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Creating features using particle swarm optimization

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Abstract: The problem of data classification or data fitting is widely applicable in a multitude of scientific areas, and for this reason a number of machine learning models have been developed. However, in many cases, these models present problems of overfitting and cannot generalize satisfactorily to unknown data. Furthermore, in many cases, many of the features of the input data do not contribute to learning, or there may even be hidden correlations between the features of the dataset. The current article proposes a method that combines Particle Swarm Optimization and Grammatical Evolution, that can produce artificial features from the original ones for a variety of pattern recognition problems. In addition, this new technique utilizes penalty factors to limit the generated features to a range of values to make training machine learning models more efficient. The performance of the proposed method was measured on some benchmark datasets from the relevant literature. Also, the method was tested against a series of widely used machine learning models.

Keywords: Particle swarm optimization, Grammatical Evolution, Evolutionary techniques, Stochastic methods.

1. Introduction

A multitude of everyday problems from various sciences can be treated as a problem of categorization or data fitting problems, such as problems that appear in the fields of physics [1–4], chemistry [5–7], economics [8,9], environmental problems [10–12], medical problems [13,14] etc. In the relevant literature there is a wide range of techniques that one can use to handle such problems, such as the k nearest neighbors model (k-NN) [15,16], artificial neural networks (ANNs) [17,18], Radial Basis Function (RBF) networks [19–21], Support Vector Machines (SVM) [22,23], decision trees [24,25] etc. A brief description of the methods that can be used for classification datasets is given in the publication of Kotsiantis et al [26].

In the majority of cases, the machine learning models have a number of parameters that should be determined through some algorithms, such as the Back Propagation method [27,28] for artificial neural networks or more advanced optimization methods such as the Genetic algorithms [29–31]. However, most of the time there are some problems in the parameterization of machine learning models:

- Requirement for large training time, which is proportional to the dimension of the input data. For example, in a neural network with one hidden layer equipped with 10 processing nodes and a provided dataset with 10 inputs, then more than $N = 100$ parameters are required to build the neural network. Therefore, the size of the network will grow proportionally to the problem and therefore, longer training times will be required for the model.
- Another important problem presented in machine learning techniques is the fact that many models require significant storage space in the computer's memory for their parameters, and in fact this space increases significantly with the increase in the dimension of the objective problem. For example in Bfgs [32] optimization method, $O(N^2)$ storage space will be required for the training model and for the partial derivatives required by the optimization method. This issue is thoroughly discussed in

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the paper of Verleysen et al [33]. Some common approaches proposed in order to reduce the dimension of the input datasets are the Principal Component Analysis (PCA) method [34–36] as well as the Minimum redundancy feature selection (MRMR) technique [37,38]. Furthermore, Wang et al proposed an auto - encoder reduction method, applied on a series of large datasets[39].

- The problem of reduced performance of models on unknown data, is also known as overfitting problem. The paper of Geman et al [40] as well the article of Hawkins [41] thoroughly discuss the topic of overfitting. Examples of techniques proposed to tackle this problem are the weight sharing methods [42,43], the prunning methods [44–46], weight elimination [47–49], weight decaying methods [50,51] etc.

This article proposes a two-phase method to overcome the above problems. During the first phase, a limited number of artificial features are created from the original ones using a method based on the Grammatical Evolution procedure [52]. Grammatical Evolution is a variation of genetic programming, where the chromosomes are production rules of the target BNF grammar and it has been used successfully in a variety of applications, such as music composition [53], economics [54], symbolic regression [55], robotics [56], caching algorithms [57] etc. These features are iteratively adjusted using a hybrid technique based on particle swarm optimization (PSO)[58–60], where the generated features are constrained using penalty factors to be within a predefined value interval and their evaluation is done using an RBF network. The RBF network was preferred over other machine learning models to be used to evaluate the generated features due to its training speed. The PSO method has been selected as the optimization method due to its simplicity and the small number of parameters that should be set. Also, the PSO method has been used in many difficult problems in all areas of the sciences, such as problems that arise in physics [61,62], chemistry [63,64], medicine [65,66], economics [67] etc. Furthermore, the PSO method was successfully applied recently in many practical problems such as flow shop scheduling [68], successful development of electric vehicle charging strategies [69], emotion recognition [70], robotics [71] etc.

