Bayesian Statistics III/IV (MATH3361/4071)

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Problem class 2: Statistical decision theory, Bayesian point estimation, Credible sets

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1 Bayesian point estimation

Exercise 1. $(\star\star)$ Consider observables $x=(x_1,...,x_n)$. Consider the Bayesian model

$$\begin{cases} x_i | \theta & \stackrel{\text{IID}}{\sim} \mathbf{N}(\theta, 1), \quad i = 1, ..., n \\ \theta & \sim \Pi(\theta) \end{cases}$$

where $\pi(\theta) \propto 1$ and that we have only one observable. Consider the LINEX loss function

$$\ell(\theta, \delta) = \exp(c(\theta - \delta)) - c(\theta - \delta) - 1$$

- 1. Show that $\ell(\theta, \delta) \geq 0$
- 2. Find the Bayes estimator $\hat{\delta}$ under LINEX loss function and under the given Bayesian model.

Hint-1: Random variable B follows a log-normal distribution $B \sim \text{LN}(\mu_A, \sigma_A^2)$ with parameters μ_A, σ_A^2 if $B = \exp(A)$ where $A \sim \text{N}(\mu_A, \sigma_A^2)$.

Hint-2: If $B \sim \text{LN}(\mu_A, \sigma_A^2)$ then $\text{E}_{\text{LN}(\mu_A, \sigma_A^2)}(B) = \exp(\mu_A + \frac{\sigma_A^2}{2})$.

Hint-3: It is

$$-\frac{1}{2}\frac{(\mu-\mu_1)^2}{v_1^2} - \frac{1}{2}\frac{(\mu-\mu_2)^2}{v_2^2}... - \frac{1}{2}\frac{(\mu-\mu_n)^2}{v_n^2} = -\frac{1}{2}\frac{(\mu-\hat{\mu})^2}{\hat{v}^2} + C$$

where

$$\hat{v}^2 = \left(\sum_{i=1}^n \frac{1}{v_i^2}\right)^{-1}; \quad \hat{\mu} = \hat{v}^2 \left(\sum_{i=1}^n \frac{\mu_i}{v_i^2}\right); \quad C = \frac{1}{2} \frac{\hat{\mu}^2}{\hat{v}^2} - \frac{1}{2} \sum_{i=1}^n \frac{\mu_i^2}{v_i^2}$$

Exercise 2. $(\star\star)$ Suppose we wish to estimate the values of a collection of discrete random variables $\vec{X} = X_1, \ldots, X_n$. We have a posterior joint probability mass function for these variables, $p(\vec{x}|y) = p(x_1, \ldots, x_n|y)$ based on some data y. We decide to use the following loss function:

$$\ell(\hat{\vec{x}}, \vec{x}) = \sum_{i=1}^{n} (1 - \delta(\hat{x}_i, x_i)) \tag{1}$$

where $\delta(a, b) = 1$ if a = b and zero otherwise.

- 1. Derive an expression for the estimated values, found by minimizing the expectation of the loss function. [Hint: use linearity of expectation.]
- 2. When the probability distribution is a posterior distribution in some problem, this type of estimate is sometimes called 'maximum posterior marginal' (MPM) estimate. Explain why this name is appropriate.
- 3. Explain in words what the loss function is measuring. Compare with the loss function for MAP estimation.

2 Credible sets

Exercise 3. (**) (Example from the Lecture's handout) Consider a Bayesian model

$$\begin{cases} y_i | \mu & \stackrel{\text{iid}}{\sim} \mathbf{N}_d(\mu, \Sigma), & i = 1, ..., n \\ \mu & \sim \mathbf{N}_d(\mu_0, \Sigma_0) \end{cases}$$

where uncertain $\mu \in \mathbb{R}^d$, $d \ge 1$, and known Σ , μ_0 , Σ_0 . Find the C_a parametric HPD credible set for μ .

Hint-1: If $z=(z_1,...,z_d)^{\top}$ such as $z_j \stackrel{\text{iid}}{\sim} \mathrm{N}(0,1)$ for j=1,...,d, and $\xi=z^{\top}z=\sum_{j=1}^d z_j^2$, then $\xi\sim\chi_d^2$

