

¹³¹ Chapter 1

¹³² Introduction

¹³³ 1.1 Motivation

¹³⁴ Improving projections of the rate of global sea level rise in response to a warming
¹³⁵ world is vital for effectively mitigating future environment and socio-economic
¹³⁶ impacts (Durand et al., 2022). A large portion of the uncertainties in sea level
¹³⁷ rise projections is related to the contribution from the Antarctic Ice Sheet. The
¹³⁸ Antarctic Ice Sheet contains a total volume of ice equivalent to 57.2 m of sea level
¹³⁹ rise (Fretwell et al., 2013). Satellite altimetry observations show that Antarctica
¹⁴⁰ contributed \sim 5 mm to mean sea level over the last \sim 20 years (2003-2019) (Smith
¹⁴¹ et al., 2020), and of the various components of sea level rise, the contribution from
¹⁴² Antarctica is accelerating the fastest (Nerem et al., 2018). By the end of the century,
¹⁴³ Antarctica is projected to contribute between 0.03 and 0.28 m to mean sea
¹⁴⁴ level (RCP 8.5, Intergovernmental Panel on Climate Change (IPCC), 2022). Optimal
¹⁴⁵ strategies for preparing coastal communities to best mitigate the impacts of
¹⁴⁶ rising sea level depends on where in this range of uncertainties the true sea level
¹⁴⁷ rise will be. Some of the uncertainty in how the Antarctic Ice Sheet will respond
¹⁴⁸ to a warming world stems from a lack of understanding of the complex interactions
¹⁴⁹ between the ice and the underlying earth.

¹⁵⁰ 1.2 Solid-earth influences on ice dynamics

¹⁵¹ The solid-earth influences ice sheets through several mechanisms, which we group as
¹⁵² those resulting from bedrock topography, geologic structures, and bedrock physical
¹⁵³ properties.

¹⁵⁴ 1.2.1 Bedrock topography

¹⁵⁵ Onshore bed topography and offshore bathymetry exert fundamental controls on
¹⁵⁶ how the Antarctic Ice Sheet behaves. Offshore, where the ice is floating, the influence
¹⁵⁷ of the bathymetry is limited to the guiding of ocean circulations. Bathymetric
¹⁵⁸ ridges have been shown to block, or re-direct, the inflow of melt-inducing waters to
¹⁵⁹ the ocean cavity beneath floating ice shelves (De Rydt et al., 2014; Zhao et al., 2019;
¹⁶⁰ Goldberg et al., 2020). Approximately 75% of Antarctica's coastline is composed of
¹⁶¹ these floating ice shelves, and 83% of total ice discharged into the Southern Ocean
¹⁶² from Antarctica is through these shelves, highlighting their significance to Antarc-

tica's ice budget (Rignot et al., 2013). Of the 83% of total ice loss from Antarctica through ice shelves, basal melt is responsible for 55% (Rignot et al., 2013). Some of this melt occurs from surface waters, where bathymetry has little effect, but for many of the largest ice shelves, the majority of basal melt occurs along the deep grounding zone (Adusumilli et al., 2020). Here, the melt-inducing water bodies are dense and flow into the ice shelf cavities along the seafloor (Holland, 2008; Tinto et al., 2015). Therefore, bathymetric features act to guide or block these circulations from reaching the grounding zone where they can melt the ice base. In addition to steering ocean currents, bed topography, in regions of grounded ice, acts to steer the ice flow.

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As revealed by extensive seismic and swath bathymetry data in Antarctica's Ross Sea (Figure 1.1a), the dynamics of an advancing or retreating ice sheet are predominantly controlled by the physiography of the bed (Halberstadt et al., 2016; Anderson et al., 2019). If large troughs and banks exist, advancing ice is initially confined by these features, while the banks remain ice-free (Anderson et al., 2014). Eventually, after the ice has covered the entire region, the retreat is initially confined to these narrow troughs, while the banks retain grounded ice for much longer (Halberstadt et al., 2016; Anderson et al., 2019). As the ice thins or retreats into regions of deeper bed topography, these banks remain grounded, while the rest of the ice sheet decouples from the bed, begins floating and forms an ice shelf (Shipp et al., 1999). This remaining grounded ice on bathymetric highs forms pinning points.

