

Quantum Ansatz design:

Ansatz for $U(\vec{\theta})$: what are we using? where are we placing them?

General for $U(\vec{\theta})$:

$$U(\vec{\theta}) = \prod_{j=1}^L e^{-i\theta_j \sigma_j} U_j$$

\uparrow
 parameterized
 gates

\uparrow
 unparameterized gate

- Problem-inspired ansatz: we take information about the problem and we embed it into the design of $U(\vec{\theta})$.

$$\text{UCC} \quad e^{-i\tilde{T}} = U(\vec{\theta})$$

$\tilde{T} = T_1 + T_2$

$$\text{GACA} \quad U(\vec{\theta}) = \prod_{i=1}^q e^{-iB_i^H \mu} e^{-i\zeta_i^H p}$$

\uparrow
 parameterized

- Problem-agnostic ansatzes: we have no information to encode into the design of $U(\vec{\theta})$.

Hardware Efficient Ansatzes

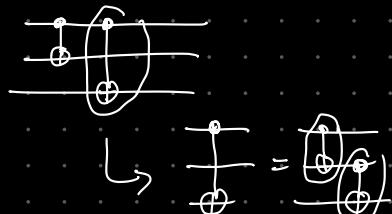
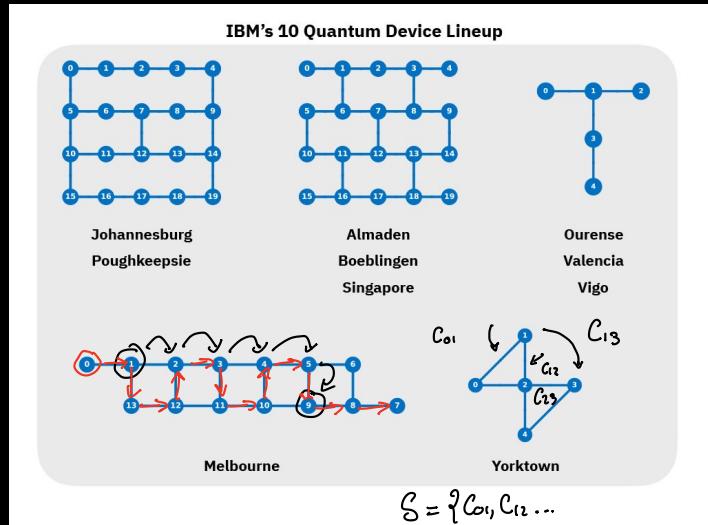
Kandala et al. Nature 549, 242-246 (2017)

arxiv 1704.08018

We are going to build a quantum circuit from the Nature set of a QC.

Native set of gates:

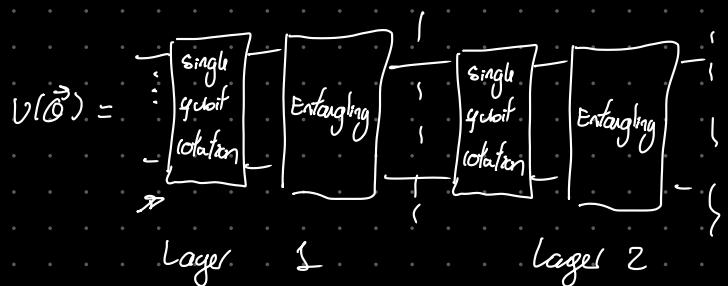
- arise from the native interactions in the device
- arise from the native connectivity



Set of Native gates is composed

$$\{R_x, R_y, R_z, CNOT\} \xrightarrow{\text{device oracles}} \{R_{x_1}, R_{y_1}, R_{z_1}, CNOT_{i, i+1}\}$$

Hardware Efficient ansatz: reduce the depth and use native native



we assume a layered structure of single-qubit rotations and entangling gates

i)

$\boxed{\text{single qubit rotation}} = \boxed{\text{R}_x} \quad \boxed{\text{R}_y} \quad \boxed{\text{R}_z} \rightarrow n \text{ parameters}$

$\boxed{\text{R}_x} = -\boxed{R_x}$

$\boxed{\text{R}_y} = -\boxed{R_y} - \boxed{R_y}$ $\boxed{\text{R}_z} = -\boxed{R_z} - \boxed{R_z}$ $\leftarrow 3n \text{ parameters}$

