
Chapter 3



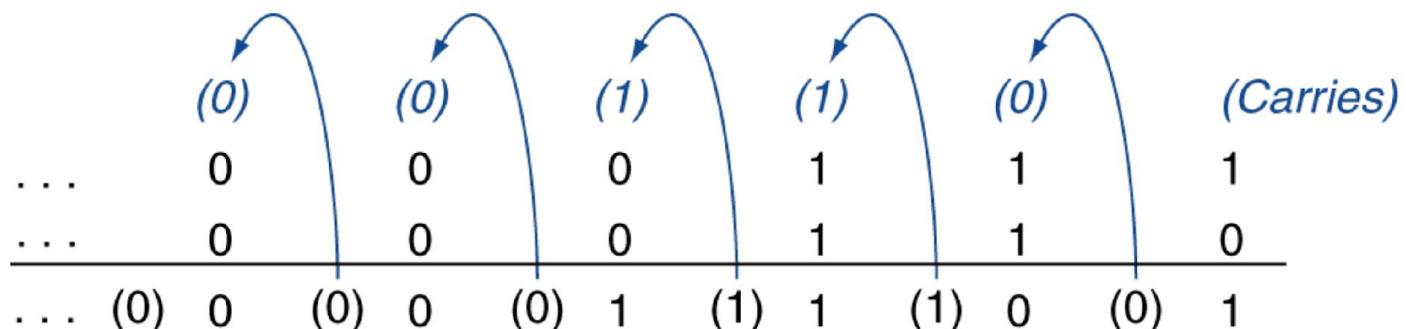
Arithmetic for Computers

Arithmetic for Computers

- Operations on integers
 - Addition and subtraction
 - Multiplication and division
 - Dealing with overflow
- Floating-point real numbers
 - Representation and operations

Integer Addition

■ Example: $7 + 6$



■ Overflow if result out of range

- Adding +ve and –ve operands, no overflow
- Adding two +ve operands
 - Overflow if result sign is 1
- Adding two –ve operands
 - Overflow if result sign is 0

Integer Subtraction

- Add negation of second operand
- Example: $7 - 6 = 7 + (-6)$

$$\begin{array}{r} +7: \quad 0000 \ 0000 \dots 0000 \ 0111 \\ -6: \quad 1111 \ 1111 \dots 1111 \ 1010 \\ \hline +1: \quad 0000 \ 0000 \dots 0000 \ 0001 \end{array}$$

- Overflow if result out of range
 - Subtracting two +ve or two –ve operands, no overflow
 - Subtracting +ve from –ve operand
 - Overflow if result sign is 0
 - Subtracting –ve from +ve operand
 - Overflow if result sign is 1

Dealing with Overflow

- Some languages (e.g., C) ignore overflow
 - Use MIPS addu, addui, subu instructions
- Other languages (e.g., Ada, Fortran) require raising an exception
 - Use MIPS add, addi, sub instructions
 - On overflow, invoke exception handler
 - Save PC in exception program counter (EPC) register
 - Jump to predefined handler address
 - mfc0 (move from coprocessor reg) instruction can retrieve EPC value, to return after corrective action

Arithmetic for Multimedia

- Graphics and media processing operates on vectors of 8-bit and 16-bit data
 - Use 64-bit adder, with partitioned carry chain
 - Operate on 8×8 -bit, 4×16 -bit, or 2×32 -bit vectors
 - SIMD (single-instruction, multiple-data)
- Saturating operations
 - On overflow, result is largest representable value
 - c.f. 2s-complement modulo arithmetic
 - E.g., clipping in audio, saturation in video

