

\mathcal{L} \mathcal{L}^{-1}

- 1) $\mathcal{L}(e^{ct}u) = e^{-cs} \cdot \mathcal{L}(u) \quad (c > 0)$
- 2) $\mathcal{L}(e^{ct}u) = \tau_c \mathcal{L}(u) \quad (c \in \mathbb{C})$
- 3) $\mathcal{L}'(u) = \mathcal{L}(-t \cdot u(t))$
- 4) $\mathcal{L}(u * v) = \mathcal{L}(u) \cdot \mathcal{L}(v)$
- 5) $\mathcal{L}(U)(s) = \frac{\mathcal{L}(u)}{s}$
- 6) $\mathcal{L}(u')(s) = s\mathcal{L}(u)(s) - u(0)$
- 7) $\mathcal{L}(u'')(s) = s^2\mathcal{L}(u) - su(0) - u'(0)$

- 1) $\mathcal{L}^{-1}(\tau_c v) = e^{-ct} \cdot \mathcal{L}^{-1}(v) \quad (c \in \mathbb{C})$
- 2) $\mathcal{L}^{-1}(e^{ct}v) = \tau_c \mathcal{L}^{-1}(v) \quad (c > 0)$
- 3) **Riemann-Fourier:**
se $\mathcal{L}^{-1}(v) \in C^0(\mathbb{R})$:
 $u \rightarrow \mathcal{L}(u)(s) = \int_0^{+\infty} u(t) e^{-st} dt$
 $v \rightarrow \mathcal{L}^{-1}(v) = \frac{1}{2\pi i} \int_{x+2\pi i \mathbb{R}} v(s) e^{st} ds$
 $x > \Re(\mathcal{L}^{-1}(v))$
- 4) **Heaviside:**
se $v = \frac{p}{q}$ con $p, q \in \mathbb{C}[s]$:
 $\mathcal{L}^{-1}(v) = \sum_{q(s_k)=0} \text{Res}(v(s) e^{st}, s_k) \cdot H(t)$

1) $\begin{cases} \ddot{y} - 3\dot{y} + 2y = \delta_1 = \delta_0(t-1), \\ y(0) = \dot{y}(0) = 0 \end{cases}, \quad t > 0$

$$\Rightarrow \mathcal{L}(y) = Y \Rightarrow \mathcal{L}(\dot{y}) = sY - y(0) \wedge \mathcal{L}(\ddot{y}) = s^2Y - \dot{y}(0) - y(0)$$

$$\Rightarrow \mathcal{L}(\delta_1) = e^{-s} \Rightarrow Y \cdot (s^2 - 3s + 2) = e^{-s}$$

$$\Rightarrow Y = \frac{e^{-s}}{s^2 - 3s + 2} = \frac{e^{-s}}{(s-1)(s-2)} = e^{-s} \cdot v(s) \text{ con } v(s) = \frac{1}{(s-1)(s-2)}$$

$$\Rightarrow \mathcal{L}^{-1}(Y) = \mathcal{L}^{-1}(e^{-s}v(s)) = \tau_1 \mathcal{L}^{-1}(v) = \mathcal{L}^{-1}(v)(t-1)$$

Ci sono 2 metodi per calcolare $\mathcal{L}^{-1}(v)$:

1) Formula di Heaviside (v è razionale !!!)

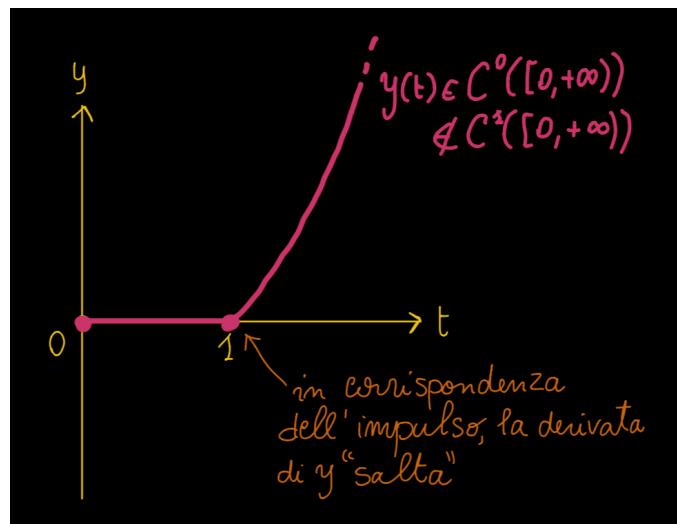
$$\begin{aligned} \mathcal{L}^{-1}(v) &= \sum_{\substack{s_k \text{ poli} \\ \text{di } e^{st} v(s)}} \text{Res}(v(s) e^{st}, s_k) \cdot H(t) \\ &= (\text{Res}(v(s) e^{st}, 1) + \text{Res}(v(s) e^{st}, 2)) \cdot H(t) \\ &= (-e^t + e^{2t}) H(t) \end{aligned}$$

