Selim Engin

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EDUCATION

University of Minnesota   Minneapolis, MN
Ph.D. Student in Computer Science and Engineering   *Sept 2016 - present*
Advisor: Prof. Volkan Isler

Sabancı University   Istanbul, Turkey
B.Sc. in Mechatronics Engineering, with high honors   *Sept 2012 - June 2016*

EXPERIENCE

Samsung Research Artificial Intelligence Center   New York City, NY
Research Intern   *Jan 2019 - Aug 2019*

- 3D reconstruction from single image; multi-view stereo; object part decomposition from images
- Velocity controller implementation for visual servoing with a manipulator robot

Robotic Sensor Networks Lab   Minneapolis, MN
Graduate Student   *Sept 2016 - present*

- State representation learning for stochastic and adversarial search problems
- Active localization of targets using multiple robots equipped with bearing-only sensors
- Approximation algorithms and online strategies for network formation of a multi-robot system
- Self-supervised learning methods for novel view synthesis and 3D reconstruction

Knowledge Representation and Reasoning Group   Istanbul, Turkey
Undergraduate Researcher   *Sept 2015 - June 2016*

- Action planner implementation for rearrangement of a cluttered scene and grasping the objects

Joint Institute of Engineering, Sun Yat-sen – Carnegie Mellon University   Guangdong, China
Undergraduate Research Intern   *June 2015 - Sept 2015*

- System identification and state of charge estimation of deteriorated Lithium-ion batteries

Automation and Information Systems, Technical University of Munich   Munich, Germany
Undergraduate Research Intern   *July 2014 - Sept 2014*

- Traffic signalization and control; conveyor band automation using sensors and actuators

PUBLICATIONS

1. **S. Engin**, V. Isler, Establishing Fault-Tolerant Connectivity of Mobile Robot Networks, *IEEE Transactions on Control of Network Systems (TCNS)*, 2020 (conditionally accepted).

2. N. Häni, **S. Engin**, J-J. Chao, V. Isler, Unsupervised Continuous Object Representation Networks for Novel View Synthesis, *Conference on Neural Information Processing Systems (NeurIPS)*, 2020.

3. **S. Engin**, V. Isler, Active Localization of Multiple Targets Using Noisy Relative Measurements, *Workshop on the Algorithmic Foundations of Robotics (WAFR)*, 2020.

4. **S. Engin**, E. Mitchell, D. Lee, V. Isler, D. D. Lee, Higher Order Function Networks for View Planning and Multi-View Reconstruction, *International Conference on Robotics and Automation (ICRA)*, 2020.

5. E. Mitchell, **S. Engin**, V. Isler, D. D. Lee, Higher Order Function Networks for Learning Composable 3D Object Representations, *International Conference on Learning Representations (ICLR)*, 2020.

6. **S. Engin**, V. Isler, Asynchronous Network Formation in Unknown and Unbounded Environments, *International Conference on Robotics and Automation (ICRA)*, 2019.

7. **S. Engin**, V. Isler, Minimizing Movement to Establish the Connectivity of Randomly Deployed Robots, *International Conference on Automated Planning and Scheduling (ICAPS)*, 2018.

8. H. Bayram, N. Stefas, **S. Engin**, V. Isler, Tracking Wildlife with Multiple UAVs: System Design, Safety and Field Experiments, *IEEE International Symposium on Multi-Robot and Multi-Agent Systems (MRS)*, 2017.

Honors

- Cedar Creek Ecosystem Science Reserve Fellowship (2018)

- University of Minnesota CSE Fellowship (2017)

- Sabancı University Scholarship (2012-16)

Teaching Experience

CSCI 1133 - Introduction to Computing and Programming Concepts (Spring 2017, Fall 2017):
GitHub organization setup for the class, preparing assignments, grading/auto-grading and interviewing students

Professional Services

Reviewer for IROS (2017-20), ICRA (2018-21), NeurIPS (2019-20), ICLR (2020-21), WAFR (2020)

Recent Talks

- Aerospace Engineering and Mechanics Research Seminar, Virtual, April 2020

- CS Graduate Research and Discussion Seminars, Minneapolis, MN, March 2020

- Samsung Vision Workshop, Seoul, Korea, November 2019

- Samsung AI Center Research Seminar, New York City, NY, November 2018

- UMN Visual Computing & AI Seminar, Minneapolis, MN, November 2018

Technical Skills

Languages: Python, C, C++, Matlab/Simulink, Standard ML, HTML/CSS
Frameworks and Libraries: PyTorch, JAX, Tensorflow, NumPy, OpenCV, Open3D, PCL, Matplotlib
Robotics and Simulation: ROS, V-REP, Gazebo, MuJoCo, Blender, SolidWorks