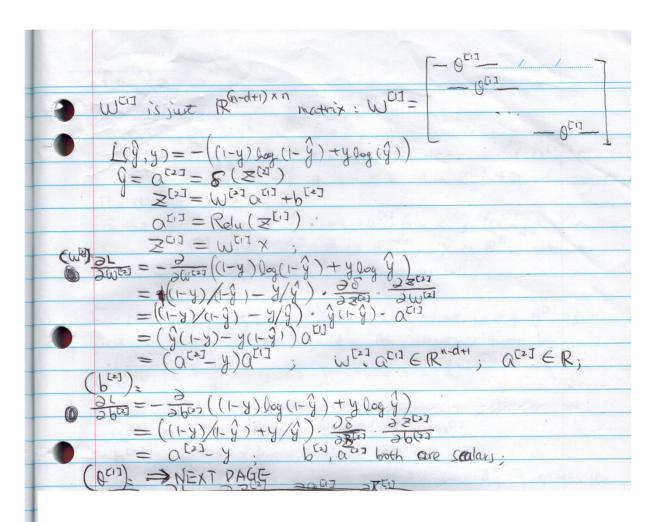
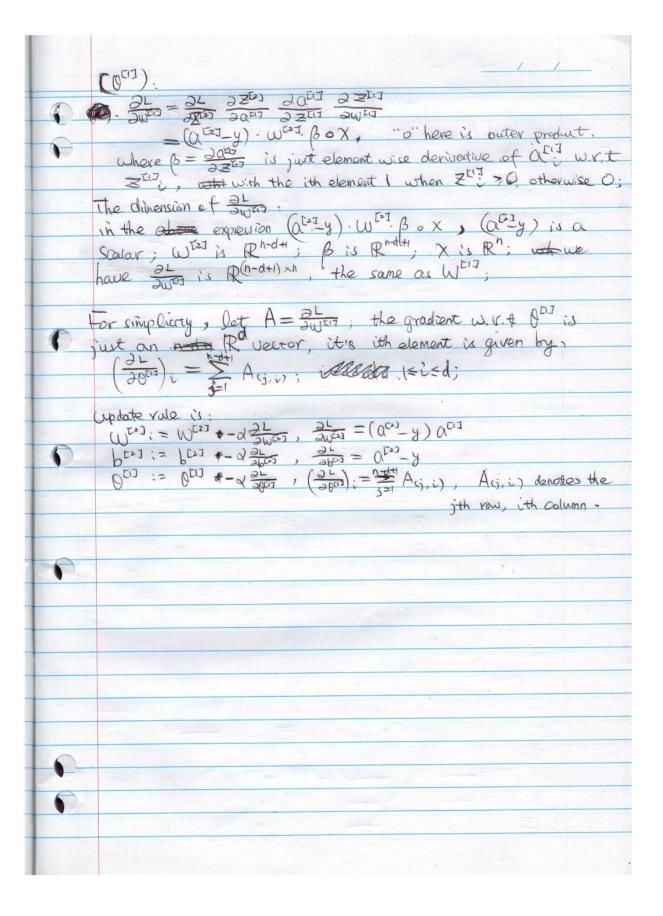
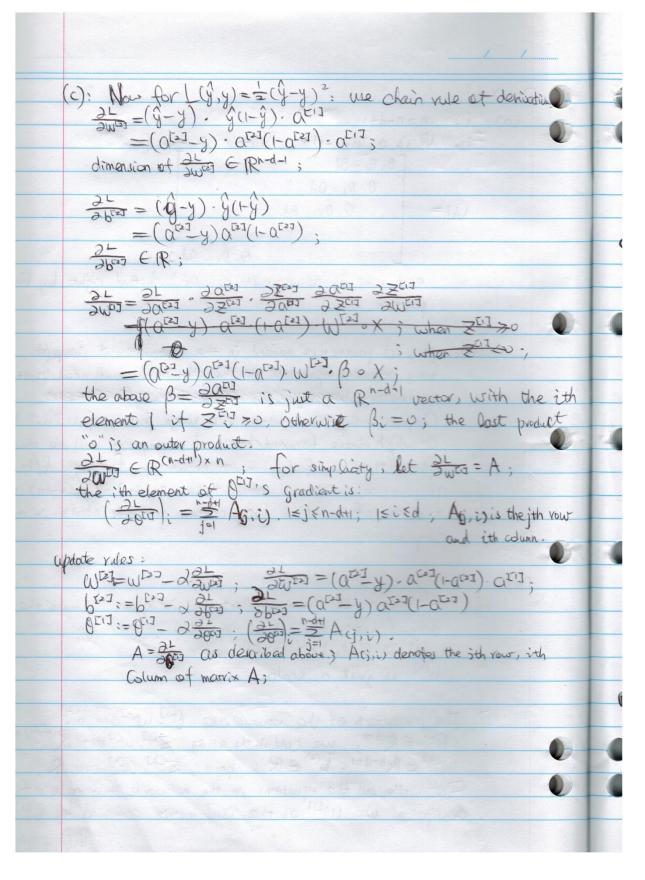
-				
0	1. (a).			
