16. Clustered and Panel Data

Spring 2021

Matthew Blackwell

Gov 2002 (Harvard)

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- Panel and clustered data are two common non-iid data.
- Panel data also holds hope for removing unmeasured heterogeneity.

1/ Panel Data

Is Democracy Good for the Poor?

Michael Ross University of California, Los Angeles

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 - $\boldsymbol{\cdot}$ posses some cultural trait correlated with better health outcomes
- If have data on countries over time, can we make any progress in spite of these problems?

Ross data

```
ross <- foreign::read.dta("../assets/ross-democracy.dta")
head(ross[,c("cty_name", "year", "democracy", "infmort_unicef")])</pre>
```

##		cty_name	year	democracy	$\verb"infmort_unicef"$
##	1	Afghanistan	1965	0	230
##	2	Afghanistan	1966	0	NA
##	3	Afghanistan	1967	0	NA
##	4	Afghanistan	1968	Θ	NA
##	5	Afghanistan	1969	Θ	NA
##	6	Afghanistan	1970	Θ	215

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- Panel data: large n, relatively short T
- Time series, cross-sectional (TSCS) data: smaller n, large T (a political science term, mostly)

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- Assume that if we could measure c_i , we would have the correct CEF:

$$\mathbb{E}[u_{it} \mid \mathbf{X}_{it}, c_i] = 0 \quad \Longrightarrow \quad \mathbb{E}[Y_{it} \mid \mathbf{X}_{it}, c_i] = \mathbf{X}'_{it}\boldsymbol{\beta} + c_i$$

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- Both problems arise out of ignoring the **unmeasured heterogeneity** inherent in c_i

Pooled OLS with Ross data

```
##
## Coefficients:
##
            Estimate Std. Error t value Pr(>|t|)
## (Intercept) 9.7640 0.3449 28.3 <2e-16 ***
## democracy -0.9552 0.0698 -13.7 <2e-16 ***
## ---
## Signif. codes:
## 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.795 on 646 degrees of freedom
  (5773 observations deleted due to missingness)
##
## Multiple R-squared: 0.504, Adjusted R-squared: 0.503
## F-statistic: 329 on 2 and 646 DF, p-value: <2e-16
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- Pooled OLS will be inconsistent for the CEF parameters, $oldsymbol{eta}$.

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- Two approaches that leverage repeated observations:
 - **Differencing** look at changes over time.
 - Fixed effects look at relationships within units.

2/ First Differencing Methods

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• Look at the change in Y over time:

$$\begin{split} \Delta Y_i &= Y_{i2} - Y_{i1} \\ &= (\mathbf{X}_{i2}' \boldsymbol{\beta} + c_i + u_{i2}) - (\mathbf{X}_{i1}' \boldsymbol{\beta} + c_i + u_{i1}) \end{split}$$

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- Under these assumptions, pooled OLS on the differences is consistent.

3/ Fixed Effects Methods

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- This regression is sometimes called the "between regression"

Within transformation

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- · Center every covariate and the outcome at its within-unit mean.
- c_i drops out because its within-unit mean is itself (time-constant).
- If we write $\ddot{Y}_{it} = Y_{it} \overline{Y}_{i}$, then we can write this more compactly as:

$$\ddot{Y}_{it} = \ddot{\mathbf{X}}'_{it} \boldsymbol{\beta} + \ddot{u}_{it}$$

Fixed effects with Ross data

```
library(lfe)
fe.mod <- lfe::felm(log(kidmort_unicef) ~ democracy + log(GDPcur) | id, data = ross)
summary(fe.mod)</pre>
```

```
##
## Call.
     lfe::felm(formula = log(kidmort unicef) ~ democracy + log(GDPcur) | id, data = ross)
##
## Residuals:
      Min
              1Q Median 3Q
## -0.7049 -0.1166 0.0063 0.1222 0.7575
##
## Coefficients:
##
              Estimate Std. Error t value Pr(>|t|)
## democracy -0.1432 0.0335 -4.28 0.000023 ***
## log(GDPcur) -0.3752 0.0113 -33.12 < 2e-16 ***
## ---
## Signif, codes:
## 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.219 on 481 degrees of freedom
## (5773 observations deleted due to missingness)
## Multiple R-squared(full model): 0.972 Adjusted R-squared: 0.962
## Multiple R-squared(proj model): 0.718 Adjusted R-squared: 0.621
## F-statistic(full model): 100 on 167 and 481 DF. p-value: <2e-16
## F-statistic(proi model): 613 on 2 and 481 DF. p-value: <2e-16
```

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- Rules out lagged dependent variables, since $Y_{i,t-1}$ is a function of $u_{i,t-1}$.

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 - · Any time-constant variable gets "absorbed" by the fixed effect.
- Can include interactions between time-constant and time-varying variables, but lower order term of the time-constant variables get absorbed by fixed effects too.

Time-constant variables

• Pooled model with a time-constant variable, proportion Islamic:

```
library(lmtest)
p.mod <- felm(log(kidmort_unicef) ~ democracy + log(GDPcur) + islam, data = ross
coeftest(p.mod)</pre>
```

Time-constant variables

• FE model, where the islam variable drops out, along with the intercept:

```
fe.mod2 <- felm(log(kidmort_unicef) ~ democracy + log(GDPcur) + islam | id, data = coeftest(fe.mod2)</pre>
```

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 - Con: computationally slow with large *n*.
 - Usually better to use dedicated software like lfe package in R.

Example with Ross data

##

democracy

log(GDPcur)

-0.143

-0.375

```
library(lmtest)
lsdv.mod <- lm(log(kidmort_unicef) ~ democracy + log(GDPcur) + as.factor(id),</pre>
              data = ross)
coeftest(lsdv.mod)[1:6,]
                  Estimate Std. Error t value Pr(>|t|)
##
  (Intercept)
                    13.764
                               0.2660 51.75 1.01e-198
  democracy
                   -0.143
                               0.0335 -4.28 2.30e-05
## log(GDPcur)
                               0.0113 -33.12 3.49e-126
                -0.375
## as.factor(id)AGO 0.300
                               0.1677
                                        1.79 7.45e-02
## as.factor(id)ALB
                   -1.931
                               0.1901 -10.16 4.39e-22
## as.factor(id)ARE
                   -1.876
                               0.1702 -11.02 2.39e-25
coeftest(fe.mod)[1:2,]
```

0.0335 -4.28 2.30e-05

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Estimate Std. Error t value Pr(>|t|)

4/ Clustering

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 - · SEs are going to be wrong.
- Called clustering or clustered dependence

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- Outcome varies at the unit-level, Y_{ig} and the main independent variable varies at the cluster level, X_{g} .

$$Y_{ig} = \beta_0 + X_g \beta_1 + v_{ig}$$
$$= \beta_0 + X_g \beta_1 + c_g + \mathbf{u}_{ig}$$

• $\emph{u}_{\emph{ig}}$ unit error component with $\mathbb{V}[\emph{u}_{\emph{ig}}|\emph{X}_{\emph{g}}] = \sigma_\emph{u}^2$

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 - $\rightsquigarrow V[v_{ig}|X_g] = \sigma_c^2 + \sigma_u^2$

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- $\mathit{c_g}$ cluster error component with $\mathbb{V}[\mathit{c_g}|\mathit{X_g}] = \sigma_\mathit{c}^2$
- c_{α} and $u_{i\alpha}$ are assumed to be independent of each other.

•
$$\rightsquigarrow \mathbb{V}[v_{ig}|X_g] = \sigma_c^2 + \sigma_u^2$$

• What if we ignore this structure and just use v_{ig} as the error?

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• Correlation between units in the same group is called the **intra-class** correlation coefficient, or ρ_c :

$$Cor[v_{ig}, v_{sg}] = \frac{\sigma_c^2}{\sigma_c^2 + \sigma_u^2} = \rho_c$$

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• Zero covariance of two units *i* and *s* in different clusters *g* and *k*:

$$\mathsf{Cov}[v_{ig},v_{sk}] = 0$$

•
$$\mathbf{v}' = \begin{bmatrix} v_{1,1} & v_{2,1} & v_{3,1} & v_{4,2} & v_{5,2} & v_{6,2} \end{bmatrix}$$

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· Variance matrix under clustering:

$$\mathbb{V}[\mathbf{v}|\mathbf{X}] = \left[\begin{array}{cccccc} \sigma_c^2 + \sigma_u^2 & \sigma_c^2 & \sigma_c^2 & 0 & 0 & 0 & 0 \\ \sigma_c^2 & \sigma_c^2 + \sigma_u^2 & \sigma_c^2 & 0 & 0 & 0 & 0 \\ \sigma_c^2 & \sigma_c^2 & \sigma_c^2 + \sigma_u^2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \sigma_c^2 + \sigma_u^2 & \sigma_c^2 & \sigma_c^2 \\ 0 & 0 & 0 & \sigma_c^2 & \sigma_c^2 + \sigma_u^2 & \sigma_c^2 \\ 0 & 0 & 0 & \sigma_c^2 & \sigma_c^2 + \sigma_u^2 & \sigma_c^2 \\ \end{array} \right]$$

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· Variance matrix under i.i.d.:

$$\mathbb{V}[\mathbf{v}|\mathbf{X}] = \left[\begin{array}{cccccc} \sigma_u^2 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & \sigma_u^2 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & \sigma_u^2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \sigma_u^2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & \sigma_u^2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & \sigma_u^2 & 0 \end{array} \right]$$

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• $\mathbb{V}^0[\hat{eta_1}] = extbf{conventional}$ OLS variance assuming i.i.d./homoskedasticity.

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- When clusters are balanced, $n^* = n_g$, comparison of clustered to conventional:

$$\mathbb{V}[\hat{\beta}_1] \approx \mathbb{V}^0[\hat{\beta}_1] \left(1 + (\mathit{n}^* - 1)\rho_c\right)$$

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• True variance will be higher than conventional when within-cluster correlation is positive, $\rho_c > 0$.

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 - $\mathbb{E}[v_{ig} \mid \mathbf{X}_{ig}] = 0$ so we have the correct CEF.
 - $\mathbb{E}[v_{ig}v_{jg'}\mid \mathbf{X}_{ig},\mathbf{X}_{jg'}]=0$ unless g=g'.

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 - Correlated errors allowed within groups, uncorrelated across. Allows heteroskedasticity.

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- · We can write the OLS estimator as:

$$\hat{\boldsymbol{\beta}} = \left(\sum_{g=1}^{m} \mathbb{X}_{g}^{\prime} \mathbb{X}_{g}\right) \left(\sum_{g=1}^{m} \mathbb{X}_{g}^{\prime} \mathbf{Y}_{g}\right)$$

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- With small-sample adjustment (reported by most software):

$$\hat{\mathbb{V}}_{CL1}[\hat{\boldsymbol{\beta}}] = \frac{m}{m-1} \frac{n-1}{n-k} \left(\mathbb{X}' \mathbb{X} \right)^{-1} \left(\sum_{g=1}^{m} \mathbb{X}'_g \hat{\mathbf{v}}_g \hat{\mathbf{v}}'_g \mathbb{X}_g \right) \left(\mathbb{X}' \mathbb{X} \right)^{-1}$$

Example: Gerber, Green, Larimer

Dear	Regist	ered	Voter
Deal	regio	CICU	A O (C)

WHAT IF YOUR NEIGHBORS KNEW WHETHER YOU VOTED?

Why do so many people fail to vote? We've been talking about the problem for years, but it only seems to get worse. This year, we're taking a new approach. We're sending this mailing to you and your neighbors to publicize who does and does not vote.

The chart shows the names of some of your neighbors, showing which have voted in the past. After the August 8 election, we intend to mail an updated chart. You and your neighbors will all know who voted and who did not.

DO YOUR CIVIC DUTY - VOTE!

MAPLE DR	Aug 04	Nov 04	Aug 06
9995 JOSEPH JAMES SMITH	Voted	Voted	
9995 JENNIFER KAY SMITH		Voted	
9997 RICHARD B JACKSON		Voted	
9999 KATHY MARIE JACKSON		Voted	

Social pressure model

