

HDP for Alignment of Multiple LC-MS Data in Metabolomics

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1 Introduction

Peak alignment is an important step in the pre-processing stages of LC-MS data. Errors produced during alignment will have a potentially significant impact in the later analysis stage (e.g. when performing differential analysis on the abundance of metabolites of interests). Existing methods do not take into account the dependencies of related peaks during alignments. We do that here by proposing a hierarchical Bayesian model that assigns related peaks to metabolite within and across files.

2 A Generative Model for LC-MS Data

Metabolites generates multiple clusters across files. In turn, clusters generates multiple peaks within files. We can model this process with a hierarchical mixture model of Gaussian components. Within each file, related peaks are grouped together. These groups are shared across files through top-level latent variables that represents the metabolites. We use Dirichlet Process (DP) prior to avoid setting the number of clusters a priori. The overall model fits into the Hierarchical Dirichlet Process (HDP) framework [1].

The observed data is the peak RT values $\mathbf{x} = (x_n^j)$ for all peaks across files. Within each file j , the peak RT value x_n^j is drawn from its parent cluster's RT t_k^j , which is normally distributed.

$$x_n^j | t_k^j, \gamma \sim \mathcal{N}(t_k^j, \gamma^{-1}) \quad (1)$$

The cluster RT t_{ij} in file j is drawn from the metabolite RT t_i that is shared across all files.

$$t_k^j | t_i, \delta \sim \mathcal{N}(t_i, \delta^{-1}) \quad (2)$$

The metabolite RT t_i is drawn from a base distribution of predicted retention times of metabolites. This is a Gaussian for now.

$$t_i | \mu_0, \sigma_0 \sim \mathcal{N}(\mu_0, \sigma_0^{-1}) \quad (3)$$

Add description about HDP, Chinese Restaurant Franchise and the stick breaking stuff

2.1 Modelling Assumptions

Some current assumptions to think about in the model:

1. Every peak must be generated by a metabolite. How about signals that are just noise (not coming from any metabolite) ?
2. Top-level component (metabolites) can produce multiple clusters in the same file. This seems to be a reasonable assumption ?
3. Not considering the mass information yet (including adducts, isotope etc) ..
4. We model RT drifts across replicates using the clusters (which are basically the noisy realisation of metabolite in each file). Assume clusters are IID given the parent metabolite, i.e. no correlation in the drift over time.

2.2 Inference

Denote the assignment of peak n to cluster k in file j by $z_{jnk} = 1$. The matrix \mathbf{Z} contains this assignment for all indices j, k and n in the model. We also need another indicator value to set the assignment of clusters within each file to the top-level component (metabolite) shared across files. Denote by $v_{jki} = 1$ if cluster k in file j is assigned to metabolite i . Collectively, we store the assignments in the matrix \mathbf{V} for all i, j and k .

Given the observed data \mathbf{x} , our task is to infer the parameters $\boldsymbol{\theta} = (\mathbf{t}, \mathbf{t}^j, \mathbf{Z}, \mathbf{V})$. We use Gibbs sampling to sample from the posterior distribution $P(\boldsymbol{\theta} | \mathbf{x}) \propto P(\mathbf{x} | \boldsymbol{\theta}) P(\boldsymbol{\theta})$. The likelihood term $P(\mathbf{x} | \boldsymbol{\theta})$ is

$$P(\mathbf{x} | \boldsymbol{\theta}) = \sum_i \sum_j \sum_n \left[p(x_n^j | t_k^j) \cdot p(t_k^j | t_i) \cdot p(z_{jnk} = 1) \cdot p(v_{jki} = 1) \right] \quad (4)$$

We set a DP prior with concentration parameter α on the assignment of peaks to clusters $p(z_{jnk} = 1)$, and another DP prior with concentration parameter α' on the assignment of clusters to metabolites $p(v_{jki} = 1)$. We use MCMC method to sample from the posterior distribution $P(\boldsymbol{\theta} | \mathbf{x})$. Specifically, we follow the posterior sampling in the Chinese restaurant franchise, as described in section 5.1 in [1]. Here, we explicitly assign the peaks to their parent clusters, which are then assigned to the parent metabolites.

