



LEGO USB Tower Interface Reference

LEGO Technology Center, LEGO System A/S
Copyright (C) 1999-2000 The LEGO Company. All rights reserved.

Table of Contents

| | | |
|------------|--|-----------|
| 1 | INTRODUCTION..... | 3 |
| 2 | USB TOWER CAPABILITIES | 3 |
| 3 | TOWER CONTROL THROUGH USB VENDOR REQUESTS..... | 3 |
| 3.1 | List of Vendor Requests | 4 |
| | SET_PARM | 5 |
| | GET_PARM..... | 6 |
| | SET_PARM_IRC..... | 7 |
| | GET_PARM_IRC..... | 8 |
| | FLUSH | 9 |
| | RESET..... | 10 |
| | GET_STAT | 11 |
| | RESET_STAT..... | 12 |
| | GET_POWER | 13 |
| | SET_LED..... | 14 |
| | GET_LED | 15 |
| | SET_TX_SPEED/SET_RX_SPEED..... | 16 |
| | GET_TX_SPEED/GET_RX_SPEED | 17 |
| | GET_TX_STATE | 18 |
| | SET_TX_CARRIER_FREQUENCY..... | 19 |
| | GET_TX_CARRIER_FREQUENCY..... | 20 |
| | SET_TX_CARRIER_DUTY_CYCLE | 21 |
| | GET_TX_CARRIER_DUTY_CYCLE..... | 22 |
| | GET_CAPS..... | 23 |
| | GET_VERSION..... | 24 |
| | GET_COPYRIGHT | 25 |
| 3.2 | Firmware Vendor Request Reply Error Codes | 26 |
| 3.3 | Firmware Internal Error Codes..... | 27 |
| 3.4 | Constant Definitions..... | 28 |

1 Introduction

This document describes in detail the communication interface between the LEGO USB Tower (tower) and the host computer (host).

Communication between the tower and the host takes place through the USB bus. The tower firmware is compliant with version 1.1 of the USB specifications. The remainder of this document assumes the reader has a basic knowledge with the USB Specification 1.1, especially with chapter 9.

The USB communication characteristics of the tower are as follows:

- Two interrupt endpoints
- Vendor-specific device class (no HID or other USB class standards)

The tower has two interrupt endpoints: endpoint 1 is used for device-to-host communications, while endpoint 2 is used for host-to-device communications.

2 USB Tower Capabilities

The USB Tower is able to send and receive infrared signals (IR) and send Visual Light Link (VLL) signals.

The communication speed for:

1. VLL is fixed
2. Available IR speeds can be requested to the tower via the GET_CAPS command. It is possible to set different tx and rx speed.

The Tower has four USB configurations:

1. Low power (default)
2. High power
3. Low power, low bandwidth (8 ms polling interval)
4. High power, low bandwidth (8 ms polling interval)

The Tower control panel on the Host/Windows system controls the active USB configuration. The Tower will always start in low power configuration and thereby being accepted by both low and high power ports on the PC system. Selecting one of the high-power configurations will allow the Tower to function in long range.

The user will see the green indicator LED switched on when the Tower:

1. Is powered and has been successfully configured from the host (ON for about 1 second)
2. Has received an IR transmission request from the host computer (ON for 1 or more seconds)
3. Is delivering IR-received data to the host computer (ON for 1 or more seconds)
4. Has detected an internal error (ON forever, until a reset occurs)

3 Tower control through USB Vendor requests

The Tower is controlled through specific USB vendor requests, defined by us and explained in detail in the following paragraphs.

All parameters set by vendor requests have default values in the Tower. The tower reverts to its default parameters every time it is reset by a vendor request or by unplugging/plug the Tower. Through the Windows control panel, it is possible to specify some parameter values that the driver automatically sets every time the tower is initialised by the application software.

In general, there is no need to set tower parameters unless there is a need for changing the default values.

All text returned on vendor requests are in Unicode format. The default word format is little-endian (PC/Windows standard). All USB-defined standard requests and any data/descriptors returned from standard requests use the little-endian format instead, no matter what's the data format defined in the tower.

3.1 List of Vendor Requests

All USB requests – standard and vendor – are identified by a setup packet containing:

- A request code (bmRequest)
- A word-sized parameter (wValue)
- A word-sized index (wIndex)
- A word-sized length of the expected reply (wLength)

See chapter 9 of the USB 1.1 specifications.

SET_PARM

Request Code

LTW_REQ_SET_PARM

Description

This command allows setting a number of different tower parameters.

Parameters

| | |
|----------------|--|
| LOBYTE(wValue) | Parameter code to be set. It's one of the following codes (the default values are shown in bold face): LTW_PARM_MODE Mode: VLL, IR or IRC LTW_PARM_RANGE Range: Short, Medium or Long LTW_PARM_ERRDETECT Filter spurious data from the IR receiver circuit: On /Off LTW_PARM_ERRSTATUS Current error status of the tower (no error) LTW_PARM_ENDIAN Vendor request word format: Little Endian (PC/Windows standard) or Big Endian (Apple/Motorola standard) LTW_PARM_ID_LED_MODE Id LED control: Firmware-controlled or Host controlled LTW_PARM_ERROR_SIGNAL Signal on internal error: On /Off |
| HIBYTE(wValue) | New value of the parameter |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_SET_PARM_REPLY) |

Response

The response is a LTW_REQ_GET_SET_PARM_REPLY structure:

| | |
|------------|---|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bValue | Current value of the parameter specified in the request. If the request succeeded, this should contain the value specified by the host in the request parameters. |

GET_PARM

Request Code

LTW_REQ_GET_PARM

Description

This command allows getting a number of different tower parameters.

