
Large Language Model-based Bayesian Optimization for Tokamak Stabilization

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Abstract

1 Nuclear fusion holds the potential to solve many of today’s most pressing problems,
2 from climate change to mass food and water production. However, modeling
3 and operating tokamaks remain highly challenging due to distribution shifts that
4 take place, e.g., due to hardware changes between experiments, actuator failures,
5 and impurities in the plasma. In this work, we focus particularly on the task
6 of predicting and mitigating tearing instabilities, which can cause the plasma
7 to disrupt and potentially damage the tokamak. To do so, we propose a large
8 language model-informed Bayesian optimization scheme, which aims to explore
9 and find highly stable electron cyclotron heating configurations efficiently. Our
10 choice of algorithm allows us to account for uncertainty in the model, which
11 in turn helps it adapt to changes that arise due to distribution shifts. The large
12 language model, by contrast, allows us to leverage high-dimensional prior data and
13 to process experiment logs written by scientists and operators, which would usually
14 be impossible with conventional Bayesian optimization tools. In preliminary offline
15 experiments, conducted using a historical dataset from the DIII-D tokamak, our
16 method shows promising performance compared to other baselines.

17 1 Introduction

18 Nuclear fusion holds the promise of producing high quantities of energy with minimal to no environmental impact. In fusion, energy is released through a sustained, controlled reaction in which light atoms are combined to form heavier atoms. Among the various technologies used to achieve controlled fusion, the most promising are tokamaks [Kikuchi, 2010], which utilize magnetic fields to confine high-temperature and high-pressure plasma, thereby creating conditions for the fusion reaction to occur. However, sustained tokamak control at high pressures is very challenging due to the occurrence of instabilities in the plasma. These instabilities can easily disrupt the plasma, which in turn ends the fusion process and can even severely damage the device. Electron cyclotron heating (ECH) has shown promise to mitigate instabilities [Kolemen et al., 2014]. However, understanding how to utilize ECH effectively remains unclear. This challenge is further compounded by fluctuations in the tokamak hardware, such as wall changes, sensor and actuator failures, and impurities resulting from prior experiments, which make it challenging to plan experiments solely based on prior data.
30 To address the aforementioned challenges, we present an LLM-based Bayesian optimization approach for tokamak control. Our approach leverages observations collected during past experiments to explore and find heating profiles that maximize the time-to-instability. Moreover, unlike classical Bayesian optimization, our LLM-based approach enables the processing of logs written by scientists between experiments. We present preliminary results obtained from a simulated Bayesian optimization setup informed by past experiments and logs.

36 **2 Related Work**

37 **2.1 Tokamak control and tearing instabilities**

38 A key challenge in tokamaks is controlling neo-
 39 classical tearing modes (also referred to as tearing
 40 instabilities), which are magnetic islands that form within the plasma. These instabilities
 41 degrade plasma confinement [Sauter et al.,
 42 1997] and can grow unless suppressed, leading
 43 to plasma disruptions [Westerhof, 1990] and po-
 44 tentially damaging the reactor wall. Plasma dis-
 45 ruptions are one of the major concerns for stable
 46 operations in future large tokamaks, e.g., ITER
 47 [Lehnen et al., 2015]

49 To counteract tearing instabilities, Electron Cy-
 50 clotron Heating (ECH) is often used to create
 51 localized current drive and heating at the loca-
 52 tion of instabilities. To create these, gyrotrons
 53 are aimed at specified locations in the plasma
 54 [Kolemen et al., 2014] [Nelson et al., 2020].
 55 Gyrotrons can also be used pre-emptively to sta-
 56 bilize the plasma [Bardóczki et al., 2023]. Since
 57 tokamak devices regularly undergo system up-
 58 grades, past data is potentially unreliable, thus,
 59 Bayesian optimization becomes a strong candi-
 60 date for pre-emptive ECH suppression, where
 61 the tokamak is treated as a black box [Sonker
 62 et al., 2025].

63 In this work, we adopt a similar approach to that in [Sonker et al., 2025] to mitigate tearing instabilities
 64 in plasma experiments by selecting the optimal shape of the feedforward ECH heating profile, which
 65 we approximate using a Gaussian curve. An example of the angle of the gyrotron and the resulting
 66 ECH deposition profile is shown in Fig. 1. In this paper, we focus on $m/n=2/1$ tearing instabilities,
 67 which are very common and highly prone to cause disruptions. We also consider experiments
 68 exclusively in a high- q_{min} plasma scenario, a type of high-pressure scenario that supports long-pulse
 69 steady-state plasma operation.

