

Indian Institute Of Technology Kanpur

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AE 351A  
Experiments in Aerospace Engineering 2020-21  
Semester II

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# **Torsion Testing**

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## 1 Objective

Perform a torsion (shear) test on a shaft with a circular cross section and measure the shear modulus of a material using two different methods.

## 2 Introduction And Theory

Torsion is a moment that twists/deforms a member about its longitudinal axis. In sections perpendicular to the torque axis, the resultant shear stress in this section is perpendicular to the radius. Assumptions :

- Plane sections remain plane and perpendicular to the Torsional axis
- Material of the shaft is uniform
- Twist along the shaft is uniform
- Axis remains straight and in-extensible
- Angle of rotation is small, hence length of shaft and its radius remain unchanged

For shafts of uniform cross-section the torsion is:

$$\frac{T}{J} = \frac{\tau}{R} = \frac{G\theta}{L}$$

Where T= torque applied for twisting

J = Polar Inertia

R= Radius of the shaft

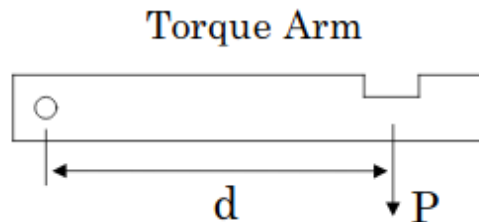
$\tau$  = Shear stress

G= Modulus of Rigidity

L = Length of the shaft

$\theta$  = Angle twisted

### 1. Calculation of Applied Torque

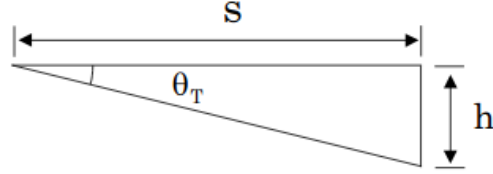


The torque is given by,

$$T = Pd \quad (1)$$

where P is the applied load, and d is the length of the torque arm

## 2. Calculation of the Angle of Twist

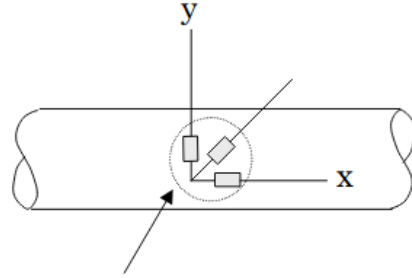


The angle of twist is measured by,

$$\tan \theta_T = \frac{h}{s} \quad (2)$$

where h is the vertical deflection of the torque arm measured using a deflection dial gage, and s is the distance between the center of the shaft and the dial gage.

## 3. Calculation of Shear Strain from the 0-45-90 Strain Gage Rosette Data



**0° - 45° - 90° Strain Gage Rosette**

From strain transformation equation the normal strain for a given orientation can be calculated by using mechanics of solids equation,

$$\epsilon_n(\theta) = \epsilon_x \cos^2 \theta + \epsilon_y \sin^2 \theta + \gamma_{xy} \sin \theta \cos \theta$$

Applying this relation at each of the gage angles leads to:

$$\begin{aligned} \epsilon_0 &= \epsilon_x \\ \epsilon_{45} &= \frac{\epsilon_x + \epsilon_y + \gamma_{xy}}{2} \\ \epsilon_{90} &= \epsilon_y \end{aligned}$$

The shear strain can be obtained by rearranging the above expressions, where  $\epsilon_0$ ,  $\epsilon_{45}$  and  $\epsilon_{90}$  are the strain values recorded using 0-45-90 strain gage rosette.

$$\gamma_{xy} = 2\epsilon_{45} - \epsilon_0 - \epsilon_{90} \quad (3)$$

### 3 Equipment's

1. Aluminium alloy 6063 T-6 specimen
2. Strain gage
3. Strain indicator
4. Dial gage
5. Weights
6. Torsion test fixtures

### 4 Procedure and Measurements

- Took measurement of specimen

Material	AA6063
Radius of Beam( <b>R</b> )	10mm
Total length of Beam( <b>L</b> )	687mm
Distance between shaft centre and dial gage( <b>s</b> )	135mm
Torque Arm Length( <b>d</b> )	170mm

Table 1: Initial measurement of specimen

- Applied loads to the torque arm and increased load by 10N
- Recorded all the three strain gage readings, and the vertical deflection of the torque arm at each load.
- Determined the torque, shear strain, and the angle of twist for each applied load. Tabulated all measurements and calculations.