Parameters

| | |
|----------------|---|
| LOBYTE(wValue) | Code of the parameter value to be fetched. It's one of the following codes: <div> <div>LTW_PARM_MODE</div> <div>LTW_PARM_RANGE</div> <div>LTW_PARM_ERRDETECT</div> <div>LTW_PARM_ERRSTATUS</div> <div>LTW_PARM_ENDIAN</div> <div>LTW_PARM_ID_LED_MODE</div> <div>LTW_PARM_ERROR_SIGNAL</div> </div> <div> <div>Mode: VLL, IR or IRC</div> <div>Range: Short, Medium or Long</div> <div>Filter spurious data from the IR receiver circuit: On/Off</div> <div>Remark: Doesn't work in the IRC mode.</div> <div>Current error status of the tower .</div> <div>Vendor request word format: Little Endian (PC/Windows standard) or Big Endian (Apple/Motorola standard)</div> <div>Id LED control: Firmware-controlled or Host controlled</div> <div>Signal on internal error: On/Off</div> </div> |
| HIBYTE(wValue) | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_SET_PARM_REPLY) |

Response

The response is a LTW_REQ_GET_SET_PARM_REPLY structure:

| | |
|------------|---|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bValue | Current value of the parameter specified in the request (values defined in VendReq.h) |

SET_PARM_IRC

Request Code

LTW_REQ_SET_PARM_IRC

Description

This command allows setting a number of different tower parameters specific to the Infrared Remote Control protocol, a special protocol for LEGO cars.

NB: The parameters listed in the above sections (GET_PARM and SET_PARM) apply to the IRC mode as well if nothing else is stated. This special command only gathers the specific IRC commands.

Parameters

| | |
|----------------|--|
| LOBYTE(wValue) | Parameter code to be set. It's one of the following codes (the default values are shown in bold face): LTW_PARM_IRC_PACKETSIZE Packet size, in bytes (default= 2) LTW_PARM_IRC_DELAY_TX Transmit delay time between packets, in ms (80) |
| HIBYTE(wValue) | The parameter to be set |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_SET_PARM_IRC_REPLY) |

Response

The response is a LTW_REQ_GET_SET_PARM_IRC_REPLY structure:

| | |
|------------|---|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bValue | Current value of the parameter specified in the request (values defined in VendReq.h) |

GET_PARM_IRC

Request Code

LTW_REQ_GET_PARM_IRC

Description

This command allows getting a number of different tower parameters specific to the Infrared Remote Control protocol, a special protocol for LEGO cars.

Parameters

| | |
|----------------|---|
| LOBYTE(wValue) | Code of the parameter value to be fetched. It's one of the following codes: LTW_PARM_IRC_PACKETSIZE Packet size, in bytes . LTW_PARM_IRC_DELAY_TX Transmit delay time between packets, in ms. |
| HIBYTE(wValue) | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_SET_PARM_IRC_REPLY) |

Response

The response is a LTW_REQ_GET_SET_PARM_IRC_REPLY structure:

| | |
|------------|---|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bValue | Current value of the parameter specified in the request (values defined in VendReq.h) |

FLUSH

Description

This requests flushes communication buffers according to the request parameter. Both firmware and driver buffers (if applicable) are flushed.

Purpose

1. Flush the transmitter buffer: Is used to flush the transmitter buffer and thereby stopping the transmission.
2. Flush the receiver buffer: Used to flush the receiver buffer before communication with the Pbrick starts.
3. Flush all buffers: Used before communication with the Pbrick starts.

Parameters

| | |
|----------------|---|
| LOBYTE(wValue) | Flush constants, ORred together: LTW_TX_BUFFER Flush the Transmit buffer LTW_RX_BUFFER Flush the receive buffer |
| HIBYTE(wValue) | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_FLUSH_REPLY) |

Response

The response is a LTW_REQ_FLUSH_REPLY structure:

| | |
|------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bBufferNo | Flushed buffers (same as wValue, above) |

RESET

Description

Reset ports and all internal parameters to the default values.

Purpose

Used in case of an internal error to restart the Tower

Parameters

| | |
|----------------|--------------------------------------|
| LOBYTE(wValue) | Not used; set to 0 |
| HIBYTE(wValue) | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_RESET_REPLY) |

Response

The response is a LTW_REQ_FLUSH_REPLY structure:

| | |
|------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |

GET_STAT

Description:

Get statistics from the IR receiver since the last RESET_STAT command.

Statistics:

1. Number of received bytes
2. Number of Overrun errors (new byte received before last received byte was read)
3. Number of Noise errors (noise in bit pattern, used to filter spurious 0xFF from the IR receiver)
4. Number of Framing errors

Purpose:

To analyze received signal quality and to filter spurious 0xFF.

Parameters

| | |
|----------------|---|
| LOBYTE(wValue) | Not used; set to 0 |
| HIBYTE(wValue) | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_STAT_REPLY) |

Response

The response is a LTW_REQ_FLUSH_REPLY structure:

| | |
|--------------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| wNoOfRxBytes | Number of received bytes |
| wOverrunErrorCount | # of times overrun error has happen |
| wNoiseCount | # of bytes with wrong bits |
| wFramingErrorCount | # of bytes with framing errors |

RESET_STAT

Description

Reset statistics from the IR receiver (See GET_STAT).

Purpose

Reset statistics after the Host has read the statistics.

Parameters

| | |
|----------------|--|
| LOBYTE(wValue) | Not used; set to 0 |
| HIBYTE(wValue) | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_RESET_STATS_REPLY) |

Response

The response is a LTW_REQ_RESET_STATS_REPLY structure:

| | |
|------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |

GET_POWER

Description

Get the Tower power configuration:

1. Low power (100 mA)
2. High power (500 mA)

The same information can be obtained in a standard way by querying the current device configuration (GET_CONFIGURATION standard request) and then retrieving the configuration descriptor (GET_DESCRIPTOR(CONFIGURATION) standard request) to see the power requirements of the device.

Purpose

To determine which power configuration is active. The Tower is only able to send in short and medium range when the low power configuration is active.

Parameters

| | |
|----------------|--|
| LOBYTE(wValue) | Not used; set to 0 |
| HIBYTE(wValue) | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_POWER_REPLY) |

Response

The response is a LTW_REQ_GET_POWER_REPLY structure:

| | |
|------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| bPowerMode | Current power mode of the tower: LTW_POWER_LOW or LTW_POWER_HIGH |

SET_LED

Description

Set the state of the ID or VLL led according to request parameters. In order to set the led state of the ID led, you must have set the led mode to software control (see SET_PARM (LED_MODE) request)

Purpose

Allow software control of the tower leds. This feature is used in the hardware production test to check that the leds are working.