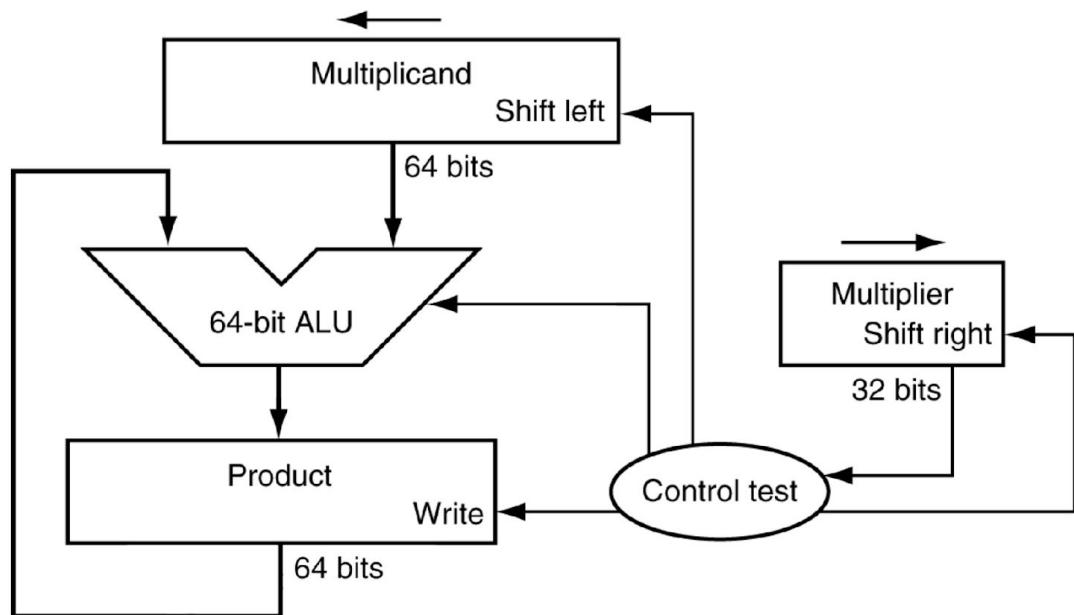
Multiplication

- Start with long-multiplication approach

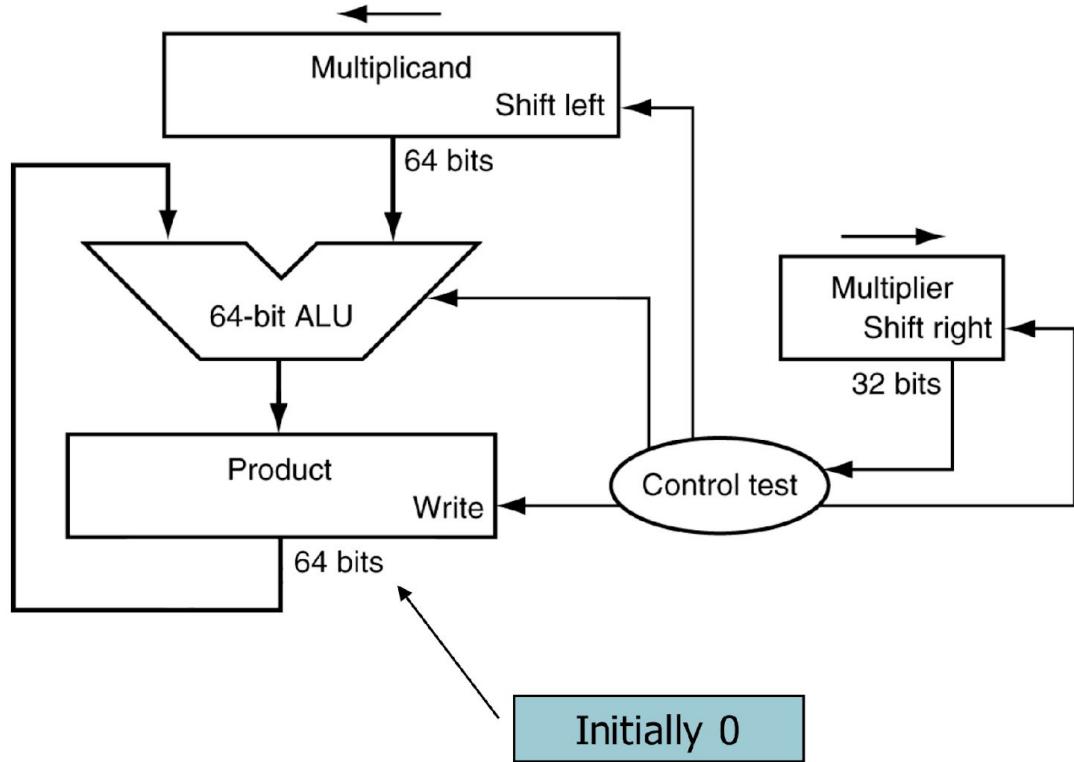
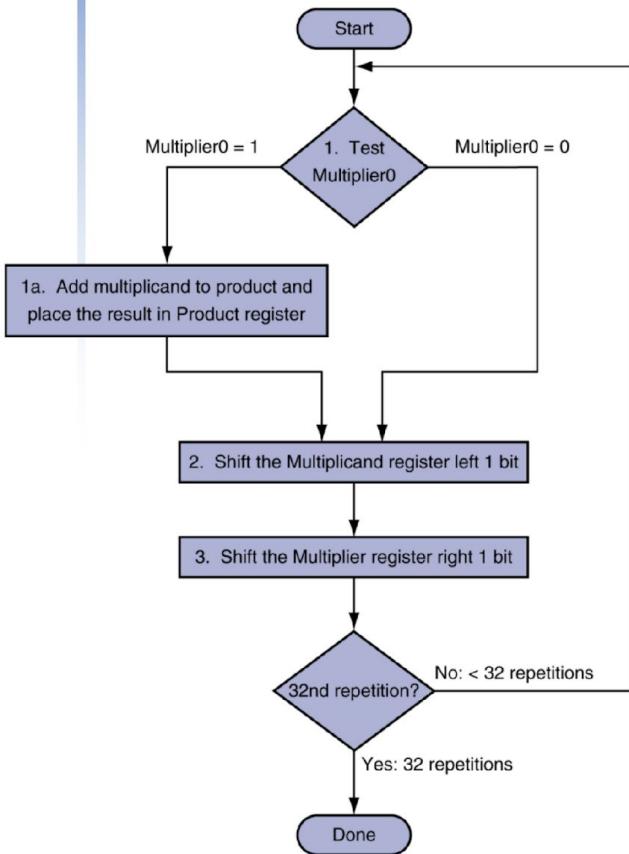
$$\begin{array}{r}
 \text{multiplicand} \\
 \times \quad 1000 \\
 \text{multiplier} \quad 1001 \\
 \hline
 1000 \\
 0000 \\
 0000 \\
 1000 \\
 \hline
 1001000
 \end{array}$$