2) Frazioni semplici (solo se v ammette UNICAMENTE poli semplici):

$$v(s) = \frac{A}{s-1} + \frac{B}{s-2} = \frac{-1}{s-1} + \frac{1}{s-2} \text{ con } A = \text{Res}(v, 1), B = \text{Res}(v, 2)$$

$$\begin{aligned} \Rightarrow \mathcal{L}^{-1}(s) &= \mathcal{L}^{-1}\left(-\frac{1}{s-1}\right) + \mathcal{L}^{-1}\left(\frac{1}{s-2}\right) = -\mathcal{L}^{-1}\left(\tau_1\left(\frac{1}{s}\right)\right) + \mathcal{L}^{-1}\left(\tau_2\left(\frac{1}{s}\right)\right) \\ &= (-e^t + e^{2t}) H(t) \end{aligned}$$

$$\Rightarrow y(t) = (-e^{(t-1)} + e^{2(t-1)}) \cdot H(t-1) = \begin{cases} -e^{(t-1)} + e^{2(t-1)} & t \geq 1 \\ 0 & t < 1 \end{cases}$$



$$2) \begin{cases} \ddot{y} + \dot{y} + y = \delta_1 & t > 0 \\ y(0) = \dot{y}(0) = 0 \end{cases}$$

$$\Rightarrow \mathcal{L}(y) = Y \Rightarrow \mathcal{L}(\dot{y}) = sY - y(0), \quad \mathcal{L}(\ddot{y}) = s^2Y - sy(0) - \dot{y}(0)$$

$$\Rightarrow \mathcal{L}(\delta_1) = e^{-s}$$

$$\Rightarrow Y \cdot (s^2 + s + 1) = e^{-s} \Rightarrow Y = \frac{e^{-s}}{s^2 + s + 1} = \frac{e^{-s}}{(s - s_+)(s - s_-)}$$

Il polinomio caratteristico non è riducibile in IR !!!

$$\Rightarrow s_{\pm} = \frac{1}{2}(-1 \pm i\sqrt{3}) \text{ MA NON È NECESSARIO CALCOLARLE !!!}$$

$$\Rightarrow y = \mathcal{L}^{-1}(Y) = \mathcal{L}^{-1}(v)(t-1) \text{ con } v(s) := \frac{1}{(s - s_+)(s - s_-)}$$

Calcolo di y :

1) Formula di Heaviside (v è razionale) ✓

2) Fratti semplici (v ha solo 2 poli semplici)

3) Metodo dei quadrati (solo se il denominatore di v è un trinomio di 2° grado IRRIDUCIBILE in IR !!!):

