

CS 229, Fall 2018

Problem Set #3 Solutions:

Deep Learning & Unsupervised learning

1. A Simple Neural Network

a) Gradient w.r.t $w_{1,2}^{[1]}$.

Denote the hidden layer output as o , the final output \tilde{y} . Forward propagation:

$$\begin{aligned} z^{[1]} &= W^{[1]T} x^{(i)} \\ o &= g(z^{[1]}) \\ z^{[2]} &= W^{[2]T} h \\ \tilde{y}^{(i)} &= g(z^{[2]}) \end{aligned}$$

Cost function:

$$\ell = \frac{1}{m} \sum_{i=1}^m (\tilde{y}^{(i)} - y^{(i)})^2$$

Derivative of $W^{(2)}$ ($W^{(2)} \in R^3$, $h \in R^3$, \tilde{y} and y are scalars).

$$\begin{aligned} \frac{\partial \ell}{\partial W^{[2]}} &= \frac{\partial}{\partial W^{[2]}} (\tilde{y}^{(i)} - y^{(i)})^2 \\ &= 2(\tilde{y}^{(i)} - y^{(i)}) \frac{\partial}{\partial W^{[2]}} (g(z^{[2]})) \\ &= 2(\tilde{y}^{(i)} - y^{(i)}) g(z^{[2]}) (1 - g(z^{[2]})) o \\ &= 2(\tilde{y}^{(i)} - y^{(i)}) \tilde{y}^{(i)} (1 - \tilde{y}^{(i)}) o \end{aligned}$$

Derivative of $W^{[1]} \in R^{2 \times 3}$, $\frac{\partial \ell}{\partial W^{[1]}}$ has the same dimension.

$$\begin{aligned} \frac{\partial \ell}{\partial W^{[1]}} &= \frac{\partial \ell}{\partial \tilde{y}} \frac{\partial \tilde{y}}{\partial z^{[2]}} \frac{\partial z^{[2]}}{\partial o} \frac{\partial o}{\partial z^{[1]}} \frac{\partial z^{[1]}}{\partial W^{[1]}} \\ &= 2(\tilde{y} - y) \tilde{y} (1 - \tilde{y}) W^{[2]} o (1 - o) \circ x \end{aligned}$$

Here \circ means outer product. Add subscription and sum up

$$\frac{\partial \ell}{\partial W_{1,2}^{[1]}} = \frac{1}{m} \sum_{i=1}^m 2(\tilde{y}^{(i)} - y^{(i)}) \tilde{y}^{(i)} (1 - \tilde{y}^{(i)}) W^{[2]} o^{(i)} (1 - o^{(i)}) \circ x^{(i)}$$

The update rule: $W_{1,2}^{[1]} = W_{1,2}^{[1]} - \alpha * \frac{\partial \ell}{\partial W_{1,2}^{[1]}}$

b) In the dataset plot, find three points clock wise which can form a triangle to separate the dataset in two:

$$\begin{aligned} a^{(1)} &= (0.5, 0.5) \\ a^{(2)} &= (0.5, 3.5) \end{aligned}$$

$$a^{(3)} = (3.5, 0.5)$$

Subtract with the next to form three vectors, and add intercept in front:

$$v^{(1)} = (0, -3.0)$$

$$v^{(2)} = (-3.0, 3.0)$$

$$v^{(3)} = (3.0, 0)$$

Equations for the above three vectors. For $v^{(1)}$ and $v^{(2)}$:

$$\frac{x_1 - a_1^{(2)}}{v_1^{(1)}} = \frac{x_2 - a_2^{(2)}}{v_2^{(1)}}$$

Which can be rewritten as:

$$v_2^{(1)} x_1 - v_1^{(1)} x_2 + (v_1^{(1)} a_2^{(2)} - v_2^{(1)} a_1^{(2)}) = 0$$

This gives us the first component of matrix $W^{[1]}$:

$$W_1^{[1]} = \begin{pmatrix} v_2^{(1)} \\ -v_1^{(1)} \\ v_1^{(1)} a_2^{(2)} - v_2^{(1)} a_1^{(2)} \end{pmatrix} = \begin{pmatrix} -3.0 \\ 0 \\ 1.5 \end{pmatrix}$$

Similarly, for $v^{(2)}$ and $v^{(3)}$ we have:

$$W_2^{[1]} = \begin{pmatrix} v_2^{(2)} \\ -v_1^{(2)} \\ v_1^{(2)} a_2^{(3)} - v_2^{(2)} a_1^{(3)} \end{pmatrix} = \begin{pmatrix} 3.0 \\ 3.0 \\ -12.0 \end{pmatrix}$$

And for $v^{(3)}$ and $v^{(1)}$ we have:

$$W_3^{[1]} = \begin{pmatrix} v_2^{(3)} \\ -v_1^{(3)} \\ v_1^{(3)} a_2^{(1)} - v_2^{(3)} a_1^{(1)} \end{pmatrix} = \begin{pmatrix} 0 \\ -3.0 \\ 1.5 \end{pmatrix}$$

Stack them to form a matrix $W^{[1]}$:

$$W^{[1]} = \begin{pmatrix} -3.0 & 3.0 & 0 \\ 0 & 3.0 & -3.0 \\ 1.5 & -12.0 & 1.5 \end{pmatrix}$$

Explanation: given any point x , if its projection on the normal of vector $v^{(i)}$ is positive then it is on the right hand of $v^{(i)}$, otherwise on the left. If it lies on the right of all the vectors, it is inside the triangle. (note the intercept is the last component of W which can be easily adjusted to be the first component)

Output layer matrix can be:

$$W^{[2]} = \begin{pmatrix} -1 \\ -1 \\ -1 \\ 2.5 \end{pmatrix}$$

Because the input can only be one of the eight values of h :

$$h = \begin{pmatrix} 0/1 \\ 0/1 \\ 0/1 \\ 1 \end{pmatrix}$$

This guarantees that only for dataset inside the triangle could the product $W^{[2]}h$ be negative, which will then make $f(x) = 0$. All the other cases will have $W^{[2]}h \geq 0$, which makes $f(x) = 1$.

- c) The activation function for h_1, h_2, h_3 is changed to $f(x) = x$, provide a set of weights that makes it achieve 100% accuracy.

Answer:

If the activation function is just $f(x)=x$, the NN is degraded to logistic regression. It is impossible to achieve 100% accuracy since the feature mappings doesn't include high order components. The decision boundary is going to be a straight line and will have misclassification.

