$$\lambda = (x_1, \dots, x_p)'$$

· t.p.m twick

t m.q.t.

$$M_X(t) = E(e^{t/X}) = E(e^{t/X_1 + \dots + t_p \times p})$$

 $(t_1, \dots t_p)$ provided the expectation exists in some

$$M_X(E) = \int - \cdot \cdot \int e^{\frac{1}{2}E(X)} f_{X}(X) dx_1 - \cdot dx_p$$
 for continuous care

=
$$\sum_{x_1} \cdots \sum_{x_p} e^{\sum_{i} b_i x_i} P(x_i - x_i)$$
 for discrete cone

$$\pi_{1}^{\mathsf{K}^{1},\cdots,\mathsf{K}^{\mathsf{b}}} = \mathbb{E}\left(\mathsf{X}_{1}^{\mathsf{l}},\cdots,\mathsf{X}_{K^{\mathsf{b}}}^{\mathsf{b}}\right) = \frac{9^{\sharp_{1}^{\mathsf{l}}}\cdots 9^{\sharp_{K^{\mathsf{b}}}}}{9^{\mathsf{k}^{\mathsf{l}}}\cdots 9^{\mathsf{k}^{\mathsf{b}}}}\Big)^{\frac{\mathsf{f}}{\mathsf{f}}} = \tilde{0}$$

joint moment of order Kit. + Kp Kin are non-negative integers

Note that we can get marginal dist m.g.f & from the Joint m.g.f.

$$M_{\chi}(0,...0,E_{i},0...0) = E\left(e^{E_{i}\chi_{i}}\right) = M_{\chi_{i}}(E_{i})$$

Sly marginal joint m.g.f. + for any subset can be obtained from $M_X(E)$.

Note: m.q.f. of X,+--. +XK tor K < b can be obtained from Mx (1)

Remark: X1, ..., Xp are independent iff $M_{X}(E) = \frac{P}{i=1} M_{X_{i}}(F_{i})$

```
Conditional expectation
Lonvider a biromate setup (X,Y) \rightarrow jt \ p.d.t \ f_{X,Y}^{(X,Y)}
           marginal p.d.t.s: fx(x), ty(y)
          Conditional p. d. t. s: $\frac{1}{X|X}, \frac{1}{Y|X}
                      f^{X'\lambda}(x,z) = f^X(x) f^{\lambda X}(z)
                                = 7 / (A) 7 X (X)
   het g(x,y) be some to fixly
     E(g(x,y)(x): conditional expectation of g(x,y)
      E(g(x, y) (y): Conditional expectation of g(x, y) giron y
  E(3(x',\lambda)/x) = E^{\lambda/x}(3(x',\lambda)/x)
        = Jed(x'a) Firsty -> + J X with
         = \phi(x), \lambda
    E_{X}(\phi(x)) = E_{X}E_{Y|X}(g(x,y)|X)
                = \left( \phi(x) \right) f_{\chi}(x) dx
               = [ [2(x,y) fy(x) fx(x) dy dx
             = \int_{-4}^{4} \int_{-4}^{4} 3(x,y) f_{x,y} = E_{x,y} (f(x,y))
```

i.e
$$E_{x} E_{y|x}(q(x,y)|x) = E_{x,y}(q(x,y))$$
 $S_{y} Cone : q(x,y) = y \text{ now}$
 $E E(y|x) = E(y)$
 $S_{y} E_{y} E_{y}(y) = E(x)$
 $S_{y} E_{y} E_{y}(y) = E(y)$
 $E(y - E(y)) = E_{x} E_{y|x}((y - E(y))) = E_{y} E_{y}(y) = E_{y}(y)$

Note: Joint m.g.f. can be derived through m.q.f. of conditional distribution wing conditional expectation e.g. $(x_1,x_2) \sim N_2(u_1, u_2, \sigma_1^{\perp}, \sigma_2^{\perp}, \rho)$ $H_{X_1,X_2}(t_1,t_2) = E(e^{t_1X_1 + b_2X_2})$; $f(x_1,x_2) = e^{t_1X_1 + b_2X_2}$ $= E(e^{t_1X_1 + b_2X_2}|X_1)$ $= E(e^{t_1X_1}(E_{X_2}|X_1))$ Now, use the fact that $X_2|X_1 \sim N(u_2 + \rho \sigma_2(x_1 - u_1), \sigma_2^{\perp}(1 - \rho^2))$.