

Compositional Choreographies

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Abstract. We propose a new programming model that supports a compositionality of choreographies. The key of our approach is the introduction of partial choreographies, which can mix global descriptions with communications among external peers. We prove that if two choreographies are composable, then the endpoints independently generated from each choreography are also composable, preserving their typability and deadlock-freedom. The usability of our framework is demonstrated by modelling an industrial use case implemented in a tool for Web Services, Jolie.

1 Introduction

Choreography-based programming is a powerful paradigm for designing communicating systems where the flow of communications is defined from a global viewpoint, instead of separately specifying the behaviour of each *endpoint* (peer). The local behaviour of the endpoints can then be automatically generated by means of *EndPoint Projection* (EPP). This paradigm has been used in standards [22, 4] and language implementations [12, 20, 21, 9]. Choreographies impact significantly the quality of software: they lower the chance for programming errors and ease their detection [17, 7, 8].

Previous works provide models for programming implementations of communicating systems with choreographies [7, 8]. These models come with a type discipline for checking choreographies against protocol specifications given as session types [13], which are used to verify that the global behaviour of a choreography implements the expected communication flows. For example, a programmer may express a protocol using a *multipart session type* [14] (or *global type*) such as the following one:

$$B \multimap C: \langle \text{string} \rangle; C \multimap B: \langle \text{int} \rangle; B \multimap T: \left\{ \begin{array}{l} \text{ok}: B \multimap T: \langle \text{string} \rangle; T \multimap B: \langle \text{date} \rangle, \\ \text{quit}: \text{end} \end{array} \right\}$$

Above, B, C and T are *roles* and abstractly represent endpoints in a system. In the protocol, a buyer B sends the name of a product to a catalogue C, which replies with the price for that product. Then, B notifies the transport role T of whether the price is accepted or not. In the first case (label *ok*), B sends also a delivery address to T and T replies with the expected delivery date. Otherwise (label *quit*), the protocol terminates immediately.

To the best of our knowledge, all previous choreography programming models (e.g., [8, 7]) require the programmer to implement the behaviour of all roles in a protocol where it is used; e.g., it would not be possible to write the choreography of a system that uses the protocol above but gives the implementations only of roles C and

T, to make those reusable by other programs as software libraries through an API. This seriously hinders the applicability of choreographies in industrial settings, where the interoperability of different systems developed independently is the key. In particular, it is not currently possible to:

- use choreographies to develop software libraries that implement subsets of roles in protocols such that they can be reused from other systems;
- reuse an existing software library that implements subsets of roles in protocols from inside a choreography.

To tackle the issues above, we ask: *Can we design a choreography model in which the EPP of a choreography can be composed with other existing systems?* The main problem is that existing choreography models rely on the complete knowledge of the implementation details of all endpoints to ensure that the systems generated by EPP will behave correctly. This complete knowledge is not available when independently developed implementations of distributed protocols need to be composed. In order to answer our question, we build a model for developing *partial choreographies*. Partial choreographies implement the behaviour of subsets of the roles in the protocols they use. Endpoint implementations are then automatically generated from partial choreographies and composed with other systems, with the guarantee that their overall execution will follow the intended protocols and the behaviour of the originating choreographies.

Main contributions. We provide the following contributions:

Compositional Choreographies. We introduce a new programming model for choreographies in which the implementation of some roles in protocols can be omitted (§ 3). These *partial choreographies* can then be composed with others through message passing. Our model allows to describe both choreographies with many participants or just a single endpoint. We provide a notion of EPP that produces correct endpoint code from a choreography, and we show that the EPP of a choreography preserves its compositional properties (§ 5). Our model introduces *shared channel mobility* to choreographies, which gains a dynamism when two protocols are composed.

Typing. We provide a type system for checking choreographies against protocol specifications given as multiparty session types [14]. The type system ensures that the composition of different programs implements the intended protocols correctly (§ 4), and that our EPP produces code that follows the behaviour of the originating choreographies. Our framework guarantees that the EPP is still typable (§ 5); therefore, the EPP is reusable as a “black box” composable with other systems and the result of the composition can be checked for errors by referring only to types.

Deadlock-freedom and Progress among Composed Choreographies. In the presence of partial choreographies, we prove that we can (i) capture the existing methodologies for deadlock-freedom in complete choreographies as in [7, 8] and (ii) extend the notion of progress for incomplete systems investigated in [14] to choreographies (§ 5). Our results demonstrate for the first time that choreographies can be effectively used also as a tool for progress in a compositional setting, offering a new viewpoint for investigating progress and giving a fresh look to the results in [7, 8].

Proofs, auxiliary definitions, and other resources are posted at [1], including an implementation of our use case (§ 2) with Jolie [16, 19].

2 Motivations: a Use Case of Compositional Choreographies

We present motivations for this study by reporting a use case from our industry collaborators [15], and informally introducing our model. For clarity, we discuss only its most relevant parts. An extended version can be found at [1].

In our use case a buyer company needs to purchase a product from one of many available seller companies. The use case has two aspects that previous choreography models cannot handle: (i) the system of the buyer company is developed independently from those of the seller companies, and use the latter as software modules without revealing internal implementation details; (ii) depending on the desired product, the buyer company selects a suitable seller company at runtime. We address these issues with *partial choreographies*. A partial choreography implements a subset of the roles in a protocol, leaving the implementation of the other roles to an external system. External systems can be discovered at runtime. In our case, the buyer company will select a seller and then run the protocol from the introduction by implementing only the buyer role B, and rely on the external seller system to implement the other two roles C and T.

Buyer Choreography. We now define a choreography for the buyer company, C_B .

$$C_B = \begin{array}{l} 1. \text{u[U] starts pd[PD] : } a(k); \text{u[U].prod} \rightarrow \text{pd[PD].x : } k; \\ 2. \text{pd[PD] starts r[R] : } b(k'); \text{pd[PD].x} \rightarrow \text{r[R].y : } k'; \text{r[R].find(y)} \rightarrow \text{pd[PD].z : } k'; \\ 3. \text{pd[B] req C, T : } z(k''); \text{pd[B].x} \rightarrow \text{C : } k''; \text{C} \rightarrow \text{pd[B].price : } k''; \\ 4. \text{if check(price)@pd then} \\ 5. \quad \text{pd[B]} \rightarrow \text{T : } k'' \oplus \text{ok}; \text{pd[PD]} \rightarrow \text{u[U] : } k[\text{del}]; \text{pd[PD]} \rightarrow \text{u[U] : } k\langle k''[\text{B}] \rangle; \\ 6. \quad \text{u[B].addr} \rightarrow \text{T : } k''; \text{T} \rightarrow \text{u[B].ddate : } k'' \\ 7. \text{else} \\ 8. \quad \text{pd[B]} \rightarrow \text{T : } k'' \oplus \text{quit}; \text{pd[PD]} \rightarrow \text{u[U] : } k[\text{quit}] \end{array}$$

Above, a purchase in the buyer company is initiated by a user process u . In Line 1, process u and the freshly created process pd (for purchasing department) start a session k by synchronising on shared channel a . Each process is annotated with the role it plays in the protocol that the session implements. Then, still in Line 1, u sends the product $prod$ the user wishes to buy to pd . In Line 2 pd starts a new session k' with a fresh process r (a service registry) through shared channel b . Then, pd forwards the product name to r , which replies with the shared channel of the seller to contact for the purchase.

We refer to statements such as those in Lines 1-2 as complete, since they describe the behaviour of all participants, both sender and receiver(s). On the other hand, the continuation in Lines 3-8 is a partial choreography that relies on the selected external seller to implement the protocol shown in the introduction and perform the purchase.

The partial choreography in Lines 3-8 is depicted as a sequence chart in Fig. 1.a, where dashed lines indicate interactions with external participants. In Line 3 pd *requests* a synchronisation on the shared channel stored in its local variable z to create the new session k'' , declaring that it will play role B and that it expects the environment to implement roles C and T. Session k'' proceeds as specified by the protocol in the introduction. First, pd sends the product name stored in x through session k'' to the external process that is playing role C (the product catalogue executed by the seller company). Observe that here we do not specify the process name of the receiver, since that will be established by the external seller system. Then, pd waits to receive the price for the product from the external process playing role C in k'' . In Line 4, pd checks whether

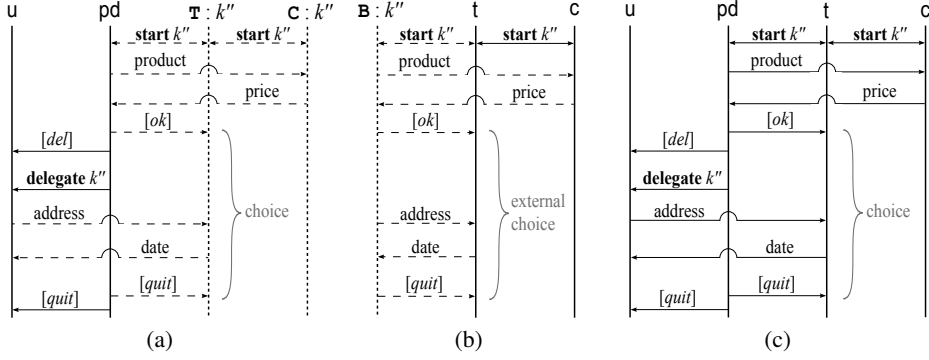


Fig. 1. Sequence charts for buyer (a), seller (b), and their composition (c).

the price is acceptable; if so, in Line 5 pd tells the external process playing role T (the transport process executed by the seller company) and user u (which remains internal to the buyer choreography) to proceed with the purchase (labels ok and del respectively). Still in Line 5, pd delegates to u the continuation of session k'' in its place, as role B . In Line 6, the user sends her address to T and receives a delivery date. If the price is not acceptable, Line 7, then in Line 8 pd informs the others to quit the purchase attempt.

Seller Choreography and Composition. We define now a choreography for a seller that can be contacted by C_B . Let the find function in C_B return shared channel c for electronic products, and c' for other products; we refer to the choreographies of the respective seller companies as C_S and C'_S . Below, we define C_S (C'_S , omitted, is similar).

$$C_S = \begin{array}{l} 1. \text{acc } c[C], t[T] : c(k''); \quad B \rightarrow c[C].x_2 : k''; \quad c[C].price(x_2) \rightarrow B : k''; \\ 2. B \rightarrow t[T] : k'' \& \left\{ \begin{array}{l} ok : B \rightarrow t[T].daddr : k''; \quad t[T].time(daddr) \rightarrow B : k'' \\ quit : 0 \end{array} \right\} \end{array}$$

The choreography C_S , depicted as a sequence chart in Fig. 1.b, starts by *accepting* the creation of session k'' through shared channel c , offering to spawn two fresh processes c and t . Choreographies starting with an acceptance act as replicated, modelling typical always-available modules. The acceptance in Line 1 would synchronise with the request made by C_B in the case $z = c$. Afterwards, c expects to receive the product name from the process playing B in session k'' , and replies with the respective price. In Line 2, t (the process for the transport) waits for either label ok or $quit$. In the first case, t also waits for a delivery address and then sends back the expected time of arrival.

From the code of C_B and C_S and, graphically, from their respective sequence charts we can see that they are *compatible*: sending actions match receiving actions on the other side and vice versa. Our model can recognise this by using roles in protocols as interfaces between partial choreographies (§ 4). The code for buyer and seller companies can be composed in a network with the parallel operator $|$ as: $C = C_B | C_S | C'_S$. Parallel composition allows partial terms in different choreographies to communicate. In (§ 3, Semantics) we formalise a semantics for choreography composition. To give the intuition behind our semantics, let us consider the sequence charts in Fig. 1.a and Fig. 1.b; their composition will behave as the sequence chart in Fig. 1.c.

$C ::= \eta; C$	(seq)	$C_1 \mid C_2$	(par)
$\mid \text{if } e @ p \text{ then } C_1 \text{ else } C_2$	(cond)	$(\nu r) C$	(res)
$\mid \text{rec } X(\widetilde{x @ p}, \tilde{k}, \tilde{p}) = C_2 \text{ in } C_1$	(rec)	$X(\widetilde{x @ p}, \tilde{k}, \tilde{p})$	(call)
$\mid \mathbf{0}$	(inact)	$A \rightarrow q : k \& \{l_i : C_i\}_{i \in I}$	(branch)
<hr/>			
$\eta ::= p \text{ starts } \tilde{q} : a(k)$	(start)	$p.e \rightarrow q.x : k$	(com)
$\mid p \rightarrow q : k[l]$	(sel)	$p \rightarrow q : k(k'[A])$	(del)
$\mid p \text{ req } \tilde{B} : u(k)$	(req)	$\text{acc } \tilde{q} : a(k)$	(acc)
$\mid p.e \rightarrow B : k$	(com-s)	$A \rightarrow q.x : k$	(com-r)
$\mid p \rightarrow B : k(k'[C])$	(del-s)	$A \rightarrow q : k(k'[C])$	(del-r)
$\mid p \rightarrow B : k \oplus l$	(sel-s)		
<hr/>			
$p, q ::= p[A]$		$u ::= x \mid a$	

Fig. 2. Compositional Choreographies.

3 Compositional Choreographies

This section introduces our model for compositional choreographies, a calculus where complete and partial actions can be freely interleaved.

Syntax. Fig. 2 defines the syntax of our calculus. C is a choreography, η is a complete or partial action, p is a typed process identifier made by a process identifier p and a role annotation A , k is a session identifier, and a is a shared channel. A term $\eta; C$ denotes a choreography that may execute action η and then proceed as C . In the productions for η , terms *(start)*, *(com)*, *(sel)* and *(del)* are complete actions, whereas all the others are partial. In the productions for C , term *(branch)* is also partial.

Complete Actions. Term *(start)* initiates a session: process p starts a new multiparty session through shared channel a and tags it with a fresh identifier k . p is already running and dubbed *active process*, while \tilde{q} (which we assume nonempty) is a set of bound *service processes* that are freshly created. A, \tilde{B} represent the respective roles played by the processes in session k . Term *(com)* denotes a communication where process p sends, on session k , the evaluation of a first-order expression e to process q , which binds it to its *local variable* x . Expressions may be shared channel names, capturing shared channel mobility. In *(sel)*, p communicates to q its selection of branch l . Term *(del)* models session mobility: process p delegates to q through session k its role C in session k' .

Partial Actions. In term *(req)*, process p is willing to start a new session k by synchronising through shared channel a with some other external processes. p is willing to play role A in the session and expects the other processes to play the other roles \tilde{B} . *(req)* terms are supposed to synchronise with always-available *service processes*, modelled by term *(acc)*. In term *(acc)*, processes \tilde{q} are dynamically spawned whenever requested by a matching *(req)* term on the same shared channel a . Term *(com-s)* models the sending of a message from a process p to an external process playing role B in session k . Dually, in *(com-r)* process q receives a message intended for B in session k from the external process playing role A . *(del-s)* and *(del-r)* model, respectively, the sending and receiving of a delegation of role C in session k' . *(sel-s)* models the sending of a selection of label

l . (*sel-s*) can synchronise with a (*branch*) term, which offers a choice on multiple labels. Once a label l_i is selected, (*branch*) proceeds by executing its continuation C_i .

Other terms. In term (*cond*), process p evaluates condition e to choose the continuation C_1 or C_2 . Term (*res*) restricts the usage of a name r to a choreography C . r can be any name, i.e., a process identifier p , a session identifier k , or a shared channel a . Term (*par*) models the parallel composition of choreographies, allowing partial actions to interact through the network. The other terms are standard: terms (*rec*), (*call*) and (*inact*) model, respectively, a recursive procedure, a recursive call, and termination.

For clarity, we have annotated process identifiers with roles in all communications. Technically, this is necessary only for terms (*start*), (*req*) and (*acc*) since roles can be inferred from session identifiers in all other terms (cf. [8]).

