



PROGRAMMING LANGUAGES LABORATORY

Universidade Federal de Minas Gerais - Department of Computer Science



CONTROL FLOW GRAPHS

PROGRAM ANALYSIS AND OPTIMIZATION – DCC888

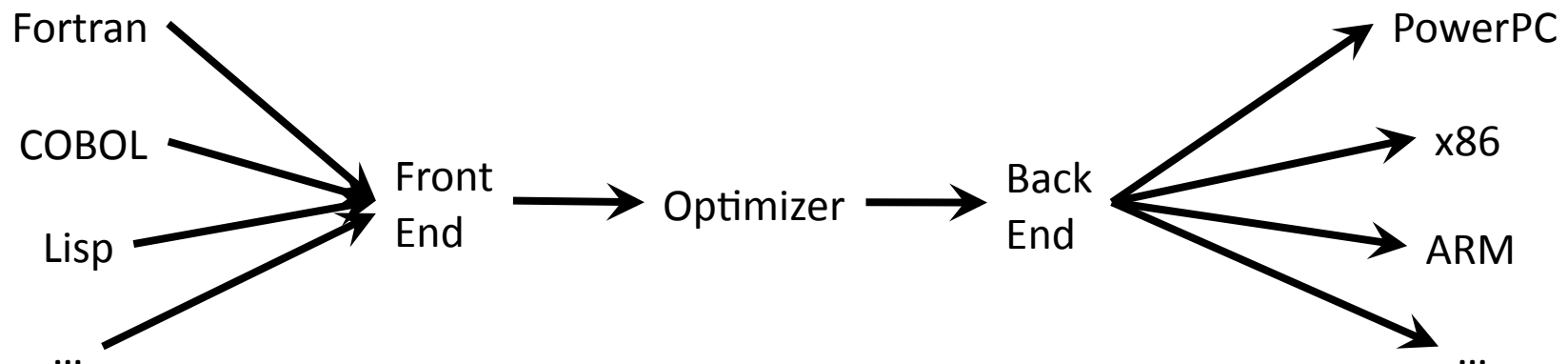
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The material in these slides have been taken from the "Dragon Book", Secs 8.5 – 8.7, by Aho *et al.*

Intermediate Program Representations

- Optimizing compilers and human beings do not see the program in the same way.
 - We are more interested in source code.
 - But, source code is too different from machine code.
 - Besides, from an engineering point of view, it is better to have a common way to represent programs in different languages, and target different architectures.



Basic Blocks and Flow Graphs

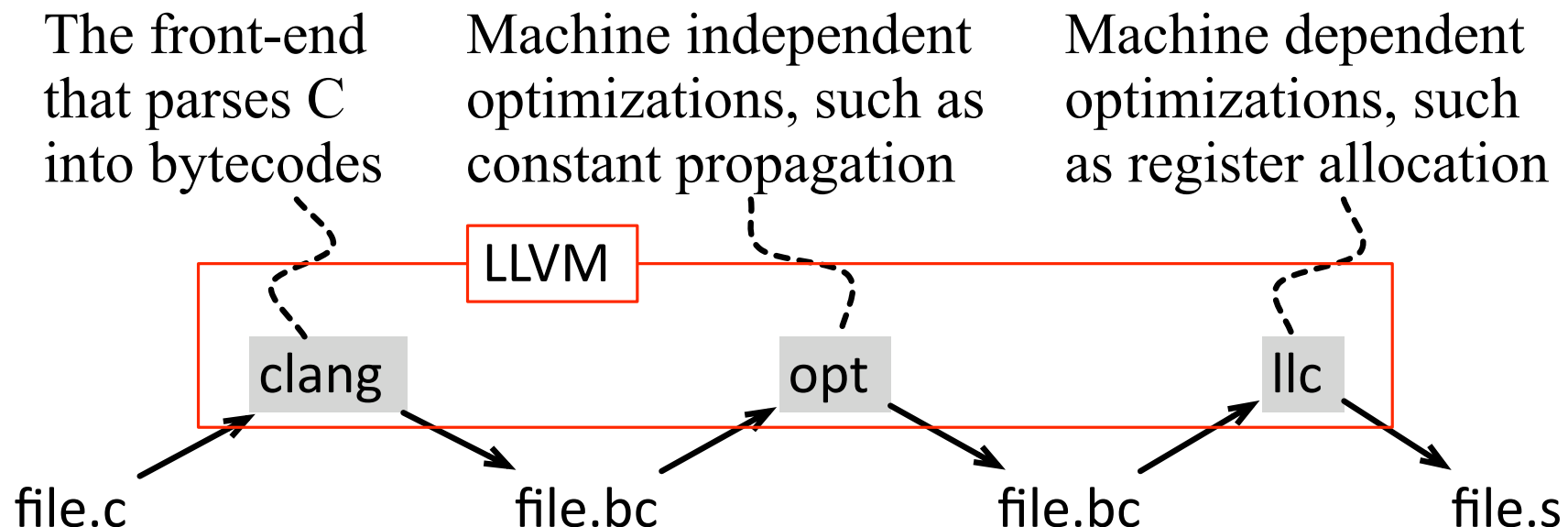
- Usually compilers represent programs as *control flow graphs* (CFG).
- A control flow graph is a directed graph.
 - Nodes are *basic blocks*.
 - There is an edge from basic block B_1 to basic block B_2 if program execution can flow from B_1 to B_2 .
- Before defining basic block, we will illustrate this notion by showing the CFG of the function on the right.

What does
this program
do?

```
void identity(int** a, int N) {  
    int i, j;  
    for (i = 0; i < N; i++) {  
        for (j = 0; j < N; j++) {  
            a[i][j] = 0;  
        }  
    }  
    for (i = 0; i < N; i++) {  
        a[i][i] = 1;  
    }  
}
```

The Low Level Virtual Machine

- We will be working with a compilation framework called The *Low Level Virtual Machine*, or LLVM, for short.
- LLVM is today the most used compiler in research.
- Additionally, this compiler is used in many important companies: Apple, Cray, Google, etc.



Using LLVM to visualize a CFG

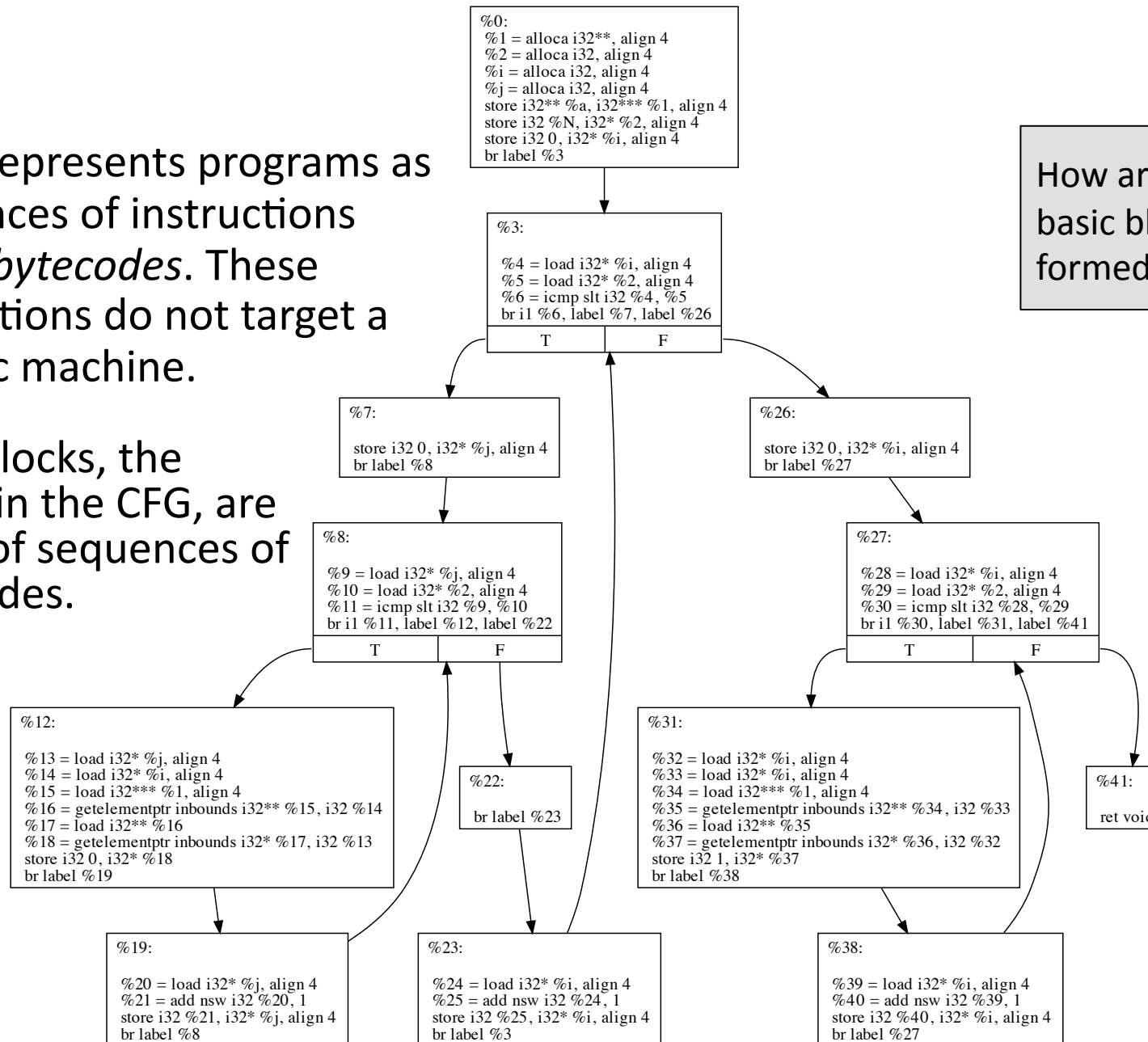
- We can use the `opt` tool, the LLVM machine independent optimizer, to visualize the control flow graph of a given function

```
$> clang -c -emit-llvm identity.c -o identity.bc  
  
$> opt -view-cfg identity.bc
```

- We will be able to see the CFG of our target program, as long as we have the tool DOT installed in our system.

- LLVM represents programs as sequences of instructions called *bytecodes*. These instructions do not target a specific machine.
- Basic blocks, the nodes in the CFG, are made of sequences of bytecodes.

