Expression for V(Xn) (It is not
$$\frac{\pi^2}{n}$$
!)

$$V(\bar{X}_{N}) = V\left(\frac{1}{N}\sum_{t=1}^{N}(X_{t}-M)\right)$$

$$= E\left(\frac{1}{N}\sum_{t=1}^{N}(X_{t}-M)\right)$$

$$= \frac{1}{N^{2}}E\left((X_{1}-M)+X_{1}-X_{1}+(X_{N}-M)\right)$$

$$= \frac{1}{N^{2}}\left[(X_{1}-M)+X_{1}-X_{1}+(X_{N}-M)\right]$$

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$$= \frac{1}{N^{2}}\left[(X_{1}-M)+X_{1}+$$

i.e.
$$V(\bar{X}_N) = \frac{1}{N^2} \sum_{h=-\infty}^{N} (n - |h|) Y_h = \frac{1}{N} \sum_{|h| \le n} (1 - \frac{|h|}{n}) Y_h$$

Estimation of V(.) and P(.)

Suppose u is known, en imbiased estimator of Y(h) 'w

$$Y_{u}^{*}(h) = \frac{1}{n-h} \sum_{t=1}^{n-h} (X_{t} - u)(X_{t+h} - u)$$

as $E\left(Y_{\mu}^{*}(h)\right) = \frac{1}{n-h}\sum_{t=1}^{n-h}E\left(X_{t}-\mu\right)\left(X_{t+h}\mu\right)$ $=\frac{(n-h)}{(n-h)}Y_h=Y_h$

An alternate estimator (difference in the divisor only)

$$Y_{\mathcal{U}}(h) = \frac{1}{n} \sum_{k=1}^{n-h} (x_{k-1}u)(x_{k+1}u)$$

 $E(\hat{Y}_{\mu}(h)) = \frac{n-h}{n} \times_h \neq \hat{Y}_h$

Bias: $E(\hat{Y}_{M}(N)) - Y_{N} = -\frac{h}{n} \cdot \hat{Y}_{N} \rightarrow 0$ as $n \rightarrow 4$

=> Yu(h) is unbiased in the limit, although It is a bigged extimator

Note that $P_{x} = \frac{1}{x} T T^{1}$ where nx2n matrix T is given by $T = \begin{cases} 0 - - - \cdot 0 & y_1 & y_2 - - \cdot \cdot y_n \\ 0 \cdot \cdot \cdot & y_1 & y_2 - - \cdot \cdot y_n & 0 \\ 0 \cdot \cdot & - y_1 & y_2 & y_3 - - \cdot \cdot y_n & 0 \\ - & - & - & - & - \\ 0 & y_1 \cdot - - \cdot y_n & 0 - - - - & 0 \end{cases}$ Yi = Xi - Xn; i=1(1)n

Thus, $fg \in \mathbb{R}^n$ $g' f_n g > 0$ $\Rightarrow Y(h) f'' is not non.d.$ Mote: $Y^*(h) f''$ is not non.d.

Standard models of time series

(I) White noise process

ACVF
$$Y_X(h) = \{T^\lambda, Tfh=0\}$$

ACF
$$P_{X}(h) = \begin{cases} 1, & \text{if } h = 0 \\ 0, & \text{of } \omega \end{cases}$$

$$\theta_0 \neq 0$$
, $\theta_q \neq 0$

Of define
$$\epsilon'_{E} = \theta_{0} \epsilon_{E} \sim WN(0, \theta_{0}^{2} \sigma_{E}^{2})$$

$$k \times_{E} = E_{E} + \left(\frac{\theta_{1}}{\theta_{0}}\right) E_{t-1} + \cdots + \left(\frac{\theta_{q}}{\theta_{0}}\right) E_{t-q}$$
alternate MA(q) representation

Note: 2-sided MA representation $X_{F} = \sum_{M} \beta^{2} e^{F-2}$ (iii) Auto Regressive (AR) process Suppose Et ~ MN(0, 42) {Xt} w AR(p) Tt $X_{t} = \phi_{1} X_{t-1} + \cdots + \phi_{b} X_{t-b} + \epsilon_{t}$ \$ \$ 0 ; Cov(EE, XE-i)=0 +1>0. P1, --, ore unknown courts; AR parameters. Note: W. L.O.g. We can take a model without constant term for a Mationary process Suppose we take X = S. + p X = + - - + + X - + E = Since [Xt] is obationary $M = EXE = 8 + \phi_1 u + \cdots + \phi_p M$ =) M(1-4,-.-4) = 8 If (1-0,-..- p) = 0 then d = 0 If of w, i.e. (1-4, -- - 4,) \$0, then we can write XE = S+P, XE-1+ -- + P, XE-p+ EL

 $X_{\xi} - M = S + \phi_1 X_{\xi-1} + \cdots + \phi_p X_{\xi-p} - M + \varepsilon_{\xi}$

i.e. $X_{t}-M = M(1-\phi_{1}-\dots-\phi_{p})+\phi_{1}X_{t}-f_{1}\dots+\phi_{p}X_{t}-f_{p}M+\epsilon_{t}$

1-6. (XF-M) = \(\langle (XF-1M) + - + \(\frac{1}{2} \rangle (XF-\frac{1}{2} m) + \(\frac{1}{2} \rangle \right) + \(\frac{1}{2} \right) \)

Define, $Y_{E} = X_{E} - U$ model is $Y_{E} = \phi, Y_{E-1} + \cdots + \phi, Y_{E-p} + \varepsilon_{E}$ (x) $Y_{E} = \phi, Y_{E-1} + \cdots + \phi, Y_{E-p} + \varepsilon_{E}$

[Xt] Covariance stationary > {Yt] is also covariance stationary
whatianary