# How to design Dust Sensor

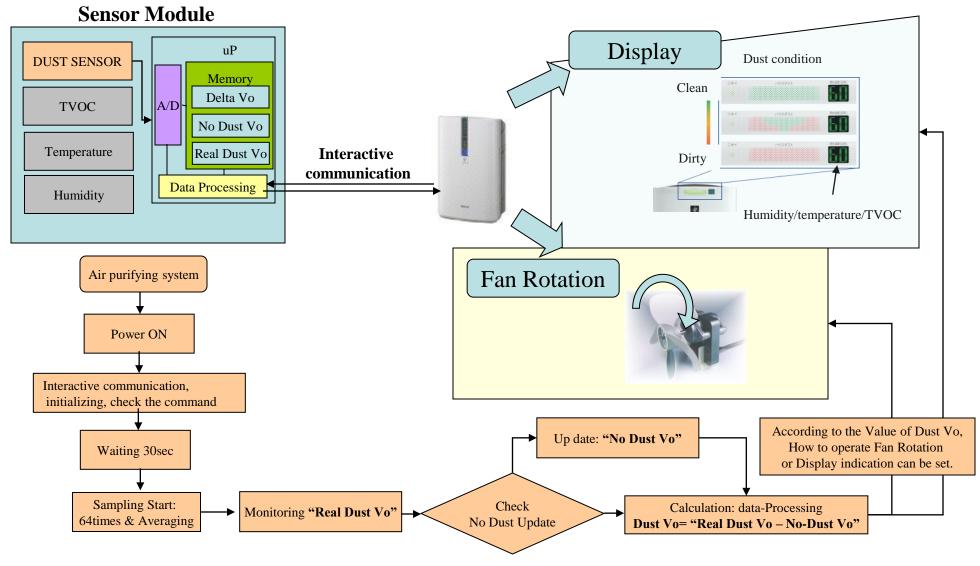
2013 Mar.

## To begin with

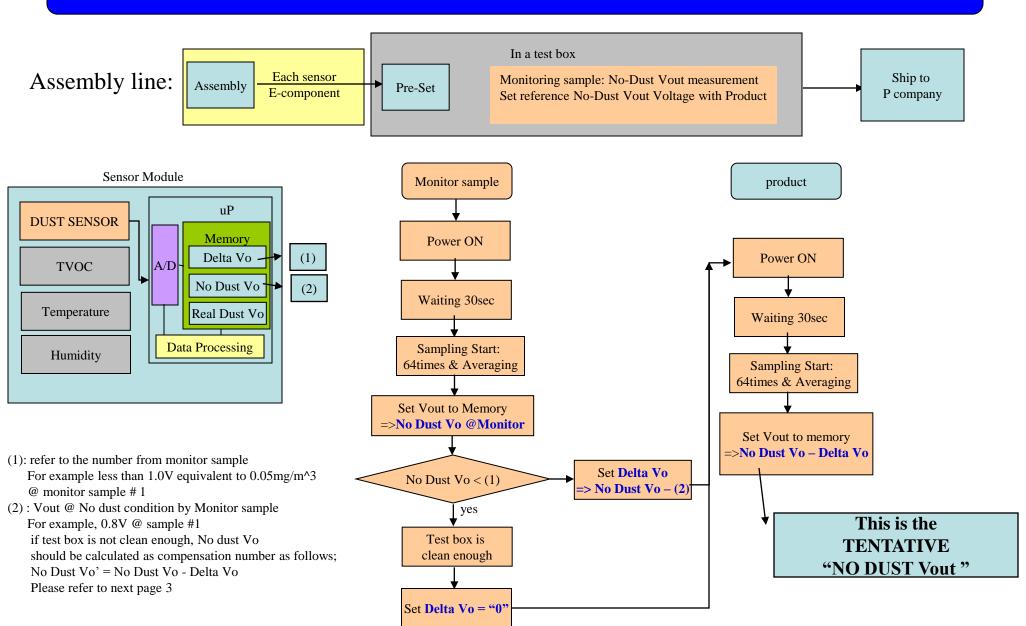
- To make sure basic information of GP2Y1010AU0F
  - Refer to presentation of "Dust Sensor "total 13page w/o cover page
    - Circuit
    - Variation => Calibration
    - Mechanical Design Consideration
    - Power consumption
- Document
  - Spec
  - Application Note
  - Temperature Drift
  - Reliability

# **Standard Operation**

### Finish product: Air purifying system



### **No-Dust Condition: Set tentative No Dust Vout**



3

Confidential

SHARP

## How to update? No-Dust Vout

When starting air purifying system as finish product, air cleaner, "No-Dust Vout" should be updated accordingly as following conditions;

