

Remark: It is always possible to write a stationary VAR(p) process as VMA(∞) process with the VWN process having elements that are mutually uncorrelated.

Consider the VMA(∞) representation of VAR(p).

$$\underset{k \times 1}{X_t} = \underset{k \times 1}{\epsilon_t} + \Psi_1 \underset{k \times 1}{\epsilon_{t-1}} + \Psi_2 \underset{k \times 1}{\epsilon_{t-2}} + \dots$$

$$\epsilon_t \sim VWN(0, \Sigma), \Sigma > 0$$

Note that \exists a non-singular matrix $H \ni$

$$H \Sigma H' = D, \text{ (diagonal matrix)}$$

Using the above non-singular matrix H , we can write

$$\underset{k \times 1}{X_t} = H^{-1} H \underset{k \times 1}{\epsilon_t} + \Psi_1 H^{-1} H \underset{k \times 1}{\epsilon_{t-1}} + \Psi_2 H^{-1} H \underset{k \times 1}{\epsilon_{t-2}} + \dots$$

$$\text{i.e. } \underset{k \times 1}{X_t} = \bar{\Psi}_0^* \underset{k \times 1}{\eta_t} + \bar{\Psi}_1^* \underset{k \times 1}{\eta_{t-1}} + \bar{\Psi}_2^* \underset{k \times 1}{\eta_{t-2}} + \dots$$

$$\bar{\Psi}_i^* = \Psi_i H^{-1} ; i = 0, 1, \dots$$

$$\bar{\Psi}_0 = I_k$$

$$\underset{k \times 1}{\eta_t} = H \underset{k \times 1}{\epsilon_t} \Rightarrow E(\underset{k \times 1}{\eta_t}) = H E(\underset{k \times 1}{\epsilon_t}) = \underset{k \times 1}{0}$$

$$\text{Cov}(\underset{k \times 1}{\eta_t}, \underset{k \times 1}{\eta_s}) = E(\underset{k \times 1}{\eta_t} \underset{k \times 1}{\eta_s}') =$$

$$\begin{aligned}
 \text{i.e. } \text{Cov}(\underline{\eta}_t, \underline{\eta}_s) &= E(\underline{H} \underline{\epsilon}_t)(\underline{H} \underline{\epsilon}_s)' \\
 &= \underline{H} E(\underline{\epsilon}_t \underline{\epsilon}_s') \underline{H}' \\
 &= \begin{cases} \underline{H} \underline{\Sigma} \underline{H}' = \underline{D}_\lambda, & \text{if } t = s \\ 0, & \text{if } t \neq s \end{cases}
 \end{aligned}$$

$$\Rightarrow \underline{\eta}_t \sim \text{VWN}(\underline{0}, \underline{D}_\lambda)$$

\Rightarrow elements of $\underline{\eta}_t$ are uncorrelated

$\Rightarrow \{X_t\}$ is expressed as VMA(α) with VWN process with uncorrelated components.

Vector ARMA (p, q)

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$$\underline{X}_t \sim VARMA(p, q) \text{ iff}$$

$$\begin{aligned} \underline{X}_t &= \underline{\Phi}_1 \underline{X}_{t-1} + \dots + \underline{\Phi}_p \underline{X}_{t-p} \\ &+ \underline{\epsilon}_t + \underline{\Theta}_1 \underline{\epsilon}_{t-1} + \dots + \underline{\Theta}_q \underline{\epsilon}_{t-q} \end{aligned}$$

$\underline{\Phi}_p \neq 0, \underline{\Theta}_q \neq 0, \underline{\epsilon}_t \sim VWN(0, \Sigma)$

$$\text{Cov}(\underline{\epsilon}_t, \underline{X}_{t-j}) = 0 \quad \forall j > 0$$