Semantics. We give semantics to choreographies with a labelled transition system (lts), whose rules are defined in Fig. 3 and whose labels λ are defined as:

$$\lambda ::= \eta \mid A \rightarrow q : k \& l \mid \text{if}@p \mid (\nu r) \lambda$$

We distinguish between labels representing complete or partial actions with the respective sets CAct and PAct. CAct is the smallest set containing all η that are complete actions and the labels of the form $\text{if}@p$, closed under restrictions (νr) . PAct is the smallest set containing all η that are partial actions and the labels of the form $A \rightarrow q : k \& l$, similarly closed under restriction of names. We also use other auxiliary definitions. $\text{fc}(C)$ returns the set of all session/role pairs $k[A]$ such that k is free in C and there is a process performing an action as role A in session k in C . $\text{rc}(\lambda)$ is defined only for partial labels that are not (*req*) or (*acc*), and returns the session/role pair of the intended external sender or receiver of λ ; e.g., $\text{rc}(p.e \rightarrow B : k) = k[B]$. fn and bn denote the sets of free and bound names in a label or a term. $\text{snd}(\eta)$ returns the name of the sender process in η , and is undefined if η has no sender process (e.g., when η is a (*com-r*)). $\text{rcv}(\eta)$, instead, returns the session/role pair $k[A]$ where k is the session used in η and A is the role of the receiver (similarly for $\text{rcv}(\lambda)$). $\text{fc}(\lambda)$ is as $\text{fc}(C)$, but applied on labels.

We comment the rules. Rule $[\text{C}|_{\text{ACT}}]$ handles actions that can be simply consumed. Rule $[\text{C}|_{\text{START}}]$ starts a session with a global action, by restricting the names of the newly created session identifier k and processes \tilde{q} . Rule $[\text{C}|_{\text{COM}}]$ handles the communication of a value by substituting, in the continuation C , the binding occurrence x under process identifier q with value v (evaluated from expression e). Similarly, rules $[\text{C}|_{\text{COM-S}}]$ and $[\text{C}|_{\text{COM-R}}]$ implement the respective partial sending and receiving actions of a communication. In rule $[\text{C}|_{\text{BRANCH}}]$, process q receives a selection on a branching label and proceeds accordingly. Rules $[\text{C}|_{\text{COND}}]$, $[\text{C}|_{\text{RES}}]$, and $[\text{C}|_{\text{CTX}}]$ are standard. Rule $[\text{C}|_{\text{PAR}}]$ makes global actions observable and blocks partial actions if their counterpart is in the parallel branch C_2 . In rule $[\text{C}|_{\text{EQ}}]$, the relation \mathcal{R} can either be the swapping relation \simeq_C , which swaps terms that describe the behaviour of different processes [8], or the structural congruence \equiv , which handles name restriction and recursion unfolding (see [1]).

Rule $[\text{C}|_{\text{SYNC}}]$ is the main rule and enables two choreographies to perform compatible sending/receiving partial actions λ and λ' to interact and realise a global action, defined by $\lambda \circ \lambda'$. Function $\circ : \text{PAct} \times \text{PAct} \rightarrow \text{CAct}$ is formally defined by the rules below:

$$\begin{aligned} p[A] \rightarrow B : k\langle v \rangle \circ A \rightarrow q[B] : k\langle v \rangle &= p[A] \rightarrow q[B] : k\langle v \rangle \\ p[A] \rightarrow B : k\langle k'[C] \rangle \circ A \rightarrow q[B] : k\langle k'[C] \rangle &= p[A] \rightarrow q[B] : k\langle k'[C] \rangle \\ p[A] \rightarrow B : k \oplus l \circ A \rightarrow q[B] : k \& l &= p[A] \rightarrow q[B] : k[l] \end{aligned}$$

$$\begin{array}{l}
\llbracket^c \text{ACT} \rrbracket \quad \eta \notin \{(com), (com-s), (com-r), (start), (acc)\} \Rightarrow \eta; C \xrightarrow{\eta} C \\
\llbracket^c \text{START} \rrbracket \quad \eta = p \text{ starts } \widetilde{q[B]} : a(k) \Rightarrow \eta; C \xrightarrow{\eta} (\nu k, \tilde{q}) C \\
\llbracket^c \text{COM} \rrbracket \quad \eta = p.e \rightarrow q[B].x : k \Rightarrow \eta; C \xrightarrow{p \rightarrow q[B]:k(v)} C[v/x@q] \quad (e \downarrow v) \\
\llbracket^c \text{COM-S} \rrbracket \quad p.e \rightarrow B : k; C \xrightarrow{p \rightarrow B:k(v)} C \quad (e \downarrow v) \\
\llbracket^c \text{COM-R} \rrbracket \quad A \rightarrow q[B].x : k; C \xrightarrow{A \rightarrow q[B]:k(v)} C[v/x@q] \\
\llbracket^c \text{BRANCH} \rrbracket \quad A \rightarrow q : k \& \{l_i : C_i\}_{i \in I} \xrightarrow{A \rightarrow q:k \& l_j} C_j \quad (j \in I) \\
\llbracket^c \text{COND} \rrbracket \quad \text{if } e @ p \text{ then } C_1 \text{ else } C_2 \xrightarrow{\text{if } @ p} C_i \quad (i = 1 \text{ if } e \downarrow \text{true}, i = 2 \text{ otherwise}) \\
\llbracket^c \text{RES} \rrbracket \quad C \xrightarrow{\lambda} C' \Rightarrow (\nu r) C \xrightarrow{(\nu r) \lambda} (\nu r) C' \\
\llbracket^c \text{CTX} \rrbracket \quad C_1 \xrightarrow{\lambda} C'_1 \Rightarrow \text{rec } X(\widetilde{x@p}, \tilde{k}, \tilde{p}) = C_2 \text{ in } C_1 \xrightarrow{\lambda} \text{rec } X(\widetilde{x@p}, \tilde{k}, \tilde{p}) = C_2 \text{ in } C'_1 \\
\llbracket^c \text{PAR} \rrbracket \quad C_1 \xrightarrow{\lambda} C'_1 \Rightarrow C_1 \mid C_2 \xrightarrow{\lambda} C'_1 \mid C_2 \quad (\lambda \in \text{CACT} \vee \text{rc}(\lambda) \notin \text{fc}(C_2)) \\
\llbracket^c \text{EQ} \rrbracket \quad \mathcal{R} \in \{\equiv, \simeq_C\} \quad C_1 \mathcal{R} C'_1 \quad C'_1 \xrightarrow{\lambda} C'_2 \quad C'_2 \mathcal{R} C_2 \Rightarrow C_1 \xrightarrow{\lambda} C_2 \\
\llbracket^c \text{SYNC} \rrbracket \quad C_1 \xrightarrow{\lambda} C'_1 \quad C_2 \xrightarrow{\lambda'} C'_2 \Rightarrow C_1 \mid C_2 \xrightarrow{\lambda \circ \lambda'} C'_1 \mid C'_2 \\
\llbracket^c \text{P-START} \rrbracket \quad \left. \begin{array}{l} i \in [1, n] \quad \{\tilde{q}\} = \{\tilde{q}_1, \dots, \tilde{q}_n\} \\ \{\tilde{B}\} = \{\tilde{B}_1, \dots, \tilde{B}_n\} \quad C'' = \prod_i C_i \\ C \xrightarrow{p \text{ req } \tilde{B}:u(k)} C' \\ C_i = \text{acc } \widetilde{q[B]}_i : a(k); C'_i \end{array} \right\} \Rightarrow \left. \begin{array}{l} C \mid C'' \xrightarrow{\lambda} (\nu k, \tilde{q}) (C' \mid \prod_i (C'_i)) \mid C'' \\ (\lambda = p \text{ starts } \widetilde{q[B]}_1, \dots, \widetilde{q[B]}_n : a(k)) \end{array} \right\} \\
\llbracket^c \text{ASYNC} \rrbracket \quad C \xrightarrow{\lambda} (\nu \tilde{r}) C' \Rightarrow \eta; C \xrightarrow{\lambda} (\nu \tilde{r}) \eta; C' \quad \left(\begin{array}{l} \text{snd}(\eta) \in \text{fn}(\lambda) \quad \tilde{r} = \text{bn}(\lambda) \\ \text{rcv}(\eta) \notin \text{fc}(\lambda) \quad \tilde{r} \notin \text{fn}(\eta) \\ \eta \notin \{(start), (acc)\} \end{array} \right)
\end{array}$$

Fig. 3. Semantics of Compositional Choreographies.

Observe that if $\lambda \circ \lambda'$ is not defined (the actions are incompatible), then the rule cannot be applied. Similarly, $\llbracket^c \text{P-START} \rrbracket$ models a session start by synchronising a partial choreography that requests to start a session with other choreographies that can accept the request on the same shared channel. The choreographies accepting the request remain available afterwards, for reuse. Finally, rule $\llbracket^c \text{ASYNC} \rrbracket$ models asynchrony, allowing the sender process of an interaction η ($\text{snd}(\eta)$) to send a message and then proceed freely before the intended receiver actually receives it. In the rule, we require asynchrony to preserve the message ordering in a session wrt receivers with a causality check ($\text{rcv}(\eta) \notin \text{fc}(\lambda)$).

4 Typing Compositional Choreographies

We now present our typing discipline, which ensures that sessions in a choreography follow protocol specifications given as global types [14, 3]. The key advances from

previous work [8] are: (i) introduction of the typing rules for partial choreographies and shared channel passing; and (ii) typing endpoints by local types, which offer transparent compositional properties for the behaviour of each process.

Global and Local Types from [14, 3] are defined below:

$$\begin{aligned} G &::= A \multimap B : \langle U \rangle; G \mid A \multimap B : \{l_i : G_i\}_{i \in I} \mid \mu \mathbf{t}. G \mid \mathbf{t} \mid \text{end} \\ T &::= !A \langle U \rangle; T \mid ?A \langle U \rangle; T \mid \oplus A \{l_i : T_i\}_{i \in I} \mid \&A \{l_i : T_i\}_{i \in I} \mid \mu \mathbf{t}. T \mid \mathbf{t} \mid \text{end} \\ S &::= G \mid \text{int} \mid \text{bool} \cdots \quad U ::= S \mid T \end{aligned}$$

G is a global type. $A \multimap B : \langle U \rangle; G$ abstracts a communication from role A to role B with continuation G , where U is the type of the exchanged message. U can either be a sort type S (used for typing values or shared channels), or a local type T (used for typing session delegation). In $A \multimap B : \{l_i : G_i\}_{i \in I}$, role A selects one label l_i offered by role B and the global type proceeds as G_i . All other terms are standard.

T denotes a local type. $!A \langle U \rangle; T$ represents the sending of a message of type U to role A , with continuation T . Dually, $?A \langle U \rangle; T$ represents the receiving of a message of type U from role A . $\oplus A \{l_i : T_i\}_{i \in I}$ and $\&A \{l_i : T_i\}_{i \in I}$ abstract the selection and the offering of some branches. The other terms are standard.

To relate a global type to the behaviour of an endpoint, we project a global type G onto a local type that represents the behaviour of a single role. We write $\llbracket G \rrbracket_A$ to denote the projection of G onto the role A , which is defined following [11] (cf. [1]).

Type checking. We now introduce our type checking discipline for checking choreographies against global types. We use two kinds of typing environments, the linear session typing environments Δ and the unrestricted service environments Γ :

$$\Delta ::= \Delta, k[A] : T \mid \emptyset \quad \Gamma ::= \Gamma, x@p : S \mid \Gamma, X : (\Gamma, \Delta) \mid \Gamma, p : k[A] \mid \Gamma, a : G \langle A | \tilde{B} | \tilde{C} \rangle \mid \emptyset$$

Δ is standard [3], where $k[A] : T$ maps a local type T to a role A in a session k . In Γ , $x@p : S$ types variable x of process p with type S . $X : (\Gamma, \Delta)$ types recursive procedure X . $p : k[A]$ establishes that process p owns role A in session k . $a : G \langle A | \tilde{B} | \tilde{C} \rangle$ types a shared channel a with global type G : A is the role of the active process that starts the session through a ; \tilde{B} are the roles of the service processes; \tilde{C} are the roles, in \tilde{B} , that a choreography implements for the shared channel a , enabling compositionality of services. Whenever we write $a : G \langle A | \tilde{B} | \tilde{C} \rangle$ in Γ , we assume that $\tilde{C} \subseteq \tilde{B}$, $A \notin \tilde{B}$, and that $A, \tilde{B} = \text{roles}(G)$. $\text{roles}(G)$ returns the set of roles in a global type G .

We can write $\Gamma, p : k[A]$ only if p is not associated to any other role in session k in Γ (a process may only play one role per session). A process p may however appear more than once in a same Γ , allowing processes to run multiple sessions. As usual, we require all other kinds of occurrences in environments to have disjoint identifiers.

A typing judgement $\Gamma \vdash C \triangleright \Delta$ establishes that a choreography C is well-typed. Intuitively, C is well-typed if shared channels are used according to Γ and sessions are used according to Δ . Δ gives the session types of the free sessions in C . Following the design idea that services should always be available, shared by other models [7, 8], we assume that all (*acc*) terms in a choreography are not guarded by other actions. A selection of the rules defining our typing judgement is reported in Fig. 4.

We comment the typing rules. Rule $\llbracket^T \rrbracket_{\text{START}}$ types a $(\text{start}); a : G \langle A | \tilde{B} | \tilde{B} \rangle$ checks that the choreography should implement all roles in protocol G ; processes \tilde{q} are checked to

$$\begin{array}{c}
\text{[T]}_{\text{START}} \frac{\Gamma, a : G\langle A|\tilde{B}|\tilde{C} \rangle, \Gamma' \vdash C \triangleright \Delta, \Delta' \quad r[c] \in p[A], \widetilde{q[B]} \Leftrightarrow (r : k[c] \in \Gamma' \wedge k[c] : \llbracket G \rrbracket_c \in \Delta') \quad \tilde{q} \notin \Gamma}{\Gamma, a : G\langle A|\tilde{B}|\tilde{C} \rangle \vdash p[A] \text{ starts } \widetilde{q[B]} : a(k); C \triangleright \Delta} \\
\text{[T]}_{\text{SEL}} \frac{j \in I \quad \Gamma \vdash p : k[A], q : k[B] \quad \Gamma \vdash C \triangleright \Delta, k[A] : T_j, k[B] : T'_j}{\Gamma \vdash p[A] \rightarrow q[B] : k[l_j]; C \triangleright \Delta, k[A] : \oplus B\{l_i : T_i\}_{i \in I}, k[B] : \& A\{l_i : T'_i\}_{i \in I}} \\
\text{[T]}_{\text{REQ}} \frac{\Gamma \vdash x @ p : G\langle A|\tilde{B}|\emptyset \rangle \quad \Gamma, p : k[A] \vdash C \triangleright \Delta, k[A] : \llbracket G \rrbracket_A}{\Gamma \vdash p[A] \text{ req } \tilde{B} : x(k); C \triangleright \Delta} \quad \text{[T]}_{\text{PAR}} \frac{\Gamma, \Gamma_i \vdash C_i \triangleright \Delta_i}{\Gamma, \Gamma_1 \circ \Gamma_2 \vdash C_1 \mid C_2 \triangleright \Delta_1, \Delta_2} \\
\text{[T]}_{\text{ACC}} \frac{\Gamma, a : G\langle D|\tilde{B}|\emptyset \rangle, \Gamma' \vdash C \triangleright \Delta, \Delta' \quad r[c] \in \widetilde{q[A]} \Leftrightarrow (r : k[c] \in \Gamma' \wedge k[c] : \llbracket G \rrbracket_c \in \Delta') \quad \tilde{q} \notin \Gamma}{\Gamma, a : G\langle D|\tilde{B}|\tilde{A} \rangle \vdash \text{acc } \widetilde{q[A]} : a(k); C \triangleright \Delta} \\
\text{[T]}_{\text{COM-S}} \frac{\Gamma \vdash e @ p : S \quad \Gamma \vdash p : k[A] \quad \Gamma \vdash C \triangleright \Delta, k[A] : T \quad q : k[B] \notin \Gamma}{\Gamma \vdash p[A].e \rightarrow B : k; C \triangleright \Delta, k[A] : !B\langle S \rangle; T} \quad \text{[T]}_{\text{ZERO}} \frac{\text{cosha}(\Gamma) \quad \Delta \text{ end only}}{\Gamma \vdash \mathbf{0} \triangleright \Delta} \\
\text{[T]}_{\text{BRANCH}} \frac{i \in I \quad \Gamma \vdash C_i \triangleright \Delta, k[A] : T_i \quad I \subseteq J \quad p : k[A] \notin \Gamma}{\Gamma \vdash A \rightarrow q[B] : k \& \{l_i : C_i\}_{i \in I} \triangleright \Delta, k[B] : \& B\{l_j : T_j\}_{j \in J}}
\end{array}$$

