

Targeted Likelihood-Free Inference of Dark Matter Substructure in Strongly-Lensed Galaxies

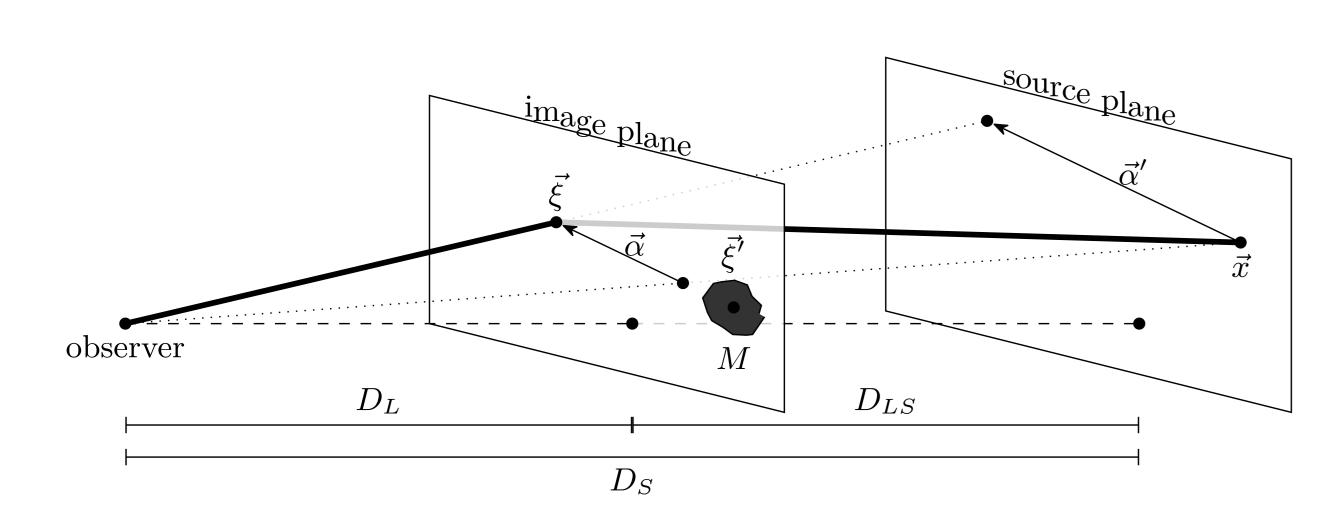


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Lensing and dark matter substructure

Strong gravitational lensing uniquely probes dark matter subhalos



Goal: compute posteriors for subhalo position and mass

Difficulties: complex correlations between image pixels; marginalization over many model parameters & subhalos

Methodology:

- 1. Fit *approximate posterior* for source and lens model parameters to an observation. Posterior acts as a *targeted simulator* to producing data similar to the observation.
- 2. Train *likelihood-free inference* network to compute substructure posteriors, marginalizing out model parameters

A new model for gravitational lenses

Standard GP $\mathbf{f} \sim N(0, \mathbf{K})$ $\mathbf{K} = \boldsymbol{\alpha}^2 \mathbf{T} \mathbf{T}^{\top}$ $\mathbf{f} = T(\mathbf{p}, \boldsymbol{\sigma}) \mathbf{y}$ $\mathbf{x} \sim N(\mathbf{f}, \sigma_n^2)$ $\mathbf{x} \sim N(\mathbf{f}, \sigma_n^2)$

 ${f f}$: true fluxes in each pixel

x: observation

 σ_n : observation noise

y: source parameters (1/pixel)