2. KL divergence

2 KL divergence and Maximum Likelihood

(a) Nonnegativity

Prove the following:

$$\forall P, Q, D_{KL}(P \parallel Q) \geq 0$$

And

$$D_{KL}(P \parallel Q) = 0 \iff P = Q$$

PROOF 1:

$$\begin{aligned} D_{KL}(P \parallel Q) &= \sum_x P(x) \log \frac{P(x)}{Q(x)} \\ &= -\sum_x P(x) \log \frac{Q(x)}{P(x)} \\ &>= -\log\left(\sum_x P(x) \frac{Q(x)}{P(x)}\right) \\ &= -\log\left(\sum_x Q(x)\right) \\ &= -\log(1) = 0 \end{aligned}$$

PROOF 2:

$$D_{KL}(P \parallel Q) = 0 \iff P = Q$$

a. If $P = Q$, $D_{KL}(P \parallel Q) = \sum_{x \in X} P \log \frac{P}{Q} = \sum_{x \in X} P \log(1) = 0$

b. If $D_{KL}(P \parallel Q) = 0$, given $-\log x$ is strictly convex, then

$$\begin{aligned} E[-\log(\frac{P}{Q})] &\geq -\log(E[\frac{P}{Q}]) = 0 \\ &= \log(E[\frac{Q}{P}]) \\ &= \log(\sum [P \frac{Q}{P}]) \\ &= \log(1) \\ &= 0 \end{aligned}$$

The equality holds iff $\frac{Q}{P}$ is a constant with probability 1, given the fact that both P and Q are pdf, we can only have $P = Q$.

(b) Chain rule for KL divergence

Prove that:

$$D_{KL}(P(X, Y) \parallel Q(X, Y)) = D_{KL}(P(X) \parallel Q(X)) + D_{KL}(P(Y|X) \parallel Q(Y|X))$$

PROOF:

$$\begin{aligned} D_{KL}(P(X) \parallel Q(X)) + D_{KL}(P(Y|X) \parallel Q(Y|X)) &= \sum_x P(x) \log \frac{P(x)}{Q(x)} + \sum_x P(x) \left(\sum_y P(y|x) \log \frac{P(y|x)}{Q(y|x)} \right) \\ &= \sum_x P(x) \left(\log \frac{P(x)}{Q(x)} + \sum_y P(y|x) \log \frac{P(y|x)}{Q(y|x)} \right) \\ &= \sum_x P(x) \left(\sum_y P(y|x) \log \frac{P(x)}{Q(x)} + \sum_y P(y|x) \log \frac{P(y|x)}{Q(y|x)} \right) \\ &= \sum_x P(x) \left(\sum_y P(y|x) \left(\log \frac{P(x)}{Q(x)} + \log \frac{P(y|x)}{Q(y|x)} \right) \right) \\ &= \sum_x \left(\sum_y P(y|x) P(x) \log \frac{P(x) P(y|x)}{Q(x) Q(y|x)} \right) \\ &= \sum_x \sum_y P(x, y) \log \frac{P(x, y)}{Q(x, y)} \\ &= D_{KL}(P(X, Y) \parallel Q(X, Y)) \end{aligned}$$

(c) KL and maximum likelihood

Prove that

$$\begin{aligned}\arg \min_{\theta} D_{KL}(\hat{P} \parallel P_{\theta}) &= \arg \max_{\theta} \sum_{i=1}^m \log P_{\theta}(x^{(i)}) \\ D_{KL}(\hat{P} \parallel P_{\theta}) &= \sum_x \hat{P}(x) \log \frac{\hat{P}(x)}{P_{\theta}(x)} \\ &= - \sum_x \hat{P}(x) \log \frac{P_{\theta}(x)}{\hat{P}(x)} \\ &= - \sum_x \frac{1}{m} \sum_{i=1}^m 1\{x^{(i)} = x\} \log \frac{P_{\theta}(x)}{\frac{1}{m} \sum_{i=1}^m 1\{x^{(i)} = x\}} \\ &= - \frac{1}{m} \sum_{i=1}^m \log \frac{P_{\theta}(x^{(i)})}{\frac{1}{m} \sum_{i=1}^m 1\{x^{(i)} = x\}} \\ &= - \frac{1}{m} \sum_{i=1}^m \log P_{\theta}(x^{(i)}) \\ &= - \frac{1}{m} \text{log-likelihood}\end{aligned}$$

Which implies that

$$\arg \min_{\theta} D_{KL}(\hat{P} \parallel P_{\theta}) = \arg \max_{\theta} \sum_{i=1}^m \log P_{\theta}(x^{(i)})$$

3. KL divergence, Fisher Information, Natural gradient

(For simplicity, $\nabla_{\theta'} \log p(y; \theta') | \theta' = \theta$ is simply written as $\nabla_{\theta} \log p(y; \theta)$, $E_{y \sim p(y; \theta)}$ is sometimes simply written as E_{θ} as it is in some Statistics textbooks.)

PS3.3 [For simplicity, $\nabla_{\theta'} \log p(y; \theta') | \theta' = \theta$ is sometimes written as $\nabla_{\theta} \log p(y; \theta)$ directly]

(a) Suppose the score function is

$$s(y; \theta) = \nabla_{\theta} \log p(y; \theta);$$

prove that: ~~E_{θ}~~

$$E_{y \sim p(y; \theta)} [s(y; \theta') | \theta' = \theta] = 0$$

PROOF:

$$\begin{aligned} E_{y \sim p(y; \theta)} [s(y; \theta') | \theta' = \theta] &= \int p(y; \theta) s(y; \theta) dy \\ &= \int p(y; \theta) \nabla_{\theta} \log p(y; \theta) dy = \int p(y; \theta) \cdot \frac{1}{p(y; \theta)} \cdot \frac{\partial p(y; \theta)}{\partial \theta} dy \\ &= \frac{\partial}{\partial \theta} \int p(y; \theta) dy = \frac{\partial}{\partial \theta} (1) = 0. \quad \text{Done.} \end{aligned}$$

(b) Fisher Information:

$$I(\theta) = \text{Cov}_{y \sim p(y; \theta)} [\nabla_{\theta} \log p(y; \theta') | \theta' = \theta]$$

show that

$$I(\theta) = E_{y \sim p(y; \theta)} [\nabla_{\theta} \log p(y; \theta) \nabla_{\theta} \log p(y; \theta)^T | \theta' = \theta]$$

PROOF: By definition of Covariance, Given a vector $X = \nabla_{\theta} \log p(y; \theta)$

$$\begin{aligned} I(\theta) &= \text{Cov}_{y \sim p(y; \theta)} [\nabla_{\theta} \log p(y; \theta') | \theta' = \theta] \\ &= E_{y \sim p(y; \theta)} [\nabla_{\theta} \log p(y; \theta') \nabla_{\theta} \log p(y; \theta')^T | \theta' = \theta] \\ &= E_{y \sim p(y; \theta)} [\nabla_{\theta} \log p(y; \theta)] \cdot E_{y \sim p(y; \theta)} [\nabla_{\theta} \log p(y; \theta)^T | \theta' = \theta] \\ &= E_{y \sim p(y; \theta)} [\nabla_{\theta} \log p(y; \theta) \nabla_{\theta} \log p(y; \theta)^T | \theta' = \theta] \end{aligned}$$

The last part is from the fact that $E_{y \sim p(y; \theta)} [s(y; \theta)] = 0$.