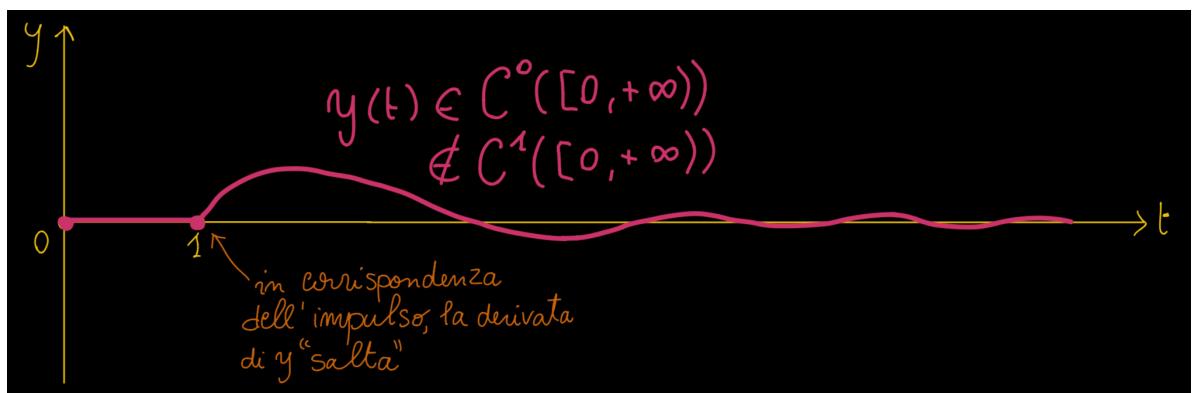
$$\begin{aligned} v(s) &= \frac{1}{(s + \frac{1}{2})^2 + \frac{3}{4}} = \frac{1}{(s + \frac{1}{2})^2 + (\frac{\sqrt{3}}{2})^2} = \underbrace{\frac{1}{\frac{\sqrt{3}}{2}}}_{=: w} \frac{1}{(s + \frac{1}{2})^2 + (\frac{\sqrt{3}}{2})^2} \cdot \frac{2}{\sqrt{3}} \\ &= \frac{1}{w} \frac{w}{(s + \frac{1}{2})^2 + w^2} = \frac{1}{w} \mathcal{L}(\sin wt)(s - (-\frac{1}{2})) = \frac{1}{w} \mathcal{T}_{-\frac{1}{2}} \mathcal{L}(\sin wt) \\ &= \frac{1}{w} \mathcal{L}(e^{-\frac{1}{2}t} \cdot \sin wt) \end{aligned}$$

$$\Rightarrow \mathcal{L}^{-1}(v)(t) = \frac{1}{w} e^{-\frac{1}{2}t} \cdot \sin\left(\frac{\sqrt{3}}{2}t\right) \cdot H(t)$$

$$\Rightarrow y(t) = \frac{2}{\sqrt{3}} e^{-\frac{1}{2}(t-1)} \sin\left(\frac{\sqrt{3}}{2}(t-1)\right) \cdot H(t-1)$$

Quindi:

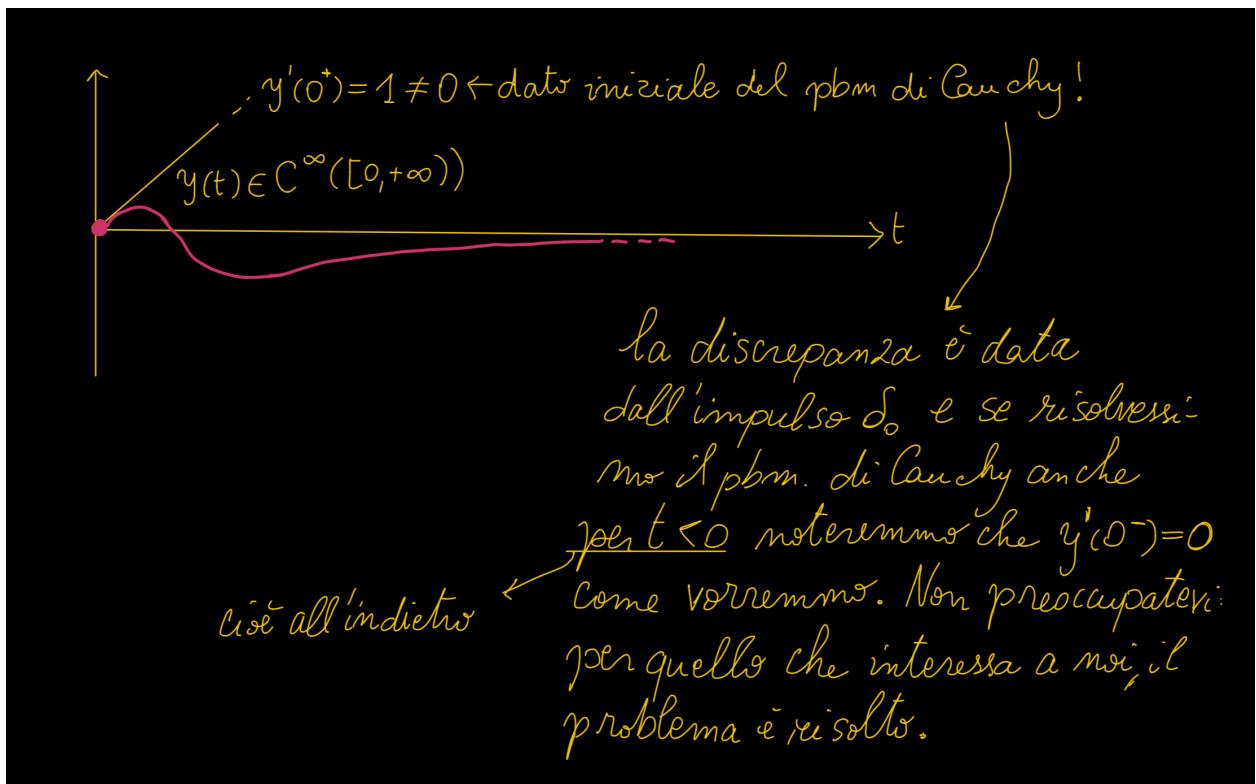
$$y(t) = \begin{cases} \frac{2}{\sqrt{3}} e^{-\frac{1}{2}(t-1)} \sin\left(\frac{\sqrt{3}}{2}(t-1)\right) & t \geq 1 \\ 0 & t < 1 \end{cases}$$