Hint-2: It is

$$\begin{split} -\frac{1}{2} \sum_{i=1}^{n} (x - \mu_{i})^{\top} \Sigma_{i}^{-1} (x - \mu_{i})) &= -\frac{1}{2} (x - \hat{\mu})^{\top} \hat{\Sigma}^{-1} (x - \hat{\mu})) + C(\hat{\mu}, \hat{\Sigma}) \quad ; \\ \hat{\Sigma} &= (\sum_{i=1}^{n} \Sigma_{i}^{-1})^{-1}; \quad \hat{\mu} = \hat{\Sigma} (\sum_{i=1}^{n} \Sigma_{i}^{-1} \mu_{i}); \\ C(\hat{\mu}, \hat{\Sigma}) &= \underbrace{\frac{1}{2} (\sum_{i=1}^{n} \Sigma_{i}^{-1} \mu_{i})^{\top} (\sum_{i=1}^{n} \Sigma_{i}^{-1})^{-1} (\sum_{i=1}^{n} \Sigma_{i}^{-1} \mu_{i}) - \frac{1}{2} \sum_{i=1}^{n} \mu_{i}^{\top} \Sigma_{i}^{-1} \mu_{i})}_{= \text{independent of } x} \end{split}$$

Example 4. $(\star\star)$ (Example from the Lecture's handout) Assume a 1-dimensional random quantity $x\sim Q(x|y)$, with unimodal density q(x|y). Show that the (1-a)-credible interval $C_a=[L,U]$ for x as a Bayesian rule C_a under the loss function

$$\ell(x,C_a;L,U) = k(U-L) - 1(x \in [L,U]), \quad \text{with} \quad k \in (0,\max_{\forall x \in \mathbb{R}}(q(x|y)))$$

is given by q(L) = q(U) = k, and $P_Q(x \in [L, U]|y) = 1 - a$.

Discuss known properties of the derived credible interval.

Solution. The decision space is $\mathcal{D} = \{C_a = [L, U] : \Pr_Q(x \in C_a | y) = 1 - a\}$. It is

$$\begin{split} \mathbf{E}_{Q} \left(\ell(x, C_{a}; L) | y \right) &= \int \left(k(U - L) - 1(x \in [L, U]) \right) \mathrm{d}Q(x | y) \\ &= \int k(U - L) q(x | y) \mathrm{d}x - \int_{L}^{U} q(x | y) \mathrm{d}x = k(U - L) - \int_{-\infty}^{U} q(x | y) \mathrm{d}x + \int_{-\infty}^{L} q(x | y) \mathrm{d}x \end{split}$$

To find the critical values \hat{L} , and \hat{U} for L and U, it is

$$\begin{split} 0 &= \left. \frac{\mathrm{d}}{\mathrm{d}L} \mathrm{E}_Q \left(\ell(x, C_a; L) | y \right) \right|_{C_a = [\hat{L}, \hat{U}]} = \left. \frac{\mathrm{d}}{\mathrm{d}L} \left(k(U - L) - \int_{-\infty}^{U} q(x|y) \mathrm{d}x + \int_{-\infty}^{L} q(x|y) \mathrm{d}x \right) \right|_{C_a = [\hat{L}, \hat{U}]} \\ &= -k + q(\hat{L}|y) \implies q(\hat{L}|y) = k \\ 0 &= \left. \frac{\mathrm{d}}{\mathrm{d}U} \mathrm{E}_Q \left(\ell(x, C_a; U) | y \right) \right|_{C_a = [\hat{L}, \hat{U}]} = \ldots = k - q(\hat{U}|y) \implies q(\hat{U}|y) = k \end{split}$$

which are minimizers because

$$\begin{split} \frac{\mathrm{d}^2}{\mathrm{d}L^2} \mathrm{E}_Q\left(\ell(x,C_a;L)|y\right)\bigg|_{C_a = [\hat{L},\hat{U}]} &= \left.\frac{\mathrm{d}}{\mathrm{d}L}q(L|y)\right|_{\hat{L}} > 0 \;; \qquad \quad \left.\frac{\mathrm{d}^2}{\mathrm{d}L\mathrm{d}U} \mathrm{E}_Q\left(\ell(x,C_a;L)|y\right)\right|_{C_a = [\hat{L},\hat{U}]} = 0 \\ \frac{\mathrm{d}^2}{\mathrm{d}U^2} \mathrm{E}_Q\left(\ell(x,C_a;U)|y\right)\bigg|_{C_a = [\hat{L},\hat{U}]} &= -\left.\frac{\mathrm{d}}{\mathrm{d}U}q(U|y)\right|_{\hat{U}} > 0 \end{split}$$

So it is $C_a=[\hat{L},\hat{U}]$ such that $q(\hat{L}|y)=q(\hat{U}|y)=k$, and $\Pr_Q(x\in[\hat{L},\hat{U}]|y)=1-a$.

Based on Theorem ??, it is the HPD credible interval and in fact the shorter length credible interval.