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Pinning points are regions of locally grounded ice within a floating ice shelf (Matsuoka et al., 2015). The friction between the bed and ice base at these points impart a critical resisting force to the discharge of upstream ice; an effect known as buttressing (Thomas, 1979; Dupont & Alley, 2005). Since the base of ice shelves is flat relative to the underlying bathymetry, the morphology of the seafloor is the dominant controls the location and geometry of these pinning points. The bedrock topography has been thought to be relatively constant over a millennial timescale, meaning that pinning points geometries vary mostly by temporal changes in the ice thickness. However, recent studies of glacial isostatic adjustment, the vertical rebound of the Earth following deglaciation, throughout West Antarctica have demonstrated high spatial variability and short (multi-centennial-to-millennial) timescales for these vertical land movements (Coulon et al., 2021; Barletta et al., 2018; Kachuck et al., 2020). As the bedrock beneath portions of West Antarctica continues to rebound, the number and extent of these pinning points will likely increase, possibly providing a stabilizing effect to the ice sheet.

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All of these above controls on ice dynamics imparted by the physiography of the bed rely on accurate knowledge of bed topography and bathymetry. Due to the inherently challenging nature of Antarctic fieldwork, and the logistical challenge of measuring bed elevations beneath thick ice, 50% of the Antarctic Ice Sheet is more than 5 km from the nearest measurement of bed elevation (Figure 1.1a, Morlighem et al., 2020). This value increases greatly if the floating ice shelves are included. For grounded ice, the dominant techniques for direct measurements of bed elevation data are airborne radio-echo sounding, over-snow radar, and seismic surveying (Figure 1.1b, Fretwell et al., 2013). In the open ocean, bathymetry data is typically collected with ship-borne multibeam echo sounding, seismic surveying (Figure 1.1b), or from satellite-altimetry. Acquiring bathymetry data beneath floating ice shelves presents

