2} \right\}$$

$$\boxed{\omega_d t_p = \pi}$$

$$\boxed{t_p = \frac{\pi}{\omega_n \sqrt{1-\zeta^2}}}$$

Overshoot in % $M_p = e^{-\pi \zeta / \sqrt{1-\zeta^2}}$

Definition $M_p = \frac{y_{\max} - y_{ss}}{y_{ss}} \times 100$

$y_{\max} = \text{Maximum of } y_s(t)$

$y_{ss} = \text{steady state value of } y_s(t)$

$y_{\max} = y_s(t_p)$

$= 1 + e^{-\zeta \omega_n t_p}$

$= 1 + e^{-\pi \zeta / \sqrt{1-\zeta^2}}$

$\therefore \text{When } y_{ss} = 1$

$M_p = \frac{1 + e^{-\pi \zeta / \sqrt{1-\zeta^2}} - 1}{1} \times 100$

$$M_p = e^{-\pi \zeta / \sqrt{1-\zeta^2}}$$

Settling Time: t_s Time at which
step response enters 99% of y_{ss} .

When $y_{ss} = 1$

$$y_s(t) = 0.99 \text{ or } 1.01.$$

$$e^{-\zeta \omega_n t_s} \approx 0.01$$

$$t_s \approx \frac{4.6}{\zeta \omega_n}$$