

Transformers

Gustave Cortal

Transformers vs recurrent neural networks

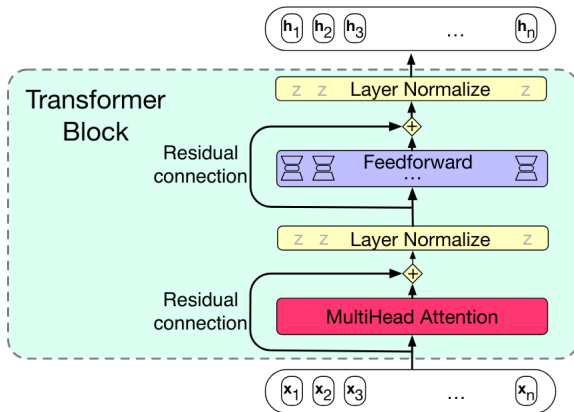
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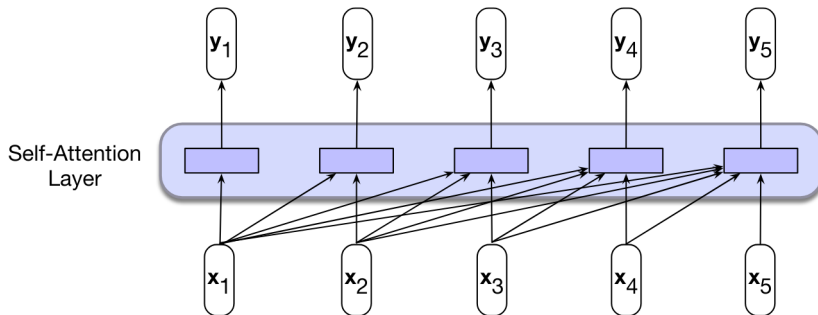
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Unlike RNNs, the computations at each time step are **independent of all the other steps** and, therefore, can **be performed in parallel**

Transformer block

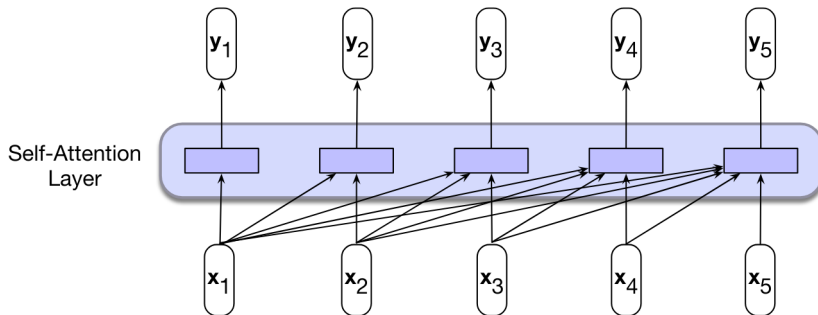


Self-attention layer



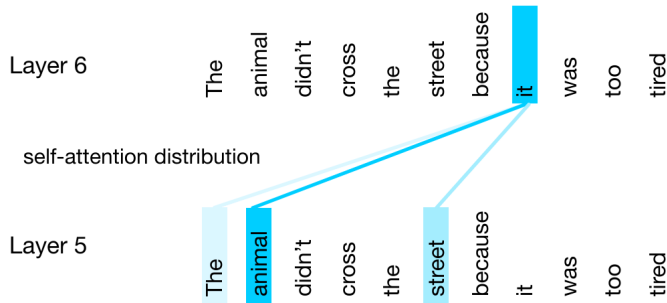
Self-attention directly extracts and uses information from arbitrarily large contexts without passing it through intermediate recurrent connections

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Attention visualization



Main idea of attention mechanisms

An attention-based approach is a set of **comparisons to relevant items** in some context, a **normalization** of those scores to provide a probability distribution, and a **weighted sum** using this distribution

Dot-product attention

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$$\text{score}(x_i, x_j) = x_i \cdot x_j$$

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$$\begin{aligned}\alpha_{ij} &= \text{softmax}(\text{score}(x_i, x_j)) \quad \forall j \leq i \\ &= \frac{\exp(\text{score}(x_i, x_j))}{\sum_{k=1}^i \exp(\text{score}(x_i, x_k))} \quad \forall j \leq i\end{aligned}$$