	i-B ii. B, C			
•	(6)			
	i. CD ii. A iii. C iv. C v. B vi. B			
	iv. C v. B · vi. B			
	(c)			
	i.C.F ii. BD iii. AE			
0	(d).			
	i. BD ii. BD iii. CE			
	(e)			
0	As False Logistic Regression comment converge when data is linearly separable,			
1	By False more leaves means more complicated hypothesis which will increase variance but decrease bias.			
	Cz			
	D: True It dependents on support vectors which is a small subset of data			
0	F: True All the linear + identity activation layers can just be replaced with			
	one linear function $a = Wx+b$, applied on $\hat{y} = signoid(wx+b)$ which is simply a linear classifier.			
	G: False Kernelized Perception doesn't maximize the margin, it only			
	Separates the data with a boundary. H: True $p(x;\theta) = \overline{\overline{\overline{\overline{\overline{\overline{\overline{\overline{\overline{\overline{\overline{\overline{\overline{\overline{\overline{\overline{\overline{\overline$			
1	$= \prod_{x} x^{-1} \theta^{-1} \exp(-\theta^{-1} x^{-1} x^{-1})$			
	$= \pi \times^{\pi-1} \exp(-6\pi \times R - \pi \log \theta),$ $b(t) : \pi \times^{\pi-1}$			
	n: -0-110			
	$\alpha(\eta): \pi(0)$			
	T(y): X"			

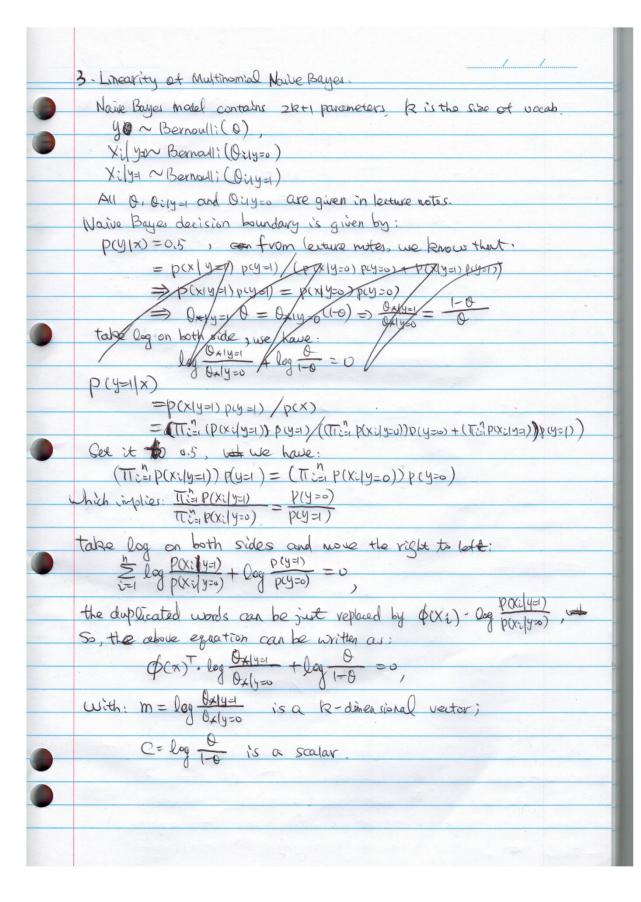
e cf	A. YES B. WO C. NO D. YES E. NO F. YES G. YES 14. WO VO I. YES J. NO