The idea of creating artificial features using Grammatical Evolution was first introduced in the paper of Gavrilis et al [72] and it has been successfully applied on a series of problems, such as Spam Identification [73], Fetal heart classification [74], epileptic oscillations[75], construction of Covid-19 predictive models [76], performance and early drop prediction for higher education students [77] etc.

Feature selection using neural networks has been also proposed in a series of papers, such as the work of Verikas and Bacauskiene [78] or the work of Kabir et al [79]. Moreover, Devi utilized a Simulated Annealing approach [80] to select the most important features for classification datasets. Also, Neshatian et al [81] developed a genetic algorithm that produces features using an entropy based fitness function.

The rest of this article is divided as follows: in section 2 the steps of the proposed method are fully described, in section 3 the used experimental datasets as well as the results obtained by the incorporation of the proposed method are outlined and finally in section 4 some conclusions are listed.

2. The proposed method

The basic steps by which the Grammatical Evolution technique produces the artificial features are then analyzed in as well as the steps in the overall process of creating and evaluating the artificial features.

2.1. The technique of Grammatical Evolution

The process of Grammatical Evolution uses chromosomes that represent production rules of the underlying BNF (Backus–Naur form) grammar[82] of the objective problem. BNF grammars have been widely used to describe the syntax of programming languages. Any BNF grammar is a set $G = (N, T, S, P)$, where

- The set N represents the non-terminal symbols of the grammar. Any non - terminal symbol is analyzed to a series of terminal symbols using the production rules of the grammar.
- T is the set of terminal symbols.
- The non - terminal symbol S represents the start symbol of the grammar.
- The set P contains the production rules of the grammar. Typically, any production rule is expressed in the form $A \to a$ or $A \to aB,\ A, B \in N,\ a \in T$.

The process that creates a valid program, starts from the symbol S and gradually replaces non-terminal symbols with the right hand of the selected production rule from the provided chromosome. The rule is selected with the following steps:

- In the first step, the next element is taken from the current chromosome. Let us denote it as V.
- The next production rule is selected through

$$\text{Rule} = V \bmod N_R$$

where N_R is the total number of production rules for the current non – terminal symbol.

The BNF grammar for the proposed method is shown in Figure 1. The constant N is the dimension of the input dataset.

Figure 1. BNF grammar of the proposed method.

```
S::=<expr>   (0)
<expr> ::=  (<expr> <op> <expr>)  (0)
          | <func> ( <expr> )    (1)
          |<terminal>            (2)
<op> ::=     +      (0)
          | -      (1)
          | *      (2)
          | /      (3)
<func> ::=   sin  (0)
          | cos  (1)
          |exp   (2)
          |log   (3)
<terminal>::=<xlist>                (0)
          |<digitlist>.<digitlist> (1)
<xlist>::=x1    (0)
          | x2 (1)
          .........
          | xN (N)
<digitlist>::=<digit>                  (0)
          | <digit><digit>             (1)
          | <digit><digit><digit>      (2)
<digit>  ::= 0 (0)
          | 1 (1)
          | 2 (2)
          | 3 (3)
          | 4 (4)
          | 5 (5)
          | 6 (6)
          | 7 (7)
          | 8 (8)
          | 9 (9)
```

An example that produces a valid expression for the chromosome

$$x = [10, 12, 20, 8, 11]$$

with $N = 3$ is shown in Table 1. The final expression that created is $f(x) = \sin(x_3)$.

Table 1. Steps to produce a valid expression from the BNF grammar.