product

Length of product is
the sum of operand
lengths

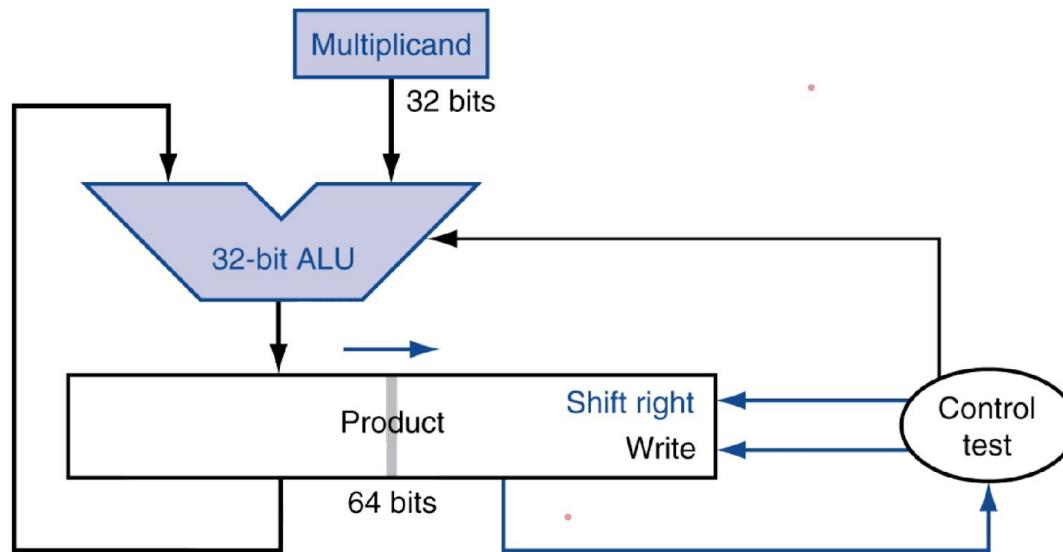


Multiplication Hardware



Optimized Multiplier

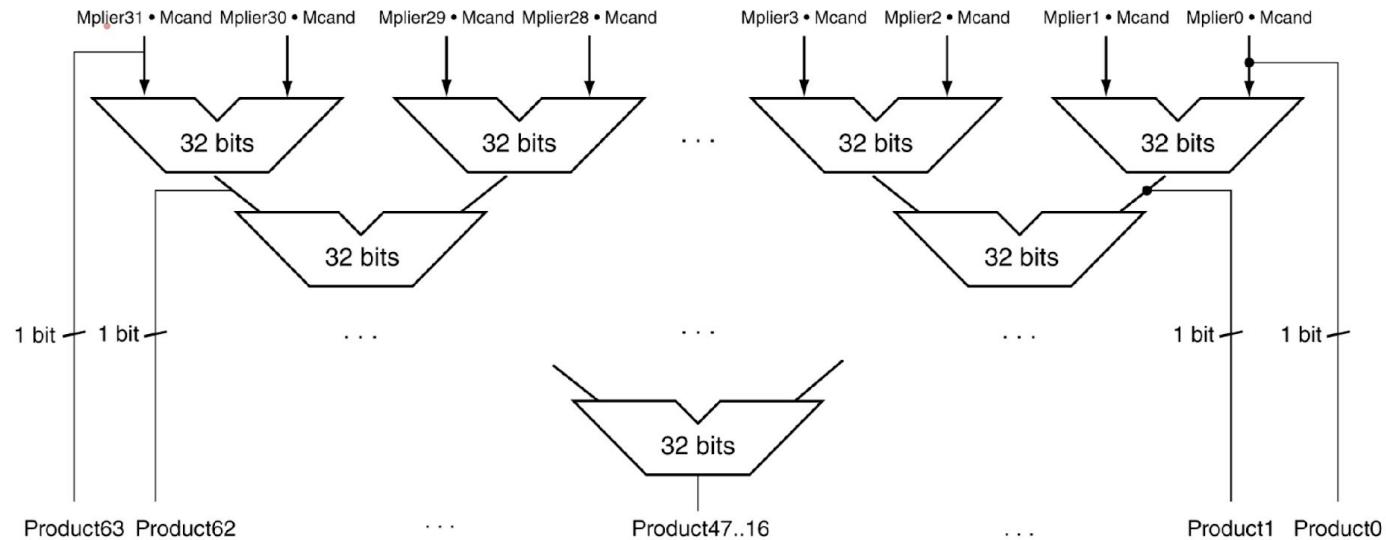
- Perform steps in parallel: addshift



- One cycle per partial-product addition
 - That's ok, if frequency of multiplications is low

Faster Multiplier

- Uses multiple adders
 - Cost/performance tradeoff

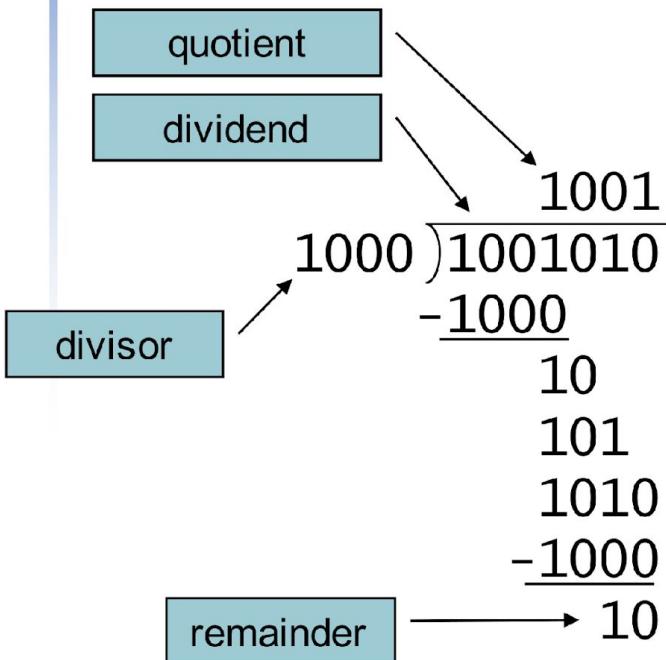


- Can be pipelined
 - Several multiplication performed in parallel

MIPS Multiplication

- Two 32-bit registers for product
 - HI: most-significant 32 bits
 - LO: least-significant 32-bits
- Instructions
 - `mult rs, rt / multu rs, rt`
 - 64-bit product in HI/LO
 - `mfhi rd / mflo rd`
 - Move from HI/LO to rd
 - Can test HI value to see if product overflows 32 bits
 - `mul rd, rs, rt`
 - Least-significant 32 bits of product → rd