$$\text{Cov}(X) = \begin{bmatrix} E(X_1^2) - E(X_1)^2 & E(X_1 X_2) - E(X_1) E(X_2) & \dots & E(X_1 X_n) - E(X_1) E(X_n) \\ E(X_2 X_1) - E(X_2) E(X_1) & E(X_2^2) - E(X_2)^2 & \dots & E(X_2 X_n) - E(X_2) E(X_n) \\ \vdots & \vdots & \ddots & \vdots \\ E(X_n X_1) - E(X_n) E(X_1) & E(X_n X_2) - E(X_n) E(X_2) & \dots & E(X_n^2) - E(X_n)^2 \end{bmatrix}$$

From (a) we know that $E(X_i) = 0$; so:

$$\text{Cov}(X) = \begin{bmatrix} E(X_1^2) & E(X_1 X_2) & \dots & E(X_1 X_n) \\ E(X_2 X_1) & E(X_2^2) & \dots & E(X_2 X_n) \\ \vdots & \vdots & \ddots & \vdots \\ E(X_n X_1) & E(X_n X_2) & \dots & E(X_n^2) \end{bmatrix} = E \begin{bmatrix} X_1^2 & X_1 X_2 & \dots & X_1 X_n \\ X_2 X_1 & X_2^2 & \dots & X_2 X_n \\ \vdots & \vdots & \ddots & \vdots \\ X_n X_1 & X_n X_2 & \dots & X_n^2 \end{bmatrix}$$

$$= E[XX^T] \text{ replace } X = \nabla_{\theta} \log p(y; \theta) \big|_{\theta = \theta_0} \text{, Proved.}$$

(c) Show that:

$$I(\theta) = E_{y \sim p(y; \theta)} \left[-\nabla_{\theta}^2 \log p(y; \theta) \big|_{\theta = \theta_0} \right]$$

Proof:

$$\begin{aligned} \nabla_{\theta}^2 \log p(y; \theta) &= \nabla_{\theta} (\nabla_{\theta} \log p(y; \theta)) \\ &= \nabla_{\theta} (\nabla_{\theta} p(y; \theta) / p(y; \theta)) \\ &= \nabla_{\theta}^2 p(y; \theta) / p(y; \theta) - (\nabla_{\theta} p(y; \theta) / p(y; \theta)) (\nabla_{\theta} p(y; \theta) / p(y; \theta))^T \\ &= \nabla_{\theta}^2 p(y; \theta) / p(y; \theta) - (\nabla_{\theta} \log p(y; \theta)) (\nabla_{\theta} \log p(y; \theta))^T \end{aligned}$$

~~E~~ Sum over y on both sides:

$$E_{y \sim p(y; \theta)} [\nabla_{\theta}^2 \log p(y; \theta)] = E_{\theta} \left[\nabla_{\theta}^2 p(y; \theta) / p(y; \theta) \right] - E_{\theta} \left[\nabla_{\theta} \log p(y; \theta) \nabla_{\theta} \log p(y; \theta)^T \right]$$

Consider the first part of the right hand side:

$$\begin{aligned} E_{y \sim p(y; \theta)} [\nabla_{\theta}^2 p(y; \theta) / p(y; \theta)] &= \int p(y; \theta) \cdot \frac{\nabla_{\theta}^2 p(y; \theta)}{p(y; \theta)} dy \\ &= \int \nabla_{\theta}^2 p(y; \theta) dy = \nabla_{\theta}^2 \int p(y; \theta) dy = \nabla_{\theta}^2 (1) = 0; \end{aligned}$$

The second part of the right hand side:

$$E_{\theta} [\nabla_{\theta} \log p(y; \theta) \nabla_{\theta} \log p(y; \theta)^T] = I(\theta)$$

So:

$$E_{\theta} [\nabla_{\theta}^2 \log p(y; \theta)] = -I(\theta)$$

$$I(\theta) = E_{\theta} [-\nabla_{\theta}^2 \log p(y; \theta)] = E_{y \sim p(y; \theta)} \left[-\nabla_{\theta}^2 \log p(y; \theta) \big|_{\theta = \theta_0} \right]$$

Done!

$$(d) D_{KL}(P_0 \| P_0 + d) \approx \frac{1}{2} d^T I(\theta) d$$

PROOF:

$$D_{KL}(P_0 \| P_0 + d) = \mathbb{E}_0[\log P_0 - \log P_0 + d] = \mathbb{E}_0[\log P_0] - \mathbb{E}_0[\log P_0 + d]$$

Consider $\log P_0 + d$ using Taylor's expansion:

$$\log P_0 + d \approx \log P_0 + d^T \nabla \log P_0 + \frac{1}{2} d^T (\nabla^2 \log P_0) d$$

Sum over $y \sim p(y; \theta)$ for both sides:

$$\begin{aligned} \mathbb{E}_0[\log P_0 + d] &\approx \mathbb{E}_0[\log P_0] + \mathbb{E}_0[d^T \nabla \log P_0] + \mathbb{E}_0[\frac{1}{2} d^T (\nabla^2 \log P_0) d] \\ &= \mathbb{E}_0[\log P_0] + d^T \mathbb{E}_0[\nabla \log P_0] + \frac{1}{2} d^T \mathbb{E}_0[\nabla^2 \log P_0] d \\ &= \mathbb{E}_0[\log P_0] - \frac{1}{2} d^T I(\theta) d \end{aligned}$$

Which implies:

$$D_{KL}(P_0 \| P_0 + d) \approx \frac{1}{2} d^T I(\theta) d. \quad \text{done!}$$

$$(e) \ell(\theta) = \log p(y; \theta); \quad \theta \in \mathbb{R}^n;$$

From (d) above we have:

$$D_{KL}(P_0 \| P_0 + d) \approx \frac{1}{2} d^T I(\theta) d;$$

The Taylor expansion for $\ell(\theta + d) \approx \ell(\theta) + d^T \nabla \ell(\theta);$

the Original problem:

$$d^* = \arg \max \ell(\theta + d), \text{ s.t. } D_{KL}(P_0 \| P_0 + d) = c,$$

Replace both Taylor expansions:

$$d^* = \arg \max (\ell(\theta) + d^T \nabla \ell(\theta)), \text{ s.t. } D_{KL}(P_0 \| P_0 + d) = \frac{1}{2} d^T I(\theta) d = c$$

→ the Lagrangian is:

$$L(d, \lambda) = \ell(\theta) + d^T \nabla \ell(\theta) - \lambda \cdot (\frac{1}{2} d^T I(\theta) d - c)$$

→ Derivatives of linear equations:

$$\frac{\partial L}{\partial d} = \nabla \ell(\theta) - \lambda I(\theta) d = 0; \quad \textcircled{a}$$

$$\frac{\partial L}{\partial \lambda} = c - \frac{1}{2} d^T I(\theta) d = 0; \quad \textcircled{b}$$

