

Data Science for Actuaries (ACT6100)

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Rappels # 1 (Vectors, Norms & Inner Product)

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 <https://github.com/freakonometrics/ACT6100/>

Norm

A **norm** $\|\cdot\|$, in \mathbb{R}^n , satisfies

- ▶ homogeneity, $\|a\vec{u}\| = |a| \cdot \|\vec{u}\|$
- ▶ triangle inequality, $\|\vec{u} + \vec{v}\| \leq \|\vec{u}\| + \|\vec{v}\|$
- ▶ positivity, $\|\vec{u}\| \geq 0$
- ▶ definiteness, $\|\vec{u}\| = 0 \iff \vec{u} = \vec{0}$

ℓ_1 norm: $\|\mathbf{x}\|_{\ell_1} = |x_1| + \dots + |x_n|$,

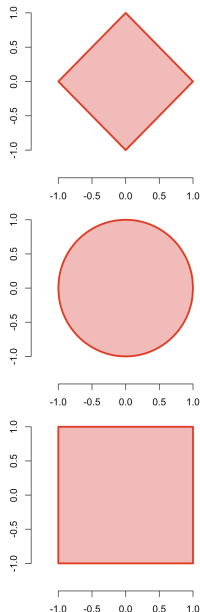
see **taxicab geometry**

ℓ_p norm: with $p \geq 1$,

$$\|\mathbf{x}\|_{\ell_p} = (|x_1|^p + \dots + |x_n|^p)^{1/p}$$

e.g. $\|\mathbf{x}\|_{\ell_\infty} = \max\{x_i\}$

Unit balls ($\|\mathbf{x}\| \leq 1$) are convex sets



Hilbert Space and Inner Products

An **inner product** $\langle \cdot, \cdot \rangle$, in \mathbb{R}^n , satisfies

- ▶ symmetry, $\langle \vec{u}, \vec{v} \rangle = \langle \vec{v}, \vec{u} \rangle$
- ▶ linearity, $\langle a\vec{u} + b\vec{v}, \vec{w} \rangle = a\langle \vec{u}, \vec{w} \rangle + b\langle \vec{v}, \vec{w} \rangle$
- ▶ positivity, $\langle \vec{u}, \vec{u} \rangle \geq 0$
- ▶ definiteness, $\langle \vec{u}, \vec{u} \rangle = 0 \iff \vec{u} = \vec{0}$

Example: On the set of \mathbb{R}^n vectors, $\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^\top \mathbf{y}$

Furthermore

- ▶ $\|\mathbf{x}\| = \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle}$ defines a norm
- ▶ $d(\mathbf{x}, \mathbf{y}) = \|\mathbf{x} - \mathbf{y}\|$ defines a distance

Example: On the set of $m \times n$ matrices, $\langle \mathbf{A}, \mathbf{B} \rangle = \text{trace}(\mathbf{A}\mathbf{B}^\top)$

Example: On the set of random variables, $\langle X, Y \rangle = \mathbb{E}(XY)$

Distance

$d(\mathbf{x}, \mathbf{y}) = \|\mathbf{x} - \mathbf{y}\|$ defines a distance.

$$d(\mathbf{a}, \mathbf{b}) + d(\mathbf{b}, \mathbf{c}) \geq d(\mathbf{a}, \mathbf{c})$$

Example Let $\mathbf{y}, \mathbf{x}_1, \dots, \mathbf{x}_n$. The **nearest neighbor** of \mathbf{y} , among the \mathbf{x}_i 's is

$$\mathbf{x}_{j^*} = \operatorname{argmin}_{\mathbf{x} \in \{\mathbf{x}_1, \dots, \mathbf{x}_n\}} \{d(\mathbf{x}, \mathbf{y})\}$$

```
1 > X = matrix(runif(8*3),8,3)
2 > dist(X,method = "euclidean")
3           1           2           3           4           5           6           7
4 2  0.832
5 3  0.698  0.455
6 4  0.539  1.054  0.716
7 5  0.834  1.074  0.785  0.921
8 6  0.755  0.977  0.554  0.354  0.871
9 7  0.153  0.739  0.691  0.666  0.885  0.849
10 8  0.734  0.990  0.804  0.977  0.263  0.989  0.752
```

Cauchy-Schwarz Inequality

$|\langle \mathbf{x}, \mathbf{y} \rangle| \leq \|\mathbf{x}\| \cdot \|\mathbf{y}\|$ with equality only when $\mathbf{x} = \lambda \mathbf{y}$

Application: $x_i \leftarrow x_i - \bar{x}$ and $y_i \leftarrow y_i - \bar{y}$,

$$\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^\top \mathbf{y} = \sum_{i=1}^n x_i y_i$$

$$\|\mathbf{x}\| \cdot \|\mathbf{y}\| = \sqrt{\mathbf{x}^\top \mathbf{x}} \cdot \sqrt{\mathbf{y}^\top \mathbf{y}} = \sqrt{\sum_{i=1}^n x_i^2} \cdot \sqrt{\sum_{i=1}^n y_i^2}$$

$$\text{corr}(\mathbf{x}, \mathbf{y}) = \frac{\sum_{i=1}^n x_i y_i}{\sum_{i=1}^n x_i^2 \cdot \sum_{i=1}^n y_i^2} = \frac{\langle \mathbf{x}, \mathbf{y} \rangle}{\|\mathbf{x}\| \cdot \|\mathbf{y}\|} \in [-1, +1]$$

and $\text{corr}(\mathbf{x}, \mathbf{y}) = \pm 1$ only when $\mathbf{x} = \lambda \mathbf{y}$.

