Data Science for Actuaries (ACT6100)

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Supervisé # 4 (Interprétation)

automne 2020

Consider a regression model

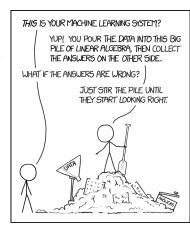
$$y_i = \beta_0 + \beta_1 x_{1,i} + \beta_2 x_{2,i} + \varepsilon_i$$

with standard econometric notations, holding x_2 fixed (*Ceteris Paribus* interpretation),

$$\beta_1 = \frac{\partial y}{\partial x_1}$$

assuming $\mathbb{E}[\varepsilon|x_1,x_2]=0$, or with notions used so far

$$\beta_1 = \frac{\partial m(\mathbf{x})}{\partial x_1} \ (= \text{constant})$$



(source Randall Munroe (xkcd, 2016))

Ceteris paribus can be translated into "all other things being equal" or "holding other factors constant."

In a linear regression, $y_i = \beta_0 + \beta_1 x_{1,i} + \beta_2 x_{2,i} + \varepsilon_i$

$$\beta_1 = \frac{\partial y}{\partial x_1}$$

In a logistic linear regression, $logit(p_i) = \beta_0 + \beta_1 x_{1,i} + \beta_2 x_{2,i}$

$$\exp[\beta_1] = \frac{\partial y}{y \partial x_1}$$

Mutatis mutandis approximately translates as "allowing other things to change accordingly" or "the necessary changes having been made."



What do we mean by interpreting a machine learning model, and why do we need it? Is it to trust the model? Or try to find causal relationships in the analyzed phenomenon? Or to visualize it?

- ► Lipton (2017, The Mythos of Model Interpretability),
- Lakkaraju et al. (2019, Faithful and Customizable Explanations of Black Box Models),
- ► Molnar (2019. Interpretable Machine Learning: A Guide for Making Black Box Models Explainable),
- ► Guidotti et al. (2018, A Survey of Methods for Explaining Black Box Models)
- ▶ Gilpin et al. (2019, Explaining Explanations: An Overview of Interpretability of Machine Learning)
- ► Lundberg & Lee (2017, A Unified Approach to Interpreting Model Predictions)

For works that describe machine learning models as black boxes, transparency and interpretability are closely related, if not the same concept.

We can open the black box either

- by explaining the model,
- by explaining the outcome
- by inspecting the black box internally
- by providing a transparent solution.

"Neural nets and random forests are considered as black boxes". Ribeiro et al. (2016, "Why Should I Trust You?": Explaining the Predictions of Any Classifier).

Following Guidotti et al. (2018, A Survey of Methods for Explaining Black Box Models) In this general setting, a (black box) model is $m: \mathcal{X} \mapsto \mathcal{Y}$ (neural nets, SVM, etc), explanators ϵ will be described after (Features Importance, Sensitivity Analysis, Partial Dependence Plot, etc).

Black-box model explanation

Given a black box predictor m and a dataset $\mathcal{D}_n = \{(\mathbf{x}_i, y_i)\} \in (\mathcal{X} \times \mathcal{Y})^n$, the black box model explanation problem consists in finding a function $f: (\mathcal{X} \mapsto \mathcal{Y}) \times (\mathcal{X} \times \mathcal{Y})^n \to (\mathcal{X} \mapsto \mathcal{Y})$ that returns a comprehensible global predictor c_g , i.e., $f(m, \mathcal{D}_n) = c_g$, such that c_g is able to mimic the behavior of m, and exists a global explanator function $\epsilon_g: (\mathcal{X} \mapsto \mathcal{Y}) \to \mathcal{E}$ that can derive from c_g a set of explanations $E \in \mathcal{E}$ modeling in a human understandable way the logic behind c_{φ} , i.e., $\epsilon(c_{\varphi}) = E$.



Black-box outcome explanation

Given a black box predictor b and a dataset $\mathcal{D}_n = \{(\mathbf{x}_i, y_i)\}$, the black box outcome explanation problem consists in finding a function $f: (\mathcal{X} \mapsto \mathcal{Y}) \times (\mathcal{X} \times \mathcal{Y})^n \to (X \mapsto Y)$ that returns a comprehensible local predictor c_{ℓ} , i.e., $f(m, \mathcal{D}_n) = c_{\ell}$, such that c_{ℓ} is able to mimic the behavior of m, and exists a local explanator function $\epsilon_{\ell}: (\mathcal{X} \mapsto \mathcal{Y}) \times (\mathcal{X} \mapsto \mathcal{Y}) \times \mathcal{X} \to \mathcal{E}$ that can derive from the black box model m, the comprehensible local predictor c_{ℓ} , and a data record x, a human understandable explanation $e \in E$ for the data record \mathbf{x} , i.e., $\epsilon_{\ell}(m, c_{\ell}, \mathbf{x}) = e$

Black box inspection explanation

Given a black box predictor b and a dataset $\mathcal{D}_n = \{(\mathbf{x}_i, y_i)\}$, the black box inspection problem consists in finding a function $f: (\mathcal{X} \mapsto \mathcal{Y}) \times (\mathcal{X} \times \mathcal{Y})^n \to V$ that returns a visual representation of the behavior of the black box, $f(m, \mathcal{D}_n) = v$ with V being the set of all possible representations.