Parameters

| | |
|----------------|---|
| LOBYTE(wValue) | Led indicator: LTW_LED_ID The "green" led (normally used to indicate IR transmission) LTW_LED_VLL The red led, normally used to carry out VLL communications |
| HIBYTE(wValue) | Color code: LTW_LED_COLOR_ON Switch on led. LTW_LED_COLOR_OFF Switch off led. LTW_LED_COLOR_DEFAULT Same as COLOR_ON. LTW_LED_COLOR_BLACK Same as COLOR_OFF. LTW_LED_COLOR_GREEN LTW_LED_COLOR_YELLOW Same as ON on the current firmware. LTW_LED_COLOR_ORANGE It could indicate a specific color if a multicolor led is used in the future. LTW_LED_COLOR_RED |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_SET_LED_REPLY) |

Response

The response is a LTW_REQ_GET_SET_LED_REPLY structure:

| | |
|------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| bLedID | Same as LOBYTE(wValue) |
| bColor | Same as HIBYTE(wValue) |

GET_LED

Description:

Get the current state of the ID or VLL led according to the request parameter:

Purpose:

Used to display the current state of the Tower leds in the Host application and in the hardware production test to check that the leds are working.

Parameters

| | |
|----------------|--|
| LOBYTE(wValue) | Led indicator: LTW_LED_ID The "green" led (normally used to indicate IR transmission) LTW_LED_VLL The red led, normally used to carry out VLL communications |
| HIBYTE(wValue) | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_SET_LED_REPLY) |

Response

The response is a LTW_REQ_GET_SET_LED_REPLY structure:

| | |
|------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| bLedID | Same as LOBYTE(wValue) |
| bColor | Color code: LTW_LED_COLOR_ON Led is switched on. LTW_LED_COLOR_OFF Led is switched off. LTW_LED_COLOR_DEFAULT Same as COLOR_ON LTW_LED_COLOR_BLACK Same as COLOR_OFF LTW_LED_COLOR_GREEN LTW_LED_COLOR_YELLOW LTW_LED_COLOR_ORANGE LTW_LED_COLOR_RED Same as ON on the current firmware. It could indicate a specific color if a multicolour led is used in the future. |

SET_TX_SPEED/SET_RX_SPEED

Description

Set IR transmit/receive speed.

Different receiver speed:

If you want to receive at a different speed than the transmission, you have to send a SET_RX_SPEED after you send the SET_TX_SPEED.

Different carrier frequency:

By default, the frequency is set to 38 kHz when you choose 2400 baud and 76 kHz when you choose 4800 baud. If you want to send at a different carrier frequency than the default you have to send a SET_TX_CARRIER_FREQUENCY.

IF YOU NEED TO SET NON STANDARD CARRIER FREQUENCY/DUTY CYCLE VALUES, YOU WANT TO DO IT **AFTER** HAVING SET THE BAUD RATE, SINCE SETTING THE BAUD RATE AUTOMATICALLY REVERTS TO THE DEFAULT FREQUENCY/DUTY CYCLE VALUES FOR THAT SPEED.

Different carrier duty cycle:

By default the duty cycle is set according to the table in SET_TX_CARRIER_DUTY_CYCLE. If you want to send with a different carrier duty cycle than the default you have to send a SET_TX_CARRIER_DUTY_CYCLE.

Purpose

Used to switch between IR transmission baud rates: 2400, 4800 baud and others depending on the capability of the Tower.

Parameters

| | |
|---------|---|
| wValue | Speed indicator. One of the following constants: SPEED_COMM_BAUD_1200 SPEED_COMM_BAUD_2400 SPEED_COMM_BAUD_4800 SPEED_COMM_BAUD_9600 SPEED_COMM_BAUD_19200 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_SET_SPEED_REPLY) |

Response

The response is a LTW_REQ_GET_SET_TX_SPEED_REPLY structure:

| | |
|------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| wTxSpeed | Same as wValue |

GET_TX_SPEED/GET_RX_SPEED

Description

Get current IR transmit/receive speed.

Purpose

Used to check the current IR transmission speed

Parameters

| | |
|---------|--|
| wValue | Not Used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_SET_SPEED_REPLY) |

Response

The response is a LTW_REQ_GET_SET_TX_SPEED_REPLY structure:

| | |
|------------|---|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| wTxSpeed | Speed indicator. One of the following constants: SPEED_COMM_BAUD_1200 SPEED_COMM_BAUD_2400 SPEED_COMM_BAUD_4800 SPEED_COMM_BAUD_9600 SPEED_COMM_BAUD_19200 |

GET_TX_STATE

Description

Get actual state of the transmitter:

1. Ready (transmitter buffer is empty, ready to receive more data to send)
2. Busy (busy sending)

Purpose

Used for communication flow control

Parameters

| | |
|----------------|---|
| LOBYTE(wValue) | Not used; set to 0 |
| HIBYTE(wValue) | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_TX_STATE_REPLY) |

Response

The response is a LTW_REQ_GET_TX_STATE_REPLY structure:

| | |
|------------|---|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| bTxState | CAPS_TX_STATE_READY or CAPS_TX_STATE_BUSY |
| bSpare2 | Not used |

SET_TX_CARRIER_FREQUENCY

Description

There are two default carrier frequencies connected to the transmission speed:

1. 38 kHz at 2400 baud
2. 76 kHz at 4800 baud

It is possible to get the supported frequency range for the device by asking for its capabilities (see the GET_CAPS request).

Purpose

Prepared for future changes

Parameters

| | |
|----------------|--|
| LOBYTE(wValue) | New frequency, in kHz |
| HIBYTE(wValue) | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_SET_CARRIER_FREQUENCY_REPLY) |

Response

The response is a LTW_REQ_GET_SET_CARRIER_FREQUENCY_REPLY structure:

| | |
|--------------|---|
| wNoOfBytes | No. of bytes contained in the structure |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| bTxFrequency | Same as LOBYTE(wValue) above |
| bSpare2 | Not used |

GET_TX_CARRIER_FREQUENCY

Description

Get current transmission carrier frequency.

Purpose

Prepared for future changes.

