

Paired factor analysis (PFA)

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1 The PFA model

1.1 Data and latent variables

Let D_{nj} be the data corresponding to n -th sample and j -th feature, where n runs from 1 to N and j runs from 1 to J . Suppose these data come from a graph with K nodes (factors) and E edges. In the PFA set up $E = \frac{K(K-1)}{2}$.

Let us define latent variables Z and Λ . Z_n is a $(E + K) \times 1$ binary vector. We use Z_{n,k_1,k_2} to indicate samples in between nodes k_1 and k_2 , and $Z_{n,l}$ to indicate samples near node l . Prior on Z is defined as:

$$\begin{aligned} Pr[Z_{n,k_1,k_2} = 1] &= \pi_{k_1,k_2} & k_1 < k_2 \\ Pr[Z_{n,l} = 1] &= \pi_l & l = 1, 2, \dots, K \end{aligned}$$

with the constraint that

$$\sum_{k_1 < k_2}^E \pi_{k_1,k_2} + \sum_{l=1}^K \pi_l = 1$$

Likelihood of Z is

$$Pr(Z|\pi) = \prod_{n=1}^N \prod_{k_1 < k_2}^E \pi_{k_1,k_2}^{z_{n,k_1,k_2}} \prod_{l=1}^K \pi_l^{z_{n,l}}$$

Λ_n is a $Q \times 1$ binary vector, where Q is the cardinality of the set of coordinates for positions in between nodes that samples are fitted to. For computational convenience we assume that these coordinates take a finite set of values between 0 and 1, say $1/100, 2/100, \dots, 99/100, 1$.

We have a prior on Λ ,

$$Pr[\Lambda_{n,q} = 1] = \delta_q$$

$$Pr(\Lambda|\delta) = \prod_{n=1}^N \prod_{q=1}^Q \delta_q^{\lambda_{n,q}}$$

1.2 The model likelihood

For data on the graph given a pair of nodes (k_1, k_2) and position q on the edge we assume a simple mixture model

$$\begin{aligned}
E[D_{nj}|Z_{n,k_1,k_2} = 1, \Lambda_{n,q} = 1, F] &= qF_{k_1,j} + (1-q)F_{k_2,j} & k_1 < k_2 \\
E[D_{nj}|Z_{n,l} = 1, F] &= F_{l,j} & k_1 = k_2 = l
\end{aligned} \tag{1}$$

Where F is a $K \times J$ matrix of factors. Then we can marginalize over Z and Λ , assuming as a first pass that the data is Gaussian in its distribution,

$$\begin{aligned}
Pr[D_n|\pi, \delta, F, s_{j=1,2,\dots,J}^2] &= \sum_{k_1 < k_2} \pi_{k_1,k_2} Pr[D_n|Z_{n,k_1,k_2} = 1, \delta, F, s_{j=1,2,\dots,J}^2] \\
&+ \sum_l \pi_l Pr[D_n|Z_{n,l} = 1, F, s_{j=1,2,\dots,J}^2] \tag{2}
\end{aligned}$$

where

$$Pr[D_n|Z_{n,k_1,k_2} = 1, \delta, F, s_{j=1,2,\dots,J}^2] = \sum_q \delta_q Pr[D_n|Z_{n,k_1,k_2} = 1, \Lambda_{n,q} = 1, F, s_{j=1,2,\dots,J}^2]$$

and s_j^2 is the residual variance of the j th feature.

The overall likelihood

$$\begin{aligned}
L(\pi, F) &= \prod_{n=1}^N Pr[D_n|\pi, F, s_{j=1,2,\dots,J}^2] \\
&= \prod_{n=1}^N \left[\sum_{k_1 < k_2} \sum_{q=1}^Q \left[\pi_{k_1,k_2,q} \times \prod_{j=1}^J N(D_{nj}; qF_{k_1,j} + (1-q)F_{k_2,j}, s_j^2) \right] + \right. \\
&\quad \left. \sum_l \left[\pi_l \times \prod_{j=1}^J N(D_{nj}; F_{l,j}, s_j^2) \right] \right] \tag{3}
\end{aligned}$$