The transparent box design problem consists in providing a model which is locally or globally interpretable on its own,



Transparent box design problem

Given a dataset $\mathcal{D}_n = \{(\mathbf{x}_i, \mathbf{y}_i)\}$, the transparent box design problem consists in finding a learning function $L: (\mathcal{X} \times \mathcal{Y})^n \to (\mathcal{X} \mapsto \mathcal{Y})$ that returns a (locally or globally) comprehensible predictor c, i.e., $L(\mathcal{D}_n) = c$. This implies that there exists an explanator function, local ϵ_{ℓ} or global ϵ_{σ} , that takes as input the comprehensible predictor c and returns a human understandable explanation $e \in E$, or a set of explanations E.

• Partial Dependence Plot

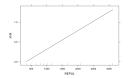
Introduced in Friedman (2001, Greedy function approximation: A gradient boosting machine). Let x be splitted in two parts : x_s (variable(s) of interest) and x_c the complementary, $x = (x_s, x_c)$. Partial dependence of x_s is

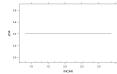
$$p(\boldsymbol{x}_s) = \mathbb{E}[m(\boldsymbol{x}_s, \boldsymbol{S}_c)] \text{ and } \widehat{p}(\boldsymbol{x}_s) = \frac{1}{n} \sum_{i=1}^n \widehat{m}(\boldsymbol{x}_s, \boldsymbol{x}_{i,c})$$

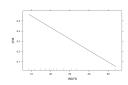
See pdp package

pdp::partial(model, pred.var = "REPUL", plot = TRUE)}

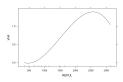
Consider a (standard) linear model on the myocarde dataset

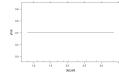


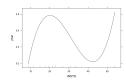




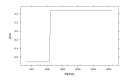
Consider an additive model (GAM) on the myocarde dataset

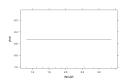


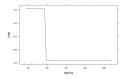




or a classification tree



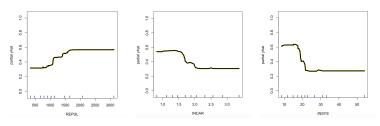


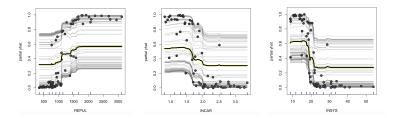


Individual Conditional Expectation

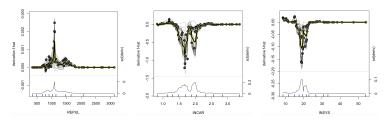
Extention of Partial Dependence Plots, introduced in Goldstein et al. (2013, Peeking inside the black box: Visualizing statistical learning with plots of individual conditional expectation), "Visually, ICE plots disaggregate the output of classical PDPs. Rather than plot the target covariates' average partial effect on the predicted response, we instead plot the n estimated conditional expectation curves"

See ICEbox package. Here m is a random forest,





One can also plot the derivative of ICE functions







Accumulated Local Effects

Introduced in Apley (2016, Visualizing the effects of predictor variables in black box supervised learning models). Partial dependence of x_s is

$$p(\mathbf{x}_s) = \mathbb{E}[m(\mathbf{x}_s, \mathbf{S}_c)] \text{ and } \widehat{p}(\mathbf{x}_s) = \frac{1}{n} \sum_{i=1}^n \widehat{m}(\mathbf{x}_s, \mathbf{x}_{i,c})$$

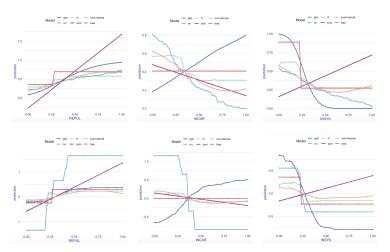
Here, we focus on

$$a(\boldsymbol{x}_s) = \int_{-\infty}^{\boldsymbol{x}_s} \mathbb{E}\left[\frac{\partial m(\boldsymbol{z}_s, \boldsymbol{S}_c)}{\partial \boldsymbol{x}_s}\right] d\boldsymbol{z}_s$$

See DALEX and

- DALEX::single_variable(explain(m), variable = x, type = "ale")
- 2 DALEX::single_variable(explain(m), variable = x, type = "pdp")

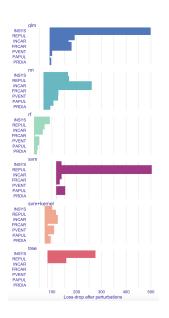
Partial Dependence Plot (on top) and Accumulated Local Effects (below)



Feature Interaction

Friedman & Popescu (2008, (Predictive learning via rule ensembles), see Greenwell et al. (2018, A simple and effective modelbased variable importance measure)

- > iml::Interaction
 - Feature (Variable) Importance Breiman (2001, Random Forests)
- > iml::FeatureImp





• Local Surrogate (LIME) - Local Interpretable Model-Agnostic **Explanations**

Alvarez-Melis & Jaakkola (2018, On the robustness of interpretability methods)

see the lime or ceterisParibus packages (and the what-if plot)