Parameters

| | |
|----------------|--|
| LOBYTE(wValue) | Not used; set to 0 |
| HIBYTE(wValue) | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_SET_CARRIER_FREQUENCY_REPLY) |

Response

The response is a LTW_REQ_GET_SET_CARRIER_FREQUENCY_REPLY structure:

| | |
|--------------|--|
| wNoOfBytes | No. of bytes contained in the structure |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| bTxFrequency | Current transmission carrier frequency, in kHz |
| bSpare2 | Not used |

SET_TX_CARRIER_DUTY_CYCLE

Description

Set transmission carrier duty cycle for the specified transmission range. The firmware is able to set a different duty cycle for each transmission range (in fact, the duty cycle values **affects** the actual range of the device).

The carrier duty cycle will by default be set to the following values if you are using the default carrier frequencies 38 and 76 kHz:

| Frequency/Range | Short | Medium | Long |
|-----------------|--------------|--------------|--------------|
| 38 kHz | 8,00 μ s | 2,50 μ s | 8,00 μ s |
| 76 kHz | 4,00 μ s | 1,25 μ s | 4,00 μ s |

Be careful in playing with these values, as they heavily affects the amount of power drawn from the USB bus – therefore wrong values could send the tower out-of-specs.

Purpose

Prepared for future changes.

Parameters

| | |
|---------|--|
| wValue | New duty cycle, in 1/100s of microsecond (μ s) |
| wIndex | Range to which the new duty cycle is to be applied. One of the following: LTW_RANGE_SHORT LTW_RANGE_MEDIUM LTW_RANGE_LONG |
| wLength | at least sizeof(LTW_REQ_GET_SET_CARRIER_DUTY_CYCLE_REPLY) |

Response

The response is a LTW_REQ_GET_SET_CARRIER_DUTY_CYCLE_REPLY structure:

| | |
|--------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| bTxRange | Range (same as wIndex, above) |
| bSpare2 | Not used |
| wTxDutyCycle | New duty cycle value (same as wValue, above) |

GET_TX_CARRIER_DUTY_CYCLE

Description

Get transmission carrier duty cycle for the given range

Purpose

Prepared for future changes.

Parameters

| | |
|---------|--|
| wValue | Not used; set to 0 |
| wIndex | Range for which we are querying the duty cycle. One of the following: LTW_RANGE_SHORT LTW_RANGE_MEDIUM LTW_RANGE_LONG |
| wLength | at least sizeof(LTW_REQ_GET_SET_CARRIER_DUTY_CYCLE_REPLY) |

Response

The response is a LTW_REQ_GET_SET_CARRIER_DUTY_CYCLE_REPLY structure:

| | |
|--------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| bTxRange | Range (same as wIndex, above) |
| bSpare2 | Not used |
| wTxDutyCycle | Current duty cycle value (same as wValue, above) |

GET_CAPS

Description

Get a list of the Tower capabilities according to the requested link type.

Purpose:

Used by the Host driver to get the capabilities of the Tower. In that way the Tower can be compatible with future versions of the Host driver that supports new Towers and other communication devices.

Parameters

| | |
|---------|--|
| wValue | Link type for which capabilities are requested. One of the following: LTW_CAPS_IR LTW_CAPS_VLL LTW_CAPS_IRC LTW_CAPS_RADIO (not supported currently) |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_CAPS_REPLY) |

Response

The response is a LTW_REQ_GET_CAPS_REPLY structure:

| | |
|--|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| bCommDirections | CAPS_COMM_DIRECTIONS_TRANSMIT and/or CAPS_COMM_DIRECTIONS_RECEIVE (they can be ORred together) |
| bCommRange | Ranges supported (can be ORred together): LTW_CAPS_RANGE_SHORT LTW_CAPS_RANGE_MEDIUM LTW_CAPS_RANGE_LONG |
| wCommTransmitRate | Supported Transmit speeds: CAPS_COMM_BAUD_1200 CAPS_COMM_BAUD_2400 CAPS_COMM_BAUD_4800 CAPS_COMM_BAUD_9600 CAPS_COMM_BAUD_19200 |
| wCommReceiveRate | Supported receive speed (same constants as above) |
| bCommTransmitMinFrequency bCommTransmitMaxFrequency | Minimum and maximum carrier frequency |
| wCommTransmitMinDutyCycle wCommTransmitMaxDutyCycle | Minimum and maximum duty cycle values (applicable to all ranges) |
| bNoOfBytesInUartTxBuffer | Maximum size of the internal UART Transmit buffer |
| bNoOfBytesInUartRxBuffer | Maximum size of the internal UART Transmit buffer |

GET_VERSION

Description

Get firmware version information.

Purpose

Version control.

Parameters

| | |
|---------|--|
| wValue | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_VERSION_REPLY) |

Response

The response is a LTW_REQ_GET_VERSION_REPLY structure:

| | |
|---------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |
| bMajorVersion | Major version number |
| bMinorVersion | Minor version number |
| wBuildNo | Build number |

GET_COPYRIGHT

Description

Get copyright information.

Purpose

Used by the Host driver to identify the firmware as LEGO firmware.

Parameters

| | |
|---------|--|
| wValue | Not used; set to 0 |
| wIndex | Not used; set to 0 |
| wLength | at least sizeof(LTW_REQ_GET_COPYRIGHT_REPLY) plus a suitable size for the copyright string. |

Response

The response is a LTW_REQ_GET_COPYRIGHT_REPLY structure, followed by a non-NULL terminated UNICODE string containing copyright information.