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Finally, we generate an output value y_i by taking the **sum** of the inputs seen so far, **weighted** by their respective α value.

$$y_i = \sum_{j \leq i} \alpha_{ij} x_j$$

Attention with queries, keys and values

But transformers create a **more sophisticated way** of representing how words can contribute to the representation of longer inputs. Consider the three roles each input embedding plays during the attention process:

- ▶ As the current focus of attention when being compared to all of the other preceding inputs → **query**
- ▶ In its role as a preceding input being compared to the current focus of attention → **key**
- ▶ And finally, as a **value** used to compute the output for the current focus of attention

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To capture these three different roles, transformers introduce weight matrices W_Q , W_K , and W_V . These weights project each input vector x_i into a representation of its role as a key, query, or value:

$$q_i = W_Q x_i,$$

$$k_i = W_K x_i,$$

$$v_i = W_V x_i$$

$$x_i \in \mathbb{R}^{d \times 1}, W_Q \in \mathbb{R}^{d \times d}, W_K \in \mathbb{R}^{d \times d}, \text{ and } W_V \in \mathbb{R}^{d \times d}.$$

Attention with queries, keys and values

Given these projections, the score between a current focus of attention, x_i , and an element in the preceding context, x_j , consists of a dot product between its query vector q_i and the preceding element's key vectors k_j :

$$\text{score}(x_i, x_j) = q_i \cdot k_j$$

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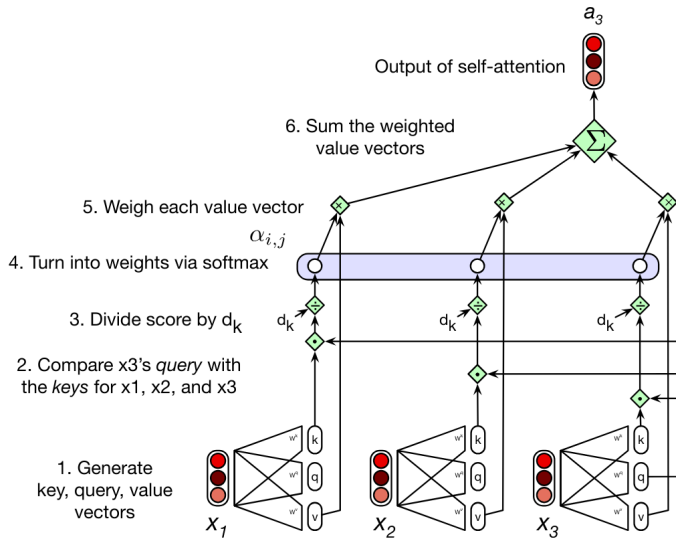
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Exponentiating large values can lead to numerical issues. To avoid this, we **scale** the dot-product by a factor related to the size of the embeddings:

$$\text{score}(x_i, x_j) = \frac{q_i \cdot k_j}{\sqrt{d}}$$

Attention with queries, keys and values



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Since each output y_i is computed independently, the entire process can be parallelized by taking advantage of matrix multiplication

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Input tokens are packed into a single matrix $X \in \mathbb{R}^{N \times d}$. We multiply X by the key, query, and value matrices:

$$Q = XW_Q; \quad K = XW_K; \quad V = XW_V$$

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We've reduced the self-attention step for a sequence of N tokens:

$$\text{SelfAttention}(Q, K, V) = \text{softmax}\left(\frac{QK^T}{\sqrt{d}}\right) V$$

Masked attention matrix

N

q1•k1	$-\infty$	$-\infty$	$-\infty$	$-\infty$
q2•k1	q2•k2	$-\infty$	$-\infty$	$-\infty$
q3•k1	q3•k2	q3•k3	$-\infty$	$-\infty$
q4•k1	q4•k2	q4•k3	q4•k4	$-\infty$
q5•k1	q5•k2	q5•k3	q5•k4	q5•k5

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QK^T results in a score for each query value to every key value, including those that follow the query