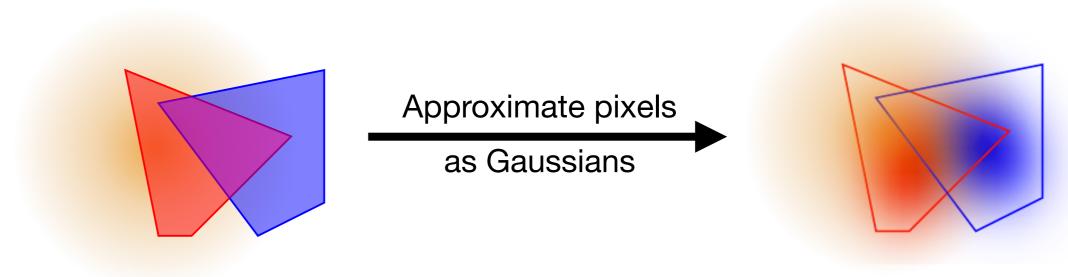
lpha : variance hyperparameter

 σ : kernel size hyperparameter

p: pixel coordinates

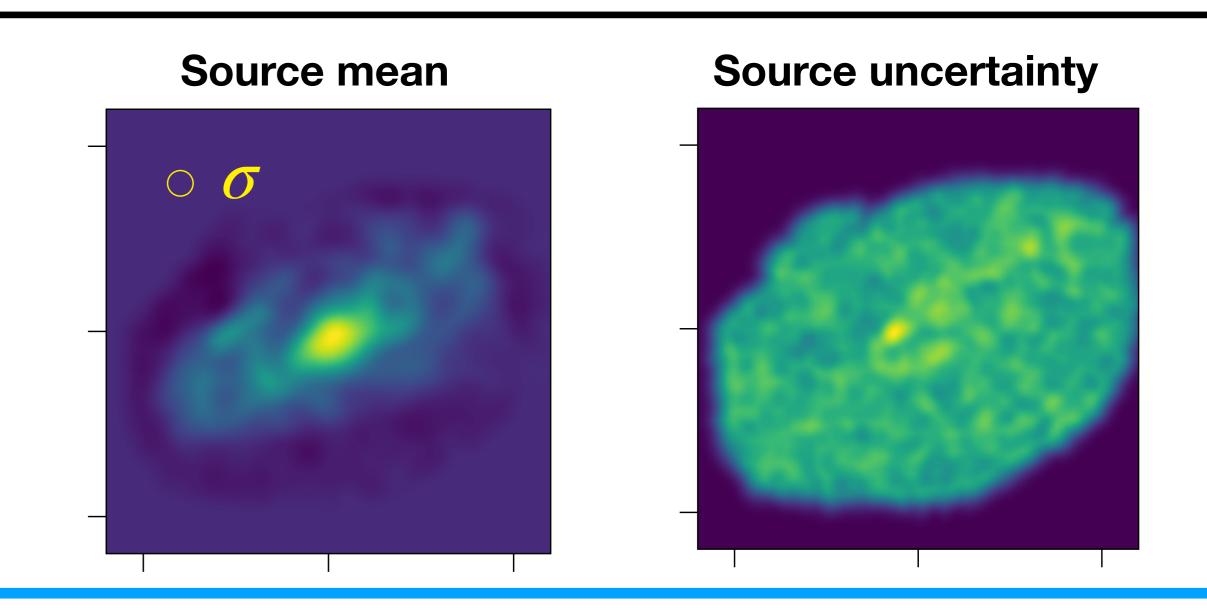
Covariance \mathbf{K} induced by intrinsic source variations & pixel overlaps in source plane:

$$\mathbf{K}_{ij} = \left[\int d\mathbf{p}_1 d\mathbf{p}_2 \, g_i(\mathbf{p}_1) \, k(\mathbf{p}_1, \mathbf{p}_2) \, g_j(\mathbf{p}_2) \right]$$



Can approximate ${f T}$ using fact that matrix multiplication ~ spatial convolution

- Instead of infeasible GP matrix inversion, fit **variational posterior** for lens & source parameters to observation, *ignoring substructure*
- ELBO maximization via gradient descent with reparametrization trick (using pyro)
- → Requires lens model to be automatically-differentiable (implemented in pytorch)
- Simultaneously optimize α hyperparameter with σ fixed by hand
- We use a diagonal-normal posterior for the ~10⁵ source parameters & multivariate normal for lens parameters



