

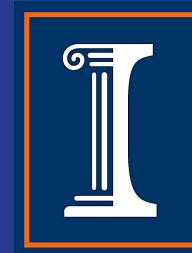
*Link to these slides:* <http://tiny.cc/nips>

[arXiv:1711.03121](https://arxiv.org/abs/1711.03121)

# Deep Learning for Gravitational Wave Analysis

## Results with LIGO Data

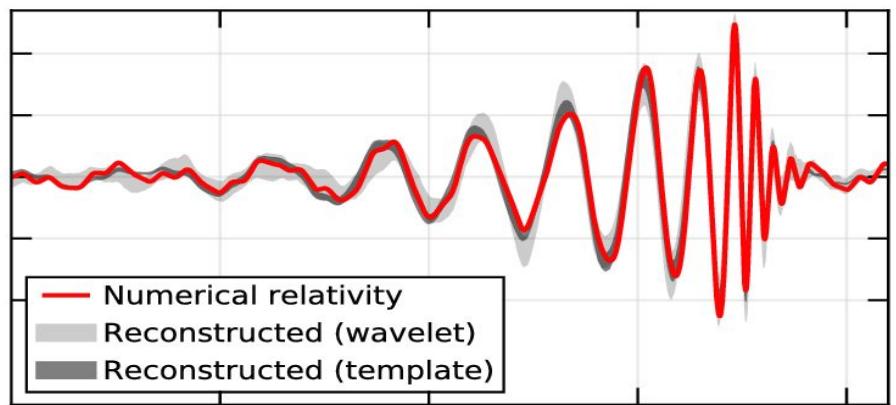
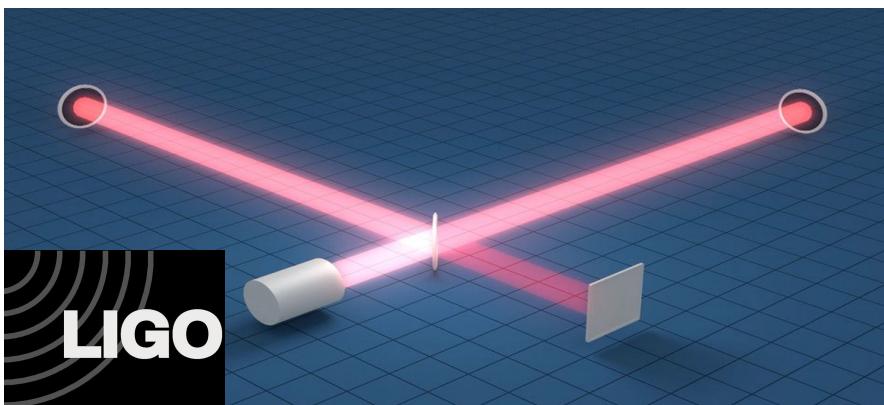
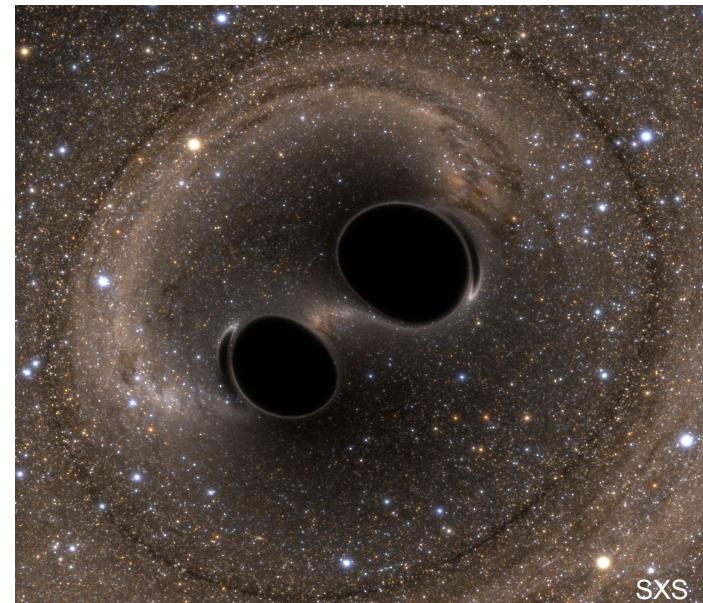
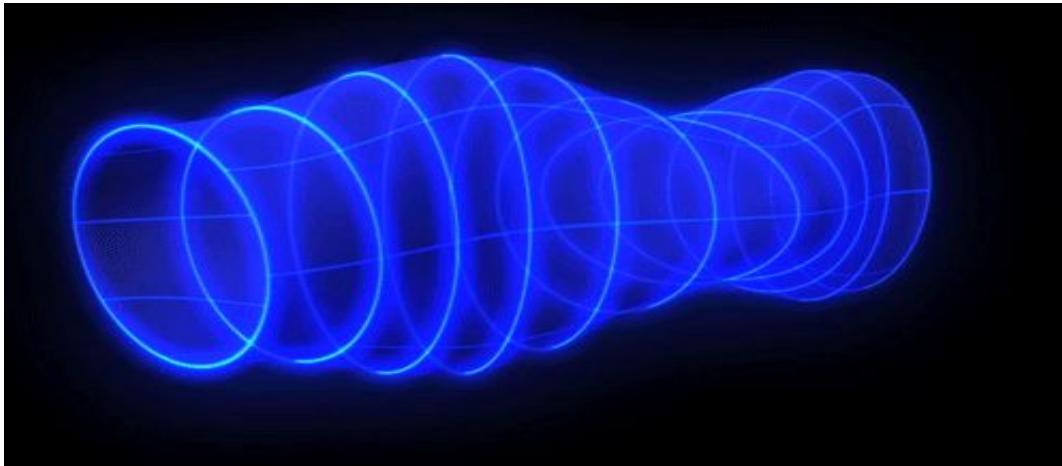
Daniel George & E. A. Huerta



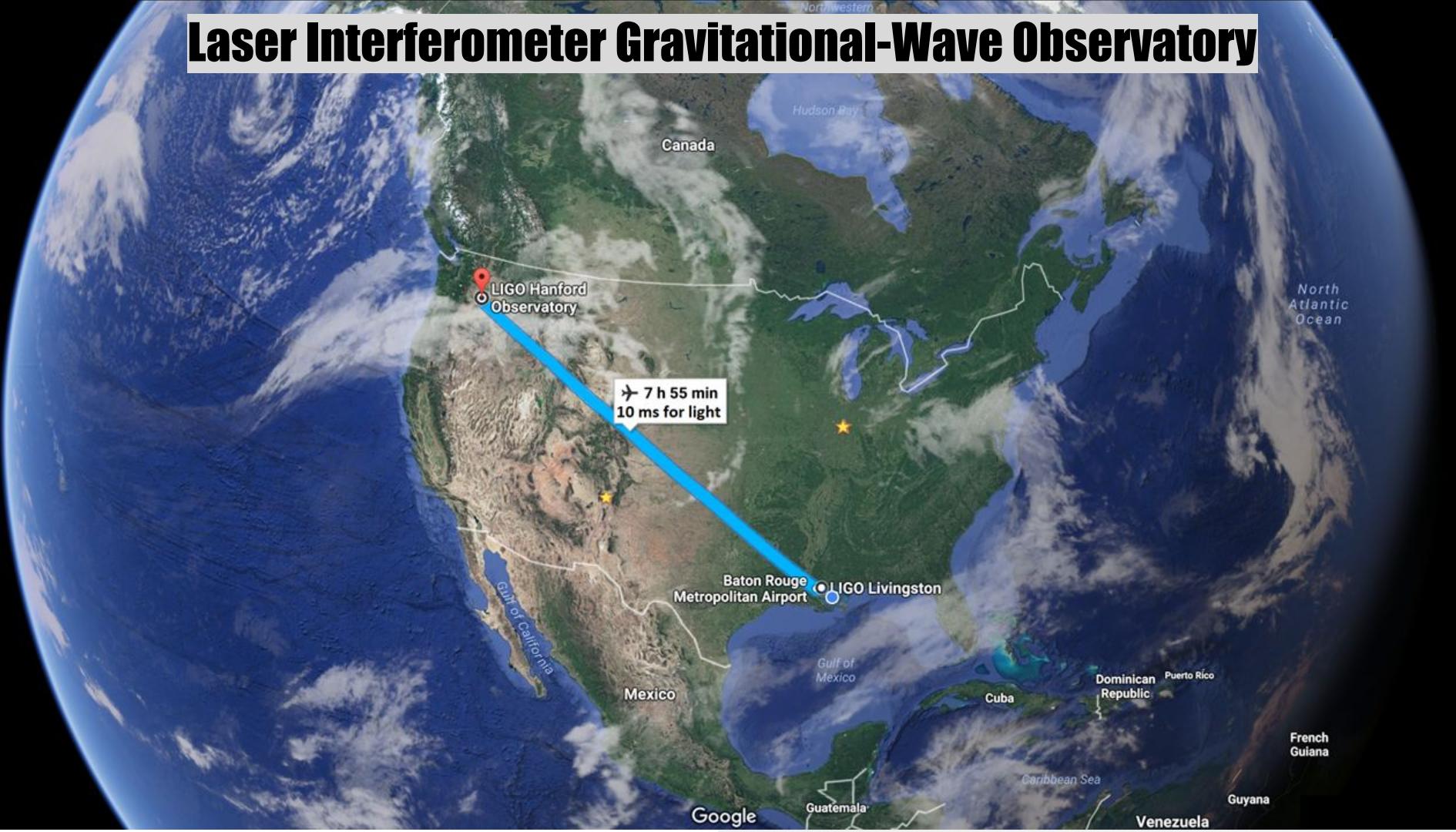
NCSA Gravity Group - <http://gravity.ncsa.illinois.edu/>  
Department of Astronomy  
University of Illinois at Urbana-Champaign