→ From ①: $d = \lambda^{-1} I(\theta)^{-1} \nabla \ell(\theta);$

→ From plug d to ②:

$$\begin{aligned} c &= \frac{1}{2} (\lambda^{-1} I(\theta)^{-1} \nabla \ell(\theta))^T I(\theta) (\lambda^{-1} I(\theta)^{-1} \nabla \ell(\theta)) \\ &= \frac{1}{2\lambda^2} \nabla \ell(\theta)^T I(\theta)^{-1} I(\theta) I(\theta)^{-1} \nabla \ell(\theta) \\ &= \frac{1}{2\lambda^2} \nabla \ell(\theta)^T I(\theta)^{-1} \nabla \ell(\theta) \end{aligned}$$

$$\Rightarrow \lambda = \frac{1}{\sqrt{2c}} \sqrt{\nabla \ell(\theta)^T I(\theta)^{-1} \nabla \ell(\theta)}$$

Remove the '-T' part: use $(AB)^T = B^T A^T$ and the fact that the result is a scalar

→ plug λ above back to (a), get d^* :

$$d^* = \sqrt{C} \cdot (\nabla^2 \ell(\theta)^T I(\theta)^{-1} \nabla^2 \ell(\theta))^{\frac{1}{2}} I(\theta)^{-1} \nabla \ell(\theta)$$

 The dimension of d^* is easy to know: $d^* \in \mathbb{R}^n$;

(f) Relation to Newton's method.

Compare the two updates (Compare the Δ s for both)
 natural gradient: $\Delta = \lambda^{-1} \cdot I(\theta)^{-1} \nabla \ell(\theta)$;
 Newton's method: $\Delta \theta = H^{-1} \nabla \ell(\theta)$

The Hessian H is just given by:

$$H = \nabla^2 \ell(\theta)$$

~~$A = \text{Var}(y|\eta)XX^T$, this is already proved in ps1.4(c)~~
~~Also in ps1.4(c) we know:~~

in ps1.4(c) we already proved:

$\nabla^2 \ell(\theta) = \text{Var}(y|\eta)XX^T$ this is with natural variable $\eta = \theta^T X$; if
 we simply use $\eta = \theta$, we have:

$\nabla^2 \ell(\theta) = \text{Var}(y|\theta)$ which is just the same as $I(\theta)$;

λ^{-1} is simply a scalar. the direction is the same for both, because:
 $I(\theta)^{-1} = H^{-1}$;

4. Semi-supervised EM

4. Semi-supervised EM

(a) : PROOF.

For ease of hand writing, we $l(\theta)$ as $l_{\text{semi-sup}}(\theta)$.

Jensen's inequality tells us:

$$\begin{aligned} l(\theta) &= \sum_{i=1}^m \log \frac{1}{m} P(x^{(i)}, z^{(i)}; \theta) + \alpha \left(\sum_{i=1}^m \log P(\tilde{x}^{(i)}, \tilde{z}^{(i)}; \theta) \right) \\ &= \sum_{i=1}^m \log \frac{1}{m} \frac{Q(z^{(i)}) P(x^{(i)}, z^{(i)}; \theta)}{Q(z^{(i)})} + \alpha \left(\sum_{i=1}^m \log P(\tilde{x}^{(i)}, \tilde{z}^{(i)}; \theta) \right) \\ &\geq \sum_{i=1}^m \frac{Q(z^{(i)})}{m} \log \frac{P(x^{(i)}, z^{(i)}; \theta)}{Q(z^{(i)})} + \alpha \left(\sum_{i=1}^m \log P(\tilde{x}^{(i)}, \tilde{z}^{(i)}; \theta) \right) \end{aligned}$$

it is already shown in lecture note that the tight equality only happens when:

$$Q_i(z^{(i)}) = P(z^{(i)} | x^{(i)}; \theta), \text{ suppose } \theta$$

suppose $\theta^{(t)}$ is the current tight point, it means:

$$l(\theta^{(t)}) = \sum_{i=1}^m \frac{Q_i^{(t)}(z^{(i)})}{m} \log \frac{P(x^{(i)}, z^{(i)}; \theta^{(t)})}{Q_i^{(t)}(z^{(i)})} + \alpha \left(\sum_{i=1}^m \log P(\tilde{x}^{(i)}, \tilde{z}^{(i)}; \theta^{(t)}) \right)$$

For ~~any~~ parameter $\theta^{(t+1)}$ will have

$$l(\theta^{(t+1)}) \geq \sum_{i=1}^m \frac{Q_i^{(t+1)}(z^{(i)})}{m} \log \frac{P(x^{(i)}, z^{(i)}; \theta^{(t+1)})}{Q_i^{(t+1)}(z^{(i)})} + \alpha \left(\sum_{i=1}^m \log P(\tilde{x}^{(i)}, \tilde{z}^{(i)}; \theta^{(t+1)}) \right)$$

because the right part of the inequality is a lower bound of $l(\theta)$;

Consider the right part again, because $\theta^{(t+1)}$ is an $\arg \max_{\theta} g(\theta)$ (here denotes the above right part). we again have:

$$\begin{aligned} g &\geq \sum_{i=1}^m \frac{Q_i^{(t)}(z^{(i)})}{m} \log \frac{P(x^{(i)}, z^{(i)}; \theta^{(t+1)})}{Q_i^{(t)}(z^{(i)})} + \alpha \left(\sum_{i=1}^m \log P(\tilde{x}^{(i)}, \tilde{z}^{(i)}; \theta^{(t+1)}) \right) \\ &= l(\theta^{(t)}) \end{aligned}$$

So, $l(\theta^{(t+1)}) \geq l(\theta^{(t)})$. Done!

• Semi-supervised GMM

(b) $z^{(i)}$'s are the latent randoms which can take value $\{1, 2, \dots, k\}$

The updated values are:

$$w_j^{(i)} = Q_i(z^{(i)}=j) = p(z^{(i)}=j | x^{(i)}; \phi, \mu_j, \Sigma_j)$$

$$= \frac{p(x^{(i)} | z^{(i)}=j; \mu_j, \Sigma_j) p(z^{(i)}=j; \phi)}{\sum_{l=1}^k p(x^{(i)} | z^{(i)}=l; \mu_l, \Sigma_l) p(z^{(i)}=l; \phi)}$$

$$= \frac{\frac{1}{(2\pi)^{d/2} |\Sigma_j|^{1/2}} \exp\left(-\frac{1}{2}(x^{(i)} - \mu_j)^T \Sigma_j^{-1} (x^{(i)} - \mu_j)\right) \phi_j}{\sum_{l=1}^k \frac{1}{(2\pi)^{d/2} |\Sigma_l|^{1/2}} \exp\left(-\frac{1}{2}(x^{(i)} - \mu_l)^T \Sigma_l^{-1} (x^{(i)} - \mu_l)\right) \phi_l}$$

$$= \frac{\frac{1}{|\Sigma_j|^{1/2}} \exp\left(-\frac{1}{2}(x^{(i)} - \mu_j)^T \Sigma_j^{-1} (x^{(i)} - \mu_j)\right) \phi_j}{\sum_{l=1}^k \frac{1}{|\Sigma_l|^{1/2}} \exp\left(-\frac{1}{2}(x^{(i)} - \mu_l)^T \Sigma_l^{-1} (x^{(i)} - \mu_l)\right) \phi_l}$$