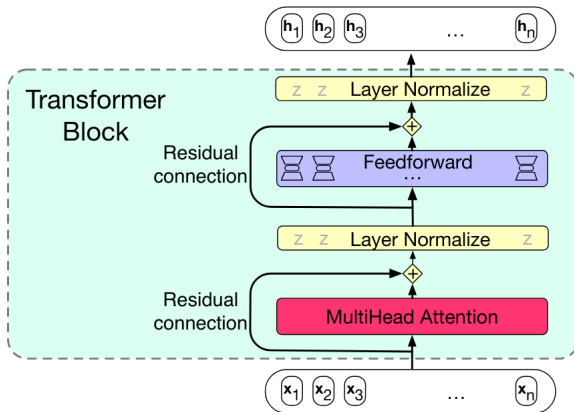
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This is inappropriate in language modeling since guessing the next word is pretty simple if you already know it. To fix this, the elements in the upper-triangular portion of the matrix are set to $-\infty$

Transformer block



Multihead attention

Different words in a sentence can relate to each other in many different ways simultaneously

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Transformers address this issue with **multihead self-attention layers**, sets of self-attention layers, called heads, that reside in parallel layers at the same depth in a model, each with its own set of parameters

Multihead attention

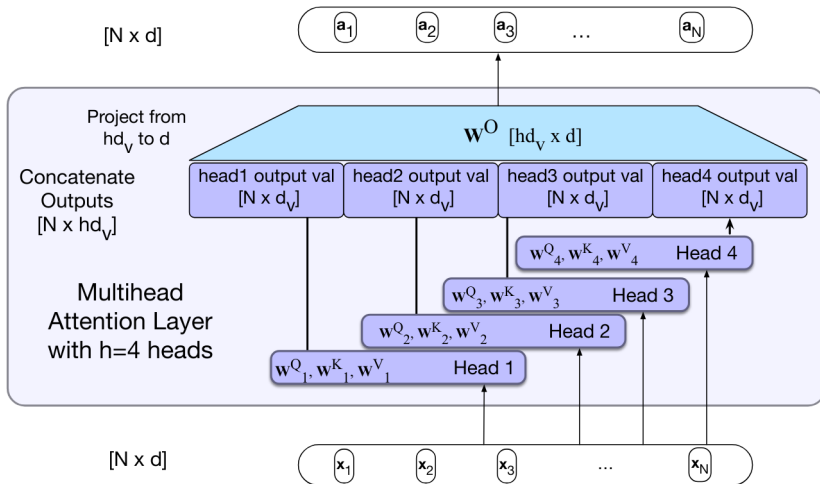
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Given these distinct sets of parameters, each head can learn different aspects of the relationships among inputs at the same level of abstraction

Multihead attention



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$$\text{MultiHeadAttention}(X) = (\text{head}_1 \oplus \text{head}_2 \dots \oplus \text{head}_h)W^O$$

$$Q_i = XW_i^Q; \quad K_i = XW_i^K; \quad V_i = XW_i^V$$

$$\text{head}_i = \text{SelfAttention}(Q_i, K_i, V_i)$$

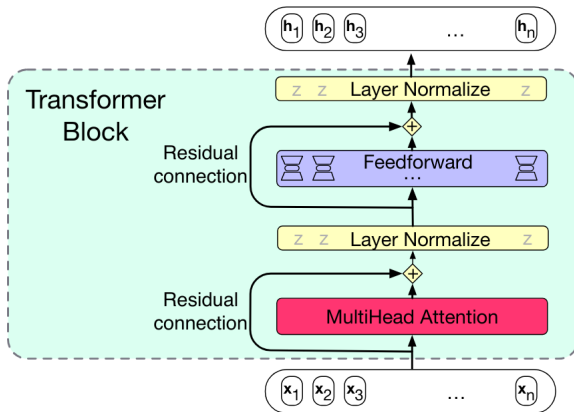
$$X \in \mathbb{R}^{N \times d}$$

$$W_i^Q \in \mathbb{R}^{d \times d_k}, \quad W_i^K \in \mathbb{R}^{d \times d_k}, \quad \text{and} \quad W_i^V \in \mathbb{R}^{d \times d_v}$$

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$$W^O \in \mathbb{R}^{hd_v \times d}$$

Transformer block



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Residual connections pass information from a lower layer to a higher layer without going through the intermediate layer