If the size specified in the request is not enough to hold the whole copyright string, the firmware just replies with the requested amount of data (so a truncated string is returned).

| | |
|------------|--|
| wNoOfBytes | No. of bytes contained in the structure. |
| bErrCode | Error code (0 if success) |
| bSpare | Not used |

3.2 Firmware Vendor Request Reply Error Codes

The following table lists all the error that the firmware can return in the bErrCode field of the various vendor requests:

| Internal Error Code | Description |
|-----------------------|---|
| LTW_REQERR_SUCCESS | Request succeeded |
| LTW_REQERR_BADPARAM | Bad vendparameter and/or value |
| LTW_REQERR_BUSY | Tower is busy |
| LTW_REQERR_NOPOWER | Not enough power to carry out the requested operation |
| LTW_REQERR_WRONGMODE | Not in the right mode to execute this request |
| LTW_INTERNAL_ERROR | Internal error in the Tower |
| LTW_REQERR_BADREQUEST | Bad request |

3.3 Firmware Internal Error Codes

The following table lists all the internal errors that the firmware can return on the GET_PARM (LTW_PARM_ERRSTATUS) vendor requests. The internal error code is only set when a serious error occur.

| Error Code | Description |
|---------------------------------|---|
| LTW_NO_ERROR | No error |
| Function/parameter error | |
| LTW_NO_SUPPORT | No support for this function |
| LTW_ERR_VEND_REQ | Invalid vendor request |
| USB errors | |
| LTW_ERR_USB | Unspecified USB problem |
| LTW_ERR_USB_FUNC | Call to wrong USB function |
| LTW_ERR_USB_DATA | No or invalid data received |
| LTW_ERR_USB_ENDPOINT | Wrong endpoint |
| LTW_ERR_USB_PACKETSIZE | Invalid packetsize |
| LTW_ERR_USB_TX_EP0 | Error on sending on endpoint 0 |
| LTW_ERR_USB_EP0_PACKETSIZE | Tried to send more than MAXPACKETSIZE on endpoint 0 |
| LTW_ERR_USB_EP1_PACKETSIZE | Tried to send more than MAXPACKETSIZE on endpoint 1 |
| LTW_ERR_USB_VEND_BUFF_FULL | Answer buffer full |
| UART errors | |
| LTW_ERR_UART | SW UART problems |
| LTW_ERR_UART_MODE | Invalid UART mode |
| LTW_ERR_UART_TX_STATE | Invalid TX state |
| Tower errors | |
| LTW_ERR_TOWER | Tower out of order 0 |
| LTW_ERR_UNDEFINED | Undefined error |

3.4 Constant Definitions

This section contains the numeric definitions of the constants mentioned in this document. This information is included here for completeness only. For actual coding, you should refer to the *VendReq.h* header file (provided by LEGO), which also contains types and structure definitions.

```

////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
//
//                                VENDOR REQUESTS TYPES
//
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////

// USB Vendor requests
//
#define LTW_REQ_GET_PARM                0x01 // Get parameter for standard IR mode
#define LTW_REQ_SET_PARM                0x02 // Set parameter for standard IR mode
#define LTW_REQ_FLUSH                   0x03 // Flush UART buffers
#define LTW_REQ_RESET                   0x04 // Performing a user reset
#define LTW_REQ_GET_STAT                0x05 // Get statistics on IR receiver
#define LTW_REQ_GET_POWER               0x06 // Get current powermode
#define LTW_REQ_GET_LED                 0x08 // Get led state and color
#define LTW_REQ_SET_LED                 0x09 // Switch on/off led + color of led
#define LTW_REQ_RESET_STAT              0x10 // Reset statistics on IR receiver
#define LTW_REQ_GET_PARM_IRC            0x11 // Get parameter for IRC mode
#define LTW_REQ_SET_PARM_IRC            0x12 // Set parameter for IRC mode
#define LTW_REQ_GET_TX_SPEED            0xEE // Get IR transmission speed
#define LTW_REQ_SET_TX_SPEED            0xEF // Set IR transmission speed
#define LTW_REQ_GET_RX_SPEED            0xF0 // Get IR receiving speed
#define LTW_REQ_SET_RX_SPEED            0xF1 // Set IR receiving speed
#define LTW_REQ_GET_TX_STATE            0xF2 // Get state of the transmitter
#define LTW_REQ_GET_TX_CARRIER_FREQUENCY 0xF3 // Set transmission carrier frequency
#define LTW_REQ_SET_TX_CARRIER_FREQUENCY 0xF4 // Set transmission carrier frequency
#define LTW_REQ_GET_TX_CARRIER_DUTY_CYCLE 0xF5 // Set transmission carrier dutycycle
#define LTW_REQ_SET_TX_CARRIER_DUTY_CYCLE 0xF6 // Set transmission carrier dutycycle
#define LTW_REQ_GET_CAPS                 0xFC // Get capabilities
#define LTW_REQ_GET_VERSION              0xFD // Get version information
#define LTW_REQ_GET_COPYRIGHT            0xFE // Get copyright information
#define LTW_REQ_GET_CREDITS              0xFF // Credits list

// Request return codes (bLtwErrCode in the reply format)
//
#define LTW_REQERR_SUCCESS                0x00 // Request succeeded
#define LTW_REQERR_BADPARAM              0x01 // Bad vendparameter and/or value
#define LTW_REQERR_BUSY                  0x02 // Tower is busy
#define LTW_REQERR_NOPOWER                0x03 // Not enough power (current)
#define LTW_REQERR_WRONGMODE              0x04 // Not in the right mode
#define LTW_INTERNAL_ERROR                0xFE // Internal error in the Tower
#define LTW_REQERR_BADREQUEST            0xFF // Bad request

// Bad request reply format
//
typedef struct LTW_REQ_BAD_REPLY
{
    Word wNoOfBytes; // Number of bytes in the reply
    Byte bErrCode;   // Request return code
    Byte bSpares;    // Structure padding byte
} LTW_REQ_BAD_REPLY;

////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
//
//                                VENDOR REQUEST: GET_PARM and SET_PARM
//
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////

// -----
// Parameter (1 byte) and value (1 byte) for GET_PARM and SET_PARM request
//
// The parameter code goes in the low-order byte of wvalue. the value (argument)
// for the request goes into the high-order byte. windex is reserved for future
// use.
//

#define LTW_PARM_MODE                0x01 // Tower mode:
    #define LTW_MODE_VLL              0x01 // - Send VLL
    #define LTW_MODE_IR               0x02 // - Send/Receive IR
    #define LTW_MODE_IRC              0x04 // - Send/Receive IR (Technic protocol)
    #define LTW_MODE_RADIO             0x08 // Send/Receive Radio signals

#define LTW_PARM_RANGE                0x02 // Transmission range:
    #define LTW_RANGE_SHORT            0x01 // - Short
    #define LTW_RANGE_MEDIUM           0x02 // - Medium