(The parameters are: $\mu_1, \mu_2, \dots, \mu_k, \Sigma_1, \Sigma_2, \dots, \Sigma_k, \phi_1, \phi_2, \dots, \phi_k$)

(c) in M-step, just plug $w_j^{(i)}$ to $Q(\theta)$ and take derivatives w.r.t μ, Σ and ϕ . The first part is the same as it is in lecture notes and we also need to plus the supervised part:

$$Q(\theta) = \sum_{i=1}^m \sum_{j=1}^k w_j^{(i)} Q_i(z^{(i)}) \log \frac{p(x^{(i)}, z^{(i)}; \phi, \mu, \Sigma)}{Q_i(z^{(i)})} + \alpha \left(\sum_{i=1}^m \log p(\tilde{x}^{(i)}, \tilde{z}^{(i)}; \tilde{\mu}, \tilde{\phi}, \tilde{\Sigma}) \right)$$

The above parameters are without subscripts, so add expand and add subscripts:

$$Q(\theta) = \sum_{i=1}^m \sum_{j=1}^k w_j^{(i)} \log \left(\frac{1}{(2\pi)^{d/2} |\Sigma_j|^{1/2}} \exp\left(-\frac{1}{2}(x^{(i)} - \mu_j)^T \Sigma_j^{-1} (x^{(i)} - \mu_j)\right) \phi_j / w_j^{(i)} \right) +$$

$$\alpha \left(\sum_{i=1}^m \log p(\tilde{x}^{(i)}, \tilde{z}^{(i)}; \phi_{\tilde{z}^{(i)}}, \mu_{\tilde{z}^{(i)}}, \Sigma_{\tilde{z}^{(i)}}) \right)$$

$$= \sum_{i=1}^m \sum_{j=1}^k w_j^{(i)} \log \left(\frac{1}{(2\pi)^{d/2} |\Sigma_j|^{1/2}} \exp\left(-\frac{1}{2}(x^{(i)} - \mu_j)^T \Sigma_j^{-1} (x^{(i)} - \mu_j)\right) \phi_j / w_j^{(i)} \right) +$$

$$\alpha \left(\sum_{i=1}^m \log \left(\frac{1}{(2\pi)^{d/2} |\Sigma_{\tilde{z}^{(i)}}|^{1/2}} \exp\left(-\frac{1}{2}(\tilde{x}^{(i)} - \mu_{\tilde{z}^{(i)}})^T \Sigma_{\tilde{z}^{(i)}}^{-1} (\tilde{x}^{(i)} - \mu_{\tilde{z}^{(i)}})\right) \phi_{\tilde{z}^{(i)}} \right) \right)$$

Take the derivative w.r.t μ_l , the first part is just the same as lecture notes, and the second part can be written out similar to the first part:

$$\nabla_{\mu_l} = \sum_{i=1}^m w_l^{(i)} (\Sigma_l^{-1} x^{(i)} - \Sigma_l^{-1} \mu_l) + \sum_{i=1}^m 1\{\tilde{z}^{(i)}=l\} (\Sigma_{\tilde{z}^{(i)}}^{-1} \tilde{x}^{(i)} - \Sigma_{\tilde{z}^{(i)}}^{-1} \mu_{\tilde{z}^{(i)}})$$

Set it to $\vec{0}$ and left multiply with Σ_l give us:

$$\sum_{i=1}^m w_l^{(i)} (x^{(i)} - \mu_l) + \sum_{i=1}^m 1\{\tilde{z}^{(i)}=l\} (\tilde{x}^{(i)} - \mu_l) = \vec{0}$$

$$\mu_l = \frac{\sum_{i=1}^m w_l^{(i)} x^{(i)} + \sum_{i=1}^m 1\{\tilde{z}^{(i)}=l\} \tilde{x}^{(i)}}{\sum_{i=1}^m w_l^{(i)} + \sum_{i=1}^m 1\{\tilde{z}^{(i)}=l\}}$$

Corrections: in (b)
 $\sqrt{2\pi}$ should be $(2\pi)^{\frac{n}{2}}$
 $|\Sigma_l|, |\Sigma_j|$ should be $|\Sigma_l|^{\frac{1}{2}}, |\Sigma_j|^{\frac{1}{2}}$

Correction: should have an 'α' in front of the 2nd term

~~Take derivative w.r.t ϕ_j :~~

Now derive the update rule for ϕ_j . Group all terms that depend on ϕ_j , we have the following:

$$\sum_{i=1}^m \sum_{j=1}^k W_j^{(i)} \log \phi_j + \cancel{2 \sum_{i=1}^m \log \phi_{\tilde{z}^{(i)}}} + 2 \sum_{i=1}^m \log \phi_{\tilde{z}^{(i)}}$$

Similar to lecture notes, the Lagrangian is:

$$L(\phi) = \sum_{i=1}^m \sum_{j=1}^k W_j^{(i)} \log \phi_j + 2 \sum_{i=1}^m \log \phi_{\tilde{z}^{(i)}} + \beta \left(\sum_{j=1}^k \phi_j - 1 \right)$$

Take derivative w.r.t ϕ_j :

$$\frac{\partial}{\partial \phi_j} = \sum_{i=1}^m \frac{W_j^{(i)}}{\phi_j} + 2 \sum_{i=1}^m \frac{\mathbb{1}_{\{\tilde{z}^{(i)}=j\}}}{\phi_j} + \beta = 0 \Rightarrow$$

$$\phi_j = \frac{\sum_{i=1}^m W_j^{(i)} + 2 \sum_{i=1}^m \mathbb{1}_{\{\tilde{z}^{(i)}=j\}}}{-\beta}$$

Use the fact that $\sum_{j=1}^k \phi_j = 1$, it's easy to come to:

$$\begin{aligned} -\beta &= \sum_{i=1}^m \sum_{j=1}^k W_j^{(i)} + 2 \sum_{i=1}^m \mathbb{1}_{\{\tilde{z}^{(i)} \in \{1, 2, \dots, k\}\}} \\ &= m + 2\tilde{m}, \end{aligned}$$

therefore:

$$\phi_j = \frac{\sum_{i=1}^m W_j^{(i)} + 2 \sum_{i=1}^m \mathbb{1}_{\{\tilde{z}^{(i)}=j\}}}{m + 2\tilde{m}}$$