Expression	Chromosome	Operation
<expr>	10,12,20,8,11	$10 \mod 3 = 1$
<func>(<expr>)	12,20,8,11	$12 \mod 4 = 0$
sin(<expr>)	20,8,11	$20 \mod 3 = 2$
sin(<terminal>)	8,11	$8 \mod 2 = 0$
sin(<xlist>)	11	$11 \mod 3 = 2$
sin(x3)		

2.2. Feature construction

The current method is used to create N_f artificial features from the original ones. The new features will be considered as non - linear transformations of the old features and the process for any particle p is as follows:

1. **Divide** p into N_f parts. Every part is denoted as the p_i sub - particle.
2. **For** each sub - particle p_i a new artificial feature $g_i(\overrightarrow{x}, p_i)$ is constructed with the grammar of Figure 1 as a non - linear combination of the original set of features $\overrightarrow{x}$.

The final set of features will be considered as mapping functions of the original ones. For example the set:

$$g(\overrightarrow{x}, p) = \begin{cases} g_1(\overrightarrow{x}, p_1) & = & x_1^2 + 2x_3 \\ g_2(\overrightarrow{x}, p_2) & = & 3\cos(x_2) \end{cases}$$

is a set of mapping functions for the original features $\overrightarrow{x} = (x_1, x_2, x_3)$. However, sometimes the generated features can lead to extreme values and this will result in generalization problems from the used machine learning models. For this reason and in the present work, penalty factors are used so that the mapping functions do not lead to extreme values. These penalty factors also modify the fitness function that the Particle Swarm Optimization technique will minimize each time and are considered next.

2.3. Fitness calculation

The following steps calculates the fitness for any given particle p.

1. **Denote as** $\text{TO} = \{(\overrightarrow{x_1}, y_1), (\overrightarrow{x_2}, y_2), \ldots, (\overrightarrow{x_M}, y_M)\}$ the original train set.
2. **Set** $V = 0$, the penalty factor
3. **Compute** the mapping function $g(\overrightarrow{x}, p)$ as suggested in subsection 2.2
4. **Set** TF=$\emptyset$,the modified train set
5. **For** $i = 1, \ldots, M$ **do**
   (a) **Set** $\widetilde{x}_i = g(\overrightarrow{x_i}, p)$
   (b) **Set** $\text{TF} = \text{TF} \cup (\widetilde{x}_i, y_i)$
   (c) **If** $\|\widetilde{x}_i\| > L_{\max}$, **then** $V = V + 1$, where $L_{\max}$ a predefined positive value.
6. **End For**
7. **Train** an RBF $C(x)$ with H processing NODES on TF and obtain the following error:

$$f_p = \sum_{j=1}^{M} \left(C(\widetilde{x}_i) - y_j\right)^2 \tag{1}$$

8. **Compute** the final fitness value:

$$f_p = f_p \times \left(1 + \lambda V^2\right) \tag{2}$$

where $\lambda > 0$.

2.4. The used PSO method

The mains steps for this algorithm are outlined in detail in Algorithm 1.

Algorithm 1 The base PSO algorithm executed in one processing unit.

1. **Initialization Step** .
   (a) **Set** iter $= 0$.
   (b) **Set** m as the total number of particles.
   (c) **Set** $\text{iter}_{\max}$ as the maximum number of iterations allowed.
   (d) **Initialize** randomly, the positions $p_1, p_2, ..., p_m$ for the particles. For the grammatical evolution, every chromosome is a series of randomly selected integers.
   (e) **Initialize** randomly the velocities $u_1, u_2, ..., u_m$. For the current work every vector of velocities is a series of randomly selected integers in a the range $[u_{\min}, u_{\max}]$. In the current work $u_{\min} = -5$, $u_{\max} = 5$.
   (f) **For** $i = 1..m$ do $b_i = p_i$. The vector b_i denotes the best located position of particle p_i.
   (g) **Set** $p_{\text{best}} = \arg\min_{i \in 1..m} f(p_i)$
2. **Termination Check Step** . If iter $\geq \text{iter}_{\max}$ then goto step 8.
3. **For** $i = 1..m$ **Do**
   (a) **Compute** the velocity u_i as a combination of the vectors u_i, p_i and p_{best}
   (b) **Set** the new position for the particle as: $p_i = p_i + u_i$
   (c) **Calculate** the fitness $f(p_i)$ for particle p_i using the procedure described in subsection 2.3.
   (d) **If** $f(p_i) \leq f(b_i)$ then $b_i = p_i$
4. **End For**
5. **Set** $p_{\text{best}} = \arg\min_{i \in 1..m} f(p_i)$
6. **Set** iter $=$ iter $+ 1$.
7. **Goto** Step 2
8. **Test step**. Apply the mapping function of the best particle p_{best} to the test set of the problem and apply a machine learning model obtaining the corresponding test error.

