

## Non-symmetric Eigenvalue Problems

Recap: For symmetric eigenvalue problem

$$A \begin{bmatrix} 1 & & & \\ v_1, v_2 & \dots & v_n \\ 1 & & & \end{bmatrix} = \begin{bmatrix} 1 & & & \\ v_1, v_2 & \dots & v_n \\ 1 & & & \end{bmatrix} \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{bmatrix}$$

$\mathbf{V}$                      $\mathbf{V}$                      $\Lambda$   
 ↳ orthogonal matrix      ↗      real eigenvalues  
 $\mathbf{V}^{-1} = \mathbf{V}^*$

QR Algorithm computes approximations to  $\mathbf{V}$  and  $\Lambda$  in two phases.

### Phase 1: Tridiagonal Reduction

$$\underbrace{\mathcal{O}_{n-1}^T \dots \mathcal{O}_2^T \mathcal{O}_1^T A \mathcal{O}_1 \mathcal{O}_2 \dots \mathcal{O}_{n-1}}_{\mathcal{Q}^T} = \begin{bmatrix} * & * & & & \\ * & * & * & & \\ & * & * & * & \\ & & * & * & * \\ & & & * & * \end{bmatrix}$$

↳ sequence of orthogonal transformations, i.e., Householder       $T$ : tridiagonal mat.

### Phase 2: Tridiagonal QR iterations (w/shifts)

$$A^{(k)} = T, \quad Q^{(k)} R^{(k)} = A^{(k-1)} - \mu^{(k)} I, \quad A^{(k)} = R^{(k)} Q^{(k)} + \mu^{(k)} I$$

$\mu^{(k)} = A_{nn}^{(k-1)}$  - Rayleigh Quotient Shifts accelerates convergence  $A^{(k)} \rightarrow \Lambda$ .

Note: The full QR Algorithm has a few more bells and whistles that improve efficiency and numerical accuracy:

- Wilkinson Shifts improve global convergence properties compared to Rayleigh-Quotient Shifts (see textbook lecture 29).
- Implicit Shift strategies calculate  $A^{(k)} = Q^{(k)T} A^{(k-1)} Q^{(k)}$  w/out explicitly factoring the shifted matrix  $A^{(k-1)} - \mu^{(k)} I$ . This is more efficient, improves stability, and is the beginning of sophisticated multi-shift iterations which are central to modern implementations.
- Deflation breaks  $A^{(k)}$  into submatrices whenever any subdiagonal entry becomes sufficiently small. This saves computational effort on eigenvalues that have converged.

Stability Since both Phase 1 & Phase 2 rely exclusively on Orthogonal transformations,

the 2-phase QR algorithm is backward stable (see Thm. 26.1 & 29.1, LN).

### Non-symmetric EVP

The EVD of a non-symmetric diagonalizable matrix is

$$A = V \Lambda V^{-1}$$

$V$  need not be orthogonal in general,  $V^{-1} \neq V^*$ .  
I.e.,  $A$  may not be diagonalized by orthogonal similarity transforms.

### Schur Decomposition

On the other hand, every  $n \times n$  matrix  $A$  can be triangularized by orthogonal similarity transforms:

$$A = Q \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} Q^*$$

$Q$        $\Lambda$        $Q^*$   
= orthogonal      = upper triangular

The eigenvalues of  $A$  appear on the diagonal

of the upper triangular matrix  $U$ . This is the Schur Decomposition.

Idea: For non-symmetric matrices, use QR-type iteration to compute Schur decomposition by orthogonal similarity.

$\Rightarrow$  Orthogonal transformations preserve numerical stability

$\Rightarrow$  eigenvalues appear along diagonal of triangular Schur factor.

$\Rightarrow$  reconstruct eigenvectors of  $A$  from the Schur basis  $Q$  (Pset 3, Problem 4).

## QR for non-symmetric matrices

Two phase algorithm with tridiagonal  $T$  replaced by upper Hessenberg matrix

$$H = \begin{bmatrix} x & x & x & x & x \\ x & x & x & x & x \\ x & x & x & x & x \\ x & x & x & x & x \\ x & x & x & x & x \end{bmatrix}$$

↑  
zeros

It has only zeros below the first subdiagonal.

$$\begin{array}{c}
 \text{Phase 1} \\
 A \xrightarrow{\text{Hessenberg}} \\
 \text{Reduction}
 \end{array}
 \quad
 \begin{bmatrix}
 x & x & x & x & x \\
 x & x & x & x & x \\
 x & x & x & x & x \\
 x & x & x & x & x \\
 x & x & x & x & x
 \end{bmatrix}
 \quad
 \begin{array}{c}
 \text{Phase 2} \\
 \xrightarrow{\text{Hessenberg}} \\
 \text{QR iter.}
 \end{array}
 \quad
 \begin{bmatrix}
 x & x & x & x & x \\
 x & x & x & x & x \\
 x & x & x & x & x \\
 x & x & x & x & x \\
 x & x & x & x & x
 \end{bmatrix}$$

$H$                              $U$

Both phases are entirely analogous to their symmetric counterpart, with  $T$  replaced by  $H$ .

### Computing the SVD

The SVD diagonalizes general non-symmetric matrices with different orthogonal transformations applied on the left and the right. In Lecture 11, we saw that these come from the EVP for

$$A^*A \quad \text{and} \quad AA^*$$

which are symmetric positive definite.

In theory, we could compute the SVD of  $A$  by applying the QR algorithm to  $A^*A$  and  $AA^*$ , but there is a more efficient, stable two-phase approach.

### Phase 1: Bidiagonalization

The extra degrees of freedom associated with separate left and right transformations allow us to bidiagonalize  $A \in \mathbb{R}^{m \times n}$

$$\begin{bmatrix} x & x & x & x \\ x & x & x & x \end{bmatrix} \xrightarrow{U_1^*} \begin{bmatrix} x & x & x & x \\ 0 & x & x & x \end{bmatrix} \xrightarrow{\cdot V_1} \begin{bmatrix} x & x & 0 & 0 \\ 0 & x & x & x \end{bmatrix}$$

$$\xrightarrow{U_2^*} \begin{bmatrix} x & x & 0 & 0 \\ 0 & x & x & x \\ 0 & 0 & x & x \\ 0 & 0 & x & x \\ 0 & 0 & x & x \end{bmatrix} \xrightarrow{\cdot V_2} \begin{bmatrix} x & x & 0 & 0 \\ 0 & x & x & 0 \\ 0 & 0 & x & x \\ 0 & 0 & x & x \\ 0 & 0 & x & x \end{bmatrix}$$

$x$  - updated zeros       $0$  - new zero

$$\Rightarrow B = U_n^* \cdots U_2^* U_1^* A V_1 V_2 \cdots V_{n-2}$$

is a bidiagonal matrix.

## Phase 2:

Similar to QR iterations, orthogonal transformations are applied iteratively to left and right of  $B$  to obtain sequence of bidiagonal matrices  $B^{(1)}, B^{(2)}, \dots$  that converge to  $\Sigma$ .

Remark The symmetric matrix (recall Pset 2)  
Problem 5.4

$$H = \begin{bmatrix} 0 & A^\top \\ A & 0 \end{bmatrix}$$

typically plays a key role in the analysis  
and derivation of Phase 2, but is not explicitly  
formed in practice.