TIP #7

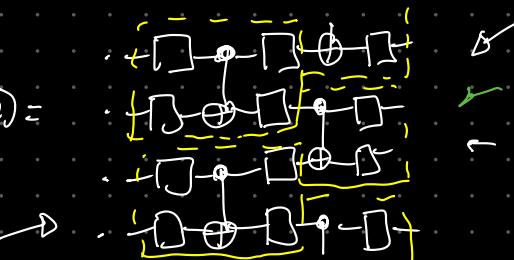
This is the most general 1-qubit gate

2) $\boxed{\text{Entangling}}$

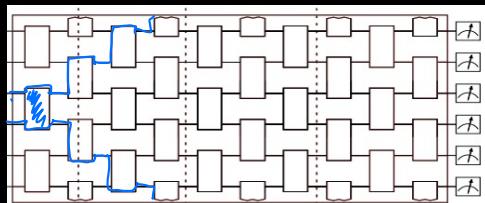
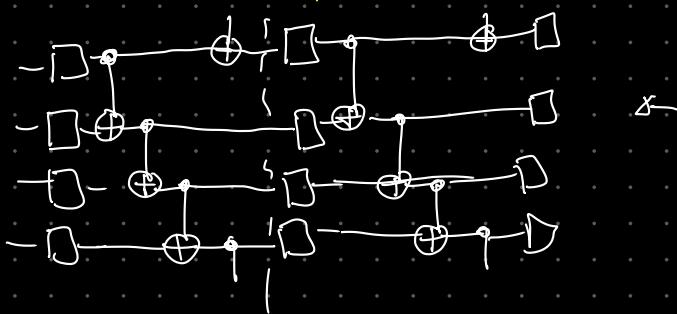
- a) Entangling alternating pairs of qubits
- b) Entangle all qubits

a)

$$U(A) =$$



b)



Hardware efficient ansatz
with alternating 2-qubit unitaries

$\boxed{\quad}$ \rightarrow $\boxed{\quad \oplus \quad}$ or $\boxed{\quad \otimes \quad}$

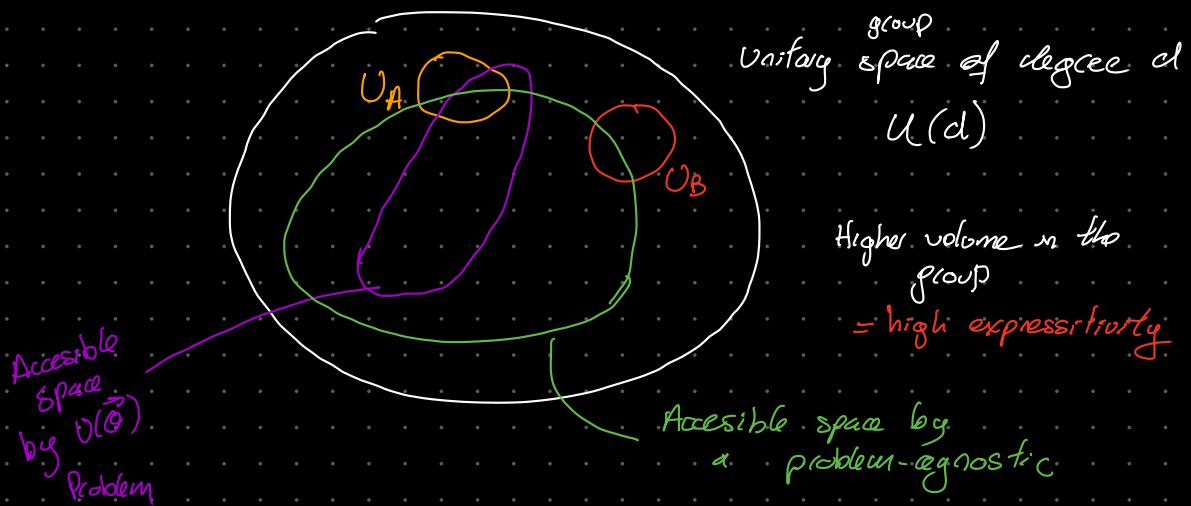
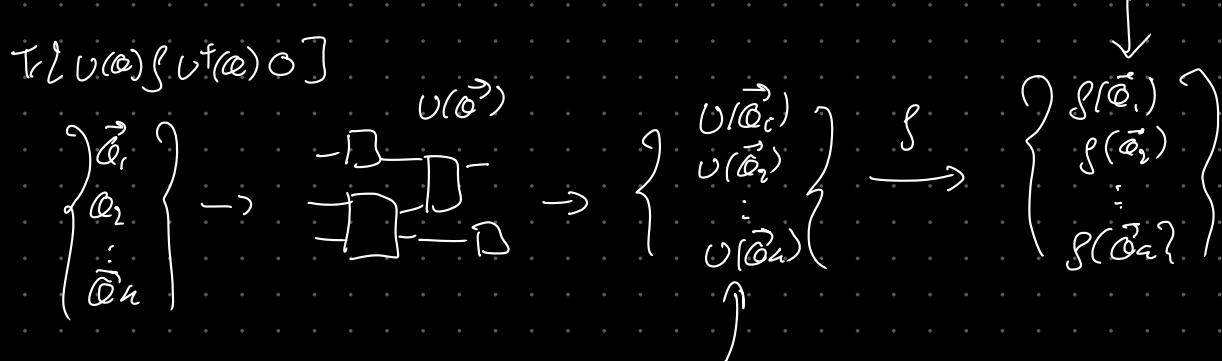
what is the most general 2-qubit gate

