

A vector space (or linear space) consists of the following

- 1) a field F of scalars
- 2) a set V of objects called vectors
- 3) a rule (or operation) called vector addition

The sum of u & v denoted by $u+v$, is in V

- i) $u+v = v+u$
- ii) $(u+v)+w = u+(v+w)$
- iii) There is a zero vector 0 in V such that $u+0 = u$
- iv). For each u in V , there is a vector $-u$ in V such that $u+(-u) = 0$.

- a operation called scalar multiplication

The scalar multiple of u by c denoted by cu , is in V

$$v) c(cu+v) = cu + cv$$

$$vi) (c+d)u = cu + du$$

$$vii) c(du) = (cd)u$$

$$viii). 1u = u$$

A vector space is a composite object consisting of a field, a set of vectors and two operations with certain special properties. The same set of vectors may be part of number of distinct vector spaces

Vector spaces as V or when we have to specify with the field we call it has a vector space over the field F .

Show that

For $n > 0$, the set of polynomials P_n of degree at most n consists of all polynomials of the form

$$p(t) = a_0 + a_1 t + a_2 t^2 + a_3 t^3 + \dots + a_n t^n \quad \text{--- (1)}$$

a_0, a_1, \dots, a_n & t are real numbers is a vector space.

Soln: The degree of P is the highest power of t whose coefficients are not zero.

$$p(t) = a_0 \quad \text{where } a_0 \neq 0 \rightarrow \text{degree of polynomial is zero}$$

If all the co-efficients are zero, p is called a zero polynomial

\therefore Zero polynomial exists in the group of polynomials

$$\text{Let } q(t) = b_0 + b_1 t + b_2 t^2 + b_3 t^3 + \dots + b_n t^n \quad \text{--- (2)}$$

$$\text{addition: } (p+q)(t) = (a_0+b_0) + (a_1+b_1)t + \dots + (a_n+b_n)t^n$$

$a_0, \dots, a_n, b_0, \dots, b_n$ are real no. a_0+b_0, a_1+b_1, \dots are also real nos. they exist.

$\therefore (p+q)$ polynomial $\in P_n$.

The scalar multiple of p i.e C_p is a polynomial defined by

$$C_p(t) = c_0 + c_1 t + \dots + (c_n)t^n$$

co-efficients are real nos $c_0 \rightarrow$ exists.

$(C_p)t$ is a polynomial in P_n

to get a negative of polynomial multiply by scalar whose value = -1 \Rightarrow

$$(-1)p(t) = -(a_0 + a_1 t + a_2 t^2 + \dots + a_n t^n)$$

$$-p(t) = -a_0 - a_1 t - \dots - a_n t^n \in P_n$$

$\therefore P_n$ is a vectorspace.

→ The n -tuple space F^n . Let F be any field, let V be the set of all n -tuples $\alpha = (x_1, x_2, \dots, x_n)$ of scalars x_i in F .

If $\beta = (y_1, y_2, \dots, y_n)$ with y_i in F , the sum of α and β is defined by

$$\alpha + \beta = (x_1 + y_1, x_2 + y_2, \dots, x_n + y_n)$$

The product of a scalar c and vector α is defined by

$$c\alpha = (cx_1, cx_2, \dots, cx_n)$$

It satisfies all the conditions of vector addition & scalar multiplication

→ Check whether the space of $m \times n$ matrices $F^{m \times n}$ $F \rightarrow$ field. is a vector space

Subspaces

Defn Let V be a vectorspace over the field F . A subspace of V is a subset W of V which is itself a vectorspace over F with the operations of vector addition and scalar multiplication in V .

The subset W of V is a subspace if

i) for each α & β in W the vector $\alpha + \beta$ is again in W .

ii) The 0 vector is in W .

iii) for each α in W the vector $(-\alpha)$ is in W .

iv) for each α in W and each scalar c the vector $c\alpha$ is in W .

v) All the commutativity and associativity of vector addition & scalar multiplication are same, since these properties are of the operation on V .

Theorem 1

A non-empty subset W of V is a subspace of V iff for each pair of vectors α, β in W and each scalar c in F the vector $c\alpha + \beta$ is again in W . (22)

Proof 1: Suppose that W is a non-empty subset of V such that

$$c\alpha + \beta \in W \quad \forall \alpha, \beta \text{ in } W \text{ and all scalar } c \text{ in } F$$

Since W is an non-empty set, \varnothing is a vector in W .

$$\therefore (-1)\varnothing + \varnothing = \varnothing \text{ is in } W.$$

If α is any vector in W and C is any scalar, the vector $C\alpha = C\alpha + 0$ is in W .

Thus $(-1)\alpha = -\alpha$ is in W

Finally if $\alpha \& \beta$ are in W , then $\alpha + \beta = (-1)\alpha + \beta$ is in W

thus W is a subspace of V

Conversely if W is a subspace of V , α and β are in W & c is a scalar such that $c\alpha + \beta$ is in W .

Alternately: Suppose W is a subset of a vector space V such

Proof 2: that $(c\alpha + \beta)$ is in W for every pairs of vectors α, β in W and every scalars c then we need to

Show that W is a vector space over F

Since W is a subset of vector space V , it inherits the properties of commutativity, associativity and all the rules of scalar multiplication from V .

It will become a subspace if only we can show that W contains the additive identity 0 and every vector $\alpha \in W$

Suppose $\varnothing \in W$, then for $C = -1$, $\alpha = \varnothing$ & $\beta = \varnothing$ wkt $c\alpha + \beta$ also is in W .

$$(-1)\varnothing + \varnothing = -\varnothing + \varnothing = \varnothing \text{ is in } W$$

Similarly for w in W , we choose $c = -1, d = 0, \beta = 0$

$$\text{We get } c\alpha + \beta = (-1)\alpha + 0 = -\alpha \in W$$

Thus we have shown that every vector belongs to W and every vector in W has additive inverse.

Here W is a subspace

Conversely, if W is a subspace, then $\alpha, \beta \in W$ & c is in field F means $c\alpha$ is in W & $c\alpha + \beta$ is in W .

① If V is any vectorspace, W is a subspace of V , the subset consisting of zero vector alone is a subspace of V , called the zero subspace of V .

Prove?