3)

$$\begin{cases} \ddot{y} + 6\dot{y} + 9y = \delta_0 - 3e^{-3t} & t > 0 \\ y(0) = \dot{y}(0) = 0 \end{cases}$$

$$\begin{aligned} \Rightarrow \text{trasformar: } \quad \mathcal{L}(y)(s) \cdot (s^2 + 6s + 9) &= 1 - \frac{3}{s+3} \\ \Rightarrow \mathcal{L}(y)(s) &= \frac{1}{(s+3)^2} - \frac{3}{(s+3)^3} = \mathcal{T}_{-3}\left(\frac{1}{s^2}\right) - 3\mathcal{T}_{-3}\left(\frac{1}{s^3}\right) \\ &= \mathcal{T}_{-3}\mathcal{L}(t)(s) - 3\mathcal{T}_{-3}\mathcal{L}\left(\frac{t^2}{2}\right)(s) \\ &= \mathcal{T}_{-3}\mathcal{L}\left(t - \frac{3}{2}t^2\right)(s) = \mathcal{L}\left(e^{-3t} \cdot \left(t - \frac{3}{2}t^2\right)\right)(s) \\ \Rightarrow y(t) &= e^{-3t} \left(t - \frac{3}{2}t^2\right) \cdot H(t) \end{aligned}$$



4)

$$\begin{cases} \ddot{y} - 4\dot{y} + 4y = 4 \cdot \mathbb{1}_{(0,2)} \\ y(0) = 1, \quad \dot{y}(0) = 0 \end{cases}$$

$$\begin{aligned} \Rightarrow \mathcal{L}(y)(s) &= Y \Rightarrow \mathcal{L}(\dot{y}) = sY - y(0) = sY - 1, \quad \mathcal{L}(\ddot{y}) = s^2Y - s \\ \Rightarrow \mathcal{L}(4 \cdot \mathbb{1}_{(0,2)}) &= 4\mathcal{L}(\mathbb{1}_{(0,2)}) = 4\mathcal{L}(H - \mathcal{T}_2 H) = 4(\mathcal{L}(H) - \mathcal{L}(\mathcal{T}_2 H)) \\ &= \frac{4}{s} - \frac{4e^{-2s}}{s} \end{aligned}$$