0	
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0	The man for of the family of the print of th
	Mest page

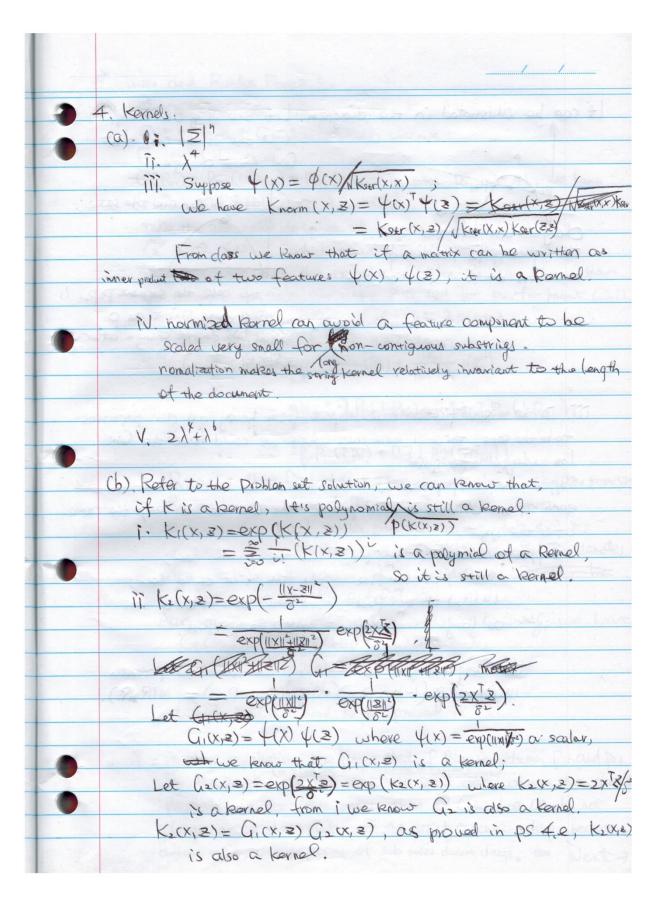
1 2 CNN. 1 = 1 = 1 (A) 1 (A) (B)					
	(a) : i, m =	n-d+1			
	ii, W	is a (n-d+1) × n matrix in the form:			
		0, 0,01			
	, 7,1	0, 0, ·· 0d			
	W=	9. 02 :: 0d			
		0.001			
	each your is a vector (0,0,000 d) shifted right by (vow-1)				
	position				
0	Salat Dish	12 X 22 1 1 X 25 2 1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2			
	iii. Only d parameters needed in the case without interpett, its				
	fully connected equivalent on the other hand will need (n-d+1).				
ATRIC	para	uncters, best consider the state of the stat			
	Com	putationally since deen, a large portion of will be			
	O which means forward backward propagation will be much				
	faster than a fully connect network. For both f/b propagation, and will only take (n-d+1)-d/(n-d+1)-n				
	= d/n of what a fully connect notwork needs in any				
	computation.				
0	THE AMERICA	on - since the comment of which were			
	(b)	NOW END TO THE PROPERTY DISCUSTED IN THE PRO			
	i: Otis is a dolimensional vector, it is used to make the				
	dian Constitution in (a) is				
	W[2] is (n-d+) dimensional Vector;				
	W[2] is just a scalar.				
