

# Solving TSP using Ant Colony Optimization

CORTAL Gustave (ID : F10815023)

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# Introduction

- The travelling salesman problem (TSP) is a NP-hard problem → find the shortest possible route between a list of cities knowing that we have distance between each pairs of cities.
- ACO algorithms try to mimic biological behaviors of ants in their colony → through iterations, an optimal solution has to emerge from different solutions proposed by ants.

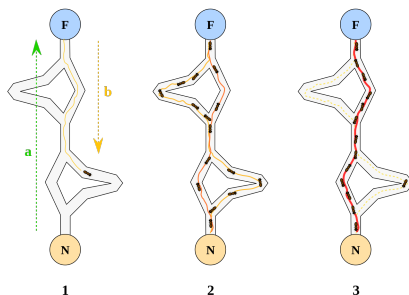


FIGURE 1 – Emergence of a solution through iterations

# A randomized algorithm : concept

## procedure ACOBasic

Set parameters, initialize pheromone trails

**while** (termination condition not met) **do**

    ConstructAntsSolutions

    DaemonActions *% optional*

    UpdatePheromones

**end**

**end**

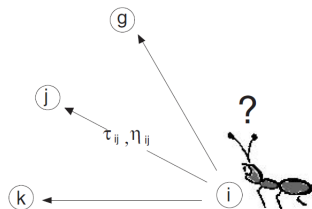


FIGURE 2 – ACO algorithm skeleton and ant choice

# A randomized algorithm : probabilistic action choice rule

The probability with which ant  $k$ , currently at city  $i$ , chooses to go to city  $j$  is :

$$p_{ij}^k = \frac{[\tau_{ij}]^\alpha [\eta_{ij}]^\beta}{\sum_{l \in N_i^k} [\tau_{il}]^\alpha [\eta_{il}]^\beta}, \text{ if } j \in N_i^k \quad (1)$$

$\eta_{ij} = 1/d_{ij}$  : heuristic desirability of visiting city  $j$  directly after city  $i$

$\tau_{ij}$  : pheromone desirability of visiting city  $j$  directly after city  $i$

$\alpha$  and  $\beta$  : the relative influence of the pheromone trail and the heuristic information

$N_i^k$  : the set of cities that ant  $k$  has not visited yet

# A randomized algorithm : update of pheromone trails

The pheromone evaporation :

$$\tau_{ij} \leftarrow (1 - \rho)\tau_{ij}, \forall (i, j) \in L \quad (2)$$

All ants deposit pheromone on the arcs they have crossed :

$$\tau_{ij} \leftarrow \tau_{ij} + \sum_{k=1}^m \Delta\tau_{ij}^k, \forall (i, j) \in L \quad (3)$$

$\rho$  : evaporation rate ( $\in [0, 1]$ )

$\Delta\tau_{ij}^k$  : the amount of pheromone ant  $k$  deposits on the arcs it has visited.

$\Delta\tau_{ij}^k = 1/C^k$  if arc  $(i, j)$  belongs to  $T^k$  where  $C^k$ , the length of the tour  $T^k$  built by the  $k$ -th ant.

# A randomized algorithm : improvements

## Elitist Ant System :

$$\tau_{ij} \leftarrow \tau_{ij} + \sum_{k=1}^m \Delta\tau_{ij}^k + e\Delta\tau_{ij}^{bs}, \forall (i,j) \in L \quad (4)$$

Where,  $\Delta\tau_{ij}^{bs} = 1/C^{bs}$  if arc  $(i,j)$  belongs to  $T^{bs}$  where  $C^{bs}$  is the length of the best-so-far tour  $T^{bs}$ .

## Initialize pheromone matrix :

$$\tau_0 = m/C^{nn} \quad (5)$$

$$\tau_0 = (e + m)/\rho C^{nn} \quad (6)$$

Where  $C^{nn}$  is the tour length found by applying nearest neighbor (NN) algorithm at a random node.

# A randomized algorithm : detect stagnation

- **Standard deviation**  $\sigma_L$  of the length of the tours the ants construct after every iteration (or compute **variation coefficient**).
- **Shannon entropy**  $\rightarrow$  the average  $\bar{\varepsilon} = \sum_{i=1}^n \varepsilon_i / n$  of the entropy  $\varepsilon_i$  of the selection probabilities at each node :

$$\varepsilon_i = - \sum_{j=1}^l p_{ij} \log(p_{ij}) \quad (7)$$

Where  $p_{ij}$  is the probability of choosing arc  $(i, j)$  when being in node  $i$ , and  $l$ ,  $1 \leq l \leq n - 1$ , is the number of possibles choices.