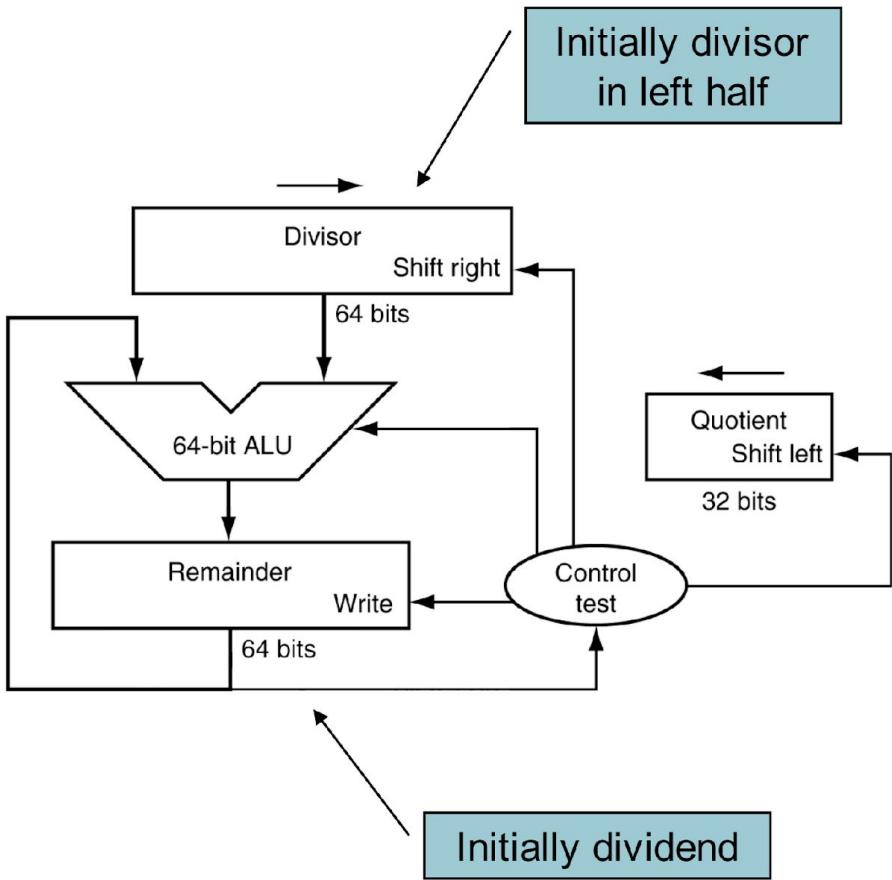
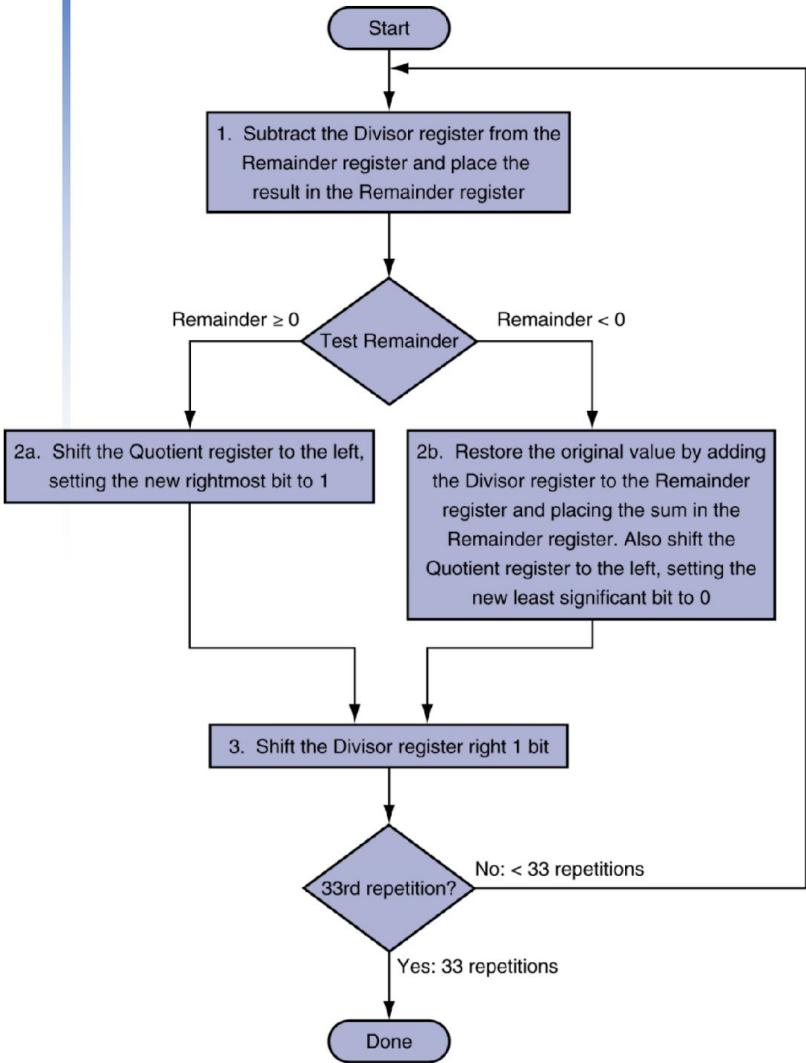
Division



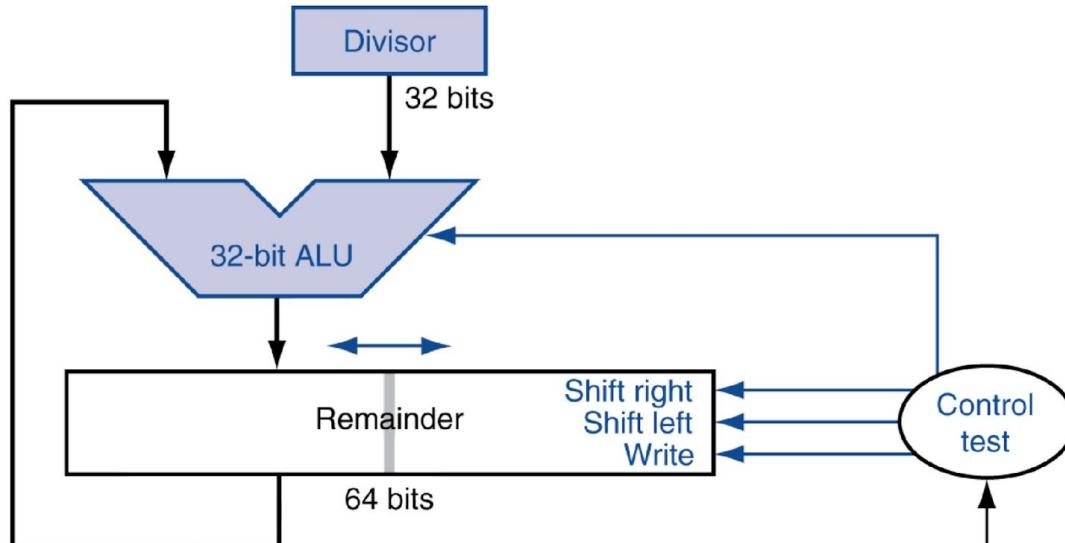
n -bit operands yield n -bit quotient and remainder

- Check for 0 divisor
- Long division approach
 - If divisor \leq dividend bits
 - 1 bit in quotient, subtract
 - Otherwise
 - 0 bit in quotient, bring down next dividend bit
- Restoring division
 - Do the subtract, and if remainder goes < 0 , add divisor back
- Signed division
 - Divide using absolute values
 - Adjust sign of quotient and remainder as required

