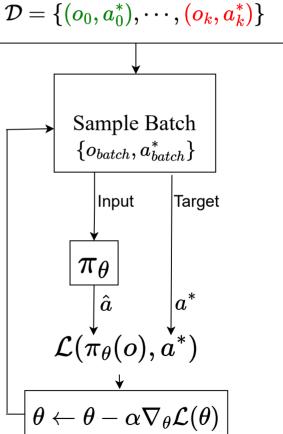
Dataset Generation Expert

 o_i

Observation

Obstacle

IL Training



 $egin{aligned} a_i^* \ & \end{bmatrix}$

Goal

Agent