Ueda, PRA 69, 032315 (2004), arxiv 0308006 (2003)

$\boxed{\quad}$ = $\begin{array}{c} 3 \\ \xrightarrow{\quad U_1 \quad} \oplus \xrightarrow{\quad R_x \quad} ^1 \\ \xrightarrow{\quad U_1 \quad} \xrightarrow{\quad R_y \quad} \oplus \xrightarrow{\quad U_1 \quad} ^3 \end{array}$ (15 parameters)

$\boxed{U_1}$ = the general 1-qubit gate
(3 parameters)

Difference between problem inspired & agnostic ansatzes



• Variable structure ansatz

$$U(\vec{\theta}, \vec{k})$$

Bilkis

arXiv 2103.06912

rotation angles

continuous variable

T

position or type
of gates

discrete variable

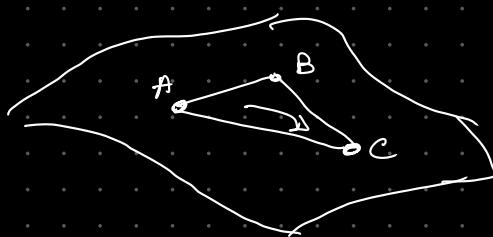
Optimizer Choice

Classical methods

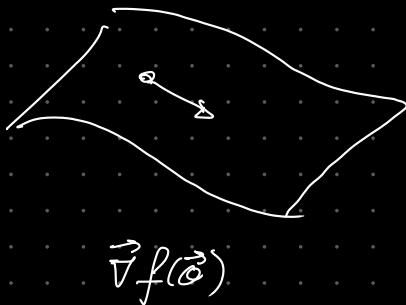
SPSA
Nelder-Mead
COBYLA
Powell

Gradient descent.
stochastic GD
Newton GD

Gradient-free



Gradient-based



- Computing Gradients on a GC

Mitari PRA 98, 032309 (2018) arxiv 1803.00745

Schuld PRA 99, 032331 (2019) arxiv 1811.11184

$$C(\vec{\phi}) = \text{Tr} \left\{ U(\vec{\phi}) \mathcal{G} U^*(\vec{\phi}) \mathcal{O} \right\} ; \quad U(\vec{\phi}) = \prod_{j=1}^L e^{-i \phi_j / 2} \sigma_j \quad W_j$$

$$\frac{\partial C(\vec{\phi})}{\partial \phi_k}$$

$$\sigma_j = ? \times i, 2?$$

$$1) \quad \frac{\partial}{\partial x} \text{Tr} [A(x)] = \text{Tr} \left[\frac{\partial}{\partial x} A(x) \right]$$

$$\frac{\partial C(\vec{\phi})}{\partial \phi_k} = \text{Tr} \left[\frac{\partial}{\partial \phi_k} \left(U(\vec{\phi}) \mathcal{G} U^*(\vec{\phi}) \mathcal{O} \right) \right]$$

