

src/P3main.java

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1 import import import import import import import import public class P3main {
2     public static void
3     main(String[] args) {
4         if (args.length < 4) {
5             System.out.println("usage: java P3main <DFS|BFS|AStar|BestF|SMAStar|...>
6             <N> <ds:as> <dg:ag> [<param>]");
7             // Print initial information
8             System.out.println("World: Oedipus " + args[1] + "
9             Departure airport -- Start: " + args[2] + " Destination airport -- Goal: " + args[3] + "
10            Search algorithm: " + args[4]);
11            // Parse start and goal from args
12            int startNode = Integer.parseInt(args[2]);
13            int goalNode = Integer.parseInt(args[3]);
14            int memorySize = Integer.parseInt(args[5]);
15            // Run the search
16            runSearch(args[1], Integer.parseInt(args[2]), Integer.parseInt(args[3]), Integer.parseInt(args[5]),
17            args[4]);
18        }
19        private static void runSearch(String algo, int startNode, int goalNode, int memorySize, String algo) {
20            switch (algo) {
21                case "DFS":
22                    PartA_DFS.bfs(startNode, goalNode, memorySize);
23                    break;
24                case "BestF":
25                    PartB_BestF.BestF(startNode, goalNode, memorySize);
26                    break;
27                case "AStar":
28                    PartB_AStar.AStar(startNode, goalNode, memorySize);
29                    break;
30                case "SMAStar":
31                    PartB_SMAStar.SMAStar(startNode, goalNode, memorySize);
32                    break;
33                case "IDS":
34                    PartC_IDS.runSearch(startNode, goalNode, memorySize);
35                    break;
36                default:
37                    System.out.println("fail");
38            }
39        }
40    }
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51  TM '
52  TMTMPartB_SMAStar.smaStar(startNode, goalNode, size, memorySize);
53  TMTM;
54  TM '
55  TMTMPartC_IDS.iterativeDeepeningSearch(startNode, goalNode, size);
56  TMTM;
57  TM ""
58  TMTMSystem.out.println();
59  TMTM;
60  TM}
61  —D
62  }

```