

28 May 2023

QBF, Polynomial Hierarchy, PSPACE.

= Quantified Boolean Formulas. (QBF).

(1) Propositional logic with universal & existential quantifications over boolean (or propositional) variables.

$$\text{Ex. } \forall p \exists q ((p \wedge \neg q) \vee (\neg p \wedge q))$$

(2) Can be written in the following prenex form.

$$Q_1 \vec{p}_1 Q_2 \vec{p}_2 \dots Q_n \vec{p}_n F$$

↑ quantifier-free.

(3) Computation problems on QBF formulas

① TQBF --- truth of a given closed QBF formula
in the prenex form

② Σ_i -SAT --- truth of a given closed QBF

Quantifier alternation $\xleftarrow{\text{formula of the following form:}}$

$$\exists \vec{p}_1 \forall \vec{p}_2 \dots Q \vec{p}_i F$$

(but \tilde{n} times). a sequence of existentially quantified propositional variables.

③ Π_i -SAT --- similar to Σ_i -SAT but

for a formula of the following form.

$$\forall \vec{p}_1 \exists \vec{p}_2 \dots Q \vec{p}_i F$$

* Note: $\Sigma_1\text{-SAT} = \text{SAT}$ --- usual satisfiability problem.

$\Pi_1\text{-SAT} = \text{Valid}$ --- usual validity problem.

(4) Q: How difficult to solve these algorithmically? Any theoretical tools from computational complexity theory?

2. PSPACE

c1) A decision problem is in PSPACE if it can be solved using only polynomial space wrt. the size of the input.

① $P \subseteq \text{PSPACE}$... why?

② $\text{TQBF} \in \text{PSPACE}$... why?

think about a recursive (exp-time) algorithm, which uses a pointer to denote the current formula and a stack to store all the info needed to compute the truth of the input formula.

(2) TQBF is PSPACE-complete.

① encoding of configurations $c \in \{0,1\}^n$ and transition relation $\varphi_M(c, c')$ of a TM.

② Reuse trick via quantifier alternation.

$$\begin{aligned} - \exists C'' \forall D^1 \forall D^2 ((D^1 = C \wedge D^2 = C') \vee \\ (D^1 = C' \wedge D^2 = C'')) \\ \Rightarrow \psi_{\exists \forall} (D^1, D^2) \end{aligned}$$

!!

$$\psi_{\exists} (C, C')$$

$$- \psi_m (C, C')$$

(3) Exercise : PSPACE-hardness of
fol model-checking pb over finite
structures. \sim FOL sentence

① $A \models G$ --- input

\uparrow
finite structure.

true / false --- output.

② TQBF .. $Q_1 P_1 Q_2 P_2 \dots Q_n P_n F$

$$A = (S_0, 1, 0, 1, =)$$

$$G = Q_1 v_1 Q_2 v_2 \dots Q_n v_n$$

$$F [v_1=1/P_1, v_2=1/P_2, \dots, v_n=1/P_n]$$

③ In fact, the model-checking pb is
also PSPACE-complete.

3 Polynomial Hierarchy.

$$\textcircled{1} \quad \Sigma_0 := \Pi_0 := P$$

$\Sigma_{i+1} := NP^{\Pi_i}$... polytime by a nondet.