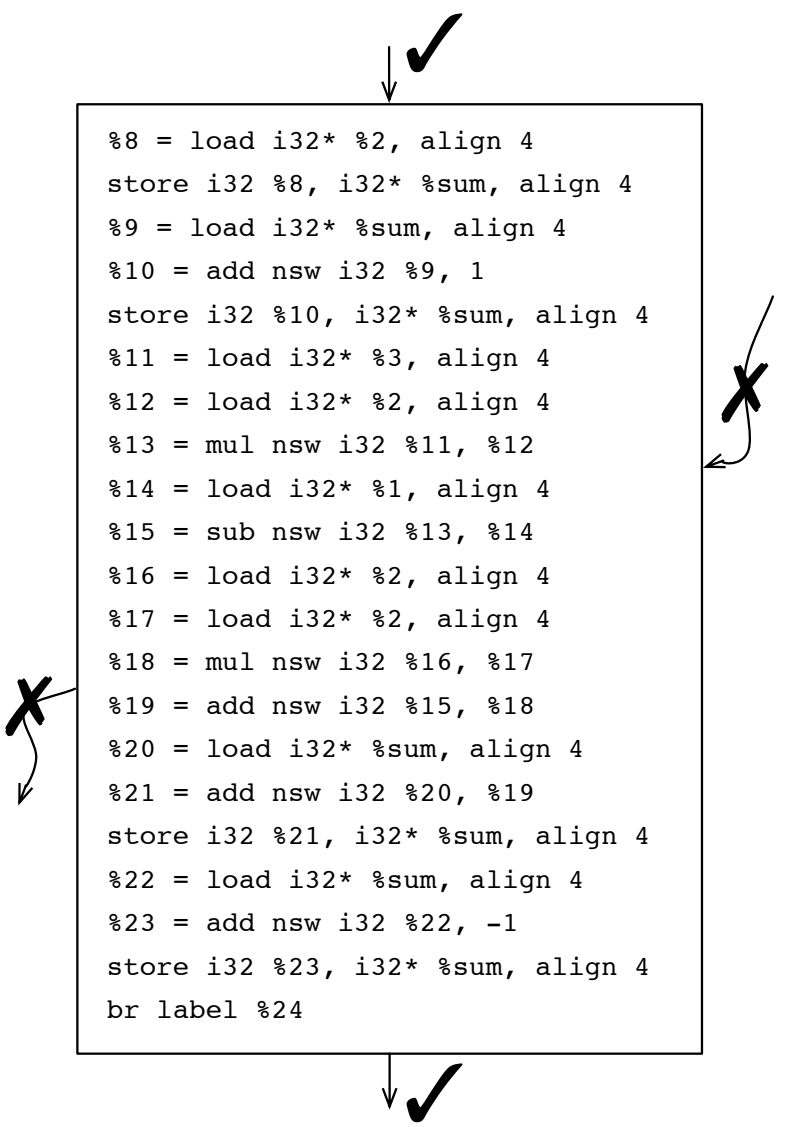
How are the basic blocks formed?



Basic Blocks

How can we identify basic blocks from linear sequences of instructions?

- Basic blocks are maximal sequences of consecutive instructions with the following properties:
 - The flow of control can only enter the basic block through the first instruction in the block.
 - There are no jumps into the middle of the block.
 - Control will leave the block without halting or branching, except possibly at the last instruction in the block.



The diagram shows a rectangular box containing a sequence of assembly instructions. An arrow with a checkmark points to the top of the box, indicating a valid entry point. An arrow with a cross points to the right side of the box, indicating an invalid entry point. An arrow with a cross points to the left side of the box, indicating an invalid exit point. An arrow with a checkmark points to the bottom of the box, indicating a valid exit point.

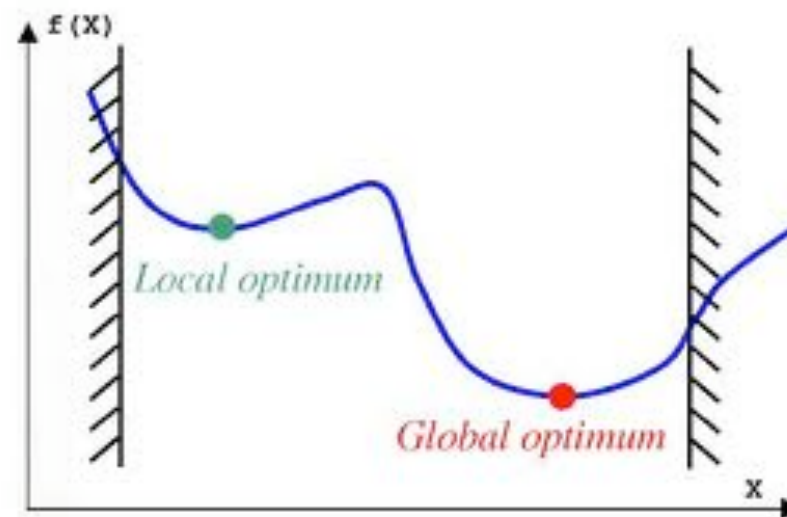
```
%8 = load i32* %2, align 4
store i32 %8, i32* %sum, align 4
%9 = load i32* %sum, align 4
%10 = add nsw i32 %9, 1
store i32 %10, i32* %sum, align 4
%11 = load i32* %3, align 4
%12 = load i32* %2, align 4
%13 = mul nsw i32 %11, %12
%14 = load i32* %1, align 4
%15 = sub nsw i32 %13, %14
%16 = load i32* %2, align 4
%17 = load i32* %2, align 4
%18 = mul nsw i32 %16, %17
%19 = add nsw i32 %15, %18
%20 = load i32* %sum, align 4
%21 = add nsw i32 %20, %19
store i32 %21, i32* %sum, align 4
%22 = load i32* %sum, align 4
%23 = add nsw i32 %22, -1
store i32 %23, i32* %sum, align 4
br label %24
```

Identifying Basic Blocks

- The first instruction of a basic block is called a *leader*.
- We can identify leaders via these three properties:
 1. The first instruction in the intermediate code is a leader.
 2. Any instruction that is the target of a conditional or unconditional jump is a leader.
 3. Any instruction that immediately follows a conditional or unconditional jump is a leader.
- Once we have found the leaders, it is straightforward to find the basic blocks:
 - For each leader, its basic block consists of the leader itself, plus all the instructions until the next leader.



LOCAL OPTIMIZATIONS



Local Optimization

- Code optimization techniques that work in the scope of a basic block are called *local optimizations*.
 - DAG based optimizations
 - Peephole optimizations
 - Local register allocation
- Code optimization techniques that need to analyze the entire control flow graph of a program are called *global optimizations*.
 - Most of the optimizations that we will see in this course are global optimizations.

1) Can you think about a concrete local optimization?

2) Can you think about any global optimization?

3) Can you think about any larger scope of optimization?

DAG-Based Optimizations

- Some of the earliest code optimizations that compilers have performed would rely on a directed acyclic representation of the instructions in the basic block. These DAGS were constructed as follows:
 - There is a node in the DAG for each *input value* appearing in the basic block.
 - There is a node associated with each instruction in the basic block.
 - If instruction S uses variables defined in statements S_1, \dots, S_2 , then we have edges from each S_i to S .
 - If a variable is defined in the basic block, but is not used inside it, then we mark it as an *output value*.

Example of DAG Representation

- | | |
|----------------|---|
| 1: $a = b + c$ | • In the program on the left, we have that b, c and d are input values, because they are used in the basic block, but are not defined before the first use. |
| 2: $b = a - d$ | |
| 3: $c = b + c$ | • We say that the definitions of c and d, at lines 3 and 4, are output values, because these definitions are not used in the basic block. |
| 4: $d = a - d$ | |

What is the DAG representation of this basic block?

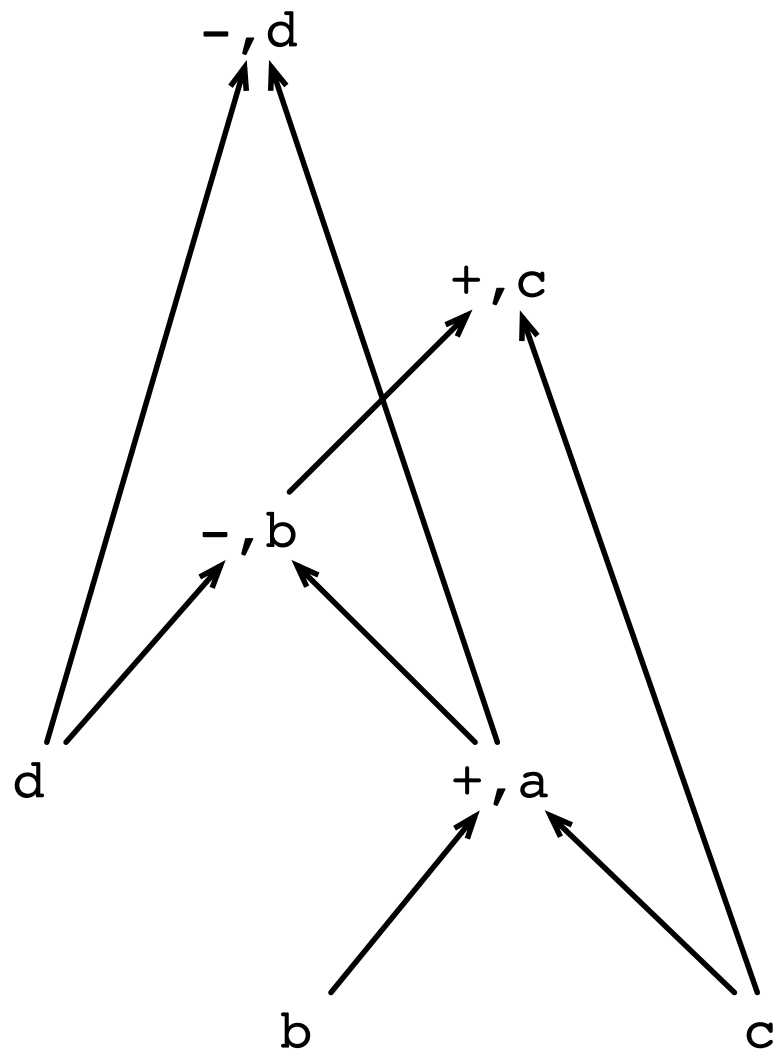
Example of DAG Representation

1: $a = b + c$

2: $b = a - d$

3: $c = b + c$

4: $d = a - d$



Could you design
a simple algorithm
to create DAGs
from basic blocks?