The next sub-sections describe the update steps during Gibbs sampling of the posterior distribution

2.2.1 Initialisation

1. For every file, assign all peaks under 1 cluster.
2. Across files, all clusters are assigned under 1 global metabolite.
3. The metabolite's RT is sampled from the base distribution (eq. 3), and the cluster's RT is sampled conditioned on it's parent metabolite RT (eq. 2).

2.2.2 Useful identities

The integral of the product of two pdf $p(x|y, c) \cdot p(y|a, b)$ where both are normal densities

$$\int [\mathcal{N}(x|y, c^{-1}) \cdot \mathcal{N}(y|a, b^{-1})] dy \propto \mathcal{N}(x|a, (c^{-1} + b^{-1})) \quad (5)$$

Proof to follow ...

2.2.3 Updating peak assignments

To update the assignment of peak n to cluster k in file j , we need the conditional probability of $p(z_{jnk} = 1)$ given other parameters. This is

$$p(z_{jnk} = 1 | \dots) \propto \begin{cases} c_{jk} \cdot L(x_n^j | z_{jnk} = 1) \\ \alpha \cdot L(x_n^j | z_{jnk^*} = 1) \end{cases} \quad (6)$$

For existing cluster k , the likelihood of the peak is proportional to c_{jk} , the number of peaks inside that cluster.

$$L(x_n^j | z_{jnk} = 1) = \mathcal{N}(x_n^j | t_k^j, \gamma^{-1}) \quad (7)$$

For a new cluster k^* , this is proportional to α . The likelihood then depends on whether the peak is assigned to an existing metabolite i or a new metabolite i^* .

$$L(x_n^j | z_{jnk^*} = 1) = \sum_i \left[\frac{c_i}{\alpha' + \sum_i c_i} p(x_i^j | v_{jk^*i} = 1) \right] + \frac{\alpha'}{\alpha' + \sum_i c_i} p(x_i^j | v_{jk^*i^*} = 1) \quad (8)$$

For existing metabolite i , $p(x_i^j | v_{jk^*i} = 1)$, the likelihood of the peak under that metabolite, can be computed by marginalising over all possible values of clusters RT t_k^j . Note that we use the identity in equation 5 to go from equation 10 to equation 11.

$$p(x_n^j | v_{jk^*i} = 1) \propto \int \left[p(x_n^j | t_k^j) p(t_k^j | t_i) \right] dt_k^j \quad (9)$$

$$\propto \int \left[\mathcal{N}(x_n^j | t_k^j, \gamma^{-1}) \cdot \mathcal{N}(t_k^j | t_i, \delta^{-1}) \right] dt_k^j \quad (10)$$

$$\propto \mathcal{N}(x_n^j | t_i, (\gamma^{-1} + \delta^{-1})) \quad (11)$$

For new metabolite i^* , the likelihood is obtained by marginalising over all possible values of clusters RT t_k^j and metabolite RT t_i

$$p(x_n^j | v_{jk^*i^*} = 1) \propto \int \int \left[p(x_n^j | t_k^j) p(t_k^j | t_i) \right] dt_k^j dt_i \quad (12)$$

$$\propto \int \int \left[\mathcal{N}(x_n^j | t_k^j, \gamma^{-1}) \cdot \mathcal{N}(t_k^j | t_i, \delta^{-1}) \cdot \mathcal{N}(t_i | \mu_0, \sigma_0^{-1}) \right] dt_k^j dt_i \quad (13)$$

$$\propto \mathcal{N}(x_n^j | \mu_0, (\sigma_0^{-1} + \gamma^{-1} + \delta^{-1})) \quad (14)$$

