# Data Science for Actuaries (ACT6100)

Arthur Charpentier

Supervisé # 2 (régularisation - 3)

automne 2020







#### Linearly Separable sample [regression notations]

Data  $(y_1, x_1), \dots, (y_n, x_n)$  - with  $y \in \{0, 1\}$  are linearly separable if there are  $(\beta_0, \beta)$  such that

- 
$$y_i = 1$$
 if  $\beta_0 + \mathbf{x}_i^{\top} \boldsymbol{\beta} > 0$   
-  $y_i = 0$  if  $\beta_0 + \mathbf{x}_i^{\top} \boldsymbol{\beta} < 0$ 

$$y_i = 0 \text{ if } \beta_0 + \boldsymbol{x}_i^{\top} \boldsymbol{\beta} < 0$$

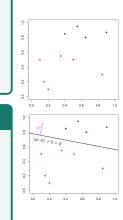
#### Linearly Separable sample [ML notations]

Data  $(y_1, x_1), \dots, (y_n, x_n)$  - with  $y \in \{-1, +1\}$ - are linearly separable if there are  $(b, \omega)$  such that

- 
$$y_i = +1$$
 if  $b + \langle \boldsymbol{x}_i, \boldsymbol{\omega} \rangle > 0$ 

- 
$$y_i = -1$$
 if  $b + \langle oldsymbol{x}_i, oldsymbol{\omega} 
angle < 0$ 

or equivalently  $y_i \cdot (b + \langle x_i, \omega \rangle) > 0$ ,  $\forall i$ .



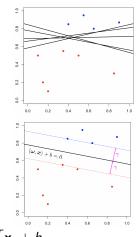
$$(b + \langle \mathbf{x}, \boldsymbol{\omega} \rangle) = b + \mathbf{x}^{\top} \boldsymbol{\omega} = 0$$

is an hyperplane (in  $\mathbb{R}^p$ ) orthogonal with  $\omega$ Use  $m(\mathbf{x}) = \mathbf{1}_{b+\langle \mathbf{x}, \boldsymbol{\omega} \rangle > 0} - \mathbf{1}_{b+\langle \mathbf{x}, \boldsymbol{\omega} \rangle < 0}$  as classifier

Problem : equation (i.e.  $(b,\omega)$ ) is not unique! Canonical form :  $\min_{i=1,\cdots,n}\left\{|b+\langle \pmb{x}_i,\pmb{\omega}\rangle|\right\}=1$ 

Problem: solution here is not unique!

Idea: use the widest (safety) margin  $\gamma$ Vapnik & Lerner (1963) and or Cover (1965).



The distance from point 
$$\mathbf{x}_i$$
 to  $\Delta$  is  $d(\mathbf{x}_i, \Delta) = \frac{\omega^T \mathbf{x}_i + b}{\|\omega\|}$ . Consider

$$\max_{\omega,b} \left\{ \min_{i=1,\cdots,n} \left\{ d(\mathbf{x}_i, \Delta) \right\} \right\}$$

Consider two points,  $x_{-1}$  and  $x_{+1}$ 

$$\gamma = \frac{1}{2} \frac{\langle \omega, \mathbf{x}_{+1} - \mathbf{x}_{-1} \rangle}{\|\omega\|}$$

It is minimal when

$$b+\langle oldsymbol{\omega}_i, oldsymbol{\mathsf{x}_{-1}} 
angle = -1$$
 and

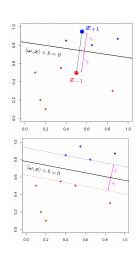
 $b + \langle \omega_i, \mathbf{x}_{+1} \rangle = +1$ , and therefore

$$\gamma^\star = rac{1}{\|oldsymbol{\omega}\|}$$

Optimization problem  $\max\{\gamma\}$  becomes

$$\min_{(\boldsymbol{h}\boldsymbol{\omega})} \left\{ \frac{1}{2} \|\boldsymbol{\omega}\|_{\ell_2}^2 \right\} \text{ s.t. } y_i \cdot (\boldsymbol{b} + \langle \boldsymbol{x}, \boldsymbol{\omega} \rangle) > 0, \ \forall i.$$

convex optimization problem with linear constraints



Here, 
$$L(b, \boldsymbol{\omega}, \boldsymbol{\alpha}) = \frac{1}{2} \|\boldsymbol{\omega}\|^2 - \sum_{i=1}^n \alpha_i \cdot (y_i \cdot (b + \langle \boldsymbol{x}, \boldsymbol{\omega} \rangle) - 1)$$