$$\begin{aligned}
&\Rightarrow s^2 Y - s - 4(sY - 1) + 4Y = \frac{4}{s} - \frac{4e^{-2s}}{s} \\
&\Rightarrow Y(s^2 - 4s + 4) = \frac{4}{s} - \frac{4e^{-2s}}{s} + s - 4 \\
&\Rightarrow Y = \frac{s-4}{(s-2)^2} + \frac{4}{s(s-2)^2} - \frac{4e^{-2s}}{s(s-2)^2} \Rightarrow Y = \mathcal{L}^{-1}(Y) \\
&\Rightarrow Y = \mathcal{L}^{-1}\left(\frac{s-4}{(s-2)^2}\right) + 4 \mathcal{L}^{-1}\left(\frac{1}{s(s-2)^2}\right) - 4 \mathcal{T}_2 \mathcal{L}^{-1}\left(\frac{1}{s(s-2)^2}\right) \\
&= \text{Res}\left(e^{st} \frac{s-4}{(s-2)^2}, s=2\right) + 4 \mathcal{L}^{-1}\left(\frac{1}{s} - \frac{1}{s-2} + \frac{2}{(s-2)^2}\right) - 4 \mathcal{T}_2 \mathcal{L}^{-1}\left(\frac{1}{s(s-2)^2}\right) \\
&= \lim_{s \rightarrow 2} \frac{d}{ds} e^{st} (s-4) + 4\left(1 - e^{2t} + 2t e^{2t}\right) H(t) - 4\left(1 - e^{2(t-2)} + 2(t-2)\right) \\
&\quad e^{2(t-2)} H(t-2) \\
&= e^{2t} (1-2t) H(t) + 4\left(1 - e^{2t} + 2t e^{2t}\right) H(t) - 4\left(1 - e^{2(t-2)} + 2(t-2)\right) \\
&\quad e^{2(t-2)} H(t-2) \\
&= (4 - 3e^{2t} + 6t e^{2t}) H(t) - (4 - 4e^{2(t-2)} + 2(t-2)e^{2(t-2)}) H(t-2)
\end{aligned}$$

5)

$$\begin{cases} \dot{Y} + \int_0^t (t-x) Y(x) dx = t + \frac{t^2}{2} + \frac{t^4}{24} \\ Y(0) = 0 \end{cases} \quad t > 0$$

$\Rightarrow \int_0^t (t-x) Y(x) dx =:$ antiderivata di $(t-x) Y(x)$

$$\Rightarrow \mathcal{L}(Y) = Y \Rightarrow \mathcal{L}(\dot{Y}) = sY$$

$$\begin{aligned}
&\Rightarrow \mathcal{L}\left(\int_0^t (t-x) Y(x) dx\right) = \mathcal{L}\left(\int_{IR} (t-x) H(t-x) \cdot \underbrace{Y(x) H(x)}_{f(t-x) g(x)} dx\right) \\
&= \mathcal{L}(f * g) \\
&= \mathcal{L}(f) \mathcal{L}(g) = \mathcal{L}(tH) \mathcal{L}(YH) = \mathcal{L}(t) \mathcal{L}(Y) = \frac{1}{s^2} Y
\end{aligned}$$

$$\Rightarrow sY + \frac{1}{s^2} Y = \frac{1}{s^2} + \frac{1}{2} \frac{2t}{s^3} + \frac{1}{24} \cdot \frac{4t}{s^5}$$

$$\begin{aligned}
&\Rightarrow Y = \frac{s^2}{s^3+1} \cdot \left(\frac{1}{s^2} + \frac{1}{s^3} + \frac{1}{s^5}\right) = \frac{1}{s^3+1} + \frac{1}{s(s^3+1)} + \frac{1}{s^3(s^3+1)}
\end{aligned}$$

3 poli semplifici
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\Rightarrow Fratti semplifici ... si trova:

$$\begin{aligned}
Y &= \frac{1}{s} + \frac{1}{s^3} - \frac{1}{3(s+1)} - \frac{2s-1}{3(s^2-s+1)} \\
&= \frac{1}{s} + \frac{1}{s^3} + \frac{1}{3(s+1)} - \frac{2}{3} \frac{s-\frac{1}{2}}{(s-\frac{1}{2})^2 + (\frac{\sqrt{3}}{2})^2} \xrightarrow{=: w} \mathcal{L}(\cos wt)(s-\frac{1}{2})
\end{aligned}$$

e, per calcolare Y , si opera come in precedenza.