```

```

#define LTW_RANGE_LONG          0x03    // - Long

#define LTW_PARM_ERRDETECT      0x03    // Error detection on IR receiver:
#define LTW_ERRDETECT_ON       0x01    // - on
#define LTW_ERRDETECT_OFF      0x02    // - off

#define LTW_PARM_ERRSTATUS      0x04    // Current internal errorcode:
#define LTW_NO_ERROR           0        // - No error
#define LTW_NO_SUPPORT         1        // - No support for this function
#define LTW_ERR_VEND_REQ       10       // - Invalid vendor request

// USB errors
#define LTW_ERR_USB            100      // - Unspecified USB problem
#define LTW_ERR_USB_FUNC       101      // - Call to wrong USB function
#define LTW_ERR_USB_DATA       102      // - No or invalid data received
#define LTW_ERR_USB_ENDPOINT   103      // - Wrong endpoint
#define LTW_ERR_USB_PACKETSIZE 104      // - Invalid packet size
#define LTW_ERR_USB_TX_EP0      105      // - Error on sending on endpoint 0
#define LTW_ERR_USB_EP0_PACKETSIZE 106  // - Wrong packet size on EP0
#define LTW_ERR_USB_EP1_PACKETSIZE 107  // - Wrong packet size on EP1
#define LTW_ERR_USB_VEND_BUFF_FULL 108  // - Vendor answer buffer full
#define LTW_ERR_USB_TX_EP1     109      // - Send error on endpoint 1

// UART errors
#define LTW_ERR_UART           200      // - UART problems
#define LTW_ERR_UART_MODE      201      // - Invalid UART mode
#define LTW_ERR_UART_TX_STATE  210      // - Invalid TX state
#define LTW_ERR_UART_LOW_POWER 211      // - Tried to send in long range when
// configured as a low power device

// Tower errors
#define LTW_ERR_TOWER          240      // - Tower out of order
#define LTW_ERR_UNDEFINED      255      // - undefined error

#define LTW_PARM_ENDIAN        0x97    // Endian (word-format):
#define LTW_ENDIAN_LITTLE      0x01    // - Little endian
#define LTW_ENDIAN_BIG         0x02    // - Big endian

#define LTW_PARM_ID_LED_MODE    0x98    // Indicator LED control mode:
#define LTW_ID_LED_HW_CTRL     0x01    // - LED controlled by firmware
#define LTW_ID_LED_SW_CTRL     0x02    // - LED controlled by the host

#define LTW_PARM_ERROR_SIGNAL   0x99    // Signal on internal error:
#define LTW_ID_LED_ON          0x01    // - Indicator LED will be switched
// on when a serious error occurs
#define LTW_ID_LED_OFF         0x02    // - Indicator LED will NOT be
// on when a serious error occurs

// -----
// Reply format
//
// All vendor request replies from the tower start with the following
// four bytes:
//

typedef struct LTW_REQ_REPLY_HEADER
{
    Word wNoOfBytes;           // Number of bytes in the reply
    Byte bErrCode;             // Request return code
    Byte bValue;               // Request return value
} LTW_REQ_REPLY_HEADER;

typedef LTW_REQ_REPLY_HEADER LTW_REQ_GET_SET_PARM_REPLY;

// =====
//
// VENDOR REQUEST: SET_PARM_IRC and GET_PARM_IRC
// =====

#define LTW_PARM_IRC_PACKETSIZE 0x01    // Packet size, in bytes (default = 2)
#define LTW_PARM_IRC_TIMEFRAME 0x02    // Time frame for packet sync, in ms(def=80)

```

```
typedef LTW_REQ_REPLY_HEADER LTW_REQ_GET_SET_PARM_IRC_REPLY;

////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
//
//                                VENDOR REQUEST: FLUSH
//
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////

//
// -----
//
// Combined parameter and value in 2 bytes for FLUSH request
//
//
// Format: 1. byte = Buffer no. as they are defined under SET_LED request, 2. byte = 00
//
// -----
//
// Parameter: Buffer no. This goes into the low-order byte of the wvalue field
// of the request's setup packet
//
//
#define LTW_TX_BUFFER          0x01          // Transmission buffer
#define LTW_RX_BUFFER          0x02          // Receiver buffer
#define LTW_ALL_BUFFERS        0x03          // All buffers

// -----
// Reply format
//
typedef struct LTW_REQ_FLUSH_REPLY
{
    Word  wNoOfBytes;          // Number of bytes in the reply
    Byte  bErrCode;           // Request return code
    Byte  bBufferno;           // Flushed bufferno.
} LTW_REQ_FLUSH_REPLY;

////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
//
//                                VENDOR REQUEST: RESET
//
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////

//
// No request parameter or value
//
//
// -----
// Reply format
//
//
typedef struct LTW_REQ_RESET_REPLY
{
    Word  wNoOfBytes;          // Number of bytes in the reply
    Byte  bErrCode;           // Request return code
    Byte  bSpare;              // Spare byte to obtain an even number of bytes
} LTW_REQ_RESET_REPLY;

////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////
//
//                                VENDOR REQUEST: GET_STAT
//
////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////////

//
// No request parameter or value
//
//
// -----
// Reply format
//
//
typedef struct LTW_REQ_GET_STAT_REPLY
{
    Word  wNoOfBytes;          // Number of bytes in the reply
    Byte  bErrCode;           // Request return code
    Byte  bSpare;              // Spare byte to obtain an even number of bytes

    Word  wNoOfRxBytes;        // Number of received bytes
    Word  wOverrunErrorCount;   // # of times overrun error has happen
    Word  wNoiseCount;         // # of bytes with wrong bits
    Word  wFramingErrorCount;   // # of bytes with framing errors
} LTW_REQ_GET_STAT_REPLY;
```

```

////////////////////////////////////
//                                VENDOR REQUESTS: GET_POWER
////////////////////////////////////

//      No request parameter or value
//

// -----
// Reply format
//
typedef struct LTW_REQ_GET_POWER_REPLY
{
    Word wNoOfBytes;    // Number of bytes in the reply
    Byte bErrCode;      // Request return code
    Byte bSpare;        // Spare byte to obtain an even number of bytes

    Byte bPower;        // Powermode (POWER_LOW or POWER_HIGH)
#define LTW_POWER_LOW    0x01    // - Tower is set to low power device
#define LTW_POWER_HIGH  0x02    // - Tower is set to high power device
    Byte bSpare2;

} LTW_REQ_GET_POWER_REPLY;

////////////////////////////////////
//                                VENDOR REQUEST: SET_LED and GET_LED
////////////////////////////////////

// -----
// Parameter (1 byte) and value (1 byte) for SET_LED request
//
// Parameter: Led no. This goes into the low-order byte of the wvalue field of the
//            request's setup packet
//
#define LTW_LED_ID                0x01 // ID LED
#define LTW_LED_VLL              0x02 // VLL LED

//      Value:      Led color  This goes into the high-order byte of the wvalue field of
//                          the request's setup packet
//
//      COLOR identifiers (low order bytes in the value field of the request)
//      if a color not supported by the hardware is used, the firmware approximates
//      to the nearest one. The current USB Tower version supports only Green color.
//
#define LTW_LED_COLOR_BLACK      0x00 // Black = same as off
#define LTW_LED_COLOR_GREEN      0x01 // Green
#define LTW_LED_COLOR_YELLOW     0x02 // Yellow
#define LTW_LED_COLOR_ORANGE     0x04 // Orange
#define LTW_LED_COLOR_RED        0x08 // Red
//
//      more color codes can be added here...
//
#define LTW_LED_COLOR_DEFAULT    0xFF // Whatever color is the default

#define LTW_LED_COLOR_ON         LTW_LED_COLOR_DEFAULT // generic ON
#define LTW_LED_COLOR_OFF        LTW_LED_COLOR_BLACK  // generic OFF

// -----
// Reply format
//
typedef struct LTW_REQ_GET_SET_LED_REPLY
{
    Word wNoOfBytes;    // Number of bytes in the reply
    Byte bErrCode;      // Request return code
    Byte bSpare;        // Spare byte to obtain an even number of bytes

    Byte bLedId;        // See parameter
    Byte bColor;        // See value
} LTW_REQ_GET_SET_LED_REPLY;