And the log likelihood

$$\begin{aligned}
\ln L(\pi, F) &= \sum_{n=1}^N \ln \left(\sum_{k_1 < k_2} \sum_q \left[\pi_{k_1,k_2,q} \times \prod_{j=1}^J N(D_{nj}; qF_{k_1,j} + (1-q)F_{k_2,j}, s_j^2) \right] + \right. \\
&\quad \left. \sum_{l=1}^K \pi_l \times \prod_{j=1}^J N(D_{nj}; F_{l,j}, s_j^2) \right) \tag{4}
\end{aligned}$$

This is the quantity we want to maximize.

2 EM algorithm

2.1 E step

We assume that q can take a finite set of values between 0 and 1, say $1/100, 2/100, \dots, 90/100, 1$.

Suppose we have run upto m iterations. For the $(m+1)$ th iteration, we have

$$\begin{aligned}\delta_{n,k_1,k_2,0,q}^{(m+1)} &= Pr \left[Z_{n,k_1,k_2,0} = 1, \Lambda_{n,q} = 1 | \pi^{(m)}, F^{(m)}, s_{j=1,2,\dots,J}^{(m)}, D_n \right] \\ &\propto Pr \left[Z_{n,k_1,k_2,0} = 1 \right] Pr \left[\lambda_{n,q} = 1 \right] Pr \left[D_n | \pi^{(m)}, F^{(m)}, s_{j=1,2,\dots,J}^{(m)}, Z_{n,k_1,k_2,0} = 1, \lambda_{n,q} = 1 \right] \\ &\propto \pi_{k_1,k_2,q}^{(m)} \prod_j N \left(D_{nj} | qF_{k_1,j}^{(m)} + (1-q)F_{k_2,j}^{(m)}, s_j^{(m)2} \right)\end{aligned}$$

$$\begin{aligned}\delta_{n,0,0,l}^{(m+1)} &= Pr \left[Z_{n,0,0,l} = 1 | \pi^{(m)}, F^{(m)}, s_{j=1,2,\dots,J}^{(m)}, D_n \right] \\ &\propto Pr \left[Z_{n,0,0,l} = 1 \right] Pr \left[D_n | \pi^{(m)}, F^{(m)}, s_{j=1,2,\dots,J}^{(m)}, Z_{n,0,0,l} = 1 \right] \\ &\propto \pi_l^{(m)} \prod_j N \left(D_{nj} | F_{l,j}^{(m)}, s_j^{(m)2} \right)\end{aligned}$$

where $s_j^{(m)2}$ is the residual variance of feature j .

We normalize δ so that

$$\sum_{k_1 < k_2} \sum_q \delta_{n,k_1,k_2,0,q}^{(m+1)} + \sum_{l=1}^K \delta_{n,0,0,l}^{(m+1)} = 1 \quad \forall n$$

We define

$$\begin{aligned}\pi_{k_1,k_2,q}^{(m+1)} &= \frac{1}{N} \sum_{n=1}^N \delta_{n,k_1,k_2,0,q}^{(m+1)} \\ \pi_l^{(m+1)} &= \frac{1}{N} \sum_{n=1}^N \delta_{n,0,0,l}^{(m+1)}\end{aligned}$$

We have therefore updated $\pi_{k_1,k_2,q}^{(m)}$ to $\pi_{k_1,k_2,q}^{(m+1)}$.