# A randomized algorithm : detect stagnation

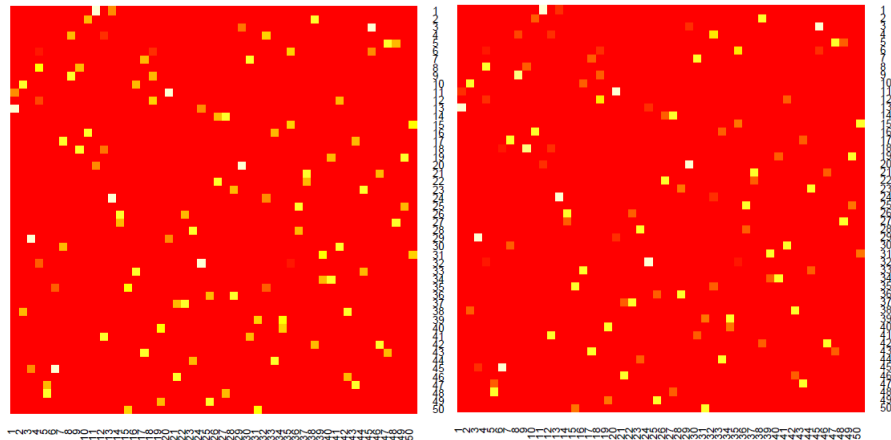


FIGURE 3 – Pheromone matrix heatmap after 100 and 300 iterations (ASE)



# A neural network idea : dropout

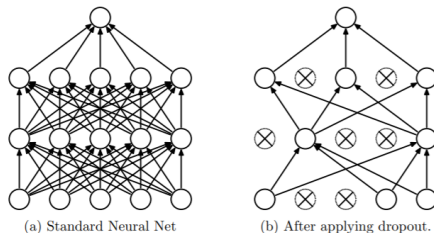


FIGURE 4 – Example of dropout in a neural network

New daemon action  $\rightarrow$  randomly vanish some interesting arcs

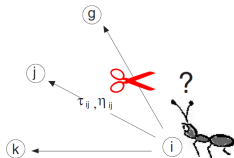


FIGURE 5 – Cut some arcs during the construction procedure

# A neural network idea : dropout

$$\tau_{ij} \leftarrow \tau_{ij} + \sum_{k=1}^m \Delta\tau_{ij}^k + e\Delta\tau_{ij}^{bs} * B_{ij}^{bs}, \forall (i,j) \in L \quad (8)$$

Where  $B_{ij}^{bs} \sim \text{Bernoulli}(p)$ .  $p$  is a new parameter to tune which decides whether or not we add pheromones to a specific arc ( $B_{ij}^{bs} = 1$  or  $0$ ).

$$\tau_{ij} \leftarrow \tau_{ij} + \sum_{k=1}^m \Delta\tau_{ij}^k + e\Delta\tau_{ij}^{bs} * N_{ij}^{bs}, \forall (i,j) \in L \quad (9)$$

Where  $N_{ij}^{bs} \sim N(1, \sigma^2)$ . The mean is set to 1 and  $\sigma$ , the standard deviation, is a new parameter to tune which decides the amount of noises we want around the best iteration tour.