The above calculates at every iteration the new position of the particle i using:

$$p_i = p_i + u_i \tag{3}$$

In most cases the new velocity could be a linear combination of the previously computed velocity and the best values b_i and p_{best} and it can be defined as:

$$u_i = \omega u_i + r_1 c_1 (b_i - p_i) + r_2 c_2 \left(p_{\text{best}} - p_i\right) \tag{4}$$

where

1. The variables r_1, r_2 are random numbers defined in $[0, 1]$.
2. The constants c_1, c_2 are defined in range $[1, 2]$.
3. The variable ω, commonly called inertia, was suggested by Shi and Eberhart [58] and in the current work was computer through the following equation

$$\omega_{\text{iter}} = 0.5 + \frac{r}{2} \tag{5}$$

The variable r is a a random number with $r \in [0, 1]$.

3. Experiments

The ability of the proposed technique to produce effective artificial features for class prediction and feature learning will be measured in this section on a some datasets from the relevant literature. This data comes from the relevant websites:

1. UCI dataset repository, https://archive.ics.uci.edu/ml/index.php
2. Keel repository, https://sci2s.ugr.es/keel/datasets.php[83].
3. The Statlib URL ftp://lib.stat.cmu.edu/datasets/index.html.

The proposed technique will be compared with a series of known machine learning techniques and the experimental results are then presented in the relevant tables.

3.1. Experimental datasets

The classification problems used in the experiments have as follows:

1. **Appendicitis**, a medical dataset [84,85].
2. **Australian** dataset [86], an dataset concerning economical transactions in banks.
3. **Balance** dataset, a dataset generated to model psychological experimental results[87].
4. **Bands** dataset, a dataset used in rotogravure printing [88].
5. **Dermatology** dataset [89], a medical dataset used to detect the type of Eryhemato-Squamous Disease.
6. **Hayes roth** dataset [91].
7. **Heart** dataset [90], a medical dataset used to detect heart diseases.
8. **HouseVotes** dataset [92], a dataset related to the Congressional voting records of USA.
9. **Ionosphere** dataset, used to classify measurements from the ionosphere and it has been examined in a variety of research papers [93,94].
10. **Liverdisorder** dataset [95,96], a dataset used for medical purposes.
11. **Mammographic** dataset [97], a medical dataset used for breast cancer diagnosis.
12. **Parkinsons** dataset [98,99], a dataset used to detect the Parkinson's decease using voice measurements.
13. **Pima** dataset [100], a dataset used for medical purposes.
14. **Popfailures** dataset [101], a dataset related to meteorological data.
15. **Regions2** dataset, a medical dataset for liver biopsy images [102].
16. **Saheart** dataset [103], a medical dataset.
17. **Segment** dataset [104], a dataset related to image segmentation.
18. **Wdbc** dataset [105] ussed in breast tumors.
19. **Wine** dataset, a dataset related to chemical analysis of wines [106,107].
20. **Eeg** datasets [108,109], it is an EEG dataset and the following cases were used in the experiments:
    (a) Z_F_S,
    (b) ZO_NF_S
    (c) ZONF_S.
21. **Zoo** dataset [110].

The regression datasets used in the relevant experiments have as follows:

1. **Abalone** dataset [112], a dataset used to predict the age of abalones.
2. **Airfoil** dataset, a dataset provided by NASA [113] obtained from a series of aerodynamic and acoustic tests.
3. **Baseball** dataset, a dataset related to the salary of baseball players.
4. **BK** dataset [114], a dataset that was used to calculate the points in a basketball game.
5. **BL** dataset, used in machine problems.
6. **Concrete** dataset [115], a civil engineering dataset to calculate The concrete compressive strength
7. **Dee** dataset, used to estimate the daily average price of TkWhe electricity energy in Spain.