Fig. 4. Typing Rules for Compositional Choreographies (selection).

be fresh ($\tilde{q} \notin \Gamma$); the continuation C is checked by updating Γ' and Δ' respectively with the process ownerships for their roles in k and the local types for their behaviour in k . [T]_{SEL} deals with selection, checking that the selected label l_j is specified in the local types. In rule [T]_{REQ} , we check that the choreography requesting the services is not responsible for implementing them, to avoid deadlocks due to the lack of services in parallel required by rule $\text{[C]}_{\text{P-START}}$, and that the requesting process behaves as expected by its role in the protocol. Conversely, [T]_{ACC} types an (*acc*) term by ensuring that all the roles for which the choreography is responsible are implemented (the other checks are similar to $\text{[T]}_{\text{START}}$). This *distribution* of the responsibilities for implementing the different roles in a protocol is handled by rule [T]_{PAR} , using the role distribution function $\Gamma_1 \circ \Gamma_2$. Formally, $\Gamma_1 \circ \Gamma_2$ is defined as the union of Γ_1 and Γ_2 except for the typing of shared channels with the same name, which are merged with the following rule:

$$a : G\langle A|\tilde{B}|\tilde{C} \rangle = a : G\langle A|\tilde{B}|\tilde{D} \rangle \circ a : G\langle A|\tilde{B}|\tilde{E} \rangle \quad (\tilde{C} = \tilde{D} \uplus \tilde{E})$$

In rule [T]_{ZERO} we check that all responsibilities have been implemented and that the sessions in Δ have been executed. Specifically, predicate $\text{cosha}(\Gamma)$ checks that for every $a : G\langle A|\tilde{B}|\tilde{C} \rangle$ in Γ either (i) $\tilde{C} = \tilde{B}$, meaning that a was used only internally with (*start*) terms; or (ii) $\tilde{C} = \emptyset$, meaning that a is used compositionally in collaboration with other choreographies and all roles that the current choreography is responsible for (\tilde{C}) have been implemented correctly with (*acc*) terms. Rules $\text{[T]}_{\text{COM-S}}$ and $\text{[T]}_{\text{BRANCH}}$ type respectively a sending action and a branching. They are very similar to their complete versions since local types allow us to look at the behaviour of processes independently. They also check that the counterpart for the partial action is not in the continuation, by ensuring that there is not process q such that q plays the other role for session k in Γ , which could obviously lead to a deadlock because process p would not have another process to communicate with in parallel as required by rule [C]_{SYNC} .

Typing Expressiveness. Our typing system exploits the global information given by complete terms and seamlessly falls back to typical session typing when dealing with partial actions. In particular, $\llbracket \cdot \rrbracket_{\text{SEL}}$ judges that a choice in a protocol is implemented correctly even if only one of the branches is actually followed. This is sound because we are typing a complete term, and therefore we know that the other branches are not used. This expressiveness is typical of choreography-based models [7, 8]. However, such a global knowledge is not available in a partial choreography. For example, in rule $\llbracket \cdot \rrbracket_{\text{BRANCH}}$ we cannot know which branch will be selected by the sender and we must therefore require that the receiver process supports at least all the branches specified by the corresponding local type, as in standard session typing for endpoints [13, 14].

Properties. We conclude this section by presenting the expected main properties of our type system. Below, to state session fidelity, we use the transition of local types $\Delta \xrightarrow{\alpha} \Delta'$ (defined as [14] and fully given in [1]), where α types a partial or complete action. $\alpha \vdash \lambda$ judges that the label λ is for the same session as α and respects its roles and carried type. We also extend our typing judgement with the extra environment Σ , for handling session ownerships with asynchronous delegations at runtime (see [1]).

Theorem 1 (Typing Soundness). *Let $\Gamma; \Sigma \vdash C \triangleright \Delta$. Then,*

- (Subject Swap) $C \simeq_C C'$ implies $\Gamma; \Sigma \vdash C' \triangleright \Delta$.
- $C \xrightarrow{\lambda} C'$ implies that there exists Δ' such that
 - (Subject Reduction) $\Gamma'; \Sigma' \vdash C' \triangleright \Delta'$ for some Γ', Σ' ;
 - (Session Fidelity) if λ is a communication on session k , then $\Delta \xrightarrow{\alpha} \Delta'$ with $\alpha \vdash \lambda$; else, $\Delta = \Delta'$.

5 Properties of Compositional Choreographies

This section states the main properties of our framework wrt the execution of actual systems composed by endpoints.

Endpoint Projection (EPP) generates correct endpoint code from a choreography. Formally, by endpoint code we refer to choreographies that do not contain complete actions. To define the complete EPP, we first define how the behaviour of a single process in a choreography can be projected. We denote this *process projection* of a process p in a choreography C with $\llbracket C \rrbracket_p$. Selected rules of process projection are given below:

$$\begin{aligned}
 & \llbracket p[A] \text{ starts } \widetilde{q[B]} : a(k); C \rrbracket_r & \llbracket p[A].e \rightarrow q[B].x : k; C \rrbracket_r \\
 & = \begin{cases} \llbracket p[A] \text{ req } \widetilde{B} : a(k); [C] \rrbracket_r & \text{if } r = p \\ \llbracket \text{acc } r[C] : a(k); [C] \rrbracket_r & \text{if } r[C] \in \widetilde{q[B]} \\ \llbracket [C] \rrbracket_r & \text{otherwise} \end{cases} & = \begin{cases} \llbracket p[A].e \rightarrow B : k; [C] \rrbracket_r & \text{if } r = p \\ \llbracket A \rightarrow q[B].x : k; [C] \rrbracket_r & \text{if } r = q \\ \llbracket [C] \rrbracket_r & \text{otherwise} \end{cases} \\
 & \llbracket p[A].e \rightarrow B : k; C \rrbracket_r & \llbracket A \rightarrow q[B].x : k; C \rrbracket_r \\
 & = \begin{cases} \llbracket p[A].e \rightarrow B : k; [C] \rrbracket_r & \text{if } r = p \\ \llbracket [C] \rrbracket_r & \text{otherwise} \end{cases} & = \begin{cases} \llbracket A \rightarrow q[B].x : k; [C] \rrbracket_r & \text{if } r = p \\ \llbracket [C] \rrbracket_r & \text{otherwise} \end{cases} \\
 & \llbracket \text{if } e @ p \text{ then } C_1 \text{ else } C_2 \rrbracket_r & \llbracket A \rightarrow q[B] : k \& \{l_i : C_i\}_{i \in I} \rrbracket_r \\
 & = \begin{cases} \llbracket \text{if } e @ p \text{ then } [C_1]_r \text{ else } [C_2]_r & \text{if } r = p \\ \llbracket [C_1]_r \sqcup [C_2]_r & \text{otherwise} \end{cases} & = \begin{cases} \llbracket A \rightarrow q[B] : k \& \{l_i : [C_i]_r\}_{i \in I} & \text{if } r = q \\ \llbracket \bigsqcup_{i \in I} [C_i]_r & \text{otherwise} \end{cases}
 \end{aligned}$$

Process projection follows the structure of the originating choreography. In a (*start*), we

project the active process p to a request and the service processes \tilde{q} to (always-available) accepts. In a (com) , the sender is projected to a partial sending action and the receiver to a partial receiving action. The projections of (sel) and (del) , omitted, follow the same principle. Above we also report the rule for projecting $(com-s)$ and $(com-r)$ to exemplify how we treat partial choreographies: these are simply projected as they are for their respective process, following the structure of the choreography. The projections of conditionals and partial branchings are the only special cases. In a conditional, we project it as it is for the process evaluating the condition, but for all other we merge their behaviours with the *merging* partial operator \sqcup [7]. $C \sqcup C'$ is defined only for partial choreographies that define the behaviour of a single process and returns a choreography isomorphic to C and C' up to branching, where all branches with distinct labels are also included. We use \sqcup also in the projection of $(branch)$ terms, where we require the behaviour of all processes not receiving the selection to be merged. As an example, the process projection for process u in the choreography C_B from our example in § 2 is:

$$\begin{aligned} & u[\mathbb{U}] \text{ req } PD : a(k); u[\mathbb{U}].prod \rightarrow PD : k; \\ \llbracket C_B \rrbracket_u = & PD \rightarrow u[\mathbb{U}] : k \& \left\{ \begin{array}{l} del : PD \rightarrow u[\mathbb{U}] : k\langle k''[\mathbb{B}] \rangle; u[\mathbb{B}].addr \rightarrow T : k''; \\ T \rightarrow u[\mathbb{U}].ddate : k'', \\ quit : 0 \end{array} \right\} \end{aligned}$$

Using process projection, we can now define the EPP of a whole system. Since different service processes may be started through $(start)$ terms on the same shared channel and play the same role, we use \sqcup for merging their behaviours into a single service. We identify these processes with the service grouping operator $\llbracket C \rrbracket_A^a$, which computes the set of all service process names in a start or a request in C on shared channel a playing role A . Formally, EPP is the endofunction $\llbracket C \rrbracket$ defined in the following.

Definition 1 (Endpoint Projection). Let $C \equiv (\nu \tilde{a}, \tilde{k}, \tilde{p}) C_f$, where C_f does not contain (res) terms. Then, the EPP of C is:

$$\llbracket C \rrbracket = (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) \left(\prod_{p \in \text{fn}(C_f)} \llbracket C_f \rrbracket_p \right) \mid \prod_{a, A} \left(\bigsqcup_{p \in \llbracket C_f \rrbracket_A^a} \llbracket C_f \rrbracket_p \right) \right)$$

The EPP of a choreography C is the parallel composition of (i) the projections of all active processes and (ii) the merged projections of all service processes started under same shared channel and role. EPP respects the following Lemma, which shows that our model can adequately capture not only typical complete choreographies, but also scale down to describing the behaviour of a single endpoint.

Lemma 1 (Endpoint Choreographies). Let C be restriction-free, contain only partial terms, and be well-typed. If one of the following two conditions apply, then $C = \llbracket C \rrbracket$.

1. $C = \text{acc } q[\mathbb{B}] : a(k); C'$ and q is the only free process name in C' ;
2. otherwise, C has only one free process name.

We refer to choreographies that respect one of the two conditions above as *endpoint choreographies*. They implement either the behaviour of a single always-available service process (1), or that of a single free process (2). The EPP for these choreographies is the identity since they already model the behaviour of only one endpoint.

The projection of services may lead to undesirable behaviour if service roles for shared channels are not distributed correctly. For example, if we put the choreography C_B from § 2 in parallel with a choreography with a conflicting service on shared channel b for role R (which is internally implemented in C_B) we obtain a race condition, *even if protocols are correctly implemented*. Consider the following choreography:

$$C_R = \text{acc } h[R] : b(k'); \text{PD} \rightarrow h[R].x : k'; h[R].c \rightarrow \text{PD} : k'$$

If we put the projection of C_B in parallel with that of C_R , we get a race condition between the service processes r and h for role R on shared channel b . Hence, the projection of process pd may synchronise with the service offered by C_R for creating session k' , instead of that by the projection of service process r in C_B . Consequently, C_B may not follow its intended behaviour. The distribution of service roles performed by our type system avoids this kind of situations. Observe that normal session typing cannot help us in detecting these problems, because the service process h correctly implements the same communication behaviour for session k' as service process r .

Main Theorems. We can now present our main theorems. We build our results on the foundation that the EPP of a choreography is still typable. As in previous work [17, 7, 8], we need to consider that in the projection of complete choreographies, due to merging, some projected processes may still offer branches that the original complete choreography has discarded with a conditional. Therefore, we state our type preservation result below under the *minimal typing* of choreographies \vdash_{\min} , in which the branches in rules $[\cdot]_{\text{SEL}}^T$ and $[\cdot]_{\text{BRANCH}}^T$ are typed using the respective minimal branch types.

Theorem 2 (EPP Type Preservation). *Let $\Gamma \vdash_{\min} C \triangleright \Delta$. Then, $\Gamma \vdash_{\min} \llbracket C \rrbracket \triangleright \Delta$.*

By Theorem 2, it follows that Theorem 1 applies also to the EPP of a choreography. We use this result to prove that EPP correctly implements the behaviour of the originating choreography, by establishing a formal relation between their respective semantics.

Theorem 3 (EPP Theorem). *Let $C \equiv (\nu \tilde{a}, \tilde{k}, \tilde{p}) C_f$, where C_f is restriction-free, be well-typed. Then,*

1. (Completeness) $C \xrightarrow{\lambda} C'$ implies $\llbracket C \rrbracket \xrightarrow{\lambda} \succ \llbracket C' \rrbracket$.
2. (Soundness) $\llbracket C \rrbracket \xrightarrow{\lambda} C'$ implies $C \xrightarrow{\lambda} C''$ and $\llbracket C'' \rrbracket \prec C'$.

Above, the *pruning relation* $C \prec C'$ is a strong typed bisimilarity [7] such that C has some unused branches and always-available accepts. \succ is a shortcut for \prec interpreted in the opposite direction.

Deadlock-freedom and Progress. We introduce our results on deadlock-freedom and progress mentioned in the Introduction. First, we define deadlock-freedom:

Definition 2 (Deadlock-freedom). *We say that choreography C is deadlock-free if either (i) $C \equiv \mathbf{0}$ or (ii) there exist C' and λ such that $C \xrightarrow{\lambda} C'$ and C' is deadlock-free.*

In our semantics (Fig. 3) complete terms can always be executed; therefore, choreographies that do not contain partial terms, or *complete choreographies*, are deadlock-free:

Theorem 4 (Deadlock-freedom for Complete Choreographies). *Let C be a complete choreography and contain no free variable names. Then, C is deadlock-free.*

By Theorems 3 and 4 we can obtain, as a corollary, that the EPP of well-typed complete choreographies never deadlock.

Corollary 1 (Deadlock-freedom for EPP). *Let C be a complete choreography, contain no free variable names, and be well-typed. Then, $\llbracket C \rrbracket$ is deadlock-free.*

Our model can also be used to talk of deadlock-freedom *compositionally*. In a compositional setting, a choreography may get stuck because of partial actions that need to be executed in parallel composition with other choreographies. We say that a choreography can *progress* if it can be composed with another choreography such that (i) all free names can be restricted and the resulting system is still well-typed, ensuring that protocols are implemented correctly; and (ii) the composition is deadlock-free. Differently from deadlock-freedom for complete choreographies, progress for partial choreographies does not follow directly from the semantics. For example, the following choreography does not have the progress property:

$$A \rightarrow q[B] : k; p[A].e \rightarrow B : k$$

Above, q is waiting for a message on session k from A , but that role is implemented by process p in the continuation. Thus, the two partial actions will never synchronise. As shown in § 4, our type system takes care of checking that roles in sessions or services are distributed correctly, avoiding cases such as this one and ensuring progress. In general, if a well-typed choreographies does not contain inner (*par*) terms we know that it can progress, since role distribution ensures that there exists a compatible environment.

Theorem 5 (Progress for Partial Choreographies). *Let C be a choreography, be well-typed, and contain no (*par*) terms. Then, there exists C' such that $(\nu \tilde{r}) (C \mid C')$ with $\tilde{r} = \text{fn}(C \mid C')$, is well-typed and deadlock-free.*

By Theorems 2 and 5, it follows as a corollary that also the EPP of a well-typed choreography can progress:

Corollary 2 (Progress for EPP). *Let C contain no free variable names, be well-typed, and contain no (*par*) terms. Then, there exists C' such that $(\nu \tilde{r}) (\llbracket C \rrbracket \mid C')$ with $\tilde{r} = \text{fn}(C \mid C')$, is well-typed and deadlock-free.*

Correctness of Choreography Composition. We end this section by presenting results that allow to reason about the composition of choreographies.

Lemma 2 (Compositional EPP). *Let $C = C_1 \mid C_2$ be well-typed. Then, $\llbracket C \rrbracket \equiv \llbracket C_1 \rrbracket \mid \llbracket C_2 \rrbracket$.*

By combining Lemma 2 with the Theorems shown so far, we get the following corollary, which summarises the properties for well-typed compositions of choreographies.