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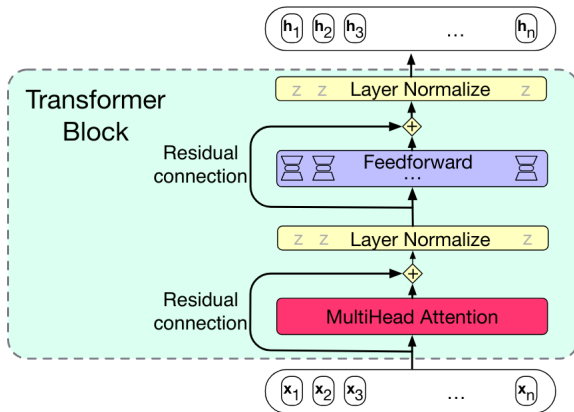
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If we think of a layer as one long vector of units, the resulting function computed in a transformer block can be expressed as:

$$O = \text{LayerNorm}(\mathbf{X} + \text{SelfAttention}(X))$$

$$H = \text{LayerNorm}(\mathbf{O} + \text{FFN}(O))$$

Transformer block



Layer normalization

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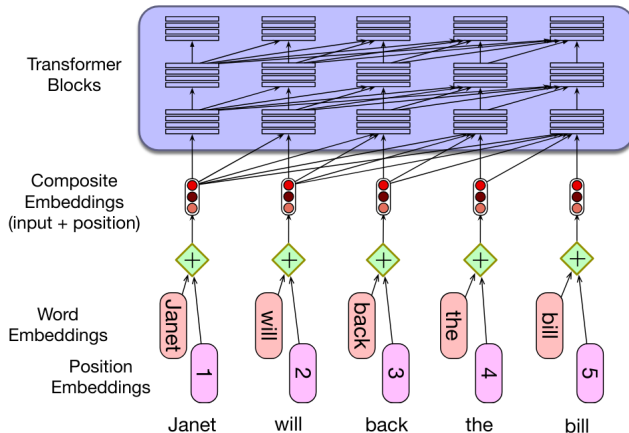
We calculate the mean, μ , and standard deviation, σ , over the elements of the vector to be normalized. Given a hidden layer with dimensionality d , these values are calculated as follows:

$$\mu = \frac{1}{d} \sum_{i=1}^d x_i$$

$$\sigma = \sqrt{\frac{1}{d} \sum_{i=1}^d (x_i - \mu)^2}$$

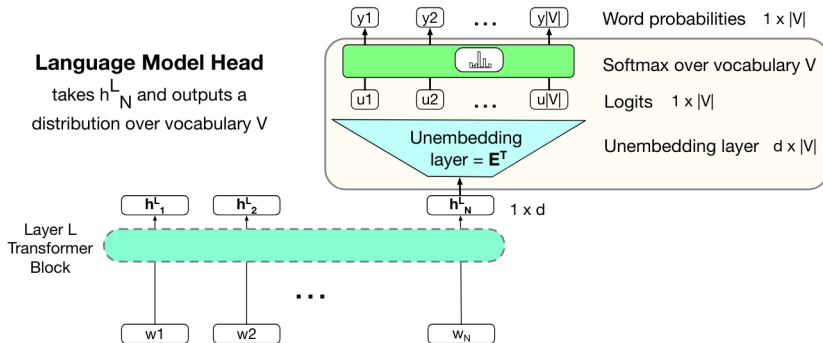
$$\hat{x} = \frac{(x - \mu)}{\sigma}$$

Positional encoding

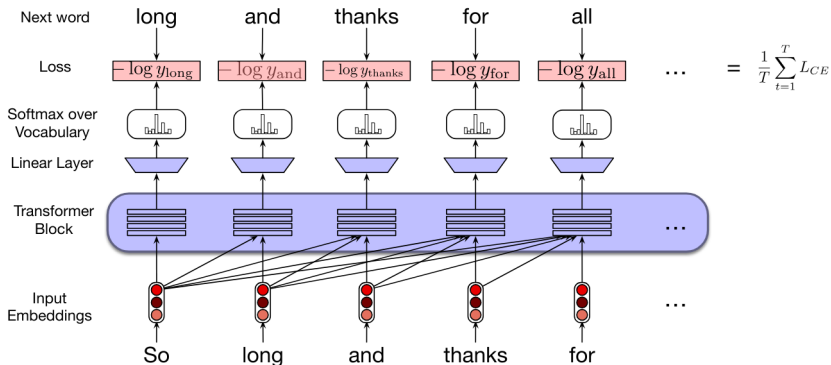


Train positional embeddings or use a static function that maps integer inputs to real-values vectors