```



```
//
//          VENDOR REQUEST: RESET_STAT
//
//
//          No request parameter or value
//
//
//          -----
// Reply format
//
typedef struct LTW_REQ_RESET_STAT_REPLY
{ Word wNoOfBytes;    // Number of bytes in the reply
  Byte bErrCode;      // Request return code
  Byte bSpare;        // Used only for having a even number of bytes in the reply
} LTW_REQ_RESET_STAT_REPLY;

//
//          VENDOR REQUEST: GET_PARM_IRC and SET_PARM_IRC
//
//
//          -----
// Parameter (1 byte) and value (1 byte) for GET_PARM_IRC and SET_PARM_IRC request
//
// The parameter code goes in the low-order byte of wvalue. the value (argument)
// for the request goes into the high-order byte. windex is reserved for future
// use.
//
//
#define LTW_PARM_IRC_PACKETSIZE 0x01 // IRC packetsize
// Value: Packetsize in bytes

#define LTW_PARM_IRC_DELAY_TX 0x02 // Delay between packets to send
// Value: Transmit delay time between packets in ms.

//
//          -----
// Reply format
//
typedef LTW_REQ_REPLY_HEADER LTW_REQ_GET_SET_PARM_IRC_REPLY;

//
//          VENDOR REQUESTS: GET and SET_TX_SPEED
//
//
//          -----
// Combined parameter and value in 2 bytes for GET and SET_TX_SPEED request
//
#define SPEED_COMM_BAUD_1200          CAPS_COMM_BAUD_1200
#define SPEED_COMM_BAUD_2400          CAPS_COMM_BAUD_2400
#define SPEED_COMM_BAUD_4800          CAPS_COMM_BAUD_4800
#define SPEED_COMM_BAUD_9600          CAPS_COMM_BAUD_9600
#define SPEED_COMM_BAUD_19200         CAPS_COMM_BAUD_19200

//
//          -----
// Reply format
//
typedef struct LTW_REQ_GET_SET_TX_SPEED_REPLY
{ Word wNoOfBytes;    // Number of bytes in the reply
  Byte bErrCode;      // Request return code
  Byte bSpare;        // Spare byte to obtain an even number of bytes

  Word wTxSpeed;      // Transmission speed
} LTW_REQ_GET_SET_TX_SPEED_REPLY;

//
//          VENDOR REQUESTS: GET and SET_RX_SPEED
//
//
//          -----
```

```

//      Combined parameter and value in 2 bytes for GET and SET_RX_SPEED request
//
//  Same definitions as SET_TX_SPEED !

// -----
// Reply format
//
typedef struct LTW_REQ_GET_SET_RX_SPEED_REPLY
{
    Word wNoOfBytes;    // Number of bytes in the reply
    Byte bErrCode;      // Request return code
    Byte bSpare;        // Spare byte to obtain an even number of bytes

    Word wRxSpeed;      // Receiving speed
} LTW_REQ_GET_SET_RX_SPEED_REPLY;

/////////////////////////////////////////////////////////////////
//                                VENDOR REQUESTS: GET_TX_STATE
/////////////////////////////////////////////////////////////////

//      No request parameter or value
//

// -----
// Reply format
//
typedef struct LTW_REQ_GET_TX_STATE_REPLY
{
    Word wNoOfBytes;    // Number of bytes in the reply
    Byte bErrCode;      // Request return code
    Byte bSpare;        // Spare byte to obtain an even number of bytes

    Byte bTxState;      // Transmitter states:
#define CAPS_TX_STATE_READY    0x01    // - Transmitter buffer empty, Ready to
                                     //   receive more data to send
#define CAPS_TX_STATE_BUSY    0x02    // - Busy sending data

    Byte bSpare2;        // Spare byte to obtain an even number of bytes
} LTW_REQ_GET_TX_STATE_REPLY;

/////////////////////////////////////////////////////////////////
//                                VENDOR REQUESTS: SET_TX_CARRIER_FREQUENCY
/////////////////////////////////////////////////////////////////

// -----
//      Combined parameter and value in 2 bytes for SET_TX_CARRIER_FREQUENCY request
//
//  Parameter (1 byte):  frequency e.g.: 38 kHz = 38
//  Value      (1 bytes): 00

//      The parameter code goes in the low-order byte of wvalue. the value (argument)
//      for the request goes into the high-order byte. windex is reserved for future
//      use.

// -----
// Reply format
//
typedef struct LTW_REQ_GET_SET_TX_CARRIER_FREQUENCY_REPLY
{
    Word wNoOfBytes;    // Number of bytes in the reply
    Byte bErrCode;      // Request return code
    Byte bSpare;        // Spare byte to obtain an even number of bytes

    Byte bTxFrequency;  // Transmission frequency
    Byte bSpare2;        // Spare byte to obtain an even number of bytes
} LTW_REQ_GET_SET_TX_CARRIER_FREQUENCY_REPLY;

/////////////////////////////////////////////////////////////////
//                                VENDOR REQUESTS: SET_TX_CARRIER_DUTY_CYCLE
/////////////////////////////////////////////////////////////////

// -----
//      Parameter (1 byte) and value (1 byte) for SET_TX_CARRIER_DUTY_CYCLE request