2.1.1 Variational EM - Model 1

In this set up, we assume prior distributions of π and δ as follows

$$Pr(\pi | \alpha_0) = C(\alpha_0) \prod_{k_1 < k_2} \pi_{k_1,k_2}^{\alpha_0-1} \prod_{l=1}^L \pi_l^{\alpha_0-1}$$

Similarly the prior distribution for δ is

$$Pr(\delta|\beta_0) = C(\beta_0) \prod_{q=1}^Q \delta_q^{\beta_0-1}$$

The likelihood above can be written as

$$p(D|Z, \Lambda, F, s_{j=1,2,\dots,J}) = \prod_{n=1}^N \left[\prod_{k_1 < k_2} \prod_{q=1}^Q \left[\prod_{j=1}^J N(D_{ng}|qF_{k1,g} + (1-q)F_{k2,g}, s_g^2) \right]^{\Lambda_{nq} Z_{n,k1,k2,0}} \right. \\ \left. \times \prod_l \left[\prod_{j=1}^J N(D_{ng}|F_{l,g}, s_g^2) \right]^{Z_{n,0,0,l}} \right] \quad (5)$$

The joint probability distribution is given by

$$p(D, Z, \Lambda, \pi, \delta|F, s_{j=1,2,\dots,J}, \alpha_0, \beta_0) = p(\pi|\alpha_0)p(\delta|\beta_0)p(\Lambda|\delta)p(Z|\pi)p(D|Z, \Lambda, F, s_{j=1,2,\dots,J})$$

We assume the following mean field variational distribution. In the first model, we assume the two latent variables Z and Λ are independent.

$$q(Z, \Lambda, \pi, \delta) = q(Z)q(\Lambda)q(\pi)q(\delta)$$

The variational distribution for Z

$$\begin{aligned} \ln q^*(Z) &= E_{\pi,\delta,\Lambda} [\ln p(\pi|\alpha_0) + \ln p(\delta|\beta_0) + \ln p(\Lambda|\delta) + \ln p(Z|\pi) + \ln p(D|Z, \Lambda, F, s_{j=1,2,\dots,J})] \\ &= E_{\pi,\delta,\Lambda} [\ln p(Z|\pi) + \ln p(D|Z, \Lambda, F, s_{j=1,2,\dots,J})] + \text{constant} \\ &= \sum_{n=1}^N \sum_{k_1 < k_2} z_{n,k1,k2} E_{\pi} [\ln(\pi_{k1,k2})] + \sum_{n=1}^N \sum_{k_1 < k_2} z_{n,k1,k2} \sum_q E_{\Lambda}(\lambda_{nq}) \left[- \sum_{j=1}^J \ln(s_j) \right. \\ &\quad \left. - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - qF_{k1,j} - (1-q)F_{k2,j})^2}{2s_j^2} \right] \end{aligned}$$

$$\begin{aligned} \ln q^*(\Lambda) &= E_{\pi,\delta,Z} [\ln p(\pi|\alpha_0) + \ln p(\delta|\beta_0) + \ln p(\Lambda|\delta) + \ln p(Z|\pi) + \ln p(D|Z, \Lambda, F, s_{j=1,2,\dots,J})] \\ &= E_{\pi,\delta,Z} [\ln p(\Lambda|\delta) + \ln p(D|Z, \Lambda, F, s_{j=1,2,\dots,J})] + \text{constant} \\ &= \sum_{n=1}^N \sum_{q=1}^Q \lambda_{n,q} E_{\delta} [\ln(\delta_q)] + \sum_{n=1}^N \sum_q \lambda_{nq} \sum_{k_1 < k_2} E_Z(z_{n,k1,k2}) \left[- \sum_{j=1}^J \ln(s_j) \right] \end{aligned}$$

$$-\frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - qF_{k1,j} - (1-q)F_{k2,j})^2}{2s_j^2} \Bigg]$$

So we get

$$q^*(Z) \propto \prod_{n=1}^N \prod_{k_1 < k_2} \rho_{n,k_1,k_2}^{Z_{n,k_1,k_2}}$$

where we define

$$\rho_{n,k_1,k_2} \propto \exp \left(E_\pi [\ln(\pi_{k_1,k_2})] + \sum_q E_\Lambda(\lambda_{nq}) \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - qF_{k1,j} - (1-q)F_{k2,j})^2}{2s_j^2} \right] \right)$$

$$\rho_{n,k_1,k_2} \propto \exp \left(E_\pi [\ln(\pi_{k_1,k_2})] + \sum_q \nu_{nq} \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - qF_{k1,j} - (1-q)F_{k2,j})^2}{2s_j^2} \right] \right)$$

$$\rho_{n,k_1,k_2} \propto \exp \left(\psi_{a_{k_1,k_2}} - \psi \left(\sum_{k_1 < k_2} a_{k_1,k_2} \right) + \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - qF_{k1,j} - (1-q)F_{k2,j})^2}{2s_j^2} \right] \right)$$

ρ_{n,k_1,k_2} is normalized to sum to 1 for each n over k_1 and k_2 .