Finally let's do Ξ_2 . Go to next page. \rightarrow

→

Terms related to Σ_j :

$$\begin{aligned}
 l(\theta) &= \sum_{i=1}^m \sum_{j=1}^K w_j^{(i)} \left(-\frac{1}{2} (\tilde{x}^{(i)} - \mu_j)^T \Sigma_j^{-1} (\tilde{x}^{(i)} - \mu_j) - \log \left(\frac{1}{2\pi} |\Sigma_j|^{1/2} \right) \right) \\
 &+ \alpha \left(\sum_{i=1}^m \sum_{j=1}^K \left(-\frac{1}{2} (\tilde{x}^{(i)} - \mu_{\tilde{z}^{(i)}})^T \Sigma_{\tilde{z}^{(i)}}^{-1} (\tilde{x}^{(i)} - \mu_{\tilde{z}^{(i)}}) - \log \left(\frac{1}{2\pi} |\Sigma_{\tilde{z}^{(i)}}|^{1/2} \right) \right) \right) \\
 &= -\sum_{i=1}^m \sum_{j=1}^K w_j^{(i)} \left(\frac{1}{2} (\tilde{x}^{(i)} - \mu_j)^T \Sigma_j^{-1} (\tilde{x}^{(i)} - \mu_j) + \frac{1}{2} \log(|\Sigma_j|) \right) \\
 &- \alpha \left(\sum_{i=1}^m \sum_{j=1}^K \left(\frac{1}{2} (\tilde{x}^{(i)} - \mu_{\tilde{z}^{(i)}})^T \Sigma_{\tilde{z}^{(i)}}^{-1} (\tilde{x}^{(i)} - \mu_{\tilde{z}^{(i)}}) + \frac{1}{2} \log(|\Sigma_{\tilde{z}^{(i)}}|) \right) \right)
 \end{aligned}$$

take derivative w.r.t Σ_ℓ , it's still an $n \times n$ matrix:

$$\begin{aligned}
 \nabla_{\Sigma_\ell} &= \frac{1}{2} \left(\sum_{i=1}^m \left((\tilde{x}^{(i)} - \mu_\ell)(\tilde{x}^{(i)} - \mu_\ell)^T \Sigma_\ell^{-2} - \Sigma_\ell^{-1} \right) w_\ell^{(i)} \right) \\
 &+ \frac{1}{2} \left(\sum_{i=1}^m \mathbb{1}\{\tilde{z}^{(i)} = \ell\} (\tilde{x}^{(i)} - \mu_\ell)(\tilde{x}^{(i)} - \mu_\ell)^T \Sigma_\ell^{-2} - \sum_{i=1}^m \mathbb{1}\{\tilde{z}^{(i)} = \ell\} \Sigma_\ell^{-1} \right) \\
 &= \frac{1}{2} \left(\sum_{i=1}^m w_\ell^{(i)} (\tilde{x}^{(i)} - \mu_\ell)(\tilde{x}^{(i)} - \mu_\ell)^T \Sigma_\ell^{-2} - \sum_{i=1}^m w_\ell^{(i)} \Sigma_\ell^{-1} \right) \\
 &+ \frac{1}{2} \left(\sum_{i=1}^m \mathbb{1}\{\tilde{z}^{(i)} = \ell\} (\tilde{x}^{(i)} - \mu_\ell)(\tilde{x}^{(i)} - \mu_\ell)^T \Sigma_\ell^{-2} - \sum_{i=1}^m \mathbb{1}\{\tilde{z}^{(i)} = \ell\} \Sigma_\ell^{-1} \right)
 \end{aligned}$$

Set it to 0 and right multiply with Σ_ℓ^2 :

$$\begin{aligned}
 &\left(\sum_{i=1}^m w_\ell^{(i)} (\tilde{x}^{(i)} - \mu_\ell)(\tilde{x}^{(i)} - \mu_\ell)^T + \alpha \sum_{i=1}^m \mathbb{1}\{\tilde{z}^{(i)} = \ell\} (\tilde{x}^{(i)} - \mu_\ell)(\tilde{x}^{(i)} - \mu_\ell)^T \right) \\
 &= \left(\sum_{i=1}^m w_\ell^{(i)} + \sum_{i=1}^m \mathbb{1}\{\tilde{z}^{(i)} = \ell\} \right) \Sigma_\ell \\
 \Rightarrow \Sigma_\ell &= \frac{\sum_{i=1}^m w_\ell^{(i)} (\tilde{x}^{(i)} - \mu_\ell)(\tilde{x}^{(i)} - \mu_\ell)^T + \alpha \sum_{i=1}^m \mathbb{1}\{\tilde{z}^{(i)} = \ell\} (\tilde{x}^{(i)} - \mu_\ell)(\tilde{x}^{(i)} - \mu_\ell)^T}{\sum_{i=1}^m w_\ell^{(i)} + \alpha \sum_{i=1}^m \mathbb{1}\{\tilde{z}^{(i)} = \ell\}}
 \end{aligned}$$

