Mathematical formulation of a time series

Let (12, Fr, P) be a probability space and T be an index set

Det": A real valued time series is a real valued function X(E, w) defined on TXI, I for a fixed E, $X(t, \omega) = X_t(\omega) = X_t$, say) is a random variable defined on (D, F, P).

A time series is thus a collection {xt! t GT} of random variables.

We can define joint distribution function of a finite set of random variables {Xt1, Xt2, ..., Xtn} from the Collection [XE: EET] is

 $F_{X_{b_1},\ldots,X_{b_n}}(x_1,\ldots,x_n) = P(X_{b_1} \leq x_1,\ldots,X_{b_n} \leq x_n)$

Concept of Mationarity of time series: {Xt] process is 3 "statistical properties" of the process do not change over time, i.e. realizations come from a stable physical System which has achieved a "steady-state statistical equilibrium" mode.

Remark: Different forms of stationarity concept is defined under different paradigms of quantifying "statistical equilibrium".

Important définitions of rotationarity

(II) Stationarity upto order m: A time series process

{Xt} is said to be stationary upto order m, II, tor

all no, I,

any admissible ti, tz, ---, tn and any integer k, all

the Joint moments upto order m of {Xt, --, Xtn}

exist and equal the corresponding joint moments

upto order m of {Xt, tk}.--, Xtn+k}

i.e. $E\left(X_{t_1}^{m_1}X_{t_2}^{m_2}...X_{t_n}^{m_n}\right) = E\left(X_{t_1+k}^{m_1}X_{t_2+k}^{m_2}...X_{t_n+k}^{m_n}\right)$ $\forall k \text{ and } \forall \text{ integer } m_1, m_2, ..., m_n \text{ } (m_i \geq 0)$ $\exists \sum_{i=1}^{n} m_i \leq m_i$

Note: In particular, selling $m_2 = m_3 = --- = m_n = 0$, we get that for any E and $E(X_{t_1}^{m_1}) = E(X_{t_1}^{m_1}) + K$ $\Rightarrow E(X_{t_1}^{m_1}) = E(X_0^{m_1}) \text{ selling } K = -E$ Const indep of E

Important special cases of stationarity upto order mo (i) Order I stationary

EXtexists & EXt= 4 +t

This is referred to as "mean stationarity"
Thus a time series {Xt} is mean stationary if
EXt exists and is indep of t.

(ii) Order 2 stationary: EXE and EXEXs exist XE,s

(a) EXt= u < const, indep of t

(b) $EX_{E}^{\prime} = u_{2}^{\prime}$ constitudely of t; hence $V(X_{E}) = \sigma^{2}$ is also indep of t

 $k(c) E(X_{t}X_{s}) = E(X_{t+h}X_{s+h}) = E(X_{0}X_{s-t}) - (*)$ $f^{n}f(s-t) \text{ only and}$ indep of t (s-t): time difference

(*) \Rightarrow (ov(X_t, X_s) = $E(x_{t}x_{s}) - M^{2}$ $f^{n} f_{t}$ time difference (s-t) only and is inally of t

Remark: The order 2 stationarity is also referred to as Covariance stationary (or weak stationary or stationary in the wide sense). This form of stationarity is the most widely used form of stationarity.

Remark: If {X + } is strict stationary, then {X + } is also covariance stationary provided moments up to order 2 exist for the joint distribution.

Pf: For n=1, def" of strict stationarity implies that X_t has the same dist" for each t in the index set,

i.e. $F_{X_{k_1}}(x) = F_{X_{k_1+k}}(x) + K - (*)$

It EXE < of, then (*) in particular implies that EXE & VXE exists and are indep of t (as the distress are identical + t).

Further, take n=2, def^n of strict stationarity implies that the jt $dist^n$ of (X_{E_1}, X_{E_2}) and $(X_{E_1}th, X_{E_2}th)$ are identical

i.e. $(X_{t_1}, X_{t_2}) \stackrel{d}{=} (X_{t_1 + h}, X_{t_2 + h})$

 $= \sum_{k=1}^{\infty} Cov(X_{k_1}, X_{k_2}) = Cov(X_{k_1+k_1}, X_{k_2+k_1}) + k_1, k_2$ $= Cov(X_0, X_{k_2-k_1}), h = -k_1$

of (b2-b1) only

=> {Xt} is covariance stationary.