Dec 8, 2017

# Gravitational Waves



# Laser Interferometer Gravitational-Wave Observatory



**Operational**  
**Under Construction**  
**Planned**

# Gravitational Wave Observatories

LIGO Hanford

LIGO Livingston

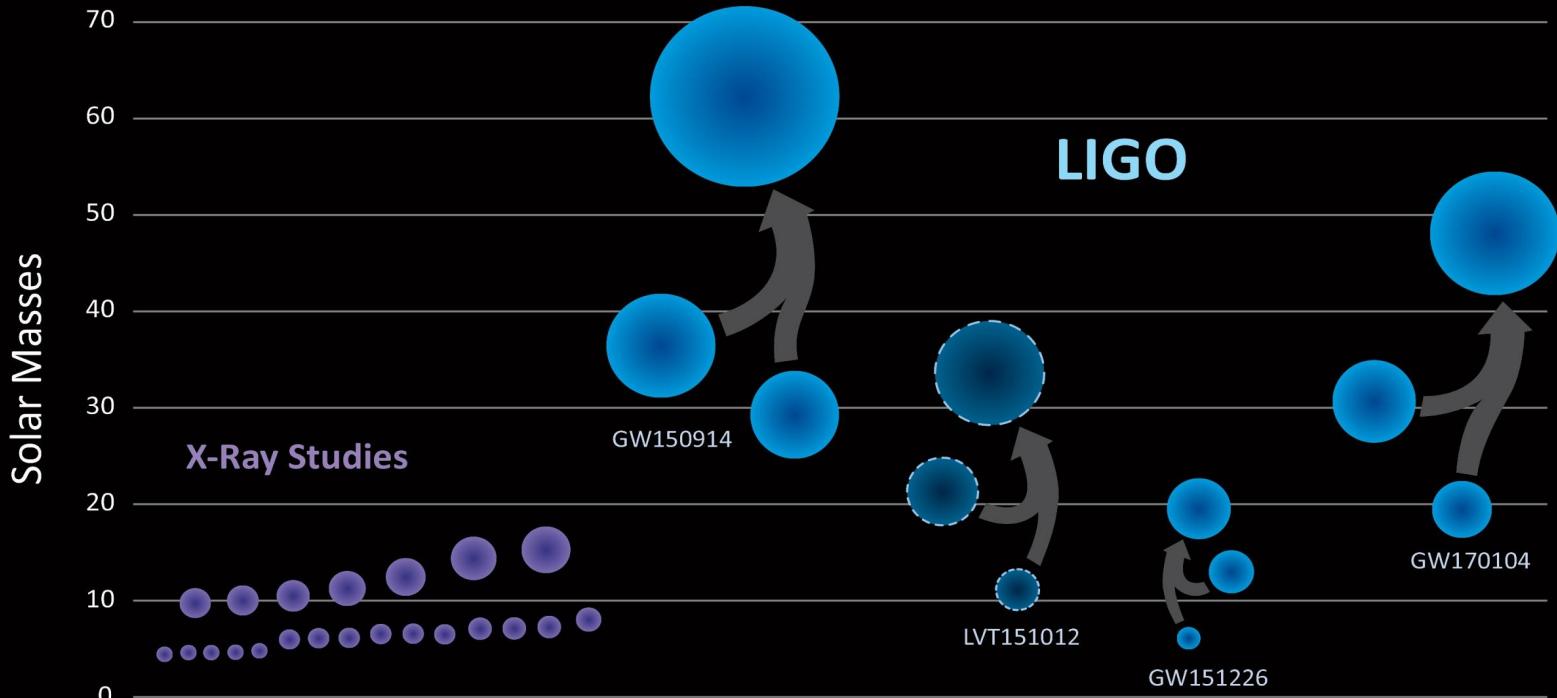
GEO600

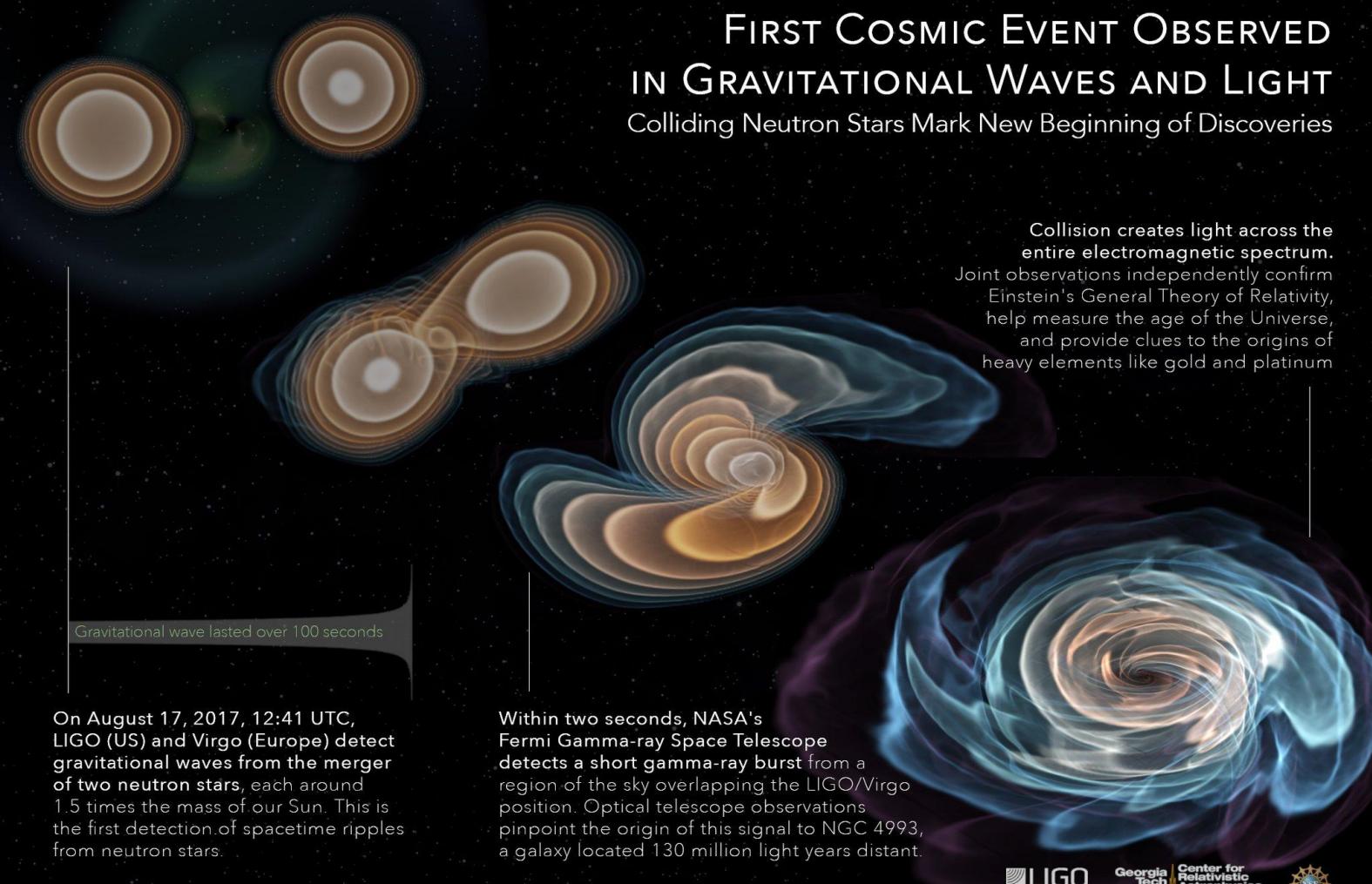
Virgo

KAGRA

LIGO India

# Black Hole Detections





# FIRST COSMIC EVENT OBSERVED IN GRAVITATIONAL WAVES AND LIGHT

## Colliding Neutron Stars Mark New Beginning of Discoveries

Collision creates light across the entire electromagnetic spectrum. Joint observations independently confirm Einstein's General Theory of Relativity, help measure the age of the Universe, and provide clues to the origins of heavy elements like gold and platinum

Gravitational wave lasted over 100 seconds

On August 17, 2017, 12:41 UTC, LIGO (US) and Virgo (Europe) detect gravitational waves from the merger of two neutron stars, each around 1.5 times the mass of our Sun. This is the first detection of spacetime ripples from neutron stars.

Within two seconds, NASA's Fermi Gamma-ray Space Telescope detects a short gamma-ray burst from a region of the sky overlapping the LIGO/Virgo position. Optical telescope observations pinpoint the origin of this signal to NGC 4993, a galaxy located 130 million light years distant.



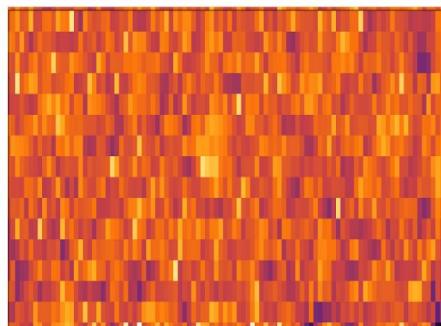
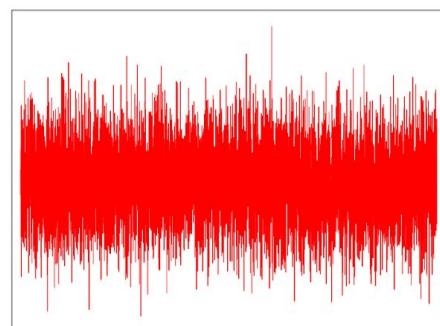
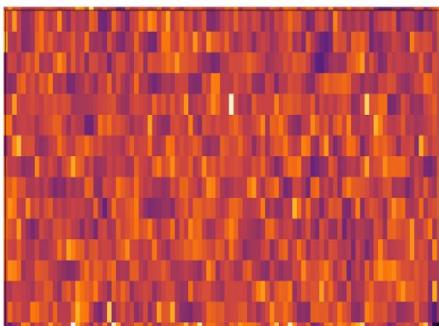
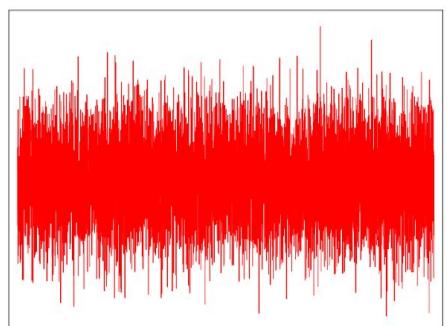
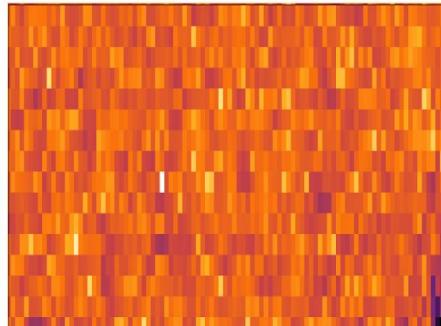
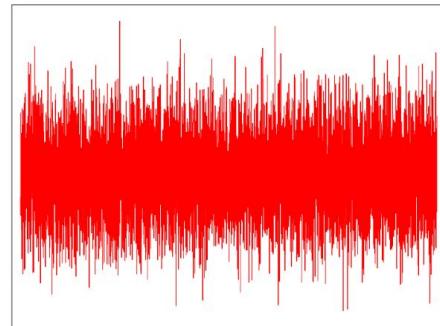
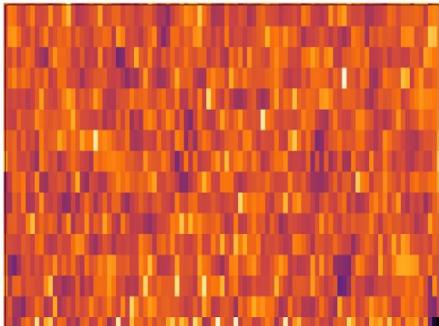
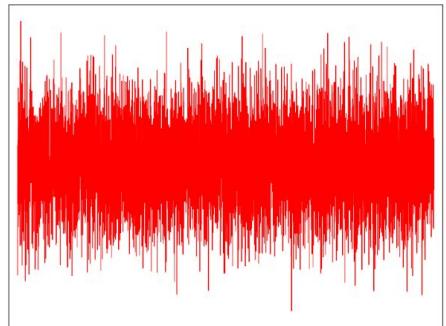


