Self-supervised Point Cloud Representation Learning via Separating Mixed Shapes

MULTIMEDIA

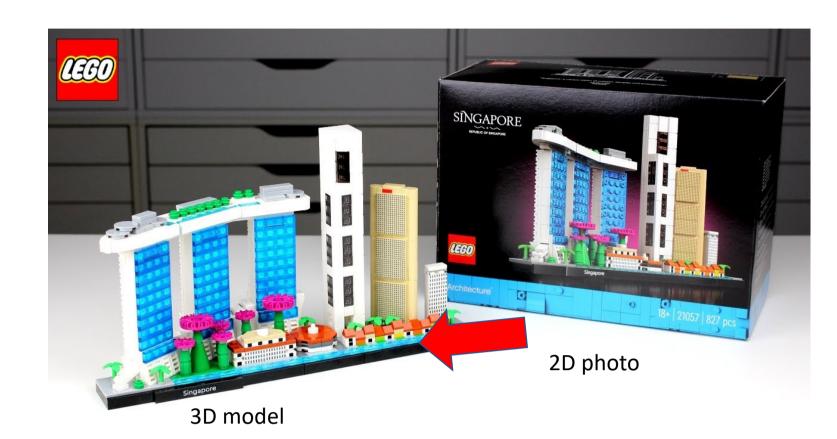
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Motivation

People can reconstruct the 3D models (left) according to 2D projection (right). How about we ask the deeply-learned model to do that as pretext task?



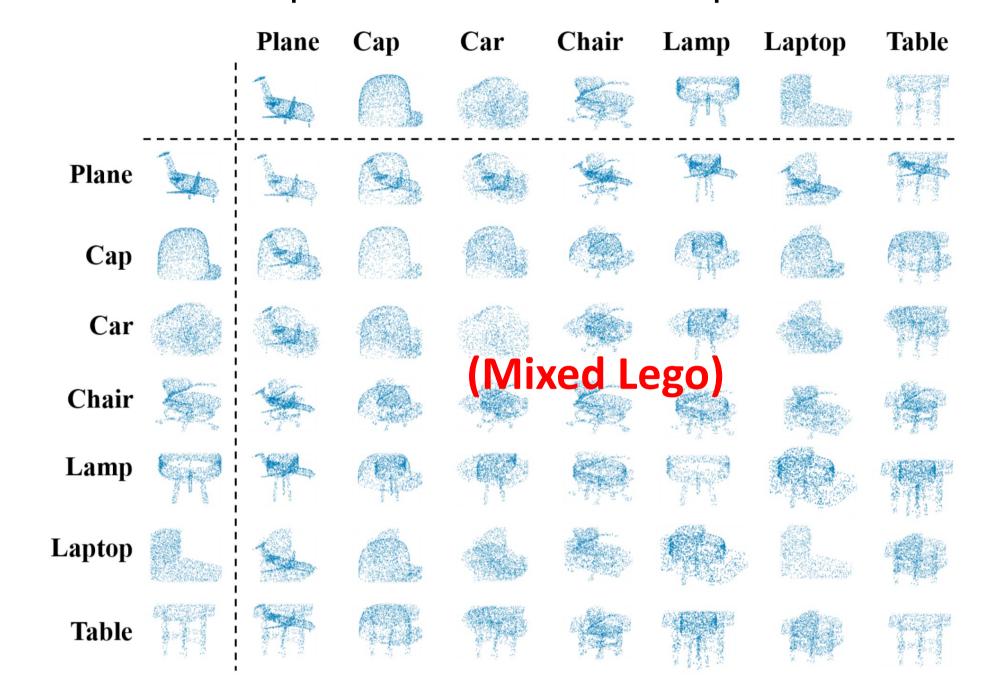
Contribution

- We leverage the mixing process to generate large-scale mixed data for 3D point cloud training. Inspired by the human ability to figure out two shapes from one mixed object, we new self-supervised learning method on the point cloud, called Mixing and Disentangling (MD), learn the to geometric prior knowledge without requisite of annotations
- We implement one basic pipeline to verify the effectiveness of the proposed self-supervised learning strategy. It contains one encoder with the learnable aggregation function and one instance- adaptive decoder, to learn from the mixed point cloud conduct and disentanglement. Albeit simple, experimental results on two benchmarks, i.e., ModelNet-40 ShapeNet-Part, show that the selfsupervised learning model can effectively and the efficiently improve accuracy classification and segmentation tasks by the pre-training and fine-tuning paradigm. Selfsupervised learning on the point cloud also reduces the network dependence on labeled data.