Corollary 3 (Compositional Choreographies). *Let $C \mid C'$ be well-typed. Then,*

1. (*EPP Type Preservation*) $\llbracket C \rrbracket \mid \llbracket C' \rrbracket$ is well-typed.
2. (*Completeness*) $C \mid C' \xrightarrow{\lambda} C''$ implies $\llbracket C \rrbracket \mid \llbracket C' \rrbracket \xrightarrow{\lambda} \succ \llbracket C'' \rrbracket$.
3. (*Soundness*) $\llbracket C \rrbracket \mid \llbracket C' \rrbracket \xrightarrow{\lambda} C''$ implies $C \xrightarrow{\lambda} C'''$ and $\llbracket C''' \rrbracket \prec C''$.

Our corollary above formally addresses the issues mentioned in the Introduction. Choreographies (C and C' in the corollary) can be developed independently and then their respective projections can be composed.

6 Related Work

Previous works have tackled the problem of defining a formal model for choreographies and giving a correct EPP [8, 7]. The main difference wrt our work is compositionality: previous models can only capture closed systems, and do not treat a methodology for composing choreographies. A major difficulty wrt composition given by the approach in [8] is that the EPP of a choreography could be untypable with known type systems for session types. Typability of EPP is important to achieve composition, since a programmer may need to reuse a choreography *after* it has been projected. [8] is the only previous work providing an asynchronous semantics for multiparty sessions in choreographies; however, asynchrony is modelled in two different ways in the choreography model and the endpoint model, raising complexity. As a consequence, the EPP Theorem in [8] has a more complex formulation with weak transitions and confluence, whereas ours can be formulated in a stronger form where EPP mimics its original choreography step by step. [7] preserves typability of projections but does not handle neither asynchrony nor multiparty sessions; instead, they type choreographies with binary sessions. We have shown that choreographies can be made compositional by introducing partial terms to perform message passing with the environment, and that it is possible to ensure typability of EPP in a multiparty and asynchronous setting. This is the first work introducing a compositional multiparty session typing for choreographies, exploiting the projection of global types onto local types. Finally, neither of [8, 7] handles shared channel passing, and does not treat how to handle delegation in a compositional setting, where sessions may be delegated to external or internal processes.

Multiparty session types have been previously used for typing endpoint programs [14, 3, 10]. In our setting, endpoint programs can be captured as special cases of partial choreographies. Our global types are taken from [3]. Differently from our framework, these works capture asynchronous communications with dedicated processes that model order-preserving message queues. An approach more similar to ours can be found in the notion of *delayed input* presented in [18]. [3] defines a type system for progress by building additional restrictions on top of standard multiparty session typing; our model yields a simpler analysis, since we can rely on the fact that complete terms in a choreography do not get stuck. Nevertheless, [3] can capture sessions started by more than one active thread. We leave an extension of our model in this direction as future work.

In [2] the authors use a concept similar to our partial choreographies for protocol specifications, to allow a single process to implement more than one role in a protocol. Differently from our approach, these are not fully-fledged system implementations but abstract behavioural types, which are then used to type check endpoint code. In our setting, the techniques in [2] can be seen as a more flexible way of handling the projection from global types to local types. An extension of our type system to allow for a process to play more than one role in a session as in [2, 10] is an interesting future work.

The relationship between choreographies and endpoints has been explored in, among others, [5, 17, 14, 7, 8]. Our work distinguishes itself by adopting the same calculus for describing choreographies and endpoints, simplifying the technical development.

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A Complete Use Case

We report an extended version of our case study, in which the buyer choreography also perform an internal authentication of its user before proceeding with the purchase.

Buyer Choreography. We define the choreography for the buyer, C_B . For clarity, we have extracted two parts of it in separate terms, C'_B and C''_B . C_B starts with a choreography for its internal network, where it performs some checks for authenticating a user. Then, it proceeds by dynamically selecting a seller in C'_B , which is finally contacted with a partial choreography in C''_B . The code follows.

$$\begin{aligned}
C_B = & \begin{aligned} & 1. \text{u}[\text{U}] \text{ starts } \text{a}[\text{A}], \text{pd}[\text{PD}] : a(k); \quad \text{u}[\text{U}].\text{cred} \rightarrow \text{a}[\text{A}].x : k; \\ & 2. \text{if } \text{auth}(x) @ \text{a} \text{ then} \\ & 3. \quad \text{a}[\text{A}] \rightarrow \text{pd}[\text{PD}] : k(ok); \quad \text{pd}[\text{PD}] \rightarrow \text{u}[\text{u}] : k(ok); \\ & 4. \quad \text{u}[\text{U}].\text{prod} \rightarrow \text{pd}[\text{PD}].y : k; \quad C'_B \\ & 5. \text{else} \\ & 6. \quad \text{a}[\text{A}] \rightarrow \text{pd}[\text{PD}] : k(quit); \quad \text{pd}[\text{PD}] \rightarrow \text{u}[\text{u}] : k(quit) \end{aligned} \\
C'_B = & \begin{aligned} & 7. \text{pd}[\text{PD}] \text{ starts } \text{r}[\text{R}] : b(k'); \quad \text{pd}[\text{PD}].y \rightarrow \text{r}[\text{R}].z : k'; \\ & 8. \text{r}[\text{R}].\text{find}(z) \rightarrow \text{pd}[\text{PD}].w : k'; \quad C''_B \\ & 9. \text{pd}[\text{B}] \text{ req } \text{C}, \text{T} : w(k''); \quad \text{pd}[\text{B}].y \rightarrow \text{C} : k''; \\ & 10. \text{C} \rightarrow \text{pd}[\text{B}].x_2 : k''; \\ & 11. \text{if } \text{check}(x_2) @ \text{pd} \text{ then} \\ & 12. \quad \text{pd}[\text{B}] \rightarrow \text{T} : k'' \oplus ok; \quad \text{pd}[\text{PD}] \rightarrow \text{u}[\text{U}] : k(del); \quad \text{pd}[\text{PD}] \rightarrow \text{u}[\text{U}] : k(k''[\text{B}]); \\ & 13. \quad \text{u}[\text{B}].\text{addr} \rightarrow \text{T} : k''; \quad \text{T} \rightarrow \text{u}[\text{B}].\text{ddate} : k'' \\ & 14. \text{else} \\ & 15. \quad \text{pd}[\text{B}] \rightarrow \text{T} : k'' \oplus quit; \quad \text{pd}[\text{PD}] \rightarrow \text{u}[\text{U}] : k(quit) \end{aligned}
\end{aligned}$$

We comment the code above. Inside the buyer, a purchase is initiated by a user process u . In Line 1, process u and the freshly created processes a and pd start a session k by synchronising on shared channel a . Each process is annotated with the role it plays in the protocol that the session implements (we omit the protocol for session k). Then, u sends her credentials “ $cred$ ” to a . In Line 2, a tries to authenticate the credentials. If successful, in Line 3 the choice ok is communicated to the others and in Line 4 u sends the name of the product she wishes to purchase to pd ; the choreography proceeds then as C'_B . Otherwise, the choice $quit$ is communicated from a to the others.

C'_B defines how the buyer actually purchases the product. In our use case, the buyer has a registry of suppliers that reports which seller should be used for purchasing each kind of product. This aspect is captured by *mobility of shared channels*. In Line 7 pd starts a new session k' with a fresh process r through shared channel b . Then, pd sends the name of the product to be purchased to r . In Line 8, r sends to pd the name of the shared channel to contact the selected seller, computed with the internal function $\text{find}(z)$, to pd . Finally, the choreography proceeds as C''_B .

C''_B is a partial choreography that relies on an external seller to implement the protocol shown in the introduction and perform the purchase. In Line 9, pd *requests* a synchronisation on the shared channel stored in its local variable w to create the new session k'' . pd declares that it will play role B , and that it expects the environment to implement roles C and T for session k'' . Session k'' proceeds now as specified by the protocol in the introduction. First, right after the request in Line 9, pd sends the product name y through session k'' to the external process that is playing role C (the product catalogue executed by the seller). Observe that here we do not specify the actual process name of the receiver, since that will be established by the environment. In Line 10, pd waits to receive the price for the product from the external process playing role C in

k'' . In Line 11, pd checks whether the price is acceptable. If so, in Line 12 it will tell the external process playing role T (the transport process executed by the seller) and user u (which remains internal to the buyer choreography) to proceed with the purchase (labels ok and del respectively). Still in Line 13, pd will also *delegate* to u the continuation of session k'' in its place, as role B . In Line 14, the user can now send her delivery address to T and receive the expected delivery date. If the price is not acceptable, then in Lines 15-16 pd informs the others to quit the purchase attempt.

Seller Choreography and Composition. We define now a choreography for a seller that can be contacted by C_B (through C_B''). The exact seller system contacted by C_B'' depends on the result of $\text{find}(z)$ in C_B' . Let us assume that find returns shared channel c for computer-related products, and c' for every other kind of products; we refer to the choreography implementations of the respective seller companies as C_S and C_S' . Below, we define the implementation for the first (the second is similar).

$$C_S = \begin{array}{l} 1. \text{acc } c[C], t[T] : c(k''); \quad B \rightarrow c[C].y_2 : k''; \\ 2. c[C].\text{price}(y_2) \rightarrow B : k''; \\ 3. B \rightarrow t[T] : k'' \& \left\{ \begin{array}{l} ok : B \rightarrow t[T].daddr : k''; \quad t[T].\text{time}(daddr) \rightarrow B : k'' \\ quit : \mathbf{0} \end{array} \right\} \end{array}$$

Above, the seller choreography C_S starts by *accepting* the creation of session k'' through shared channel c , offering to spawn two fresh processes c and t . Choreographies starting with an acceptance act as replicated processes, modeling typical always-available modules. The acceptance in Line 1 would synchronise with the request made by C_B'' in the case for $w = c$. Right afterwards, still in Line 1, $c[C]$ expects to receive the product name from the process playing B in session k'' . In Line 2, c sends back the price for the product. Finally, in Line 3, t (the process for the transport) waits to receive either label ok or $quit$. In the first case, t will also wait to receive a delivery address and send back the expected time of arrival.

Now that we have the code for both buyer and seller companies (we omit the code for C_S'), we can compose their choreographies in a network with the parallel operator $|$ as: $C = C_B | C_S | C_S'$. Parallel composition allows different choreographies to communicate with each other through the interaction of their partial terms.

B Auxiliary Definitions

This section lists the auxiliary definitions.

B.1 Structural Congruence

Structural congruence \equiv for C is the smallest congruence supporting α -conversion and satisfying the following rules:

$$\begin{aligned}
(\nu r) \mathbf{0} &\equiv \mathbf{0} & (\nu r) (\nu r') C &\equiv (\nu r') (\nu r) C & \text{rec } X(\widetilde{x@p}, \tilde{k}, \tilde{p}) = C \text{ in } \mathbf{0} &\equiv \mathbf{0} \\
\text{rec } X(\widetilde{x@p}, \tilde{k}, \tilde{p}) = C' \text{ in } (\nu r) C &\equiv (\nu r) \text{rec } X(\widetilde{x@p}, \tilde{k}, \tilde{p}) = C' \text{ in } C & \text{if } r \notin \text{fn}(C') \\
\text{rec } X(\widetilde{x@p}, \tilde{k}, \tilde{p}) = C' \text{ in } X(\widetilde{v@p}, \tilde{k}, \tilde{p}) &\equiv \text{rec } X(\widetilde{x@p}, \tilde{k}, \tilde{p}) = C' \text{ in } C'[\tilde{v}/\tilde{x@p}] \\
C \mid C' &\equiv C' \mid C & ((\nu r) C) \mid C' &\equiv (\nu r) (C \mid C') \text{ if } r \notin \text{fn}(C') \\
(C_1 \mid C_2) \mid C_3 &\equiv C_1 \mid (C_2 \mid C_3)
\end{aligned}$$

B.2 Swap Relations

As in previous models [7, 8], we assume that all processes described in a choreography run in parallel. We represent this concurrent behaviour with the swapping relation \simeq_C , which allows us to swap terms that describe the behaviour of different threads. \simeq_C is defined as the smallest congruence closed under the rules in Fig. 5. Rule $\llbracket^{\text{SW}}\rrbracket_{\text{ETA-ETA}}$ han-

$$\begin{aligned}
\llbracket^{\text{SW}}\rrbracket_{\text{ETA-ETA}} \quad \text{pn}(\eta) \cap \text{pn}(\eta') = \emptyset &\Rightarrow \eta; \eta' \simeq_C \eta'; \eta \\
&\text{if } e@p \text{ then (if } e'@q \text{ then } C_1 \text{ else } C_2) \text{ else (if } e'@q \text{ then } C'_1 \text{ else } C'_2) \\
\llbracket^{\text{SW}}\rrbracket_{\text{COND-COND}} \quad p \neq q &\Rightarrow \text{if } e'@q \text{ then (if } e@p \text{ then } C_1 \text{ else } C'_1) \text{ else (if } e@p \text{ then } C_2 \text{ else } C'_2) \\
&\simeq_C \text{if } e'@q \text{ then (if } e@p \text{ then } C_1 \text{ else } C_2) \text{ else (if } e'@q \text{ then } C'_1 \text{ else } C'_2) \\
\llbracket^{\text{SW}}\rrbracket_{\text{ETA-COND}} \quad p \notin \text{pn}(\eta) &\Rightarrow \text{if } e@p \text{ then } (\eta; C_1) \text{ else } (\eta; C_2) \simeq_C \eta; (\text{if } e@p \text{ then } C_1 \text{ else } C_2) \\
\llbracket^{\text{SW}}\rrbracket_{\text{ETA-BR}} \quad q \notin \text{pn}(\eta) &\Rightarrow A \rightarrow q[B] : k \& \{l_i : \eta; C_i\}_{i \in I} \simeq_C \eta; A \rightarrow q[B] : k \& \{l_i : C_i\}_{i \in I} \\
&A \rightarrow p[B] : k \& \{l_i : C \rightarrow q[D] : k' \& \{l'_{ij} : C_{ij}\}_{j \in J}\}_{i \in I} \\
\llbracket^{\text{SW}}\rrbracket_{\text{BR-BR}} \quad p \neq q &\Rightarrow C \rightarrow q[D] : k' \& \{l'_j : A \rightarrow p[B] : k \& \{l_{ij} : C_{ij}\}_{i \in I}\}_{j \in J} \\
&\simeq_C A \rightarrow p[B] : k \& \{l_i : \text{if } e@q \text{ then } C_{i1} \text{ else } C_{i2}\}_{i \in I} \\
\llbracket^{\text{SW}}\rrbracket_{\text{BR-COND}} \quad p \neq q &\Rightarrow \text{if } e@q \text{ then (} A \rightarrow p[B] : k \& \{l_i : C_{i1}\}_{i \in I} \text{) else (} A \rightarrow p[B] : k \& \{l_i : C_{i2}\}_{i \in I} \text{)} \\
&\simeq_C \text{if } e@q \text{ then (} A \rightarrow p[B] : k \& \{l_i : C_{i1}\}_{i \in I} \text{) else (} A \rightarrow p[B] : k \& \{l_i : C_{i2}\}_{i \in I} \text{)}
\end{aligned}$$

Fig. 5. Global/Local Calculus, swap relation \simeq_C .

dles the swapping of two interactions that do not share any process identifier (pn is a function that computes the set of process identifiers, or names, in a term). $\llbracket^{\text{SW}}\rrbracket_{\text{COND-COND}}$ swaps two conditionals if they are performed by different processes. The other rules work similarly, handling the cases for (*branch*) terms and the other possible combinations.