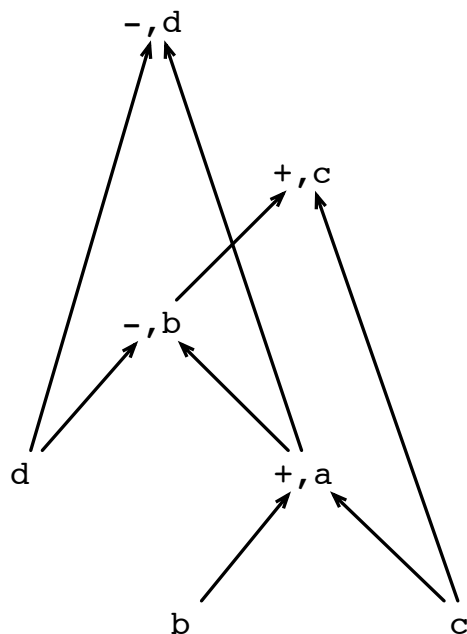
Example of DAG Representation

1: $a = b + c$

2: $b = a - d$

3: $c = b + c$

4: $d = a - d$



- For each input value v_i :
 - create a node v_i in the DAG
 - label this node with the tag ***in***
- For each statement $v = f(v_1, \dots, v_n)$, in the sequence defined by the basic block:
 - create a node v in the DAG
 - create an edge (v_i, v) for each $i, 1 \leq i \leq n$
 - label this node with the tag ***f***

1) Could you optimize this DAG in particular?

2) Can you think about any optimization that we could perform in general?

Finding Local Common Subexpressions

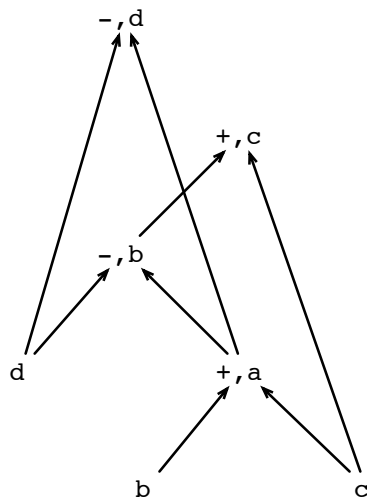
1: $a = b + c$

2: $b = a - d$

3: $c = b + c$

4: $d = a - d$

- For each input value v_i :
 - create a node v_i in the DAG
 - label this node with the tag *in*
- For each statement $v = f(v_1, \dots, v_n)$, in the sequence defined by the basic block:
 - create a node v in the DAG
 - create an edge (v_i, v) for each $i, 1 \leq i \leq n$
 - label this node with the tag *f*



How could we adapt our algorithm to reuse expressions that have already been created?

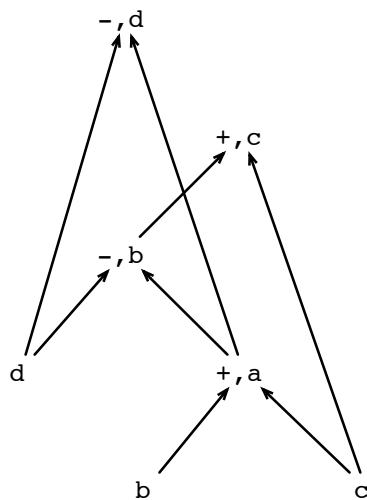
Finding Local Common Subexpressions

1: $a = b + c$

2: $b = a - d$

3: $c = b + c$

4: $d = a - d$



1. For each input value v_i :

1. create a node v_i in the DAG
2. label this node with the tag ***in***

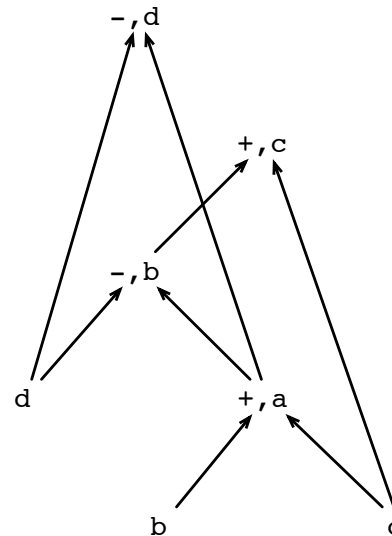
2. For each statement $v = f(v_1, \dots, v_n)$, in the sequence defined by the basic block:

1. If the DAG already **contains** a node v' labeled f , with all the children (v_1, \dots, v_n) in the order given by i , $1 \leq i \leq n$
 1. Let v' be an alias of v in the DAG
2. else:
 1. create a node v in the DAG
 2. create an edge (v_i, v) for each i , $1 \leq i \leq n$
 3. label this node with the tag ***f***

How can we check **this** property?

Value Numbers

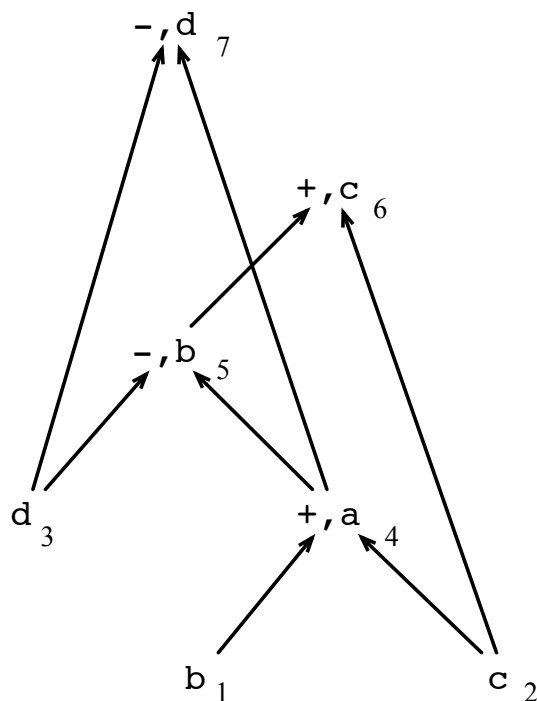
- We can associate each node in the DAG with a signature (lb, v_1, \dots, v_n) , where lb is the label of the node, and each v_i , $1 \leq i \leq n$ is a child of the node
 - We can use this signature as the key of a *hash-function*
 - The value produced by the hash-function is called the *value-number* of that variable
- Thus, whenever we build a new node to our DAG, e.g., step 2.1 of our algorithm, we perform a search in the hash-table. If the node is already there, we simply return a reference to it, instead of creating a new node.



What is the result of optimizing this DAG?

Value Numbers

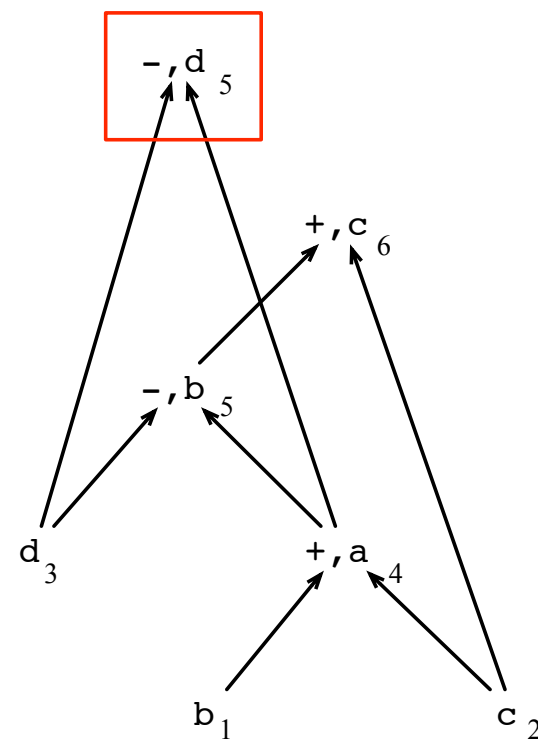
- Value numbers allows us to refer to nodes in our DAG by their semantics, instead of by their textual program representation.



Original DAG

1 (b)	\rightarrow	(in, _)
2 (c)	\rightarrow	(in, _)
3 (d)	\rightarrow	(in, _)
4 (a = b + c)	\rightarrow	(+, 1, 2)
5 (b = d - a)	\rightarrow	(-, 3, 4)
6 (c = b + c)	\rightarrow	(+, 5, 2)
7 (d = d - a)	\rightarrow	(-, 3, 4)

