Sistemas Inteligentes

Hidden Markov Models(Columbia-Collins)

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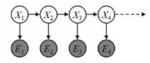
Reasoning over Time or Space

We want to reason about a sequence of observations

- Speech recognition
- Robot localization
- Medical monitoring
- Machine translation

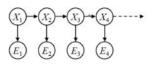
Hidden Markov Models

- Underlying Markov chain over states S
- You observe outputs (effects) at each time step
- $P(X_1), P(X_t|X_{t-1})$ and $P(E_t|X_t)$



Properties

- Hidden Markov process, future depends on past via the present (e.g. if X_3 is observed then $X_2 \perp X_4$)
- Current observation independent of all else given current state (e.g. if X_2 is observed then $E_2 \perp Z$)



HMM Examples

Speech Recognition HMMs:

- Observations are acoustic signals
- States are specific positions in specific words

Machine Translation HMMs:

- Observations are words
- States are translation options

Robot Tracking:

- Observations are range readings
- States are positions on a map

 ${\sf HMM} \,\, {\sf for} \,\, {\sf Tagging}$

Part-of-Speech Tagging

INPUT:

Profits soared at Boeing Co., easily topping forecasts on Wall Street, as their CEO Alan Mulally announced first quarter results.

OUTPUT:

```
Profits/N soared/V at/P Boeing/N Co./N ,/, easily/ADV topping/V forecasts/N on/P Wall/N Street/N ,/, as/P their/POSS CEO/N Alan/N Mulally/N announced/V first/ADJ quarter/N results/N ./.
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```
N = Noun
V = Verb
P = Preposition
Adv = Adverb
Adj = Adjective
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Named Entity Recognition

INPUT: Profits soared at Boeing Co., easily topping forecasts on Wall Street, as their CEO Alan Mulally announced first quarter results.

OUTPUT: Profits soared at [Company Boeing Co.], easily topping forecasts on [Location Wall Street], as their CEO [Person Alan Mulally] announced first quarter results.

Named Entity Recognition as Tagging

INPUT:

Profits soared at Boeing Co., easily topping forecasts on Wall Street, as their CEO Alan Mulally announced first quarter results.

OUTPUT:

Profits/NA soared/NA at/NA Boeing/SC Co./CC ,/NA easily/NA topping/NA forecasts/NA on/NA Wall/SL Street/CL ,/NA as/NA their/NA CEO/NA Alan/SP Mulally/CP announced/NA first/NA quarter/NA results/NA ./NA

NA = No entity

SC = Start Company

CC = Continue Company

SL = Start Location

CL = Continue Location

. . .

The Goal

Training set:

```
1 Pierre/NNP Vinken/NNP ,/, 61/CD years/NNS old/JJ ,/, will/MD join/VB the/DT board/NN as/IN a/DT nonexecutive/JJ director/NN Nov./NNP 29/CD ./.
2 Mr./NNP Vinken/NNP is/VBZ chairman/NN of/IN Elsevier/NNP N.V./NNP ,/, the/DT Dutch/NNP publishing/VBG group/NN ./.
3 Rudolph/NNP Agnew/NNP ,/, 55/CD years/NNS old/JJ and/CC chairman/NN of/IN Consolidated/NNP Gold/NNP Fields/NNP PLC/NNP ,/, was/VBD named/VBN a/DT nonexecutive/JJ director/NN of/IN
```

38,219 It/PRP is/VBZ also/RB pulling/VBG 20/CD people/NNS out/IN of/IN Puerto/NNP Rico/NNP ./, who/WP were/VBD helping/VBG Huricane/NNP Hugo/NNP victims/NNS ./, and/CC sending/VBG them/PRP to/TO San/NNP Francisco/NNP instead/RB ./.

this/DT British/JJ industrial/JJ conglomerate/NN ./.

From the training set, induce a function / algorithm that maps new sentences to their tag sequences $x^{(1)} = \text{The dog laughs}, \ v^{(1)} = \text{DT NN VB}$

Two Types of Constraints

Influential/JJ members/NNS of/IN the/DT House/NNP Ways/NNP and/CC Means/NNP Committee/NNP introduced/VBD legislation/NN that/WDT would/MD restrict/VB how/WRB the/DT new/JJ savings-and-loan/NN bailout/NN agency/NN can/MD raise/VB capital/NN ./.

- Local:e.g. can is more likely to be a modal verb MD rather than a noun NN
- Contextual: e.g., a noun is much more likely than a verb to follow a determiner (DT NN)
- Sometimes these preferences are in conflict: The trash can is in the garage

Supervised Learning Problem

- We have training examples $x^{(i)}, y^{(i)}$ for i = 1 ... m. Each $x^{(i)}$ is an input, each $y^{(i)}$ is a label
- Task is to learn a function f mapping inputs x to labels f(x)
- Conditional models:
 - Learn a distribution p(y|x) from training examples
 - For any test input x, define $f(x) = \arg \max_{y} p(y|x)$

Decoding with Generative Models

- We have training examples $x^{(i)}, y^{(i)}$ for i = 1...m. Task is to learn a function f mapping inputs x to labels f(x)
- Generative models:
 - Learn a distribution p(x, y) from training examples
 - p(x,y) = p(y)p(x|y)
- Output from the model:

$$\begin{array}{ll} f(x) & = & \arg\max_y p(y|x) \\ & = & \arg\max_y \frac{p(y)p(x|y)}{p(x)} (p(x) \text{ does not vary with y}) \\ & = & \arg\max_y p(y)p(x|y) \end{array}$$

Trigram HMM

Hidden Markov Models

- We have an input sentence $x = x_1, x_2, ..., x_n$ (x_i is the i'th word in the sentence)
- We have a tag sequence $y = y_1, y_2, \dots, y_n$ (y_i is the i'th tag in the sentence)
- We'll use an HMM to define

$$p(x_1, x_2, \ldots, x_n, y_1, y_2, \ldots, y_n)$$

for any sentence $x_1 ldots x_n$ and tag sequence $y_1 ldots y_n$ of the same length

• Then the most likely tag sequence for x is

$$\arg\max_{y_1...y_n} p(x_1,\ldots,x_n,y_1,y_2\ldots,y_n)$$

Trigram HMM

For any sentence $x_1 \ldots x_n$ where $x_i \in \mathcal{V}$ for $i=1\ldots n$, and any tag sequence $y_1 \ldots y_{n+1}$, where $y_i \in \mathcal{S}$ for $i=1\ldots n$, and y_{n+1} =STOP (e.g. $\mathcal{V}=\{the,dog,cat,\ldots\}$, $\mathcal{S}=$ DT,NN,P,ADV,...), the joint probability of the sentence and tag sequence is

$$p(x_1,\ldots,x_n,y_1,\ldots,y_{n+1})=\prod_{i=1}^{n+1}q(y_i|y_{i-2},y_{i-1})\prod_{i=1}^ne(x_i|y_i)$$

We have assumed that $y_0 = y_{-1} = *$ Parameters of the model:

- q(s|u,v) for any $s \in S \cup STOP$, $u,v \in S \cup *$
- e(x|s) for any $s \in \mathcal{S}, x \in \mathcal{V}$

Example

If we have $n=3, x_1 \dots x_3$ equal to the sentence the dog laughs, and $y_1 \dots y_4$ equal to the tag sequence D N V STOP, then

$$p(x_1, ..., x_n, y_1, ..., y_{n+1})$$

$$= q(D|*, *) \times q(N|*, D) \times q(V|D, N) \times q(STOP|N, V)$$

$$\times e(the|D) \times e(dog|N) \times e(laughs|V)$$

- STOP is a special tag that terminates the sequence
- We take $y_0 = y_{-1} = *$, where * is a special padding symbol

Parameters estimation

Smoothed Estimation

$$q(V_t|DT,JJ) = \lambda_1 \times \frac{Count(DT,JJ,V_t)}{Count(DT,JJ)}$$

$$\lambda_2 \times \frac{Count(JJ,V_t)}{Count(JJ)}$$

$$\lambda_3 \times \frac{Count(V_t)}{Count()}$$

$$\lambda_1 + \lambda_2 + \lambda_3, \text{ and for all } i, \lambda_i \geq 0$$

$$e(base|V_t) = \frac{Count(V_t, base)}{Count(V_t)}$$

Dealing with Low-Frequency Words

e(rare|y) = 0 for all tags y then p(x,y) = 0 for all tag sequences $y_1 \dots y_{n+1}$

- Step 1: Split vocabulary into two sets: a) frequent words (words occurring ≥ 5 times in training); b) low frequency words (all other words)
- Step 2: map low frequency words into a small, finite set, depending on prefixes, suffixes, etc

Dealing with Low-Frequency Words

