```
Eigenvalue problems
 Goal: Given a matrix AC ["x".
                                                                           Find \lambda \in \mathbb{C}, V \in \mathbb{C}^n (V \neq 0) such that
                                                                                                                                         Av = \lambda v (*)
                                                                         1: eigenvalue, V: eigenvector
                                                        Along direction V, matrix A acts like scalar.
                                                        When A has n linearly independent eigenvectors.
                                                          we can rewrite (x) for all at once
                                                                                                    Applications: Control system, economic models, power grids,
                                                                                                        biostatistics, machine bearning ...
                 ex. Decoupling odEs
                                                                           A = V \Lambda V^{-1} 'n wupled ODEs with
                                                  Solution: Change to eigenvector coordinates u.1+), ..., un(t) "
                                                                                                 Let \begin{bmatrix} u_n(t) \\ \vdots \\ u_n(t) \end{bmatrix} = \begin{bmatrix} v_1 & \cdots & v_n \\ \vdots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\
```

same then  $\frac{d}{dt}\begin{bmatrix} u, lt \end{bmatrix} = \begin{bmatrix} v_1 & \dots & v_n \end{bmatrix} \begin{bmatrix} c_1(t) \\ \vdots \\ c_n(t) \end{bmatrix}$ 

 $\dot{c}_i(t) = \frac{d}{dt} c_i(t)$ 

The system is diagonalized (decoupled)

$$\frac{d}{dt}\begin{bmatrix} c_i(t) \\ \vdots \\ c_n(t) \end{bmatrix} = \begin{bmatrix} \lambda_i \\ \vdots \\ \lambda_n \end{bmatrix}\begin{bmatrix} c_i(t) \\ \vdots \\ c_n + i \end{bmatrix}$$

$$(=)$$
  $\frac{dc_i}{dt}(t) = \lambda_i c_i t_i$ ,  $i=1,...,n$ 

$$\Leftrightarrow$$
  $C_i(t) = e^{\lambda_i t} C_i(0)$ ,  $i = 1....$ 

Suppose initially 
$$u(0) = C_1(0) v_1 + \cdots + C_n(0) v_n$$
  
then  $u(t) = e^{\lambda_1 t} C_1(0) v_1 + \cdots + e^{\lambda_n t} C_n(0) v_n$   
If  $Re(\lambda_i) > 0$ , then  $e^{\lambda_1 t} C_1(0) v_i$  persists  
If  $Re(\lambda_i) < 0$ , then  $e^{\lambda_1 t} C_1(0) v_i \rightarrow 0$  as  $t \rightarrow +\infty$ 