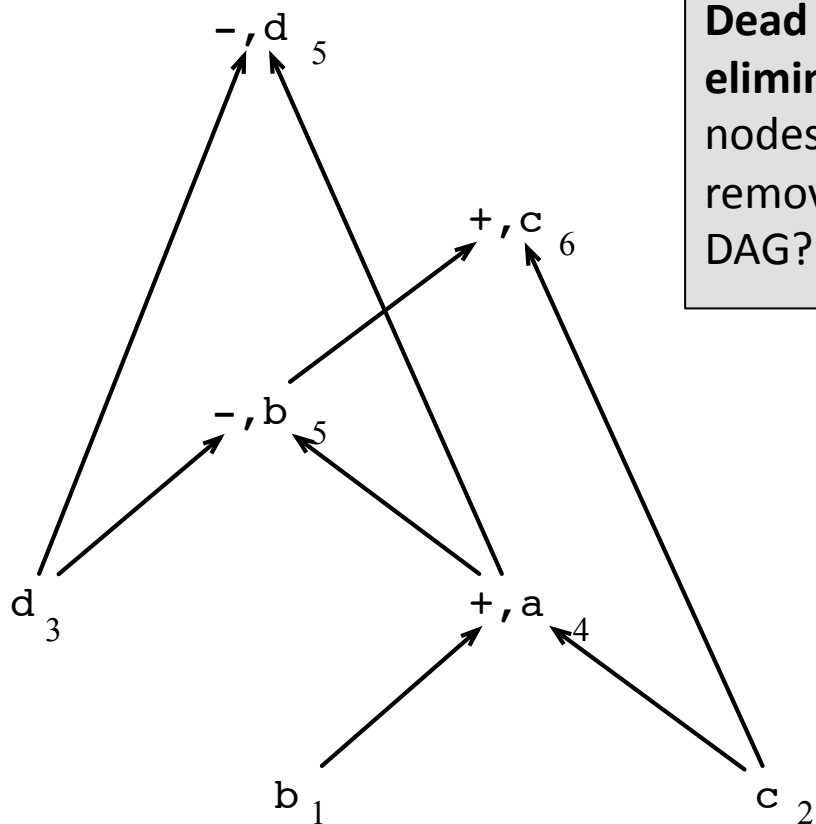
Value-Number Table



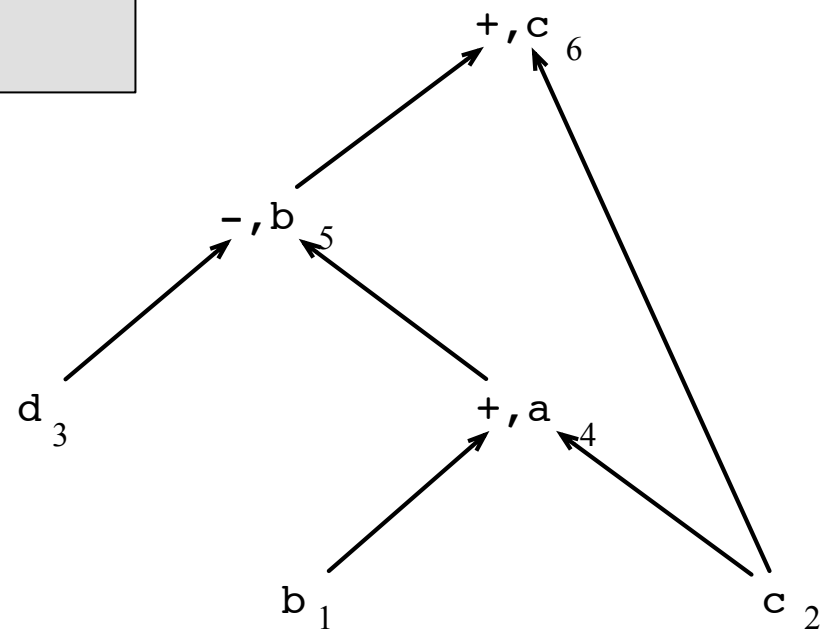
Optimized DAG

Value Numbers

**Dead code
elimination:** which
nodes can be safely
removed from the
DAG?



Original DAG



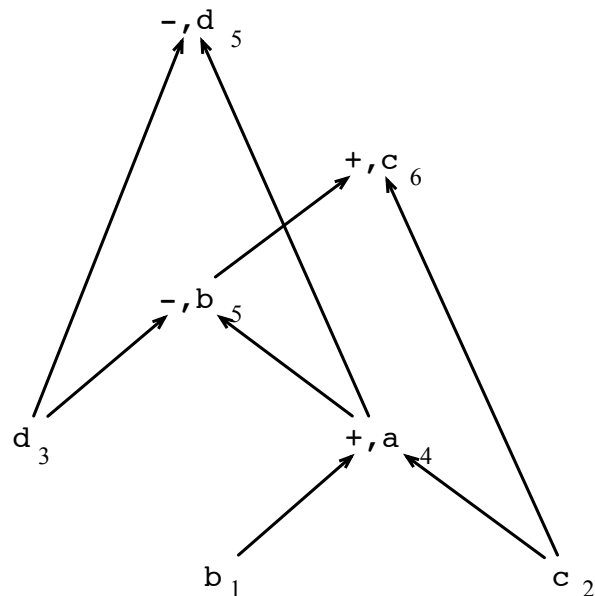
Optimized DAG

Finding more identities

- We can use several tricks to find common subexpressions in DAGs
 - Commutativity: the value number of $x + y$ and $y + x$ should be the same.
 - Identities: the comparison $x < y$ can often be implemented by $t = x - y; t < 0$
 - Associativity:
$$\begin{array}{l} a = b + c \\ t = c + d \\ e = t + b \end{array} \quad \longrightarrow \quad \begin{array}{l} a = b + c \\ e = a + d \end{array}$$

Dead Code Elimination

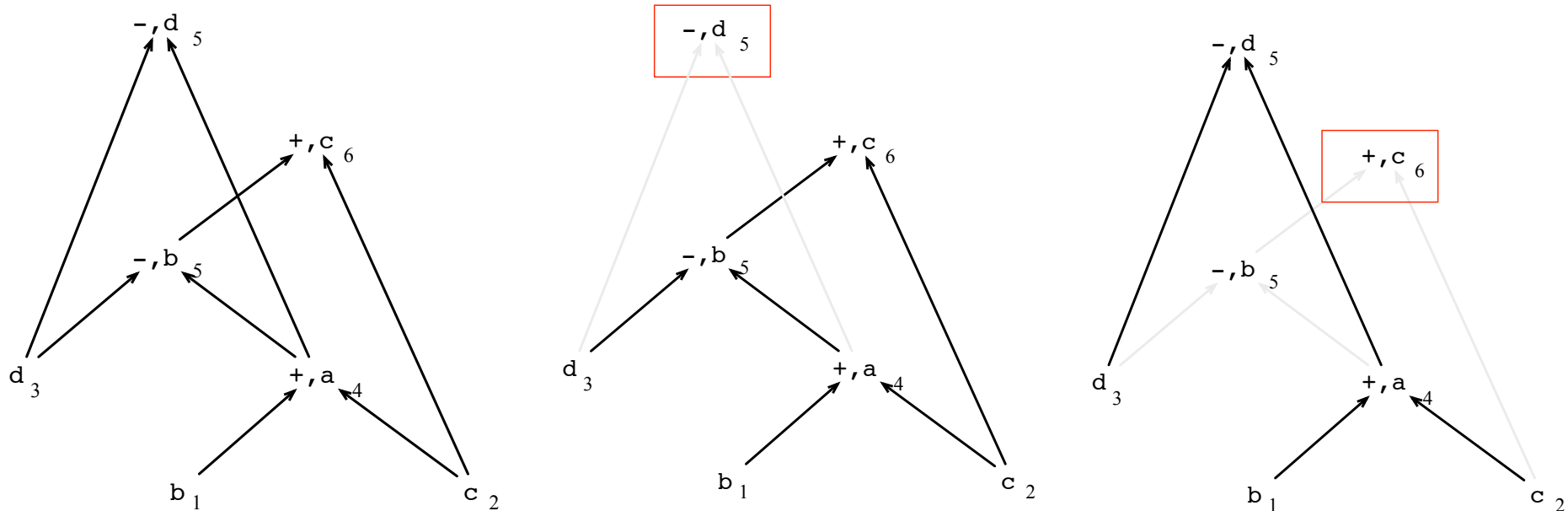
- We can eliminate any node if:
 - This node has no ancestors, e.g., it is a *root node*.
 - This node is not marked as an *output node*.
- We can iterate this pattern of eliminations until we have no more nodes that we can remove.



- Which nodes could we eliminate if $(-, d)$ were not an output node?
- Which nodes could we eliminate if $(+, c)$ were not an output node?

Dead Code Elimination

- We can eliminate any node if:
 - This node has no ancestors, e.g., it is a *root node*.
 - This node is not marked as an *output node*.
- We can iterate this pattern of eliminations until we have no more nodes that we can remove.



Algebraic Identities

- We can explore algebraic identities to optimize DAGs
 - Arithmetic Identities:
 - $x + 0 = 0 + x = x$; $x * 1 = 1 * x = x$; $x - 0 = x$; $x / 1 = x$
 - Reduction in strength:
 - $x^2 = x * x$; $2 * x = x + x$; $x / 2 = x * 0.5$ ←
 - Constant folding:
 - evaluate expressions at compilation time, replacing each expression by its value

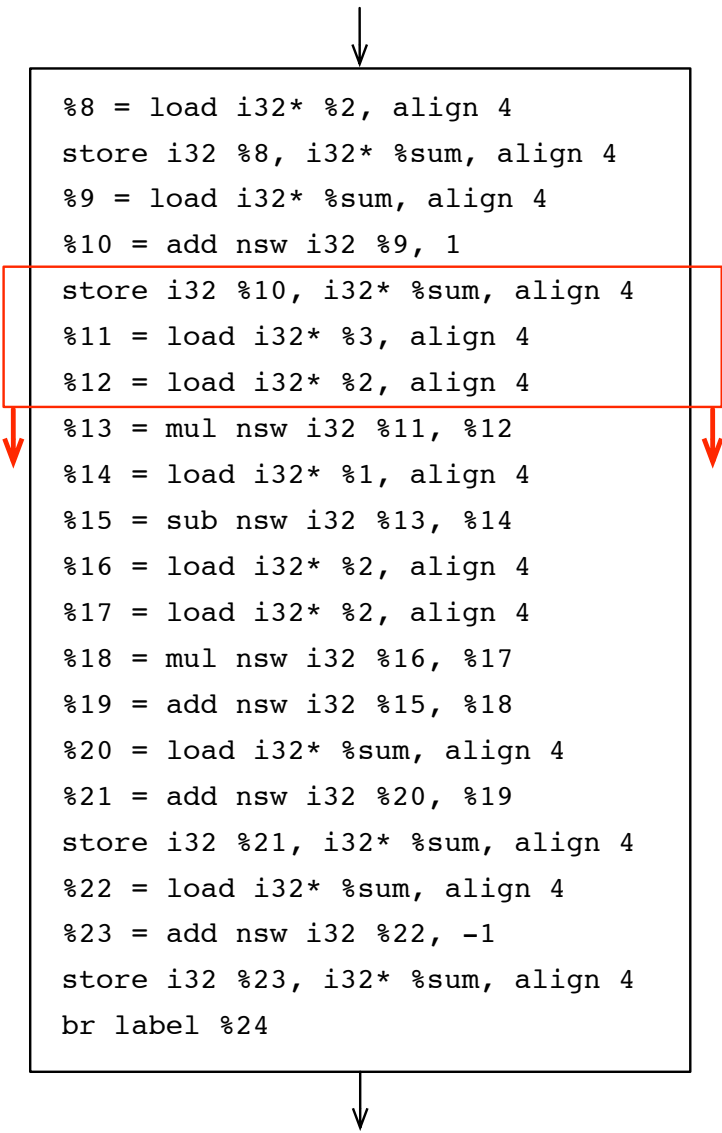
Reduction in strength optimizes code by replacing some sequences of instructions by others, which can be computed more efficiently.

Could you provide a rational for each of these reductions in strength?

Peephole Optimizations

How to find the best window size?

- Peephole optimizations are a category of local code optimizations.
- The principle is very simple:
 - the optimizer analyzes sequences of instructions.
 - only code that is within a small window of instructions is analyzed each time.
 - this window slides over the code.
 - once patterns are discovered inside this window, optimizations are applied.



```
%8 = load i32* %2, align 4
store i32 %8, i32* %sum, align 4
%9 = load i32* %sum, align 4
%10 = add nsw i32 %9, 1
store i32 %10, i32* %sum, align 4
%11 = load i32* %3, align 4
%12 = load i32* %2, align 4
%13 = mul nsw i32 %11, %12
%14 = load i32* %1, align 4
%15 = sub nsw i32 %13, %14
%16 = load i32* %2, align 4
%17 = load i32* %2, align 4
%18 = mul nsw i32 %16, %17
%19 = add nsw i32 %15, %18
%20 = load i32* %sum, align 4
%21 = add nsw i32 %20, %19
store i32 %21, i32* %sum, align 4
%22 = load i32* %sum, align 4
%23 = add nsw i32 %22, -1
store i32 %23, i32* %sum, align 4
br label %24
```


Redundant Loads and Stores

- Some memory access patterns are clearly redundant:

```
load R0, m  
store m, R0
```

1) This code is very naïve.
How could it appear in
actual assembly programs?

