

src/Algorithms/PartA_DFS.java

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1 packageimportimportimportimportimportimportimportimportimportimportimportimport/**
2  * This class implements the Depth-First Search (DFS) algorithm for graph
3  * traversal.
4  */publicclassPartA_DFS/**
5      * Executes the Depth-First Search (DFS) from a start node to a goal
node within
6      * a given planet size.
7      *
8      * @param@param@param@returnpublicstaticdfs(Node start, Node goal, int
newStacknewHashMapnewHashSetnullwhileNodecurrent=ifcontinueifreturnforinti=10
Nodenext=ifreturnnull/**
9      * Prints the current state of the frontier (nodes to be visited).
10     *
11     * @paramprivatestaticvoidprintFrontier(Stack<Node> frontier)ifString
result="forinti=10Nodenode=","["01"]" Algorithms;
12
13     java.util.Collections;
14     java.util.Comparator;
15     java.util.HashMap;
16     java.util.Map;
17     java.util.Set;
18     java.util.HashSet;
19     java.util.List;
20     java.util.Stack;
21
22     General.Node;
23     General.Utility;
24
25
26     {
27
28         start          The starting node of the search.
29         * goal          The target node to find.
30         * planetSize The size of the planet, which influences the bounds of
the
31         *                search area.
32         * A list of nodes representing the path from the start to the goal if
33         * found, otherwise null.
34     */</span>
35     List<Node> planetSize)</span> {
36         Stack<Node> frontier = <>();
37         Map<Node, Node> parentMap = <>();
38         Set<Node> visited = <>();
39
40         frontier.push(start);
41         parentMap.put(start, );
42
43         (!frontier.isEmpty()) {
44             printFrontier(frontier);
45             frontier.pop();
46
47             (visited.contains(current)) {
48                 ;
49             }
50
51             visited.add(current);
52             (current.equals(goal)) {
53                 List<Node> path = Utility.constructPath(current,
```

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parentMap);
54         Utility.printPath(path, visited.size());
55         path;
56     }
57
58     List<Node> successors = current.getSuccessors(planetSize,
goal);
59     Collections.sort(successors,
Comparator.comparingInt(Node::getD).thenComparingInt(Node::getAngle));
60
61     (    successors.size() - ; i >= ; i--) {
62         successors.get(i);
63         (!visited.contains(next) && !frontier.contains(next)) {
64             frontier.push(next);
65             parentMap.put(next, current);
66         }
67     }
68 }
69 Utility.algorithmFails(visited.size());
70 ;
71 }
72
73 frontier The stack containing the nodes currently in the frontier.
74 */</span>
75 {
76     (!frontier.isEmpty()) {
77         ;
78         (    frontier.size() - ; i >= ; i--) {
79             frontier.get(i);
80             result += node.toString() + ;
81         }
82     }
83     System.out.println( + result.substring(, result.length() - )
+ );
84 }
85 }
86 }

```