Division Hardware



Optimized Divider



- One cycle per partial-remainder subtraction
- Looks a lot like a multiplier!
 - Same hardware can be used for both

Faster Division

- Can't use parallel hardware as in multiplier
 - Subtraction is conditional on sign of remainder
- Faster dividers (e.g. SRT devision) generate multiple quotient bits per step
 - Still require multiple steps

MIPS Division

- Use HI/LO registers for result
 - HI: 32-bit remainder
 - LO: 32-bit quotient
- Instructions
 - `div rs, rt / divu rs, rt`
 - No overflow or divide-by-0 checking
 - Software must perform checks if required
 - Use `mfhi`, `mflo` to access result

Floating Point

- Representation for non-integral numbers
 - Including very small and very large numbers
- Like scientific notation
 - -2.34×10^{56} ← normalized
 - $+0.002 \times 10^{-4}$ ← not normalized
 - $+987.02 \times 10^9$ ← not normalized
- In binary
 - $\pm 1.xxxxxxx_2 \times 2^{yyyy}$
- Types `float` and `double` in C

Floating Point Standard

- Defined by IEEE Std 754-1985
- Developed in response to divergence of representations
 - Portability issues for scientific code
- Now almost universally adopted
- Two representations
 - Single precision (32-bit)
 - Double precision (64-bit)

IEEE Floating-Point Format

single: 8 bits

double: 11 bits

single: 23 bits

double: 52 bits

S	Exponent	Fraction
---	----------	----------

$$x = (-1)^S \times (1 + \text{Fraction}) \times 2^{(\text{Exponent} - \text{Bias})}$$

- S: sign bit (0 ↗ non-negative, 1 ↗ negative)
- Normalize significand: $1.0 \leq |\text{significand}| < 2.0$
 - Always has a leading pre-binary-point 1 bit, so no need to represent it explicitly (hidden bit)
 - Significand is Fraction with the “1.” restored
- Exponent: excess representation: actual exponent + Bias
 - Ensures exponent is unsigned
 - Single: Bias = 127; Double: Bias = 1203

Single-Precision Range

- Exponents 0000000 and 1111111 reserved
- Smallest value
 - Exponent: 0000001
☞ actual exponent = $1 - 127 = -126$
 - Fraction: 000...00 ☞ significand = 1.0
 - $\pm 1.0 \times 2^{-126} \approx \pm 1.2 \times 10^{-38}$
- Largest value
 - exponent: 1111110
☞ actual exponent = $254 - 127 = +127$
 - Fraction: 111...11 ☞ significand ≈ 2.0
 - $\pm 2.0 \times 2^{+127} \approx \pm 3.4 \times 10^{+38}$

Double-Precision Range

- Exponents 0000...00 and 1111...11 reserved
- Smallest value
 - Exponent: 00000000001
☞ actual exponent = $1 - 1023 = -1022$
 - Fraction: 000...00 ☞ significand = 1.0
 - $\pm 1.0 \times 2^{-1022} \approx \pm 2.2 \times 10^{-308}$
- Largest value
 - Exponent: 11111111110
☞ actual exponent = $2046 - 1023 = +1023$
 - Fraction: 111...11 ☞ significand ≈ 2.0
 - $\pm 2.0 \times 2^{+1023} \approx \pm 1.8 \times 10^{+308}$

Floating-Point Precision

■ Relative precision

- all fraction bits are significant
- Single: approx 2^{-23}
 - Equivalent to $23 \times \log_{10}2 \approx 23 \times 0.3 \approx 6$ decimal digits of precision
- Double: approx 2^{-52}
 - Equivalent to $52 \times \log_{10}2 \approx 52 \times 0.3 \approx 16$ decimal digits of precision

Floating-Point Example

- Represent -0.75
 - $-0.75 = (-1)^1 \times 1.1_2 \times 2^{-1}$
 - $S = 1$
 - Fraction = $1000\dots00_2$
 - Exponent = $-1 + \text{Bias}$
 - Single: $-1 + 127 = 126 = 01111110_2$
 - Double: $-1 + 1023 = 1022 = 01111111110_2$
- Single: $101111101000\dots00$
- Double: $101111111101000\dots00$

Floating-Point Example

- What number is represented by the single-precision float

1100000010100...00

- S = 1
- Fraction = 01000...00₂
- Exponent = 10000001₂ = 129
- $x = (-1)^1 \times (1 + 01_2) \times 2^{(129 - 127)}$
 $= (-1) \times 1.25 \times 2^2$
 $= -5.0$

Denormal Numbers

- Exponent = 000...0  hidden bit is 0

$$x = (-1)^S \times (0 + \text{Fraction}) \times 2^{-\text{Bias}}$$

- Smaller than normal numbers
 - allow for gradual underflow, with diminishing precision
- Denormal with fraction = 000...0

$$x = (-1)^S \times (0 + 0) \times 2^{-\text{Bias}} = \pm 0.0$$

Two representations
of 0.0!

Infinities and NaNs

- Exponent = 111...1, Fraction = 000...0
 - $\pm\infty$
 - Can be used in subsequent calculations, avoiding need for overflow check
- Exponent = 111...1, Fraction \neq 000...0
 - Not-a-Number (NaN)
 - Indicates illegal or undefined result
 - e.g., $0.0 / 0.0$
 - Can be used in subsequent calculations

Floating-Point Addition

- Consider a 4-digit decimal example
 - $9.999 \times 10^1 + 1.610 \times 10^{-1}$
- 1. Align decimal points
 - Shift number with smaller exponent
 - $9.999 \times 10^1 + 0.016 \times 10^1$
- 2. Add significands
 - $9.999 \times 10^1 + 0.016 \times 10^1 = 10.015 \times 10^1$
- 3. Normalize result & check for over/underflow
 - 1.0015×10^2
- 4. Round and renormalize if necessary
 - 1.002×10^2