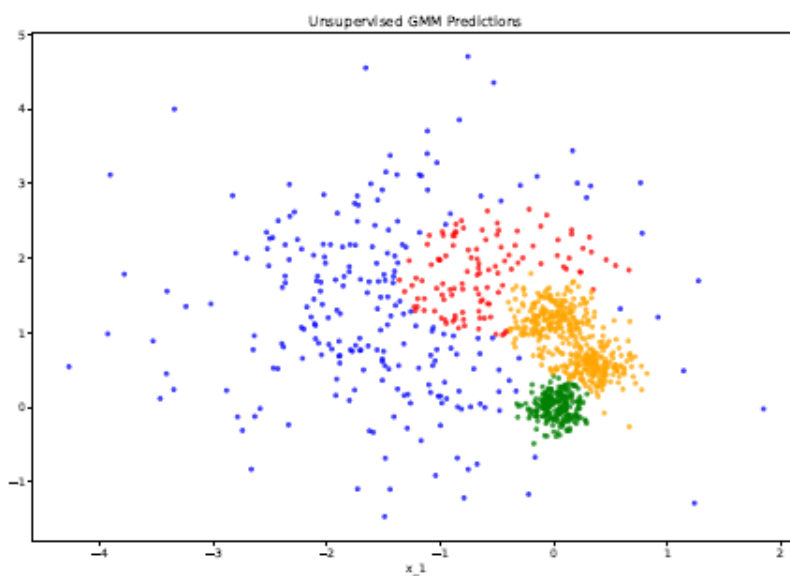
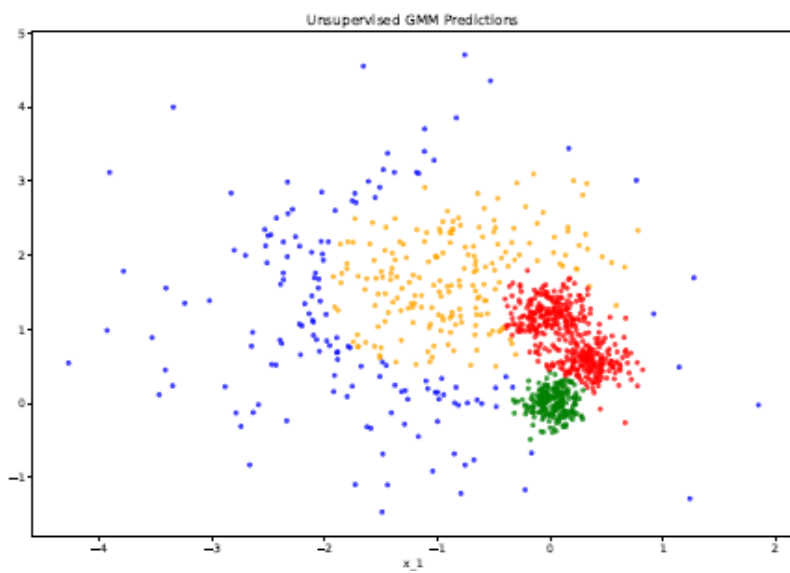
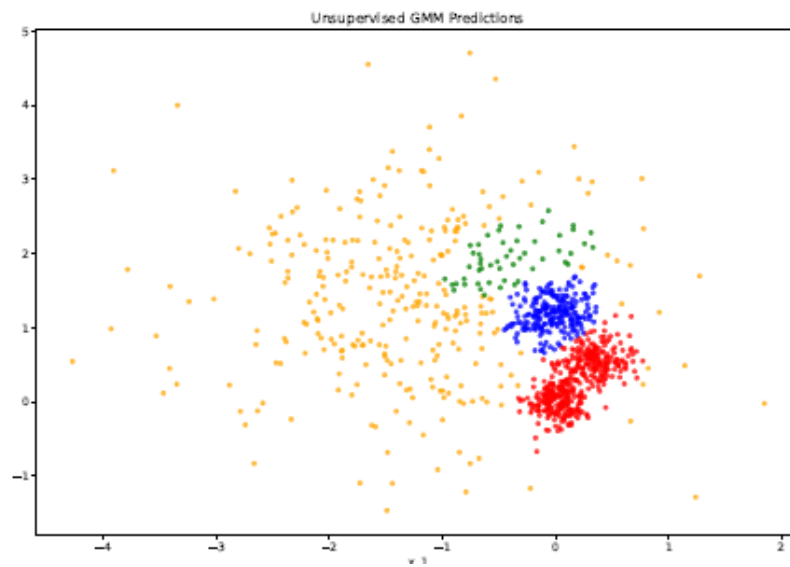
the denominator is a scalar, the numerator is an $n \times n$ matrix.

Done!

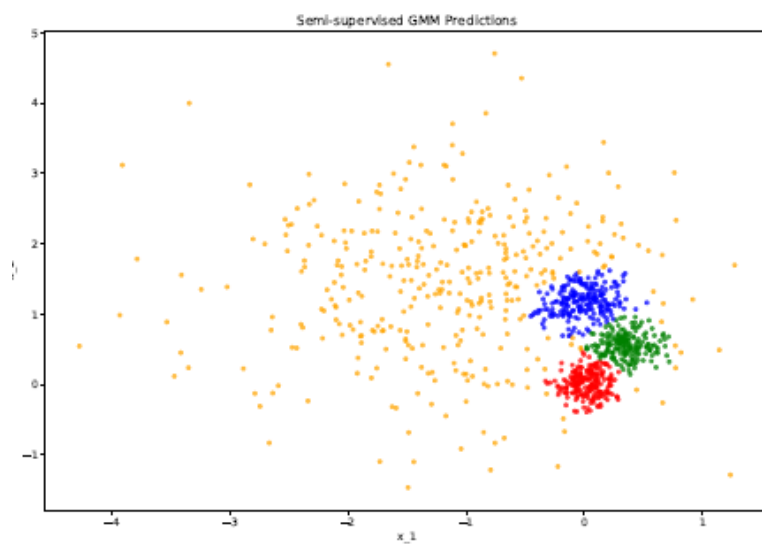
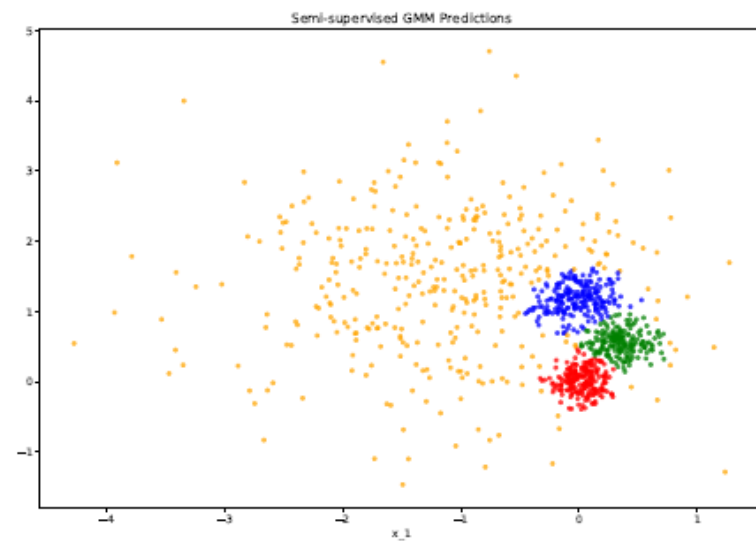
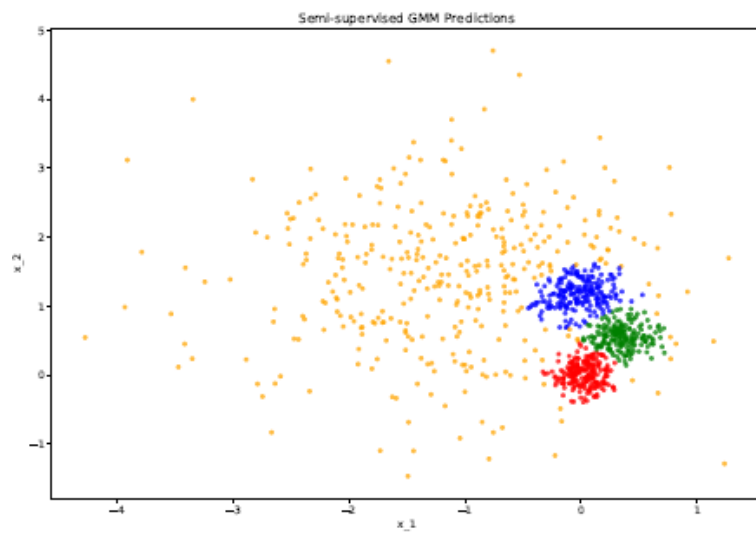
(d) plot.

(e) plot.

d) Unsupervised GMM predictions, , run three times, not stable



e) Semi-supervised GMM predictions, run three times, stable



f) Comparison of Unsupervised and Semi-supervised EM

i) Number of iterations taken to converge

Answer:

Unsupervised EM takes 162,118,117 iterations to converge. Three runs are shown below:

Unsupervised EM: converged in 162 iterations, log-likelihood=-1831.349043

Unsupervised EM: converged in 118 iterations, log-likelihood=-1835.448461

Unsupervised EM: converged in 117 iterations, log-likelihood=-1835.444311

Semi-supervised EM only takes 15,31,31 iterations to converge.

