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Eigenvalue problems
 Goal: Given a matrix AC ["x".
                                                                           Find \lambda \in \mathbb{C}, V \in \mathbb{C}^n (V \neq 0) such that
                                                                                                                                         Av = \lambda v (*)
                                                                         1: eigenvalue, V: eigenvector
                                                        Along direction V, matrix A acts like scalar.
                                                        When A has n linearly independent eigenvectors.
                                                          we can rewrite (x) for all at once
                                                                                                    Applications: Control system, economic models, power grids,
                                                                                                        biostatistics, machine bearning ...
                 ex. Decoupling odEs
                                                                           A = V \Lambda V^{-1} 'n wupled ODEs with
                                                  Solution: Change to eigenvector coordinates u.1+), ..., un(t) "
                                                                                                 Let \begin{bmatrix} u_n(t) \\ \vdots \\ u_n(t) \end{bmatrix} = \begin{bmatrix} v_1 & \cdots & v_n \\ \vdots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\
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same then $\frac{d}{dt}\begin{bmatrix} u, lt \end{bmatrix} = \begin{bmatrix} v_1 & \dots & v_n \end{bmatrix} \begin{bmatrix} c_1(t) \\ \vdots \\ c_n(t) \end{bmatrix}$

 $\dot{c}_i(t) = \frac{d}{dt} c_i(t)$

The system is diagonalized (decoupled)

$$\frac{d}{dt}\begin{bmatrix} c_i(t) \\ \vdots \\ c_n(t) \end{bmatrix} = \begin{bmatrix} \lambda_i \\ \vdots \\ \lambda_n \end{bmatrix}\begin{bmatrix} c_i(t) \\ \vdots \\ c_n + i \end{bmatrix}$$

$$(=)$$
 $\frac{dc_i}{dt}(t) = \lambda_i c_i t_i$, $i=1,...,n$

$$\Leftrightarrow$$
 $C_i(t) = e^{\lambda_i t} C_i(0)$, $i = 1....$

Suppose initially
$$u(0) = C_1(0) v_1 + \cdots + C_n(0) v_n$$

then $u(t) = e^{\lambda_1 t} C_1(0) v_1 + \cdots + e^{\lambda_n t} C_n(0) v_n$
If $Re(\lambda_i) > 0$, then $e^{\lambda_1 t} C_1(0) v_i$ persists
If $Re(\lambda_i) < 0$, then $e^{\lambda_1 t} C_1(0) v_i \rightarrow 0$ as $t \rightarrow +\infty$

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· Eigenvalue solvers must be iterative

$$Av = \lambda v \implies (A - \lambda I)v = 0 \implies det(A - \lambda I) = 0$$

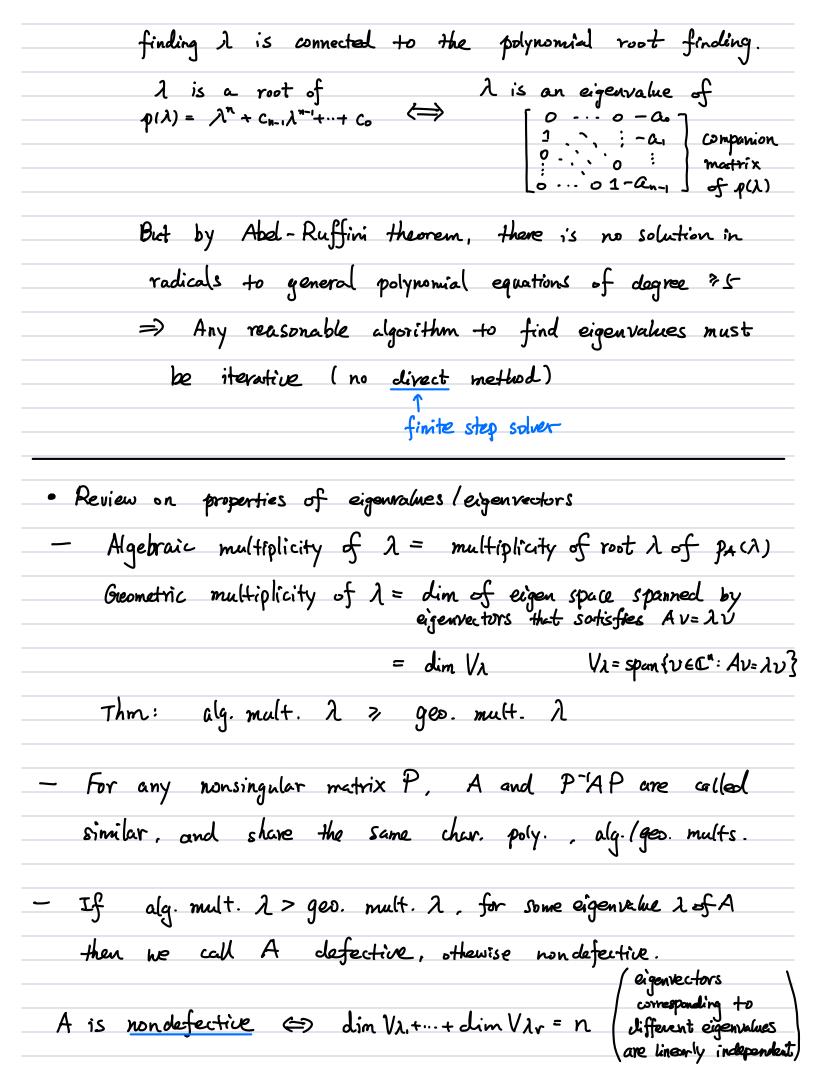
- Characteristic polynomial
$$p_A(\lambda) = det(A - \lambda I)$$