### 5 Results And Discussion

#### 5.1 Sample Calculations

- Polar moment of inertia

$$J = \pi R^4 / 2$$
$$J = \frac{\pi * (0.01)^4}{2}$$
$$J = 1.5707 * 10^{-8} m^4$$

- For 14.715N load

- h = 1.29 mm
- **Angle of twist**  $\theta = \tan^{-1}(\frac{1.29}{135}) = 0.0096 \text{ rad}$
- **Torque**

$$\begin{aligned} T &= 2 * \text{load} * (\text{torque arm length}) \\ &= 2 * 14.715 * 0.170 \\ &= 5.0031 \text{ N.m} \end{aligned}$$

- **Shear Strain**

$$\begin{aligned} \gamma &= 2\epsilon_{45} - \epsilon_0 - \epsilon_{90} \\ &= 2 * 61 - (-1) - 0.019 \\ &= 122.981 \mu\text{m/m} \end{aligned}$$

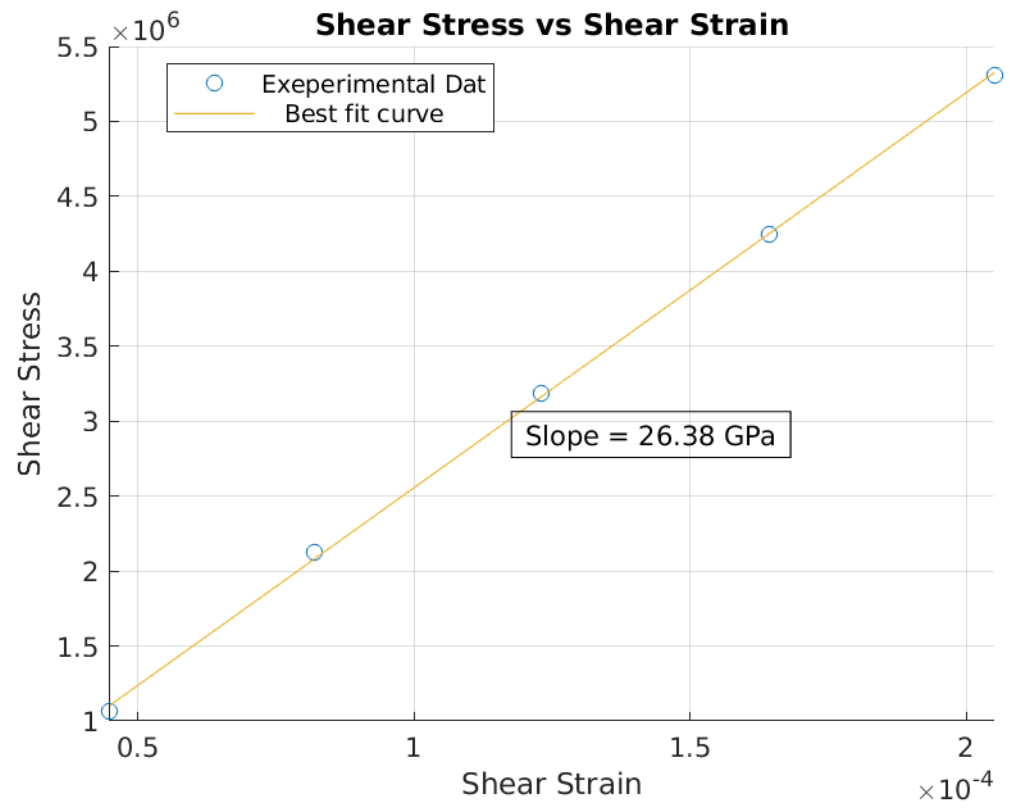
- **Shear Stress**

$$\begin{aligned} \tau &= \frac{T * R}{J} \\ &= \frac{5.0031 * 0.01}{1.5707 * 10^{-8}} \\ &= 3.18 \text{ MPa} \end{aligned}$$