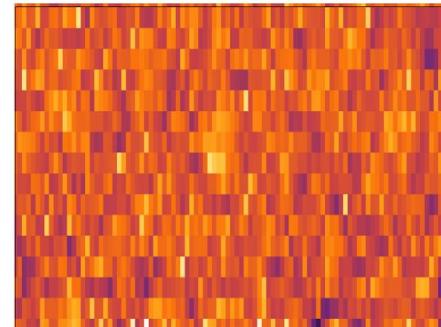
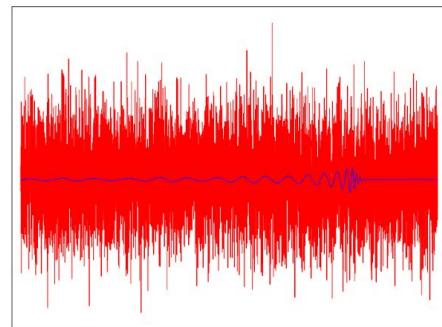
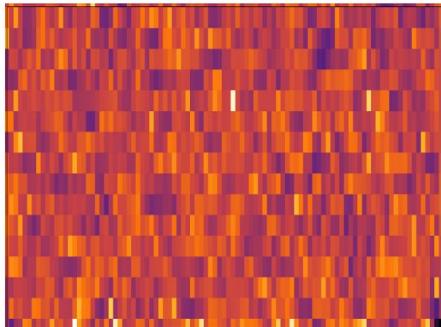
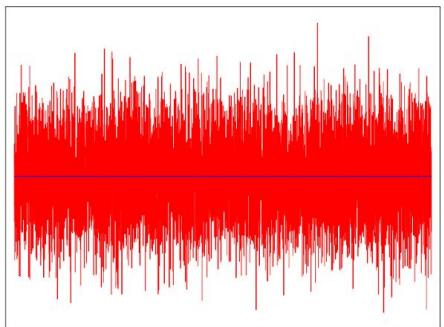
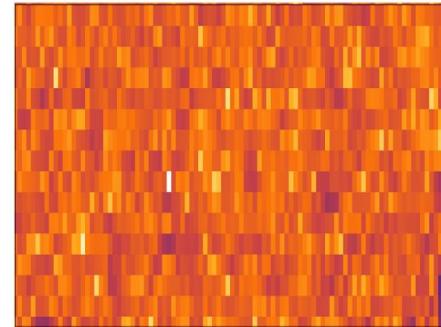
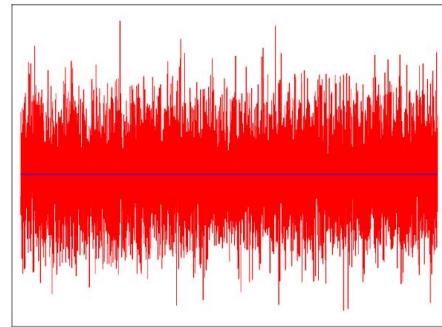
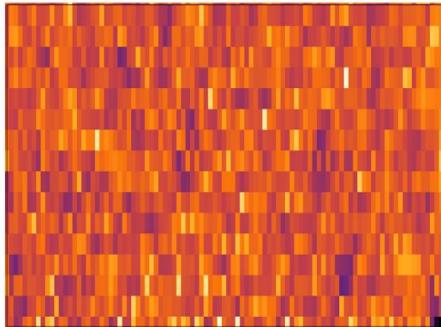
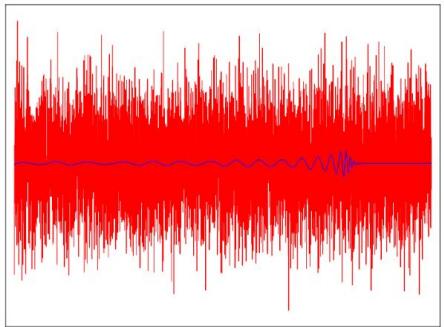
*The Royal Swedish Academy of Sciences has decided to award the*

# **2017 NOBEL PRIZE IN PHYSICS**



# Challenge

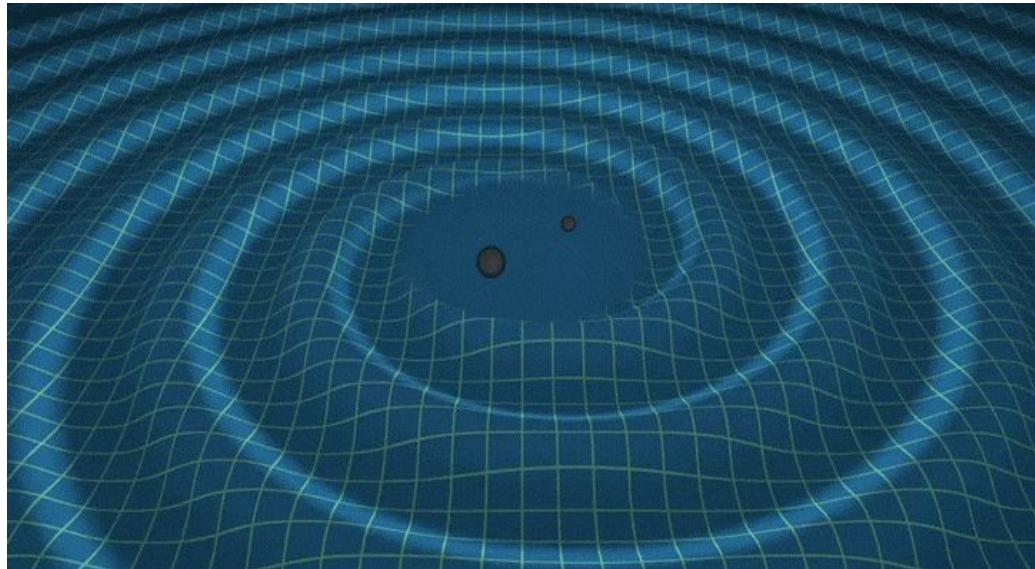




# Classification & Regression

# Numerical Relativity - Supercomputing

einstein  
toolkit



 NCSA



# Method?

## Matched-Filtering:

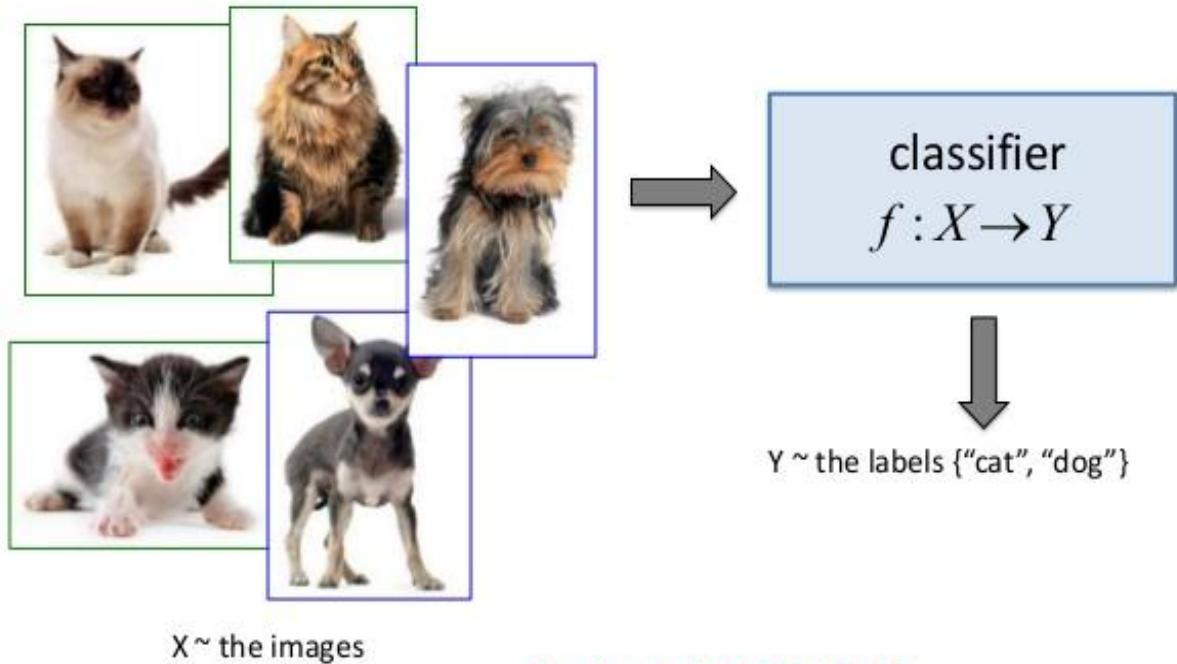
Compare an input image with millions of photos of cats and dogs and see which matches best.

Template matching is not scalable

## Solution:

Deep Learning!

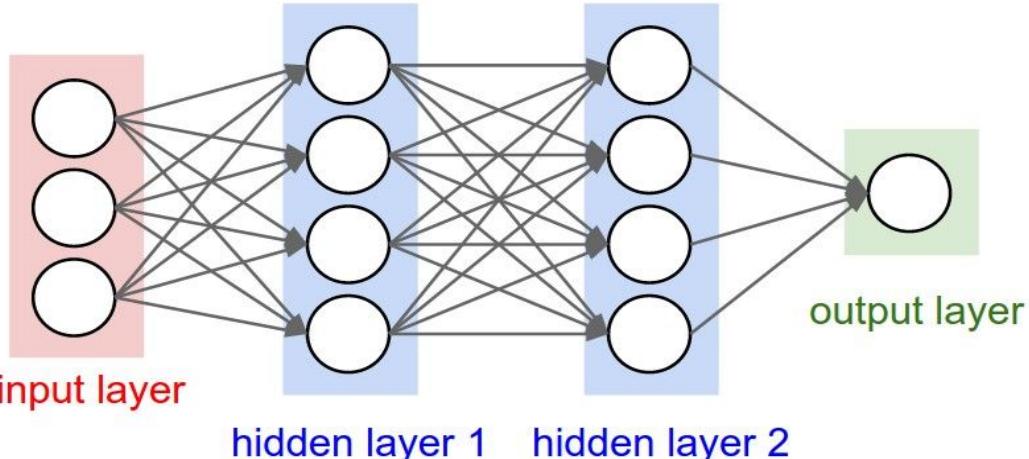
We want to build this....



# Deep Learning

## Overview

- Very long networks of artificial neurons (dozens of layers)
- State-of-the-art algorithms for face recognition, object identification, natural language understanding, speech recognition and synthesis, web search engines, self-driving cars, games (Go) etc.