Angles

Since $|\langle \mathbf{x}, \mathbf{y} \rangle| \leq \|\mathbf{x}\| \cdot \|\mathbf{y}\|$, define θ as the unique number in $[0, \pi]$ that satisfies

$$\langle \mathbf{x}, \mathbf{y} \rangle = \|\mathbf{x}\| \cdot \|\mathbf{y}\| \cos(\theta), \text{ or } \theta = \arccos \frac{\langle \mathbf{x}, \mathbf{y} \rangle}{\|\mathbf{x}\| \cdot \|\mathbf{y}\|}$$

Mahalanobis distance

A $n \times n$ symmetric matrix \mathbf{M} is **positive definite** if $\mathbf{x}^\top \mathbf{M} \mathbf{x} > 0$ for any $\mathbf{x} \in \mathbb{R}^n$.

Proposition: If \mathbf{M} is a positive definite (symmetric) matrix, then $\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^\top \mathbf{M} \mathbf{y}$ defines an inner product.

(furthermore, conversely, if $\langle \mathbf{x}, \mathbf{y} \rangle = \mathbf{x}^\top \mathbf{M} \mathbf{y}$ defines an inner product, then \mathbf{M} is definite positive)

- ▶ $\langle \mathbf{x}, \mathbf{y} \rangle_M = \mathbf{x}^\top \mathbf{M} \mathbf{y}$ defines an inner product,
- ▶ $\|\mathbf{x}\|_M = \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle_M}$ defines a norm
- ▶ $d_M(\mathbf{x}, \mathbf{y}) = \|\mathbf{x} - \mathbf{y}\|_M$ defines a distance

Given Σ some $n \times n$ definite positive matrix, define

$$d(\mathbf{x}, \mathbf{y}) = \sqrt{(\mathbf{x} - \mathbf{y})^\top \Sigma^{-1} (\mathbf{x} - \mathbf{y})}$$

Given $\mu \in \mathbb{R}^n$, define the **Mahalanobis “norm”** as

$$\|\mathbf{x}\| = d(\mathbf{x}, \mu) = \sqrt{(\mathbf{x} - \mu)^\top \Sigma^{-1} (\mathbf{x} - \mu)}$$

If Σ is diagonal, it is also called standardized Euclidean distance.

See [on the generalised distance in statistics](#), 1936.

Linear Independence

A collection of k vectors $\{\vec{x}_1, \dots, \vec{x}_k\}$ (in \mathbb{R}^n) are **linearly dependent** if there are $\alpha_1, \dots, \alpha_k$ such that

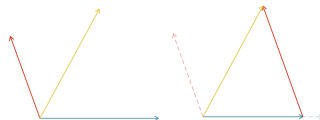
$$\alpha_1 \vec{x}_1 + \alpha_2 \vec{x}_2 + \dots + \alpha_k \vec{x}_k = \vec{0}$$

They are **linearly independent** if they are not linearly dependent, i.e.

$$\alpha_1 \vec{x}_1 + \alpha_2 \vec{x}_2 + \dots + \alpha_k \vec{x}_k = \vec{0} \implies \alpha_1 = \dots = \alpha_k = 0$$

Proposition A collection of linearly independent vectors in \mathbb{R}^n can have, at most, n elements.

$(n + 1)$ vectors in \mathbb{R}^n are linearly dependent



Orthonormalization (Gram-Schmidt)

If vectors $\{\vec{x}_1, \dots, \vec{x}_k\}$ are linearly independent, the Gram-Schmidt algorithm produces an **orthonormal** collection of vectors $\{\vec{u}_1, \dots, \vec{u}_k\}$ with the following properties

- ▶ every \vec{x}_j is a linear combination of $\{\vec{u}_1, \dots, \vec{u}_k\}$
- ▶ every \vec{u}_j is a linear combination of $\{\vec{x}_1, \dots, \vec{x}_k\}$

Algorithm 1: Gram-Schmidt

- 1 initialization : $\{\vec{x}_1, \dots, \vec{x}_n\}$;
 - 2 **for** $t=1,2,\dots,k$ **do**
 - 3 $\vec{u}_t = \vec{x}_t - [\langle \vec{u}_1, \vec{x}_t \rangle \vec{u}_1 + \dots + \langle \vec{u}_{t-1}, \vec{x}_t \rangle \vec{u}_{t-1}]$;
 $\vec{u}_t = \vec{u}_t / \|\vec{u}_t\|$
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