**W** 

· Eigenvalue solvers must be iterative

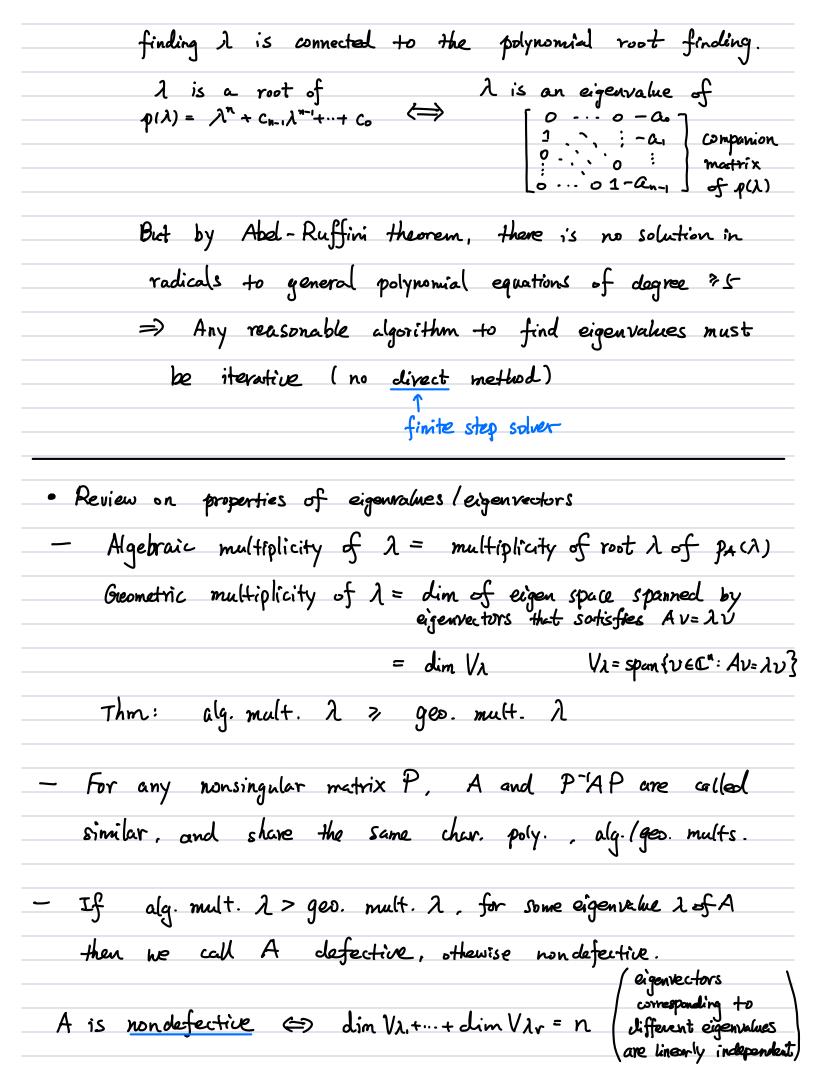
$$Av = \lambda v \implies (A - \lambda I)v = 0 \implies det(A - \lambda I) = 0$$

- Characteristic polynomial 
$$p_A(\lambda) = det(A - \lambda I)$$
  
Eigenvalues of  $A \iff roots$  of  $p_A(\lambda)$ 

- Implication: Algorithms to find eigenvalues is very different from solving linear system Ax = b

\* For 
$$Ax=b$$
, the solution  $x=A^{-1}b$  is a rational function of aij and bi

\* For  $Ax = \lambda x$ , since  $\lambda$  is the root of  $p_A(\lambda) = dot(A - \lambda I)$ ,



$$\Leftrightarrow$$
 A has eigen decomposition  $A = V \Lambda V^{-1}$  (diagonalizable)

where  $V \in \mathbb{C}^{n \times n}$  nonsingular

and 
$$\Lambda = diag(\lambda_1, \dots, \lambda_n)$$
.  $\lambda_i \in C$ ,  $i=1,\dots, n$ 

ex. Defective matrices do exist in many problems

ex.  $A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$  (not singular)

 $p_A(\lambda) = \det(A - \lambda I) = (\lambda - 1)^2$   $\lambda = 1$ , alg. mult. = 2 A triangular matrix  $\Rightarrow$  eigenvalues = diagonal entries

 $A-1 \cdot I = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad rank(A) = 1$ 

Null (A-1.I) = 2- rank(A) = 1  $\lambda = 1$  geo. mult. = 1 A is defective

In practice, almost no matrices are exactly defective.

(Actually, the set of nxn diagonalizable matrice is dense in CMTM, that is, if A is defective and there exists arbitrorily small perturbation DA & CMTM such that A + DA is diagonalizable, which is usually the case when we take into account the rounding error in real implementation)

However, working with almost defective mostrix is still dangerous in finding eig. decomposition.