② In \mathbb{F}^n , the set of n -tuples (x_1, \dots, x_n) with $x_1 = 0$ is a subspace however, the set of n -tuples with $x_1 = 1 + x_2$ is not a subspace ($n \geq 2$)

③ The space of polynomial functions over the field F is a subspace of the space of all functions from F into F

④ An $n \times n$ (square matrix) A over the field F is symmetric if $A_{ij} = A_{ji}$ for each i and j . The symmetric matrices form a subspace of the space of all $n \times n$ matrices over F

⑤ An $n \times n$ (square) matrix A over the field C of complex numbers is Hermitian (or self adjoint) if

$$A_{jk} = \overline{A_{kj}}$$

for each j, k : the bar denoting complex conjugation.

A 2×2 matrix is Hermitian iff it has the form

$$\begin{bmatrix} z & x+iy \\ x-iy & w \end{bmatrix}$$

where x, y, z, w are real numbers

The solution space of a system of homogeneous linear equations

Let A be an $m \times n$ matrix over F

then the set of all $n \times 1$ (column) matrices X over F such that

$AX=0$ is a subspace of the space of all $n \times 1$ matrices over F

To prove this we must S.T $A(cx+y)=0$

when $AX=0$, $AY=0$ & c is an arbitrary scalar in F

Lemma :- If A is an $m \times n$ matrix over F and B, C are $n \times p$ matrices over F then

$$A(DB+C) = d(AB) + AC \text{ for each scalar } d \text{ in } F$$

Proof :-

$$[A(DB+C)]_{ij} = \sum_k A_{ik} (DB+C)_{kj}$$
$$= \sum_k [dA_{ik} B_{kj} + A_{ik} C_{kj}]$$

$$= d \sum_k A_{ik} B_{kj} + \sum_k A_{ik} C_{kj}$$

$$= d(AB)_{ij} + (AC)_{ij}$$

$$= [d(AB) + AC]_{ij} \rightarrow \text{Refer Page - 50}$$

Theorem 2 :- Let V be a vectorspace over the field F . The intersection of any collection of subspaces of V is a subspace of V .

Proof :- Let $\{W_a\}$ be a collection of subspaces of V and

$$\boxed{W = \bigcap_a W_a}$$
 be their intersection

i.e. W contains set of all the elements belonging to every W_a

Each W_a is a subspace it has a zero vector

\therefore Intersection of W_a i.e. W has a zero vector. W is a non empty set.

Let α and β be vectors in W . & c be a scalar

By defn of W both α & β belongs to each W_a and because each W_a has $(c\alpha + \beta)$ since it is a subspace in every W_a

$\therefore [c\alpha + \beta \text{ is in } W]$

Hence by Theorem 1 W is a subspace of V

→ Union of collection of subspaces need not be a subspace

Proof: Let us consider the x -axis and y -axis as the subspaces

W_1 and W_2 of the vector space R^2

Let $W = W_1 \cup W_2$ union of the x -axis and y -axis
 W is not a (subspace) vectorspace \because is not closed

under addition.

$\alpha \rightarrow (1, 0) \in W$, $\beta \rightarrow (0, 1) \in W$, $c=1$ scalar

$$\begin{aligned} c\alpha + \beta &= 1(1, 0) + (0, 1) \\ &= (1, 0) + (0, 1) \\ &= (1, 1) \notin W \end{aligned}$$

Refer page (26)

Defn of Subspace Spanned by Vectors

Let S be a set of vectors in a vectorspace V .

The subspace spanned by S is defined to be the intersection W of all subspaces of V which contains S . When

S is a finite set of vectors, $S = \{\alpha_1, \alpha_2, \dots, \alpha_n\}$ we

shall simply call W the subspace spanned by the vectors

$\alpha_1, \alpha_2, \dots, \alpha_n$

Theorem 3: The subspace spanned by a non-empty subset S of a vector space V is the set of all linear combinations of vectors in S .

Proof: Let W be the subspace spanned by S . If α is a linear combination of vectors in S then

$$\alpha = c_1 d_1 + c_2 d_2 + c_3 d_3 + \dots + c_m d_m$$

We can see that α is in W because W contains the linear combinations vectors in S .

Hence if L is the set of all linear combinations of vectors in S , L is in W .

Let α, β belongs to L , then α and β are linear combination of elements in S .

$$\alpha = \sum x_i d_i = x_1 d_1 + x_2 d_2 + \dots + x_m d_m$$

$$\beta = \sum d_i d_i = d_1 d_1 + d_2 d_2 + \dots + d_m d_m$$

$$\begin{aligned} \text{So } c\alpha + \beta &= cx_1 d_1 + cx_2 d_2 + cx_3 d_3 + \dots + cx_m d_m + d_1 d_1 \\ &\quad + d_2 d_2 + \dots + d_m d_m \\ &= (cx_1 + d_1) d_1 + (cx_2 + d_2) d_2 + \dots + (cx_m + d_m) d_m \end{aligned}$$

$$\therefore c\alpha + \beta \in L$$

$\therefore L$ is a subspace of V .

We also know that each $d_i \in S$ can be written as

$$d_i = 0 \cdot d_1 + 0 \cdot d_2 + 0 \cdot d_3 + \dots + 1 \cdot d_i + 0 \cdot d_{i+1} + 0 \cdot d_m$$

i.e d_i is also a linear combination of elements in S .

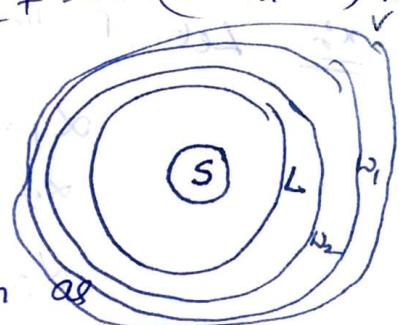
Hence each d_i in S is also in L , i.e. $S \subseteq L$

We have also seen that $L \subseteq W$

where $W \rightarrow$ Subspace Spanned by S

i.e $W = \cap W_i$ where each W_i contains S .

Thus L must be equal to W_i i.e L is the ~~subspace~~ subspace spanned by S .



Definition:-

If S_1, S_2, \dots, S_k are subsets of a vectorspace V , the set of all sums $\alpha_1 + \alpha_2 + \alpha_3 + \dots + \alpha_k$.

of vectors α_i in S_i is called the sum of the subsets S_1, S_2, \dots, S_k and is denoted by

$$S_1 + S_2 + S_3 + \dots + S_k$$

where p works

or
$$\sum_{i=1}^k S_i$$

If W_1, W_2, \dots, W_k are subspaces of V , then the sum $W = W_1 + W_2 + \dots + W_k$.

is a subspace of V which contains each of the subspaces W_i , it follows from the Thm ③ that W is a ~~subspace~~ subspace spanned by the union of W_1, W_2, \dots, W_k .