Example 5. $(\star\star)$ (Example from the Lecture's handout) Assume an 1- dimensional random quantity $x \sim Q(x|y)$. In the Lecture Handout (Handout 11: Bayesian point estimation), discussed the following Hint:

Hint: The Bayes estimate $\hat{\delta}$ of x under the linear loss function

$$\ell(x,\delta;\varpi) = (1-\varpi)(\delta-x)1_{x\leq\delta}(\delta) + \varpi(x-\delta)1_{x>\delta}(\delta),$$

where $\varpi \in [0,1]$, is the ϖ -th quantile of distribution Q, let's denote it as x_{ϖ} .

1. Derive the (1-a)-credible interval $C_a = [L, U]$ for x as a Bayesian rule C_a under the loss function

$$\ell(x, C_a; \varpi_L, \varpi_U) = \ell(x, L; \varpi_L) + \ell(x, U; \varpi_U)$$
(2)

by computing L and U.

- 2. Your client is worried the same both for under-estimation and over-estimation; derive a suitable (1 a)credible interval $C_a = [L, U]$ based on (2) by computing L, and U.
- 3. Your client is worried only for over-estimation; derive a suitable (1-a)-credible interval $C_a = [L, U]$ based on (2) by computing L and U.

Solution. It is given that

$$0 = \frac{\mathrm{d}}{\mathrm{d}\delta} \mathrm{E}_{Q} \left(\ell(x, \delta; \varpi) | y \right) \Big|_{\delta = \hat{\delta}} = \frac{\mathrm{d}}{\mathrm{d}\delta} \int \ell(x, \delta; \varpi) \mathrm{d}Q(x | y) \Big|_{\delta = \hat{\delta}} \implies \hat{\delta} = x_{\varpi}$$
$$= (1 - \varpi) \Pr_{Q} \left(\{ x \leq \hat{\delta} \} | y \right) - \varpi \Pr_{Q} \left(\{ x \leq \hat{\delta} \}^{\complement} | y \right) \implies \hat{\delta} = x_{\varpi}$$

1. The decision space is $\mathcal{D}=\{C_a=[L,U]: \Pr_Q(x\in C_a|y)=1-a\}$. Therefore, to find the Bayes rule (or Bayes estimate) of $C_a=[L,U]$ I need to minimize the expected posterior loss $\operatorname{E}_Q(\ell(x,C_a;\varpi_L,\varpi_U)|y)$ with respect to C_a or equivalently L,U, so

$$0 = \frac{\mathrm{d}}{\mathrm{d}L} \mathrm{E}_{Q} \left(\ell(x, C_{a}; \varpi_{L}, \varpi_{U}) | y \right) \Big|_{C_{a} = [\hat{L}, \hat{U}]} = \mathrm{E}_{Q} \left(\ell(x, L; \varpi_{L}) | y \right) \Big|_{L = \hat{L}} \implies \hat{L} = x_{\varpi_{L}}$$

$$0 = \frac{\mathrm{d}}{\mathrm{d}U} \mathrm{E}_{Q} \left(\ell(x, C_{a}; \varpi_{L}, \varpi_{U}) | y \right) \Big|_{C_{a} = [\hat{L}, \hat{U}]} = \mathrm{E}_{Q} \left(\ell(x, U; \varpi_{U}) | y \right) \Big|_{U = \hat{U}} \implies \hat{U} = x_{\varpi_{U}}$$

So $x \in [x_{\varpi_L}, x_{\varpi_U}]$ where $\varpi_U + \varpi_L = 1 - a$. It is the minimum because

$$\left.\frac{\mathrm{d}^2}{\mathrm{d}U^2}\mathrm{E}_Q\left(\ell(x,C_a;\varpi_L,\varpi_U)|y\right)\right|_{C_a=[\hat{L},\hat{U}]}=q(\hat{U}|y)>0$$

$$\frac{\mathrm{d}^2}{\mathrm{d}L^2} \mathrm{E}_Q \left(\ell(x, C_a; \varpi_L, \varpi_U) | y \right) \bigg|_{C_a = [\hat{L}, \hat{U}]} = q(\hat{L}|y) > 0$$

$$\left.\frac{\mathrm{d}}{\mathrm{d}U}\frac{\mathrm{d}}{\mathrm{d}L}\mathrm{E}_{Q}\left(\ell(x,C_{a};\varpi_{L},\varpi_{U})|y\right)\right|_{C_{a}=[\hat{L},\hat{U}]}=0$$

and hence the determinant of the Hessian in positive.

- 2. Then I can use the equi-tail interval: $x \in [x_{a/2}, x_{1-a/2}]$ with $\varpi_L = a/2$ and $\varpi_U = 1 a/2$
- 3. Then I can use the lower-tail interval: $x \in (-\infty, x_{1-a}]$ with $\varpi_L = 0$ and $\varpi_U = 1 a$.