- Patterns like this can be easily eliminated by a peephole optimizer.

2) Why is this
optimization only
safe inside a basic
block?

Branch Transformations

- Some branches can be rewritten into faster code. For instance:

```
if debug == 1 goto L1
goto L2
L1: ...
L2: ...
```

```
if debug != 1 goto L2
L1: ...
L2: ...
```

- This optimization crosses the boundaries of basic blocks, but it is still performed on a small sliding window.

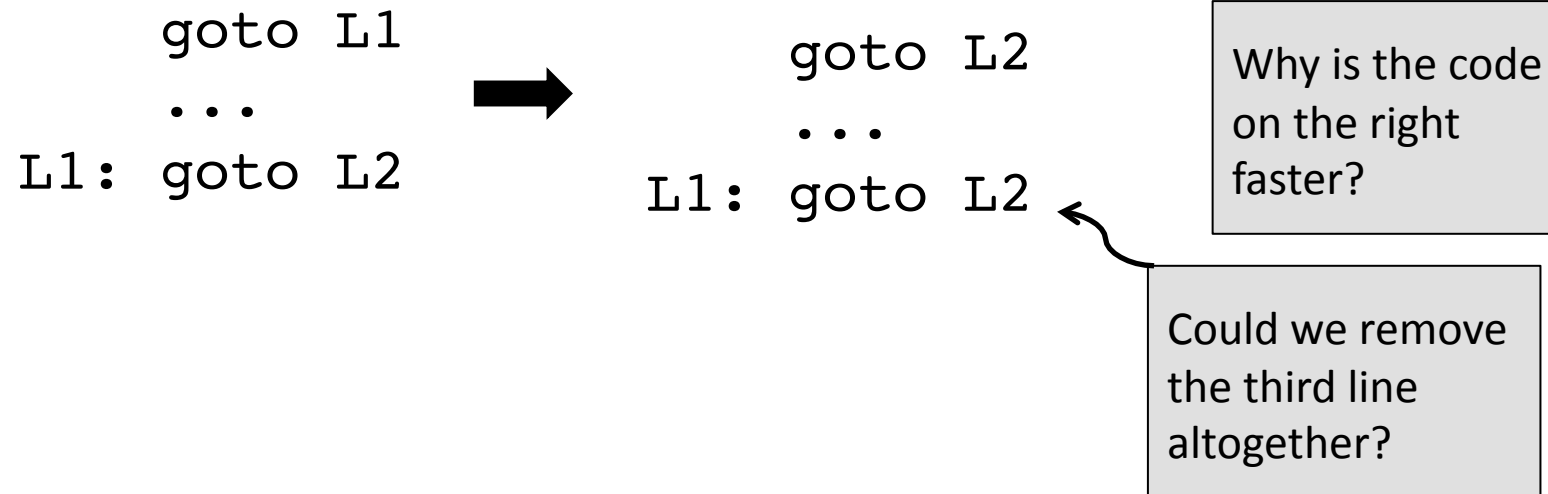
Jumps to Jumps

- How could we optimize this code sequence?

```
    goto L1  
    ...  
L1: goto L2
```

Jumps to Jumps

- How could we optimize this code sequence?



Jumps to Jumps

- How could we optimize this code sequence?

```
      goto L1  
      ...  
L1: goto L2
```

→

```
      goto L2  
      ...  
L1: goto L2
```

→

```
      goto L2  
      ...
```

- We can eliminate the second jump, provided that we know that there is no jump to L1 in the rest of the program.
 - Why?
- Notice that this peephole optimization requires some previous information gathering: we must know which instructions are targets of jumps.

Jumps to Jumps

- How could we optimize this code sequence?

We saw how to optimize the sequence on the right. Does the same optimization applies on the code below?

```
goto L1  
...  
L1: goto L2
```

```
if a < b goto L1  
...  
L1: goto L2
```

Jumps to Jumps

- How could we optimize this code sequence?
 - Under which assumptions is your optimization valid?

```
        goto L1
        ...
L1:  if a < b goto L2
L3:
```

Jumps to Jumps

- How could we optimize this code sequence?
 - Under which assumptions is your optimization valid?

```
        goto L1                                if a < b goto L2
        ...                                    goto L3
L1:  if a < b goto L2                          ...
L3:                                     L3:
```

- In order to apply this optimization, we need to make sure that:
 - There is no jump to L1
 - L1 is preceded by an unconditional goto.

Why are these assumptions necessary?

Reduction in Strength

- Instead of performing reduction in strength at the DAG level, many compilers do it via a peephole optimizer.
 - This optimizer allows us to replace sequences such as $4 * x$ by, $x \ll 2$, for instance.

$4 * x$ is a pattern that is pretty common in loops that range over 32-bit words. Why?

Machine Idioms

- Many computer architectures have efficient instructions to implement some common operations.
 - A typical example is found in the increment and decrement operators:

`addl $1, %edi` ➡ `incl %edi`

Is there any other
machine idioms
that we could think
about?

Local Register Allocation

- Registers are memory locations which have very fast memory access.
- However, registers exist in small number. For instance, the 32-bits x86 processor has eight visible registers.
- A key optimization consists in mapping the most used variables in a program onto registers.
- Compilers usually need to see the entire function (or even the whole program) to perform a good register allocation.
- But, if we need to do it quickly, we can only look into a basic block. In this case, we are doing *local register allocation*.

- 1) What are the most used variables in a program?
- 2) Why is it better to see the entire function, instead of a basic block, to do better register allocation?
- 3) Why would we be willing to do register allocation quickly?
- 4) How could we find registers for the variables in a basic block?

Registers vs Memory

```
int arith(int a1, int an, int N) {  
    return (a1 + an) * N / 2;  
}
```

_arith_all_mem: ←

BB#0:

```
subl $12,%esp  
movl 16(%esp),%eax  
movl %eax,8(%esp)  
movl 20(%esp),%eax  
movl %eax,4(%esp)  
movl 24(%esp),%eax  
movl %eax,(%esp)  
movl 8(%esp),%ecx  
addl 4(%esp),%ecx  
imull %eax,%ecx  
movl %ecx,%eax  
shrl $31,%eax  
addl %ecx,%eax  
sarl %eax  
addl $12,%esp  
ret
```

_arith_reg_alloc: ←

BB#0:

```
movl 4(%esp),%ecx  
addl 8(%esp),%ecx  
imull 12(%esp),%ecx  
movl %ecx,%eax  
shrl $31,%eax  
addl %ecx,%eax  
sarl %eax  
ret
```

The program that uses registers is substantially faster than the program that maps all the variables to memory. It is shorter too, as we do not need so many loads and stores to move variables to and from memory.

1) Why we do not need to worry about "memory allocation"?

2) Can you think about an algorithm to find registers for the variables inside a basic block?

Local Register Allocation

```
allocate(Block b) {  
  for (Inst i = b.first_inst; i != b.last_inst; i++) {  
    for (Operand o = i.first_operand; o != i.last_operand; o++) {  
      if (o is in memory m) {  
        r = find_reg(i)  
        assign r to o  
        add "r = load m" before i  
      }  
    }  
    v = i.definition  
    r = find_reg(i)  
    assign r to v  
  }  
  for (Operand o = i.first_operand; o != i.last_operand; o++) {  
    if (i is the last use of o) {  
      return the register bound to o to the list of free registers  
    }  
  }  
}
```

- 1) Why do we need to insert this load instruction in our code?
- 2) When are registers mapped into memory?
- 3) How would be the implementation of `find_reg`?

Spilling

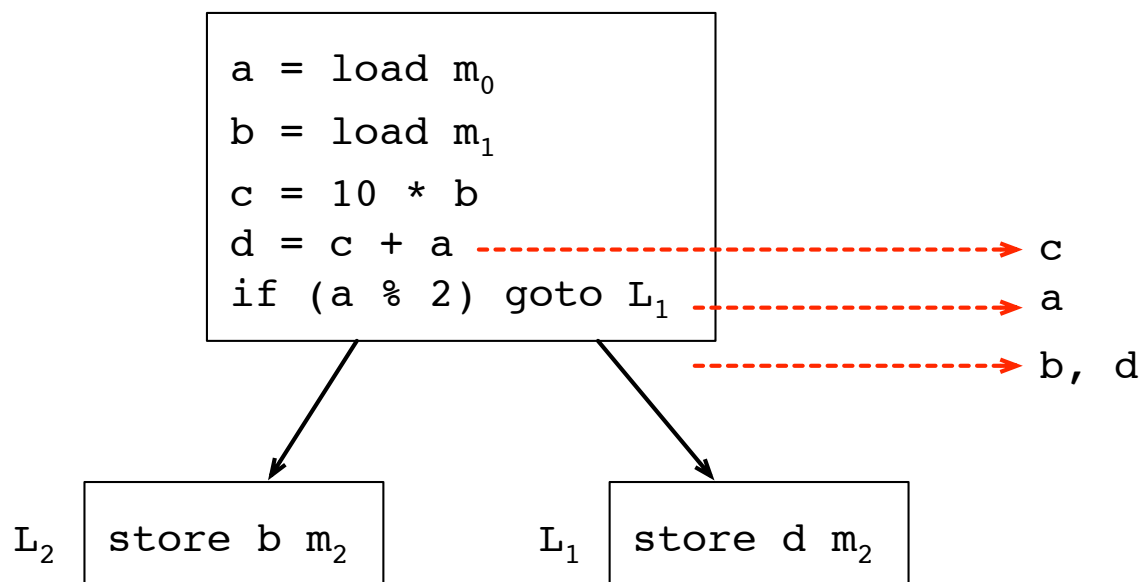
```
find_reg(i) {  
  if there is free register r  
    return r  
  else  
    let v be the last used variable after i, that is in a register  
    if v is does not have a memory slot  
      let m be a fresh memory slot  
      add "store v m" right after the definition point of v  
    else  
      let m be the memory slot assigned to v  
    return r  
}
```

If the *register pressure* is too high, we may have to evict some variable to memory. This action is called *spilling*. If a variable is mapped into memory, then we call it a *spill*.

- 1) Why do we spill the variable that has the last use after the current instruction i?
- 2) Why do we need to insert this store in our code?
- 3) How many stores can we have per variable?