70 **2.2 LLM-Augmented Bayesian Optimization**

71 Classical Bayesian optimization methods have been deployed for adaptive experimental design
 72 across a range of settings such as adaptive clinical trials [Berry, 2006], ecological monitoring
 73 [Diggle and Lophaven, 2006], and recently, for ECH profile optimization in tokamaks [Sonker et al.,
 74 2025]. Despite these successes, these BO methods often fail to leverage the rich task-specific prior
 75 information available to us. This has motivated a recent surge in interest using language models as a
 76 tool for more informed Bayesian optimization [Liu et al., 2024, Chang et al., 2025]. Our methodology
 77 primarily follows previous work on directly prompting the language models with prior experiment
 78 history and the observed values of the variable of interest, and prompting it to generate the next
 79 experiment [Zhang et al., 2023]. Our approach contrasts with these in that we incorporate detailed
 80 experimental logs into the experimental design observations.

81 **3 Problem Setup**

82 **3.1 Contextual Bayesian Optimization (CBO)**

83 We now formulate our problem in a contextual Bayesian optimization setup. Our goal is to find
 84 an ECH profile (a_{ech}) that maximizes the time-to-instability given the context. The ECH profile is
 85 approximated by a Gaussian, parameterized by a 3-dimensional vector. In this work, we use the target
 86 normalized plasma pressure β_N , which strongly correlates with plasma stability and is frequently

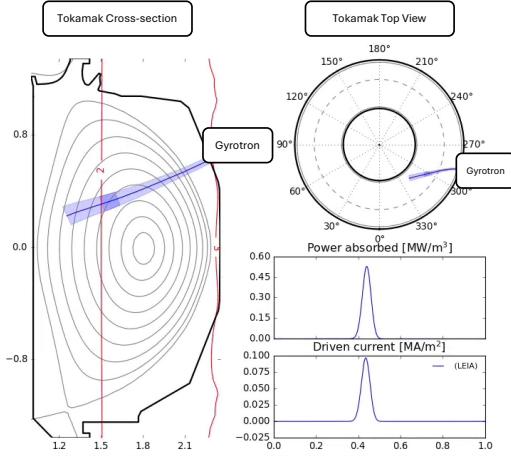


Figure 1: Gyrotron action on the Plasma inside the Tokamak. The bottom 2 curves indicate the heating power absorbed (ECH profile) and current driven in the plasma (ECCD profile) from the core to outer region of the plasma.

87 adjusted between experiments by physicists [Sonker et al., 2025]. Our goal is to perform well on any
88 given target β_N .

89 The contextual decision problem is then as follows: every round t , a context $\beta_{N,t}$ is determined
90 prior to action selection. The agent then chooses a heating profile configuration x_t and measures the
91 (noisy) time-to-instability

$$y_t = f(x_t, \beta_{N,t}) + \varepsilon_t,$$

92 where f is the unknown objective, i.e., the expected time-to-instability, and ε_t is the observation
93 noise. The goal is to learn a policy π that maps contexts to actions with high utility, i.e., $\pi(\beta_N) \approx$
94 $\arg \max_x f(x, \beta_N)$. This is achieved by choosing actions that trade off exploration and exploitation
95 over multiple rounds.

96 3.2 Auxiliary Feedback from experiments

97 In addition to the observations y_t , we also include experiment logs written down by scientists after
98 the experiment is performed. The information presented here encompasses a wide range of specific
99 details about the experiment and tokamak, including neutral beam failures, pellet injection, and
100 gyrotron lag. Importantly, these logs can contain information that is impossible to express in the
101 low-dimensional search space of traditional BO tools. Logs written during and after experiments are
102 often written in shorthand; hence, we first pass these logs through a Llama-3-8b model to eliminate
103 short forms and turn them into well-formed, complete sentences. Some examples are shown in table
104 1. Note that despite cleaning, these logs contain a lot of additional information and are very noisy by
105 nature.

Experiment Logs

- 1 The experiment began 330 seconds before the start time of 2.5 seconds with a planned current of 0.75 megaamperes, a magnetic field strength of 1.7 teslas, and a neutral beam injection power of 1 MW. The experimental plan for shot 2019-22-03 was step 6. The plasma's internal magnetic field was set to 10/40 for the entire shot duration. The gyrotrons were successfully activated, with actual delays matching the requested delays of 4500 microseconds for Luke and Leia, and 4728 microseconds for Tinman. The plasma was stable, with the current reaching the minimum value, IpMin, indicating a successful plasma formation.
- 2 The experiment logs indicate that a plasma shot was conducted at the DIII-D National Fusion Facility, utilizing three gyrotrons, Leia, R2D2, and Luke, to control the plasma. The gyrotrons were set to operate with a delay of 1500 microseconds, a requested power of 5000 megawatts, and an actual power of approximately 3599-3612 megawatts. The plasma was successfully initiated, and all beams were functioning as expected until a mode began to affect the beta value. The plasma shot was deemed successful, with the result being classified as "OK, good shot."
- 3 The last shot of the hybrid part of today's experiment was completed by increasing the plasma density to the same level as shot 155541 and maximizing the co-beam power. This shot was very successful until 4.5 seconds, when a 2/1 mode began to grow, although the plasma's betaN remained above 3.2 until the beam was turned off at 4.9 seconds. Between 3.0 and 4.5 seconds, the average plasma properties were betaN = 3.64, H89P = 2.4, and a surface loop voltage of -0.003 volts. Today's experiment consisted of 11 plasma shots, including 1 reference shot, 6 clean-up shots at two different dRsep values, and 4 successful shots with a betaN of over 3.2, three of which had a negative loop voltage at 1.0 MA.