8. **Diabetes** dataset, a medical dataset.
9. **Housing** dataset [116].
10. **FA** dataset, used to fit body fat to other measurements.
11. **MB** dataset [117].
12. **MORTGAGE** dataset, holding economic data from USA. The goal is to predict the 30-Year Conventional Mortgage Rate.
13. **PY** dataset, (Pyrimidines problem)[118].
14. **Quake** dataset, used to approximate the strength of a earthquake given its the depth of its focal point, its latitude and its longitude.
15. **Treasure** dataset, which contains Economic data information of USA, where the the goal is to predict 1-Month CD Rate.

3.2. Experimental results

In order to give greater credibility to the experiments carried out, the method of 10 - fold cross validation was incorporated for every experimental dataset. Every experiment was repeated 30 times using different seeds for the random generator each time. All the used code was implemented in ANSI C++ using the OPTIMUS programming library for optimization purposes, freely available from https://github.com/itsoulos/OPTIMUS/. For the classification datasets, the average classification error as measured in the test set is reported, while for the regression datasets the average regression error is reported. Also, in every table, an additional column denoted as AVERAGE is added to show the average classification or regression error for the corresponding datasets. The values for the experimental parameters are shown in Table 2.

Table 2. The values for every parameter used in the experiments.

PARAMETER	MEANING	VALUE
m	Particles or Chromosomes	200
H	Number of hidden nodes	10
$\text{iter}_{\max}$	Maximum number of iterations	200
$L_{\max}$	Limit used in penalty calculation	100
λ	Penalty factor	100

The proposed technique that created artificial features is compared on the same datasets against a series of well - known method from the relevant literature:

1. A genetic algorithm with m chromosomes, denotes as GENETIC in the experimental tables. This genetic algorithm is used to train an artificial neural network with H hidden nodes. After the termination of the genetic algorithm the local optimization method BFGS is applied to the best chromosome of the population.
2. The Radial Basis Function (RBF) network [120] with H processing nodes.
3. The optimization method Adam [121], used to train an artificial neural network with H hidden nodes.
4. The Rprop optimization method [122–124], used to train an artificial neural network with H hidden nodes.
5. The NEAT method (NeuroEvolution of Augmenting Topologies) [125].

The experimental results using the above methods on the classification datasets are shown in Table 3 and the results for the regression datasets are illustrated in Table 4.

Table 3. Average classification error for the classification datasets using the well - known methods.

DATASET	GENETIC	RBF	ADAM	RPROP	NEAT
Appendicitis	18.10%	12.23%	16.50%	16.30%	17.20%
Australian	32.21%	34.89%	35.65%	36.12%	31.98%
Balance	8.97%	33.42%	7.87%	8.81%	23.14%
Bands	35.75%	37.22%	36.25%	36.32%	34.30%
Dermatology	30.58%	62.34%	26.14%	15.12%	32.43%
Hayes Roth	56.18%	64.36%	59.70%	37.46%	50.15%
Heart	28.34%	31.20%	38.53%	30.51%	39.27%
HouseVotes	6.62%	6.13%	7.48%	6.04%	10.89%
Ionosphere	15.14%	16.22%	16.64%	13.65%	19.67%
Liverdisorder	31.11%	30.84%	41.53%	40.26%	30.67%
Lymography	23.26%	25.31%	29.26%	24.67%	33.70%
Mammographic	19.88%	21.38%	46.25%	18.46%	22.85%
Parkinsons	18.05%	17.42%	24.06%	22.28%	18.56%
Pima	32.19%	25.78%	34.85%	34.27%	34.51%
Popfailures	5.94%	7.04%	5.18%	4.81%	7.05%
Regions2	29.39%	38.29%	29.85%	27.53%	33.23%
Saheart	34.86%	32.19%	34.04%	34.90%	34.51%
Segment	57.72%	59.68%	49.75%	52.14%	66.72%
Wdbc	8.56%	7.27%	35.35%	21.57%	12.88%
Wine	19.20%	31.41%	29.40%	30.73%	25.43%
Z_F_S	10.73%	13.16%	47.81%	29.28%	38.41%
ZO_NF_S	8.41%	9.02%	47.43%	6.43%	43.75%
ZONF_S	2.60%	4.03%	11.99%	27.27%	5.44%
ZOO	16.67%	21.93%	14.13%	15.47%	20.27%
AVERAGE	**22.94%**	**26.78%**	**30.24%**	**24.60%**	**28.63%**