- Does not require hand-crafted features to be extracted first
- Automatic end-to-end learning
- Deeper layers can learn highly abstract functions

# Signal Processing with Convolutional Networks

## Our method: Deep Filtering

CNNs for directly processing highly noisy time-series data for classification and regression.

### Advantages

- Can process raw/whitened data
- Automatically learns optimal strategies
- Train once. Constant-time for evaluation
- Optimized hardware (GPUs, FPGAs)
- Resilient to glitches, non-stationary noise
- Does not perform template matching
- Learns patterns connecting signals
- Interpolates to new templates
- Small and efficient (few MBs)

# Designing 1-D CNNs

- Explored only simple designs.
- Up to 4 dilated convolutional layers and 3 fully connected layers.

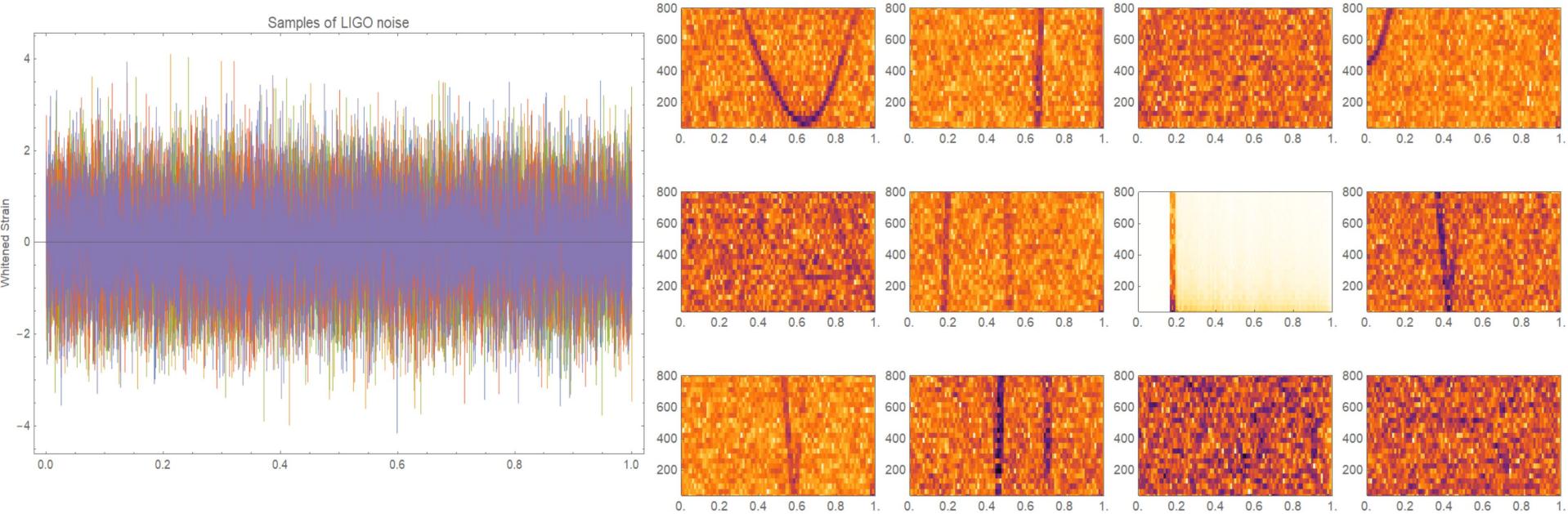
**2 nets:** Classifier for detection;

Predictor for estimating source parameters

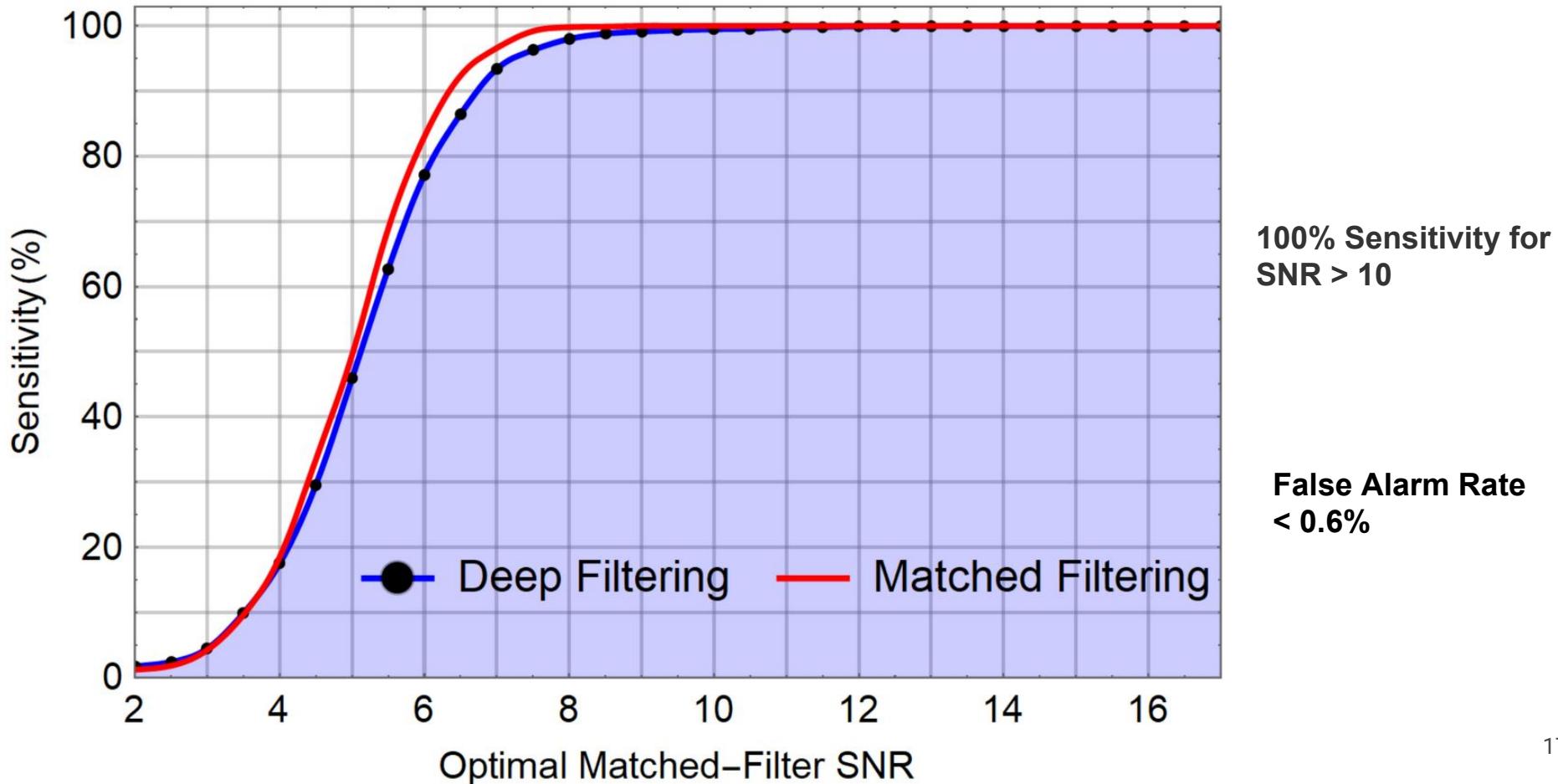
	Input (1s, 8192Hz)	vector (size: 8192)
1	Reshape Layer	tensor (size: $1 \times 1 \times 8192$ )
2	Convolution Layer	tensor (size: $16 \times 1 \times 8177$ )
3	Pooling Layer	tensor (size: $16 \times 1 \times 2045$ )
4	Ramp	tensor (size: $16 \times 1 \times 2045$ )
5	Convolution Layer	tensor (size: $32 \times 1 \times 2017$ )
6	Pooling Layer	tensor (size: $32 \times 1 \times 505$ )
7	Ramp	tensor (size: $32 \times 1 \times 505$ )
8	Convolution Layer	tensor (size: $64 \times 1 \times 477$ )
9	Pooling Layer	tensor (size: $64 \times 1 \times 120$ )
10	Ramp	tensor (size: $64 \times 1 \times 120$ )
11	Flatten Layer	vector (size: 7680)
12	Linear Layer	vector (size: 64)
13	Ramp	vector (size: 64)
14	Linear Layer	vector (size: 2)
15	Softmax Layer	vector (size: 2)
	Output	vector (size: 2)

# Using Real LIGO Data

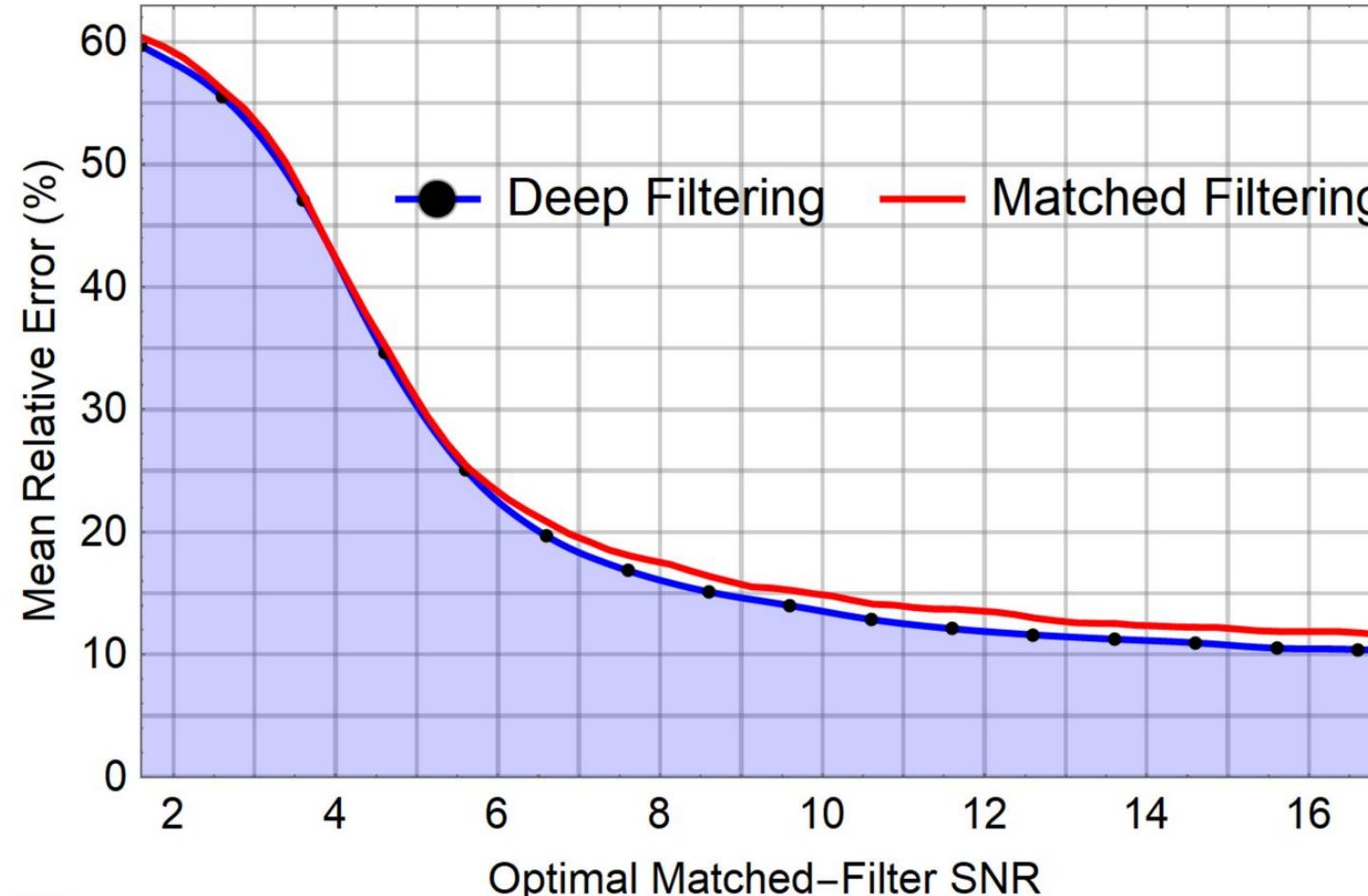
1. Added real noise from LVT151210 and GW151226 for training (4096s each).  
Open source, data taken from <https://losc.ligo.org/events/GW150914/>
2. Tested on real data from GW150914 (includes many glitches as shown below)
3. Same nets work on non-stationary colored noise with different PSD without re-training.