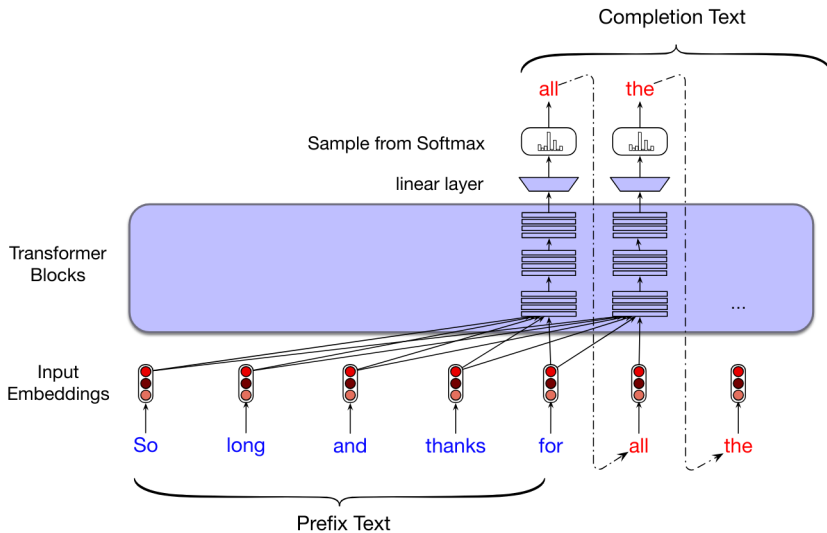
Language model head



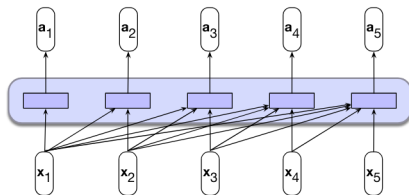
Language modeling using next word prediction



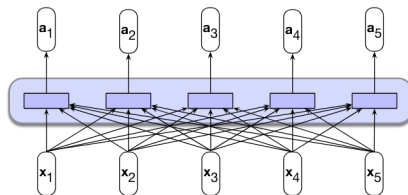
Conditional generation



Causal vs bidirectional language model



a) A causal self-attention layer



b) A bidirectional self-attention layer

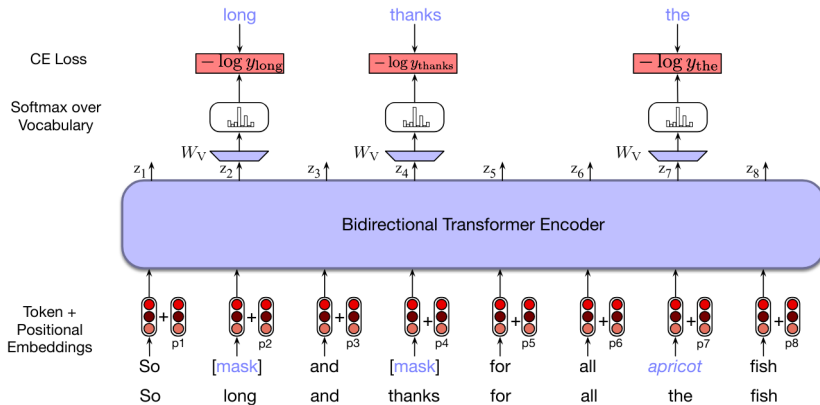
Attention matrix for bidirectional language model