```
Profits/NA soared/NA at/NA Boeing/SC Co./CC./NA easily/NA
topping/NA forecasts/NA on/NA Wall/SL Street/CL ,/NA as/NA their/NA
CEO/NA Alan/SP Mulally/CP announced/NA first/NA guarter/NA
results/NA ./NA
firstword/NA soared/NA at/NA initCap/SC Co./CC ,/NA easily/NA
lowercase/NA forecasts/NA on/NA initCap/SL Street/CL ,/NA as/NA
their/NA CEO/NA Alan/SP initCap/CP announced/NA first/NA
quarter/NA results/NA ./NA
NA
         = No entity
                                     e (first wood INA)
e (int cap 150)
SC
         = Start Company
CC
         = Continue Company
SL
         = Start Location
CL
         = Continue Location
```

The Viterbi Algorithm

The Viterbi Algorithm

Problem: for an input $x_1 ldots x_n$, find

$$\arg\max_{y_1\dots y_{n+1}} p(x_1,\dots,x_n,y_1,\dots,y_{n+1})$$

where the arg max is taken over all sequences $y_1 \dots y_{n+1}$ such that $y_i \in \mathcal{S}$ (e.g D,N,V) for $i=1\dots n$, and $y_{n+1}=\mathsf{STOP}$ We assume that p again takes the form

$$p(x_1,\ldots,x_n,y_1,\ldots,y_{n+1})=\prod_{i=1}^{n+1}q(y_i|y_{i-2},y_{i-1})\prod_{i=1}^ne(x_i|y_i)$$

Recall that $y_0 = y_{-1} = *$, and $y_{n+1} = STOP$.

Brute Force Search

Problem: for an input $x_1 ldots x_n$, find

$$\arg \max_{y_1...y_{n+1}} p(x_1,...,x_n,y_1,...,y_{n+1})$$

where the arg max is taken over all sequences $y_1 \dots y_{n+1}$ such that $y_i \in \mathcal{S}$ (e.g D,N,V)for $i = 1 \dots n$, and $y_{n+1} = \mathsf{STOP}$

the dog laughs
$$\rightarrow$$
 D D D STOP=0.3 \rightarrow D D N STOP=0.01 \rightarrow D D V STOP=0.0001

General Case $|S|^n$

The Viterbi Algorithm

- Define *n* to be the length of the sentence
- Define S_k for $k = -1 \dots n$ to be the set of possible tags at position k:

$$\mathcal{S}_{-1} = \mathcal{S}_0 = \{*\}$$

 $\mathcal{S}_k = \mathcal{S} ext{ for } k \in \{1 \dots n\}$

Define

$$r(y_{-1}, y_0, y_1, \dots, y_k) = \prod_{i=1}^k q(y_i|y_{i-2}, y_{i-1}) \prod_{i=1}^k e(x_i|y_i)$$

• Define a dynamic programming table

$$\pi(k, u, v) = \max_{u, v \text{ at position } k} \max_{u, v \text{ at position } k} \sup_{u, v \text{ at position } k} \max_{u, v \text{ at position } k} \sup_{u, v \text{ at p$$

That is,

$$\pi(k, u, v) = \max_{\langle y_{-1}, y_0, y_1, \dots, y_k \rangle : y_{k-1} = u, y_k = v} r(y_{-1}, y_0, y_1, \dots, y_k)$$

An Example

 $\pi(k, u, v) = \max_{u, v \text{ at position } k} \max_{v \in V} \min_{v \in V} \min_{$

$$\mathcal{S} = \{D, N, V, P\}$$

The man saw the dog with the telescope

A Recursive Definition

- Base case: $\pi(0, *, *) = 1$
- Rec. definition: for any $k \in \{1 \dots n\}$, for any $u \in \mathcal{S}_{k-1}$ and $v \in \mathcal{S}_k$:

$$\pi(k, u, v) = \max_{w \in \mathcal{S}_{k-2}} (\pi(k-1, w, u) \times q(v|w, u) \times e(x_k|v))$$

Justification for Recursive Definition

For any $k \in \{1 \dots n\}$, for any $u \in \mathcal{S}_{k-1}$ and $v \in \mathcal{S}_k$:

$$\pi(k, u, v) = \max_{w \in \mathcal{S}_{k-2}} (\pi(k-1, w, u) \times q(v|w, u) \times e(x_k|v))$$

The man saw the dog with the telescope
$$\pi(7, P, D) = \max_{w \in \{P, V, N, P\}} \left(\pi(b, w, P) \times 2(D|u, P) \times e(the|D)\right)$$

The Viterbi Algorithm