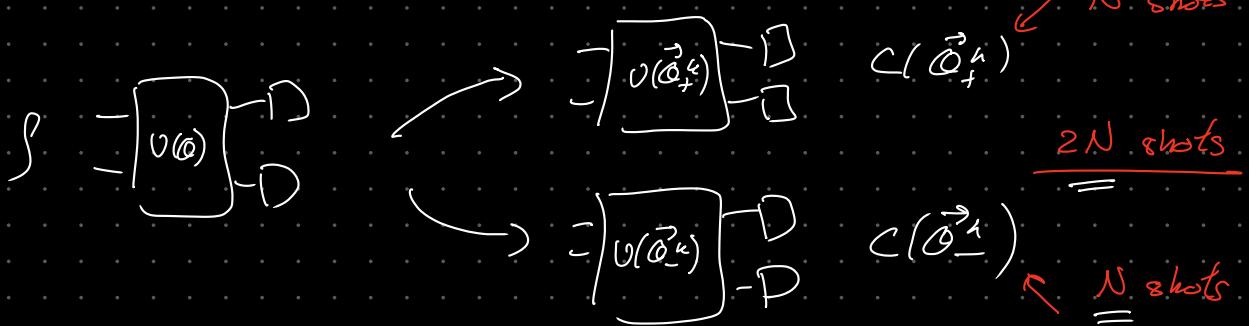
$$2) \quad \frac{\partial}{\partial x} A(x) B C(x) = \left(\frac{\partial}{\partial x} A(x) \right) B C(x) + A(x) B \left(\frac{\partial C(x)}{\partial x} \right)$$

$$3) \quad \frac{\partial}{\partial \phi_k} U(\vec{\phi})$$

$$\boxed{\frac{\partial C(\vec{\phi})}{\partial \phi_k} = \frac{1}{2} (C(\vec{\phi}_+^k) - C(\vec{\phi}_-^k))}$$

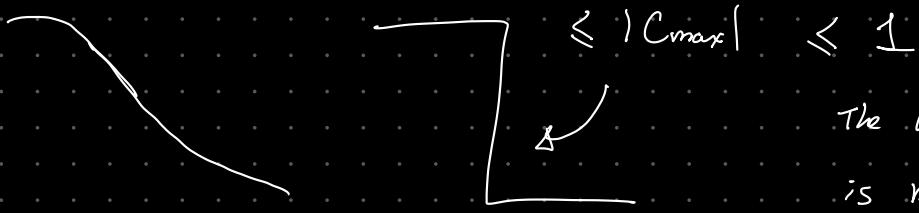
Parameter Shift Rule

$$\vec{\phi}_{\pm}^k = (\phi_1, \phi_2, \dots, \phi_{k-\frac{\pi}{2}}, \dots, \phi_L)$$



$$\vec{\nabla} C(\vec{\phi}) = \left(\frac{\partial C(\vec{\phi})}{\partial \phi_i}, \dots \right) \quad \boxed{2N \text{ shots}}$$

$$\left| \frac{\partial C(\vec{\phi})}{\partial \phi_k} \right| = \frac{1}{2} |C(\vec{\phi}_+^k) - C(\vec{\phi}_-^k)| \leq \frac{1}{2} (|C(\vec{\phi}_+^k)| + |C(\vec{\phi}_-^k)|)$$



The landscape of VQA
is not rugged.

Quantum-aware optimizer

Arrasmith arxiv 2004.06282

Kulber Quantum 4, 263 (2020)
arxiv 1909.09023.

$$\phi = \sum c_i \frac{\phi_i}{\parallel \phi_i \parallel}$$

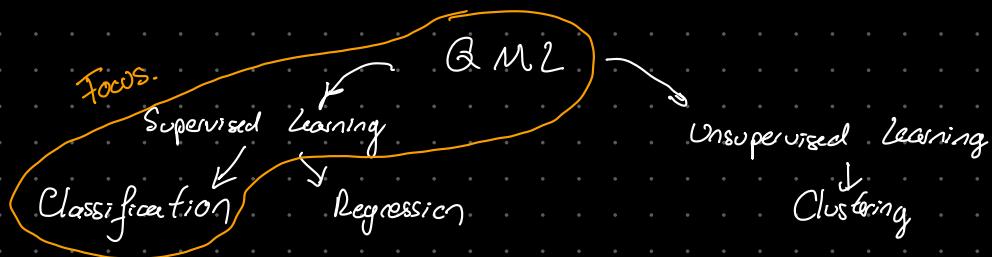
$$|\phi\rangle \uparrow$$

Quantum Machine Learning

Use Quantum Computers to learn from data.