N

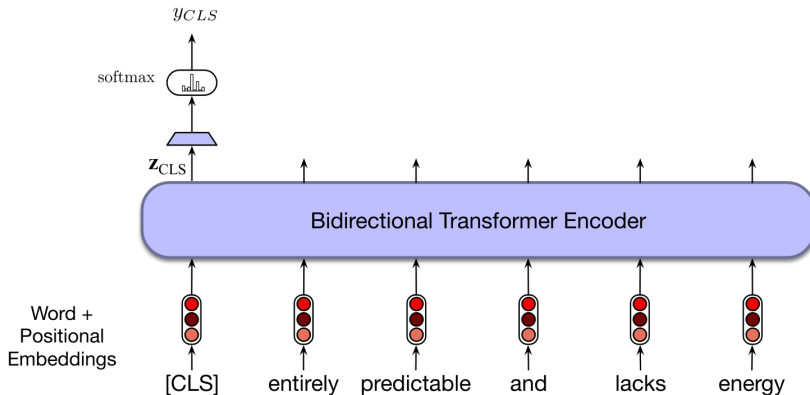
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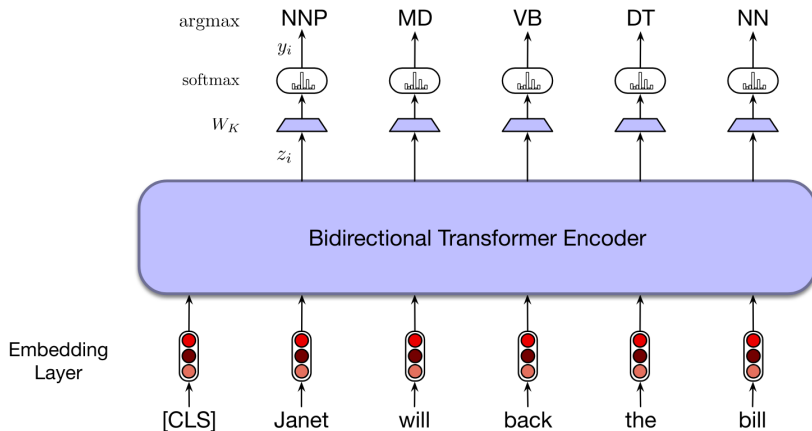
Masked language modeling



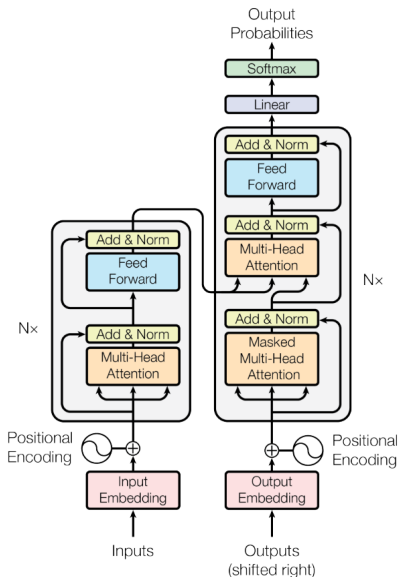
Sequence classification



Token classification



Transformer architecture from *Attention is All you Need*



Architecture, size, and hyperparameters of GPT-3 from *Language Models are Few-Shot Learners*

Model Name	n_{params}	n_{layers}	d_{model}	n_{heads}	d_{head}	Batch Size	Learning Rate
GPT-3 Small	125M	12	768	12	64	0.5M	6.0×10^{-4}
GPT-3 Medium	350M	24	1024	16	64	0.5M	3.0×10^{-4}
GPT-3 Large	760M	24	1536	16	96	0.5M	2.5×10^{-4}
GPT-3 XL	1.3B	24	2048	24	128	1M	2.0×10^{-4}
GPT-3 2.7B	2.7B	32	2560	32	80	1M	1.6×10^{-4}
GPT-3 6.7B	6.7B	32	4096	32	128	2M	1.2×10^{-4}
GPT-3 13B	13.0B	40	5140	40	128	2M	1.0×10^{-4}
GPT-3 175B or “GPT-3”	175.0B	96	12288	96	128	3.2M	0.6×10^{-4}

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Feedforward neural networks handle longer inputs and generalize better compared to N-grams thanks to embeddings, have fixed context windows

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Attention mechanisms solve the bottleneck problem to produce dynamically derived context vectors

Transformers use self-attention layers combined with feedforward layers to handle more complex distant relationships between tokens, enable parallelization due to independent computation between tokens, have fixed context windows

Ressources

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[//web.stanford.edu/~jurafsky/slp3/ed3bookfeb3_2024.pdf](https://web.stanford.edu/~jurafsky/slp3/ed3bookfeb3_2024.pdf)

3Blue1Brown, *Essence of linear algebra* and *Neural Networks* playlists :

<https://www.youtube.com/@3blue1brown/playlists>

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