

Eigenvalue Problems, Part II

Goal: Find $\lambda \in \mathbb{C}$, $v \in \mathbb{C}^n$, $v \neq 0$, such that

$$Av = \lambda v$$

Today: Methods to find a single eig. value/vector.

- Power iteration (Find the dominate eig. val/vector)

Suppose that A is diagonalizable,

with eig. values $|\lambda_1| \geq |\lambda_2| \geq \dots \geq |\lambda_n| \geq 0$

eig. vectors $v_1, v_2, \dots, v_n \in \mathbb{C}^n$, $\|v_i\| = 1$
 $i=1, \dots, n$

- Starting with an $x_0 \in \mathbb{C}^n$, keep multiplying it with A , what do we get?

Since $\{v_1, \dots, v_n\} \subseteq \mathbb{C}^n$ forms a basis in \mathbb{C}^n ,

we have $x_0 = a_1 v_1 + \dots + a_n v_n$

$$A^k x_0 = a_1 \lambda_1^k v_1 + \dots + a_n \lambda_n^k v_n$$

$$= \lambda_1^k \left[a_1 v_1 + a_2 \left(\frac{\lambda_2}{\lambda_1} \right)^k v_2 + \dots + a_n \left(\frac{\lambda_n}{\lambda_1} \right)^k v_n \right]$$

if $\left| \frac{\lambda_i}{\lambda_1} \right| < 1$, $\forall i = 2, \dots, n$, then

when $k \gg 1$, $A^k x_0 \sim \lambda_1^k a_1 v_1$

Now let $x_k = A^k x_0$, then $x_{k+1} \sim \lambda_1^{k+1} a_1 v_1 \sim \lambda_1 x_k$

so $\frac{x_{k+1}^{(i)}}{x_k^{(i)}} \sim \lambda_1$, and $\frac{x_k}{\|x_k\|} \sim v_1$

Implementation :

Given $x_0 \in \mathbb{C}^n$,

For $k = 1, 2, \dots, n, \dots$

$$\hat{x}_k = A x_{k-1}$$

$$m_k = \max(\hat{x}_k)$$

$$x_k = \hat{x}_k / m_k$$

Define $\max(\cdot)$ so that
 $|\max(x)| = \|x\|_\infty$

Thm Suppose that $|\lambda_1| > |\lambda_2| \geq |\lambda_3| \geq \dots \geq |\lambda_n| \geq 0$

and $v_1^* x_0 \neq 0$ \longleftarrow almost always possible due to rounding error

then $|m_k - \lambda_1| = O\left(\left|\frac{\lambda_2}{\lambda_1}\right|^k\right)$

$$\left\| x_k - \left(\pm \frac{v_1}{\max(v_1)}\right) \right\| = O\left(\left|\frac{\lambda_2}{\lambda_1}\right|^k\right)$$

Pf: $m_k = \max(\hat{x}_k) = \frac{\max(A \hat{x}_{k-1})}{\max(\hat{x}_{k-1})}$

$$= \frac{\max(A^2 \hat{x}_{k-2})}{\max(A \hat{x}_{k-2})} = \dots = \frac{\max(A^k x_0)}{\max(A^{k-1} x_0)}$$

Now let $x_0 = a_1 v_1 + \dots + a_n v_n$, then

$$m_k = \lambda_1 \frac{\max\left(a_1 v_1 + \sum_{i=2}^n \left(\frac{\lambda_i}{\lambda_1}\right)^k a_i v_i\right)}{\max\left(a_1 v_1 + \sum_{i=1}^n \left(\frac{\lambda_i}{\lambda_1}\right)^{k-1} a_i v_i\right)} = \lambda_1 (1 + O\left(\left|\frac{\lambda_2}{\lambda_1}\right|^k\right))$$

Note that x_k is in the same direction as $A^k x_0$.

we have $x_k = \pm \frac{A^k x_0}{\max(A^k x_0)}$ $\left(x_k = \frac{A x_{k-1}}{m_k} = \dots = \frac{A^k x_0}{m_k \dots m_1} \right)$

$$= \pm \frac{a_1 v_1 + \sum_{i=2}^n \left(\frac{\lambda_i}{\lambda_1}\right)^k a_i v_i}{\max(a_1 v_1 + \sum_{i=1}^n \left(\frac{\lambda_i}{\lambda_1}\right)^k a_i v_i)}$$

$$= \pm \frac{v_1}{\max |v_1|} + O\left(\left|\frac{\lambda_2}{\lambda_1}\right|^k\right) \quad \square$$