Conditions for stationarity

\underline{X}_t is covariance stationary if all values of z satisfying

$$|\underline{I}_K - \underline{\Phi}_1 z - \dots - \underline{\Phi}_p z^p| = 0 \text{ lie outside the}$$

unit circle

i.e. all z satisfying $|\Phi(z)| = 0$ lie outside the unit circle (with model as $\Phi(B)\underline{X}_t = \Theta(B)\underline{\epsilon}_t$)

Every covariance stationary vector ARMA(p, q) has a causal representation through,

$$\underline{X}_t = \Phi(B)^{-1} \Theta(B) \underline{\epsilon}_t = \Psi(B) \underline{\epsilon}_t, \text{ say}$$

$$\text{i.e. } \Phi(B)^{-1} \Theta(B) = \Psi(B)$$

$$\Rightarrow \Theta(B) = \Phi(B) \Psi(B)$$

$$\begin{aligned} \text{i.e. } (\underline{I}_K + \underline{\Theta}_1 B + \dots + \underline{\Theta}_q B^q) &= (\underline{I}_K - \underline{\Phi}_1 B - \dots - \underline{\Phi}_p B^p) \\ &(\underline{\Psi}_0 + \underline{\Psi}_1 B + \dots) \end{aligned}$$

i.e.

$$(\mathbf{I}_K + \Phi_1 B + \dots + \Phi_q B^q)$$

$$= \Psi_0 + (\Psi_1 - \Phi_1 \Psi_0) B + (\Psi_2 - \Phi_1 \Psi_1 - \Phi_2 \Psi_0) B^2 + (\Psi_3 - \Phi_1 \Psi_2 - \Phi_2 \Psi_1 - \Phi_3 \Psi_0) B^3 + \dots$$

comparing coefficients,

$$B^0 : \Psi_0 = \mathbf{I}_K$$

$$B^1 : \Psi_1 = \Phi_1 + \Phi_1 \Psi_0$$

$$B^2 : \Psi_2 = \Phi_1 \Psi_1 + \Phi_2 \Psi_0 + \Phi_2 \Psi_0$$

$$B^3 : \Psi_3 = \Phi_1 \Psi_2 + \Phi_2 \Psi_1 + \Phi_3 \Psi_0 + \Phi_3 \Psi_0$$

In general,

$$\Psi_s = \Phi_1 \Psi_{s-1} + \Phi_2 \Psi_{s-2} + \dots + \Phi_p \Psi_{s-p} + \Phi_s \Psi_0$$

$$\forall s \leq q$$

$$\& \Psi_s = \Phi_1 \Psi_{s-1} + \Phi_2 \Psi_{s-2} + \dots + \Phi_p \Psi_{s-p}$$

$$\forall s > q$$

$$\text{with } \Psi_r = 0 \quad \forall r < 0 \quad \& \Psi_r = \mathbf{I}_K \quad \text{if } r = 0$$

X_t is said to be invertible if all values of z satisfying $|\Phi(z)| = 0$ lie outside the unit circle. In this case,

$$\underline{\epsilon}_t = \Phi(B)^{-1} \Phi(B) \underline{\epsilon}_t = \Psi(B) \underline{\epsilon}_t$$

Vector ARMA(p, q) \rightarrow VAR(∞) ↑
use comparing coeffs.

VMA(q) to VAR(∞)

VMA(q) model

VMA(q) is invertible if all z satisfying $|H(z)|=0$ lie outside the unit circle.

$$\tilde{X}_t = \tilde{\epsilon}_t + H_1 \tilde{\epsilon}_{t-1} + \dots + H_q \tilde{\epsilon}_{t-q}$$

$$H_q \neq 0, \quad \tilde{\epsilon}_t \sim \text{WN}(0, \Sigma)$$

$$\tilde{X}_t = H(B) \tilde{\epsilon}_t$$

$$H(B) = I_K + H_1 B + \dots + H_q B^q$$

Let $H(B)^{-1}$ denote the inverse operator of $H(B)$, then

$$\tilde{\epsilon}_t = H(B)^{-1} \tilde{X}_t = \Psi(B) \tilde{X}_t = \sum_{j=0}^{\infty} \Psi_j \tilde{X}_{t-j}$$