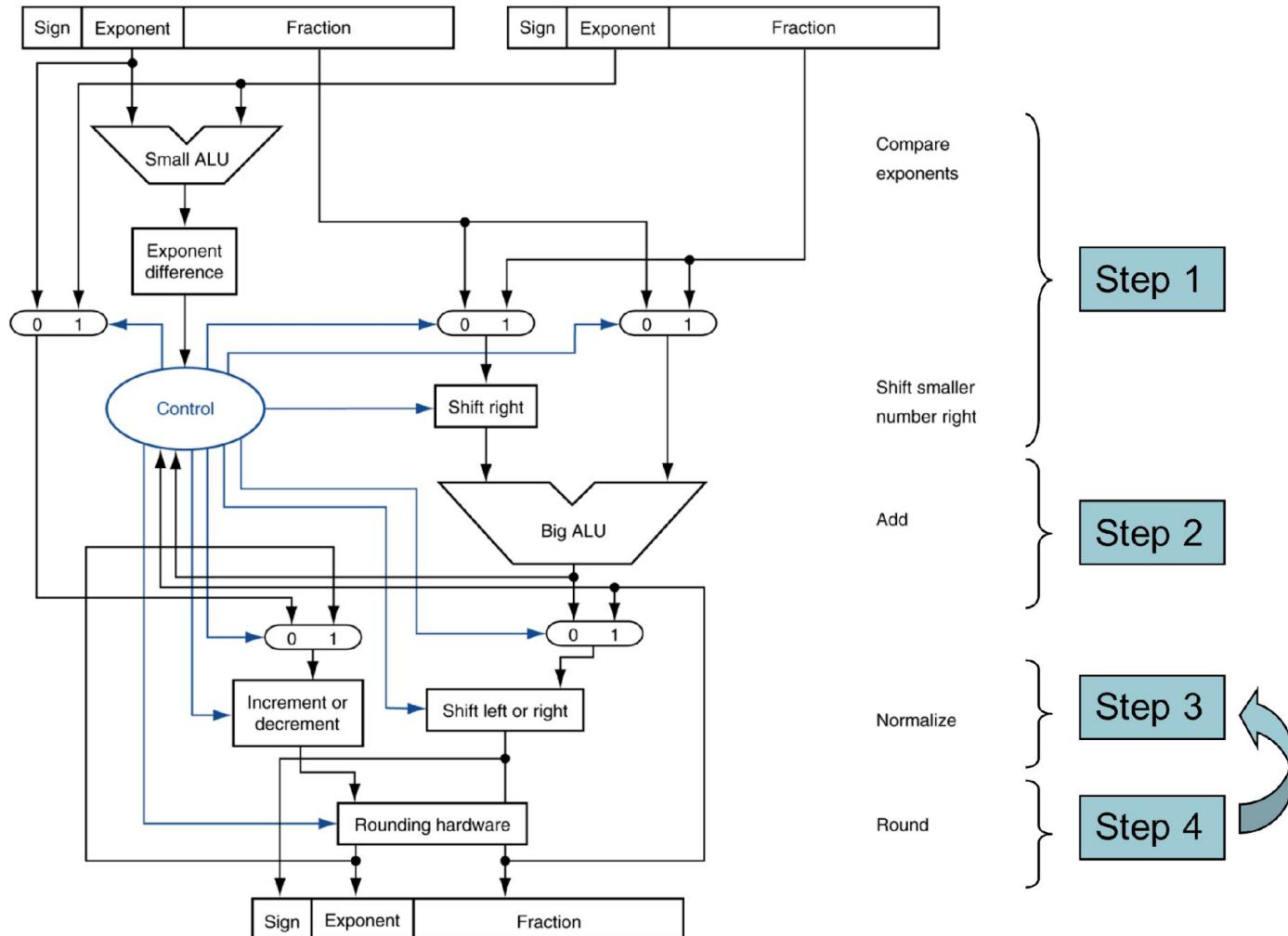
Floating-Point Addition

- Now consider a 4-digit binary example
 - $1.000_2 \times 2^{-1} + -1.110_2 \times 2^{-2}$ ($0.5 + -0.4375$)
- 1. Align binary points
 - Shift number with smaller exponent
 - $1.000_2 \times 2^{-1} + -0.111_2 \times 2^{-1}$
- 2. Add significands
 - $1.000_2 \times 2^{-1} + -0.111_2 \times 2^{-1} = 0.001_2 \times 2^{-1}$
- 3. Normalize result & check for over/underflow
 - $1.000_2 \times 2^{-4}$, with no over/underflow
- 4. Round and renormalize if necessary
 - $1.000_2 \times 2^{-4}$ (no change) = 0.0625

FP Adder Hardware

- Much more complex than integer adder
- Doing it in one clock cycle would take too long
 - Much longer than integer operations
 - Slower clock would penalize all instructions
- FP adder usually takes several cycles
 - Can be pipelined

FP Adder Hardware



Floating-Point Multiplication

- Consider a 4-digit decimal example
 - $1.110 \times 10^{10} \times 9.200 \times 10^{-5}$
- 1. Add exponents
 - For biased exponents, subtract bias from sum
 - New exponent = $10 + -5 = 5$
- 2. Multiply significands
 - $1.110 \times 9.200 = 10.212 \rightsquigarrow 10.212 \times 10^5$
- 3. Normalize result & check for over/underflow
 - 1.0212×10^6
- 4. Round and renormalize if necessary
 - 1.021×10^6
- 5. Determine sign of result from signs of operands
 - $+1.021 \times 10^6$

Floating-Point Multiplication

- Now consider a 4-digit binary example
 - $1.000_2 \times 2^{-1} \times -1.110_2 \times 2^{-2}$ (0.5×-0.4375)
- 1. Add exponents
 - Unbiased: $-1 + -2 = -3$
 - Biased: $(-1 + 127) + (-2 + 127) = -3 + 254 - 127 = -3 + 127$
- 2. Multiply significands
 - $1.000_2 \times 1.110_2 = 1.110_2 \quad \Rightarrow \quad 1.110_2 \times 2^{-3}$
- 3. Normalize result & check for over/underflow
 - $1.110_2 \times 2^{-3}$ (no change) with no over/underflow
- 4. Round and renormalize if necessary
 - $1.110_2 \times 2^{-3}$ (no change)
- 5. Determine sign: +ve \times -ve \Rightarrow -ve
 - $-1.110_2 \times 2^{-3} = -0.21875$