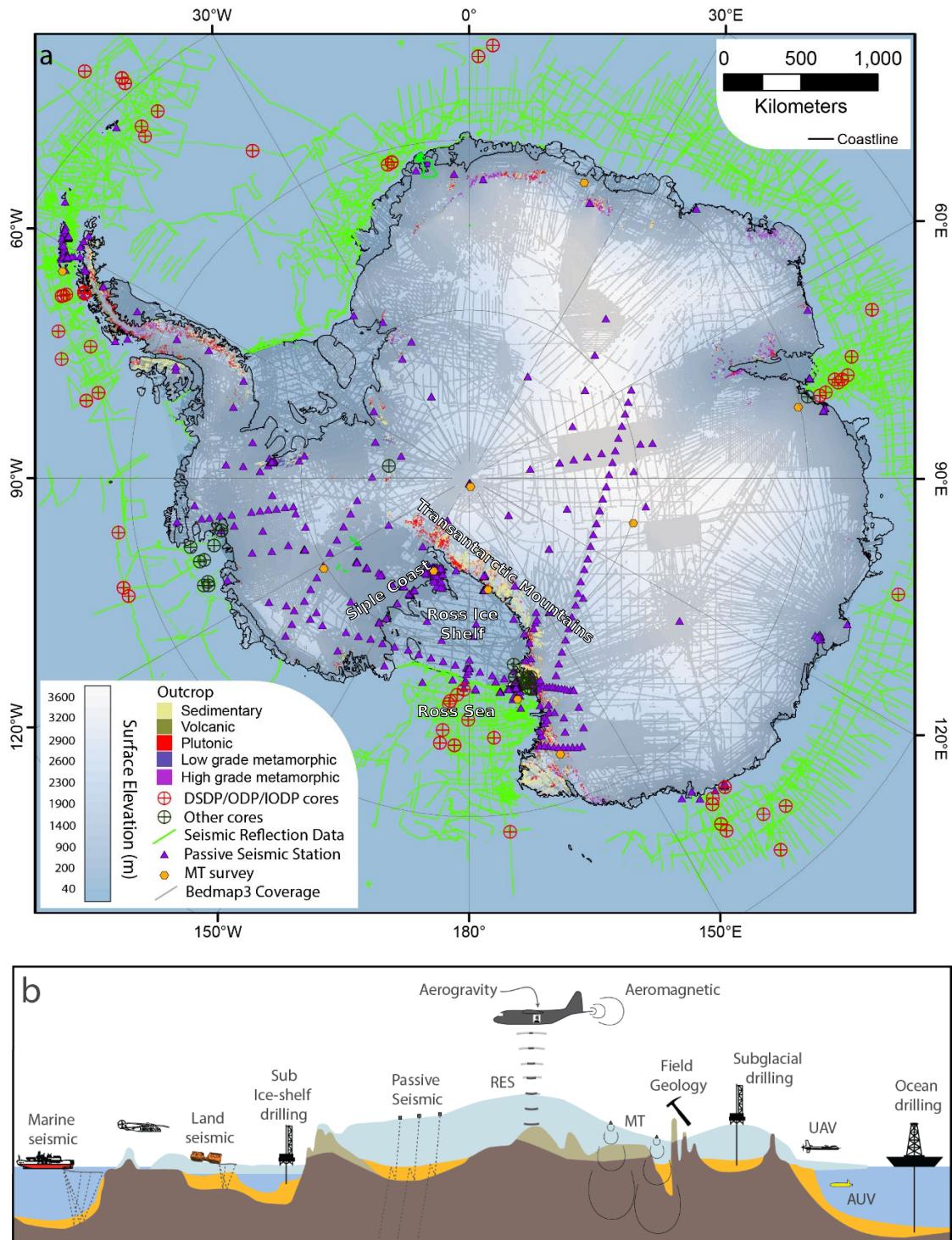


Figure 1.1: Summary of existing geologic and geophysical data for Antarctica. **a)** Map of data coverage in Antarctica indicating outcropping regions, drill core sites, seismic and magnetotelluric surveys, and bed elevation data points of Bedmap3, mostly from airborne radio-echo sounding (Frémand et al., 2022). **b)** Various methods of acquiring information sub-surface geology. Figure adapted from Aitken et al. (2023a).

212 a particular challenge. The efficient shipborne methods are unavailable since the ice
 213 shelves are persistent year-round, unlike the sea ice in the open ocean. Radio-echo
 214 sounding, either ground-based or airborne, cannot image through the water column.
 215 Direct observations through drilling are possible and exist, but typically require
 216 drilling through 100's to 1000's of meters of ice (Figure 1.1, Clough & Hansen, 1979;

217 Patterson et al., 2022). Autonomous underwater vehicles (Figure 1.1b) present
218 another option, but are expensive and have limited range (Dowdeswell et al., 2008;
219 Nicholls et al., 2006). The only feasible method of direct observations of sub-ice shelf
220 bathymetry is over-snow seismic surveying (Figure 1.1b). However, for the vast area
221 of many ice shelves, even sparse coverage (~ 50 km spacing) of seismic points across
222 the ice shelf takes several field seasons of data acquisition (Bentley, 1984).

223 1.2.2 Geologic structures

224 Additional solid-earth influences on the overriding ice include the delivery of geother-
225 mal heat and subglacial water to the ice base and the vertical deformation of the
226 bedrock in response to changing ice loads. Geothermal heat influences ice dynamics
227 through several mechanisms; 1) increasing the temperature of the ice which lowers
228 its viscosity, leading to enhanced flow via internal deformation (Llubes et al., 2006),
229 2) meltwater lubrication of the bed reduces friction, enhancing flow (Pollard et al.,
230 2005), and 3) increasing the ability of the bed to deform via increased pore-fluid
231 pressure, which increases ice flow (Tulaczyk et al., 2000). The latter two effects,
232 while enhanced by geothermal heat through the melting of ice, also occur with sim-
233 plly the presence of liquid water at the ice-bed interface. As briefly mentioned in
234 the above section, glacial isostatic adjustments of the bedrock following changes in
235 ice load can influence the ice by altering the geometry and locations of grounded ice.
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237 Each of these effects; geothermal heat flow, subglacial water availability, and
238 glacial isostatic adjustment, are in turn influenced by geologic structures within the
239 upper crust. A portion of subglacial water comes from either transport along the
240 ice-bed interface, or from the melting of the ice base. However, an often overlooked
241 component of the subglacial hydrologic system is groundwater stored in deep sedi-
242 mentary aquifers. For example, hydrologic modelling of the ice streams of the Siple
243 Coast (Figure 1.1a) estimated the components of the hydrologic budget to be 8%
244 from local basal melting, 47% from inflow from the ice sheet interior, and 45% from
245 groundwater reservoirs (Christoffersen et al., 2014). These modelling observations of
246 extensive groundwater have been recently verified beneath the Whillans Ice Stream
247 by a magnetotelluric survey. This survey imaged an extensive groundwater aquifer
248 within a sedimentary basin, containing at least an order of magnitude more water
249 than the shallow hydrologic system (Gustafson et al., 2022). The vertical flow of this
250 basinal groundwater is controlled by the pressure of the overriding ice sheet. As this
251 overburden pressure decreases with thinning ice, groundwater is discharged to the
252 ice base (Gooch et al., 2016; Li et al., 2022). This discharge is likely concentrated
253 along pre-existing weaknesses or impermeable surfaces, such as fault damage zones,
254 or the margins of crystalline basement (Jolie et al., 2021). During this ice-induced
255 hydraulic unloading, regional geothermal heat is advected along the fluid pathways,
256 leading to potentially highly elevated heat flow delivered to the ice base (Li et al.,
257 2022; Ravier & Buoncristiani, 2018). In addition to concentrating both subglacial
258 water and geothermal heat, these faults, or more generically, regions of the crust
259 which have experienced recent faulting, will respond differently to stresses induced
260 by glacial isostatic adjustment. To a first order, the isostatic response of the solid-
261 earth to changing ice load is controlled by the rheology of the mantle (Whitehouse
262 et al., 2019). However, on a more local scale, pre-existing faults are shown to ac-
263 commodate glacial isostatic rebound-induced stresses (Peltier et al., 2022; Steffen