We also get

$$q^*(\Lambda) \propto \prod_{n=1}^N \prod_{q=1}^Q \nu_{nq}^{\Lambda_{nq}}$$

where

$$\nu_{nq} \propto \exp \left(E_\delta [\ln(\delta_q)] + \sum_{k_1 < k_2} E_Z(z_{n,k_1,k_2}) \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - qF_{k1,j} - (1-q)F_{k2,j})^2}{2s_j^2} \right] \right)$$

$$\nu_{nq} \propto \exp \left(E_\delta [\ln(\delta_q)] + \sum_{k_1 < k_2} \rho_{n,k_1,k_2} \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - qF_{k1,j} - (1-q)F_{k2,j})^2}{2s_j^2} \right] \right)$$

$$\nu_{nq} \propto \exp \left(\psi(b_q) - \psi\left(\sum_{q=1}^Q b_q\right) + \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - qF_{k1,j} - (1-q)F_{k2,j})^2}{2s_j^2} \right] \right)$$

ν_{nq} are normalized to sum to 1.

We can also derive variational distributions similarly for π and δ .

$$\begin{aligned} \ln q^*(\pi) &= E_{\Lambda, Z, \delta} [\ln p(\pi|\alpha_0) + \ln p(\delta|\beta_0) + \ln p(\Lambda|\delta) + \ln p(Z|\pi) + \ln p(D|Z, \Lambda, F, s_{j=1,2,\dots,J})] \\ &= E_Z [\ln p(Z|\pi)] + \ln p(\pi|\alpha_0) + \text{constant} \\ &= \sum_{n=1}^N \sum_{k1 < k2} E(z_{n,k1,k2}) \ln \pi_{k1,k2} + (\alpha_0 - 1) \sum_{k1 < k2} \ln \pi_{k1,k2} \\ &= \sum_{k1 < k2} \left[\sum_{n=1}^N \rho_{n,k1,k2} + (\alpha_0 - 1) \right] \ln \pi_k \end{aligned}$$

We define

$$\begin{aligned} a_{k1,k2} &= \alpha_0 + \sum_{n=1}^N \rho_{n,k1,k2} \\ q^*(\pi) &= \text{Dir}(\pi|a) \end{aligned}$$

$$\begin{aligned} \ln q^*(\delta) &= E_{\Lambda, Z, \pi} [\ln p(\pi|\alpha_0) + \ln p(\delta|\beta_0) + \ln p(\Lambda|\delta) + \ln p(Z|\pi) + \ln p(D|Z, \Lambda, F, s_{j=1,2,\dots,J})] \\ &= E_{\Lambda} [\ln p(\Lambda|\delta)] + \ln p(\delta|\beta_0) + \text{constant} \\ &= \sum_{n=1}^N \sum_{q=1}^Q E(\lambda_{n,q}) \ln \delta_q + (\beta_0 - 1) \sum_{q=1}^Q \ln \delta_q \\ &= \sum_{q=1}^Q \left[\sum_{n=1}^N \nu_{n,q} + (\beta_0 - 1) \right] \ln \delta_q \end{aligned}$$

We define

$$\begin{aligned} b_q &= \beta_0 + \sum_{n=1}^N \nu_{n,q} \\ q^*(\delta) &= \text{Dir}(\delta|b) \end{aligned}$$

We alternate between the Variational E and M steps, E steps being the ones where we compute

the responsibilities $\rho_{n,k1,k2}$ and $\nu_{n,q}$ and the M step is where we update the variational distribution of the parameters π and δ .

