

# Possibilistic C-Means Clustering ToolBox

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## Abstract

**Keywords:**

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## 1. PCM\_

The `PCM_` function performs Possibilistic C-Means (PCM) clustering on the input data.

### Definition

Possibilistic C-Means (PCM) is a clustering algorithm that extends Fuzzy C-Means (FCM) to handle uncertain memberships and noisy data points. It allows each data point to belong to multiple clusters with varying degrees of membership.

### Syntax

```
1 results = PCM_(Data, param, varargin)
```

### Inputs

- **Data** - A matrix where each column represents a data point.
- **param** - A structure containing the following fields:
  - **kClust** (required) - Number of clusters.
  - **maxIter** (optional) - Maximum number of iterations (default: 100).
  - **mFuzzy** (optional) - Fuzziness parameter (default: 2.0).
  - **epsilon** (optional) - Convergence threshold (default: 1e-5).
  - **alphaCut** (optional) - Threshold for noise identification (default: 0.5).
  - **K** (optional) - Scaling factor for eta calculation (default: 0.5).

- `x` (optional) - Support points for the PDFs.
- `varargin` - Optional parameters for visualization:
  - `'Visualize'` - Visualization type: `'None'`, `'CDF'`, or `'CDE'` (default: `'None'`).

## Outputs

- `results` - A structure containing clustering results:
  - `Cluster.U` - Final partition matrix.
  - `Data.fv` - Representative PDFs of clusters.
  - `iter` - Number of iterations performed.
  - `ObjFun` - Final value of the objective function.
  - `Data.Data` - Input data.
  - `Cluster.IDX` - Cluster indices for each data point.
  - `Dist.D` - Distance matrix between representative PDFs and data.
  - `isnoise` - Data points identified as noise.

## Algorithm Steps

1. **Initialization:** Initialize cluster centers and membership values.
2. **Membership Update:** Update memberships based on distance to cluster centers and fuzziness parameter.
3. **Cluster Center Update:** Update cluster centers based on new memberships.
4. **Convergence Check:** Check convergence based on objective function change or maximum iterations.
5. **Noise Identification:** Identify noise data points based on alpha cut threshold.
6. **Output:** Return final cluster assignments, representative PDFs, and other diagnostic information.

## Example

Consider a dataset where each data point represents measurements in a two-dimensional space. We apply PCM clustering to this dataset with the following parameters:

```

1 % Define the input data
2 x =
3
4 Data = normpdf(x, mu, sigma)
5
6 % Define the parameters
7 param.kClust = 3;           % Number of clusters
8 param.maxIter = 100;       % Maximum number of iterations

```

```

9 param.mFuzzy = 2.0;      % Fuzziness parameter
10 param.epsilon = 1e-5;   % Convergence threshold
11 param.alphaCut = 0.5;    % Threshold for noise identification
12 param.K = 0.5;          % Scaling factor for eta calculation
13 param.x = linspace(0, 1, 100); % Support points for the PDFs
14
15 % Call the PCM_ function
16 results = PCM_(Data, param, 'Visualize', 'None');
17
18 % Display the results
19 disp('Cluster Indices:');
20 disp(results.Cluster.IDX);
21
22 disp('Representative PDFs:');
23 disp(results.Data.fv);
24
25 disp('Number of Iterations:');
26 disp(results.iter);
27
28 disp('Objective Function Value:');
29 disp(results.ObjFun);

```

In this example, we generate random data points in a two-dimensional space and apply PCM clustering to identify clusters in the data. The `PCM_` function computes cluster memberships, updates cluster centers, and identifies noise points based on specified parameters.

## 2. ExtractKernel

The MATLAB function `ExtractKernel` computes the kernel density estimate (pdf) for images in an `ImageDatastore`.

### Description

`ExtractKernel` filters grayscale images from the `ImageDatastore` `imds`, computes the bandwidth ( $h$ ) for kernel density estimation, and returns the pdf values and corresponding  $x$  values.

### Syntax

```

1 [pdf, x] = ExtractKernel(imds)
2 [pdf, x] = ExtractKernel(imds, Name, Value)

```

### Input Arguments

- `imds` - A `matlab.io.datastore.ImageDatastore` object containing images.

## Optional Name-Value Pair Arguments

- `'numPoints'` - Number of points for kernel density estimation (default: 1000).
- `'extensions'` - File extensions of images in `imds` (default: `{'.png'}`).

## Output Arguments

- `pdf` - Kernel density estimate values for each image.
- `x` - Points at which the kernel density estimate is evaluated.

## Example

```
1 folderPath = 'link/to/folder/data'
2 imds = imageDatastore(folderPath);
3 [pdf, x] = ExtractKernel(imds, 'numPoints', 500);
```

## See also

- `ksdensity`
- `imageDatastore`