264 et al., 2021).

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266 To be able to understand the above influence of the solid-earth on the ice, we
267 must have some fundamental knowledge of the geologic structures beneath the ice.
268 This includes knowing where sedimentary basins, and possible aquifers within, are
269 located, where faults likely intersect the ice base, and the geometry of the crystalline
270 basement. Each of these components is difficult to image directly. Drilling, seismic
271 surveys, or geologic analysis of rock outcrops all provide valuable information but
272 are not feasible to cover wide regions (Figure 1.1). Indirect methods are therefore
273 needed. These include techniques such as gravity, magnetic, or electromagnetic
274 methods. Each of these techniques records measurements of the spatial variation
275 of a potential field, such as the Earth’s gravity, magnetic, or electromagnetic fields.
276 These fields are all partially dependant on a physical Earth property, such as rock
277 density, magnetic susceptibility, or resistivity. From these relationships, sub-surface
278 geologic information can be learned.

279 1.2.3 Basal roughness

280 The last major influence on the ice from the solid-earth we present is the roughness
281 of the bed which the ice sheet flows over. This bed roughness is important on both
282 a micro and macro scale. At a micro-scale, roughness is determined by the material
283 which the bed is composed of. A bed of erosion-resistance crystalline basement, for
284 example, can greatly hinder the flow of ice. This material results in high friction
285 with the ice base, slowing the sliding of ice (Bell et al., 1998). Conversely, beds
286 composed of fine-grained tills allow fast ice flow. This fast flow is predominantly
287 due to deformation within the till as the ice flows (Alley et al., 1986). In between
288 the end members of crystalline basement and fine grain till are lithified sedimentary
289 rocks, for example. This type of bed may initially lead to high friction with the ice,
290 but due to their high erodability, sedimentary rock will quickly generate till (Anan-
291 dakrishnan et al., 1998). A macro-scale view of basal roughness is also important
292 for ice dynamics. As observed at the Siple Coast (Figure 1.1a) ice streams, there is
293 a strong inverse relation between bed roughness, from scales of 5 km to >40km, and
294 ice stream velocities (Siegert et al., 2004). The composition of the bed also plays
295 an important role in the total effective resistance imparted on ice flow from pinning
296 points (Still et al., 2019).

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298 To best quantify the effect of basal roughness on ice dynamics, information on
299 the material properties of the bed is needed. While sediment samples beneath the ice
300 yield valuable information, they may only represent the bed at the specific location
301 where they were sampled. The most fundamental information needed is the generic
302 rock type of the bed, namely, is the bed loose, unconsolidated sediment, lithified
303 sedimentary rock, or crystalline rock? Aitken et al. (2023a) provide a detailed
304 review of Antarctica’s sedimentary basins, and the methods employed to determine
305 both the presence of sediment and the sediment thickness. These methods, as well as
306 the methods described in the above sections, are shown in Figure 1.1, as reproduced
307 from Aitken et al. (2023a).

308 With the dominant solid-earth influences on ice dynamics laid out, we will now
309 introduce the study area of this thesis, Antarctica’s Ross Ice Shelf.