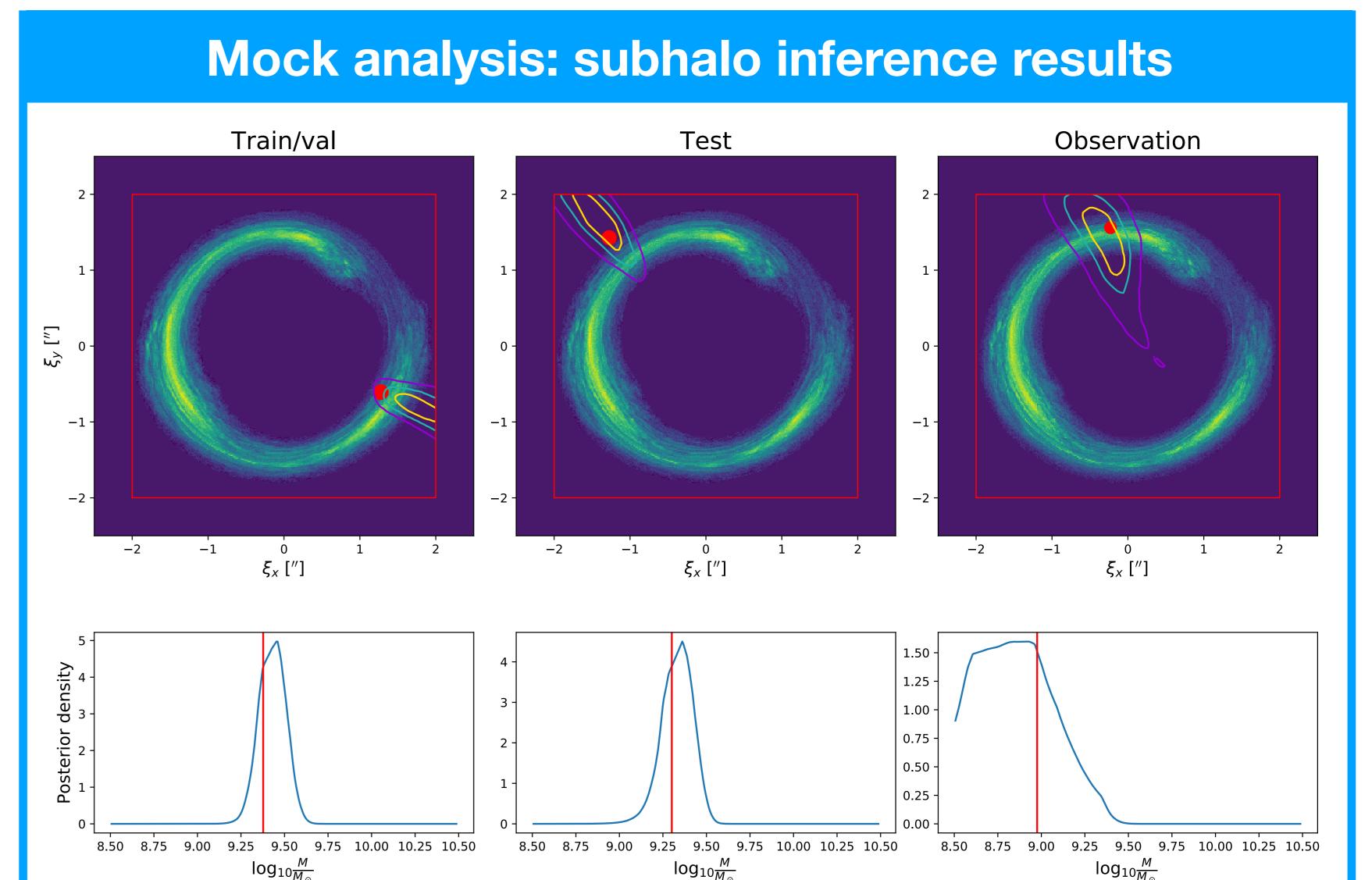
Substructure inference

- Aim: posteriors for substructure parameters \mathbf{z}_d marginalized over source and lens parameters
- Neural likelihood-to-evidence ratio estimation: estimate $p(\mathbf{z}_d | \mathbf{x})/p(\mathbf{z}_d)$
- Train classifier $d(\mathbf{x}, \mathbf{z}_d)$ to distinguish two classes:

1. \mathbf{x} , $\mathbf{z}_d \sim p(\mathbf{x}, \mathbf{z}_d)$ data & parameters sampled from joint distribution

2. \mathbf{x} , $\mathbf{z}_d \sim p(\mathbf{x}) \, p(\mathbf{z}_d)$ sampled independently

- → Can recover ratio through $d(\mathbf{x}, \mathbf{z}_d)/(1 d(\mathbf{x}, \mathbf{z}_d))$
- Training samples: draw from approximate posterior
- Implemented using swyft (see paper & poster at this workshop!)
- Mock data analysis of high-resolution image: only 10,000 training samples, runs in a few hours on single GPU. Promising results!
- Next up: apply to real Hubble Space Telescope data



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