```

```

//
//      Parameter: Range This goes into the low-order byte of the wvalue field of the
//                      request's setup packet
//
//      See LTW_PARM_RANGE for definitions.
//

//      Value:      Duty cycle This goes into the high-order byte of the wvalue field of
//                      the request's setup packet
//
//      Duty cycle in us multiplied by 10. E.g. 1,5 us = 15

// -----
// Reply format
//
typedef struct LTW_REQ_GET_SET_TX_CARRIER_DUTY_CYCLE_REPLY
{
    Word wNoOfBytes;        // Number of bytes in the reply
    Byte bErrCode;          // Request return code
    Byte bSpare;            // Spare byte to obtain an even number of bytes

    Byte bTxRange;          // Transmission range
    Byte bSpare2;

    Word wTxDutyCycle;      // Transmission dutycycle in this range in 1/10 of a ms.
} LTW_REQ_GET_SET_TX_CARRIER_DUTY_CYCLE_REPLY;

////////////////////////////////////
//      VENDOR REQUEST: GET_CAPS
////////////////////////////////////

// -----
//      Combined parameter and value in 2 bytes for GET_CAPS request
//

//      Supported communication modes
#define LTW_CAPS_VLL          LTW_MODE_VLL
#define LTW_CAPS_IR           LTW_MODE_IR
#define LTW_CAPS_IRC          LTW_MODE_IRC
#define LTW_CAPS_RADIO        LTW_MODE_RADIO

// -----
// Reply format
//
typedef struct LTW_REQ_GET_CAPS_REPLY
{
    Word wNoOfBytes;        // Number of bytes in the reply
    Byte bErrCode;          // Request return code
    Byte bSpare;            // Spare byte to obtain even number of bytes

    Byte bCommDirections;   // Communication directions:
#define CAPS_COMM_DIRECTION_TRANSMIT 0x01 // - Transmit
#define CAPS_COMM_DIRECTION_RECEIVE 0x02 // - Receive
#define CAPS_COMM_DIRECTION_BOTH    0x03 // - Both transmit and receive
    Byte bCommRange;        // Communication range:
#define CAPS_COMM_RANGE_SHORT        0x01 // - Short
#define CAPS_COMM_RANGE_MEDIUM       0x02 // - Medium
#define CAPS_COMM_RANGE_LONG         0x04 // - Long
#define CAPS_COMM_RANGE_ALL          0x07 // - short, medium and long range
    Word wCommTransmitRate;      // Communication transmit rate
                                   // (same definition as receive rate)
    Word wCommReceiveRate;      // Communication receive rate:
#define CAPS_COMM_BAUD_1200          0x0004 // - 1200 baud
#define CAPS_COMM_BAUD_2400          0x0008 // - 2400 baud
#define CAPS_COMM_BAUD_4800          0x0010 // - 4800 baud
#define CAPS_COMM_BAUD_9600          0x0020 // - 9600 baud
#define CAPS_COMM_BAUD_19200         0x0040 // - 19200 baud
    Byte bCommTransmitMinFrequency; // Minimum frequency between 30 and 99 kHz
                                   // E.g. 30 kHz = 30
    Byte bCommTransmitMaxFrequency; // Maximum frequency between 30 and 99 kHz.
                                   // E.g. 30 kHz = 30
    Word wCommTransmitMinDutyCycle; // Minimum duty cycle in us multiplied by

```

```

        Word wCommTransmitMaxDutyCycle;    // 100. E.g. 1,25 us = 125
        Byte bNoOfBytesInUartTxBuffer;     // Maximum duty cycle in us multiplied by
        Byte bNoOfBytesInUartRxBuffer;     // 100. E.g. 18,9 us = 1890
                                           // Number of bytes defined in the
                                           // transmitter buffer
                                           // Number of bytes defined in the
                                           // receiver buffer
    } LTW_REQ_GET_CAPS_REPLY;

// =====
//          VENDOR REQUEST: GET_VERSION
// =====

//      No request parameter or value
//

// -----
// Reply format
//
typedef struct LTW_REQ_GET_VERSION_REPLY
{
    Word wNoOfBytes;    // Number of bytes in the reply
    Byte bErrCode;      // Request return code
    Byte bSpare;        // Spare byte to obtain an even number of bytes

    Byte bMajorVersion; // Major version e.g. 1
    Byte bMinorVersion; // Minor version e.g. 01
    Word wBuildNo;      // Build no. e.g. 0112
} LTW_REQ_GET_VERSION_REPLY;

// =====
//          VENDOR REQUEST: GET_COPYRIGHT
// =====

//      No request parameter or value
//

// -----
// Reply format
//
typedef struct LTW_REQ_GET_COPYRIGHT_REPLY
{
    Word wNoOfBytes;    // Number of bytes in the reply
    Byte bErrCode;      // Request return code
    Byte bSpare;        // Spare byte to obtain an even number of bytes

    // Copyright string: placed in the Tower ROM -- NOT null-terminated
} LTW_REQ_GET_COPYRIGHT_REPLY;

#endif

```