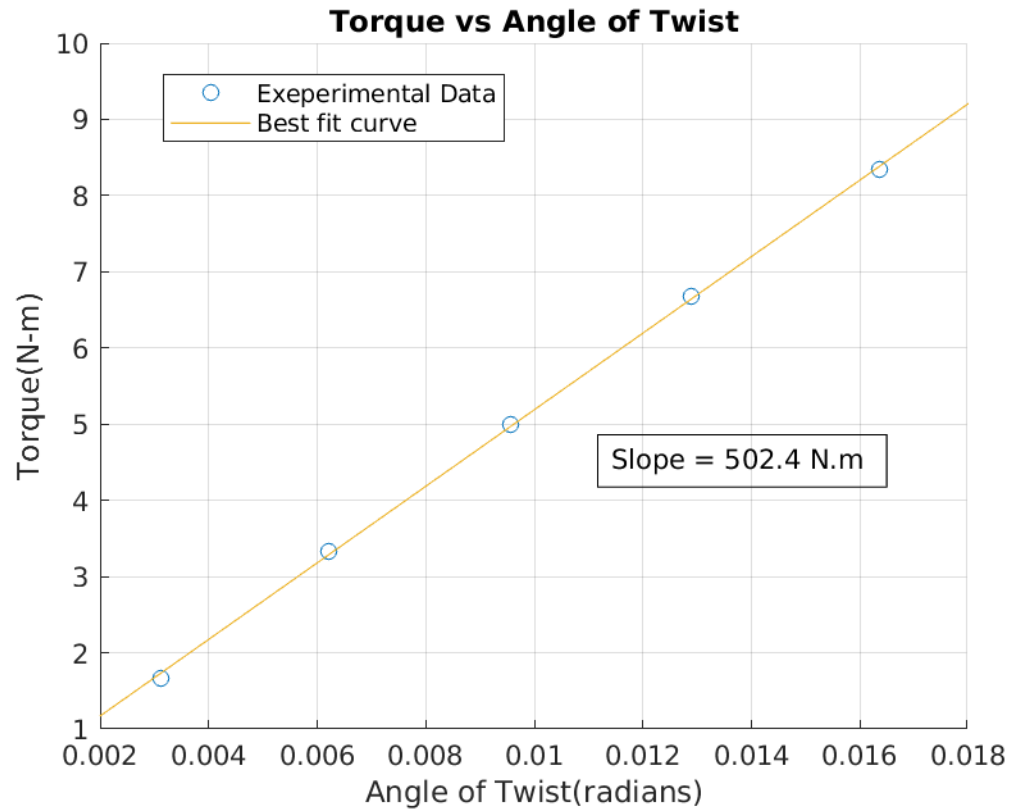
## 5.2 Data Presentation

Load (N)	$\epsilon_0$ ( $\mu\text{m/m}$ )	$\epsilon_{45}$ ( $\mu\text{m/m}$ )	$\epsilon_{90}$ ( $\mu\text{m/m}$ )	h (mm)	$\theta = \tan^{-1}(h/s)$ (radian)	Torque (N.m)	$\gamma_{xy}$ ( $\mu\text{m/m}$ )	$\tau_{xy}$ (MPa)
4.905	0	22.5	0.02	0.42	0.0031	1.6677	44.98	1.061
9.81	-1	40.5	0.015	0.84	0.0062	3.3354	81.985	2.1234
14.715	-1	61	0.019	1.29	0.0096	5.0031	122.981	3.1851
19.62	-1.5	81.4	0.016	1.74	0.0129	6.6708	164.284	4.2468
24.525	-2	101.5	0.012	2.21	0.0164	8.3385	204.989	5.3085

Table 2: Experimental Data



slope of the curve : **G (Rigidity modulus) = 26.38 GPa**



$$\text{slope of the curve} = \mathbf{JG/L} = 502.4 \text{ N.m}$$

$$\mathbf{G} = \text{slope} * (L/J)$$

$$\mathbf{G} = \frac{502.4 * 0.687}{1.5707 * 10^{-8}}$$

$$\mathbf{G} = 21.97 \text{ GPa}$$

### 5.3 Discussion and Error analysis

#### 1. Stress-Strain curve (Method-I)

- Published Shear modulus = 25.8 GPa
- Experimental Shear modulus = 26.38 GPa
- Error =

$$\frac{26.38 - 25.8}{26.38} * 100\% = \mathbf{2.19\%}$$

## 2. Torque-Twist angle curve (Method-II)

- Published Shear modulus = 25.8 GPa
- Experimental Shear modulus = 21.97 GPa
- Error = 
$$\frac{25.8 - 21.97}{25.8} * 100\% = \mathbf{14.84\%}$$

## 6 Conclusion

- The shear modulus value obtained from stress strain curve is more accurate because the values are recorded from the pure torsion region.
- In method II, whole specimen is considered for calculation, however whole specimen is not only under the action of pure torsion but bending also.
- The difference in value obtained from Method II is also due to the human error that might have occurred during the experiment.

## 7 Appendix

**Experimental Table**

Load	h	strain_0	strain_45	strain_90
4.905	0.42	0	22.5	0.02
9.81	0.84	-1	40.5	0.015
14.715	1.29	-1	61	0.019
19.62	1.74	-1.5	81.4	0.016
24.525	2.21	-2	101.5	0.012