VQA : Input \oplus program = Output

QML : Input \oplus Output = program



Framework for Supervised Classification:

• we denote by X the set of all possible examples or instances.
 $X = \text{input space}$

• we denote by Y the set of labels or target values

we limit ourselves to the case where $Y = \{-1, 1\}$ = Binary classification

- we assume there is an unknown map $h: X \rightarrow Y$ what we want to learn
- we have a way to draw examples independently and identically distributed (i.i.d.) according to some (unknown) distribution D .

Learning Problem :

Draw iid according
to D

train set S $\xrightarrow{\quad}$ test set T

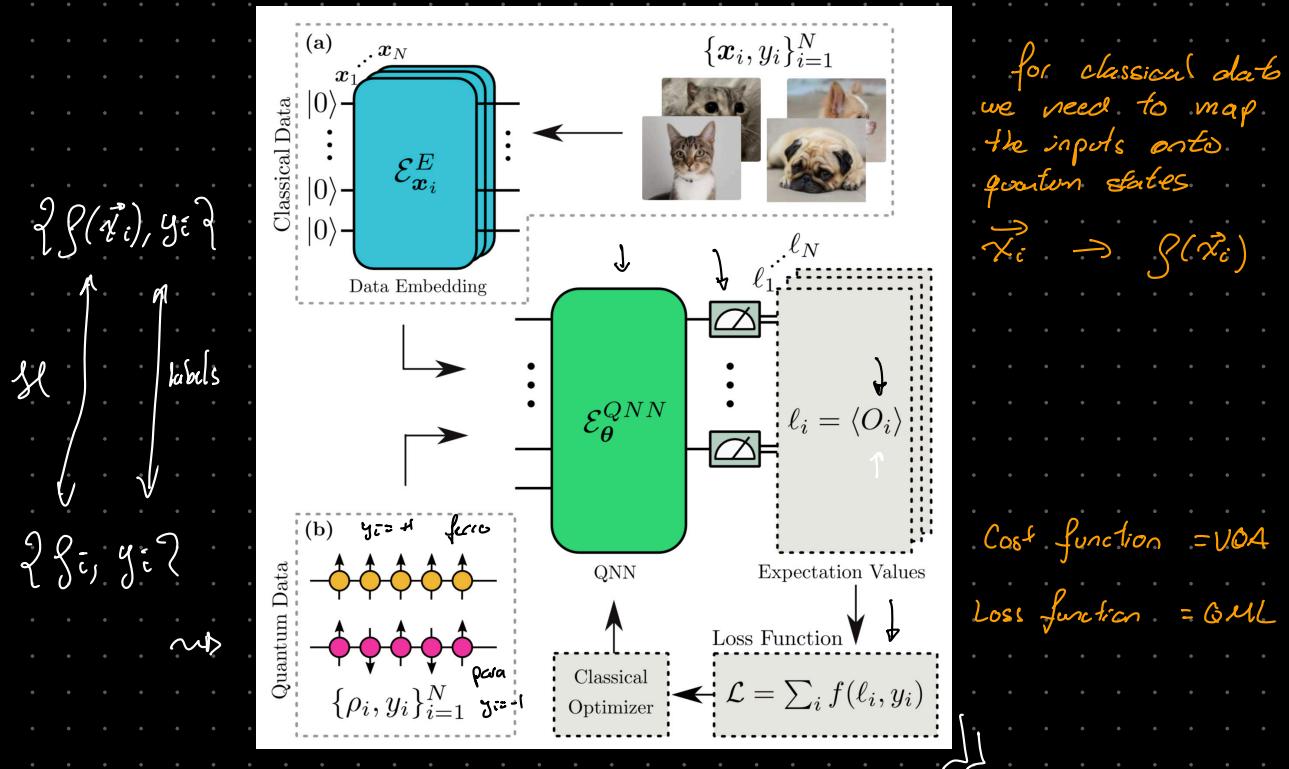
given a possible set of maps M , a hypothesis set, we want to train a QML model $\hat{h} \in M$ over the training data so that the predictions of \hat{h} match those of h with high probability in

the training set low training error

- the test set, previously unseen cases, low generalization error.

why low training error \neq low generalization
 $\tilde{h}(x_i) = y_i \quad x_i \in S$
 $\tilde{h}(x_i) = \begin{cases} 1 & 50\% \quad x_i \notin S \\ 0 & 50\% \end{cases}$

What does the QML model look like? Main goal: use a QC to give our hypothesis \tilde{h} access to the exponentially large Hilbert space.