We can start with $a = \alpha_0$ and $b = \beta_0$. We can then estimate $\rho_{n,k1,k2}$ and also ν_{nq} and then then product of these two terms to get new responsibility

$$\delta_{n,k1,k2,q} = \rho_{n,k1,k2} \nu_{nq}$$

and we use this $\delta_{n,k1,k2,q}$ as the responsibility for the M-step of the original EM updates.

2.1.2 Variational EM - Model 2

In model 2, we do not assume independence of the latent variables Z and Λ and instead estimate their joint variational distribution.

$$q(Z, \Lambda, \pi, \delta) = q(Z, \Lambda)q(\pi)q(\delta)$$

$$\begin{aligned} \ln q^*(Z, \Lambda) &= E_{\pi, \delta} [\ln p(\pi|\alpha_0) + \ln p(\delta|\beta_0) + \ln p(\Lambda|\delta) + \ln p(Z|\pi) + \ln p(D|Z, \Lambda, F, s_{j=1,2,\dots,J})] \\ &= E_{\pi, \delta, \Lambda} [\ln p(Z|\pi) + \ln p(\Lambda|\delta) + \ln p(D|Z, \Lambda, F, s_{j=1,2,\dots,J})] + \text{constant} \\ &= \sum_{n=1}^N \sum_{k_1 < k_2} \sum_{q=1}^Q z_{n,k1,k2,0} \lambda_{nq} E_{\pi} [\ln(\pi_{k1,k2})] + \sum_{n=1}^N \sum_{q=1}^Q \sum_{k_1 < k_2} \lambda_{n,q} z_{n,k1,k2,0} E_{\delta} [\ln(\delta_q)] \\ &\quad + \sum_{n=1}^N \sum_{k_1 < k_2} \sum_q z_{n,k1,k2,0} \lambda_{nq} \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - qF_{k1,j} - (1-q)F_{k2,j})^2}{2s_j^2} \right] \\ &\quad + \sum_{n=1}^N \sum_l z_{n,0,0,l} \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - F_{l,j})^2}{2s_j^2} \right] \\ &\quad + \sum_{n=1}^N \sum_{l=1}^K z_{n,0,0,l} E_{\pi} [\ln(\pi_l)] \end{aligned} \tag{6}$$

From here one can get

$$q^*(Z, \Lambda) \propto \prod_{n=1}^N \left[\prod_{k_1 < k_2} \prod_{q=1}^Q \delta_{n,k1,k2,0,q}^{Z_{n,k1,k2,0} \Lambda_{n,q}} \prod_{l=1}^K \delta_{n,0,0,l,q}^{Z_{n,0,0,l}} \right]$$

then

$$\begin{aligned} \delta_{n,k1,k2,0,q} &\propto \exp \left(E_{\pi} [\ln(\pi_{k1,k2})] + E_{\delta} [\ln(\delta_q)] \right. \\ &\quad \left. + \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - qF_{k1,j} - (1-q)F_{k2,j})^2}{2s_j^2} \right] \right) \end{aligned} \tag{7}$$

$$\delta_{n,k1,k2,0,q} \propto \exp \left(\psi(a_{k1,k2,0}) - \psi\left(\sum_l a_{0,0,l} + \sum_{k_1 < k_2} a_{k1,k2,0}\right) + \psi(b_q) - \psi\left(\sum_{q=1}^Q b_q\right) \right. \\ \left. \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - qF_{k1,j} - (1-q)F_{k2,j})^2}{2s_j^2} \right] \right) \quad (8)$$

$$\delta_{n,0,0,l} \propto \exp \left(E_\pi [\ln(\pi_l)] + \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - F_{l,j})^2}{2s_j^2} \right] \right) \quad (9)$$

$$\delta_{n,0,0,l} \propto \exp \left(\psi_{a_{0,0,l}} - \psi\left(\sum_l a_{0,0,l} + \sum_{k_1 < k_2} a_{k1,k2,0}\right) + \left[-\sum_{j=1}^J \ln(s_j) - \frac{J}{2} \ln(2\pi) - \sum_{j=1}^J \frac{(D_{nj} - F_{l,j})^2}{2s_j^2} \right] \right) \quad (10)$$