We also define the smallest congruence for swapping global types satisfying the rules in Fig. 6.

$$\begin{aligned}
[\text{GS}]_{\text{COM-COM}} & \frac{\{A, B\} \cap \{C, D\} = \emptyset}{A \rightarrow B : \langle U \rangle \simeq_G C \rightarrow D : \langle U' \rangle} \\
[\text{GS}]_{\text{COM-BR}} & \frac{\{A, B\} \cap \{C, D\} = \emptyset}{A \rightarrow B : \{l_i : C \rightarrow D : \langle U \rangle; G_i\}_{i \in I} \simeq_G C \rightarrow D : \langle U \rangle; A \rightarrow B : \{l_i : G_i\}_{i \in I}} \\
[\text{GS}]_{\text{BR-BR}} & \frac{\{A, B\} \cap \{C, D\} = \emptyset}{A \rightarrow B : \{l_i : C \rightarrow D : \{l_j : G_{ij}\}_{j \in J}\}_{i \in I} \simeq_G C \rightarrow D : \{l_j : A \rightarrow B : \{l_i : G_{ij}\}_{i \in I}\}_{j \in J}}
\end{aligned}$$

Fig. 6. Global Types, swap relation \simeq_G .

$$\begin{aligned}
[\text{G}]_{\text{COM}} & \quad A \rightarrow B : \langle U \rangle; G \xrightarrow{A \rightarrow B : \langle U \rangle} G \quad [\text{G}]_{\text{BRA}} \quad A \rightarrow B : \{l_i : G_i\}_{i \in I \cup \{j\}} \xrightarrow{A \rightarrow B : \langle l_j \rangle} G_j \\
[\text{G}]_{\text{REC}} & \quad G[\mu \mathbf{t}. G / \mathbf{t}] \xrightarrow{\alpha} G' \Rightarrow \mu \mathbf{t}. G \xrightarrow{\alpha} G' \\
[\text{G}]_{\text{SWAP}} & \quad G_1 \simeq_G G'_1 \xrightarrow{\alpha} G'_2 \simeq_G G_2 \Rightarrow G_1 \xrightarrow{\alpha} G_2 \\
[\text{G}]_{\text{ACOM}} & \quad \left. \begin{array}{l} G \xrightarrow{\alpha} G' \\ A \in \text{roles}(\alpha), B \notin \text{roles}(\alpha) \end{array} \right\} \Rightarrow A \rightarrow B : \langle U \rangle; G \xrightarrow{\alpha} A \rightarrow B : \langle U \rangle; G' \\
[\text{G}]_{\text{ABRA}} & \quad \left. \begin{array}{l} G_j \xrightarrow{\alpha} G'_j \\ A \in \text{roles}(\alpha), B \notin \text{roles}(\alpha) \end{array} \right\} \Rightarrow A \rightarrow B : \{l_i : G_i\}_{i \in I \cup \{j\}} \xrightarrow{\alpha} A \rightarrow B : \{l_i : G'_i\}_{i \in I \cup \{j\}}
\end{aligned}$$

Fig. 7. Semantics of Global Types.

B.3 The Labelled Transition Relations for Global and Local Types

Semantics of Global and Local Types. We give a semantics to global and local types for expressing the (abstract) execution of protocols. $G \xrightarrow{\alpha} G'$ is the smallest relation on the recursion-unfolding of global types satisfying the rules reported in Fig. 7. A label α describes which interaction is executed. All rules are standard, from [8], and account for the parallel and asynchronous behaviour of roles.

The semantics of local types is defined with typing environments $\Delta ::= k[A] : T, \Delta \mid \emptyset$. Formally, the semantics of local typings $\Delta \xrightarrow{\alpha} \Delta'$ is defined as the smallest relation closed under the rules reported in Fig. 8. The rules in Fig. 8 follow the intuition of the semantics for partial actions in choreographies. Rules $[\text{L}]_{\text{SEND}}$ and $[\text{L}]_{\text{RECV}}$ model respectively the sending and receiving of values. $[\text{L}]_{\text{SEL}}$ and $[\text{L}]_{\text{BRANCH}}$ abstract selection. Rules $[\text{L}]_{\text{ASEND}}$ and $[\text{L}]_{\text{ASEL}}$ capture asynchrony. In rule $[\text{L}]_{\text{CONC}}$, $\text{rc}(\alpha)$ is similar to $\text{rc}(\lambda)$. Finally, $[\text{L}]_{\text{SYNC}}$ synchronise (abstract) actions that are compatible according to the composition function for abstract labels \circ . Intuitively, $\alpha \circ \alpha'$ is defined for compatible sending/receiving actions and returns the corresponding global label α . For example, $k[A] : !B \langle U \rangle \circ k[B] : ?A \langle U \rangle = k : A \rightarrow B : \langle U \rangle$. All other rules are standard.

$$\begin{array}{l}
\llbracket^L \rrbracket_{\text{SEND}} \quad !\mathbf{A}\langle U \rangle; T \xrightarrow{! \mathbf{A}\langle U \rangle} T \quad \llbracket^L \rrbracket_{\text{RECV}} \quad ?\mathbf{A}\langle U \rangle; T \xrightarrow{? \mathbf{A}\langle U \rangle} T \\
\llbracket^L \rrbracket_{\text{SEL}} \quad \oplus \mathbf{A}\{l_i : T_i\}_{i \in I \cup \{j\}} \xrightarrow{\oplus \mathbf{A}\langle l_j \rangle} T_j \quad \llbracket^L \rrbracket_{\text{BRA}} \quad \&\mathbf{A}\{l_i : T_i\}_{i \in I \cup \{j\}} \xrightarrow{\&\mathbf{A}\langle l_j \rangle} T_j \\
\llbracket^L \rrbracket_{\text{REC}} \quad T[\mu \mathbf{t}. T/\mathbf{t}] \xrightarrow{\alpha} T' \Rightarrow \mu \mathbf{t}. T \xrightarrow{\alpha} T' \\
\llbracket^L \rrbracket_{\text{ASEND}} \quad T \xrightarrow{\alpha} T', \mathbf{A} \notin \text{roles}(\alpha) \Rightarrow !\mathbf{A}\langle U \rangle; T \xrightarrow{\alpha} !\mathbf{A}\langle U \rangle; T' \\
\llbracket^L \rrbracket_{\text{ASEL}} \quad T_j \xrightarrow{\alpha} T'_j, \mathbf{A} \notin \text{roles}(\alpha) \Rightarrow \oplus \mathbf{A}\{l_i : T_i\}_{i \in I \cup \{j\}} \xrightarrow{\alpha} \oplus \mathbf{A}\{l_j : T'_j\} \\
\llbracket^L \rrbracket_{\text{LIFT}} \quad T \xrightarrow{\alpha} T' \Rightarrow k[\mathbf{A}]:T \xrightarrow{k[\mathbf{A}]:\alpha} k[\mathbf{A}]:T' \\
\llbracket^L \rrbracket_{\text{CONC}} \quad \Delta \xrightarrow{\alpha} \Delta' \Rightarrow \Delta, \Delta'' \xrightarrow{\alpha} \Delta', \Delta'' \quad (\text{rc}(\alpha) \notin \Delta'') \\
\llbracket^L \rrbracket_{\text{SYNC}} \quad \Delta_1 \xrightarrow{\alpha} \Delta'_1 \quad \Delta_2 \xrightarrow{\alpha'} \Delta'_2 \Rightarrow \Delta_1 \mid \Delta_2 \xrightarrow{\alpha \circ \alpha'} \Delta'_1 \mid \Delta'_2
\end{array}$$

Fig. 8. Semantics of Local Types.

B.4 Type Projection

We report the rules for projecting a global type onto a corresponding local type, following [11]. Intuitively, gives an encoding of the local actions expected by role \mathbf{A} in the global type G .

$$\begin{array}{ll}
\llbracket \mathbf{A} \rightarrow \mathbf{B} : \langle U \rangle; G \rrbracket_{\mathbf{C}} & \llbracket \mathbf{A} \rightarrow \mathbf{B} : \{l_i : G_i\}_{i \in I} \rrbracket_{\mathbf{C}} \\
= \begin{cases} !\mathbf{B}\langle U \rangle; (\llbracket G \rrbracket_{\mathbf{C}}) & \text{if } \mathbf{C} = \mathbf{A} \\ ?\mathbf{A}\langle U \rangle; (\llbracket G \rrbracket_{\mathbf{C}}) & \text{if } \mathbf{C} = \mathbf{B} \\ \llbracket G \rrbracket_{\mathbf{C}} & \text{otherwise} \end{cases} & = \begin{cases} \oplus \mathbf{B}\{l_i : \llbracket G_i \rrbracket_{\mathbf{C}}\}_{i \in I} & \text{if } \mathbf{C} = \mathbf{A} \\ \&\mathbf{A}\{l_i : \llbracket G_i \rrbracket_{\mathbf{C}}\}_{i \in I} & \text{if } \mathbf{C} = \mathbf{B} \\ \bigsqcup_{i \in I} \llbracket G_i \rrbracket_{\mathbf{C}} & \text{otherwise} \end{cases} \\
\llbracket \mu \mathbf{t}. G \rrbracket_{\mathbf{A}} = \mu \mathbf{t}. \llbracket G \rrbracket_{\mathbf{A}} & \text{(if } \mathbf{A} \in G) \quad \llbracket \mu \mathbf{t}. G \rrbracket_{\mathbf{A}} = \text{end} \quad \text{(otherwise)} \\
\llbracket \mathbf{t} \rrbracket_{\mathbf{A}} = \mathbf{t} & \llbracket \text{end} \rrbracket_{\mathbf{A}} = \text{end}
\end{array}$$

In the rule for projecting a branching, we require the local behaviour of all roles involved in the choice to be *merged* with the merging operator \sqcup . $T \sqcup T'$ is isomorphic to T and T' up to branching, where all branches of T or T' with distinct labels are also included. Our definition of projection from global to local types is the same as in [11], where it is proven sound.

Type projection respects the following Lemma.

Lemma B.1 (Type Projection is invariant under \simeq_G). *Let G and G' be global types. Then, $G \simeq_G G'$ implies $\llbracket G \rrbracket_{\mathbf{A}} = \llbracket G' \rrbracket_{\mathbf{A}}$ for every role \mathbf{A} .*

Proof. Immediate, from the definitions of \simeq_G and type projection, since \simeq_G allows to swap only terms that have different roles.

C Typing

We report all the rules of our typing system. We give first the rules for programs and then the rules for runtime terms.

C.1 Typing rules for programs

Fig. 9 reports the rules for typing complete terms, while Fig. 10 the rules for typing partial terms. The typing rules follow the intuition reported in the main paper. The minimal typing \vdash_{\min} is defined by changing the rules for typing branchings in global terms as described in the main paper, following the line of the minimal typings defined in [7, 8]. We will refer to such rules with the prefix $\llbracket^{\text{Min}}\rrbracket$.

$$\begin{array}{c}
\frac{\Gamma \vdash a : G\langle \mathbf{A} | \tilde{\mathbf{B}} | \tilde{\mathbf{B}} \rangle \quad \tilde{\mathbf{q}} \notin \Gamma \quad \Gamma, \Gamma' \vdash C \triangleright \Delta, \Delta' \quad \llbracket^{\text{T}}_{\text{START}} \rrbracket \quad r[\mathbf{C}] \in \mathbf{p}[\mathbf{A}], \widetilde{\mathbf{q}[\mathbf{B}]} \Leftrightarrow r : k[\mathbf{C}] \in \Gamma' \wedge k[\mathbf{C}] : \llbracket G \rrbracket_c \in \Delta'}{\Gamma \vdash \mathbf{p}[\mathbf{A}] \text{ starts } \mathbf{q}[\mathbf{B}] : a(k); C \triangleright \Delta} \\
\\
\llbracket^{\text{T}}_{\text{COM}} \rrbracket \frac{\Gamma \vdash e @ \mathbf{p} : S \quad \Gamma \vdash \mathbf{p} : k[\mathbf{A}], \mathbf{q} : k[\mathbf{B}] \quad \Gamma, x @ \mathbf{q} : S \vdash C \triangleright \Delta, k[\mathbf{A}] : T, k[\mathbf{B}] : T'}{\Gamma \vdash \mathbf{p}[\mathbf{A}].e \rightarrow \mathbf{q}[\mathbf{B}].x : k; C \triangleright \Delta, k[\mathbf{A}] : !\mathbf{B}\langle S \rangle; T, k[\mathbf{B}] : ?\mathbf{A}\langle S \rangle; T'} \\
\\
\llbracket^{\text{T}}_{\text{DEL}} \rrbracket \frac{\Gamma \vdash \mathbf{p} : k[\mathbf{A}], \mathbf{q} : k[\mathbf{B}] \quad \Gamma, \mathbf{q} : k'[\mathbf{C}] \vdash C \triangleright \Delta, k[\mathbf{A}] : T, k[\mathbf{B}] : T', k'[\mathbf{C}] : T''}{\Gamma, \mathbf{p} : k'[\mathbf{C}] \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{q}[\mathbf{B}] : k\langle k'[\mathbf{C}] \rangle; C \triangleright \Delta, k[\mathbf{A}] : !\mathbf{B}\langle T'' \rangle; T, k[\mathbf{B}] : ?\mathbf{A}\langle T'' \rangle; T', k'[\mathbf{C}] : T''} \\
\\
\llbracket^{\text{T}}_{\text{SEL}} \rrbracket \frac{j \in I \quad \Gamma \vdash \mathbf{p} : k[\mathbf{A}], \mathbf{q} : k[\mathbf{B}] \quad \Gamma \vdash C \triangleright \Delta, k[\mathbf{A}] : T_j, k[\mathbf{B}] : T'_j}{\Gamma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{q}[\mathbf{B}] : k[l_j]; C \triangleright \Delta, k[\mathbf{A}] : \oplus \mathbf{B}\{l_i : T_i\}_{i \in I}, k[\mathbf{B}] : \& \mathbf{A}\{l_i : T'_i\}_{i \in I}} \\
\\
\llbracket^{\text{T}}_{\text{COND}} \rrbracket \frac{\Gamma \vdash e @ \mathbf{p} : \text{bool} \quad \Gamma \vdash C_i \triangleright \Delta}{\Gamma \vdash \text{if } e @ \mathbf{p} \text{ then } C_1 \text{ else } C_2 \triangleright \Delta} \quad \llbracket^{\text{T}}_{\text{ZERO}} \rrbracket \frac{\text{cosha}(\Gamma) \quad \Delta \text{ end only}}{\Gamma \vdash \mathbf{0} \triangleright \Delta} \\
\\
\llbracket^{\text{T}}_{\text{RESSHA}} \rrbracket \frac{\Gamma, a : G\langle \mathbf{A} | \tilde{\mathbf{B}} | \tilde{\mathbf{B}} \rangle \vdash C \triangleright \Delta}{\Gamma \vdash (\nu a) C \triangleright \Delta} \quad \llbracket^{\text{T}}_{\text{CALL}} \rrbracket \frac{\Gamma = \Gamma_{\text{srv}}, \Gamma' \quad \Delta' \text{ end only}}{\Gamma, X : (\Gamma', \Delta) \vdash X(\widetilde{x @ \mathbf{p}}, \tilde{k}, \tilde{\mathbf{p}}) \triangleright \Delta, \Delta'} \\
\\
\llbracket^{\text{T}}_{\text{REC}} \rrbracket \frac{\Gamma, X : (\Gamma|_{\widetilde{x @ \mathbf{p}}}, \Delta|_{\tilde{k}}) \vdash C \triangleright \Delta \quad \Gamma_{\text{rec}}, \Gamma_{\text{srv}}, \Gamma|_{\widetilde{x @ \mathbf{p}}} \vdash C' \triangleright \Delta|_{\tilde{k}}}{\Gamma \vdash \text{rec } X(\widetilde{x @ \mathbf{p}}, \tilde{k}, \tilde{\mathbf{p}}) = C' \text{ in } C \triangleright \Delta} \\
\\
\llbracket^{\text{T}}_{\text{RESLIN}} \rrbracket \frac{\Gamma \vdash C \triangleright \Delta \quad \text{co}(\Delta, k)}{\Gamma \vdash (\nu k) C \triangleright \Delta \setminus k} \quad \llbracket^{\text{T}}_{\text{RESPROC}} \rrbracket \frac{\Gamma \vdash C \triangleright \Delta}{\Gamma \setminus \mathbf{p} \vdash (\nu \mathbf{p}) C \triangleright \Delta}
\end{array}$$

Fig. 9. Program typing rules for complete terms.