Method

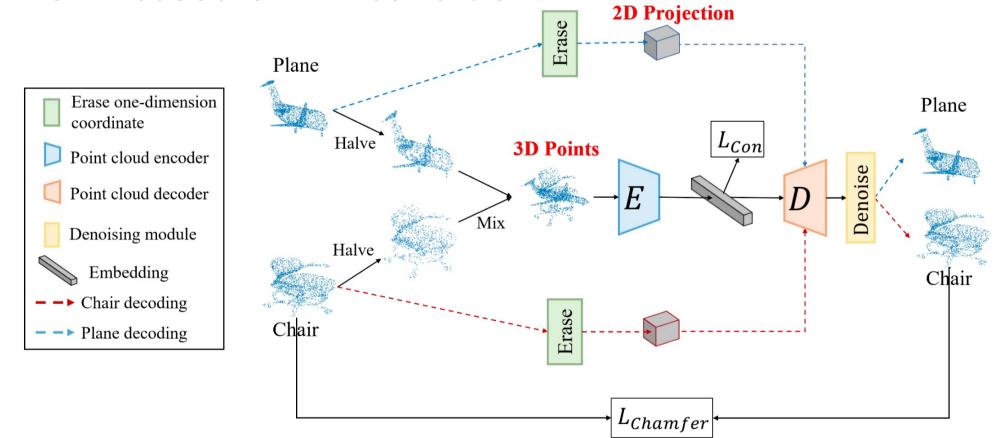
Data Mixing

Our data mixing process is simple, which randomly selects 50% points from A and 50% points from B.

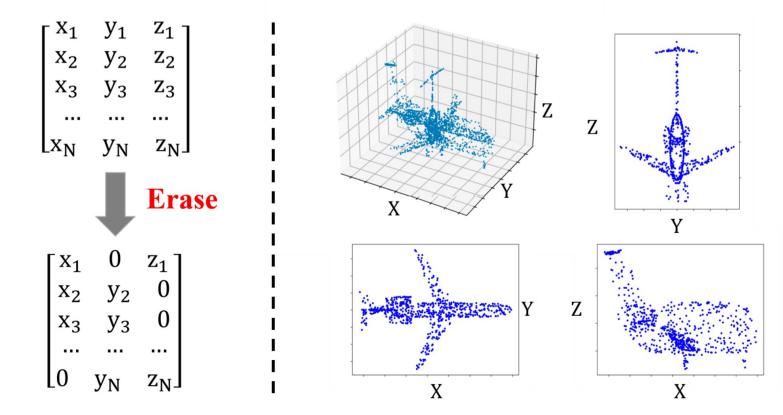


Disentangle Learning

The Encoder is to learn the salient pattern in A and B. During decoding, the Decoder is asked to reconstruct A or B based on 2D condition.



■ 2D Projection as Condition



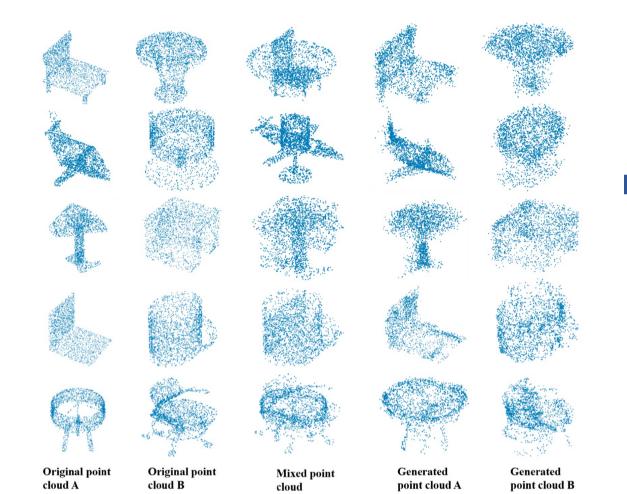
Experiment

Downstream tasks (Classification & Segmentation)