# Accuracy of Classifier (Detection)



# Relative Error in Predicting Masses

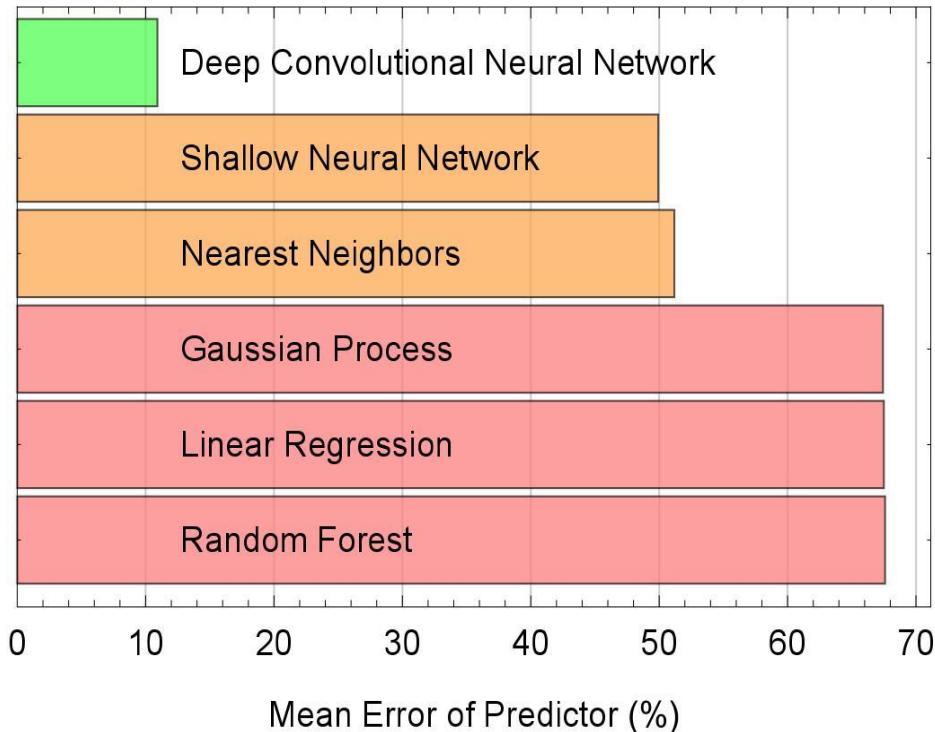
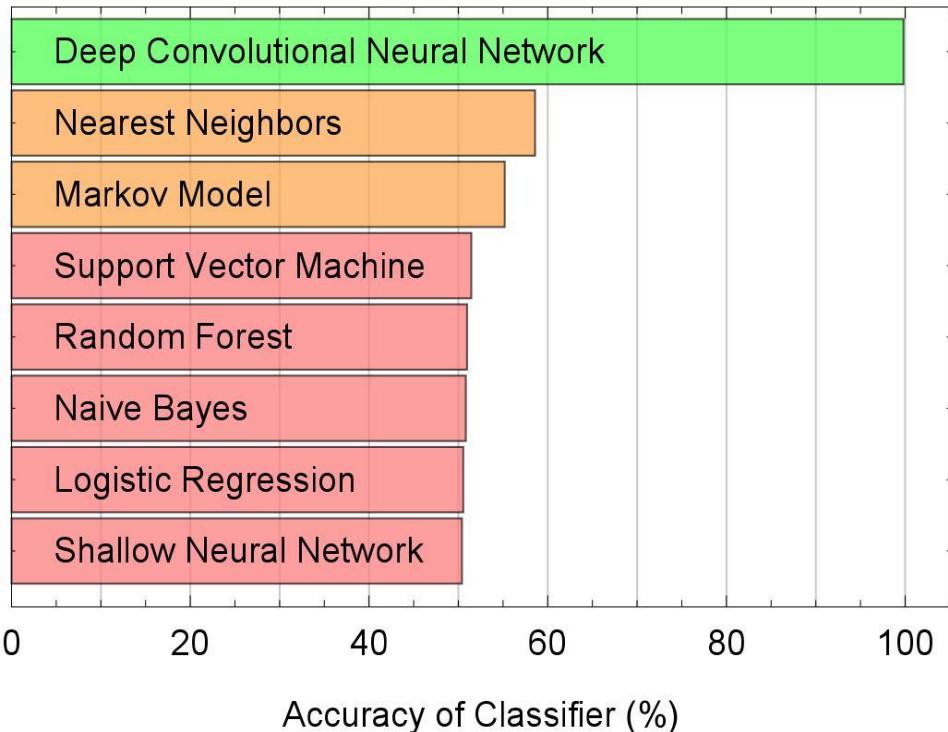


Deep Filtering error  
< 5% for SNR>50

Can interpolate  
between templates

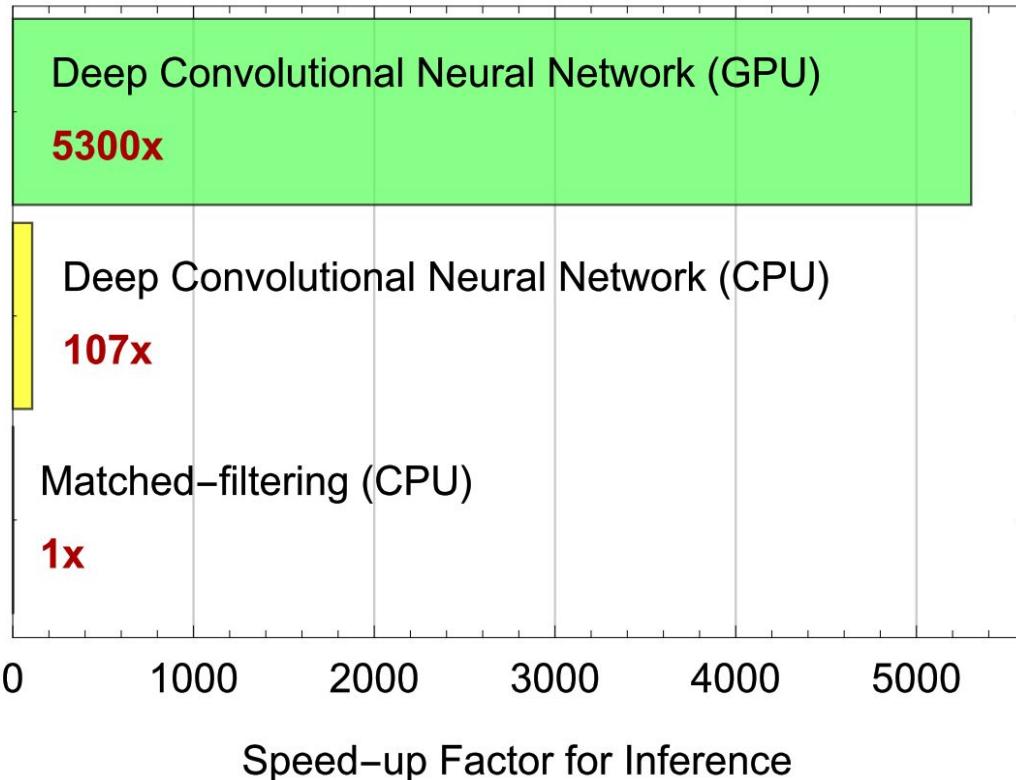
Matched-Filtering  
error with same  
template bank is  
always > 11%