Table 4. Average regression error using the well - known methods for the regression datasets.

DATASET	GENETIC	RBF	ADAM	RPROP	NEAT
ABALONE	7.17	7.37	4.30	4.55	9.88
AIRFOIL	0.003	0.27	0.005	0.002	0.067
BASEBALL	103.60	93.02	77.90	92.05	100.39
BK	0.027	0.02	0.03	1.599	0.15
BL	5.74	0.01	0.28	4.38	0.05
CONCRETE	0.0099	0.011	0.078	0.0086	0.081
DEE	1.013	0.17	0.63	0.608	1.512
DIABETES	19.86	0.49	3.03	1.11	4.25
HOUSING	43.26	57.68	80.20	74.38	56.49
FA	1.95	0.02	0.11	0.14	0.19
MB	3.39	2.16	0.06	0.055	0.061
MORTGAGE	2.41	1.45	9.24	9.19	14.11
PY	1.21	0.02	0.09	0.039	0.075
QUAKE	0.04	0.071	0.06	0.041	0.298
TREASURY	2.929	2.02	11.16	10.88	15.52
AVERAGE	**12.84**	**10.30**	**11.70**	**12.44**	**12.70**

The results using the proposed method and for the construction of 2,3 and 4 artificial features are presented in the relevant tables, 5 and 6. The RBF column represents the experimental results in which, after the construction of the artificial features, a RBF network with H processing nodes is applied on the modified dataset. Also, the column GENETIC in tables 5, 6 stands for the results obtained by the application of a genetic algorithm with

m chromosomes to the modified dataset, when the feature creation procedure has been finished.

Table 5. Experimental results for the classification datasets using the proposed method. Number in cells denote average classification error as measured on the test set.

	$f = 2$		$f = 3$		$f = 4$	
DATASET	RBF	GENETIC	RBF	GENETIC	RBF	GENETIC
APPENDICITIS	15.40%	14.33%	16.90%	15.77%	15.97%	17.30%
AUSTRALIAN	15.49%	14.48%	14.53%	15.33%	14.75%	15.97%
BALANCE	16.67%	2.89%	22.54%	4.94%	17.26%	4.62%
BANDS	38.09%	38.13%	37.09%	39.22%	37.22%	35.51%
DERMATOLOGY	41.58%	30.37%	35.46%	25.44%	40.45%	21.97%
HAYES ROTH	37.41%	27.92%	38.10%	25.74%	39.59%	25.82%
HEART	21.53%	17.13%	17.64%	16.87%	19.63%	15.69%
HOUSEVOTES	6.36%	3.78%	7.17%	3.25%	4.25%	3.52%
IONOSPHERE	10.32%	10.17%	10.12%	10.01%	11.42%	9.02%
LIVERDISORDER	34.23%	32.33%	35.84%	32.97%	35.93%	30.74%
LYMOGRAPHY	34.93%	28.67%	32.00%	23.00%	29.00%	23.83%
MAMMOGRAPHIC	16.92%	16.51%	16.47%	16.35%	17.54%	16.50%
PARKINSONS	11.14%	13.00%	11.30%	11.11%	12.95%	9.42%
PIMA	22.85%	22.76%	24.93%	24.67%	24.25%	24.20%
POPFAILURES	7.32%	7.41%	6.96%	7.62%	5.96%	5.67%
REGIONS2	28.52%	26.84%	24.91%	25.28%	25.35%	24.93%
SAHEART	29.29%	28.63%	28.92%	30.31%	28.25%	30.25%
SEGMENT	52.69%	45.59%	46.83%	41.06%	50.15%	39.52%
WDBC	5.00%	4.66%	5.76%	4.97%	5.13%	3.84%
WINE	8.92%	7.22%	6.76%	5.75%	6.00%	5.86%
Z_F_S	7.91%	8.37%	7.89%	7.67%	5.21%	6.86%
ZO_NF_S	6.90%	6.85%	6.95%	5.65%	6.24%	5.28%
ZONF_S	3.08%	3.40%	2.44%	2.52%	3.47%	3.33%
ZOO	26.47%	7.83%	31.73%	10.03%	28.70%	11.57%
AVERAGE	**20.79%**	**17.47%**	**20.39%**	**16.90%**	**20.19%**	**16.30%**