Ex:- Let F be a subfield of the field C of complex numbers.

$$\alpha_1 = (1, 2, 0, 3, 0)$$

$$\alpha_2 = (0, 0, 1, 4, 0)$$

$$\alpha_3 = (0, 0, 0, 0, 1)$$

By thm 3 α is in subspace W of F^5 spanned

by $\alpha_1, \alpha_2, \alpha_3$

$$\alpha = c_1 \alpha_1 + c_2 \alpha_2 + c_3 \alpha_3$$

$$\alpha = c_1(1, 2, 0, 3, 0) + c_2(0, 0, 1, 4, 0) + c_3(0, 0, 0, 0, 1)$$

$$= (c_1, 2c_1, 0, 3c_1, 0) + (0, 0, c_2, 4c_2, 0) + (0, 0, 0, 0, c_3)$$

$$= (c_1 + 2c_1, c_2, 3c_1 + 4c_2, c_3) \quad c_1, c_2, c_3 \text{ are scalars in } F$$

W can be set of all 5-tuples.
 $\alpha = (x_1, x_2, x_3, x_4, x_5)$

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With x_i in F such that

$$x_2 = 2x_1$$

$$x_4 = 3x_1 + 4x_2$$

$$x_1 = -3, x_2 = 1, x_3 = 2$$

$\alpha = (-3, -6, 1, -5, 2)$ is in W, whereas $(2, 4, 6, 7, 8)$ is not in W.

Example

Let F be a subfield of the field C of Complex nos.

Let V be the vectorspace of all 2×2 matrices over F.

Let W_1 be the subset V consisting of all matrices of the form

$$\begin{bmatrix} x & y \\ z & 0 \end{bmatrix}$$

where x, y, z are arbitrary scalars in F,

Let W_2 be the subset of V consisting of all matrices of the form $\begin{bmatrix} x & 0 \\ 0 & y \end{bmatrix}$

where x and y are arbitrary scalars in F,
 W_1 & W_2 are subspaces of V.

Also $V = W_1 + W_2$

$$\therefore \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a & b \\ c & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & d \end{bmatrix}$$

$$W_2 \Rightarrow \begin{bmatrix} 0 & 0 \\ 0 & d \end{bmatrix}$$

by $x=0$
 $y=d$.

Subspace $W_1 \cap W_2$ consists of all matrices of the form $\begin{bmatrix} x & 0 \\ 0 & 0 \end{bmatrix}$

Linear Combinations

v_1, v_2, \dots, v_n in \mathbb{R}^n

$$c_1 v_1 + c_2 v_2 + \dots + c_n v_n$$

$c_1 \rightarrow c_n$ vectors in \mathbb{R}^2

$$\vec{a} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \vec{b} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}, \vec{c} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$0 \cdot \vec{a} + 0 \cdot \vec{b} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

if

$$3\vec{a} + (-2)\vec{b} = \begin{bmatrix} 3 - 0 \\ 6 - 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 6 \end{bmatrix}$$

$$c_1 \quad c_2$$

\vec{a}, \vec{b} scaled by an arbitrary multiples. we can generate all vectors in \mathbb{R}^2 .

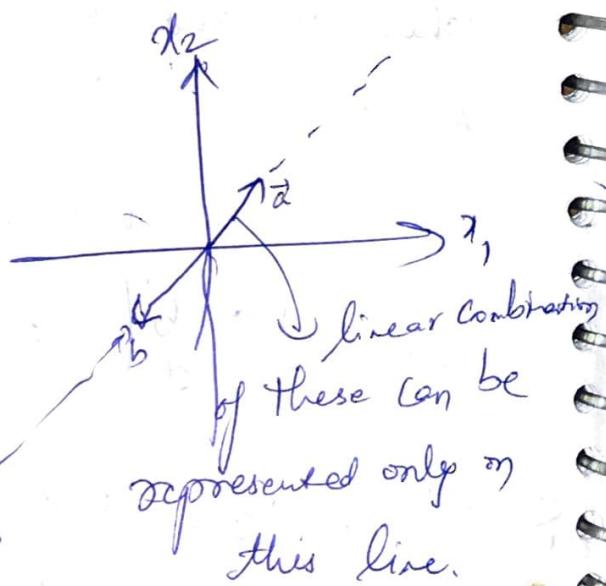
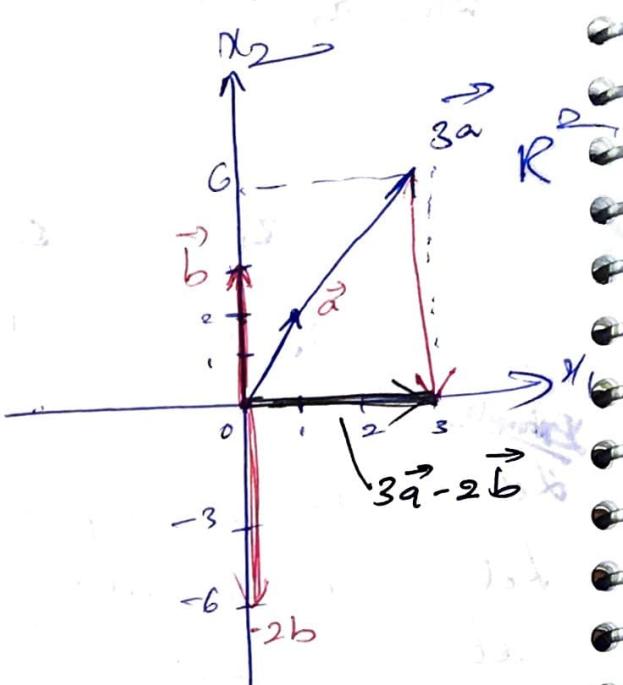
$$\text{Span}(\vec{a}, \vec{b}) = \mathbb{R}^2$$

i.e any vector in \mathbb{R}^2 can be represented by a linear combination of vector a & b .

Let $\vec{a} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}, \vec{b} = \begin{bmatrix} -2 \\ -2 \end{bmatrix}$ \rightarrow slope is same.

$\text{Span}(\vec{a}, \vec{b})$ is the line representing vectors \vec{a} and \vec{b} .