# Detection and Parameter Estimation

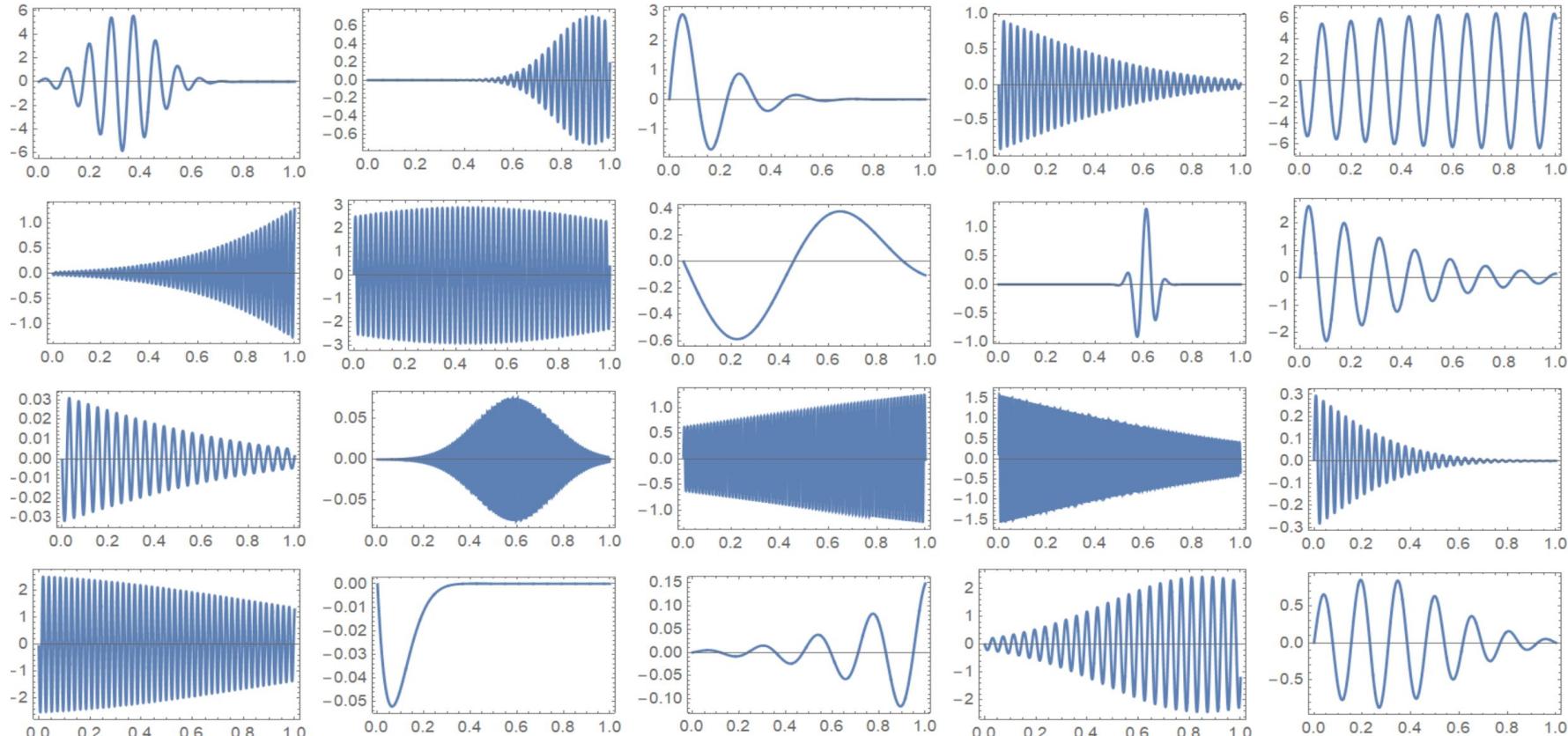


# Speed-Up

- Real-time analysis (milliseconds).
- Constant time regardless of number of templates, after training once.
- Thousands of inputs can be processed at once on a cheap GPU.
- Dedicated inference engines can offer additional speed-up.

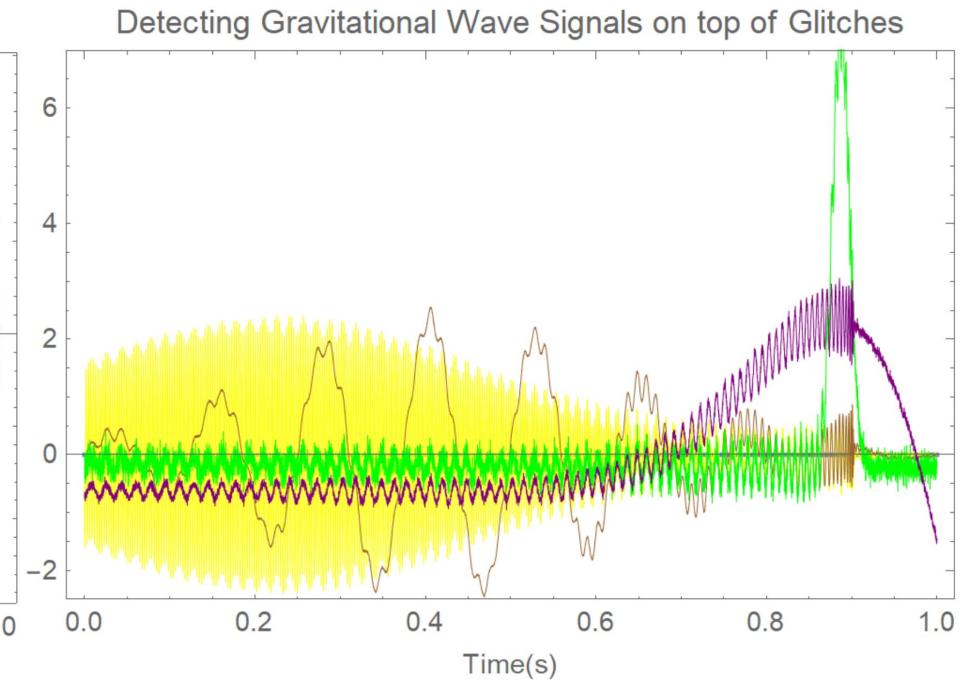
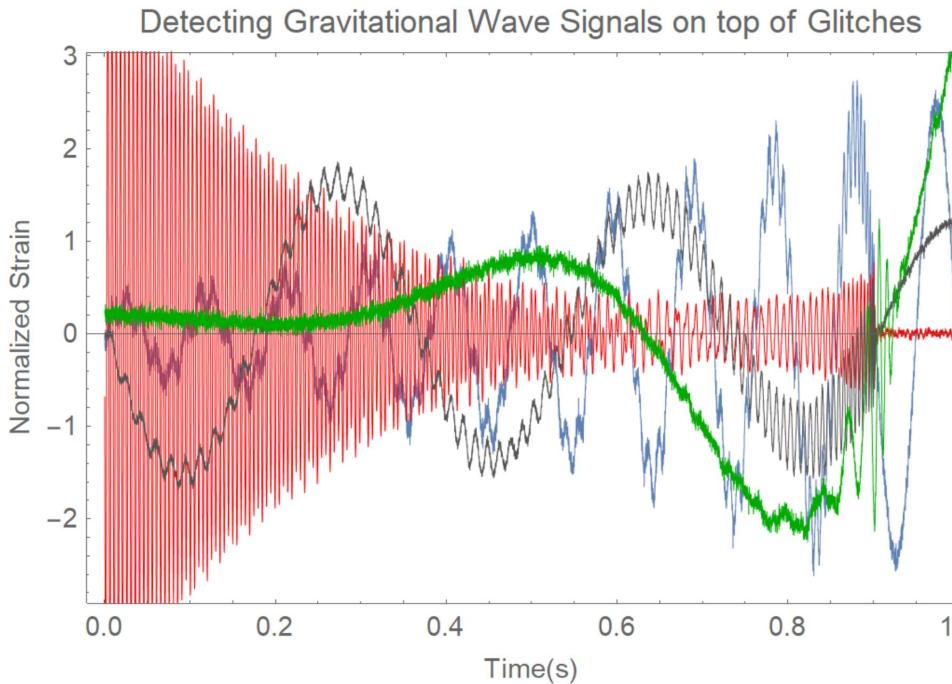


# Automatically resilient to Glitches



**False Alarm Rate with sine-gaussian glitch injections:** Matched-Filter = ~30%, Deep Filtering = <1%

# Even works for Events during Glitches!



**Successfully recovered ~80% of signals injected in real noise plus sine-gaussian glitches.**

**Mean relative error of parameter estimation during glitches <30% for SNR>10**

# Live Demo:

[www.tiny.cc/DLGW](http://www.tiny.cc/DLGW)

## Detecting GW150914

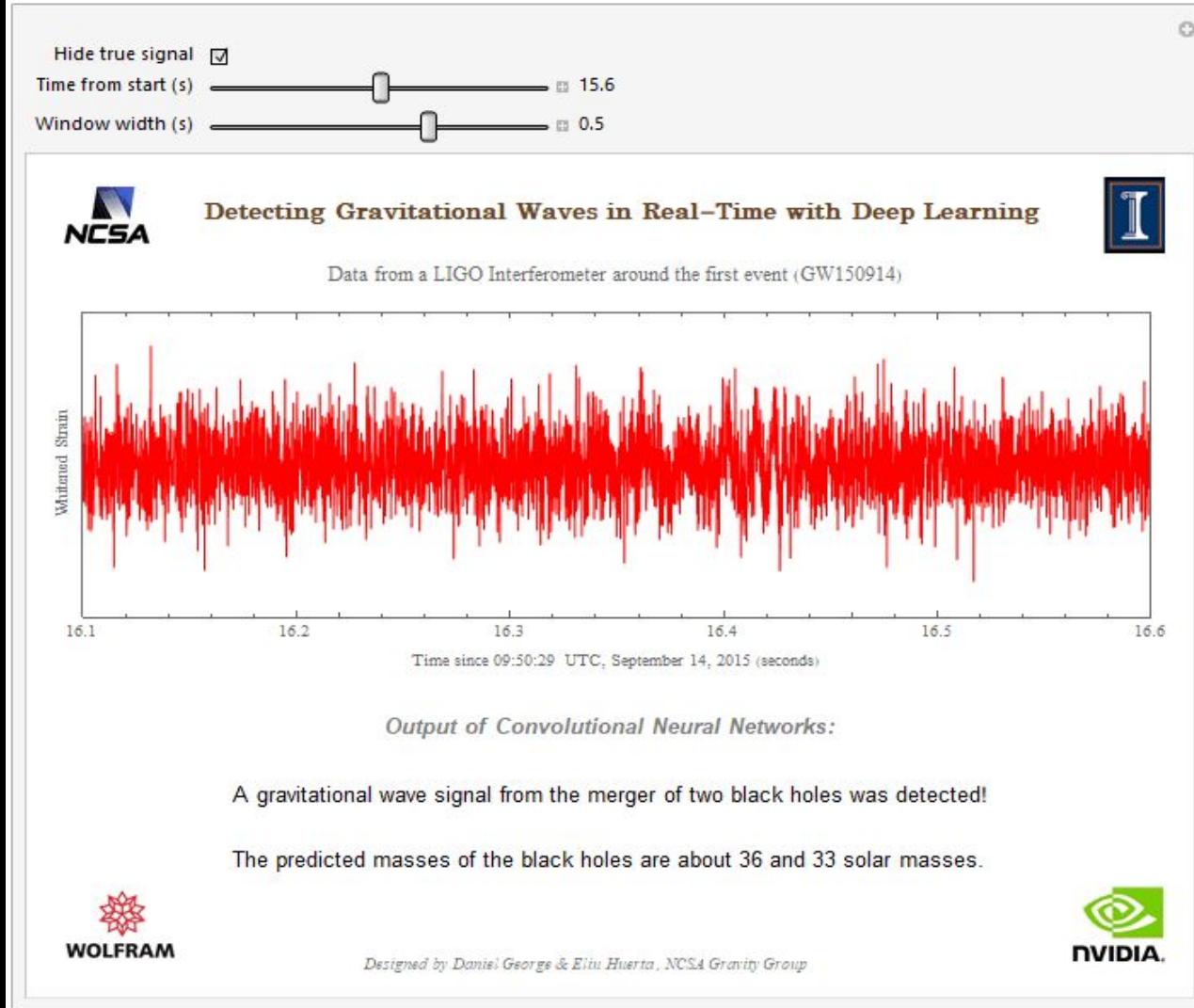
Data not included in training

Trained with only non-spinning,  
non-eccentric simulations

~1s to analyze 4096s of data.

Masses correct within error bars

No False Alarms with two  
detectors!