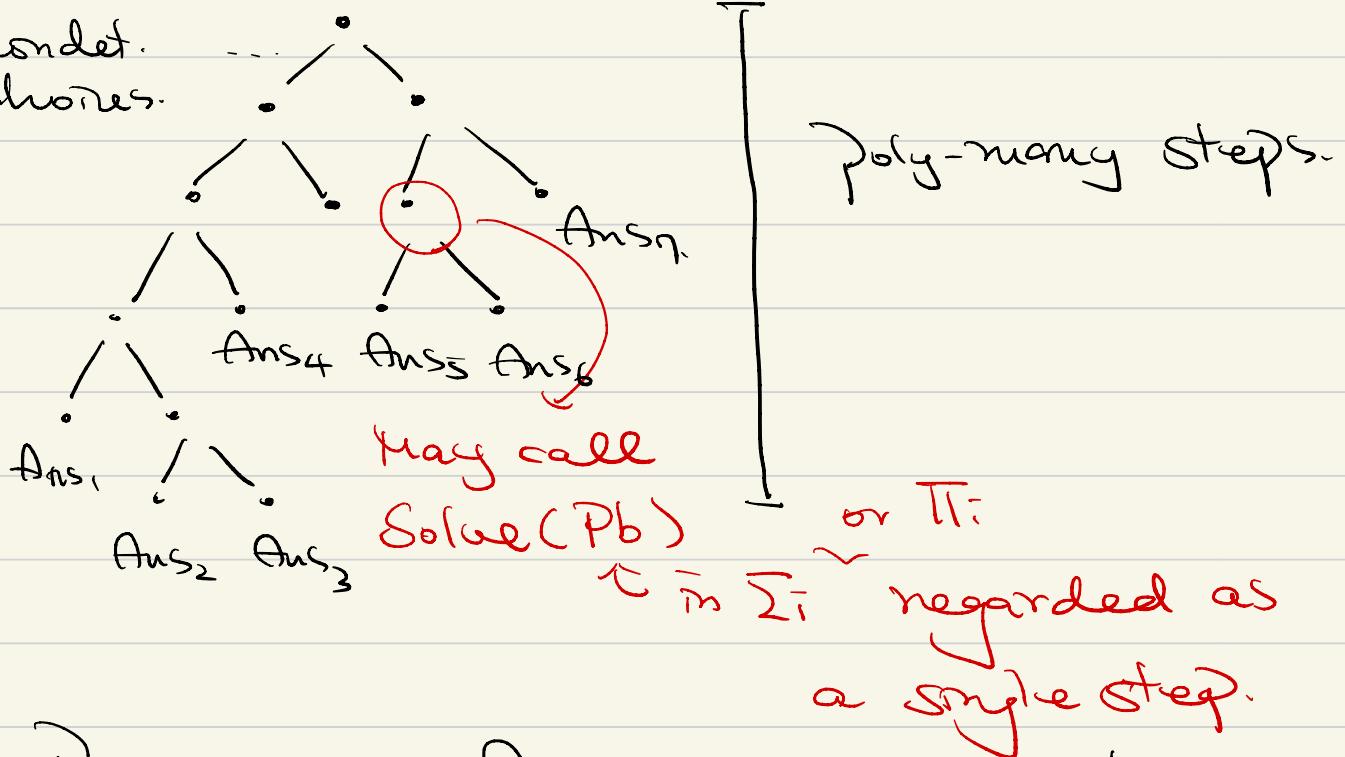
$$\Pi_{i+1} := coNP^{\Sigma_i}$$

complement of
 NP^{Σ_i}

TH with
an oracle to
 Σ_i .

① Intuition of $\Sigma_{i+1} \times \Pi_{i+1}$

nondet.
drones.



NP ... some $Ans_i = \text{true}$... return true.

otherwise ... return false.

coNP ... all $Ans_i = \text{true}$... return true

otherwise ... return false

② We may assume the oracle for $\Sigma_{\tilde{i}}$ only.

Similar to the use of a solver for SAT

to solve Validity.

③ $\Sigma_1 = NP$, $\Pi_1 = coNP$.

(a) Σ_i -SAT ... Σ_j -complete

Π_i -SAT ... Π_j -complete

Intuitively, the use of Π_i in the def'n of Σ_{i+1} , and " Σ_i " in the " Π_{i+1} " corresponds to the alternation of quantifiers.

$$\text{PH} = \bigcup_{i=0}^{\infty} \Sigma_i = \bigcup_{i=0}^{\infty} \Pi_i$$

$\text{PH} \subseteq \text{PSPACE}$ (Think about

Σ_i -SAT, Π_i -SAT,
TQBF)

(b) People believe that $\text{PH} \neq \text{PSPACE}$.

① If PH has a complete pb,
then $\exists j$ s.t. $\text{PH} = \Sigma_j$.

(\because the pb should belong to Σ_i).

thus, collapse of the hierarchy.

② But PSPACE has a complete pb,
such as TQBF.

People think that
this is unlikely.

④ VC-Dim = { $\langle S, k \rangle : \text{VC-dim}(S) \geq k$ }

① VC-Dim $\stackrel{?}{=} \Sigma_3$

② Prove this by reduction from $\Sigma_3 \text{SAT}$.

$$\exists \vec{p} \forall \vec{q} \exists \vec{r} F \quad \mapsto \quad \langle S, k+1 \rangle.$$

⋮

(shattered. $S = \{S_1, \dots, S_m\}$)
 $\text{VC-dim. } \underbrace{\text{max shattered}}_{\text{size of } S_m}$

$$(\vec{u}, \vec{v}, \vec{v}', \vec{w}) \in \{0,1\}^k \times \{0,1\}^k \times \{0,1\}^k \times \{0,1\}^k.$$

$$S(\vec{u}, \vec{v}, \vec{v}', \vec{w}) \subseteq \{0,1\}^k \times \{1, \dots, k+1\}.$$

$$= \{(\vec{y}, z) \mid \vec{y} = \vec{u} \text{ and.}$$

$$(\vec{v}' \vec{v})_z = 1\}$$

$$S = \{S(\vec{u}, \vec{v}, \vec{v}', \vec{w}) \mid F(\vec{u}, \vec{v}, \vec{w}) \text{ is true}\}.$$

Then, $\exists \vec{p} \forall \vec{q} \exists \vec{r} F \text{ true iff.}$

$$\text{VC-dim}(S) \geq k+1.$$

* $\forall \vec{q} \exists \vec{r} F[\vec{a}/\vec{p}] \text{ true.}$

$\Rightarrow \{(\vec{a}, 1), \dots, (\vec{a}, k+1)\} \stackrel{?}{=} \text{shattered.}$

by $S_0 = \{S(\vec{a}, \vec{v}, \vec{v}', \vec{w}) \mid F(\vec{a}, \vec{v}, \vec{w}) \text{ true}\}.$

$$\therefore \text{VC-dim} \geq k+1$$

* VC-dim $\geq k+1$

$\{\vec{y}_1, z_1, \dots, \vec{y}_{k+1}, z_{k+1}\}$. B shattered.

But || $\exists \vec{a} \in \{0,1\}^k$ s.t.

$\{\vec{a}, 1, \dots, \vec{a}, k+1\}$.

Thus, $\forall \vec{q} \exists \vec{x} F(\vec{a}, \vec{q}, \vec{x})$ true.

each shattering set implies
the existence of \vec{x} for each \vec{q} .