$\text{Span}(\vec{0}) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ \rightarrow its just a point at O .
i.e zero vector



$\text{Span}(v_1, v_2, \dots, v_m)$ The set of all the vectors linear combinations of vectors

$$\text{Span}(v_1, v_2, \dots, v_m) = \{c_1 v_1, c_2 v_2, \dots, c_m v_m \mid c_i \in \mathbb{F} \text{ for } i \leq m\}$$

Consider $\vec{a} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \vec{b} = \begin{bmatrix} 0 \\ 3 \end{bmatrix}, \vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

$$c_1 \vec{a} + c_2 \vec{b} = \vec{x}$$

$$c_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\boxed{c_1 = x_1}$$

$$2c_1 + 3c_2 = x_2$$

$$c_2 = \frac{x_2 - 2x_1}{3} \Rightarrow \frac{x_2 - 2x_1}{3}$$

\therefore We can get any value of c_1

Bases and Dimensions (Linearly Independent Sets)

Let V be a vector space over \mathbb{F} , An indexed set of vectors $\{v_1, v_2, \dots, v_p\}$ in V said to be linearly independent if the vector equation

$$c_1 v_1 + c_2 v_2 + \dots + c_p v_p = 0 \quad (1)$$

has only the trivial solution $c_1 = 0, c_2 = 0, \dots, c_p = 0$

A set $\{v_1, v_2, \dots, v_p\}$ is said to be linearly dependent

if eqn (1) has a non-trivial solution, i.e., if there are some scalars c_1, \dots, c_p not all zeros, such that (1) holds. In such a case eqn (1) is called a linear dependence relation among v_1, \dots, v_p .

Let V be a vectorspace over F , A subset S of V is said to be linearly dependent (or simply dependent) if there exists distinct vectors $\alpha_1, \alpha_2, \dots, \alpha_n$ in S and scalars c_1, c_2, \dots, c_n in F , not all of which are 0 such that

$$c_1\alpha_1 + c_2\alpha_2 + \dots + c_n\alpha_n = 0$$

A set which is not linearly dependent is called linearly independent. If the set S contains only finitely many vectors $\alpha_1, \alpha_2, \dots, \alpha_n$

- A set of n vectors is linearly dependent iff one of the vectors is a multiple of the other.
- Any set containing the zero vector is linearly dependent

Ex:- The set $(\sin t, \cos t)$ is linearly independent in $C([0, 1])$
as $\sin t$ and $\cos t$ are not multiples of one another as
 $(n+1)$ vectors in $C([0, 1])$

Basis :- Let V be a vectorspace, A basis for V is a linearly independent set of vectors in V which spans the space V .
The Space V is finite dimensional if it has a finite basis

Let H be a subspace of a vectorspace V . An indexed set of vectors $B = \{b_1, \dots, b_p\}$ in V is a basis for H if

- (i) B is a linearly independent set and
(ii) the subspace spanned by B coincides with H i.e.

$$H = \text{Span} \{b_1, \dots, b_p\}$$

Let A be an invertible $n \times n$ matrix $A = [a_1 \dots a_n]$ then ⁽²⁷⁾
 the columns of A form a basis for \mathbb{R}^n because they are
 linearly independent and they span \mathbb{R}^n , by the Invertible Matrix
 theorem

Let $e_1, e_2 \dots e_n$ be the columns of $n \times n$ identity matrix I_n
 i.e. $e_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$ $e_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}$... $e_n = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$

The set $\{e_1 \dots e_n\}$ is called the standard basis for \mathbb{R}^n

Let F be a subfield of the complex numbers \mathbb{C} .
 the vectors $\alpha_1 = (3, 0, -3)$ $\alpha_2 = (-1, 1, 2)$ $\alpha_3 = (4, 2, -2)$
 $\alpha_4 = (2, 1, 1)$ are linearly independent

$$2\alpha_1 + 2\alpha_2 - \alpha_3 + 0 \cdot \alpha_4 = 0.$$

the set $v_1 = \begin{bmatrix} 3 \\ 0 \\ -6 \end{bmatrix}$ $v_2 = \begin{bmatrix} -4 \\ 1 \\ 7 \end{bmatrix}$ $v_3 = \begin{bmatrix} -2 \\ 1 \\ 5 \end{bmatrix}$ Determine $\{v_1, v_2, v_3\}$
 is a basis in \mathbb{R}^3

If $A = [v_1 \ v_2 \ v_3]$ is invertible, then v_1, v_2, v_3 forms
 a basis in \mathbb{R}^3

$$A = \begin{bmatrix} 3 & -4 & -2 \\ 0 & 1 & 1 \\ -6 & 7 & 5 \end{bmatrix} \xrightarrow{R_3 + 2R_1} \begin{bmatrix} 3 & -4 & -2 \\ 0 & 1 & 2 \\ 0 & -1 & 1 \end{bmatrix} \xrightarrow{R_3 + R_2}$$

3 pivot positions
 matrix is invertible
 \therefore it forms
 a basis

$$\begin{bmatrix} 3 & -4 & -2 \\ 0 & 1 & 2 \\ 0 & 0 & 3 \end{bmatrix}$$

Let $S = \{1, t, t^2, \dots, t^n\}$. Verify that S forms a basis for P_n . This basis is called the standard basis of P_n .

$$C_0 \cdot 1 + C_1 t + C_2 t^2 + \dots + C_n t^n = 0 \quad (t) \quad \text{--- (1)}$$

A fundamental theorem in algebra says that the only polynomial in P_n with more than n zeros is the zero polynomial.

i.e. $C_0 = C_1 = \dots = C_n = 0$ (1) holds good only if all $C_0 = C_n = 0$

$\therefore S$ is linearly independent.
∴ this is a basis of P_n

Dimension of a finite dimensional vector space As the number of elements in a basis for V it is denoted by $\dim V$.

Find the dimension of the subspace spanned by vectors
 $(1, -2, 0, -1)$ $(2, 3, 0, -2, 0)$ &
 $(1, 2, 0, -4, 1)$ Find basis for that space.
 $(0, 1, 3, -3, 2)$

First we find basis and the dimension

$$\left[\begin{array}{ccccc} 1 & 1 & -2 & 0 & -1 \\ 1 & 2 & 0 & -4 & 1 \\ 0 & 1 & 3 & -3 & 2 \\ 2 & 3 & 0 & -2 & 0 \end{array} \right] \xrightarrow{\substack{R_2 - R_1 \\ R_3 - 2R_1}} \left[\begin{array}{ccccc} 1 & 1 & -2 & 0 & -1 \\ 0 & 1 & 2 & -4 & 2 \\ 0 & 1 & 3 & -3 & 2 \\ 0 & 1 & 4 & -2 & 2 \end{array} \right]$$

$$\left[\begin{array}{ccccc} 1 & 1 & -2 & 0 & -1 \\ 0 & 1 & 2 & -4 & 2 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{\substack{R_1 - R_2 \\ R_2 - R_3}} \left[\begin{array}{ccccc} 1 & -2 & 0 & -1 \\ 0 & 1 & 2 & -4 & 2 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 2 & 2 & 0 \end{array} \right] \xrightarrow{\substack{V \cdot R_2 - R_2 \\ R_4 - R_2}}$$

basis $(1, 1, -2, 0, -1)$
 $(0, 1, 2, -4, 2)$
 $(0, 0, 1, 1, 0)$.

$$\left[\begin{array}{ccccc} 1 & 1 & 0 & 2 \\ 1 & 2 & 1 & 3 \\ -2 & 0 & 3 & 0 \\ 0 & -4 & -3 & -2 \\ 1 & 1 & 2 & 0 \end{array} \right] \xrightarrow{\text{Operations}} \left[\begin{array}{ccccc} 1 & 1 & 0 & 2 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

↑ ↑ ↑
Basis.