Table 1: Examples of experiment logs which are usually written post experiment. These logs are used as auxiliary feedback in our LLM-powered Bayesian optimization method.

106 4 Experiment Setup

107 In this section, we describe our experiments.

108 We employ an end-to-end LLM to perform Bayesian optimization, with the difference that we include
109 written logs in the observations. We utilize historical data from 281 past experiments carried out

110 at the DIII-D tokamak facility between 2012 to 2023. These experiments correspond to high q_{min}
 111 plasma scenario with β_N values ranging from 2.6 to 3.9.

112 This data is used to simulate live experiments. At each step we sample a target plasma pressure β_N^t
 113 from the range of historical values. We then select a subset of historical experiments whose β_N lies
 114 between $[\beta_N^t - \epsilon, \beta_N^t + \epsilon]$, where $\epsilon = 0.05$. Now, the Bayesian optimization task corresponds to
 115 selecting the ECH value corresponding to any experiment in this subset. After selecting the ECH
 116 value, we treat the corresponding experiment and its time to tearing mode as an evaluated observation,
 117 which is then used to perform the posterior update. To evaluate each method, we employ contextual
 118 cumulative regret

$$\mathcal{R}_T = \sum_{t=1}^T [f^{\max} - f(x_t, \beta_{N,t})],$$

119 where f^{\max} denotes the maximal time-to-instability and T denotes the current round.

120 **Methods Compared** We compare the following approaches -

- 121 • **GP-EI** : Traditional Bayesian optimization with a Gaussian Process surrogate model and
 122 Expected Improvement as the Acquisition Function
- 123 • **LLM-E2E** : LLM as an end-to-end Bayesian Optimizer. Here, we provide the history of
 124 past observations, the current context and subset of ECH values to select from.
- 125 • **LLM-E2E with Aux Feedback** : Similar to LLM-E2E, along with experiment logs as
 126 auxiliary feedback for each evaluation point.

127

128 The LLM used for experiments was Llama-3.3-
 129 70B instruction-tuned model [Grattafiori et al.,
 130 2024].

131 The results can be seen in fig. 2. GP-EI con-
 132 verges with the least cumulative regret. This is
 133 closely followed by LLM-E2E With Aux feed-
 134 back which shows that including this additional
 135 information leads to substantial improvement in
 136 regret. We notice that the LLM based method
 137 matches the GP performance initially, however
 138 later on diverges. We also see that LLM-E2E
 139 method (without Aux feedback) performs better
 140 than Random Search. We attribute the advan-
 141 tage of GP-EI after a long horizon to the exact
 142 Bayesian updates, which do not suffer from in-
 143 accuracies for long context windows as with the
 144 LLM, ultimately driving better convergence.

145 5 Conclusion

146 We have presented an LLM-based BO approach
 147 for tokamak plasma stabilization. Our method
 148 incorporates freeform text into the optimization
 149 loop, contrasting with vanilla Bayesian optimiza-
 150 tion methods. Preliminary results using a simulated setup show promise compared to an LLM-based
 151 approach without text feedback. However, vanilla Bayesian optimization outperforms our strategy in
 152 the long run, indicating that improvements can be achieved. This motivates our future work, where
 153 we will combine both methods in a way that simultaneously leverages their advantages.

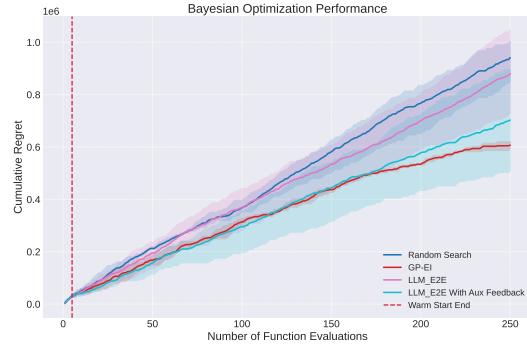


Figure 2: Cumulative Regret across different methods. GP-EI corresponds to Vanilla Contextual BO with GP and Expected improvement as Acquisition Function. LLM-E2E corresponds to BO using LLM as next query selector. LLM-E2E with Aux Feedback incorporates additional text feedback from experiments. All methods were run for 3 random seeds.

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