Spilling the Furthest Use

- Usually we spill the variable that has the furthest use from the spilling point.
- This strategy is called the Belady♣ Algorithm, and it is also used in operating systems, when deciding which page to evict to disk in the virtual memory system.



But we must be careful when doing local register allocation, because if a variable is used after the basic block, we must assume that it has a use at the end of the block.



A QUICK INTRO TO LLVM



DCC 888

LLVM is a Compilation Infra-Structure

- It is a framework that comes with lots of tools to compile and optimize code.

```
$> cd llvm/Debug+Asserts/bin
$> ls
FileCheck          count          llvm-dis        llvm-stress
FileUpdate         diagtool      llvm-dwarfdump  llvm-symbolizer
arcmt-test         fpcmp        llvm-extract    llvm-tblgen
bugpoint           llc         llvm-link       macho-dump
c-arcmt-test       lli         llvm-lit        modularize
c-index-test       lli-child-target llvm-lto        not
clang            llvm-PerfectSf llvm-mc         obj2yaml
clang++         llvm-ar      llvm-mcmarkup  opt
llvm-as            llvm-nm      pp-trace       llvm-size
clang-check        llvm-bcanalyzer llvm-objdump   rm-cstr-calls
clang-format       llvm-c-test  llvm-ranlib    tool-template
clang-modernize    llvm-config  llvm-readobj   yaml2obj
clang-tblgen       llvm-cov     llvm-rtdyld    llvm-diff
clang-tidy
```

LLVM is a Compilation Infra-Structure

- Compile C/C++ programs:

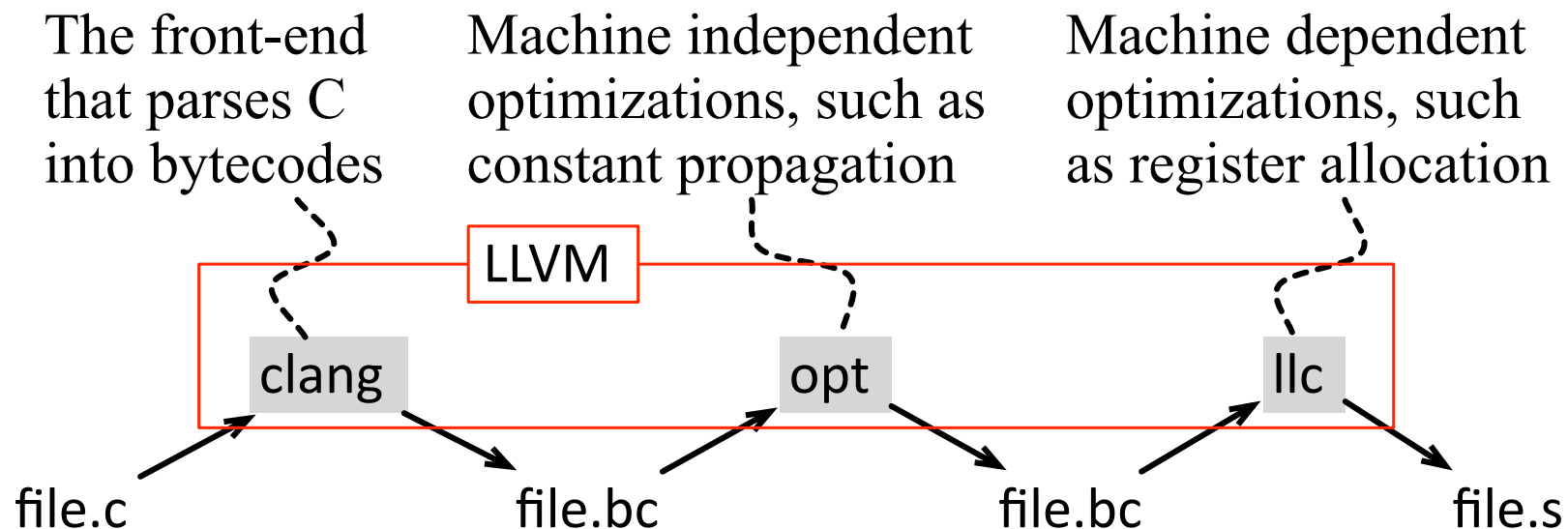
```
$> echo "int main() {return 42;}" > test.c  
$> clang test.c  
$> ./a.out  
$> echo $?  
42
```

clang/clang++ are very competitive when compared with, say, gcc, or icc. Some of these compilers are faster in some benchmarks, and slower in others. Usually clang/clang++ have faster compilation times. The Internet is crowded with benchmarks.



Optimizations in Practice

- The **opt** tool, available in the LLVM toolbox, performs machine independent optimizations.
- There are many optimizations available through opt.
 - To have an idea, type `opt --help`.



Optimizations in Practice

```
$> opt --help
```

```
Optimizations available:
```

-adce	- Aggressive Dead Code Elimination
-always-inline	- Inliner for always_inline functions
-break-crit-edges	- Break critical edges in CFG
-codegenprepare	- Optimize for code generation
-constmerge	- Merge Duplicate Global Constants
-constprop	- Simple constant propagation
-correlated-propagation	- Value Propagation
-dce	- Dead Code Elimination
-deadargelim	- Dead Argument Elimination
-die	- Dead Instruction Elimination
-dot-cfg	- Print CFG of function to 'dot' file
-dse	- Dead Store Elimination
-early-cse	- Early CSE
-globaldce	- Dead Global Elimination
-globalopt	- Global Variable Optimizer
-gvn	- Global Value Numbering
-indvars	- Induction Variable Simplification
-instcombine	- Combine redundant instructions
-instsimplify	- Remove redundant instructions
-ipconstprop	- Interprocedural constant propagation
-loop-reduce	- Loop Strength Reduction
-reassociate	- Reassociate expressions
-reg2mem	- Demote all values to stack slots
-sccp	- Sparse Conditional Constant Propagation
-scev-aa	- ScalarEvolution-based Alias Analysis
-simplifycfg	- Simplify the CFG
...	

What do you think
each of these
optimizations do?

Levels of Optimizations

- Like gcc, clang supports different levels of optimizations, e.g., -O0 (default), -O1, -O2 and -O3.
- To find out which optimization each level uses, you can try:

llvm-as is the LLVM assembler. It reads a file containing human-readable LLVM assembly language, translates it to LLVM bytecode, and writes the result into a file or to standard output.

```
$> llvm-as < /dev/null | opt -O3 -disable-output -debug-pass=Arguments
```

In my system (LLVM/Darwin), -O1 gives me:

-targetlibinfo -no-aa -tbaa -basicaa -notti -globalopt -ipsccp -deadargelim -instcombine -simplifycfg -basiccg -prune-eh -inline-cost -always-inline -functionattrs -sroa -domtree -early-cse -lazy-value-info -jump-threading -correlated-propagation -simplifycfg -instcombine -tailcallelim -simplifycfg -reassociate -domtree -loops -loop-simplify -lcssa -loop-rotate -licm -lcssa -loop-unswitch -instcombine -scalar-evolution -loop-simplify -lcssa -indvars -loop-idiom -loop-deletion -loop-unroll -memdep -memcpyopt -sccp -instcombine -lazy-value-info -jump-threading -correlated-propagation -domtree -memdep -dse -adce -simplifycfg -instcombine -strip-dead-prototypes -preverify -domtree -verify

Virtual Register Allocation

- One of the most basic optimizations that opt performs is to map memory slots into variables.
- This optimization is very useful, because the clang front end maps every variable to memory:

```
int main() {  
    int c1 = 17;  
    int c2 = 25;  
    int c3 = c1 + c2;  
    printf("Value = %d\n", c3);  
}
```

```
$> clang -c -emit-llvm const.c -o const.bc  
  
$> opt -view-cfg const.bc
```

```
%0:  
%1 = alloca i32, align 4  
%c1 = alloca i32, align 4  
%c2 = alloca i32, align 4  
%c3 = alloca i32, align 4  
store i32 0, i32* %1  
store i32 17, i32* %c1, align 4  
store i32 25, i32* %c2, align 4  
%2 = load i32* %c1, align 4  
%3 = load i32* %c2, align 4  
%4 = add nsw i32 %2, %3  
store i32 %4, i32* %c3, align 4  
%5 = load i32* %c3, align 4  
%6 = call @printf(...)  
%7 = load i32* %1  
ret i32 %7
```

CFG for 'main' function

Virtual Register Allocation

- One of the most basic optimizations that opt performs is to map memory slots into variables.
- We can map memory slots into registers with the `mem2reg` pass:

```
int main() {  
    int c1 = 17;  
    int c2 = 25;  
    int c3 = c1 + c2;  
    printf("Value = %d\n", c3);  
}
```

```
$> opt -mem2reg const.bc > const.reg.bc  
  
$> opt -view-cfg const.reg.bc
```

How could we
further optimize
this program?

```
%0:  
%1 = add nsw i32 17, 25  
%2 = call @printf(...), i32 %1)  
ret i32 0
```

CFG for 'main' function

Constant Propagation

- We can fold the computation of expressions that are known at compilation time with the `constprop` pass.

```
%0:  
%1 = add nsw i32 17, 25  
%2 = call @printf(...), i32 %1)  
ret i32 0
```

CFG for 'main' function



```
%0:  
%1 = call i32 @i8*, ...) * @printf(..., i32 42)  
ret i32 0
```

CFG for 'main' function

```
$> opt -constprop const.reg.bc > const.cp.bc  
  
$> opt -view-cfg const.cp.bc
```

