# Optimized Schwarz Method for the Linearized KdV equation and for coupling a NSWE-Serre model

J. Caldas <sup>1</sup> R. Cienfuegos <sup>3</sup> **J. Galaz** <sup>3</sup> A. Rousseau <sup>2</sup>

<sup>1</sup>MERIC, Chile

<sup>2</sup>Inria and Inria Chile

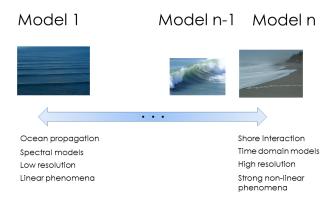
 $^3$ Department of Hydraulic and Environmental Engineering, Pontifical Catholic University of Chile

WTE2016

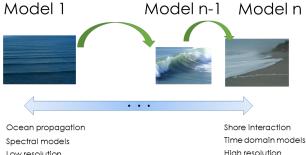
Advanced modelling for marine energy



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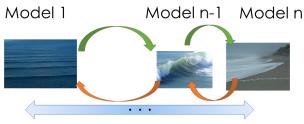


Advanced modelling for marine energy



Low resolution Linear phenomena High resolution Strong non-linear phenomena

Advanced modelling for marine energy



Ocean propagation Spectral models Low resolution Linear phenomena Shore interaction Time domain models High resolution Strong non-linear phenomena

#### Question

Can we make these different models communicate with each other?

### Truncated domain error: A tsunami simulation

Nonlinear long wave model (GeoClaw from the U. Washington)

### Challenges

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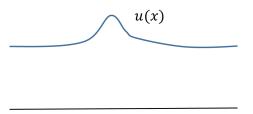
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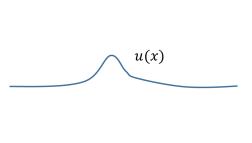
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#### Ongoing work

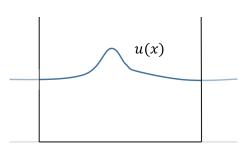
Develop a coupled model between the Non Linear Shallow Water Equations (NSWE) and the Serre equations

Start with an infinite domain:

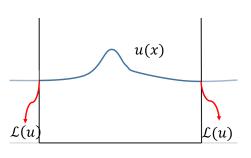




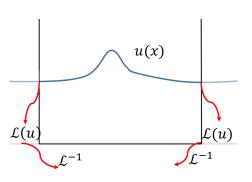
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- Un-apply it and get new equations for the boundaries

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• Not suited for numerical computations!

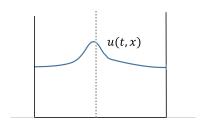
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# Approximate TBC's

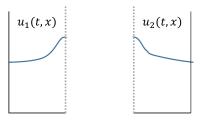
#### Result

Using the approximation  $\lambda(s) \approx c$  we obtain the following approximate TBC's

$$\begin{cases} u(t, left) - cu_x(t, left) + c^2 u_{xx}(t, left) = 0\\ u(t, right) - c^2 u_{xx}(t, right) = 0\\ u_x(t, right) + cu_{xx}(t, right) = 0 \end{cases}$$

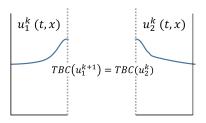


#### **DDM Methodology**



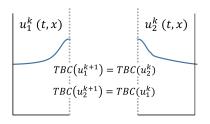
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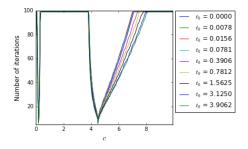


#### DDM Methodology

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- Iterate until convergence criteria.
- How do we determine the  $c_I$  and  $c_R$  constants?

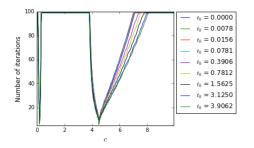
## DDM: Determination of optimal $c_L = c_R = c$

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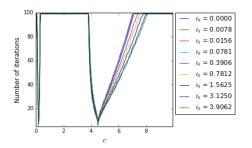


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• There exist optimal values for c (e.g  $\approx$  4.5) where convergence is observed with (only) 5-7 iterations.

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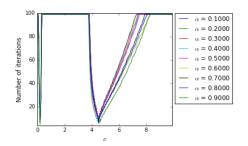
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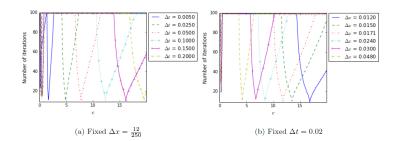
- There exist optimal values for c (e.g  $\approx$  4.5) where convergence is observed with (only) 5-7 iterations.
- There is no observed dependency on the initial condition.

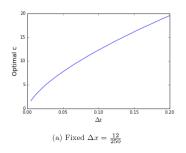
## DDM: Dependency on the location of the interface

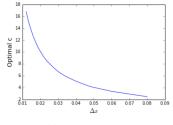


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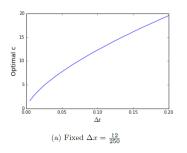


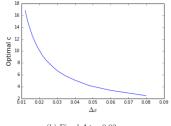


(b) Fixed  $\Delta t = 0.02$ 

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There is a strong dependance on  $\Delta x$  and  $\Delta t$ .





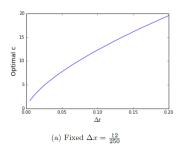
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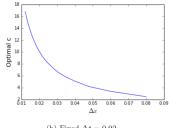
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$$c_{opt}(\Delta t, \Delta x) = \kappa + \alpha(\Delta t)^{2/3} + \beta \frac{1}{\Delta x} + \gamma \frac{\Delta t^{2/3}}{\Delta x}$$

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fits the numerical experiments with  $R^2=0.9999894$  for  $\kappa=0.0775$ ,  $\alpha=-0.3353$ ,  $\beta=-0.0012$ ,  $\gamma=2.7407$ 

## A coupled shallow water (NSWE) - Serre model

#### The Serre equations

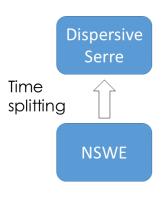
$$h_t + (hu)_x = 0$$

$$u_t + uu_x + gh_x - \frac{1}{3h} \left( h^3 \left( u_{xt} + uu_{xx} - (u_x)^2 \right) \right)_x = 0$$

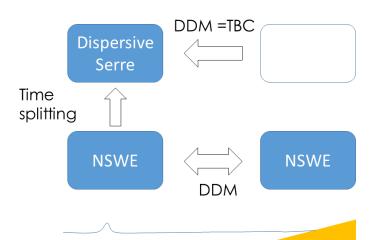
- *h* = the water column height
- u = depth averaged horizontal velocity (1D)



# Coupling methodology



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#### Numerical method

- Fractional splitting scheme for non-linear/dispersive terms (Bonneton et al, 2011).
- Well-balanced fourth order accurate Finite Volume NSWE model (Berthon and Marche, 2008)
- Fourth order Finite Difference model for the dispersive equation

## Three domain coupling: NSWE-Serre-NSWE