From the first order conditions

$$\frac{\partial L(b, \omega, \alpha)}{\partial \omega} = \omega - \sum_{i=1}^{n} \alpha_{i} \cdot y_{i} \mathbf{x}_{i} = \mathbf{0}, \text{ i.e. } \omega^{*} = \sum_{i=1}^{n} \alpha_{i}^{*} y_{i} \mathbf{x}_{i}$$
$$\frac{\partial L(b, \omega, \alpha)}{\partial b} = -\sum_{i=1}^{n} \alpha_{i} \cdot y_{i} = 0, \text{ i.e. } \sum_{i=1}^{n} \alpha_{i}^{*} \cdot y_{i} = 0$$

and

$$\Lambda(\boldsymbol{\alpha}) = \sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i,i=1}^{n} \alpha_i \alpha_j y_i y_j \langle \boldsymbol{\alpha}_i, \boldsymbol{\alpha}_j \rangle$$

i.e. 
$$\Lambda(\alpha) = \mathbf{1}^{ op} \alpha - \frac{1}{2} \alpha^{ op} \mathbf{Q} \alpha$$

The dual problem is

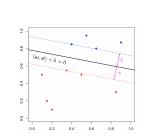
$$\min_{\alpha} \left\{ \frac{1}{2} \alpha^{\top} \mathbf{Q} \alpha - \mathbf{1}^{\top} \alpha \right\} \text{ s.t. } \left\{ \begin{array}{l} \alpha_i \geq 0, \ \forall i \\ \mathbf{y}^{\top} \alpha = 0 \end{array} \right.$$

where  $m{Q} = [m{Q}_{i,j}]$  and  $m{Q}_{i,j} = y_i y_j \langle m{x}_i, m{x}_j \rangle$ , and then

$$\boldsymbol{\omega}^{\star} = \sum_{i=1}^{n} \alpha_{i}^{\star} y_{i} \boldsymbol{x}_{i} \text{ and } \boldsymbol{b}^{\star} = -\frac{1}{2} \left[ \min_{i: y_{i} = +1} \{ \langle \boldsymbol{x}_{i}, \boldsymbol{\omega}^{\star} \rangle \} + \min_{i: y_{i} = -1} \{ \langle \boldsymbol{x}_{i}, \boldsymbol{\omega}^{\star} \rangle \} \right]$$

Points  $x_i$  such that  $\alpha_i^* > 0$  are called support

$$\begin{aligned} y_i \cdot \left(b^\star + \langle \mathbf{x}_i, \boldsymbol{\omega}^\star \rangle \right) &= 1 \\ \text{Classifier } m^\star(\mathbf{x}) &= \mathbf{1}_{b^\star + \langle \mathbf{x}, \boldsymbol{\omega}^\star \rangle \geq 0} - \mathbf{1}_{b^\star + \langle \mathbf{x}, \boldsymbol{\omega}^\star \rangle < 0} \\ \text{Observe that } \gamma^\star &= \left(\sum_{i=1}^n \alpha_i^{\star 2} \right)^{-1/2} \end{aligned}$$



Consider here the more general case where the space is not linearly separable

$$(\langle \boldsymbol{\omega}, \boldsymbol{x}_i \rangle + b) y_i \geq 1$$

becomes

$$(\langle \omega, \mathbf{x}_i \rangle + b) y_i \geq 1 - \xi_i$$

for some slack variables  $\xi_i$ 's. and penalize large slack variables  $\xi_i$  (when > 0) by solving (for

some cost C)

$$\min_{\boldsymbol{\omega},\boldsymbol{b}} \left\{ \frac{1}{2} \boldsymbol{\omega}^{\top} \boldsymbol{\omega} + C \sum_{i=1}^{n} \xi_{i} \right\}$$

subject to  $\forall i, \xi_i \geq 0$  and  $(\mathbf{x_i}^{\top} \boldsymbol{\omega} + b) \mathbf{y_i} \geq 1 - \xi_i$ .