C.2 Runtime typing rules

Fig. 11 reports the rules for typing complete terms, while Fig. 12 the rules for typing partial terms. The handling of environment Σ is standard, from [8], but is extended to partial choreographies by using the extra judgement $\Gamma, \Sigma \vdash \mathbf{p} \rightarrow \mathbf{q} : k$, where

$$\begin{array}{c}
\begin{array}{c}
\text{[T]}_{\text{REQ1}} \frac{\Gamma \vdash a : G\langle \mathbf{A} | \tilde{\mathbf{B}} | \emptyset \rangle \quad \Gamma, \mathbf{p} : k[\mathbf{A}] \vdash C \triangleright \Delta, k[\mathbf{A}] : \llbracket G \rrbracket_{\mathbf{A}}}{\Gamma \vdash \mathbf{p}[\mathbf{A}] \text{ req } \tilde{\mathbf{B}} : a(k); C \triangleright \Delta} \\
\\
\text{[T]}_{\text{REQ2}} \frac{\Gamma \vdash x @ \mathbf{p} : G\langle \mathbf{A} | \tilde{\mathbf{B}} | \emptyset \rangle \quad \Gamma, \mathbf{p} : k[\mathbf{A}] \vdash C \triangleright \Delta, k[\mathbf{A}] : \llbracket G \rrbracket_{\mathbf{A}}}{\Gamma \vdash \mathbf{p}[\mathbf{A}] \text{ req } \tilde{\mathbf{B}} : x(k); C \triangleright \Delta} \\
\\
\text{[T]}_{\text{ACC}} \frac{\Gamma, a : G'\langle \mathbf{D} | \tilde{\mathbf{B}} | \emptyset \rangle, \Gamma' \vdash C \triangleright \Delta, \Delta' \quad \Gamma' = \{r : k[\mathbf{C}] \mid r[\mathbf{C}] \in \widetilde{\mathbf{q}[\mathbf{A}]}\} \quad \Delta' = \{k[\mathbf{C}] : \llbracket G \rrbracket_{\mathbf{C}} \mid r[\mathbf{C}] \in \widetilde{\mathbf{q}[\mathbf{A}]}\} \quad \tilde{\mathbf{q}} \notin \text{dom}(\Gamma), \text{dom}(\Sigma)}{\Gamma, a : G'\langle \mathbf{D} | \tilde{\mathbf{B}} | \tilde{\mathbf{A}} \rangle \vdash \text{acc } \widetilde{\mathbf{q}[\mathbf{A}]} : a(k); C \triangleright \Delta} \\
\\
\text{[T]}_{\text{COM-S}} \frac{\Gamma \vdash e @ \mathbf{p} : S \quad \Gamma \vdash \mathbf{p} : k[\mathbf{A}] \quad \Gamma \vdash C \triangleright \Delta, k[\mathbf{A}] : T \quad \mathbf{q} : k[\mathbf{B}] \notin \Gamma}{\Gamma \vdash \mathbf{p}[\mathbf{A}].e \rightarrow \mathbf{B} : k; C \triangleright \Delta, k[\mathbf{A}] : !\mathbf{B}\langle S \rangle; T} \\
\\
\text{[T]}_{\text{COM-R}} \frac{\Gamma, x @ \mathbf{p} : S \vdash C \triangleright \Delta, k[\mathbf{B}] : T \quad \Gamma \vdash \mathbf{q} : k[\mathbf{B}] \quad \mathbf{p} : k[\mathbf{A}] \notin \Gamma}{\Gamma \vdash \mathbf{A} \rightarrow \mathbf{q}[\mathbf{B}].x : k; C \triangleright \Delta, k[\mathbf{A}] : ?\mathbf{B}\langle S \rangle; T} \\
\\
\text{[T]}_{\text{DEL-S}} \frac{\Gamma \vdash \mathbf{p} : k[\mathbf{A}] \quad \Gamma \vdash C \triangleright \Delta, k[\mathbf{A}] : T \quad \mathbf{q} : k[\mathbf{B}] \notin \Gamma}{\Gamma, \mathbf{p} : k'[\mathbf{C}] \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{B} : k(k'[\mathbf{C}]); C \triangleright \Delta, k[\mathbf{A}] : !\mathbf{B}\langle T'' \rangle; T, k'[\mathbf{C}] : T''} \\
\\
\text{[T]}_{\text{DEL-R}} \frac{\Gamma \vdash \mathbf{q} : k[\mathbf{B}] \quad \Gamma, \mathbf{q} : k'[\mathbf{C}] \vdash C \triangleright \Delta, k[\mathbf{B}] : T', k'[\mathbf{C}] : T'' \quad \mathbf{p} : k[\mathbf{A}] \notin \Gamma}{\Gamma \vdash \mathbf{A} \rightarrow \mathbf{q}[\mathbf{B}] : k(k'[\mathbf{C}]); C \triangleright \Delta, k[\mathbf{B}] : ?\mathbf{A}\langle T'' \rangle; T'} \\
\\
\text{[T]}_{\text{SEL-S}} \frac{j \in I \quad \Gamma \vdash \mathbf{p} : k[\mathbf{A}] \quad \Gamma \vdash C \triangleright \Delta, k[\mathbf{A}] : T_j \quad \mathbf{q} : k[\mathbf{B}] \notin \Gamma}{\Gamma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{B} : k \oplus l_j; C \triangleright \Delta, k[\mathbf{A}] : \oplus \mathbf{B}\{l_i : T_i\}_{i \in I}} \\
\\
\text{[T]}_{\text{BRANCH}} \frac{\Gamma \vdash C_i \triangleright \Delta, k[\mathbf{A}] : T_i \quad \mathbf{p} : k[\mathbf{A}] \notin \Gamma}{\Gamma \vdash \mathbf{A} \rightarrow \mathbf{q}[\mathbf{B}] : k \& \{l_i : C_i\}_{i \in I} \triangleright \Delta, k[\mathbf{B}] : \& \mathbf{B}\{l_i : T_i\}_{i \in I}} \\
\\
\text{[T]}_{\text{PAR}} \frac{\Gamma, \Gamma_i \vdash C_i \triangleright \Delta_i}{\Gamma, \Gamma_1 \circ \Gamma_2 \vdash C_1 \mid C_2 \triangleright \Delta_1, \Delta_2}
\end{array}
\end{array}$$

Fig. 10. Program typing rules for partial terms.

$$\begin{array}{c}
\Gamma \vdash a : G\langle \mathbf{A} | \tilde{\mathbf{B}} | \tilde{\mathbf{B}} \rangle \quad \tilde{\mathbf{q}} \notin \Gamma; \Sigma \quad \Gamma, \Gamma'; \Sigma \vdash C \triangleright \Delta, \Delta' \\
\text{[T]$_{\text{START}}$} \quad \frac{r[\mathbf{C}] \in \mathbf{p}[\mathbf{A}], \widetilde{\mathbf{q}[\mathbf{B}]} \Leftrightarrow r : k[\mathbf{C}] \in \Gamma' \wedge k[\mathbf{C}] : \llbracket G \rrbracket_{\mathbf{C}} \in \Delta'}{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \text{ starts } \widetilde{\mathbf{q}[\mathbf{B}]} : a(k); C \triangleright \Delta} \\
\\
\text{[T]$_{\text{COM}}$} \quad \frac{\Gamma \vdash e @ \mathbf{p} : S \quad \Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{q}[\mathbf{B}] : k \quad \Gamma, x @ \mathbf{q} : S; \Sigma \vdash C \triangleright \Delta, k[\mathbf{A}] : T, k[\mathbf{B}] : T'}{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}].e \rightarrow \mathbf{q}[\mathbf{B}].x : k; C \triangleright \Delta, k[\mathbf{A}] : \mathbf{B}\langle S \rangle; T, k[\mathbf{B}] : \mathbf{A}\langle S \rangle; T'} \\
\\
\text{[T]$_{\text{DEL}}$} \quad \frac{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{q}[\mathbf{B}] : k \quad \Gamma \vdash \mathbf{p} : k'[\mathbf{C}] \quad k'[\mathbf{C}] \notin \Sigma \quad \Gamma[\mathbf{q} \mapsto k'[\mathbf{C}]] ; \text{rem}(\Sigma, \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{q}[\mathbf{B}] : k\langle k'[\mathbf{C}] \rangle) \vdash C \triangleright \Delta, k[\mathbf{A}] : T, k[\mathbf{B}] : T', k'[\mathbf{C}] : T''}{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{q}[\mathbf{B}] : k\langle k'[\mathbf{C}] \rangle; C \triangleright \Delta, k[\mathbf{A}] : \mathbf{B}\langle T'' \rangle; T, k[\mathbf{B}] : \mathbf{A}\langle T'' \rangle; T', k'[\mathbf{C}] : T''} \\
\\
\text{[T]$_{\text{SEL}}$} \quad \frac{j \in I \quad \Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{q}[\mathbf{B}] : k \quad \Gamma; \Sigma \vdash C \triangleright \Delta, k[\mathbf{A}] : T_j, k[\mathbf{B}] : T'_j}{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{q}[\mathbf{B}] : k[l_j]; C \triangleright \Delta, k[\mathbf{A}] : \oplus \mathbf{B}\{l_i : T_i\}_{i \in I}, k[\mathbf{B}] : \& \mathbf{A}\{l_i : T'_i\}_{i \in I}} \\
\\
\text{[T]$_{\text{COND}}$} \quad \frac{\Gamma \vdash e @ \mathbf{p} : \text{bool} \quad \Gamma; \Sigma \vdash C_i \triangleright \Delta}{\Gamma; \Sigma \vdash \text{if } e @ \mathbf{p} \text{ then } C_1 \text{ else } C_2 \triangleright \Delta} \quad \text{[T]$_{\text{ZERO}}$} \quad \frac{\text{cosha}(\Gamma) \quad \Delta \text{ end only}}{\Gamma; \Sigma \vdash \mathbf{0} \triangleright \Delta} \\
\\
\text{[T]$_{\text{RESHA}}$} \quad \frac{\Gamma, a : G\langle \mathbf{A} | \tilde{\mathbf{B}} | \tilde{\mathbf{B}} \rangle; \Sigma \vdash C \triangleright \Delta}{\Gamma; \Sigma \vdash (\nu a) C \triangleright \Delta} \quad \text{[T]$_{\text{CALL}}$} \quad \frac{\Gamma = \Gamma_{\text{srv}}, \Gamma' \quad \Delta' \text{ end only}}{\Gamma, X : (\Gamma', \Sigma, \Delta); \Sigma \vdash X(\widetilde{x @ \mathbf{p}}, \tilde{k}, \tilde{\mathbf{p}}) \triangleright \Delta, \Delta'} \\
\\
\text{[T]$_{\text{REC}}$} \quad \frac{\Gamma, X : (\Gamma|_{\widetilde{x @ \mathbf{p}}}, \Sigma|_{\tilde{k}, \tilde{\mathbf{p}}}, \Delta|_{\tilde{k}}); \Sigma \vdash C \triangleright \Delta \quad \Gamma_{\text{rec}}, \Gamma_{\text{srv}}, \Gamma|_{\widetilde{x @ \mathbf{p}}}; \Sigma|_{\tilde{k}, \tilde{\mathbf{p}}} \vdash C' \triangleright \Delta|_{\tilde{k}}}{\Gamma; \Sigma \vdash \text{rec } X(\widetilde{x @ \mathbf{p}}, \tilde{k}, \tilde{\mathbf{p}}) = C' \text{ in } C \triangleright \Delta} \\
\\
\text{[T]$_{\text{RESLIN}}$} \quad \frac{\Gamma; \Sigma \vdash C \triangleright \Delta \quad \text{co}(\Delta, k)}{\Gamma; \Sigma \setminus k \vdash (\nu k) C \triangleright \Delta \setminus k} \quad \text{[T]$_{\text{RESPROC}}$} \quad \frac{\Gamma; \Sigma \vdash C \triangleright \Delta}{\Gamma \setminus \mathbf{p}; \Sigma \setminus \mathbf{p} \vdash (\nu \mathbf{p}) C \triangleright \Delta}
\end{array}$$

Fig. 11. Runtime typing rules for complete terms.

$$\begin{array}{c}
\begin{array}{c}
\text{[T]}_{\text{REQ1}} \frac{\Gamma \vdash a : G\langle \mathbf{A} | \tilde{\mathbf{B}} | \emptyset \rangle \quad \Gamma, \mathbf{p} : k[\mathbf{A}]; \Sigma \vdash C \triangleright \Delta, k[\mathbf{A}] : \llbracket G \rrbracket_{\mathbf{A}}}{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \text{ req } \tilde{\mathbf{B}} : a(k); C \triangleright \Delta} \\
\text{[T]}_{\text{REQ2}} \frac{\Gamma \vdash x @ \mathbf{p} : G\langle \mathbf{A} | \tilde{\mathbf{B}} | \emptyset \rangle \quad \Gamma, \mathbf{p} : k[\mathbf{A}]; \Sigma \vdash C \triangleright \Delta, k[\mathbf{A}] : \llbracket G \rrbracket_{\mathbf{A}}}{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \text{ req } \tilde{\mathbf{B}} : x(k); C \triangleright \Delta}
\end{array} \\
\\
\begin{array}{c}
\text{[T]}_{\text{ACC}} \frac{\Gamma, a : G\langle \mathbf{D} | \tilde{\mathbf{B}} | \emptyset \rangle, \Gamma'; \Sigma \vdash C \triangleright \Delta, \Delta' \quad \Gamma' = \{r : k[\mathbf{C}] \mid r[\mathbf{C}] \in \widetilde{\mathbf{q}[\mathbf{A}]}\} \\
\Delta' = \{k[\mathbf{C}] : \llbracket G \rrbracket_{\mathbf{C}} \mid r[\mathbf{C}] \in \widetilde{\mathbf{q}[\mathbf{A}]}\} \quad \tilde{\mathbf{q}} \notin \text{dom}(\Gamma), \text{dom}(\Sigma)}{\Gamma, a : G\langle \mathbf{D} | \tilde{\mathbf{B}} | \tilde{\mathbf{A}} \rangle; \Sigma \vdash \text{acc } \tilde{\mathbf{q}}[\mathbf{A}] : a(k); C \triangleright \Delta}
\end{array} \\
\\
\begin{array}{c}
\text{[T]}_{\text{COM-S}} \frac{\Gamma \vdash e @ \mathbf{p} : S \quad \Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{B} : k \quad \Gamma; \Sigma \vdash C \triangleright \Delta, k[\mathbf{A}] : T \quad \mathbf{q} : k[\mathbf{B}] \notin \Gamma}{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}].e \rightarrow \mathbf{B} : k; C \triangleright \Delta, k[\mathbf{A}] : \mathbf{!B}\langle S \rangle; T}
\end{array} \\
\\
\begin{array}{c}
\text{[T]}_{\text{COM-R}} \frac{\Gamma, x @ \mathbf{p} : S; \Sigma \vdash C \triangleright \Delta, k[\mathbf{B}] : T \quad \Gamma; \Sigma \vdash \mathbf{A} \rightarrow \mathbf{q}[\mathbf{B}] : k \quad \mathbf{p} : k[\mathbf{A}] \notin \Gamma}{\Gamma; \Sigma \vdash \mathbf{A} \rightarrow \mathbf{q}[\mathbf{B}].x : k; C \triangleright \Delta, k[\mathbf{A}] : \mathbf{?B}\langle S \rangle; T}
\end{array} \\
\\
\begin{array}{c}
\text{[T]}_{\text{DEL-S}} \frac{\Gamma; \Sigma \vdash C \triangleright \Delta, k[\mathbf{A}] : T \quad \Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{B} : k \\
\Gamma \vdash \mathbf{p} : k'[\mathbf{C}] \quad k'[\mathbf{C}] \notin \Sigma \quad \mathbf{q} : k[\mathbf{B}] \notin \Gamma}{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{B} : k(k'[\mathbf{C}]); C \triangleright \Delta, k[\mathbf{A}] : \mathbf{!B}\langle T' \rangle; T, k'[\mathbf{C}] : T'}
\end{array} \\
\\
\begin{array}{c}
\text{[T]}_{\text{DEL-R}} \frac{\Gamma; \Sigma \vdash \mathbf{A} \rightarrow \mathbf{q}[\mathbf{B}] : k \\
\Gamma[\mathbf{q} \mapsto k'[\mathbf{C}]] ; \text{rem}(\Sigma, \mathbf{A} \rightarrow \mathbf{q}[\mathbf{B}] : k(k'[\mathbf{C}])) \vdash C \triangleright \Delta, k[\mathbf{B}] : T, k'[\mathbf{C}] : T' \quad \mathbf{p} : k[\mathbf{A}] \notin \Gamma}{\Gamma; \Sigma \vdash \mathbf{A} \rightarrow \mathbf{q}[\mathbf{B}] : k(k'[\mathbf{C}]); C \triangleright \Delta, k[\mathbf{B}] : \mathbf{?B}\langle T' \rangle; T}
\end{array} \\
\\
\begin{array}{c}
\text{[T]}_{\text{SEL-S}} \frac{j \in I \quad \Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{B} : k \quad \Gamma; \Sigma \vdash C \triangleright \Delta, k[\mathbf{A}] : T_j \quad \mathbf{q} : k[\mathbf{B}] \notin \Gamma}{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{B} : k \oplus l_j; C \triangleright \Delta, k[\mathbf{A}] : \oplus \mathbf{B}\{l_i : T_i\}_{i \in I}}
\end{array} \\
\\
\begin{array}{c}
\text{[T]}_{\text{BRANCH}} \frac{\Gamma; \Sigma \vdash C_i \triangleright \Delta, k[\mathbf{A}] : T_i \quad \mathbf{p} : k[\mathbf{A}] \notin \Gamma}{\Gamma; \Sigma \vdash \mathbf{A} \rightarrow \mathbf{q}[\mathbf{B}] : k \& \{l_i : C_i\}_{i \in I} \triangleright \Delta, k[\mathbf{B}] : \& \mathbf{B}\{l_i : T_i\}_{i \in I}}
\end{array} \\
\\
\begin{array}{c}
\text{[T]}_{\text{PAR}} \frac{\Gamma, \Gamma_i; \Sigma_i \vdash C_i \triangleright \Delta_i}{\Gamma, \Gamma_1 \circ \Gamma_2; \Sigma_1, \Sigma_2 \vdash C_1 \mid C_2 \triangleright \Delta_1, \Delta_2}
\end{array}
\end{array}$$

Fig. 12. Runtime typing rules for partial terms.