	ii the m	marine of the warms on this was and tail			
	Ocide	ERd. We CIN in the setting . ZCIJ acid are Rinday)			
	41[2]	ii. The parameters of the newsork are. (Fi) wist and (Fi) of the parameters of the newsork are. (Fi) wist are Render) with the setting, Zill, at are Render) with the setting, Zill are R;			
	First w	rite all the equations in the network, for ease cet			
	First write all the equations in the network. for ease of description, we will as the CNN matrix composed by Otiz;				
		West page →			





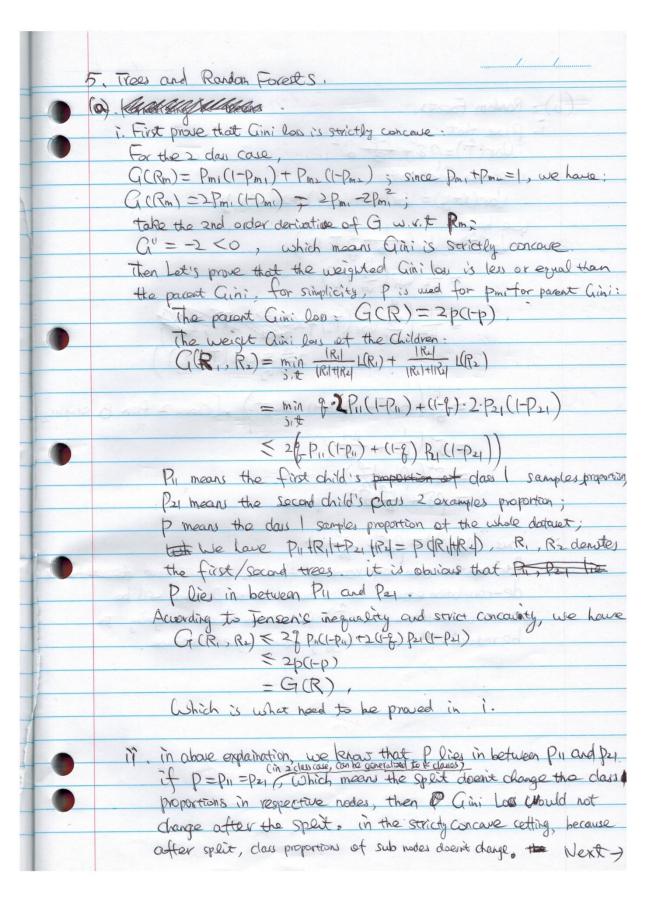






iii. From Gausian integral we have: NT/a = (- xp(-a(t+b)*)dt, together with = $k(x,z) = \exp(-\frac{1}{2}(x-z)^2)$, Set $a = \frac{1}{2}$, b = (x+2) $k(x,z) = \exp(-\frac{1}{2}(x-z)^2)$ $\int_{-\infty}^{\infty} \frac{1}{2\pi} \exp(-\frac{1}{2}(t+x+z)^2) dt$ This gives us the final feature mapping function: $\phi(x,t) = (2\pi)^{-\frac{1}{2}} \exp(-(\frac{x+2x}{2})^2)$

(c): Korrelizing K-means The indess controid is now an infinite dihersion parameter which connoct be represented by computer, updating centroid divertly is changed to update the indeparties in Controlds calculation After Kenelizing, Uj is still a linear combination of $\phi(x^{(i)})$: $U_j = \sum_{i=1}^{n} Y_i \phi(x^{(i)})$, where $Y_i = \frac{1}{N_j}$ for $C^{(i)} = j$, otherwise The norm is now : 11 \$(x(2)) - 115 112 = (\$(x(2)) To(x(2)) - 2\$ (x(2)) Tu; + u; t;) Plug in linear combination of U_i : $\|U(X^{(i)})^T\|_{L^{\infty}}\|^2 = K(X^{(i)}, X^{(i)}) - 2\phi(X^{(i)})^T \tilde{\varphi}(X^{(i)})$ $+ \tilde{\mathbb{Z}} \tilde{\mathbb{Z}} \tilde{Y}_i \tilde{Y}_i \tilde{\varphi}(X^{(i)})^T \phi(X^{(i)})$ $+ \tilde{\mathbb{Z}} \tilde{\mathbb{Z}} \tilde{Y}_i \tilde{Y}$ So the update rule should be changed to $\widetilde{C}^{(i)} = \underset{k}{\text{arg min}} \left(K(X^{(i)}, X^{(i)}) - 2 \sum_{k=1}^{m} r_k r_k K(X^{(k)}, X^{(k)}) \right) + \sum_{k=1}^{m} \sum_{k=1}^{m} r_k r_k K(X^{(k)}, X^{(k)}) \right),$



It can be illustrated in the diagram, Lete one is a Cini changed; Right one is the case that aini doesn't change P. P., Pz, are the same, Changed Gini loss after Split the segment Pupy lies below the curve of Cini function in this case the segment Pupzi is just a some point as p Cini loss doesn't change after Split. iii, in the misday ification case, apart from having all class proportions to be the same, there is more cases where we could have the Gin: loss unchanged after split. Suppose the max proportion of a dass are all the same in sub trees and each of the children and in parent, the Cin; los will keep the same ofter the split. Suppose M(R) = 1-max PR is the parent loss; M(R) =1-max Pie is the first child loss; (M(R2) =+ max P2R is the second dild boss as long as max PR = max PIR = max PAR, the way Hed Gini loss will keep the same as parent. (M(R) = 9 (1- max Pir) + (1-9) (1-max Pab) = M(R) R)