ex. 
$$A = \begin{pmatrix} 1+\xi & 1 \\ 0 & 1-\xi \end{pmatrix}$$
  $\lambda_1 = 1+\xi$ ,  $\lambda_2 = 1-\xi$ 

$$A v_1 = \lambda_1 v_1 \Rightarrow v_1 = (1, 0)^T$$

$$A \nu_{2} = \lambda_{2} \nu_{2} = (1 + \xi) \nu_{2}^{(1)} + \nu_{2}^{(2)} = (1 - \xi) \nu_{2}^{(1)}$$

$$\Rightarrow$$
  $V_2 = (1, -25)^T / \sqrt{1+45^2}$ 

$$V = \begin{pmatrix} 1 & \sqrt{1+4\epsilon^2} \\ 0 & -2\sqrt[4]{1+4\epsilon^2} \end{pmatrix} \implies V^{-1} = \begin{pmatrix} 1 & * \\ 0 & -\sqrt{1+4\epsilon^2}/2 \end{pmatrix}$$

$$\implies ||V^{-1}||_2 = O(\frac{1}{\xi})$$

These ill-conditioned similarity transformation could lead to lurge rounding error:

floating  $\longrightarrow fl(V^-|AV) = V^-|AV + E$ point matrix multiplication where  $||E||_2 \approx K_2(Y) ||A||_2$  Smach

We want to work with unitary similarity for numerical stability

## · Schur factorization

For the purpose of finding eigenvalues, we can relax the restriction on diagonality. That is, consider a factorization of the form

$$A = QTQ^*$$
.

the diagonal entries of T are eig. val. of A.

Thm: For all  $A \in \mathbb{C}^{n \times n}$ , I uniformy  $Q \in \mathbb{C}^{n \times n}$  such that  $Q^*AQ = T$ , where T is upper triangular.

Pf: induction. n=1 obvious.

Suppose true for n-1.

let Av= Av , 11 1/2=1,

We can find a unitary  $\hat{Q}$  with  $1^{st}$  col =  $\mathcal{V}$ 

$$\Rightarrow \hat{Q}^* A \hat{Q} = \begin{pmatrix} \lambda & \omega^T \end{pmatrix} \begin{pmatrix} 1 \\ 0 & B \end{pmatrix} \begin{pmatrix} 1 \\ n-1 \end{pmatrix}$$

By induction, Q\*BQ, = T,

$$\Rightarrow \begin{pmatrix} 1 & 0 \\ 0 & Q_1 \end{pmatrix}^{*} \hat{Q}^{*} A \hat{Q} \begin{pmatrix} 1 & 0 \\ 0 & Q_1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & Q_1^{*} \end{pmatrix} \begin{pmatrix} \lambda & \omega^{\mathsf{T}} \\ 0 & \mathsf{B} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & Q_1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & o \\ o & Q_1^* \end{pmatrix} \begin{pmatrix} \lambda & \omega^T Q_1 \\ o & B Q_1 \end{pmatrix}$$

$$= \begin{pmatrix} \lambda & \omega^{\mathsf{T}} \mathcal{Q}_{1} \\ \sigma & \alpha_{1}^{\mathsf{T}} \beta \mathcal{Q}_{1} \end{pmatrix} = \begin{pmatrix} \lambda & \omega^{\mathsf{T}} \mathcal{Q}_{1} \\ \sigma & \mathsf{T}_{1} \end{pmatrix} = :\mathsf{T}$$

· Special case: A\*A = AA\* ← normal mastrix

Thm A is normal

$$A = Q \Lambda Q^*$$

where QEQuXn is antary R\*Q=I

and  $\Delta = \text{diag}(\lambda_i, \dots, \lambda_n), \lambda_i + C, i = 1, \dots, n$ 

Pf: Let A = QTQ\* be schur factorization of A

Lamma: If T is upper Hiangular and T\*T=TT\*

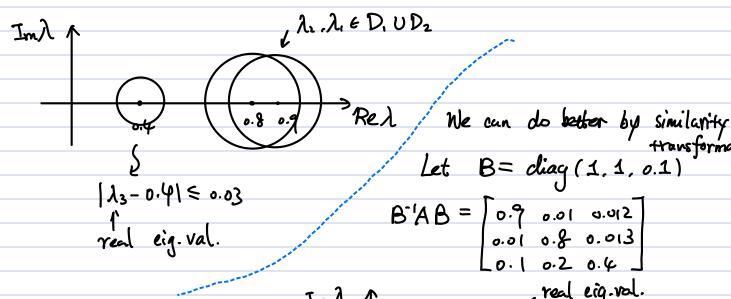
then T is diagonal. (Hint: Cheek off-diagonal entries)