$\mathbf{p} ::= p \mid \mathbf{A}$. $\Gamma, \Sigma \vdash \mathbf{p} \rightarrow \mathbf{q} : k$ is defined by the rules in Fig. 13. The auxiliary predicate $\text{co in } [\top]_{\text{RESLIN}}$ is from [3].

$$\begin{array}{c} [\circ]_{\text{COM}} \frac{(\Gamma \vdash \mathbf{p} : k[\mathbf{A}] \vee \Sigma \vdash \mathbf{p} : k[\mathbf{A}]) \quad \Gamma \vdash \mathbf{q} : k[\mathbf{B}] \quad \Sigma \not\vdash \mathbf{q} : k[\mathbf{B}]}{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{q}[\mathbf{B}] : k} \\ \\ [\circ]_{\text{SEND}} \frac{\Gamma \vdash \mathbf{p} : k[\mathbf{A}] \vee \Sigma \vdash \mathbf{p} : k[\mathbf{A}]}{\Gamma; \Sigma \vdash \mathbf{p}[\mathbf{A}] \rightarrow \mathbf{B} : k} \quad [\circ]_{\text{RECV}} \frac{\Gamma \vdash \mathbf{q} : k[\mathbf{B}] \quad \Sigma \not\vdash \mathbf{q} : k[\mathbf{B}]}{\Gamma; \Sigma \vdash \mathbf{A} \rightarrow \mathbf{q}[\mathbf{B}] : k} \end{array}$$

Fig. 13. Ownership Typing.

C.3 Typing soundness

Our typing is proven sound by following the standard techniques reported in respectively [8] for the global terms and [14] for the partial terms, treating Σ as in [8].

Lemma C.2 (Substitution). *Assume $\Gamma; \Sigma \vdash C \triangleright \Delta$. Then, $\Gamma \vdash x @ \mathbf{p} : S, v : S$ implies $\Gamma; \Sigma \vdash C[v/x @ \mathbf{p}] \triangleright \Delta$.*

Proof. By induction on the typing rules. □

Lemma C.3 (Subject Congruence). *$\Gamma; \Sigma \vdash C \triangleright \Delta$ and $C \equiv C'$ imply $\Gamma; \Sigma \vdash C' \triangleright \Delta$ (up to α -renaming).*

Proof. By induction on the rules for \equiv .

Theorem C.1 (Typing Soundness). *Let $\Gamma; \Sigma \vdash C \triangleright \Delta$. Then,*

- (Subject Swap) $C \simeq_C C'$ implies $\Gamma; \Sigma \vdash C' \triangleright \Delta$.
- $C \xrightarrow{\lambda} C'$ implies that there exists Δ' such that (1) (Subject Reduction) $\Gamma'; \Sigma' \vdash C \triangleright \Delta'$ for some Γ', Σ' ; (2) (Session Fidelity) if λ is a communication on session k , then $\Delta \xrightarrow{\alpha} \Delta'$ with $\alpha \vdash \lambda$; else, $\Delta = \Delta'$.

Proof. (Subject Swap) is by induction on the rules of \simeq_C . (Subject Reduction) and (Session Fidelity) are by induction on the derivation $C \xrightarrow{\lambda} C'$, following the lines of [14, 8]. □

D Endpoint Projection and its Properties

D.1 Auxiliary EPP Lemmas

We are now going to introduce some auxiliary lemmas, which will be useful in the proofs of our theorems.

Lemma D.4 (EPP Free Names). *Let C be a choreography. Then, $\text{fn}(C) = \text{fn}(\llbracket C \rrbracket)$.*

Proof. Immediate, from the definition of EPP.

Lemma D.5 (EPP Substitution Lemma). $\llbracket C[v/x@p] \rrbracket_p = \llbracket C \rrbracket_p[v/x@p]$.

Proof. Immediate from the definition of EPP.

Lemma D.6 (EPP Substitution Locality). Let $C \equiv (\nu \tilde{a}, \tilde{k}, \tilde{p})C_f$, where C_f is restriction-free, and $p \in \text{fn}(C)$. Then,

$$\llbracket C[v/x@p] \rrbracket = (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) \left(\llbracket C_f[v/x@p] \rrbracket_p \mid \prod_{p \in \text{fn}(C_f)} \llbracket C_f \rrbracket_p \right) \mid \prod_{a, A} \left(\bigsqcup_{p \in \llbracket C_f \rrbracket_A^a} \llbracket C_f \rrbracket_p \right) \right)$$

Proof. Immediate from the definition of EPP and Lemma D.5.

Lemma D.7 (Endpoint Choreographies). Let C be restriction-free, contain only partial terms, and be well-typed. If one of the following two conditions apply, then $C = \llbracket C \rrbracket$.

1. $C = \text{acc } q[B] : a(k); C'$ and q is the only free process name in C' ;
2. otherwise, C has only one free process name.

Proof. We prove the Lemma for the second condition. The first follows immediately by similar reasoning. For the second condition, we prove that $\llbracket C \rrbracket_p = C$. This is immediate from the definition of EPP, since C has p as only free name and does not contain restrictions. Thus, the parallel composition in Definition 1 is exactly $\llbracket C \rrbracket_p$. \square

Lemma D.8 (Compositional EPP). Let $C = C_1 \mid C_2$ be well-typed. Then, $\llbracket C \rrbracket \equiv \llbracket C_1 \rrbracket \mid \llbracket C_2 \rrbracket$.

Proof (Sketch). From $\llbracket \cdot \rrbracket_{\text{PAR}}$, we know that C_1 and C_2 cannot share services. Therefore, the projection of the respective services would be put in parallel in $\llbracket C \rrbracket$. Furthermore, for every free process name p in C , we know from the definition of EPP that $\llbracket C \rrbracket_p = \llbracket C_1 \rrbracket_p \mid \llbracket C_2 \rrbracket_p$. Hence, both services and processes would be projected in parallel as expected.

Lemma D.9 (EPP Swap Invariance). Let $C \simeq_C C'$. Then, $\llbracket C \rrbracket = \llbracket C' \rrbracket$.

Proof (Sketch). The main part of the proof is to show that process projection is invariant under the rules for the swapping relation \simeq_C , reported in Fig. 5. $\llbracket \cdot \rrbracket_{\text{ETA-ETA}}^{\text{SW}}$ is a trivial case. For $\llbracket \cdot \rrbracket_{\text{ETA-COND}}^{\text{SW}}$, we have to check that the projections of the processes in the swapped interaction η do not change. This follows immediately from the definition of EPP for (*cond*) terms, since merging of the same η is the identity. The other cases follow by similar reasoning on the merging operator.

D.2 Main EPP Theorems

Theorem D.2 (EPP Type Preservation). *Let $\Gamma \vdash_{\min} C \triangleright \Delta$. Then, $\Gamma \vdash_{\min} \llbracket C \rrbracket \triangleright \Delta$.*

Proof. Let $C \equiv (\nu \tilde{a}, \tilde{k}, \tilde{p}) C_f$, where C_f is restriction-free. The proof is by induction on the typing derivation $\Gamma \vdash_{\min} C_f \triangleright \Delta$. We report the most interesting cases.

– **Case $\llbracket^{\min} \rrbracket_{\text{COM}}$.** We know that

$$\llbracket^{\min} \rrbracket_{\text{COM}} \frac{\Gamma \vdash e @ p : S \quad \Gamma \vdash p : k[A], q : k[B] \quad \Gamma, x @ q : S \vdash_{\min} C' \triangleright \Delta, k[A] : T, k[B] : T'}{\Gamma \vdash_{\min} p[A].e \rightarrow q[B].x : k; C' \triangleright \Delta, k[A] : !B \langle S \rangle; T, k[B] : ?A \langle S \rangle; T'}$$

where $C_f = p[A].e \rightarrow q[B].x : k; C'$. From the definition of EPP we have that:

$$\begin{aligned} \llbracket C \rrbracket &\equiv (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) C_{\text{act}} \mid \prod_{a, A} \left(\bigsqcup_{p \in \llbracket C' \rrbracket_A^a} \llbracket C' \rrbracket_p \right) \right) \\ C_{\text{act}} &= p[A].e \rightarrow B : k; \llbracket C' \rrbracket_p \mid A \rightarrow q[B].x : k; \llbracket C' \rrbracket_q \\ &\quad \mid \prod_{r \in \text{fn}(C') \setminus \{p, q\}} \llbracket C' \rrbracket_r \end{aligned} \tag{1}$$

We can type $p[A].e \rightarrow B : k; \llbracket C' \rrbracket_p$ and $A \rightarrow q[B].x : k; \llbracket C' \rrbracket_q$ by using $\llbracket^{\min} \rrbracket_{\text{COM-S}}$ and $\llbracket^{\min} \rrbracket_{\text{COM-R}}$ respectively, since their premises are a subset of those given in our hypothesis to $\llbracket^{\min} \rrbracket_{\text{COM}}$. Then, the thesis follows by induction hypothesis.

– **Case $\llbracket^{\min} \rrbracket_{\text{COM-S}}$.** We know that

$$\llbracket^{\min} \rrbracket_{\text{COM-S}} \frac{\Gamma \vdash e @ p : S \quad \Gamma \vdash p : k[A] \quad \Gamma \vdash_{\min} C' \triangleright \Delta, k[A] : T}{\Gamma \vdash_{\min} p[A].e \rightarrow B : k; C' \triangleright \Delta, k[A] : !B \langle S \rangle; T}$$

where $C_f = p[A].e \rightarrow B : k; C'$. From the definition of EPP we have that:

$$\begin{aligned} \llbracket C \rrbracket &\equiv (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) C_{\text{act}} \mid \prod_{a, A} \left(\bigsqcup_{p \in \llbracket C' \rrbracket_A^a} \llbracket C' \rrbracket_p \right) \right) \\ C_{\text{act}} &= p[A].e \rightarrow B : k; \llbracket C' \rrbracket_p \mid \prod_{r \in \text{fn}(C') \setminus \{p\}} \llbracket C' \rrbracket_r \end{aligned} \tag{2}$$

The thesis now follows by applying $\llbracket^{\min} \rrbracket_{\text{COM-S}}$ for typing $p[A].e \rightarrow B : k; \llbracket C' \rrbracket_p$ and then by applying the induction hypothesis.

– **Case $\llbracket^{\min} \rrbracket_{\text{COM-R}}$.** We know that

$$\llbracket^{\min} \rrbracket_{\text{COM-R}} \frac{\Gamma \vdash q : k[B] \quad \Gamma, x @ q : S \vdash_{\min} C' \triangleright \Delta, k[B] : T}{\Gamma \vdash_{\min} p[A].e \rightarrow q[B].x : k; C' \triangleright \Delta, k[B] : ?A \langle S \rangle; T}$$

where $C_f = A \rightarrow q[B].x : k; C'$. From the definition of EPP we have that:

$$\begin{aligned} \llbracket C \rrbracket &\equiv (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) C_{\text{act}} \mid \prod_{a, A} \left(\bigsqcup_{p \in \llbracket C' \rrbracket_A^a} \llbracket C' \rrbracket_p \right) \right) \\ C_{\text{act}} &= A \rightarrow q[B].x : k; \llbracket C' \rrbracket_q \mid \prod_{r \in \text{fn}(C') \setminus \{q\}} \llbracket C' \rrbracket_r \end{aligned} \tag{3}$$

The thesis now follows by applying $\llbracket^{\min} \rrbracket_{\text{COM-R}}$ for typing $A \rightarrow q[B].x : k; \llbracket C' \rrbracket_q$ and then by applying the induction hypothesis.

– **Case** $\lfloor^{\text{MIN}}_{\text{PAR}}\rfloor$. We know that

$$\lfloor^{\text{MIN}}_{\text{PAR}}\rfloor \frac{\Gamma, \Gamma_i \vdash_{\text{min}} C_i \triangleright \Delta_i}{\Gamma, \Gamma_1 \circ \Gamma_2 \vdash_{\text{min}} C_1 \mid C_2 \triangleright \Delta_1, \Delta_2}$$

where $C_f = C_1 \mid C_2$. The thesis follows by Lemma 2 and by applying the induction hypothesis. \square

In order to prove that our EPP procedure is correct, we need to relate the behaviour of choreographies with that of their respective projections. To make that task easier (and more precise), we will make use of the notion of strict transitions, defined in the following.

Definition 3 (Strict Transition). *A strict transition is a transition where (ν) -restricted names that are active, i.e., not under a prefix, are not renamed.*

Strict transitions are the base of our main assumption in our proofs, presented below.

Assumption 1 (Transitions and Restriction). *We assume that all transitions $C \xrightarrow{\lambda} C'$ are strict transitions. Furthermore, we assume that rule $\lfloor^{\text{C}}_{\text{RES}}\rfloor$ is changed to the following form:*

$$\lfloor^{\text{C}}_{\text{RES}}\rfloor C \xrightarrow{\lambda} C' \quad \Rightarrow \quad (\nu r) \xrightarrow{\lambda} (\nu r) C'$$

The assumption above allows us to observe actions of restricted names. Observe that our assumption does not make our proofs any less general, since for every transition there is always a corresponding strict transition [7, 8]

Theorem D.3 (EPP Theorem). *Let $C \equiv (\nu \tilde{a}, \tilde{k}, \tilde{p}) C_f$, where C_f is restriction-free, be well-typed. Then,*

1. (Completeness) $C \xrightarrow{\lambda} C'$ implies $\llbracket C \rrbracket \xrightarrow{\lambda} \succ \llbracket C' \rrbracket$.
2. (Soundness) $\llbracket C \rrbracket \xrightarrow{\lambda} C'$ implies $C \xrightarrow{\lambda} C''$ and $\llbracket C'' \rrbracket \prec C'$.

Proof (Completeness). The proof is by induction on the derivation of $C \xrightarrow{\lambda} C'$. We analyse the most interesting cases.