We can also derive variational distributions similarly for π and δ .

$$\begin{aligned} \ln q^*(\pi) &= E_{\Lambda, Z, \delta} [\ln p(\pi|\alpha_0) + \ln p(\delta|\beta_0) + \ln p(\Lambda|\delta) + \ln p(Z|\pi) + \ln p(D|Z, \Lambda, F, s_{j=1,2,\dots,J})] \\ &= E_Z [\ln p(Z|\pi)] + \ln p(\pi|\alpha_0) + \text{constant} \\ &= \sum_{n=1}^N \sum_{k1 < k2} E(z_{n,k1,k2,0}) \ln \pi_{k1,k2} + \sum_{n=1}^N \sum_{l=1}^K E(z_{n,0,0,l}) \ln \pi_l + (\alpha_0 - 1) \sum_{k1 < k2} \ln \pi_{k1,k2} \\ &= \sum_{k1 < k2} \left[\sum_{n=1}^N \rho_{n,k1,k2,0} + (\alpha_0 - 1) \right] \ln \pi_{k1,k2} + \sum_{l=1}^K \left[\sum_{n=1}^N \rho_{n,0,0,l} + (\alpha_0 - 1) \right] \ln \pi_l \end{aligned}$$

We define

$$\begin{aligned} a_{k1,k2,0} &= \alpha_0 + \sum_{n=1}^N \rho_{n,k1,k2,0} \\ a_{0,0,l} &= \alpha_0 + \sum_{n=1}^N \rho_{n,0,0,l} \\ q^*(\pi) &= \text{Dir}(\pi|a) \end{aligned}$$

$$\begin{aligned}
\ln q^*(\delta) &= E_{\Lambda, Z, \pi} [\ln p(\pi|\alpha_0) + \ln p(\delta|\beta_0) + \ln p(\Lambda|\delta) + \ln p(Z|\pi) + \ln p(D|Z, \Lambda, F, s_{j=1,2,\dots,J})] \\
&= E_{\Lambda} [\ln p(\Lambda|\delta)] + \ln p(\delta|\beta_0) + \text{constant} \\
&= \sum_{n=1}^N \sum_{q=1}^Q E(\lambda_{n,q}) \ln \delta_q + (\beta_0 - 1) \sum_{q=1}^Q \ln \delta_q \\
&= \sum_{q=1}^Q \left[\sum_{n=1}^N \nu_{n,q} + (\beta_0 - 1) \right] \ln \delta_q
\end{aligned}$$

We define

$$b_q = \beta_0 + \sum_{n=1}^N \nu_{n,q}$$

$$q^*(\delta) = \text{Dir}(\delta|b)$$

The updates for π and δ are same as before. Here also we have the same way of initializing π and δ first, then use $a_{k1,k2} = \alpha_0$ and $b_q = \beta_0$ to begin with and estimate $\delta_{n,k1,k2,q}$. Then use the $\delta_{n,k1,k2,q}$ to update $a_{k1,k2}$ and b_q and proceed in this way. In this case, we do not assume independence of the Λ and Z variational distributions, so this model is more generalized.

2.2 M step

We take the expectation of this quantity with respect to $[Z, \lambda|D, \theta^{(m)}]$.

$$Q(\theta|\theta^{(m)}) \propto - \sum_{n=1}^N \sum_{k_1 < k_2} \sum_{q=1}^Q \delta_{n,k_1,k_2,0,q}^{(m+1)} \sum_j \left[\log s_j^{(m+1)} + \frac{(D_{nj} - qF_{k_1,j} - (1-q)F_{k_2,j})^2}{2s_j^{(m+1)^2}} \right] \quad (11)$$

$$- \sum_{n=1}^N \sum_{l=1}^K \sum_{q=1}^Q \delta_{n,0,0,l,q}^{(m+1)} \sum_j \left[\log s_j^{(m+1)} + \frac{(D_{nj} - F_{l,j})^2}{2s_j^{(m+1)^2}} \right] \quad (12)$$

We try to maximize this quantity with respect to F , So, we can take derivative with respect to F and try to solve the resulting normal equation.