Table 6. Experimental results on the regression datasets using the proposed method. The number in cells denote average regression error as measured on the test set.

	$f = 2$		$f = 3$		$f = 4$	
DATASET	RBF	GENETIC	RBF	GENETIC	RBF	GENETIC
ABALONE	4.361	3.518	4.159	3.839	4.859	3.786
AIRFOIL	0.003	0.001	0.003	0.001	0.003	0.001
BASEBALL	66.00	53.74	60.79	57.04	66.19	61.69
BK	0.022	0.031	0.021	0.029	0.019	0.023
BL	0.413	0.0001	0.019	0.007	0.043	0.011
CONCRETE	0.008	0.006	0.007	0.005	0.008	0.004
DEE	0.259	0.252	0.339	0.286	0.609	0.5
DIABETES	0.611	0.832	0.634	1.411	0.857	1.157
HOUSING	22.387	15.583	18.614	13.602	14.83	13.208
FA	0.056	0.011	0.015	0.011	0.015	0.012
MB	0.258	0.087	0.115	0.078	0.342	0.072
MORTGAGE	0.621	0.046	0.65	0.037	0.078	0.04
PY	2.894	0.14	0.936	0.029	0.724	0.031
QUAKE	0.069	0.036	0.057	0.037	0.04	0.037
TREASURY	0.912	0.088	0.874	0.084	0.173	0.076
AVERAGE	**6.59**	**4.96**	**5.82**	**5.10**	**5.92**	**5.38**

The experimental results are of great interest, as one can see from their careful study, the proposed technique is able to significantly reduce the error in the corresponding test sets. Especially in the case of regression problems, the reduction in error is on average greater than 50%. Moreover, the usage of a neural network trained by a genetic algorithm on the modified datasets, gives clearly better results than the use of an RBF neural network, especially in the classification datasets. Moreover, a graphical comparison between the genetic algorithm when applied to artificial datasets and the genetic algorithm when applied to the original classification datasets is given in Figure 2. The same graphical comparison is also shown for the RBF model in Figure 3. And in these figures, the ability of the proposed method to drastically reduce learning error through the construction of artificial features is evident.