```
load("../assets/gerber_green_larimer.RData")
library(lmtest)
social$voted <- 1 * (social$voted == "Yes")
social$treatment <- factor(
    social$treatment,
    levels = c("Control", "Hawthorne", "Civic Duty", "Neighbors", "Self")
)
mod1 <- lm(voted ~ treatment, data = social)
coeftest(mod1)</pre>
```

```
##
  t test of coefficients:
##
                    Estimate Std. Error t value
##
  (Intercept)
                 0.29664 0.00106 279.53
## treatmentHawthorne 0.02574 0.00260 9.90
## treatmentCivic Duty 0.01790 0.00260 6.88
## treatmentNeighbors 0.08131 0.00260 31.26
  treatmentSelf
              0.04851 0.00260
                                       18.66
                  Pr(>|t|)
##
## (Intercept) < 2e-16 ***
## treatmentHawthorne < 2e-16 ***
## treatmentCivic Duty 5.8e-12 ***
## treatmentNeighbors < 2e-16 ***
## treatmentSelf < 2e-16 ***
## ---
```

Social pressure model, CRSEs

```
library(sandwich)
coeftest(mod1, vcov = sandwich::vcovCL(mod1, cluster = social$hh_id))
```

```
##
## t test of coefficients:
##
##
                     Estimate Std. Error t value
## (Intercept)
               0.29664 0.00131 226.52
  treatmentHawthorne 0.02574 0.00326 7.90
## treatmentCivic Duty 0.01790 0.00324 5.53
## treatmentNeighbors 0.08131 0.00337 24.13
                                        14.70
## treatmentSelf 0.04851 0.00330
                    Pr(>|t|)
##
## (Intercept) < 2e-16 ***
## treatmentHawthorne 2.8e-15 ***
## treatmentCivic Duty 3.2e-08 ***
## treatmentNeighbors < 2e-16 ***
## treatmentSelf < 2e-16 ***
##
## Signif. codes:
  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

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- Consistency of the CRSE are in the number of groups, not the number of individuals
 - CRSEs can be incorrect with a small (< 50 maybe) number of clusters