# A neural network idea : dropout

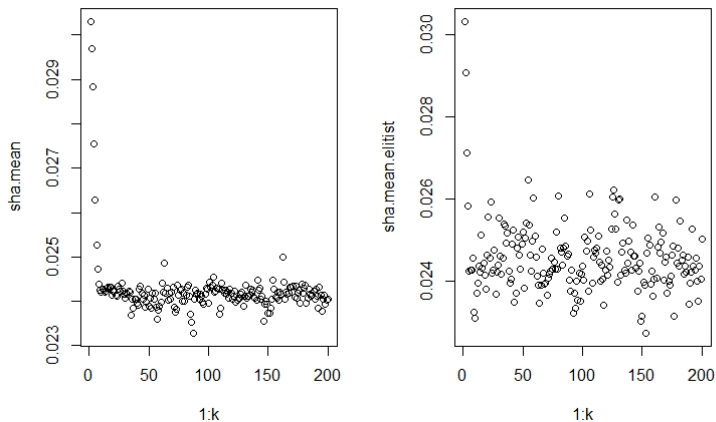


FIGURE 6 – Shannon index analysis on ASE and ASE+Drop

# Experimental results

$$\alpha = 1, \beta = 3.5, \rho = 0.5, m = n.$$

$$\text{Gap error} : (\text{Avg} - \text{opt}) / \text{opt} * 100$$

TSP (opt)	Algorithm	Best	Worst	Avg	Std	Gap
eil51 (426)	ASE+Drop	430.35	437.60	433.66	2.07	1.79%
	ASE	432.33	440.83	435.74	3.12	2.29%
	AS	443.35	455.26	450.76	3.39	5.81%
	NN+2-opt	438.72	514.62	476.61	22.57	11.89%
berlin52 (7542)	ASE+Drop	7544.37	7544.66	7544.46	0.14	0.03%
	ASE	7544.37	7663.21	7558.22	36.96	0.22%
	AS	7549.29	7677.12	7622.91	53.62	1.07%
	NN+2-opt	8042.95	8894.5	8448.54	326.69	12.02%
eil76 (538)	ASE+Drop	546.19	555.90	550.89	3.49	2.39%
	ASE	547.33	558.25	551.96	3.41	2.59%
	AS	558.17	570.54	565.45	3.81	5.10%
	NN+2-opt	568.46	630.15	597.18	22.26	11.00%

FIGURE 7 – Experimental results on three different benchmarks

# A practical problem : Youbike stations

- Taipei Youbike stations dataset provided by Taipei City.
- Get the distance matrix between the stations → Google Maps API.

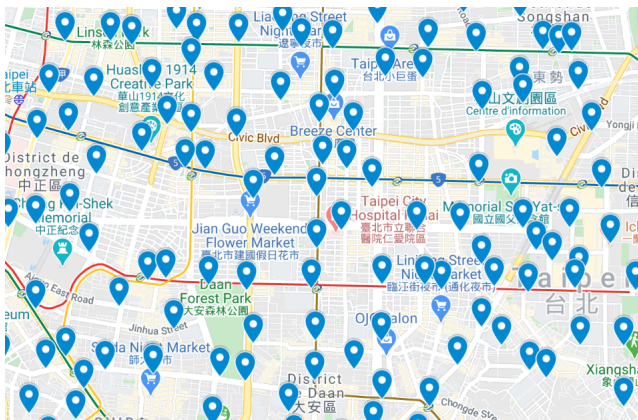


FIGURE 8 – Youbike stations in Google Maps

# A practical problem : Youbike Stations

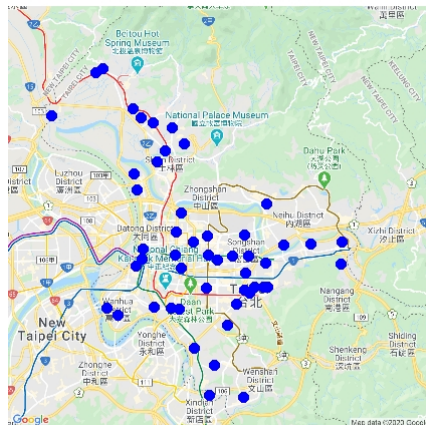


FIGURE 9 – Youbike stations (blue nodes) in Google Maps

## A practical problem : results

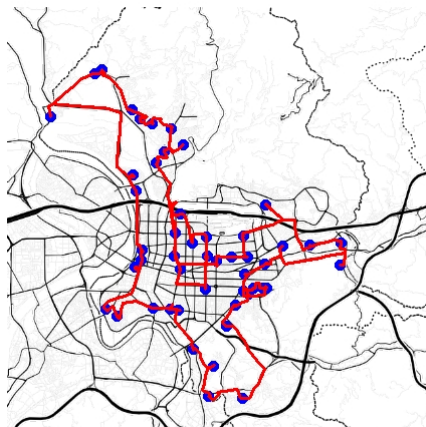







FIGURE 10 – Youbike stations (blue nodes) with best found tour in Google Maps

# References

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