Classical Data the dataset is of the form \vec{x}_i, y_i

bitstrings \downarrow
real-valued vectors \uparrow
labels

The first step is to embed the classical data points \vec{x}_i onto quantum states that a QC can use for information processing

i) Basis encoding : real numbers, arithmetic operations

Take a bitstring, or convert real valued number into bitstring representation
 $\vec{x} \in \mathbb{C}^{1 \otimes m}$

we promote $\vec{x} \rightarrow |\vec{x}\rangle$ if $m = n$

$$010 \rightarrow |010\rangle$$

The whole dataset can be expressed in a superposition

$$|S\rangle = \frac{1}{\sqrt{|S|}} \sum_{i \in S} |\vec{x}_i\rangle$$

PRO: easy

CON: wasteful, QM is linear

2) Amplitude encoding

The data is embedded into the amplitudes of a quantum state

$$\vec{x} = (x_1, x_2, \dots, x_m) \rightarrow \vec{x} \downarrow |z\rangle = \left(\begin{array}{c} \\ \\ \end{array} \right)$$

$$|z\rangle = \sum_{j=1}^m \frac{x_j}{\sqrt{\sum_{j=1}^m x_j^2}} |z_j\rangle$$

$$|S\rangle = \frac{1}{\sqrt{|S|}} \sum_{i \in S} |\vec{x}_i\rangle$$

$$|z_j\rangle := |10\rangle, |11\rangle, \dots$$

CON: widely used in many QML algorithm, qubit efficient

$\log_2(m)$ qubits to encode a bitstring of length m

$$n = \log_2(m)$$

$$2^n = 2^{\log_2(m)} = m$$

$$O(\text{poly}(n)) = O(\text{poly}(\log(m)))$$

PRO: not obvious how to prepare $|\vec{x}\rangle$, we have to fine-tune or optimise circuits that prepare $|\vec{x}\rangle$. Also linear.

3) Quantum Circuit encoding

use the values of \vec{x} as parameters in a embedding/encoding circuit.

Lloyd arxiv 2001.08622 (2020)

Thomson et al arxiv 2105.02276 (2021)

Hubregtsen arxiv 2105.02276 (2021)

Havlicek Nature 567, 209-212 (2019)
arxiv 1804.11326

Initialize qubits to a fiducial state $|0\rangle = |0\rangle^{\otimes n}$

$$|0\rangle \xrightarrow{E(\vec{x})} |0\rangle$$

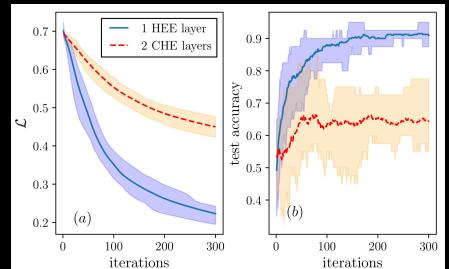
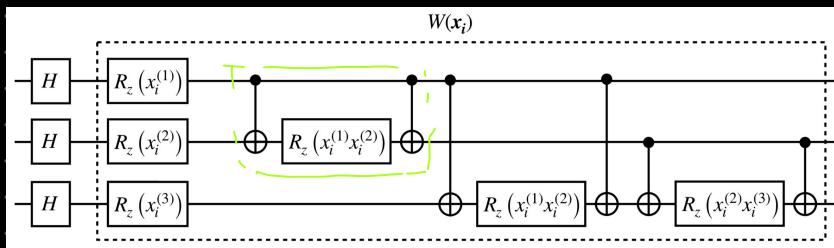
Fixed structure or a variable structure

$$\vec{x}_i = (x_i^{(1)}, x_i^{(2)}, \dots)$$

Parametrized Quantum Circuit

$$E(\vec{x}_i) = \left(\prod_{j=1}^n e^{-i x_i^{(j)} z_j} \right) \left(\prod_{j=1}^m e^{-i x_i^{(j)} z_j} \right)$$