FP Arithmetic Hardware

- FP multiplier is of similar complexity to FP adder
 - But uses a multiplier for significands instead of an adder
- FP arithmetic hardware usually does
 - Addition, subtraction, multiplication, division, reciprocal, square-root
 - FP  integer conversion
- Operations usually takes several cycles
 - Can be pipelined

FP Instructions in MIPS

- FP hardware is coprocessor 1
 - Adjunct processor that extends the ISA
- Separate FP registers
 - 32 single-precision: \$f0, \$f1, ... \$f31
 - Paired for double-precision: \$f0/\$f1, \$f2/\$f3, ...
 - Release 2 of MIPS ISA supports 32×64
- FP instructions operate only on FP registers
 - Programs generally don't do integer ops on FP data, or vice versa
 - More registers with minimal code-size impact
- FP load and store instructions
 - lwc1, ldc1, swc1, sdc1
 - e.g., ldc1 \$f8, 32(\$sp)

FP Instructions in MIPS

- Single-precision arithmetic
 - add.s, sub.s, mul.s, div.s
 - e.g., add.s \$f0, \$f1, \$f6
- Double-precision arithmetic
 - add.d, sub.d, mul.d, div.d
 - e.g., mul.d \$f4, \$f4, \$f6
- Single- and double-precision comparison
 - c.xx.s, c.xx.d (xx is eq, lt, le, ...)
 - Sets or clears FP condition-code bit
 - e.g. c.lt.s \$f3, \$f4
- Branch on FP condition code true or false
 - bc1t, bc1f
 - e.g., bc1t TargetLabel

FP Example: °F to °C

- C code:

```
float f2c (float fahr) {  
    return ((5.0/9.0)*(fahr - 32.0));  
}
```

- fahr in \$f12, result in \$f0, literals in global memory space

- Compiled MIPS code:

```
f2c:  lw $f16, const5($gp)  
      lw $f18, const9($gp)  
      div.s $f16, $f16, $f18  
      lw $f18, const32($gp)  
      sub.s $f18, $f12, $f18  
      mul.s $f0, $f16, $f18  
      jr $ra
```

FP Example: Array Multiplication

- $X = X + Y \times Z$

- All 32×32 matrices, 64-bit double-precision elements

- C code:

```
void mm (double x[][],  
         double y[][], double z[][]) {  
    int i, j, k;  
    for (i = 0; i != 32; i = i + 1)  
        for (j = 0; j != 32; j = j + 1)  
            for (k = 0; k != 32; k = k + 1)  
                x[i][j] = x[i][j]  
                        + y[i][k] * z[k][j];  
}
```

- Addresses of x, y, z in \$a0, \$a1, \$a2, and
 i, j, k in \$s0, \$s1, \$s2

FP Example: Array Multiplication

MIPS code:

```
    li    $t1, 32          # $t1 = 32 (row size/loop end)
    li    $s0, 0           # i = 0; initialize 1st for loop
L1: li    $s1, 0           # j = 0; restart 2nd for loop
L2: li    $s2, 0           # k = 0; restart 3rd for loop
    sll  $t2, $s0, 5       # $t2 = i * 32 (size of row of x)
    addu $t2, $t2, $s1 # $t2 = i * size(row) + j
    sll  $t2, $t2, 3       # $t2 = byte offset of [i][j]
    addu $t2, $a0, $t2 # $t2 = byte address of x[i][j]
    l.d  $f4, 0($t2)      # $f4 = 8 bytes of x[i][j]
L3: sll  $t0, $s2, 5       # $t0 = k * 32 (size of row of z)
    addu $t0, $t0, $s1 # $t0 = k * size(row) + j
    sll  $t0, $t0, 3       # $t0 = byte offset of [k][j]
    addu $t0, $a2, $t0 # $t0 = byte address of z[k][j]
    l.d  $f16, 0($t0)     # $f16 = 8 bytes of z[k][j]
```

...

FP Example: Array Multiplication

...

s11	\$t0, \$s0, 5	# \$t0 = i*32 (size of row of y)
addu	\$t0, \$t0, \$s2	# \$t0 = i*size(row) + k
s11	\$t0, \$t0, 3	# \$t0 = byte offset of [i][k]
addu	\$t0, \$a1, \$t0	# \$t0 = byte address of y[i][k]
l.d	\$f18, 0(\$t0)	# \$f18 = 8 bytes of y[i][k]
mul.d	\$f16, \$f18, \$f16	# \$f16 = y[i][k] * z[k][j]
add.d	\$f4, \$f4, \$f16	# f4=x[i][j] + y[i][k]*z[k][j]
addiu	\$s2, \$s2, 1	# \$k k + 1
bne	\$s2, \$t1, L3	# if (k != 32) go to L3
s.d	\$f4, 0(\$t2)	# x[i][j] = \$f4
addiu	\$s1, \$s1, 1	# \$j = j + 1
bne	\$s1, \$t1, L2	# if (j != 32) go to L2
addiu	\$s0, \$s0, 1	# \$i = i + 1
bne	\$s0, \$t1, L1	# if (i != 32) go to L1

Accurate Arithmetic

- IEEE Std 754 specifies additional rounding control
 - Extra bits of precision (guard, round, sticky)
 - Choice of rounding modes
 - Allows programmer to fine-tune numerical behavior of a computation
- Not all FP units implement all options
 - Most programming languages and FP libraries just use defaults
- Trade-off between hardware complexity, performance, and market requirements