		ModelNet-40 Classification		ShapeNet-Part	
Methods	Publication			Segmentation	
		OA (%)	mA (%)	mIoU (%)	
3DShapeNets [11]	CVPR'15	84.7	77.3	-	
VoxNet [31]	IROS'15	85.9	83.0	-	
PointNet [35]	CVPR'17	89.2	86.0	83.7	
PointNet++ [36]	NeurIPS'17	91.9	-	85.1	
SpecGCN [73]	ECCV'18	91.5	-	-	
PCNN by Ext [74]	SIGGRAPH'18	92.2	-	85.1	
DGCNN [39]	TOG'19	92.9	90.2	85.1	
Point Trans. [43]	ICCV'21	93.7	90.6	86.6	
PAConv [41]	CVPR'21	93.9	-	86.1	
CurveNet [75]	ICCV'21	94.2	-	86.8	
Ours (from scratch)	-	92.74	89.88	85.27	
Ours (pre-training)	-	93.39	90.26	85.50	

OA: Overall Accuracy; mA: Mean Class Accuracy; mIoU: mean IoU

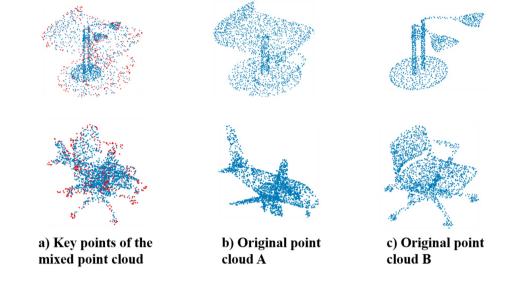
Reconstruction results



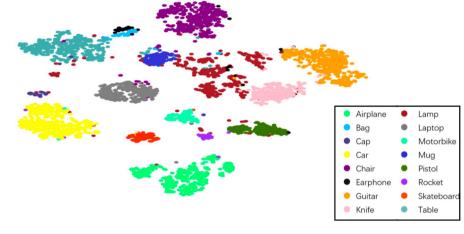
Limited labeled data

,	Labeled Data Ratio (%)	Pre-trained	Average Accuracy (%)	mIoII (%)
		11c-trafficu		
	10		74.02	81.59
	10	✓	77.04	82.23
	25		80.39	83.76
	25	✓	81.11	84.49
	50		81.46	84.71
	50	✓	83.31	85.04

■ Visualization of the key points of the mixed point cloud



Good Scalability (ModelNet-40 to ShapeNet-Part)



Fusion with other methods

		ModelNet-40		
Methods	Pre-trained	Classification		
		OA (%)	mA (%)	
Ours	-	92.74	89.88	
Ours	ShapeNet-Part	92.79	90.10	
Ours	ModelNet-40	93.39	90.26	
PointNet++ [36] *	-	92.07	88.89	
PointNet++ * + Ours	ShapeNet-Part	92.19	89.63	
PointNet++ * + Ours	ModelNet-40	92.57	89.96	
OGNet* [76]	-	93.23	89.82	
OGNet* + Ours	ShapeNet-Part	93.35	90.51	
OGNet* + Ours	ModelNet-40	93.31	90.71	
PAConv* (PN) [41]	-	92.50	-	
$PAConv^* (PN) + Ours$	ShapeNet-Part	92.70	-	
$PAConv^* (PN) + Ours$	ModelNet-40	92.79	-	
PT* [43]	-	91.47	89.32	
PT* + Ours	ShapeNet-Part	92.03	89.50	
PT* + Ours	ModelNet-40	92.07	89.58	
PCT* [42]	-	92.71	89.36	
PCT* + Ours	ShapeNet-Part	93.07	90.27	
PCT* + Ours	ModelNet-40	93.15	90.56	

PT donates Point Transformer. PCT donates Point Cloud Transformer. PAConv (PN) donates using PointNet as the backbone (without voting). OA Overall Accuracy; mA: Mean Class Accuracy; mIoU: mean IoU; *: We re-implement the model, which achieves a slightly different performance.

Conclusion

In this paper, we propose a new self-supervised learning method, called Mixing and Disentangling (MD), for point cloud pre-training. Different from existing works, we propose to mix the original point clouds in the training set to form "new" data and then demand the model to "separate" the mixed point cloud. In this way, the model is asked to mine the geometric knowledge, e.g., the shape-related key points for reconstruction. (Chinese blog is here) (Code is here)