$$\Psi(B) = H(B)^{-1}$$

$$\text{i.e. } I_K = H(B) \Psi(B)$$

$$I_K = (I_K + H_1 B + \dots + H_q B^q)$$

$$(\Psi_0 + \Psi_1 B + \Psi_2 B^2 + \dots)$$

$$\text{i.e. } I_K = \Psi_0 + (H_1 \Psi_0 + \Psi_1) B$$

$$+ (\Psi_2 + H_1 \Psi_1 + H_2 \Psi_0) B^2 + \dots$$

Comparing Coeff of B^j :

$$B^0: \quad \Psi_0 = I_K$$

$$B^1: \quad \Psi_1 = -H_1 \Psi_0 = -H_1$$

$$B^2: \quad \Psi_2 = -H_1 \Psi_1 - H_2 \Psi_0$$

$$\Psi_2 = H_1^2 - H_2 \rightarrow \Psi_2 = H_1^2 - H_2$$

$$B^3: \quad \Psi_3 = -H_1 \Psi_2 - H_2 \Psi_1 - H_3 \Psi_0$$

$$\text{i.e. } \Psi_3 = -H_1 (H_1^2 - H_2) - H_2 (-H_1) - H_3$$

$$= -H_1^3 + H_1 H_2 + H_2 H_1 - H_3$$

$$\Psi_s = -H_1 \Psi_{s-1} - H_2 \Psi_{s-2} - \dots - H_q \Psi_{s-q}$$

$$\Psi_0 = I, \Psi_s = 0 \quad \forall s < 0$$

Remark : Impulse response function (IRF)

Covariance stationary VAR(p) \rightarrow VMA(∞)

Covariance stationary VARMA(p,q) \rightarrow VMA(∞)

$$X_t = \epsilon_t + \bar{\Psi}_1 \epsilon_{t-1} + \bar{\Psi}_2 \epsilon_{t-2} + \dots$$

$$\begin{pmatrix} X_{1t} \\ \vdots \\ X_{Kt} \end{pmatrix} = \begin{pmatrix} \epsilon_{1t} \\ \vdots \\ \epsilon_{Kt} \end{pmatrix} + \begin{pmatrix} \psi_{11}^{(1)} & \dots & \psi_{1K}^{(1)} \\ \vdots & \ddots & \vdots \\ \psi_{K1}^{(1)} & \dots & \psi_{KK}^{(1)} \end{pmatrix} \begin{pmatrix} \epsilon_{1,t-1} \\ \vdots \\ \epsilon_{K,t-1} \end{pmatrix} + \dots$$

$$\dots + \begin{pmatrix} \psi_{11}^{(s)} & \dots & \psi_{1K}^{(s)} \\ \vdots & \ddots & \vdots \\ \psi_{K1}^{(s)} & \dots & \psi_{KK}^{(s)} \end{pmatrix} \begin{pmatrix} \epsilon_{1,t-s} \\ \vdots \\ \epsilon_{K,t-s} \end{pmatrix} + \dots$$

$$X_{it} = \epsilon_{it} + \left(\psi_{i1}^{(1)} \epsilon_{1,t-1} + \dots + \psi_{iK}^{(1)} \epsilon_{K,t-1} \right) + \dots$$

$$\dots + \left(\psi_{i1}^{(s)} \epsilon_{1,t-s} + \dots + \psi_{iK}^{(s)} \epsilon_{K,t-s} \right) + \dots$$

$$i = 1(1)K$$

$$\frac{\partial X_{i,t+s}}{\partial \epsilon_{j,t}} = \psi_{ij}^{(s)}$$

$$\frac{\partial X_{\sim t+s}}{\partial \epsilon_{\sim t}} = \bar{\Psi}_s$$

and the proof