# New Types of GWs

## Eccentric, Spinning

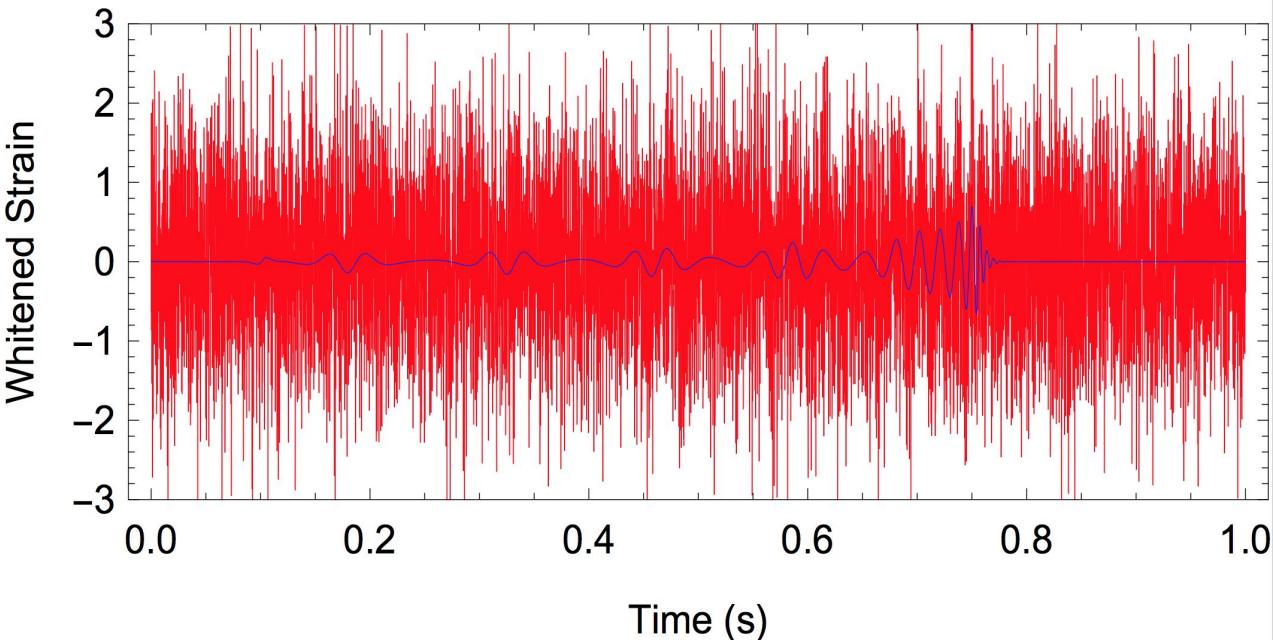
Not included in training.

Same accuracy of detection.

DNNs learned to generalize.

Missed by current methods.

Eccentric BBH Signal: L0020



# Real-time Multimessenger Astrophysics

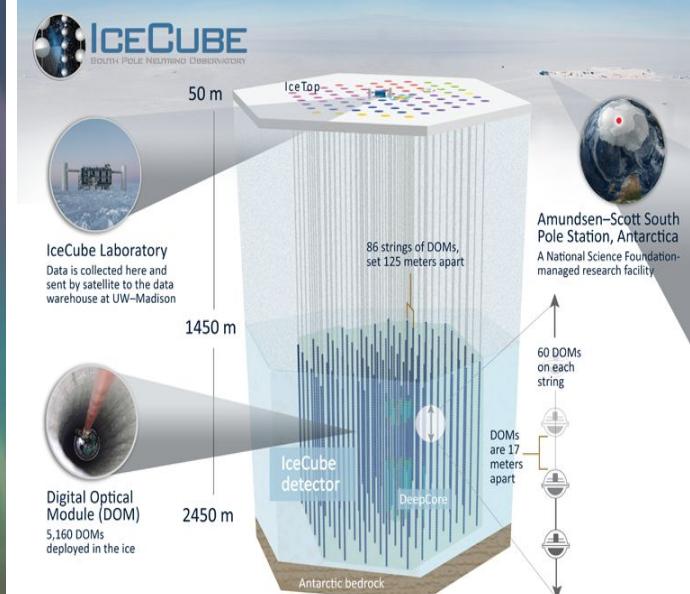
**Hear** gravitational waves



**See** electromagnetic waves



**Feel** astroparticles

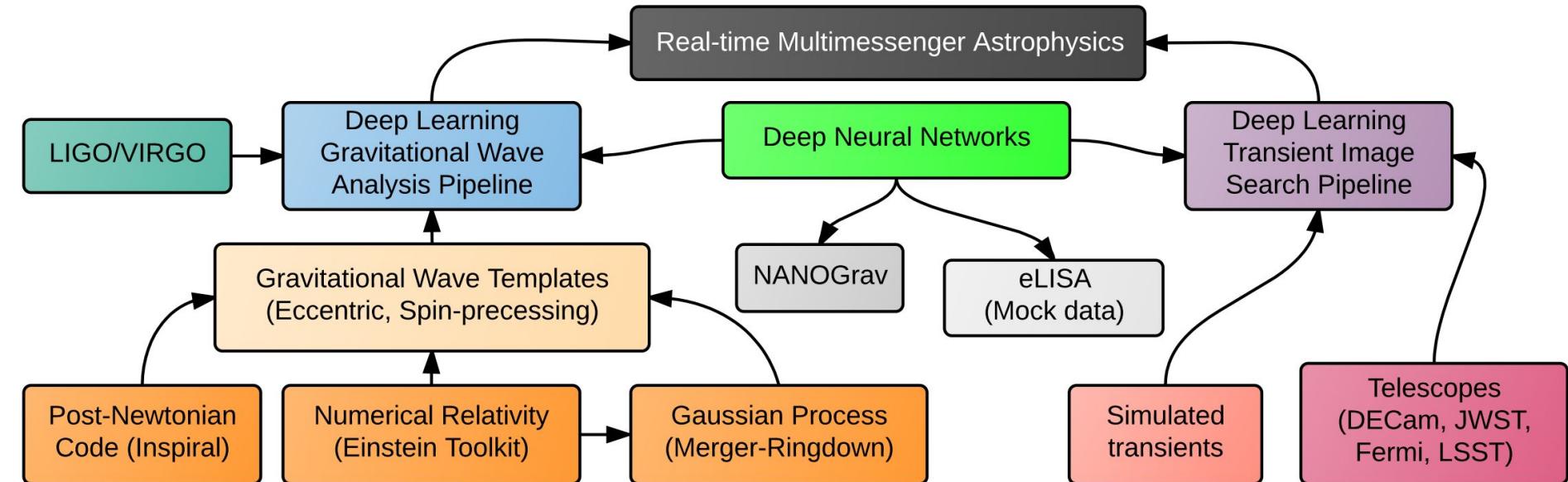


LIGO, VIRGO, KAGRA, eLISA

DES, LSST, JWST, WFIRST

IceCube (neutrinos)

# Enabling Real-Time Multimessenger Astrophysics



Link to these slides: [www.tiny.cc/nips](http://www.tiny.cc/nips)

Extended article: [arXiv:1711.03121](https://arxiv.org/abs/1711.03121)

Awarded 1st place at the ACM student research competition at SC17

# Conclusion

**HPC (*Blue Waters*) + AI (*Deep Learning*) + GPUs  
= Real-time Big Data Analysis for Science!**

# Anomaly Detection, Unsupervised Clustering



# Glitch Classification and Clustering for LIGO with Deep Transfer Learning

With LIGO O1 Gravity Spy Dataset

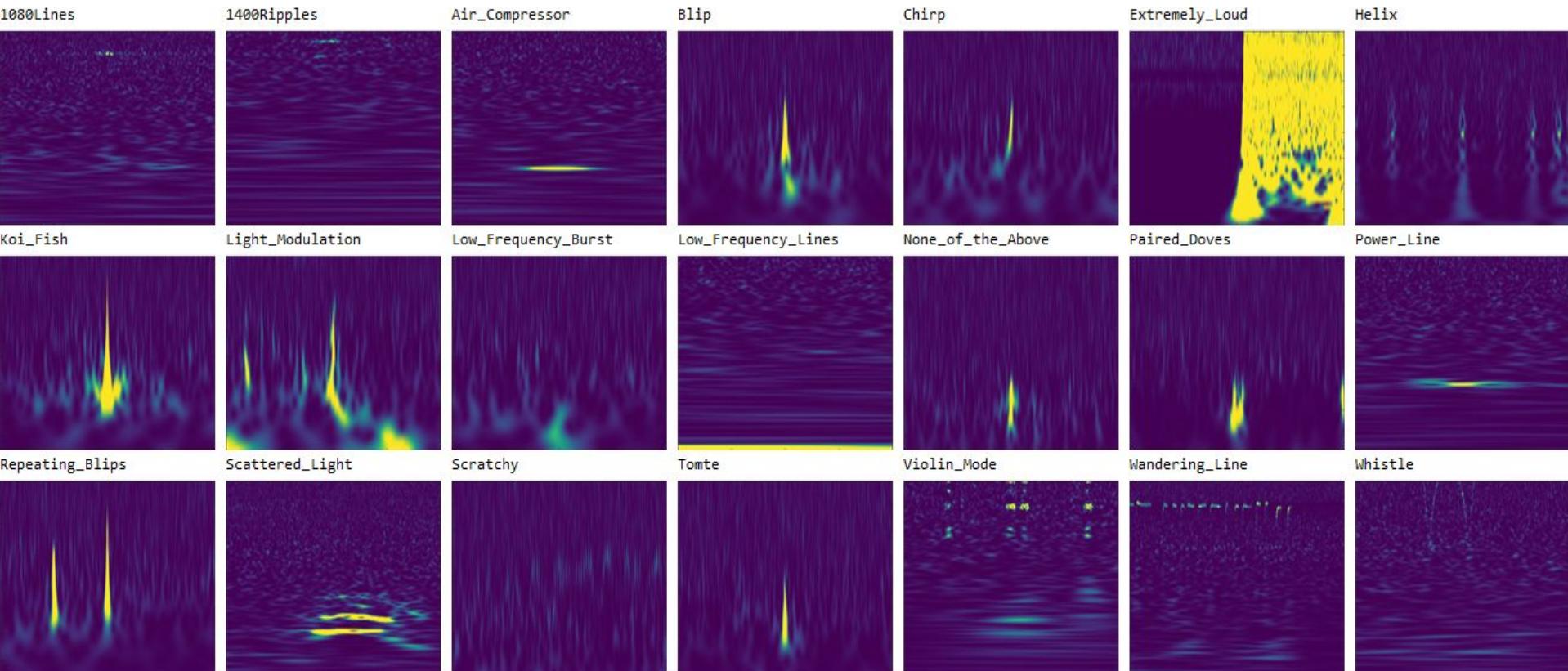
[arXiv:1711.07468](https://arxiv.org/abs/1711.07468)

Daniel George, Hongyu Shen, Eliu Huerta

National Center For Supercomputing Applications (NCSA)  
University of Illinois at Urbana-Champaign



# Classes in the Gravity Spy dataset



# Transfer Learning Approach

Humans aren't trained on large glitch datasets yet perform well. Why?