### No Dust check when starting

1, When starting air purifying system like fun-rotation,
comparing Real Dust Vo with No Dust Vo(tentative one) which was set before shipment.
if Real Vo < No Dust Vo => replace the Real Vo to No Dust Vo
=> Then this will be the latest No Dust Vo

#### More clean condition

2, When operating if find the cleaner condition such as Real Vo < No Dust Vo, => replace the Real Vo to No Dust Vo => Then this will be the latest No Dust Vo

### **Compensation of unexpected incident**

3, When operating if find steady Vo for long term, => replace the Real Vo to No Dust Vo => Then this will be the latest No Dust Vo

## Proposal of calibration for no-dust condition

Data of monitor

sample

### process

Sharp makes monitor sample (3pcs)

Monitor sample

Measuring monitor sample

@ tentative no-dust condition

Mo-Vout @tentative no-dust

- Monitor sample has data of Vout vs. Dust density
- Data should be shown low density condition such as 0 to 0.1mg/m3.

TEST BOX

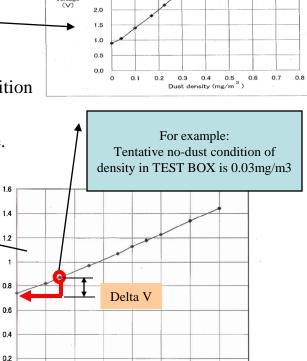
@manufacture

Product

Manufacture can use this monitor sample and set initial tentative no-dust condition

Monitoring the value of monitor sample and convert the Vout to

initial tentative no-dust condition for mass production board of Manufacture.



0.14

GP2Y1010AU Dust density vs Output voltage

Convert Pr-Vout @ tentative no-dust condition to **Real no-dust Vout** by calibration as follows; Real No-Dust Vout = Pr-Vout @ tentative no dust - delta V

Measuring Product

@ tentative no-dust condition

Pr-Vout @tentative no-dust

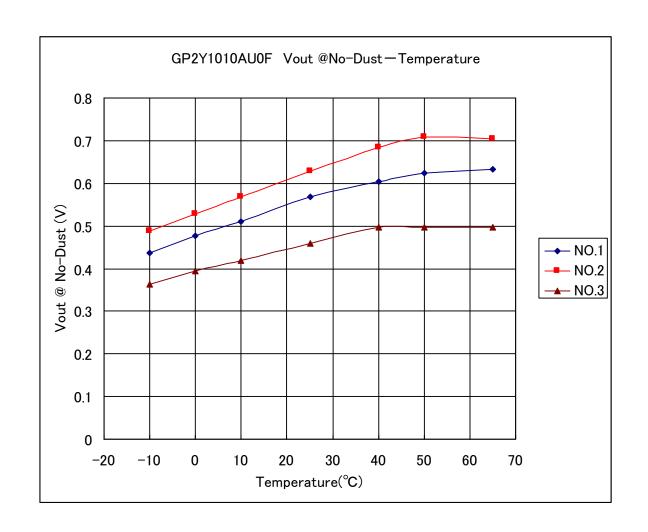


Dust density (mg/m<sup>3</sup>)

### Variation

- Calibration
  - No-Dust Vo
    - Refresh/Update as latest cleaner condition
    - Dust Density Vo = Real-Dust Vo No-Dust Vo
      - Value of Dust Density can be used for set thresh level of starting fan rotation or segmentation of the Dust density level on Display
- Compensation
  - Temperature Drift
    - Normalize the value for compensation: from 0 to 50 degree C
      - Please refer to attached graph of temperature drift
  - Time Aging
    - **♦** TBD
      - can be ignorable?

# Vout @ No-Dust condition vs. Temperature





## Impact of contamination for Sensor Output

#### -<u>Test concept</u>

-To measure the impact of contamination for Sensor Output

#### -Test Method

- -Take the date of K(Sensitivity) and Vout @ no-Dust for the sensor
- -Set the sensor in the test box (W50 x H50 x D50cm).
- -Smoke 1pcs of Cigarette completely and pour the smoke into the test box.

And keep the condition for 20 minutes. => It's the one cycle.

-Repeat above process for N times and take the date of K(Sensitivity) and Vout @ no-Dust for the sensor

Variation of Vout(sensitivity) (%) = ( K(Sensitivity) after N times )/Initial K(Sensitivity)

Variation of Vout @ No-dust (%) = ( Vout @ No-dust after N times/Initial Vout @ No-dust )

#### -Note

- -This is acceleration test, so it can be equivalent to the real condition of smoking at room.
  - -Real condition of cigarette smoke = (Size of room) / (size of the test box) X (smoked cigarettes)
  - -For ex. Size of room(  $3.6m \times 3.6m \times 2.4m$  )/(  $0.5m \times 0.5m \times 0.5m$  )  $\times 300 = 74,649$  pcs It can be equivalent to 3,732 days with 20pcs smoking a day.