The above assignment steps can be illustrated using the Chinese Restaurant Franchise metaphor. Here, a peak is a customer, a file is a restaurant, a cluster is a table, and a metabolite is a dish. During the Gibbs sampling step, a new customer $n + 1$ arrives in the restaurant. We then need to determine whether this new customer is to be seated on a new or existing table. For an existing table, the likelihood proportional to the number of people already sitting on that table (c_{jk}) times the likelihood of the new customer belonging on the table (eq. 7). For a new table, the likelihood is proportional to the DP concentration parameter α times the likelihood of ordering any of the existing or new dishes (eq. 8). When deciding which dish to order, we marginalise over all possible tables in eq. 9 and eq. 12 (so we don't have to care about which table is actually selected).

Having computed both likelihood values of the customer sitting on existing tables or a new table (eq. 6), we do a coin toss to decide which table k is actually selected. At this point, we should have maintained a restaurant-level variable K , which is the counter of all tables that exist in the restaurant. If $k \leq K$, we send the customer to sit on table k and share the dish already ordered by his friends sitting on table k . Otherwise if $k > K$, we increment K by 1, create a new table $k + 1$ and offers the customer the menu of dishes to order. At this point, the new table $k + 1$ is created but not assigned any retention time value (mixture parameter) yet. We will return to this later.

Since the customer is the first to sit on the table, he would order the dish to be shared on that table. We reuse the computation done for eq. 8 to compute the likelihood of the new customer ordering existing dishes or new dish, and do a coin toss to select the dish i . If $i \leq I$, where I is the global counter of all dishes that exist *across restaurants*, we serve the customer the dish i . Otherwise, we get our chef to devise a new dish $i + 1$ for him. The new dish $i + 1$ can subsequently be ordered by any new customer that arrives

in any of the restaurant in our franchise. The mixture parameter (retention time value) t_i of the new dish $i + 1$ can be computed given the data x_n^j using Bayes' rule:

$$p(t_i|x_n^j) \propto p(x_n^j|t_i)p(t_i) \quad (15)$$

$$\propto \left[\int p(x_n^j|t_k^j)p(t_k^j|t_i) dt_k^j \right] \cdot p(t_i) \quad (16)$$

$$\propto \left[\int \mathcal{N}(x_n^j|t_k^j, \gamma^{-1}) \cdot \mathcal{N}(t_k^j|t_i, \delta^{-1}) dt_k^j \right] \cdot \mathcal{N}(t_i|\mu_0, \sigma_0^{-1}) \quad (17)$$

$$\propto \mathcal{N}(x_n^j|t_i, \gamma^{-1} + \delta^{-1}) \cdot \mathcal{N}(t_i|\mu_0, \sigma_0^{-1}) \quad (18)$$

In the LHS of the equation above, $p(t_i|x_n^j)$ is a Normal distribution. Let's say it is parameterised by $\mathcal{N}(t_i|\mu_i, \gamma_i^{-1})$.

$$\mathcal{N}(t_i|\mu_i, \gamma_i^{-1}) \propto \mathcal{N}(x_n^j|t_i, \gamma^{-1} + \delta^{-1}) \cdot \mathcal{N}(t_i|\mu_0, \sigma_0^{-1}) \quad (19)$$

$$\exp\left(\frac{-\gamma_i}{2}(t_i - \mu_i)^2\right) \propto \exp\left(\frac{-(\gamma^{-1} + \delta^{-1})^{-1}}{2}(x_n^j - t_i)^2 + \frac{-\sigma_0}{2}(t_i - \mu_0)^2\right) \quad (20)$$