```
Input: a sentence x_1 \dots x_n, parameters q(s|u,v) and e(x|s) Initialization: Set \pi(0,*,*)=1 Definition: \mathcal{S}_{-1}=\mathcal{S}_0=\{*\}, \mathcal{S}_k=\mathcal{S} \text{ (e.g. D,N,V,P) for } k\in\{1\dots n\} Algorithm:
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- For k = 1 ... n
 - For $u \in \mathcal{S}_{k-1}, v \in \mathcal{S}_k$,

$$\pi(k, u, v) = \max_{w \in \mathcal{S}_{k-2}} (\pi(k-1, w, u) \times q(v|w, u) \times e(x_k|v))$$

• Return $\max_{u \in S_{n-1}, v \in S_n} (\pi(n, u, v) \times q(STOP|u, v))$

The Viterbi Algorithm with Backpointers $(O(n|S|^3))$

Input: a sentence $x_1 \dots x_n$, parameters q(s|u,v) and e(x|s) Initialization: Set $\pi(0,*,*)=1$ Definition: $\mathcal{S}_{-1}=\mathcal{S}_0=0$, $\mathcal{S}_k=\mathcal{S}$ (e.g. {D,N,V,P}) for $k\in 1\dots n$ Algorithm:

- For k = 1 ... n
 - For $u \in \mathcal{S}_{k-1}$, $v \in \mathcal{S}_k$,

$$\pi(k, u, v) = \max_{w \in \mathcal{S}_{k-2}} (\pi(k-1, w, u) \times q(v|w, u) \times e(x_k|v))$$

$$bp(k, u, v) = \arg\max_{w \in \mathcal{S}_{k-2}} (\pi(k-1, w, u) \times q(v|w, u) \times e(x_k|v))$$

- Set $(y_{n-1}, y_n) = \operatorname{arg\,max}_{(u,v)}(\pi(n, u, v) \times q(STOP|u, v))$
- For $k = (n-2)...1, y_k = bp(k+2, y_{k+1}, y_{k+2})$
- Return the tag sequence $y_1 \dots y_n$

Tarea

- Crear un Jupyter notebook e implementar HMM para realizar Named Entity Recognition en Español
- Utilizar el dataset CoNLL-2002 (https://www.clips.uantwerpen.be/conll2002/ner/)