$$|\vec{x}_i| = m = n$$



PRO: easy to obtain non-linearities, Quantum Kernel

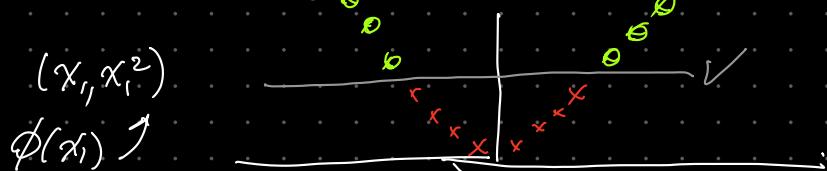
CON: not obvious what ansatz to use for $E(\vec{x})$

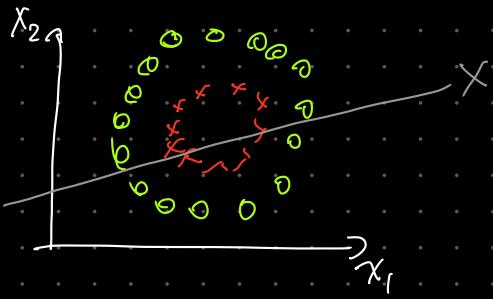
Kernel Trick in Machine Learning

We have data that is not linearly separable in some original input data space.

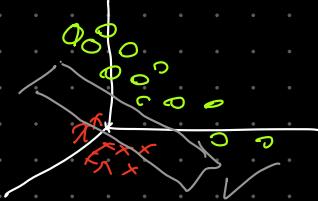


We apply a transformation to the data and map it to a higher-dimensional space where we try to fit a hyper-plane as the decision boundary.





$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \rightarrow \phi \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1^2 \\ \sqrt{2}x_1x_2 \\ x_2^2 \end{pmatrix}$$

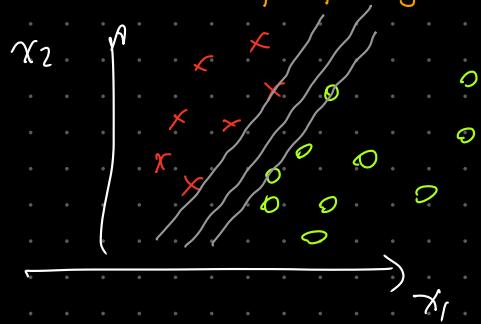


The kernel trick used to analyze data in the higher-dimensional space.

Take the vectors in the original space, and return the inner product in the higher-dimensions.

$$\vec{x}_1, \vec{x}_2 \text{ and a map } \phi : K(\vec{x}_1, \vec{x}_2) = \langle \phi(\vec{x}_1), \phi(\vec{x}_2) \rangle$$

Task Goal: of finding the decision boundary:



Support Vector Machines (SVM)

We solve the optimization problem of determining the hyperplane that separates the data by class.

Data points with minimum distance to the hyperplane are called the support vectors.

Can be solved via the

Due to their closeness to the boundary, their influence on the exact position of hyperplane is larger.

kernel $K(\vec{x}_i, \vec{x}_j)$

$$\vec{x} \xrightarrow{\phi} f(\vec{x}) = E(\vec{x}) | 0 \times 0 | E^T(\vec{x})$$

What's the kernel

$$K(\vec{x}_i, \vec{x}_j) = \text{Tr} [f(x_i) f(x_j)^T] \quad \text{sum for classifier}$$

Classification

Kernel methods, SVM

Neural Networks

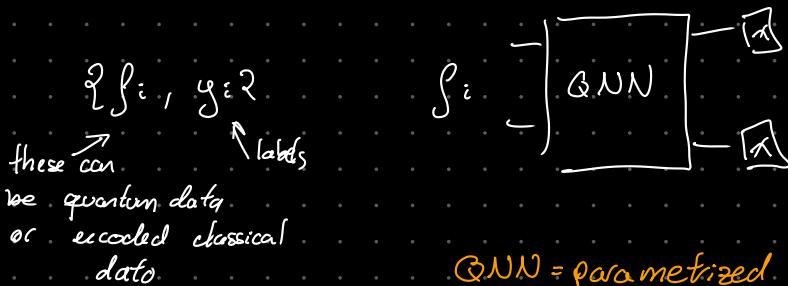
Kernel CON: Kernel might not properly bifurcate the space, hyperplane is not enough

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Quantum Neural Networks

Framework

QNN = generalize classical NN for information processing based on the laws of QM.