This is the soft-margin extension, see

- > e1071::svm()
  - > kernlab::ksvm()

The dual optimization problem is now

$$\min_{\alpha} \left\{ \frac{1}{2} \boldsymbol{\alpha}^{\top} \boldsymbol{Q} \boldsymbol{\alpha} - \mathbf{1}^{\top} \boldsymbol{\alpha} \right\} \text{ s.t. } \left\{ \begin{array}{l} 0 \leq \alpha_{i} \leq \boldsymbol{C}, \ \forall i \\ \boldsymbol{y}^{\top} \mathbf{1} = 0 \end{array} \right.$$

where  $\mathbf{Q} = [\mathbf{Q}_{i,i}]$  and  $\mathbf{Q}_{i,i} = y_i y_i \langle \mathbf{x}_i, \mathbf{x}_i \rangle$ , and then

$$\boldsymbol{\omega}^{\star} = \sum_{i=1}^{n} \alpha_{i}^{\star} y_{i} \boldsymbol{x}_{i} \text{ and } b^{\star} = -\frac{1}{2} \left[ \min_{i:y_{i}=+1} \{ \langle \boldsymbol{x}_{i}, \boldsymbol{\omega}^{\star} \rangle \} + \min_{i:y_{i}=-1} \{ \langle \boldsymbol{x}_{i}, \boldsymbol{\omega}^{\star} \rangle \} \right]$$

Note further that the (primal) optimization problem can be written

$$\min_{(b,\boldsymbol{\omega})} \left\{ \frac{1}{2} \|\boldsymbol{\omega}\|_{\ell_2}^2 + \sum_{i=1}^n \left( 1 - y_i \cdot (b + \langle \boldsymbol{x}, \boldsymbol{\omega} \rangle) \right)_+ \right\},\,$$

where  $(1-z)_+$  is a convex upper bound for empirical error  $\mathbf{1}_{z<0}$ 

The dual optimization problem is now

$$\min_{\alpha} \left\{ \frac{1}{2} \alpha^{\top} \mathbf{Q} \alpha - \mathbf{1}^{\top} \alpha \right\} \text{ s.t. } \left\{ \begin{array}{l} 0 \leq \alpha_{i} \leq \mathbf{C}, \ \forall i \\ \mathbf{y}^{\top} \alpha = 0 \end{array} \right.$$

where  $m{Q} = [m{Q}_{i,j}]$  and  $m{Q}_{i,j} = y_i y_j \langle m{x}_i, m{x}_j 
angle$ 

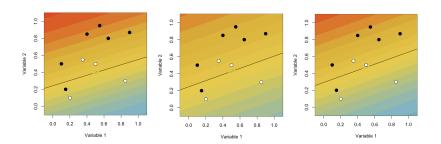
```
1 > library(quadprog)
2 > C = .5
3 > y = (myocarde[,"PRONO"] == "SURVIE") *2-1
4 > X = as.matrix(cbind(1,myocarde[,1:7]))
5 > n = length(y)
6 > Q = sapply(1:n, function(i) y[i]*t(X)[,i])
7 > D = t(Q)%*%Q
8 > d = matrix(1, nrow=n)
9 > A = rbind(y,diag(n),-diag(n))
10 > b = c(0,rep(0,n),rep(-C,n))
```

```
_{1} > eps = 5e-4
> sol = solve.QP(D+eps*diag(n), d, t(A),b, meq=1,
      factorized=FALSE)
3 > qpsol = sol$solution
4 > omega = apply(qpsol*y*X,2,sum)
5 > omega
1 FRCAR INCAR INSYS PRDIA PAPUL PVENT REPUL
7 0.000 0.055 -0.092 0.361 -0.109 -0.049 -0.066 0.001
 \operatorname{car} \boldsymbol{\omega}^{\star} = \sum_{i=1}^{n} \alpha_{i}^{\star} y_{i} \boldsymbol{x}_{i}
```





```
1 x1 = c(.4,.55,.65,.9,.1,.35,.5,.15,.2,.85)
2 x2 = c(.85,.95,.8,.87,.5,.55,.5,.2,.1,.3)
3 y = c(1,1,1,1,1,0,0,1,0,0)
4 df = data.frame(x1=x1,x2=x2,y=2*y-1)
5 library(kernlab)
6 SVM2 = ksvm(y ~ x1 + x2, data = df, C=2.5, kernel = "vanilladot", prob.model=TRUE, type="C-svc")
```



One can also consider the kernel trick :  $\mathbf{x}_i^{\top} \mathbf{x}_j$  is replace by  $\varphi(\mathbf{x}_i)^{\top} \varphi(\mathbf{x}_j)$  for some mapping  $\varphi$ ,

$$K(\mathbf{x}_i, \mathbf{x}_j) = \varphi(\mathbf{x}_i)^{\top} \varphi(\mathbf{x}_j)$$

