

Camera Matrix

$$\begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} f_x & c_x \\ f_y & c_y \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

2d location:

$\left(\frac{u}{w}, \frac{v}{w}\right)$   $w$  is  $z$  distance from camera

Point location in camera coords

Suppose we are trying to find the camera ray from a pixel  $\left(\frac{u}{w}, \frac{v}{w}\right)$ ... Divide eqn by  $w$ , let  $u_0 = \frac{u}{w}$ ,  $v_0 = \frac{v}{w}$

$$\begin{bmatrix} u_0 \\ v_0 \\ 1 \end{bmatrix} = \begin{bmatrix} f_x & c_x \\ f_y & c_y \\ 1 \end{bmatrix} \begin{bmatrix} x/w \\ y/w \\ z/w \end{bmatrix}$$

$$\begin{bmatrix} u_0 \\ v_0 \end{bmatrix} = \underbrace{\begin{bmatrix} f_x & c_x \\ f_y & c_y \end{bmatrix}}_{\text{SVD into } U S V^T} \begin{bmatrix} x/w \\ y/w \\ 1 \end{bmatrix}$$

$\uparrow = 1$  since  $z=w$

SVD into  
 $U S V^T$

$$\begin{bmatrix} u_0 \\ v_0 \end{bmatrix} = \begin{bmatrix} u_1 & u_2 \end{bmatrix} \begin{bmatrix} s_1 & 0 \\ s_2 & 0 \end{bmatrix} \begin{bmatrix} v_1 & v_2 & v_3 \end{bmatrix}^T \begin{bmatrix} x/w \\ y/w \\ 1 \end{bmatrix} \quad \text{let } V^T \begin{bmatrix} x/w \\ y/w \\ 1 \end{bmatrix} =$$

$$U^T \begin{bmatrix} u_0 \\ v_0 \end{bmatrix} = \begin{bmatrix} s_1 & 0 \\ s_2 & 0 \end{bmatrix} \begin{bmatrix} v_1^T \\ v_2^T \\ v_3^T \end{bmatrix} \begin{bmatrix} x/w \\ y/w \\ 1 \end{bmatrix}$$

define  $\begin{bmatrix} q \\ r \end{bmatrix}$  as

$$\text{Then } q = s_1 v_1^T \begin{bmatrix} x/w \\ y/w \\ 1 \end{bmatrix}, \quad r = s_2 v_2^T \begin{bmatrix} x/w \\ y/w \\ 1 \end{bmatrix}$$

$$\text{Or } v_1 \cdot \begin{bmatrix} x/w \\ y/w \\ 1 \end{bmatrix} = \frac{q}{s_1} \quad \text{and} \quad v_2 \cdot \begin{bmatrix} x/w \\ y/w \\ 1 \end{bmatrix} = \frac{r}{s_2}$$

$$\text{Or } \begin{bmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{bmatrix} \begin{bmatrix} x/w \\ y/w \end{bmatrix} = \begin{bmatrix} q/s_1 - v_{31} \\ r/s_2 - v_{32} \end{bmatrix}$$

So end up with

$$\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} v_{11} & v_{21} \\ v_{12} & v_{22} \end{bmatrix}^{-1} \begin{bmatrix} q/s_1 - v_{31} \\ r/s_2 - v_{32} \end{bmatrix}$$

where  $\frac{x}{w} = c_1$  where  $w \neq z$   
 $\frac{y}{w} = c_2$

Ray leaving  $(x, y, z) = (0, 0, 0)$   
vector  $(c_1, c_2, 1)$

Derivative w.r.t  $u_0$ :

From  $U^T$ , evaluate  $\frac{\partial q}{\partial u_0}$  and  $\frac{\partial r}{\partial u_0}$

$$\frac{\partial}{\partial u_0} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} v_{11} & v_{21} \\ v_{12} & v_{22} \end{bmatrix}^{-1} \begin{bmatrix} \frac{1}{s_1} \frac{\partial q}{\partial u_0} \\ \frac{1}{s_2} \frac{\partial r}{\partial u_0} \end{bmatrix}$$

camera - to - object transform  $A$  ( $4 \times 4$ )

$$A \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \rightarrow \text{transform focal point}$$

$$A \begin{bmatrix} c_1 \\ c_2 \\ 0 \\ 1 \end{bmatrix} \rightarrow \text{transform vector}$$

then ray - to - polygon intersection