Eigenvalues of $A \iff roots$ of $p_A(\lambda)$

- Implication: Algorithms to find eigenvalues is very different from solving linear system Ax = b

* For
$$Ax = b$$
, the solution $x = A^{-1}b$ is a rational function of aij and bi

* For $Ax = \lambda x$, since λ is the root of $p_A(\lambda) = dot(A - \lambda I)$,



$$\Leftrightarrow$$
 A has eigen decomposition $A = V \Lambda V^{-1}$

(diagonalizable)

where $V \in \mathbb{C}^{n \times n}$ nonsingular

and
$$\Lambda = diag(\lambda_1, \dots, \lambda_n)$$
. $\lambda_i \in C$, $i=1,\dots, n$

ex. Defective matrices do exist in many problems

ex. $A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ (not singular)

 $p_A(\lambda) = \det(A - \lambda I) = (\lambda - 1)^2$ $\lambda = 1$, alg. mult. = 2 A triangular matrix \Rightarrow eigenvalues = diagonal entries

 $A-1 \cdot I = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad rank(A) = 1$

Null (A-1.I) = 2- rank(A) = 1 $\lambda = 1$ geo. mult. = 1 A is defective

In practice, almost no matrices are exactly defective.

(Actually, the set of nxn diagonalizable matrice is dense in CMTM, that is, if A is defective and there exists arbitrorily small perturbation DA & CMTM such that A + DA is diagonalizable, which is usually the case when we take into account the rounding error in real implementation)

However, working with almost defective mostrix is still dangerous in finding eig. decomposition.

ex.
$$A = \begin{pmatrix} 1+\xi & 1 \\ 0 & 1-\xi \end{pmatrix}$$
 $\lambda_1 = 1+\xi$, $\lambda_2 = 1-\xi$

$$A v_1 = \lambda_1 v_1 \Rightarrow v_1 = (1, 0)^T$$

$$A \nu_{2} = \lambda_{2} \nu_{2} = (1 + \xi) \nu_{2}^{(1)} + \nu_{2}^{(2)} = (1 - \xi) \nu_{2}^{(1)}$$

$$\Rightarrow$$
 $V_2 = (1, -25)^T / \sqrt{1+45^2}$

$$V = \begin{pmatrix} 1 & \sqrt{1+4\epsilon^2} \\ 0 & -2\sqrt[4]{1+4\epsilon^2} \end{pmatrix} \implies V^{-1} = \begin{pmatrix} 1 & * \\ 0 & -\sqrt{1+4\epsilon^2}/2 \end{pmatrix}$$

$$\implies ||V^{-1}||_2 = O(\frac{1}{\xi})$$

These ill-conditioned similarity transformation could lead to lurge rounding error:

floating $\longrightarrow fl(V^-|AV) = V^-|AV + E$ point matrix multiplication where $||E||_2 \approx K_2(Y) ||A||_2$ Smach

We want to work with unitary similarity for numerical stability

· Schur factorization

For the purpose of finding eigenvalues, we can relax the restriction on diagonality. That is, consider a factorization of the form

$$A = QTQ^*$$
.

the diagonal entries of T are eig. val. of A.

Thm: For all $A \in \mathbb{C}^{n \times n}$, I uniformy $Q \in \mathbb{C}^{n \times n}$ such that $Q^*AQ = T$, where T is upper triangular.

Pf: induction. n=1 obvious.

Suppose true for n-1.

let Av= Av. 11 1/2=1.