– **Case** $\lfloor^{\text{C}}_{\text{COM}}\rfloor$. We know that:

$$p[A].e \rightarrow q[B].x : k; C'' \xrightarrow{\lambda} C''[v/x@q] = C' \quad (e \downarrow v) \quad (4)$$

where $\lambda = p[A] \rightarrow q[B] : k \langle v \rangle$. From the definition of EPP we have:

$$\begin{aligned} \llbracket C \rrbracket &\equiv (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) C_{\text{act}} \mid \prod_{a, A} \left(\bigsqcup_{p \in \llbracket C_f \rrbracket_a^a} \llbracket C_f \rrbracket_p \right) \right) \\ C_{\text{act}} &= p[A].e \rightarrow B : k; \llbracket C_f'' \rrbracket_p \mid A \rightarrow q[B].x : k; \llbracket C_f'' \rrbracket_q \\ &\quad \mid \prod_{r \in \text{fn}(C_f) \setminus \{p, q\}} \llbracket C_f \rrbracket_r \end{aligned} \quad (5)$$

We can now apply rule $\llbracket^c|_{\text{COM-S}}\rrbracket$ for the sending action, rule $\llbracket^c|_{\text{COM-R}}\rrbracket$ for the receiving action, and then rule $\llbracket^c|_{\text{SYNC}}\rrbracket$, proving that:

$$C_{\text{act}} \xrightarrow{\lambda} \llbracket C_f'' \rrbracket_p \mid \llbracket C_f'' \rrbracket_q[v/x@q] \mid \prod_{r \in \text{fn}(C_f) \setminus \{p,q\}} \quad (6)$$

By the transition above and rules $\llbracket^c|_{\text{PAR}}\rrbracket$, $\llbracket^c|_{\text{RES}}\rrbracket$ and $\llbracket^c|_{\text{EQ}}\rrbracket$ we can finally prove the thesis by Lemma D.6.

– **Case** $\llbracket^c|_{\text{ASYNC}}\rrbracket$. We know that:

$$C_a \xrightarrow{\lambda} (\nu \tilde{r}) C'_a \Rightarrow \eta; C_a \xrightarrow{\lambda} (\nu \tilde{r}) \eta; C'_a \left(\begin{array}{ll} \text{snd}(\eta) \in \text{fn}(\lambda) & \tilde{r} = \text{bn}(\lambda) \\ \text{rcv}(\eta) \notin \text{fc}(\lambda) & \tilde{r} \notin \text{fn}(\eta) \\ \eta \notin \{\text{start}, \text{acc}\} \end{array} \right) \quad (7)$$

where $C = \eta; C_a$ and $C' = (\nu \tilde{r}) \eta; C'_a$. Let us analyse the case in which $\eta = p[A].e \rightarrow q[B].x : k$ (the other cases are similar). By the definition of EPP we have that:

$$\begin{aligned} \llbracket C \rrbracket &\equiv (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) C_{\text{act}} \mid \prod_{a,A} \left(\bigsqcup_{p \in \llbracket C_f \rrbracket_a^a} \llbracket C_f \rrbracket_p \right) \right) \\ C_{\text{act}} &= p[A].e \rightarrow B : k; \llbracket C_f'' \rrbracket_p \mid A \rightarrow q[B].x : k; \llbracket C_f'' \rrbracket_q \\ &\quad \mid \prod_{r \in \text{fn}(C_f) \setminus \{p,q\}} \llbracket C_f \rrbracket_r \end{aligned} \quad (8)$$

From the side conditions in 7, we know that we can apply $\llbracket^c|_{\text{ASYNC}}\rrbracket$ to $p[A].e \rightarrow B : k; \llbracket C_f'' \rrbracket_p$. Moreover, we know that $\text{rcv}(\eta) = k[B] \notin \text{fc}(\lambda)$. Therefore, we have two possibilities for $\llbracket C \rrbracket$ to mimic λ : either λ is an internal action if $@p$ doable by $\llbracket C_f'' \rrbracket_p$, or $\llbracket C_f'' \rrbracket_p$ needs to interact with another process in parallel. In both cases, the thesis follows from the induction hypothesis by case analysis on λ .

– **Case** $\llbracket^c|_{\text{EQ}}\rrbracket$. For $\mathcal{R} = \equiv$, the thesis follows by induction hypothesis and rule $\llbracket^c|_{\text{EQ}}\rrbracket$. Otherwise, for $\mathcal{R} = \simeq_C$, the thesis follows from the induction hypothesis and Lemma D.9.

The other cases are standard [8]. \square

Proof (Soundness). of the reduction The proof proceeds by induction on the structure of C_f . We report the most interesting cases.

– **Case** $C_f = p[A].e \rightarrow q[B].x : k; C_c$. From the definition of EPP we have that:

$$\begin{aligned} \llbracket C \rrbracket &\equiv (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) C_r \mid \prod_{a,A} \left(\bigsqcup_{p \in \llbracket C_c \rrbracket_a^a} \llbracket C_c \rrbracket_p \right) \right) \\ C_r &= p[A].e \rightarrow B : k; \llbracket C_c \rrbracket_p \mid A \rightarrow q[B].x : k; \llbracket C_c \rrbracket_q \\ &\quad \mid \prod_{r \in \text{fn}(C_c) \setminus \{p,q\}} \llbracket C_c \rrbracket_r \end{aligned} \quad (9)$$

We proceed now by case analysis on the reduction $\llbracket C \rrbracket \xrightarrow{\lambda} C'$.

- p and q communicate through $\llbracket^c\rrbracket_{\text{SYNC}}$, by executing their respective prefixes $p[A].e \rightarrow B : k$ and $A \rightarrow q[B].x : k$. In this case, we obtain that:

$$\begin{aligned} C' &\equiv (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) C_r \mid \prod_{a,A} \left(\bigsqcup_{p \in \llbracket C_c \rrbracket_A^a} \llbracket C_c \rrbracket_p \right) \right) \\ C_r &= \llbracket C_c \rrbracket_p \mid \llbracket C_c \rrbracket_q[v/x@q] \mid \prod_{r \in \text{fn}(C_c) \setminus \{p,q\}} \llbracket C_c \rrbracket_r \end{aligned} \quad (10)$$

Also, we know that $\lambda = p[A] \rightarrow q[B] : k\langle v \rangle$. Clearly, C can mimic the transition of $\llbracket C \rrbracket$ by executing its prefix $p[A].e \rightarrow q[B].x : k$ through rule $\llbracket^c\rrbracket_{\text{COM}}$.

We obtain that $C \xrightarrow{\lambda} C''[v/x@q]$. The thesis follows by Lemma D.6.

- p may communicate with another process r in $\prod_{r \in \text{fn}(C_c) \setminus \{p,q\}}$. In this case, it must be that p is executing a sending action and that the derivation for its transition ended with an application of rule $\llbracket^c\rrbracket_{\text{ASYNC}}$. Therefore, it must be case (from the premises of $\llbracket^c\rrbracket_{\text{ASYNC}}$) that we can apply $\llbracket^c\rrbracket_{\text{ASYNC}}$ also for C' and mimic the transition correctly.
 - p may start a new session with a service in $\prod_{a,A} \left(\bigsqcup_{p \in \llbracket C_c \rrbracket_A^a} \llbracket C_c \rrbracket_p \right)$. The reasoning for this case is similar to the one above.
 - Other two processes, say r and s in $\text{fn}(C_r) \setminus \{p,q\}$, may interact inside $\prod_{r \in \text{fn}(C_c) \setminus \{p,q\}}$. In this case, since we know that r and s are different than p and q , C' can mimic the transition by using the swapping relation $\llbracket^c\rrbracket_{\text{SWAP}}$.
 - A process r in $\prod_{r \in \text{fn}(C_c) \setminus \{p,q\}}$ may start a new session with a service in $\prod_{a,A} \left(\bigsqcup_{p \in \llbracket C_c \rrbracket_A^a} \llbracket C_c \rrbracket_p \right)$. The reasoning for this case is similar to the one above.
- **Case** $C_f = p[A].e \rightarrow B : k; C_c$. From the definition of EPP we have that:

$$\begin{aligned} \llbracket C \rrbracket &\equiv (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) C_r \mid \prod_{a,A} \left(\bigsqcup_{p \in \llbracket C_c \rrbracket_A^a} \llbracket C_c \rrbracket_p \right) \right) \\ C_r &= p[A].e \rightarrow B : k; \llbracket C_c \rrbracket_p \mid \prod_{r \in \text{fn}(C_c) \setminus \{p\}} \llbracket C_c \rrbracket_r \end{aligned} \quad (11)$$

We proceed now by case analysis on the reduction $\llbracket C \rrbracket \xrightarrow{\lambda} C'$.

- p may execute its sending action $p.e \rightarrow B : k$ by $\llbracket^c\rrbracket_{\text{COM-S}}$. In this case, by rules $\llbracket^c\rrbracket_{\text{PAR}}$ and $\llbracket^c\rrbracket_{\text{RES}}$ we would have that $\lambda = p[A] \rightarrow B : k\langle v \rangle$, where $e \downarrow v$, and that:

$$\begin{aligned} C' &\equiv (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) C_r \mid \prod_{a,A} \left(\bigsqcup_{p \in \llbracket C_c \rrbracket_A^a} \llbracket C_c \rrbracket_p \right) \right) \\ C_r &= \llbracket C_c \rrbracket_p \mid \prod_{r \in \text{fn}(C_c) \setminus \{p\}} \llbracket C_c \rrbracket_r \end{aligned} \quad (12)$$

The thesis follows from the definition of pruning.

- p may communicate with another process r in $\prod_{r \in \text{fn}(C_c) \setminus \{p\}}$. In this case, it must be that p is executing a sending action and that the derivation for its transition ended with an application of rule $\llbracket^c\rrbracket_{\text{ASYNC}}$. Therefore, it must be case (from the premises of $\llbracket^c\rrbracket_{\text{ASYNC}}$) that we can apply $\llbracket^c\rrbracket_{\text{ASYNC}}$ also for C and mimic the transition correctly.

- p may start a new session with a service in $\prod_{a,A} \left(\bigsqcup_{p \in \lfloor C_c \rfloor_A^a} \llbracket C_c \rrbracket_p \right)$. The reasoning for this case is similar to the one above.
 - Other two processes, say r and s in $\text{fn}(C_r) \setminus \{p\}$, may interact inside $\prod_{r \in \text{fn}(C_c) \setminus \{p\}}$. In this case, since we know that r and s are different than p , C can mimic the transition by using the swapping relation $\llbracket^C \rrbracket_{\text{SWAP}}$.
 - A process r in $\prod_{r \in \text{fn}(C_c) \setminus \{p\}}$ may start a new session with a service in $\prod_{a,A} \left(\bigsqcup_{p \in \lfloor C_c \rfloor_A^a} \llbracket C_c \rrbracket_p \right)$. The reasoning for this case is similar to the one above.
- **Case** $C_f = C_1 \mid C_2$. From the definition of EPP we have that:

$$\begin{aligned} \llbracket C \rrbracket &\equiv (\nu \tilde{a}) \left((\nu \tilde{k}, \tilde{p}) C_r \mid \prod_{a,A} \left(\bigsqcup_{p \in \lfloor C_f \rfloor_A^a} \llbracket C_1 \mid C_2 \rrbracket_p \right) \right) \\ C_r &= \prod_{r \in \text{fn}(C_f)} \llbracket C_1 \mid C_2 \rrbracket_r \end{aligned} \quad (13)$$

By Lemma 2, we can rewrite the above as:

$$\begin{aligned} \llbracket C \rrbracket &\equiv \llbracket C_1 \rrbracket \mid \llbracket C_2 \rrbracket \\ \llbracket C_1 \rrbracket &\equiv (\nu \tilde{a}_1) \left((\nu \tilde{k}_1, \tilde{p}_1) C_{r1} \mid \prod_{a,A} \left(\bigsqcup_{p \in \lfloor C_{r1} \rfloor_A^a} \llbracket C_{r1} \rrbracket_p \right) \right) \\ C_{r1} &= \prod_{r \in \text{fn}(C_{r1})} \llbracket C_{r1} \rrbracket_r \\ \llbracket C_2 \rrbracket &\equiv (\nu \tilde{a}_2) \left((\nu \tilde{k}_2, \tilde{p}_2) C_{r2} \mid \prod_{a,A} \left(\bigsqcup_{p \in \lfloor C_{r2} \rfloor_A^a} \llbracket C_{r2} \rrbracket_p \right) \right) \\ C_{r2} &= \prod_{r \in \text{fn}(C_{r2})} \llbracket C_{r2} \rrbracket_r \end{aligned} \quad (14)$$

where \tilde{a}_i , \tilde{k}_i , and \tilde{p}_i are respectively the free shared channel, session, and process names in C_i where $i \in \{1, 2\}$. We proceed now by case analysis on the last applied rule for the transition $\llbracket C \rrbracket \xrightarrow{\lambda} C'$.

- **Case** $\llbracket^C \rrbracket_{\text{PAR}}$. In this case, we know that:

$$\begin{aligned} \llbracket C_1 \rrbracket \xrightarrow{\lambda} C'_1 \quad \Rightarrow \quad \llbracket C_1 \rrbracket \mid \llbracket C_2 \rrbracket \xrightarrow{\lambda} C'_1 \mid \llbracket C_2 \rrbracket &= C' \\ (\lambda \in \text{CACT} \vee \text{rc}(\lambda) \notin \text{fc}(\llbracket C_2 \rrbracket)) & \end{aligned} \quad (15)$$

Now we have two subcases, depending on the condition respected by λ .

- * If $\lambda \in \text{CACT}$, then the thesis follows by induction hypothesis.
 - * Otherwise, if $\lambda \notin \text{CACT}$ and $\text{rc}(\lambda) \notin \text{fc}(\llbracket C_2 \rrbracket)$, then from the typing rules we know that $\text{rc}(\lambda)$ does not appear in $\llbracket C_1 \rrbracket$ either. The thesis follows then from the induction hypothesis and Lemma D.4.
- **Case** $\llbracket^C \rrbracket_{\text{SYNC}}$. In this case we know that:

$$\llbracket C_1 \rrbracket \xrightarrow{\lambda_1} C'_1 \quad \llbracket C_2 \rrbracket \xrightarrow{\lambda_2} C'_2 \quad \Rightarrow \quad \llbracket C_1 \rrbracket \mid \llbracket C_2 \rrbracket \xrightarrow{\lambda} C' \quad (16)$$

where $\lambda = \lambda_1 \circ \lambda_2$. From the typing rules we know that C_1 and C_2 have disjoint session/role pairs. Therefore, the terms emitting the labels λ_1 and λ_2 cannot be the projection of a complete action in C ; rather, the two terms must have already been separate partial actions in C . We can conclude by applying the induction hypothesis to C_1 and C_2 .

- **Case** $\llbracket C \rrbracket_{\text{P-START}}$. This case is similar to the one above.

The other cases follow similar reasonings to the ones above.

D.3 Proofs for Deadlock-freedom and Progress

Theorem D.4 (Deadlock-freedom for Complete Choreographies). *Let C be a complete choreography and contain no free variable names. Then, C is deadlock-free.*

Proof. Immediate from the rules of the semantics, since each complete term can always be reduced. The only special case is for *(com)* terms, since they could be stuck due to free variables in the expressions to be evaluated. Our assumption that C contains no free variable name avoids this case. \square

Corollary D.1 (Deadlock-freedom for EPP). *Let C be a complete choreography, contain no free variable names, and be well-typed. Then, $\llbracket C \rrbracket$ is deadlock-free.*

Proof. By Theorem 4, we know that C can always make a transition until it eventually terminates. By Theorem 3, we know that $\llbracket C \rrbracket$ is able to mimic all moves by C . Hence, also $\llbracket C \rrbracket$ must be able to make those transitions by C until it eventually terminates. \square

Theorem D.5 (Progress for Partial Choreographies). *Let C be a choreography, be well-typed, and contain no *(par)* terms. Then, there exists C' such that $(\nu \tilde{r}) (C \mid C')$, where $\tilde{r} = \text{fn}(C)$, is well-typed and deadlock-free.*

Proof (Sketch). Theorem 4 allows us to concentrate only on the progress of partial terms, since complete terms are deadlock-free. For partial term in C we observe that the type system ensures that, since C contains no *(par)* terms, the corresponding dual action is not in C . Hence, we can construct a catalyser for C' for C such that the thesis holds, following the construction technique presented in the works [6, 3]. In particular, we can reuse the technique in the long version of [3] by adapting the syntax of processes to those of our partial terms with a single fresh process identifier. \square

Corollary D.2 (Progress for EPP). *Let C be a choreography, contain no free variable names, be well-typed, and contain no *(par)* terms. Then, there exists C' such that $(\nu \tilde{r}) (\llbracket C \rrbracket \mid C')$, where $\tilde{r} = \text{fn}(C)$, is well-typed and deadlock-free.*

Proof. By reasoning similar to the proof for Corollary 1, we can apply Theorem 3 and Theorem 5. Then, the thesis follows by case analysis on the possible transitions of $\llbracket C \rrbracket$. \square