Collecting the quadratic term containing $(t_i)^2$, we can solve for γ_i

$$\frac{-\gamma_i}{2}(t_i)^2 = \frac{(\gamma^{-1} + \delta^{-1})^{-1}}{2}(t_i)^2 + \frac{-\sigma_0}{2}(t_i)^2 \quad (21)$$

$$\gamma_i = (\gamma^{-1} + \delta^{-1})^{-1} + \sigma_0 \quad (22)$$

Similarly, collecting the linear term containing t_i , we can solve for μ_i

$$\frac{-\gamma_i}{2}(2t_i\mu_i) = \frac{-(\gamma^{-1} + \delta^{-1})^{-1}}{2}(2x_n^j t_i) + \frac{-\sigma_0}{2}(2t_i\mu_0) \quad (23)$$

$$-\gamma_i\mu_i = -(\gamma^{-1} + \delta^{-1})^{-1}x_n^j - \sigma_0\mu_0 \quad (24)$$

$$\mu_i = \frac{1}{\gamma_i} [(\gamma^{-1} + \delta^{-1})^{-1}x_n^j + \sigma_0\mu_0] \quad (25)$$

So, when creating a new dish t_i , we sample its value from a Normal distribution $\mathcal{N}(t_i|\mu_i, \gamma_i^{-1})$ with mean μ_i and precision γ_i given above. Similarly, we can sample from the posterior distribution of table value t_k^j given its parent t_i and the data x_n^j :

$$p(t_k^j|x_n^j) \propto p(x_n^j|t_k^j)p(t_k^j|t_i) = \mathcal{N}(t_k^j|\mu_k, \gamma_k^{-1}) \quad (26)$$

where

$$\gamma_k = \gamma + \delta \quad (27)$$

$$\mu_k = \frac{1}{\gamma_k} [\gamma x_n^j + \delta t_i] \quad (28)$$

The specific steps to update $p(z_{jnk} = 1)$ is given in algorithm 1.

Algorithm 1 Updating peak assignments (assign_peaks.m)

```

I = 0, K = 0
j = loop randomly over files
  n = loop randomly over peaks

    remove peak n from model
    if this results in empty cluster k
      delete cluster k from model
      if this results in empty metabolite i
        delete metabolite i from model
      end
    end
  end

  P1 = compute cjk * L(peak n|existing cluster, eq 7, 8)
  P2 = compute alpha * L(peak n|new cluster, eq 7, 9)
  new_k = pick_cluster(P1, P2)
  if new_k > K

    K = K+1
    P3 = compute ci * L(peak n|existing metabolite, eq 10)
    P4 = compute alpha' * L(peak n|new metabolite, eq 11)
    new_i = pick_metabolite(P3, P4)

    if new_i > I
      I = I+1
      ti = sample new metabolite RT given peak n (eq. 16)
      set metabolite RT = ti
    end
    tij = sample new cluster RT given ti and peak n (eq. 27)
    set cluster RT = tij

  end
  assign Zjnk = 1 for peak n to cluster k in file j
end

```

2.2.4 Updating cluster assignments

Given some existing cluster k , we would like to assign this cluster (a whole block of peaks $\{x_n^j\}$ under k) into a new metabolite i .

The probability is proportional to c_i for existing metabolite and α' for new metabolite. The likelihood term for existing table is

$$p(t_k^j|t_i) = \mathcal{N}(t_i, \delta^{-1}) \quad (29)$$

For new table, it is

$$p(t_k^j|t_{i*}) \propto \int \left[p(t_k^j|t_i) \cdot p(t_i|\mu_0, \sigma_0) \right] dt_i \quad (30)$$

$$\propto \int \left[\mathcal{N}(t_k^j|t_i, \delta^{-1}) \cdot \mathcal{N}(t_i|\mu_0, \sigma_0^{-1}) \right] dt_i \quad (31)$$

$$\propto \mathcal{N}(t_i|\mu_0, (\delta^{-1} + \sigma_0^{-1})) \quad (32)$$

If we marginalise out t_k^j , the metabolite RT t_i is known but the new cluster RT t_k^j is unknown, so we can no longer assume conditional independence between the peaks. To compute the probability of this block of peaks under the new metabolite i , we have to apply the chain rule:

$$p(x_1^j, x_2^j, \dots, x_n^j|t_i) = p(x_1^j|t_i) \cdot p(x_2^j|t_i, x_1^j) \cdot p(x_3^j|t_i, x_1^j, x_2^j) \dots p(x_n^j|t_i, x_1^j, x_2^j, \dots, x_{n-1}^j) \quad (33)$$

where

$$p(x_n^j|t_i, x_1^j, x_2^j, \dots, x_{n-1}^j) = \int \left[p(x_n^j|t_k^j) \cdot p(t_k^j|t_i, x_1^j, x_2^j, \dots, x_{n-1}^j) \right] dt_k^j \quad (34)$$

More to come ..

2.2.5 Updating metabolite RTs

The conditional probability of metabolite RTs $p(t_i|\dots)$ is given by the product of the prior probability on t_i multiplied by the likelihood of the RT values of metabolite i 's child clusters. $t_{v_{jki}=1}^j$ denotes the retention time of cluster k in file j that is assigned to metabolite i . There is a total of J files altogether. So, for every metabolite i , we update its RT:

$$p(t_i|\dots) \propto p(t_i|\mu_0, \sigma_0^{-1}) \prod_j^J \prod_k^K p(t_{v_{jki}=1}^j|t_i, \delta^{-1}) = \mathcal{N}(\mu_a, \gamma_a^{-1}) \quad (35)$$

where

$$\mu_a = \frac{1}{\gamma_a} \left[\mu_0 \sigma_0 + \delta \sum_j \sum_k t_{v_{jki}=1}^j \right] \quad (36)$$

$$\gamma_a = \sigma_0 + c_{v_{jki}=1} \delta \quad (37)$$

$$c_{v_{jki}=1} = \sum_j \sum_k I(v_{jki} = 1) \quad (38)$$

2.2.6 Updating cluster RTs

Similar to above, for every j file, there is a total of N peaks inside. $x_{z_{jnk}=1}^j$ denotes the retention time of peak n that is assigned to cluster k in file j . So, for every cluster k in file j , we update its RT:

$$p(t_k^j | \dots) \propto p(t_k^j | t_i, \delta^{-1}) \prod_n^N p(x_{z_{jnk}=1}^j | t_k^j, \gamma^{-1}) = \mathcal{N}(\mu_b, \gamma_b^{-1}) \quad (39)$$

where

$$\mu_b = \frac{1}{\gamma_b} \left[t_i \delta + \gamma \sum_n x_{z_{jnk}=1}^j \right] \quad (40)$$

$$\gamma_b = \delta + c_{z_{jnk}=1} \gamma \quad (41)$$

$$c_{z_{jnk}=1} = \sum_n I(z_{jnk} = 1) \quad (42)$$

2.2.7 Results

Some plots ..

References

- [1] Yee Whye Teh, Michael I Jordan, Matthew J Beal, and David M Blei. Hierarchical Dirichlet Processes. pages 1–30, 2005.

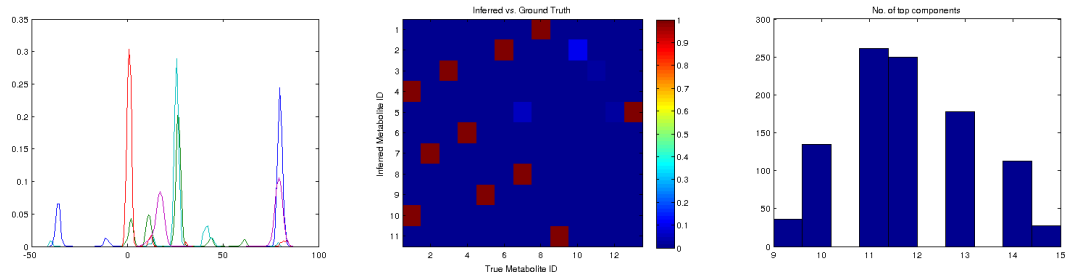


Figure 1: Sample result