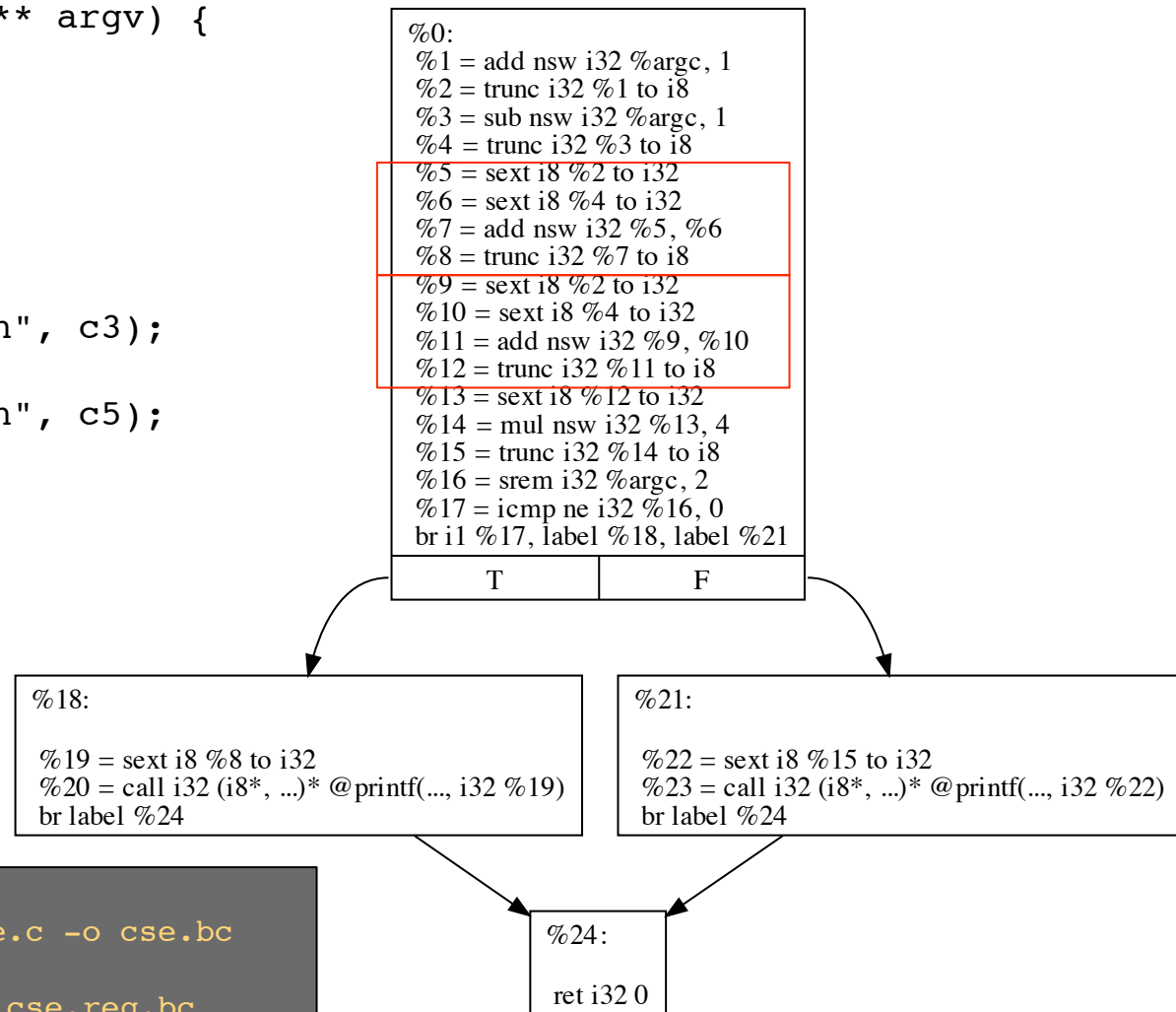
What is %1 in the left CFG? And what is i32 42 in the CFG on the right side?

One more: Common Subexpression Elimination

```
int main(int argc, char** argv) {
    char c1 = argc + 1;
    char c2 = argc - 1;
    char c3 = c1 + c2;
    char c4 = c1 + c2;
    char c5 = c4 * 4;
    if (argc % 2)
        printf("Value = %d\n", c3);
    else
        printf("Value = %d\n", c5);
}
```

How could we optimize this program?

```
$> clang -c -emit-llvm cse.c -o cse.bc
$> opt -mem2reg cse.bc -o cse.reg.bc
$> opt -view-cfg cse.reg.bc
```



One more: Common Subexpression Elimination

```
%0:
%1 = add nsw i32 %argc, 1
%2 = trunc i32 %1 to i8
%3 = sub nsw i32 %argc, 1
%4 = trunc i32 %3 to i8
%5 = sext i8 %2 to i32
%6 = sext i8 %4 to i32
%7 = add nsw i32 %5, %6
%8 = trunc i32 %7 to i8
%9 = sext i8 %2 to i32
%10 = sext i8 %4 to i32
%11 = add nsw i32 %9, %10
%12 = trunc i32 %11 to i8
%13 = sext i8 %12 to i32
%14 = mul nsw i32 %13, 4
%15 = trunc i32 %14 to i8
%16 = srem i32 %argc, 2
%17 = icmp ne i32 %16, 0
br i1 %17, label %18, label %21
```

Original Basic Block



```
%0:
%1 = add nsw i32 %argc, 1
%2 = trunc i32 %1 to i8
%3 = sub nsw i32 %argc, 1
%4 = trunc i32 %3 to i8
%5 = sext i8 %2 to i32
%6 = sext i8 %4 to i32
%7 = add nsw i32 %5, %6
%8 = trunc i32 %7 to i8
%9 = sext i8 %8 to i32
%10 = mul nsw i32 %9, 4
%11 = trunc i32 %10 to i8
%12 = srem i32 %argc, 2
%13 = icmp ne i32 %12, 0
br i1 %13, label %14, label %16
```

T

F

```
%14:
%15 = call i32 @printf(..., i32 %9)
br label %19
```

```
%16:
%17 = sext i8 %11 to i32
%18 = call i32 @printf(..., i32 %17)
br label %19
```

```
%19:
ret i32 0
```

CFG for 'main' function

Can you
intuitively tell
how CSE works?

```
$> opt -early-cse cse.reg.bc > cse.o.bc
```

```
$> opt -view-cfg cse.o.bc
```

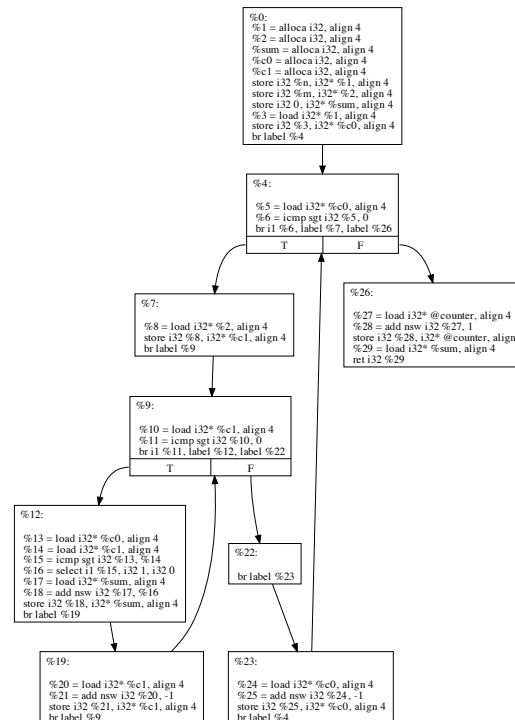
Writing a LLVM pass

- LLVM applies a chain of analyses and transformations on the target program.
- Each of these analyses or transformations is called a *pass*.
- We have seen a few passes already: `mem2reg`, `early-cse` and `constprop`, for instance.
- Some passes, which are machine independent, are invoked by the `opt` tool.
- Other passes, which are machine dependent, are invoked by the `llc` tool.
- A pass may require information provided by other passes. Such dependencies must be explicitly stated.
 - For instance: a common pattern is a transformation pass requiring an analysis pass.

Counting Number of Opcodes in Programs

Let's write a pass that counts the number of times that each opcode appears in a given function. This pass must print, for each function, a list with all the instructions that showed up in its code, followed by the number of times each of these opcodes has been used.

```
int foo(int n, int m) {
    int sum = 0;
    int c0;
    for (c0 = n; c0 > 0; c0--) {
        int c1 = m;
        for (; c1 > 0; c1--) {
            sum += c0 > c1 ? 1 : 0;
        }
    }
    counter++;
    return sum;
}
```



Function foo

add: 4

alloca: 5

br: 8

icmp: 3

load: 11

ret: 1

select: 1

store: 9

Counting Number of Opcodes in Programs

```
#define DEBUG_TYPE "opCounter"
#include "llvm/Pass.h"
#include "llvm/IR/Function.h"
#include "llvm/Support/raw_ostream.h"
#include <map>
using namespace llvm;
namespace {
    struct CountOp : public FunctionPass {
        std::map<std::string, int> opCounter;
        static char ID;
        CountOp() : FunctionPass(ID) {}
        virtual bool runOnFunction(Function &F) {
            errs() << "Function " << F.getName() << '\n';
            for (Function::iterator bb = F.begin(), e = F.end(); bb != e; ++bb) {
                for (BasicBlock::iterator i = bb->begin(), e = bb->end(); i != e; ++i) {
                    if(opCounter.find(i->getOpcodeName()) == opCounter.end()) {
                        opCounter[i->getOpcodeName()] = 1;
                    } else {
                        opCounter[i->getOpcodeName()] += 1;
                    }
                }
            }
            std::map<std::string, int>::iterator i = opCounter.begin();
            std::map<std::string, int>::iterator e = opCounter.end();
            while (i != e) {
                errs() << i->first << ": " << i->second << "\n";
                i++;
            }
            errs() << "\n";
            opCounter.clear();
            return false;
        }
    };
}
char CountOp::ID = 0;
static RegisterPass<CountOp> X("opCounter", "Counts opcodes per functions");
```

Our pass runs once for each function in the program; therefore, it is a `FunctionPass`. If we had to see the whole program, then we would implement a `ModulePass`.

This line defines the name of the pass, in the command line, e.g., `opCounter`, and the help string that `opt` provides to the user about the pass.

A Closer Look into our Pass

```
struct CountOp : public FunctionPass {
    std::map<std::string, int> opCounter;
    static char ID;
    CountOp() : FunctionPass(ID) {}
    virtual bool runOnFunction(Function &F) {
        errs() << "Function " << F.getName() << '\n';
        for (Function::iterator bb = F.begin(), e = F.end(); bb != e; ++bb) {
            for (BasicBlock::iterator i = bb->begin(), e = bb->end(); i != e; ++i) {
                if(opCounter.find(i->getOpcodeName()) == opCounter.end()) {
                    opCounter[i->getOpcodeName()] = 1;
                } else {
                    opCounter[i->getOpcodeName()] += 1;
                }
            }
        }
        std::map<std::string, int>::iterator i = opCounter.begin();
        std::map<std::string, int>::iterator e = opCounter.end();
        while (i != e) {
            errs() << i->first << ": " << i->second << "\n";
            i++;
        }
        errs() << "\n";
        opCounter.clear();
        return false;
    }
};
```

We will be recording the number of each opcode in **this** map, that binds opcode names to integer numbers.

This code collects the opcodes. We will look into it more closely soon.

This code prints our results. It is a standard loop on an STL data structure. We use iterators to go over the map. Each element in a map is a pair, where the first element is the key, and the second is the value.