We can find a unitary \hat{Q} with 1^{st} col = \mathcal{V}

$$\Rightarrow \hat{Q}^* A \hat{Q} = \begin{pmatrix} \lambda & \omega^T \end{pmatrix} \begin{pmatrix} 1 \\ 0 & B \end{pmatrix} \begin{pmatrix} 1 \\ n-1 \end{pmatrix}$$

By induction, Q*BQ, = T,

$$\Rightarrow \begin{pmatrix} 1 & 0 \\ 0 & Q_1 \end{pmatrix}^{*} \hat{Q}^{*} A \hat{Q} \begin{pmatrix} 1 & 0 \\ 0 & Q_1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & Q_1^{*} \end{pmatrix} \begin{pmatrix} \lambda & \omega^{\mathsf{T}} \\ 0 & \mathsf{B} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & Q_1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & o \\ o & Q_1^* \end{pmatrix} \begin{pmatrix} \lambda & \omega^T Q_1 \\ o & B Q_1 \end{pmatrix}$$

$$= \begin{pmatrix} \lambda & \omega^{\mathsf{T}} \mathcal{Q}_{1} \\ \sigma & \alpha_{1}^{\mathsf{T}} \beta \mathcal{Q}_{1} \end{pmatrix} = \begin{pmatrix} \lambda & \omega^{\mathsf{T}} \mathcal{Q}_{1} \\ \sigma & \mathsf{T}_{1} \end{pmatrix} = :\mathsf{T}$$

· Special case: A*A = AA* ← normal mastrix

Thm A is normal

$$A = Q \Lambda Q^*$$

where QEQuXn is antary R*Q=I

and $\Delta = diag(\lambda_i, \dots, \lambda_n), \lambda_i + C, i = 1, \dots, n$

Pf: Let A = QTQ* be schur factorization of A

Lamma: If T is upper Hiangular and T*T=TT*

then T is diagonal. (Hint: Cheek off-diagonal entries)

Special case: A is Hermitian => A is normal

· Eigenvalue sensitivity:

Many eigenvalue solvers: V R'AVK -> D

Question: how well do diagonal elements of a matrix approximate its eig. vals?

Thm (Gershgorin Circle theorem)

If
$$A = D + N$$
 with $Nii = 0$, $i = 1 \cdot \cdot \cdot \cdot \cdot n$

then
$$\{\lambda : \lambda \text{ is an eig. val of } A\} \subseteq \bigcup_{i=1}^{n} D_i$$

$$D_{i}:= \left\{ \begin{array}{l} \frac{1}{2} \in \mathbb{C} : |2-D_{i}| \leq \sum_{j=1}^{n} |N_{ij}| \\ \frac{1}{3} = \sum_{j=1}^{n} |N_{ij}| \end{array} \right\}$$

Pf: Let 2 be an eig, val. of A

We can assume 2 = Dii \ti=1...., n

We know that $(D-\lambda I) + N$ is singular

$$\Rightarrow$$
 I + (D- λ I) N is singular

$$\Rightarrow 1 \le ||(D-\lambda I)^{-1}N||_{\infty} = \sum_{j=1}^{n} \frac{|N_{i,j}|}{|D_{i,j}|} \text{ for some } i$$

Remark: It can also be shown that

if some $D: N \cup D_j = \emptyset$, then D: has exactly = eig-val.

Remark: This theorem is also useful in estimating eig. rakes.

In some methods, it is possible to show that the computed eig. vals are the exact eig. vols of A+E, 11E11<<1 we are thus interested in the following perforbation result Thm (Bauer - Fike) If u is an eig. val of A+E and V-AV = D = diag (l., ..., ln) min $|\lambda;-\mu| \leq Kp(V) \|E\|_p \quad \forall \quad p \in [1,+\infty)$ $|\sin p|$ (4/1/2 = 1/1/10 1/2 /1/2) Pf: It suffices to assume u € {\lumber \lambda \lumber \lambda \lumber \lambda \lumber \lumber \lumber \lambda \lumber \lumbe V-1(A+E-UI)Y = D-UI+Y7EY $= (D-\mu I) (I+(D-\mu I)^{-1}V^{-1}EV)$ Since A+E-UI is singular \Rightarrow I+(D-uI)-'V-'EV is singular 11 (D-MI) -1/p = max 1/1 | 1/5 MI Note: If A is normal, $K_2(V) = 1$ (b.c. V is anifony) An analogous result can be obtained via the Schur factorization Thm Let Q*AQ = D+N be Schur fact. of A 6 CMX Let u be an eig. val of A+E, and p is the smallest

integer such that INIP = 0, then

	min 1 1/2 - rel = max { 0, 0 } }
	1818 1 200 1
Where	0= 11 E 2 \sum_{k=0}^{p-1} N 2
N.O.C	K=0
	<u> </u>
Remark: The	eigenvalues of a nonnormal matrix may be
,,,	
	sensitive to perturbation!