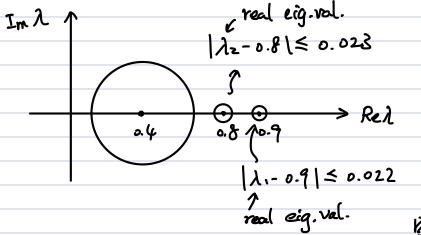
Special case: A is Harmitian => A is normal
Eigenvalue sensitivity:
Many eigenvalue solvers: V k A V k → D
Question: how well do diagonal elements of a matrix
approximate its eig. vals? = perturbation of cliagonal matrices
Thm (Gershgorin Circle theorem)
If $A = D + N$ with $Nii = 0$ , $i = 1, \dots, n$
then $\{\lambda: \lambda \text{ is an eig. val of } A\} \subseteq \bigcup_{i=1}^{N} D_i$
$D_{i}:=\left\{ z\in C:  z-D_{ii}  \leq \sum_{j=1}^{n}  N_{ij}  \right\}$ or $\sum_{j=1}^{n}  N_{ji} $
Pf: Let 2 be an eig. val. of A.
We can assume 2 = Dii Vi=1, N
We know that (D- )II) + N is singular
$\Rightarrow$ 1 + $(D-\lambda I)^{-1}N$ is singular
$\Rightarrow 1 \le    (D-\lambda I)^{-1} N   _{\infty} = \sum_{j=1}^{n} \frac{ N_{i,j} }{ D_{i,j} } \text{ for some } 0$
⇒ λ ∈ D;.
Remark: It can also be shown that

if some  $Din \bigcup D_j = \phi$ , then  $D_i$  has exactly  $d = eig \cdot val$ .

Remark: This theorem is also useful in estimating eig. rakes.

$$ex.$$
  $A = \begin{bmatrix} 0.9 & 0.01 & 0.12 \\ 0.01 & 0.8 & 0.13 \\ 0.01 & 0.02 & 0.4 \end{bmatrix}$ 





In some methods, it is possible to show that the computed eig. vals are the exact eig. vals of A+E, 11E11<<1 perturbation.

We are thus interested in the following perturbation result

Thm (Bauer - Fike)

If  $\mu$  is an eig. val of A+E and  $V^{-1}AV = D = diag(\lambda_1, ..., \lambda_n)$ 

then  $\min |\lambda_i - \mu| \le Kp(V) \|E\|_p \quad \forall \quad p \in [1, +\infty)$   $|\sin \mu| = |\mu| =$ 

( 4/11- 1/4 - 1/4 - 1/4 - 1/4 )

```
Pf: It suffices to assume u € {\langle \langle \langl
                            V-(A+E-MI)Y = D-MI+Y-EY
                                                                                                         = (D-\mu I) (I+(D-\mu I)^{-1}V^{-1}EV)
                           Since A+E-NI is singular
                                     => I+(D-uI)-'V-'EV is singular
                                                      1 < 1/D- uI) V-1EY | > = 11(D- uI) 1/1/1 p 11Ellp 11V1/1
                                                                                                                                                                     11 (D-uI)-1/1p = max 1
1<1<n | 1/2 |
  Note: If A is normal, K_2(V) = 1 (b.c. V is anifony)
 An analogous result can be obtained via the Schur factorization
Thm Let Q*AQ = D+N be Schur fact. of A & CMXM
               Let u be an eig. val of A+E, and p is the smallest
                integer such that |N|^p = 0, then
                                                              min / /i - ul < max { 0, 0 }
                         Remark: The eigenvalues of a nonnormal matrix may be
```

sensitive to perturbation!