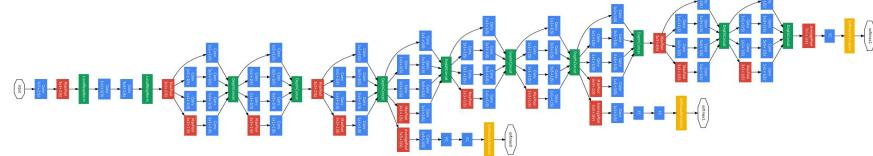
Indicates real-world pattern recognizers are useful even for glitch classification

**Idea:** Use pre-trained weights from state-of-the-art networks trained on real photos

Provides off-the-shelf features in the initial layers, fine-tuned later

Much faster (few minutes of training > 98.7% accuracy), less data needed

# Fine-tuning Inception



98.8+ % (4 rounds / 5 min of training)

5ms to 15ms speed of evaluation

Perfect precision and recall:

1080 Lines, 1440 Ripples, Air Compressor,

Chirp, Helix, Paired Doves, Scratty, Power Line



# CNNs as a Feature-Extractors

## Original CNN (VGG-16)

relu4_3	Ramp	3-tensor (size: 512 × 28 × 28)
pool4	PoolingLayer	3-tensor (size: 512 × 14 × 14)
conv5_1	ConvolutionLayer	3-tensor (size: 512 × 14 × 14)
relu5_1	Ramp	3-tensor (size: 512 × 14 × 14)
conv5_2	ConvolutionLayer	3-tensor (size: 512 × 14 × 14)
relu5_2	Ramp	3-tensor (size: 512 × 14 × 14)
conv5_3	ConvolutionLayer	3-tensor (size: 512 × 14 × 14)
relu5_3	Ramp	3-tensor (size: 512 × 14 × 14)
pool5	PoolingLayer	3-tensor (size: 512 × 7 × 7)
flatten_0	FlattenLayer	vector (size: 25088)
fc6	LinearLayer	vector (size: 4096)
relu6	Ramp	vector (size: 4096)
drop6	DropoutLayer	vector (size: 4096)
fc7	LinearLayer	vector (size: 4096)
relu7	Ramp	vector (size: 4096)
drop7	DropoutLayer	vector (size: 4096)
fc8	LinearLayer	vector (size: 22)
prob	SoftmaxLayer	vector (size: 22)
	Output	class

## Truncated CNN

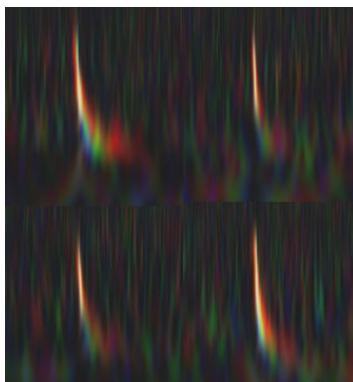
relu4_3	Ramp	3-tensor (size: 512 × 28 × 28)
pool4	PoolingLayer	3-tensor (size: 512 × 14 × 14)
conv5_1	ConvolutionLayer	3-tensor (size: 512 × 14 × 14)
relu5_1	Ramp	3-tensor (size: 512 × 14 × 14)
conv5_2	ConvolutionLayer	3-tensor (size: 512 × 14 × 14)
relu5_2	Ramp	3-tensor (size: 512 × 14 × 14)
conv5_3	ConvolutionLayer	3-tensor (size: 512 × 14 × 14)
relu5_3	Ramp	3-tensor (size: 512 × 14 × 14)
pool5	PoolingLayer	3-tensor (size: 512 × 7 × 7)
flatten_0	FlattenLayer	vector (size: 25088)
fc6	LinearLayer	vector (size: 4096)
relu6	Ramp	vector (size: 4096)
drop6	DropoutLayer	vector (size: 4096)
fc7	LinearLayer	vector (size: 4096)
	Output	vector (size: 4096)

**Output: Feature Vector**

# Visualizing Clusters of New Classes

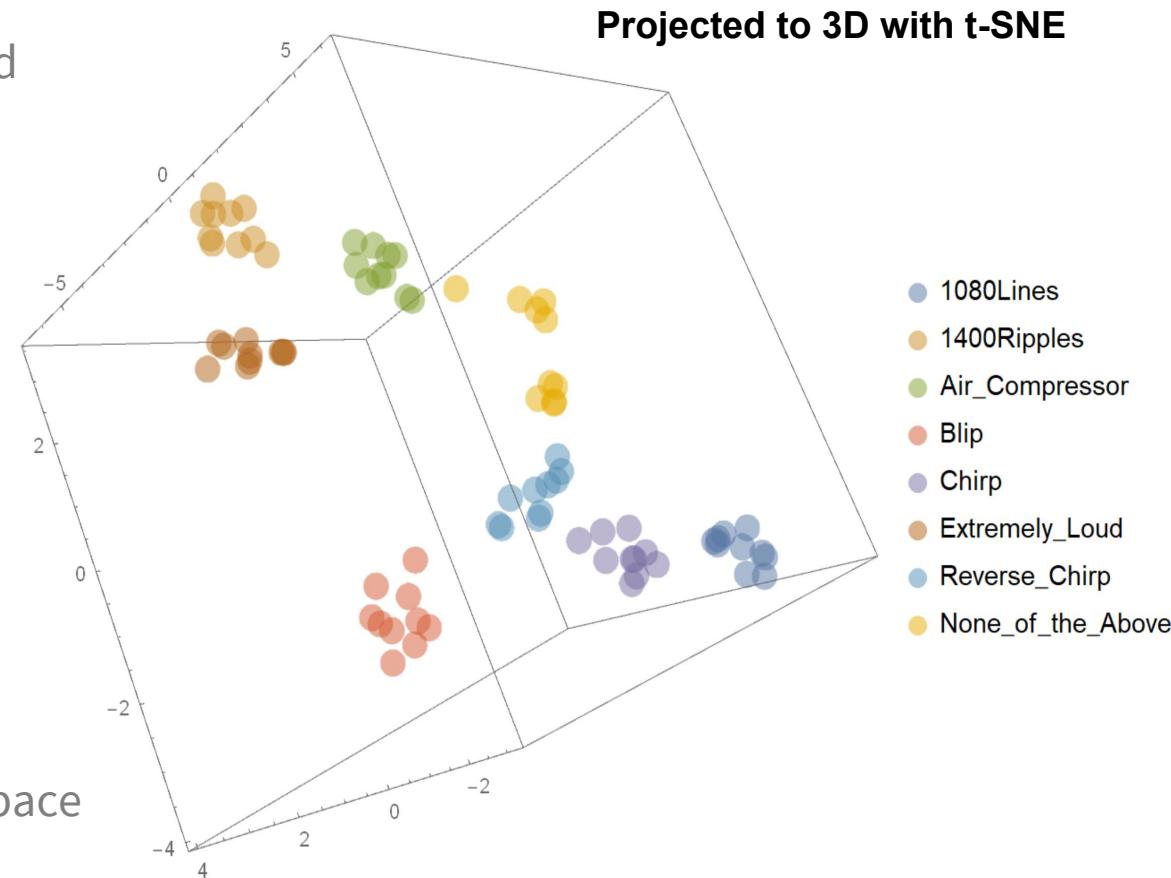
After transfer learning, our truncated CNNs can automatically cluster new classes not seen before.

Synthetic class:



Reverse\_Chirp

Glitches are organized according to their morphologies in this feature-space



# Denoising

# Denoising Gravitational Waves with Recurrent Neural Networks



[arXiv:1711.09919](https://arxiv.org/abs/1711.09919)



Hongyu Shen, Daniel George, E.A. Huerta, Zhizhen Zhao

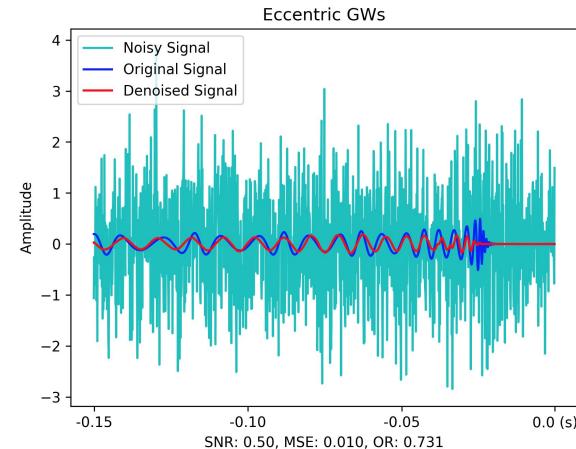
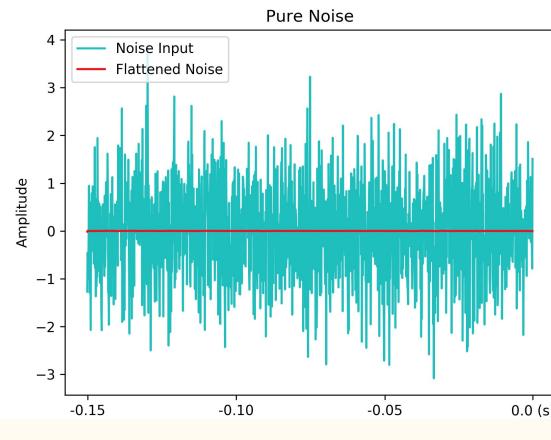
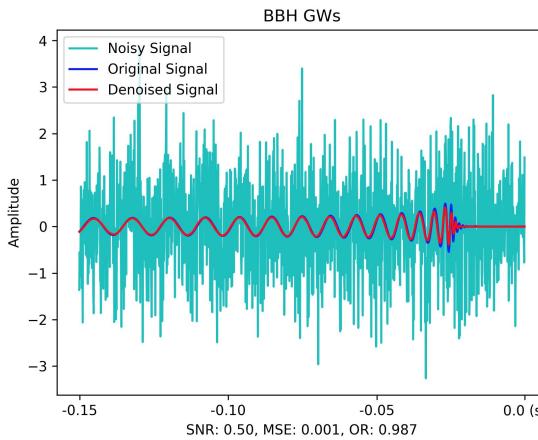
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NCSA Gravity Group - <http://gravity.ncsa.illinois.edu/>

Department of Statistics, Department of Astronomy,  
Department of ECE and Coordinated Science Lab, UIUC

# Results on Real Noise

1. At very low SNR, the network can still recover the shape of the true signal
2. Pure noise input is denoised to a flat line (red in the middle).
3. The network is capable of denoising new types of waveforms (right).



*Link to these slides: [www.tiny.cc/nips](http://www.tiny.cc/nips)*

# Questions?