Can't be considered

$$(1, 1, -2, 0, -1)$$

$$(1, 2, 0, -4, 1)$$

$$(0, 1, 3, -3, 2)$$

Independent columns of A :- The only solution $AV=0$
 ie $v=0$

$$\left[\begin{array}{ccc} 2 & 1 & 1 \\ 1 & 2 & 0 \\ 5 & 0 & 0 \end{array} \right]$$

Basis
for subspace.

Independent vector that
span the subspace.

Dimension is a number of basis vectors from the subspace

Theorem Let V be a vectorspace which is spanned by a finite set of vectors $\beta_1, \beta_2, \dots, \beta_m$. Then an independent set of vectors V is finite and contains no more than m elements.

Proof To prove the theorem it suffices to show that every subset S of V which contains more than m vectors, is linearly dependent.

Let S be such a set. i.e. $S = \{x_1, x_2, \dots, x_n\}$ where $n > m$.

Since $\beta_1, \beta_2, \dots, \beta_m$ span V , there exists scalars A_{ij} in F such that

$$x_j = \sum_{i=1}^m A_{ij} \beta_i$$

For any n scalars x_1, x_2, \dots, x_n ,

$$\begin{aligned} \text{We have } x_1 x_1 + x_2 x_2 + \dots + x_n x_n &= \sum_{j=1}^n x_j x_j \\ &= \sum_{j=1}^n x_j \sum_{i=1}^m A_{ij} \beta_i \\ &= \sum_{j=1}^n \sum_{i=1}^m x_j (A_{ij} \beta_i) \\ &\leq \sum_{j=1}^n \sum_{i=1}^m (x_j A_{ij}) \beta_i \\ &= \sum_{i=1}^m \sum_{j=1}^n (A_{ij} x_j) \beta_i \end{aligned}$$

If A is an $m \times n$ matrix & $m < n$, then the homogeneous system of linear equations has a non trivial soln

$$\therefore \sum_{j=1}^n (A_{ij} x_j) = 0 \quad 1 \leq i \leq m$$

i.e. x_1, x_2, \dots, x_n not all 0

$x_1 x_1 + x_2 x_2 + \dots + x_n x_n = 0$
This shows that S is a linearly dependent set.

Corollary If V is a finite dimensional vectorspace, then any two bases of V have the same (finite) number of elements. (29)

Since V is a finite dimensional, it has a finite basis $\{\beta_1, \beta_2, \dots, \beta_m\}$

By this every basis of V is finite and contains no more than on elements.

\Rightarrow Let V be a finite dimensional vectorspace and let $n = \dim V$. Then

(a) any subset of V contains no more than n vectors is linearly dependent

(b) no subset of V which contains fewer than n vectors can span V

Theorem If W is a subspace of a finite dimensional vector space V , every linearly independent subset of W is finite and is a part of (finite) basis for W .

Proof: Suppose S_0 is a linearly independent subset of W .

If S is linearly independent subset of W containing S_0 then S is also linearly independent subset of V .

~~(a)~~ V is finite dimensional, S contains no more than $\dim V$ elements

~~(b)~~ \Rightarrow if we extend S_0 to a basis for W .

If S_0 spans W , then S_0 is a basis for W .

If S_0 does not span W then find a vector β_1 in W such that

Set $S_1 = S_0 \cup \{\beta_1\}$ is independent.

If S_1 spans W then S_1 is a basis, else we find another vector $\beta_2 \dots$ in W

Such that $S_2 = S_1 \cup \{\beta_2\}$ is independent.

If we continue this way. (not more than $\dim V$ steps)

we reach a set

$$S_m = S_0 \cup \{\beta_1, \beta_2, \dots, \beta_m\}$$

which is a basis for W .

→ If W is a proper subspace of a finite dimensional vector space V , then W is a finite-dimensional and $\dim W < \dim V$

→ In a finite-dimensional vector space V every non-empty linearly independent set of vectors is a part of basis.

Theorem:- If W_1 and W_2 are finite dimensional subspaces of a vector space V , ~~$W_1 \cap W_2 = \{0\}$~~ Then $W_1 + W_2$ is finite dimensional and $\dim W_1 + \dim W_2 = \dim(W_1 \cap W_2) + \dim(W_1 + W_2)$

Proof:- $W_1 \cap W_2 \rightarrow$ finite basis $\{d_1, d_2, \dots, d_k\}$

which is a part of a basis

$\{d_1, \dots, d_k, \beta_1, \dots, \beta_m\}$ for W_1

and part of a basis of W_2

$\{d_1, \dots, d_k, \gamma_1, \dots, \gamma_n\}$ for W_2 .

The subspace $W_1 + W_2$ is spanned by the ~~all~~ vectors

$\{d_1, \dots, d_k, \beta_1, \dots, \beta_m, \gamma_1, \dots, \gamma_n\}$

and these vectors form an independent set

$$\text{i.e. } \sum x_i d_i + \sum y_j \beta_j + \sum z_r \gamma_r = 0$$

then $-\sum z_r \gamma_r = \sum x_i d_i + \sum y_j \beta_j$
 this shows that $\boxed{\sum z_r \gamma_r \text{ belongs to } W_1}$

$\sum z_r \gamma_r$ also belongs to W_2 it follows.

$$\boxed{\sum z_r \gamma_r = \sum c_i d_i} \text{ for certain scalars } c_1, \dots, c_k.$$

\therefore the set

$$\{d_1, \dots, d_k, \gamma_1, \dots, \gamma_n\} \text{ is independent}$$

each of the scalars $z_i = 0$ thus.

$$\sum x_i d_i + \sum y_j \beta_j = 0.$$

Since $\{d_1, \dots, d_k, \beta_1, \dots, \beta_m\}$ is also an independent set.

i.e each $x_i = 0$ & $y_i = 0$.
 Thus $\{d_1, \dots, d_k, \beta_1, \dots, \beta_m, \gamma_1, \dots, \gamma_n\}$ is a basis
 for $W_1 + W_2$.

$$\therefore \dim W_1 + \dim W_2 = k + m + k + n \\ = k + (m + k + n)$$

$$\boxed{\dim W_1 + \dim W_2 = \dim(W_1 \cap W_2) + \dim(W_1 + W_2)}$$

Co-ordinates

If V is a finite dimensional vector space, an ordered basis
 for V is a finite sequence of vectors which is linearly independent
 and spans V .