For instance  $K(\boldsymbol{a}, \boldsymbol{b}) = (\boldsymbol{a}^{\top} \boldsymbol{b})^3 = \varphi(\boldsymbol{a})^{\top} \varphi(\boldsymbol{b})$  where  $\varphi(a_1, a_2) = (a_1^3 \ , \ \sqrt{3} a_1^2 a_2 \ , \ \sqrt{3} a_1 a_2^2 \ , \ a_2^3)$  Consider polynomial kernels

$$K(\boldsymbol{a}, \boldsymbol{b}) = (1 + \boldsymbol{a}^{\top} \boldsymbol{b})^{p}$$

or a Gaussian kernel

$$K(\boldsymbol{a}, \boldsymbol{b}) = \exp(-(\boldsymbol{a} - \boldsymbol{b})^{\top}(\boldsymbol{a} - \boldsymbol{b}))$$

and solve  $\max_{\alpha_i \geq 0} \left\{ \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n y_i y_j \alpha_i \alpha_j K(\mathbf{x}_i, \mathbf{x}_j) \right\}$ 

The radial kernel is formed by taking an infinite sum over polynomial kernels...

$$K(\mathbf{x}, \mathbf{y}) = \exp\left(-\gamma \|\mathbf{x} - \mathbf{y}\|^2\right) = \langle \psi(\mathbf{x}), \psi(\mathbf{y}) \rangle$$

where  $\psi$  is some  $\mathbb{R}^n \to \mathbb{R}^{\infty}$  function, since

$$K(\mathbf{x}, \mathbf{y}) = \exp\left(-\gamma \|\mathbf{x} - \mathbf{y}\|^2\right) = \underbrace{\exp(-\gamma \|\mathbf{x}\|^2 - \gamma \|\mathbf{y}\|^2)}_{= \text{constant}} \cdot \exp\left(2\gamma \langle \mathbf{x}, \mathbf{y} \rangle\right)$$

i.e.

$$K(\mathbf{x}, \mathbf{y}) \propto \exp\left(2\gamma \langle \mathbf{x}, \mathbf{y} \rangle\right) = \sum_{k=0}^{\infty} 2\gamma \frac{\langle \mathbf{x}, \mathbf{y} \rangle^k}{k!} = \sum_{k=0}^{\infty} 2\gamma K_k(\mathbf{x}, \mathbf{y})$$

where  $K_k$  is the polynomial kernel of degree k.

If  $K = K_1 + K_2$  with  $\psi_i : \mathbb{R}^n \to \mathbb{R}^{d_i}$  then  $\psi : \mathbb{R}^n \to \mathbb{R}^d$  with  $d \sim d_1 + d_2$ 

A kernel is a measure of similarity between vectors.

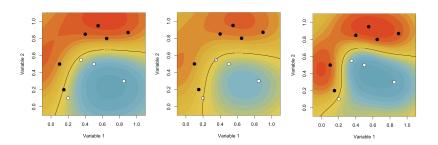
The smaller the value of  $\gamma$  the narrower the vectors should be to have a small measure

Is there a probabilistic interpretation? Platt (2000, Probabilities for SVM) suggested to use a logistic function over the SVM scores.

$$p(\mathbf{x}) = \frac{\exp[b + \langle \mathbf{x}, \boldsymbol{\omega} \rangle]}{1 + \exp[b + \langle \mathbf{x}, \boldsymbol{\omega} \rangle]}$$

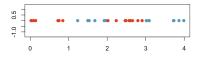


```
1 x1 = c(.4,.55,.65,.9,.1,.35,.5,.15,.2,.85)
2 x2 = c(.85,.95,.8,.87,.5,.55,.5,.2,.1,.3)
3 y = c(1,1,1,1,1,0,0,1,0,0)
4 df = data.frame(x1=x1,x2=x2,y=2*y-1)
5 library(kernlab)
6 SVM2 = ksvm(y ~ x1 + x2, data = df, C=1, kernel = "rbfdot", prob.model=TRUE, type="C-svc")
```



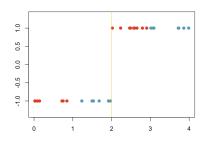
# Nomlinear kernels & adding features

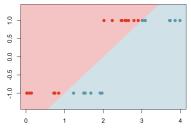
Consider the following data,  $(x_i, y_i)$  with binary y, and  $x \in \mathbb{R}$ 



Any linear classifier on  $(x_i, y_i)$  will behave poorly...

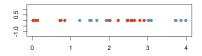
Why not a linear classifier on  $(x_i, \mathbf{1}(x_i > 2), y_i)$ ?





## Nomlinear kernels & adding features

Consider the following data,  $(x_i, y_i)$  with binary y, and  $x \in \mathbb{R}$ 



Any linear classifier on  $(x_i, y_i)$  will behave poorly...

Why not a linear classifier on  $(x_i, x_i^2, x_i^3, y_i)$ ?