Subword Parallelism

- Graphics and audio applications can take advantage of performing simultaneous operations on short vectors
 - Example: 128-bit adder:
 - Sixteen 8-bit adds
 - Eight 16-bit adds
 - Four 32-bit adds
- Also called data-level parallelism, vector parallelism, or Single Instruction, Multiple Data (SIMD)

x86 FP Architecture

- Originally based on 8087 FP coprocessor
 - 8×80 -bit extended-precision registers
 - Used as a push-down stack
 - Registers indexed from TOS: ST(0), ST(1), ...
- FP values are 32-bit or 64 in memory
 - Converted on load/store of memory operand
 - Integer operands can also be converted on load/store
- Very difficult to generate and optimize code
 - Result: poor FP performance

x86 FP Instructions

Data transfer	Arithmetic	Compare	Transcendental
<code>FILD</code> mem/ST(i)	<code>FIADDP</code> mem/ST(i)	<code>FICOMP</code>	<code>FPATAN</code>
<code>FISTP</code> mem/ST(i)	<code>FISUBRP</code> mem/ST(i)	<code>FIUCOMP</code>	<code>F2XMI</code>
<code>FLDPI</code>	<code>FIMULP</code> mem/ST(i)	<code>FSTSW</code> AX/mem	<code>FCOS</code>
<code>FLD1</code>	<code>FIDIVRP</code> mem/ST(i)		<code>FPTAN</code>
<code>FLDZ</code>	FSQRT FABS FRNDINT		<code>FPREM</code> <code>FPSIN</code> <code>FYL2X</code>

- Optional variations
 - I: integer operand
 - P: pop operand from stack
 - R: reverse operand order
 - But not all combinations allowed

Streaming SIMD Extension 2 (SSE2)

- Adds $4 \times 128
 - Extended to 8 registers in AMD64/EM64T$
- Can be used for multiple FP operands
 - 2×64
 - 4×32
 - Instructions operate on them simultaneously
 - Single-Instruction Multiple-Data

Matrix Multiply

■ Unoptimized code:

```
1. void dgemm (int n, double* A, double* B, double* C)
2. {
3.     for (int i = 0; i < n; ++i)
4.         for (int j = 0; j < n; ++j)
5.         {
6.             double cij = C[i+j*n]; /* cij = C[i][j] */
7.             for (int k = 0; k < n; k++)
8.                 cij += A[i+k*n] * B[k+j*n]; /* cij += A[i][k]*B[k][j] */
9.             C[i+j*n] = cij; /* C[i][j] = cij */
10.        }
11. }
```

Matrix Multiply

x86 assembly code:

```
1. vmovsd (%r10),%xmm0    # Load 1 element of C into %xmm0
2. mov %rsi,%rcx           # register %rcx = %rsi
3. xor %eax,%eax          # register %eax = 0
4. vmovsd (%rcx),%xmm1    # Load 1 element of B into %xmm1
5. add %r9,%rcx            # register %rcx = %rcx + %r9
6. vmulsd (%r8,%rax,8),%xmm1,%xmm1 # Multiply %xmm1,
element of A
7. add $0x1,%rax           # register %rax = %rax + 1
8. cmp %eax,%edi          # compare %eax to %edi
9. vaddsd %xmm1,%xmm0,%xmm0 # Add %xmm1, %xmm0
10. jg 30 <dgemm+0x30>   # jump if %eax > %edi
11. add $0x1,%r11d          # register %r11 = %r11 + 1
12. vmovsd %xmm0,(%r10)    # Store %xmm0 into C element
```

Matrix Multiply

■ Optimized C code:

```
1. #include <x86intrin.h>
2. void dgemm (int n, double* A, double* B, double* C)
3. {
4.     for ( int i = 0; i < n; i+=4 )
5.         for ( int j = 0; j < n; j++ ) {
6.             __m256d c0 = _mm256_load_pd(C+i+j*n); /* c0 = C[i][j] */
7.             for( int k = 0; k < n; k++ )
8.                 c0 = _mm256_add_pd(c0, /* c0 += A[i][k]*B[k][j] */ 
9.                                     _mm256_mul_pd(_mm256_load_pd(A+i+k*n),
10.                                     _mm256_broadcast_sd(B+k+j*n)));
11.             _mm256_store_pd(C+i+j*n, c0); /* C[i][j] = c0 */
12.         }
13. }
```

Matrix Multiply

■ Optimized x86 assembly code:

```
1. vmovapd (%r11),%ymm0      # Load 4 elements of C into %ymm0
2. mov %rbx,%rcx             # register %rcx = %rbx
3. xor %eax,%eax            # register %eax = 0
4. vbroadcastsd (%rax,%r8,1),%ymml # Make 4 copies of B element
5. add $0x8,%rax             # register %rax = %rax + 8
6. vmulpd (%rcx),%ymml,%ymml # Parallel mul %ymml, 4 A elements
7. add %r9,%rcx              # register %rcx = %rcx + %r9
8. cmp %r10,%rax             # compare %r10 to %rax
9. vaddpd %ymml,%ymm0,%ymm0 # Parallel add %ymml, %ymm0
10. jne 50 <dgemm+0x50>     # jump if not %r10 != %rax
11. add $0x1,%esi             # register %esi = %esi + 1
12. vmovapd %ymm0,(%r11)     # Store %ymm0 into 4 C elements
```

Right Shift and Division

- Left shift by i places multiplies an integer by 2^i
- Right shift divides by 2^i ?
 - Only for unsigned integers
- For signed integers
 - Arithmetic right shift: replicate the sign bit
 - e.g., $-5 / 4$
 - $11111011_2 \gg 2 = 11111110_2 = -2$
 - Rounds toward $-\infty$
 - c.f. $11111011_2 \ggg 2 = 00111110_2 = +62$

Associativity

- Parallel programs may interleave operations in unexpected orders
 - Assumptions of associativity may fail

		$(x+y)+z$	$x+(y+z)$
x	-1.50E+38		-1.50E+38
y	1.50E+38	0.00E+00	
z	1.0	1.0	1.50E+38
	1.00E+00	0.00E+00	

- Need to validate parallel programs under varying degrees of parallelism

Who Cares About FP Accuracy?

- Important for scientific code
 - But for everyday consumer use?
 - “My bank balance is out by 0.0002¢!” ☹
- The Intel Pentium FDIV bug
 - The market expects accuracy
 - See Colwell, *The Pentium Chronicles*

Concluding Remarks

- Bits have no inherent meaning
 - Interpretation depends on the instructions applied
- Computer representations of numbers
 - Finite range and precision
 - Need to account for this in programs

Concluding Remarks

- ISAs support arithmetic
 - Signed and unsigned integers
 - Floating-point approximation to reals
- Bounded range and precision
 - Operations can overflow and underflow
- MIPS ISA
 - Core instructions: 54 most frequently used
 - 100% of SPECINT, 97% of SPECFP
 - Other instructions: less frequent