If the sequence (d_1, \dots, d_n) is an ordered basis for V , then the
 set $\{d_1, \dots, d_n\}$ is a basis for V : linearly independent, and

$$B = \{d_1, \dots, d_n\}$$

Suppose V is a finite dimensional vectorspace over the field F

that $B = \{d_1, \dots, d_n\}$

is an ordered basis for V .

Given α in V , there is a unique n -tuple (x_1, \dots, x_n) of scalars

such that

$$\alpha = \sum_{i=1}^n x_i d_i \quad \text{①.}$$

The n -tuple is unique because if we also have

$$\alpha = \sum_{i=1}^n z_i d_i$$

$$\sum_{i=1}^n (x_i - z_i) d_i = 0$$

Eg the linear independence of the d_i tells us that $x_i - z_i = 0$ for each i .

$x_i \rightarrow i^{\text{th}}$ co-ordinate of α relative to the ordered basis

$$B = \{d_1, d_2, \dots, d_n\}$$

$$\beta = \sum_{i=1}^n y_i d_i$$

$$\text{then } \alpha + \beta = \sum_{i=1}^n (x_i + y_i) d_i$$

i^{th} coordinate of $(\alpha + \beta)$ in the ordered basis is $(x_i + y_i)$

Co-ordinate matrix of α relative to the ordered basis B :

$$X = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$[X]_B \rightarrow$ indicate the coordinate matrix

It will be of size $n \times 1$ in (Co-ord. mat.) example

If V is finite(n) dimensional, and that

$$B = \{d_1, \dots, d_n\} \text{ and } B' = \{d'_1, \dots, d'_n\}$$

are two ordered bases for V .

There are unique scalars P_{ij} such that

$$\alpha'_j = \sum_{i=1}^n P_{ij} \alpha_i \quad \text{for } 1 \leq j \leq n.$$

Let $x_1' \dots x_n'$ be the co-ordinates of a given vector α in the ordered basis B' then

$$\begin{aligned}\alpha &= x_1' \alpha_1 + \dots + x_n' \alpha_n \\ &= \sum_{j=1}^n x_j' \alpha_j = \sum_{j=1}^n x_j' \left(\sum_{i=1}^n P_{ij} \alpha_i \right) \\ &= \sum_{j=1}^n \sum_{i=1}^n (P_{ij} x_j') \alpha_i \\ &= \sum_{i=1}^n \left(\sum_{j=1}^n P_{ij} x_j' \right) \alpha_i \end{aligned} \quad \text{--- (2)}$$

Compare (1) & (2).

$$x_i' = \sum_{j=1}^n P_{ij} x_j' \quad (1 \leq i \leq n)$$

Let P be the $n \times n$ matrix whose i,j entry is the scalar P_{ij} and let X and X' be the co-ordinates matrices of the vector α in the ordered basis B and B'

Then we can write

$$X = P X' \quad \text{--- (3)}$$

B and B' are linearly independent sets.

$$X = 0 \quad \text{if} \quad X' = 0$$

$\therefore P$ is invertible.

$$\begin{aligned} \text{by (3)}: \quad P^{-1} X &= P^{-1} P X' \\ \Rightarrow X' &= P^{-1} X \end{aligned}$$

$$[\alpha]_B = P [\alpha]_{B'}$$

$$[\alpha]_{B'} = P^{-1} [\alpha]_B$$

Theorem 4 Let V be an n -dimensional vector space over the field F , and let B and B' be two ordered bases of V .

Then there is a unique, necessarily invertible, $n \times n$ matrix P with entries in F such that

$$(i) [\alpha]_{B'} = P[\alpha]_B$$

$$(ii) [\alpha]_B = P^{-1}[\alpha]_{B'}$$

for every vector α in V . The columns of P are given by

$$P_j = [\alpha_j^i]_B \quad j=1, \dots, n$$

Theorem 5 Suppose P is an $n \times n$ invertible matrix over F

Let V be an n -dimensional vector space over F , and let B be an ordered basis of V . Then there is a unique ordered basis B' of V such that

$$i) [\alpha]_{B'} = P[\alpha]_B$$

$$ii) [\alpha]_B = P^{-1}[\alpha]_{B'} \text{ for every vector } \alpha \text{ in } V$$

Proof Let B consist of the vectors $\alpha_1, \dots, \alpha_n$. If $B' = \{\alpha'_1, \dots, \alpha'_n\}$ is an ordered basis of V for which (i) is valid, it is

clear that

$$\alpha'_j = \sum_{i=1}^n P_{ij} \alpha_i$$

Thus we need only show the vectors α'_j , defined by these eqns, form a basis

Assume $Q = P^{-1}$ then

$$\sum_j Q_{jk} \alpha'_j = \sum_j Q_{jk} \sum_{i=1}^n P_{ij} \alpha_i$$

$$= \sum_{j,n} \sum_i P_{ij} Q_{jk} \alpha_i$$

$$= \sum_i \left(\sum_j P_{ij} Q_{jk} \right) \alpha_i$$

$$= \alpha_k.$$

Thus the subspace spanned by the set

$$B' = \{ \alpha'_1, \dots, \alpha'_m \}$$

Contains B and hence equals V . Thus B' is a basis, from its defn. it is clear that (i) is valid & hence also (ii).