1.3 Ross Ice Shelf

The Ross Ice Shelf is Antarctica's largest ice shelf ($\sim 480,000 \text{ km}^2$), Figure 1.1). It is situated between the Transantarctic Mountains and Marie Byrd Land. It buttresses a catchment of ice that flows from both the East and West Antarctic Ice Sheets. This catchment contains 11.6 m of global sea level equivalent (Tinto et al., 2019; Fretwell et al., 2013; Rignot et al., 2011). Compared to many other ice shelves, the Ross Ice Shelf is currently relatively stable (Rignot et al., 2013; Moholdt et al., 2014). However, geologic evidence from throughout the Ross Sea and the Siple Coast shows that in the past $\sim 7,000$ years the shelf has experienced rapid destabilization, disintegration, and large-scale grounding line retreat (e.g., Venturelli et al., 2020; Naish et al., 2009). This major Holocene retreat is thought to have been primarily caused by ocean forcings (Lowry et al., 2019), as bathymetric troughs guided in the inflow of melt-inducing ocean circulations (Tinto et al., 2019). Once destabilized, the grounding line retreat from the outer continental shelf to the present-day location was controlled primarily by the physiography and geology of the bed (Halberstadt et al., 2016; Anderson et al., 2019). This shows the importance of the solid-earth's influence on the dynamics of the Ross Ice Shelf.

1.3.1 Past investigations

By examining solid-earth influence on ice dynamics, we identified some key data needed to understand these influences. This data included onshore bed topography, offshore bathymetry, the distribution of sediment, and upper crustal structures such as faults and the topography of the basement. Here, we summarize the history of data collection in the Ross Ice Shelf region specific to these geologic and physiographic features. Geological and geophysical exploration has occurred in the Ross Embayment for over a century. The earliest of these include the 1901-1904 *Discovery* expedition, the 1907-1909 *Nimrod* expedition, and the 1910-1913 *Terra Nova* expedition. These expeditions laid the groundwork of interest in the Ross Embayment from a scientific perspective. The first major survey of the Ross Ice Shelf was part of the 1957-1959 International Geophysics Year traverses. The three over-snow traverses all included a portion of the ice shelf and collected radar, gravity, and seismic data to determine ice thickness, surface elevation, and bed elevation (Crary, 1959). These surveys produced early evidence of the extensive below-sea-level bed, thin crust, and distinct geologic provinces throughout West Antarctica (Bentley et al., 1960). In the 1970s the Ross Ice Shelf Geophysical and Glaciological Survey (RIGGS, Bentley, 1984) consisted of a systematic grid of seismic surveys over the entire ice shelf with an average spacing between survey points of 55 km. After the RIGGS survey, there were a total of ~ 223 point-source seismic surveys across the ice shelf, all yielding sub-ice shelf bathymetry depths. Of these, eight reported sediment thicknesses beneath. Several faults were hypothesized, based on 2D gravity profiles conducted at many of the stations (Greschar et al., 1992). Since the 1970s, there have been many additional local surveys on the ice shelf, but these have been focused along the grounding zones (e.g., Patterson et al., 2022; Horgan et al., 2017; Muto et al., 2013a; Stern et al., 1994; ten Brink et al., 1993; Wannamaker et al., 2017). The next, and most recent major data-collection campaign on the Ross Ice Shelf was the ROSETTA-ice project.

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356 The Ross Ocean and ice Shelf Environment, and Tectonic setting Through Aero-
357 geophysical surveys and modelling project (ROSETTA-ice, Tinto et al., 2019), was
358 a 3-season (2015-2017) airborne geophysical survey of the Ross Ice Shelf. It flew
359 a regular grid of flight lines, with nominal N-S and E-W line spacings of 10 and
360 55 km, respectively. During each flight, various geophysical data was collected, in-
361 cluding ice-penetrating radar, gravity, magnetics and laser altimetry. So far, these
362 ROSETTA-ice data have been used to begin characterizing the geologic nature of
363 the crust (Tinto et al., 2019), to model the depths to the sea floor (Tinto et al.,
364 2019), and to quantify basal melt (Das et al., 2020).

