

**Kazim Selim Engin**  
Ph.D. Student  
100 Union St. SE Minneapolis, MN

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engin003@umn.edu  
<http://z.umn.edu/ksen>

## Education

- University of Minnesota** Minneapolis, MN
  - *Ph.D. Student in Computer Science and Engineering* *Sept 2016 - present*  
Advisor: Prof. Volkan Isler
- Sabancı University** Istanbul, Turkey
  - *B.S. in Mechatronics Engineering, with high honors* *Sept 2012 - June 2016*

## Research Experience

- Samsung Research Artificial Intelligence Center New York City, NY  
*Research Intern* *Jan 2019 - Aug 2019*
  - Single and multi-view 3D reconstruction; learning manipulable object representations; object part decomposition from images
  - Velocity controller implementation for visual servoing with a manipulator robot
- Robotic Sensor Networks Lab Minneapolis, MN  
*Graduate Student* *Sept 2016 - present*
  - Approximation algorithms and online strategies for network formation of a multi-robot system
  - Localization of targets using multiple UAVs equipped with bearing-only sensors
  - Self-supervised learning methods for novel view synthesis and 3D reconstruction
- Knowledge Representation and Reasoning Group Istanbul, Turkey  
*Undergraduate Researcher* *Sept 2015 - June 2016*
  - Action planner implementation for rearrangement of a cluttered scene and grasping the objects
- Joint Institute of Engineering, SYSU-CMU Guangdong, China  
*Undergraduate Research Intern* *June 2015 - Sept 2015*
  - System identification and state of charge estimation of deteriorated Lithium-ion batteries
- Automation and Information Systems, Technical University of Munich Munich, Germany  
*Undergraduate Research Intern* *July 2014 - Sept 2014*
  - Traffic signalization and control using Matlab Stateflow
  - Conveyor band automation using various sensors and actuators

## Publications

1. **S. Engin**, V. Isler, Establishing Fault-Tolerant Connectivity of Mobile Robot Networks, *IEEE Transactions on Control of Network Systems (TCNS)*, 2020 (under review).

2. N. Häni, **S. Engin**, J-J. Chao, V. Isler, Unsupervised Continuous Object Representation Networks for Novel View Synthesis, *Conference on Neural Information Processing Systems (NeurIPS)*, 2020.
3. **S. Engin**, V. Isler, Active Localization of Multiple Targets Using Noisy Relative Measurements, *Workshop on the Algorithmic Foundations of Robotics (WAFR)*, 2020.
4. **S. Engin**, E. Mitchell, D. Lee, V. Isler, D. D. Lee, Higher Order Function Networks for View Planning and Multi-View Reconstruction, *International Conference on Robotics and Automation (ICRA)*, 2020.
5. E. Mitchell, **S. Engin**, V. Isler, D. D. Lee, Higher Order Function Networks for Learning Composable 3D Object Representations, *International Conference on Learning Representations (ICLR)*, 2020.
6. **S. Engin**, V. Isler, Asynchronous Network Formation in Unknown and Unbounded Environments, *International Conference on Robotics and Automation (ICRA)*, 2019.
7. **S. Engin**, V. Isler, Minimizing Movement to Establish the Connectivity of Randomly Deployed Robots, *International Conference on Automated Planning and Scheduling (ICAPS)*, 2018.
8. H. Bayram, N. Stefas, **S. Engin**, V. Isler, Tracking Wildlife with Multiple UAVs: System Design, Safety and Field Experiments, *IEEE International Symposium on Multi-Robot and Multi-Agent Systems (MRS)*, 2017.

## Honors

- Cedar Creek Ecosystem Science Reserve Fellowship (2018)
- University of Minnesota CSE Fellowship (2017)
- Sabancı University Scholarship (2012-16)

## Teaching Experience

CSCI 1133 - Introduction to Computing and Programming Concepts (Spring 2017, Fall 2017):  
GitHub organization setup for the class, preparing assignments, grading/auto-grading and interviewing students

## Professional Services

Reviewer for IROS (2017-20), ICRA (2018-20), NeurIPS (2019-20), ICLR (2020-21), WAFR (2020)

## Recent Talks

- Aerospace Engineering and Mechanics Research Seminar, Minneapolis, MN, April 2020
- CS Graduate Research and Discussion Seminars, Minneapolis, MN, March 2020
- Samsung Vision Workshop, Seoul, Korea, November 2019

- Samsung AI Center Research Seminar, New York City, NY, November 2018
- UMN Visual Computing & AI Seminar, Minneapolis, MN, November 2018

## **Technical Skills**

Python, C++, PyTorch, Matlab/Simulink