\Rightarrow Let F be a field and let $\alpha = (x_1, x_2, \dots, x_n)$ be vectors in F^n . If B is a standard ordered basis of F^n , $B = \{e_1, e_2, \dots, e_n\}$ The co-ordinate matrix of the vector α in the basis B is given by

$$[\alpha]_B = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

~~Let R be the field of real numbers and let θ be a fixed real no.~~ The matrix

$$P = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$[\alpha]_B = P[\alpha]_{B'}$$

$$[\alpha]_{B'} = P^{-1}[\alpha]_B$$

is invertible with inverse,

$$P^{-1} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

\therefore for each θ the set $B' \rightarrow (\cos \theta, \sin \theta), (-\sin \theta, \cos \theta)$ is a basis for R^2

This basis is obtained by rotating the standard basis through the angle θ

$$\alpha = (x_1, x_2)$$

$$[\alpha]_{B'} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\begin{bmatrix} \alpha'_1 \\ \alpha'_2 \end{bmatrix} = \begin{bmatrix} x_1 \cos \theta + x_2 \sin \theta \\ -x_1 \sin \theta + x_2 \cos \theta \end{bmatrix}$$

$$\alpha'_1 = x_1 \cos \theta + x_2 \sin \theta$$

$$\alpha'_2 = x_1 \sin \theta - x_2 \cos \theta$$

Let F be a subfield of the complex numbers. The matrix.

$$P = \begin{bmatrix} -1 & 4 & 5 \\ 0 & 2 & -3 \\ 0 & 0 & 8 \end{bmatrix}$$

Find the co-ordinates
of vector $\alpha(x_1, x_2, x_3)$
in given basis
 B'

$$[\alpha]_{B'} = P [\alpha]_B$$

If P is invertible (P^{-1}) then $[\alpha]_{B'} = P^{-1} [\alpha]_B$

$$P^{-1} = \begin{bmatrix} -1/4 & 1/8 & 0 \\ 0 & 2/3 & 0/1 \\ 0 & 0 & 1/8 \end{bmatrix} \xrightarrow{R_1 - 2R_2} \begin{bmatrix} -1/4 & 1/8 & 1/2 & 0 \\ 0 & 2/3 & 0 & 1/8 \\ 0 & 0 & 1/8 & 0 \end{bmatrix} \xrightarrow{R_1/(-1), R_2/2, R_3/8} \begin{bmatrix} 1 & 0 & -1/2 & 0 \\ 0 & 1 & -3/2 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -1/2 & 0 \\ 0 & 1 & -3/2 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \xleftarrow{R_1 + 11R_3} \begin{bmatrix} 1 & 0 & -1 & 2 & 0 \\ 0 & 1 & -3/2 & 0 & 1/2 \\ 0 & 0 & 1 & 0 & 1/8 \end{bmatrix} \xleftarrow{R_2 + 3R_3} \begin{bmatrix} 1 & 0 & -1 & 2 & 0 \\ 0 & 1 & 0 & 1/2 & 0 \\ 0 & 0 & 1 & 0 & 1/8 \end{bmatrix}$$

$$P^{-1} = \begin{bmatrix} -1 & 2 & 1/8 \\ 0 & 1/2 & 3/16 \\ 0 & 0 & 1/8 \end{bmatrix}$$

$$\therefore \alpha' = (1, 0, 0) \quad \alpha'_1 = (4, 2, 0) \quad \alpha'_2 = (5, -3, 8) \quad \alpha'_3 = (0, 0, 8)$$

forms a Basis B' of F^3

Co-ordinates of x'_1, x'_2, x'_3 of the vectors
 $\alpha = \{x_1, x_2, x_3\}$ given basis

$$[\alpha]_{B'} = P^{-1} [\alpha]_B$$

$$\begin{bmatrix} x'_1 \\ x'_2 \\ x'_3 \end{bmatrix} = \begin{bmatrix} -1 & 2 & 1/8 \\ 0 & 1/2 & 3/16 \\ 0 & 0 & 1/8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\begin{aligned} x'_1 &= -x_1 + 2x_2 + 1/8 x_3 \\ x'_2 &= 0 + 1/2 x_2 + 3/16 x_3 \\ x'_3 &= 0 + 0 + 1/8 x_3 \end{aligned}$$

$$1) \text{ Show that the vectors } \alpha_1 = (1, 1, 0, 0), \alpha_2 = (0, 0, 1, 1), \alpha_3 = (1, 0, 0, 4), \alpha_4 = (0, 0, 0, 2) \quad (33)$$

form a basis for \mathbb{R}^4 . Find the co-ordinates of each of the standard basis vectors in the ordered basis $\{\alpha_1, \alpha_2, \alpha_3, \alpha_4\}$

Soln $P = [\alpha_1, \alpha_2, \alpha_3, \alpha_4]$ or $A = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \\ \alpha_4 \end{bmatrix}$ & check for L.I.

$$A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 4 & 2 \end{bmatrix} \xrightarrow{R_2 - R_1} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 4 & 2 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_3 \text{ columns}} P = \{d_1, d_2, \dots, d_m\}$$

↓
vectors are represented in

$$\xleftarrow{R_4 + R_2} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 4 & 2 \end{bmatrix} \xleftarrow{R_4 - R_2} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 4 & 2 \end{bmatrix}$$

$$\xrightarrow{R_1 + R_3} \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix} \xrightarrow{R_4/2} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \rightarrow \text{Linearly independent}$$

$\therefore \{\alpha_1, \alpha_2, \alpha_3, \alpha_4\}$ forms a basis.

Co-ordinates for standard Basis

$$e_1 = (1, 0, 0, 0) = \sum x_i d_i$$

Std Basis. $B = \{e_1, e_2, e_3, e_4\}$

$$[\alpha]_{B'} = P^{-1} [e_1]_B$$

$$[\alpha]_B = P [\alpha]_{B'}$$

$$[e_1]_{B'} = P[\alpha]_B$$

$$(1, 0, 0, 0) = \alpha_1(1, 1, 0, 0) + \alpha_2(0, 0, 1, 1) + \alpha_3(1, 0, 0, 4) + \alpha_4(0, 0, 0, 2)$$

$$(1, 0, 0, 0) = x_1 + x_3, \quad x_2, \quad x_2 + 4x_3 + 2x_4$$

$$x_1 + x_3 = 0 \Rightarrow x_3 = 1$$

$$0 + 4 + 2x_4 = 0 \Rightarrow x_4 = -2$$

$$x_1 = 0$$

$$x_2 = 0$$

$$[e_1]_B = \begin{bmatrix} 0 \\ 0 \\ -2 \end{bmatrix}$$

$$= \text{Co-ordinates for } e_2 \\ (0, 1, 0, 0) = x_1(1, 1, 0, 0) + x_2(0, 0, 1, 1) + x_3(1, 0, 0, 4) \\ + x_4(0, 0, 0, 2)$$

$$(0, 1, 0, 0) = (x_1 + x_3, x_1, x_2, x_2 + 4x_3 + 2x_4)$$

$$\therefore \boxed{x_1 = 1} \quad \boxed{x_2 = 0} \quad \boxed{x_3 = -1}$$

$$x_2 + 4x_3 + 2x_4 = 0$$

$$+ 4 + 2x_4 = 0 \quad \boxed{x_4 = 2}$$

$$[e_2]_{B'} = \begin{bmatrix} 1 \\ 0 \\ -1 \\ 2 \end{bmatrix} \xrightarrow{\text{Co-ordinates}} P^{-1} e_2$$

$$\text{Co-ordinates for } e_3 \\ (0, 0, 1, 0) = \sum_{i=1}^4 x_i d_i$$

$$= (x_1 + x_3, x_1, x_2, x_2 + 4x_3 + 2x_4)$$

$$x_1 = 0, x_3 = 0$$

$$x_2 = 1 \quad 1 + 2x_4 = 0 \\ x_4 = -\frac{1}{2}$$

$$\therefore [e_3]_{B'} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ -\frac{1}{2} \end{bmatrix}$$