This equation, conditional on $[Z, \lambda|D, \theta^{(m)}]$, can be written as

$$D_{N \times J} = L_{N \times K} F_{K \times J} + E_{N \times J} \quad (13)$$

where

$$e_{nj} \sim N(0, s_j^2)$$

We define

$$D'_{nj} := \frac{D_{nj}}{s_j}$$

If we consider finding the factors on a feature-by-feature basis, we do not need to worry about s_j .

$$L_{nk} = \begin{cases} q \text{ or } (1-q) & \lambda_n = q \text{ } Z_{n,k,*,0} = 1 \text{ or } Z_{n,*,k,0} = 1 \\ 1 & Z_{n,0,0,k} = 1 \\ 0 & \text{o.w.} \end{cases}$$

We have

$$\begin{aligned} E_{Z,\lambda|D,\theta^{(m)}} [L_{nk}] &= \sum_q \sum_{k_2 > k} q \delta_{n,k,k_2,0,q}^{(m+1)} + \sum_q \sum_{k_1 < k} (1-q) \delta_{n,k_1,k,0,q}^{(m+1)} + \delta_{n,0,0,k}^{(m+1)} \\ E_{Z,\lambda|D,\theta^{(m)}} [L_{nk}^2] &= \sum_q \sum_{k_2 > k} q^2 \delta_{n,k,k_2,q}^{(m+1)} + \sum_q \sum_{k_1 < k} (1-q)^2 \delta_{n,k_1,k,q}^{(m+1)} + \delta_{n,0,0,k}^{(m+1)} \end{aligned}$$

Also for any $k \neq l$,

$$E_{Z,\lambda|D,\theta^{(m)}} [L_{nk} L_{nl}] = \sum_q q(1-q) \delta_{n,k,l,q}^{(m+1)}$$

We use these to solve for the equation

$$\left[E_{Z,\lambda|D,\theta^{(m)}} (L^T L) \right] F \approx \left[E_{Z,\lambda|D,\theta^{(m)}} (L) \right]^T D$$

The solution therefore is

$$F \approx \left[E_{Z,\lambda|D,\theta^{(m)}} (L^T L) \right]^{-1} \left[E_{Z,\lambda|D,\theta^{(m)}} (L) \right]^T D$$

For $W = L^T L$

$$W_{kl} = \sum_n L_{kn} L_{nl}$$

$$E_{Z,\lambda|D,\theta^{(m)}} (W_{kl}) = \sum_n E_{Z,\lambda|D,\theta^{(m)}} (L_{kn} L_{nl})$$

We use the definition of $E_{Z,\lambda|D,\theta^{(m)}} [L_{nk}^2]$ and $E_{Z,\lambda|D,\theta^{(m)}} [L_{nk} L_{nl}]$ from above to solve F .

In the same way as we computed F by solving for the normal equation obtained from taking derivative of the function $Q(\theta|\theta^{(m)})$, we take derivative of the latter with respect to s_j^2 to obtain EM updates of the residual variance terms. Taking the derivative, we obtain the estimate as

$$\begin{aligned}
\widehat{s_j^{(m+1)}}^2 &= \frac{1}{N} \sum_{n=1}^N \sum_{k_1 < k_2} \sum_q \delta_{n,k_1,k_2,0,q}^{(m+1)} (D_{nj} - qF_{k_1,j} - (1-q)F_{k_2,j})^2 \\
&\quad + \frac{1}{N} \sum_{n=1}^N \sum_{l=1}^K \delta_{n,0,0,l,q}^{(m+1)} (D_{nj} - F_{l,j})^2 \quad (14)
\end{aligned}$$

where the F are the estimated values of the factors from the previous step.
We then continue this procedure described above for multiple iterations.