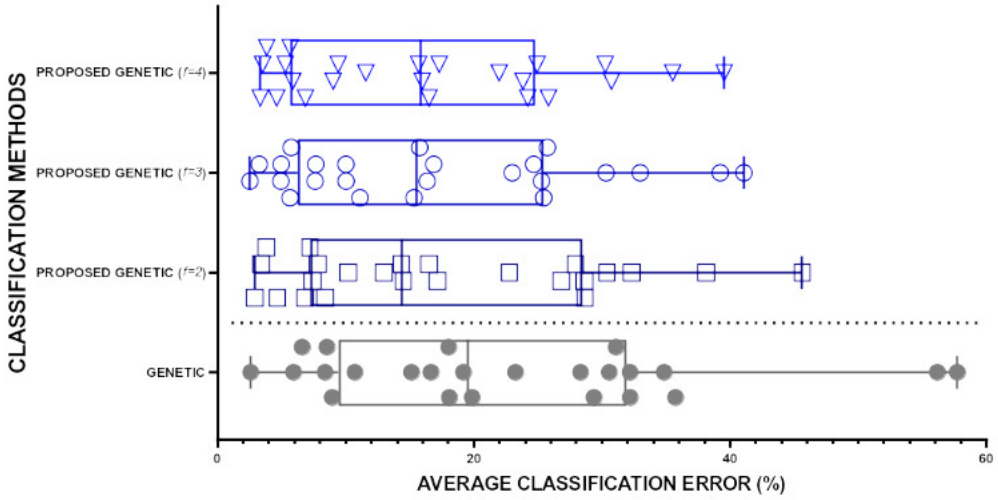

Figure 2. Comparison of the proposed Genetic classification algorithm for the construction of 2,3 and 4 artificial features (blue color) vs. a well-known Genetic classification algorithm (grey color) to the 24 different datasets.

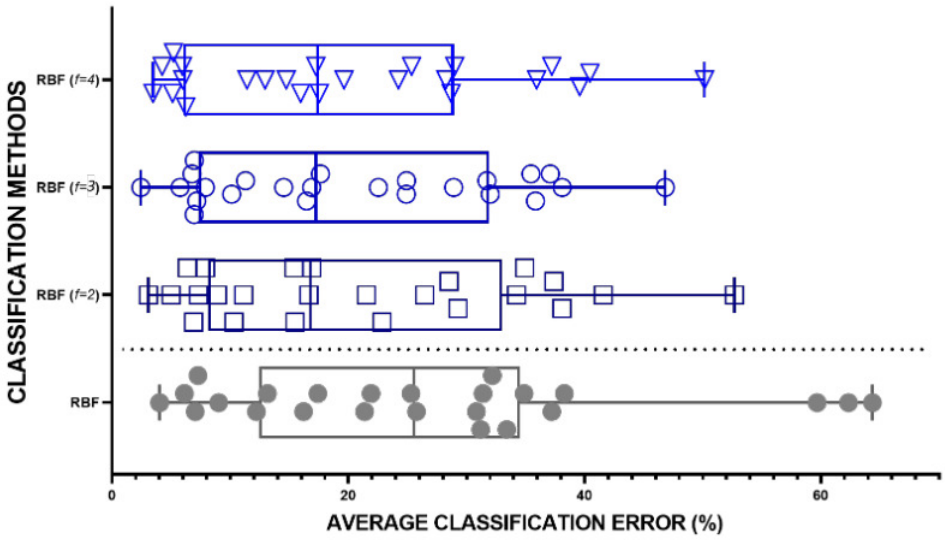

Figure 3. Comparison of the proposed RBF classification network for the construction of 2,3 and 4 artificial features (blue color) vs. a well-known RBF classification network (grey color) to the 24 different datasets.

4. Conclusions

A hybrid technique that utilizes a Particle Swarm Optimizer and a feature creation method using Grammatical Evolution was introduced here. The proposed method can identify possible dependencies between the original features and can also reduce the number of required features to a limited number. Also, the method can remove from the set of features those features that may not contribute to the learning of the data set by some machine learning model. In addition, to make learning more efficient, the values of the generated features are bounded within a value interval using penalty factors. The constructed features are evaluated in terms of their effectiveness with the help of a fast machine learning model such as the RBF network, even though other more effective models could also be used. Among the advantages of the proposed procedure is the fact that it does not require any prior knowledge of the data set to which it will be applied and furthermore, the procedure is exactly the same whether it is a data classification problem or a data fitting problem. The Particle Swarm Optimization method was used for the production of the characteristics as it has been proven by the relevant literature to be an extremely efficient technique and has a limited number of parameters that must be defined by the user.

The current work was applied on an extended series of widely used datasets from the various fields and was compared against some machine learning models on the same datasets. From the experimental results, it was seen that the proposed technique dramatically improves the performance of traditional learning techniques when applied to artificial features. This improvement reaches an average of 30% for data classification and 50% for data fitting problems. Furthermore, as shown in the experimental results, the proposed technique is able to give excellent results even when only two features are used. Future work in the nethod may include the use of parallel techniques for feature construction to drastically reduce the required execution time.

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