Finally Co-ordinates of e_4

$$(0, 0, 0, 1) = \sum_{i=1}^4 x_i d_i$$

$$(0, 0, 0, 1) = (x_1 + x_3, x_1, x_2, x_2 + 4x_3 + 2x_4)$$

$$(0, 0, 0, 1) = x_1 + x_3, x_2 = 0, x_3 = 0$$

$$(0, 0, 0, 1) = x_2 + 4x_3 + 2x_4 = 1 \quad x_4 = \frac{1}{2}$$

$$[e_4]_{B'} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \frac{1}{2} \end{bmatrix}$$

2) find the co-ordinate matrix of the vector $(1, 0, 1)$ in the basis of C^3 consisting of the vectors $(2i, 1, 0), (2, -1, 1), (0, 1+i, 1-i)$ in that order. (34)

$$\alpha_1 = (2i, 1, 0) \quad \alpha_2 = (2, -1, 1) \quad \alpha_3 = (0, 1+i, 1-i)$$

So ordered Basis $B' (\alpha_1, \alpha_2, \alpha_3)$.

$$\begin{aligned} (1, 0, 1) &= x_1 \alpha_1 + x_2 \alpha_2 + x_3 \alpha_3 \\ &= x_1 (2i, 1, 0) + x_2 (2, -1, 1) + x_3 (0, 1+i, 1-i) \\ (1, 0, 1) &= (2ix_1 + 2x_2, x_1 - x_2 + x_3 + ix_3, x_2 + 3x_3 - ix_1) \end{aligned}$$

$$P = \begin{pmatrix} 2i & 1 & 0 \\ 2 & -1 & 1 \\ 0 & 1 & 1-i \end{pmatrix}$$

$$P^{-1} = \begin{pmatrix} \frac{1-i}{2} & -i & -1 \\ -\frac{i}{2} & -1 & 0 \\ \frac{i}{2} & 1 & 2 \\ \frac{-1+i}{4} & \frac{1+i}{2} & 1 \end{pmatrix}$$

~~Find $P^{-1}A$~~

$$\begin{pmatrix} \frac{1-i}{4} & \frac{1-i}{2} & \frac{-1+i}{2} \\ \frac{1-i}{4} & \frac{-1-i}{2} & \frac{-1+i}{2} \\ 0 & 0 & \frac{1+i}{2} \end{pmatrix} \begin{pmatrix} \frac{-1-i}{2} \\ \frac{1}{2} \\ \frac{2+i}{4} \end{pmatrix}$$

$$[\alpha']_{B'} = \begin{bmatrix} \alpha'_1 \\ \alpha'_2 \\ \alpha'_3 \end{bmatrix} = P^{-1} [\alpha]_B = \begin{bmatrix} \frac{1-i}{4} & \frac{1-i}{2} & -\frac{1-i}{2} \\ \frac{1-i}{4} & \frac{-1-i}{2} & \frac{-1+i}{2} \\ 0 & 0 & \frac{1+i}{2} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{-1-5i}{4} \\ \frac{-1+i}{4} \\ \frac{1+i}{2} \end{bmatrix}$$

$$[\alpha]_B =$$

Summary of Row-Equivalence

If A is an $m \times n$ matrix over the field F , then the row vectors of A are the vectors $\alpha_1, \dots, \alpha_m$ in F^n defined by $\alpha_i = (A_{i1}, A_{i2}, \dots, A_{in})$.

and that the row space of A is the subspace of F^n spanned by these vectors. The row rank of A is the dimension of the row space of A .

If P is a $k \times m$ matrix over F , then the product

$B = PA$ is $k \times n$ matrix whose row vectors β_1, \dots, β_k are linear combinations

$$\beta_i = p_{i1}\alpha_1 + p_{i2}\alpha_2 + \dots + p_{im}\alpha_m$$

of the row vectors of A . Then the row space of B is a subspace of the row space of A .

If P is an $m \times m$ matrix, then B is row equivalent to A if P is invertible.

so that symmetry of row equivalence or the equation $A = P^{-1}B$

implies that the row space of A is a subspace of the row space of B

Theorem 9: Row equivalent matrices have the same ^{row} space

Theorem 10: Let R be a non-zero row reduced echelon matrix. Then the non-zero row vectors of R form a basis for the row space of R .

Proof: Let s_1, \dots, s_r be the non-zero row vectors of R

$$s_i = (R_{i1}, R_{i2}, \dots, R_{in})$$

Certainly these vectors span the row space of R . we need to prove that they are linearly independent.

Since R is a row reduced echelon matrix, there are positive integers k_1, \dots, k_r such that for $i \leq r$

(a) $R(i,j) = 0$ if $j < k_i$

(b) $R(i,k_i) = 1$

(c) $k_1 < k_2 < \dots < k_r$

β is (b_1, \dots, b_n) is a vector in the row ~~the~~ space of R

$$\beta = c_1 s_1 + \dots + c_r s_r$$

Then we claim that $c_j = b_{k_j}$

$$\begin{aligned} b_{k_j} &= \sum_{i=1}^r c_i R(i, k_j) \\ &= \sum_{i=1}^r c_i s_{ij} \\ &= c_j \end{aligned}$$

if $\beta = 0$ i.e. if $c_1 s_1 + \dots + c_r s_r = 0$ then c_j must be the k_j th co-ordinate of the zero vector so that $c_j = 0$
 $j = 1, \dots, r$ thus s_1, \dots, s_r are linearly independent

\Rightarrow Let A and B be $m \times n$ ~~matrices~~ over the field F .
Then A and B are row-equivalent iff they ~~have~~ have the same row space.