Semi-supervised EM: converged in **15 iterations**, log-likelihood=-2344.767485, ll_sup=-552.478311, ll_unsup=-1792.289174

Semi-supervised EM: converged in **31 iterations**, log-likelihood=-2344.614540, ll_sup=-553.009998, ll_unsup=-1791.604542

Semi-supervised EM: converged in **31 iterations**, log-likelihood=-2344.613954, ll_sup=-553.011754, ll_unsup=-1791.602200

ii) Stability

Answer:

As can be seen in the above plot, Unsupervised EM is very sensitive to initialization and the class assignment changes dramatically with different random initializations.

Semi-supervised EM is very stable and class assignments do not change much.

iii) Overall quality of assignments

Answer:

Overall the Semi-supervised EM has a much better quality compared to Unsupervised EM.

5. K-means for compression.

a) K-means compression implementation.

```
from matplotlib.image import imread
import matplotlib.pyplot as plt
import numpy as np

# reduce to n colors
def kmeans_compress(X, n = 16):
    X = X.reshape(-1, 3)
    centroids = X[np.random.choice(np.arange(X.shape[0]), size=n, replace=False)]
    centers = np.zeros([n, 3])
    #
    while not np.array_equal(centers, centroids):
        centers = centroids
        norms = [np.sqrt(np.sum((centers[i] - X) ** 2, axis=1)) for
                  i in range(0, len(centers))]
        idxs = np.stack(norms).argmin(axis=0)
        #recalc centroids
        centroids = np.array([np.mean(X[np.where(idxs == i, True, False)],
                                       axis = 0).round() for i in range(n)])
    #you need the data type conversion, otherwise you are in big trouble!!
    return np.uint8(centroids), np.uint8(idxs)

def show_img(X, ax, s):
    ax.imshow(X)
    ax.set_title(s)

def main():
    fig, axes = plt.subplots(2, 1, figsize=(12, 4))
    axb1, axb2 = axes.ravel()

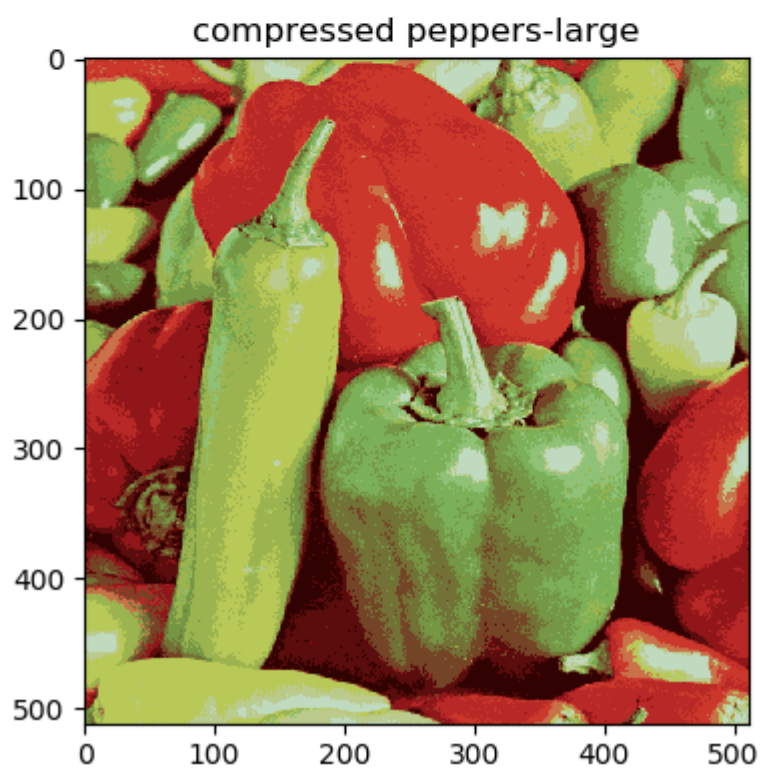
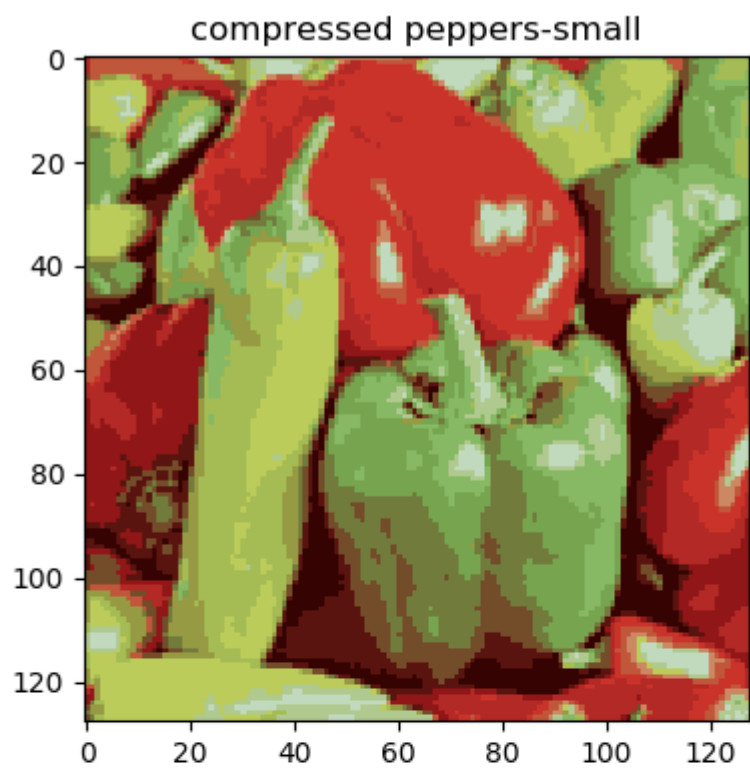
    A1 = imread('..\data\peppers-small.tiff')
    centroids, idxs = kmeans_compress(A1)
    B1 = np.array([centroids[idxs[i]] for i in range(0, len(idxs))])
    B1 = B1.reshape(A1.shape)
    show_img(B1, axb1, 'compressed peppers-small')

    A2 = imread('..\data\peppers-large.tiff')
    centroids, idxs = kmeans_compress(A2)
    B2 = np.array([centroids[idxs[i]] for i in range(0, len(idxs))])
    B2 = B2.reshape(A2.shape)
    show_img(B2, axb2, 'compressed peppers-small')

    plt.show()

if __name__ == '__main__':
    main()
```

Compressed images:



b) K-means compression Factor

Answer:

To store the original image, each pixel requires 24bit for the RGB value (255 x 255 x 255 colors);

To store the compressed image, each pixel will only need 16 colors, which need only 4bit storage.

The compression factor is thus $24:4 = 6:1$.