Iterating Through Functions, Blocks and Insts

```
for(Function::iterator bb = F.begin(), e = F.end(); bb != e; ++bb) {  
    for(BasicBlock::iterator i = bb->begin(), e = bb->end(); i != e; ++i) {  
        if(opCounter.find(i->getOpcodeName()) == opCounter.end()) {  
            opCounter[i->getOpcodeName()] = 1;  
        } else {  
            opCounter[i->getOpcodeName()] += 1;  
        }  
    }  
}
```

We go over LLVM data structures through iterators.

- An **iterator over a Module** gives us a list of Functions.
- An **iterator over a Function** gives us a list of basic blocks.
- An **iterator over a Block** gives us a list of instructions.
- And we can **iterate over the operands** of the instruction too.

```
for (Module::iterator F = M.begin(), E = M.end(); F != E; ++F);
```

```
for (User::op_iterator O = I.op_begin(), E = I.op_end(); O != E; ++O);
```

Compiling the Pass

- To Compile the pass, we can follow these two steps:

1. Generally we save the pass into `/llvm/lib/Transforms/DirectoryName`, where `DirectoryName` can be, for instance, `CountOp`.
2. We build a Makefile for the project. If we invoke the LLVM standard Makefile, we save some time.

```
# Path to top level of LLVM hierarchy  
LEVEL = ../../..
```

```
# Name of the library to build  
LIBRARYNAME = CountOp
```

```
# Make the shared library become a  
# loadable module so the tools can  
# dlopen/dlsym on the resulting library.  
LOADABLE_MODULE = 1
```

```
# Include the makefile implementation  
include $(LEVEL)/Makefile.common
```



Running the Pass

- Our pass is now a shared library, in `llvm/Debug/lib`, if we have compiled our LLVM distribution with the `—Debug` directive, or in `llvm/Release/lib`, if we have not.
- We can invoke it using the `opt` tool:

```
$> clang -c -emit-llvm file.c -o file.bc
```

```
$> opt -load CountOp.dylib -opCounter -disable-output t.bc
```

Just to avoid
printing the
binary t.bc file



- Remember, if we are running on Linux, then our shared library has the extension `".so"`, instead of `".dylib"`, as in the Mac OS.

LLVM Provides an Intermediate Representation

- LLVM represents programs, internally, via its own instruction set.
 - The LLVM optimizations manipulate these bytecodes.
 - We can program directly on them.
 - We can also interpret them.

♠

```
int callee(const int* X) {  
    return *X + 1;  
}  
  
int main() {  
    int T = 4;  
    return callee(&T);  
}
```

```
$> clang -c -emit-llvm f.c -o f.bc
```

```
$> opt -mem2reg f.bc -o f.bc
```

```
$> llvm-dis f.bc
```

```
$> cat f.ll
```

```
; Function Attrs: nounwind ssp  
define i32 @callee(i32* %X) #0 {  
entry:  
    %0 = load i32* %X, align 4  
    %add = add nsw i32 %0, 1  
    ret i32 %add  
}
```

LLVM Bytecodes are Interpretable

- Bytecode is a form of instruction set designed for efficient execution by a software interpreter.
 - They are portable!
 - Example: Java bytecodes.
- The tool **lli** directly executes programs in LLVM bitcode format.
 - lli may compile these bytecodes just-in-time, if a JIT is available.

```
$> echo "int main() {printf(\"Oi\\n\");}" > t.c  
$> clang -c -emit-llvm t.c -o t.bc  
$> lli t.bc
```

How Does the LLVM IR Look Like?

- RISC instruction set, with usual opcodes
 - add, mul, or, shift, branch, load, store, etc
- Typed representation.

```
%0 = load i32* %X, align 4
%add = add nsw i32 %0, 1
ret i32 %add
```

- Static Single Assignment format
 - That is something smart, which we will see later in the course.

- Control flow is represented explicitly.



This is C

```
switch(argc) {
    case 1: x = 2;
    case 2: x = 3;
    case 3: x = 5;
    case 4: x = 7;
    case 5: x = 11;
    default: x = 1;
}
```

This is LLVM

```
switch i32 %0, label %sw.default [
    i32 1, label %sw.bb
    i32 2, label %sw.bb1
    i32 3, label %sw.bb2
    i32 4, label %sw.bb3
    i32 5, label %sw.bb4
]
```

We can program directly on the IR♣

This is C

```
int callee(const int* X) {  
    return *X + 1;  
}  
  
int main() {  
    int T = 4;  
    return callee(&T);  
}
```

```
$> clang -c -emit-llvm ex0.c -o  
ex0.bc  
  
$> opt -mem2reg -instnamer  
ex0.bc -o ex0.bc  
  
$> llvm-dis < ex0.bc
```

This is LLVM

```
; Function Attrs: nounwind ssp  
define i32 @callee(i32* %X) #0 {  
entry:  
    %tmp = load i32* %X, align 4  
    %add = add nsw i32 %tmp, 1  
    ret i32 %add  
}
```

```
; Function Attrs: nounwind ssp  
define i32 @main() #0 {  
entry:  
    %T = alloca i32, align 4  
    store i32 4, i32* %T, align 4  
    %call = call i32 @callee(i32* %T)  
    ret i32 %call  
}
```

Which opts could
we apply on this
code?

♣: although this is not something to the faint of heart.

Hacking the Bytecode File

This is the original bytecode

```
; Function Attrs: nounwind ssp
define i32 @callee(i32* %X) #0 {
entry:
    %tmp = load i32* %X, align 4
    %add = add nsw i32 %tmp, 1
    ret i32 %add
}
```

```
; Function Attrs: nounwind ssp
define i32 @main() #0 {
entry:
    %T = alloca i32, align 4
    store i32 4, i32* %T, align 4
    %call = call i32 @callee(i32* %T)
    ret i32 %call
}
```

Can you point all
the differences
between the files?

This is the optimized bytecode

```
; Function Attrs: nounwind ssp
define i32 @callee(i32 %X) #0 {
entry:
    %add = add nsw i32 %X, 1
    ret i32 %add
}
```

```
; Function Attrs: nounwind ssp
define i32 @main() #0 {
entry:
    %call = call i32 @callee(i32 4)
    ret i32 %call
}
```

*We can compile and execute
the bytecode file:*

```
$> clang ex0.hack.ll
$> ./a.out
$> echo $?
$> 5
```

Understanding our Hand Optimization

```
; Function Attrs: nounwind ssp
define i32 @callee(i32* %X) #0 {
entry:
  %tmp = load i32* %X, align 4
  %add = add nsw i32 %tmp, 1
  ret i32 %add
}
```

```
int callee(const int* X) {
    return *X + 1;
}

int main() {
    int T = 4;
    return callee(&T);
}
```

```
; Function Attrs: nounwind ssp
define i32 @callee(i32 %X) #0 {
entry:
  %add = add nsw i32 %X, 1
  ret i32 %add
}
```

```
; Function Attrs: nounwind ssp
define i32 @main() #0 {
entry:
  %T = alloca i32, align 4
  store i32 4, i32* %T, align 4
  %call = call i32 @callee(i32* %T)
  ret i32 %call
}
```

```
int callee(int X) {
    return X + 1;
}

int main() {
    int T = 4;
    return callee(T);
}
```

```
; Function Attrs: nounwind ssp
define i32 @main() #0 {
entry:
  %call = call i32 @callee(i32 4)
  ret i32 %call
}
```

We did, by hand, some sort of scalarization, i.e., we are replacing pointers with scalars. Scalars are, in compiler jargon, the variables whose values we can keep in registers.

Generating Machine Code

- Once we have optimized the intermediate program, we can translate it to machine code.
- In LLVM, we use the llc tool to perform this translation. This tool is able to target many different architectures.

```
$> llc --version
```

Registered Targets:

alpha	- Alpha [experimental]
arm	- ARM
bfin	- Analog Devices Blackfin
c	- C backend
cellspu	- STI CBEA Cell SPU
cpp	- C++ backend
mblaze	- MBlaze
mips	- Mips
mips64	- Mips64 [experimental]
mips64el	- Mips64el [experimental]
mipsel	- Mipsel
msp430	- MSP430 [experimental]
ppc32	- PowerPC 32
ppc64	- PowerPC 64
ptx32	- PTX (32-bit) [Experimental]
ptx64	- PTX (64-bit) [Experimental]
sparc	- Sparc
sparcv9	- Sparc V9
systemz	- SystemZ
thumb	- Thumb
x86	- 32-bit X86: Pentium-Pro
x86-64	- 64-bit X86: EM64T and AMD64
xcore	- XCore

Generating Machine Code

- Once we have optimized the intermediate program, we can translate it to machine code.
- In LLVM, we use the llc tool to perform this translation. This tool is able to target many different architectures.

```
$> clang -c -emit-llvm identity.c -o identity.bc  
  
$> opt -mem2reg identity.bc -o identity.opt.bc  
  
$> llc -march=x86 identity.opt.bc -o identity.x86
```

```
.globl    _identity  
.align    4, 0x90  
_identity:  
    pushl %ebx  
    pushl %edi  
    pushl %esi  
    xorl  %eax, %eax  
    movl  20(%esp), %ecx  
    movl  16(%esp), %edx  
    movl  %eax, %esi  
    jmp   LBB1_1  
    .align    4, 0x90  
LBB1_3:  
    movl  (%edx,%esi,4), %ebx  
    movl  $0, (%ebx,%edi,4)  
    incl  %edi  
LBB1_2:  
    cmpl  %ecx, %edi  
    jl    LBB1_3  
    incl  %esi  
LBB1_1:  
    cmpl  %ecx, %esi  
    movl  %eax, %edi  
    jl    LBB1_2  
    jmp   LBB1_5  
LBB1_6:  
    movl  (%edx,%eax,4), %esi  
    movl  $1, (%esi,%eax,4)  
    incl  %eax  
LBB1_5:  
    cmpl  %ecx, %eax  
    jl    LBB1_6  
    popl  %esi  
    popl  %edi  
    popl  %ebx  
    ret
```

A Bit of History

- Some of the first code optimizations were implemented only locally
 - Fortran was one of the first programming languages to be optimized by a compiler
 - The LLVM infra-structure was implemented by Chris Lattner, during his PhD, at UIUC
- Kam, J. B. and J. D. Ullman, "Monotone Data Flow Analysis Frameworks", Acta Informatica 7:3 (1977), pp. 305-318
 - Kildall, G. "A Unified Approach to Global Program Optimizations", ACM Symposium on Principles of Programming Languages (1973), pp. 194-206
 - Lattner, C., and Adve, V., "LLVM: A Compilation Framework for Lifelong Program Analysis & Transformation", CGO, pp. 75-88 (2004)