QNN = parametrized quantum circuit

Take a quantum state \vec{s}_i from the dataset, send it to QNN (i.e. parametrized quantum circuit) and compute some expectation value via measurements.

$$\rho_i(\vec{\theta}, g_i) = \text{Tr} [U(\vec{\theta}) \vec{s}_i U^\dagger(\vec{\theta}) O_{g_i}]$$

And we are going to compute the loss function

$$L(\vec{\theta}) = \sum_{i=1}^{18} f(l_i(\vec{\theta}, g_i), g_i)$$

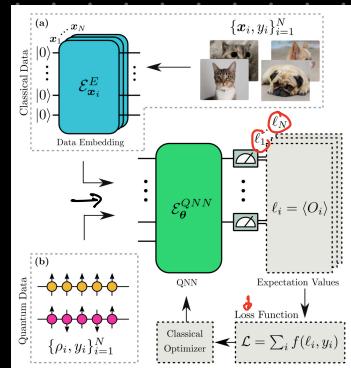
Example Binary classification on quantum data

$$X = \text{subspace of } \mathcal{H} \quad Y = \{-1, 1\}$$

①

- We can assign labels via measuring k qubits ($k \leq n$) and estimate the number of bits string with even / odd parity

label 1 label -1



$$g_i = \begin{cases} 0 & \text{if } z \text{ is even} \\ 1 & \text{if } z \text{ is odd} \end{cases}$$

$00, 100$	$\rightarrow P_{00} = N_{00}/N$	even
$01, 101$	$\rightarrow P_{01} = N_{01}/N$	odd
$10, 110$	$\rightarrow P_{10} = N_{10}/N$	odd
$11, 111$	$\rightarrow P_{11} = \frac{N_{11}}{N}$	even

parity of z = number of 1's in $z \pmod{2}$

$$\begin{array}{lll} \text{How many outcomes had even parity} & N_{00} + N_{01} + P_{00} + P_{01} \\ \text{u u u odd u u} & N_{10} + N_{11} / P_{10} + P_{11} \end{array}$$

The probability of assigning label y_i

$$P(y_i | \vec{\phi}) = T_i [V(\vec{\phi}) f_i V^T(\vec{\phi}) O_{y_i}] \quad \leftarrow O_1 = \sum_{z: \text{even}} (z \times z) \\ O_{-1} = \sum_{z: \text{odd}} (z \times z)$$

②

Instead of the measurement outcome being a probability, the measurement outcome can be in itself the assigned label

$$\tilde{y}_i(\vec{\phi}) = T_i [V(\vec{\phi}) f_i V^T(\vec{\phi}) Z^{\otimes k}] \in [-1, 1] \quad \text{continuous label}$$

Approach ① and ② are equivalent

$$Z^{\otimes k} = \sum_{z: \text{even}} (z \times z) - \sum_{z: \text{odd}} (z \times z)$$

$$Z^{\otimes k} = O_1 - O_{-1}$$

$$\tilde{y}_i(\vec{\phi}) = P_i(1|\vec{\phi}) - P_i(-1|\vec{\phi})$$

$$P_i(y_i | \vec{\phi}) = \frac{1 + \tilde{y}_i(\vec{\phi})}{2}$$

Labels			
00	01	10	11
\tilde{y}_i	\tilde{y}_i	\tilde{y}_i	\tilde{y}_i
P_{00}	P_{01}	P_{10}	P_{11}
$\underline{\underline{=}}$			

For the purpose of accuracy testing we need a discrete value.

Assign label \hat{y}_i if $P_i(y_i | \vec{\phi}) \geq P_i(-y_i | \vec{\phi})$

$$\hat{y}_i \in Y$$

Common loss functions

ϵ_{CE}

Mean-squared error (MSE)

$$L_{MSE} = \frac{1}{|S|} \sum_{i=1}^{|S|} (\tilde{g}_i(\vec{\theta}) - g_i)^2$$

Negative log-likelihood

$$L_{\text{log}} = - \frac{1}{|S|} \sum_{i=1}^{|S|} \log(p_i(g_i | \vec{\theta}))$$

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