365
366 Following 60 years of surveying and exploration of the Ross Ice Shelf, our fun-
367 damental understanding of the subglacial geology and physiography is still lacking.
368 For an area almost twice the size of New Zealand, we have approximately 8 locations
369 of reported sediment thickness, several hypothesized locations of faults, gaps of over
370 100 km without bathymetric depths, and limited understanding of our uncertainty
371 in the bathymetry where it has been modelled/interpolated. With this, we propose
372 several research questions which we aim to answer in this thesis.

373 1.4 Research questions

374 The aim of this thesis is to improve our geologic knowledge beneath the Ross Ice Shelf
375 in order to better understand the past, present, and future interactions between the
376 ice, ocean, and solid-earth. We aim to accomplish this by answering the following
377 questions:

- 378 1. What is the geologic structure of the upper crust beneath the Ross Ice Shelf?
379 If there are sediments, what is their thickness and distribution? Where are
380 the major faults likely located?
- 381 2. How can bathymetry beneath an ice shelf best be modelled? Are there further
382 improvements that can be made to the gravity-inversion process? What are
383 the predominant sources of uncertainty, and how can these be limited?
- 384 3. How deep is the bathymetry beneath the Ross Ice Shelf and where are we most
385 and least certain about it?
- 386 4. What are the geologic controls on the Ross Ice Shelf's stability?

387 1.5 Outline

388 This thesis is comprised of five chapters.

389
390 This chapter, Chapter 1, establishes the context behind the research, introduces
391 the study region, proposes a series of research questions, and contains an outline of
392 this thesis.

393
394 Chapter 2 is adapted from a journal paper submitted to Geophysical Research
395 Letters (Tankersley et al., 2022), reformatted to be included in this thesis. It presents
396 a model of the basement topography, and overlying sediment distribution, beneath

397 the Ross Ice Shelf. We used airborne magnetic data from the ROSETTA-ice project,
398 and a depth-to-magnetic source technique to model the sediment-basement contact.
399 This revealed large-scale, fault-controlled extensional basins throughout the sub-
400 Ross Ice Shelf crust. From this, we were able to draw a wide range of inferences on
401 the likely influence of this basement topography on the past, present, and future ice
402 sheet, as well as some tectonic implications. These results provided the first holistic
403 view of the upper crust beneath the Ross Ice Shelf.

404

405 Chapter 3 detailed our development of a method to model the depth to the sea
406 floor beneath a floating ice shelf. This method is a gravity inversion, where ob-
407 servations of changes in Earth's gravitational field are used to model bathymetry
408 beneath an ice shelf. We developed open-source Python code with the aim for other
409 researchers to utilize the inversion. We tested the inversion against a suite of syn-
410 thetic and semi-realistic data. This confirmed the feasibility of using gravity data
411 to attain bathymetry depths in an Antarctic setting. Additionally, these synthetic
412 tests revealed the relative importance of various aspects of a gravity inversion. These
413 included the importance of *a priori* constraints on the bathymetry, the large errors
414 which can be introduced during the removal of the regional component of gravity,
415 and several suggestions for optimal survey design to minimize error in the resulting
416 bathymetry model. Our use of Monte Carlo simulation provides both a spatially
417 variable estimation of uncertainty in the resulting bathymetry and an estimate of
418 the various sources of this uncertainty.

419

420 Chapter 4 used the inversion algorithm developed in Chapter 3 to create a new
421 bathymetry model and associated uncertainties beneath the Ross Ice Shelf. Our
422 model shows some major differences with past bathymetry models, highlighting ar-
423 eas of the ice shelf that should be carefully considered in future surveys. These
424 include a deeper bathymetric trench along the Transantarctic Mountains, a thicker
425 ocean cavity along a portion of the ice front which may allow the incursion of warm
426 ocean waters and a deeper ground line along the Siple Coast. Our uncertainty anal-
427 ysis shows the region of highest uncertainties is along the Transantarctic Mountain
428 Front. Within this chapter, we perform a comprehensive review of past bathymetry-
429 gravity inversions, for all Antarctic studies, and several Greenland studies. This
430 highlighted some key differences, which we believe we have improved on.

431

432 Chapter 5 presents a synthesis of the 3 research chapters, and provides a dis-
433 cussion of the research questions. Various future works are suggested and the main
434 conclusions of this thesis are presented. The research chapters in this thesis were
435 written with the intent to publish, including Chapter 2 which is already published.
436 Therefore, I have chosen to keep the style of writing consistent throughout the thesis,
437 with the use of plural possessive pronouns ("we") instead of singular ("I").