Remark:

1) If there are a number of linearly independent eig. vectors corresponding to the dominant eig. value, we still get convergence

If $\lambda_1 = \lambda_2 = \dots = \lambda_r$, $|\lambda_1| > |\lambda_{r+1}| \geq \dots \geq |\lambda_n| \geq 0$

then $A^k x_0 = \lambda_1^k \left[\sum_{i=1}^r a_i v_i + \sum_{i=r+1}^n \left(\frac{\lambda_i}{\lambda_1}\right)^k a_i v_i \right]$

$$\sim \lambda_1^k \left[\sum_{i=1}^r a_i v_i + O\left(\left|\frac{\lambda_{r+1}}{\lambda_1}\right|^k\right) \right]$$

the limit of iteration lies in the subspace spanned by v_1, \dots, v_r and depends on x_0 .

2) If there are more than one eigenvalue with the same largest magnitude, the iterated vector does not converge.

Instead, it will oscillate. For example, when a real matrix has two conjugate dominate eigenvalues $(\lambda_1, \bar{\lambda}_1)$, starting with a real initial vector, all m_k 's are real and it is impossible to converge to λ_1 or $\bar{\lambda}_1$. Actually, it will oscillate between some real numbers related to λ_1 . Even though the outputs oscillate, it is still possible to extract the eigenvalues.

(See Wilkinson. The algebraic eigenvalue problems, p.579)

- Variants of power iteration

- Inverse iteration (Find the "smallest" eig. val / vector)

Suppose $|\lambda_1| \geq |\lambda_2| \geq \dots \geq |\lambda_{n-1}| > |\lambda_n| > 0$

$$v_1, v_2, \dots, v_{n-1}, v_n \in \mathbb{C}^n$$

Apply power iteration to A^{-1} to compute λ_n^{-1} and v_n

Implementation:

Given $x_0 \in \mathbb{C}^n$,

For $k = 1, 2, \dots, n, \dots$

Solve \hat{x}_k from $A \hat{x}_k = x_{k-1}$

$$m_k = \max(\hat{x}_k)$$

$$x_k = \hat{x}_k / m_k$$

- Shifted inverse power iteration
(Find eig. val. / vector near μ)

Suppose $\frac{1}{|\lambda_i - \mu|} > \frac{1}{|\lambda_j - \mu|}, \forall j \neq i \quad (\lambda_i \neq \mu)$

Apply inverse power iteration to $A - \mu I$

Remark: The convergence rate depends on how μ is close to λ_i . Shifted inverse power iteration can be used to find eigenvectors when we have a good approximation to some eigenvalues.

- Rayleigh quotient iteration

Power iteration is slow when $|\frac{\lambda_2}{\lambda_1}| \approx 1$.

Can we accelerate? When A is Hermitian, this is possible.

Need a better eig. val. estimator than $\max(Ax_k)$:

Def Given vector $x \in \mathbb{C}^n$, $R(x) = \frac{x^* A x}{x^* x}$ is called
the Rayleigh quotient of A at x

If (λ, v) is an eigenpair, $R(v) = \lambda$.

Let \tilde{v} be a perturbation to v , then Taylor expansion $R(\tilde{v})$

$$R(\tilde{v}) = \lambda + \underbrace{\nabla R(v)^* (\tilde{v} - v)}_{\text{when } A \text{ is real symmetric}} + O(\|\tilde{v} - v\|_2^2)$$

when A is real symmetric

$$\nabla R(v) = \frac{v^T v (2Av) - v^T A v (2v)}{(v^T v)^2}$$

$$\begin{aligned} \|\tilde{v}\|_2 = 1 \\ &= \frac{2(Av - R(v)v)}{(v^T v)^2} = 0 \end{aligned}$$

We can use $R(x)$ as our eig. val. estimator in power iteration.

Implementation:

Given $x_0 \in \mathbb{C}^n$,

For $k = 1, 2, \dots, n, \dots$

$$\hat{x}_k = Ax_{k-1} \quad (\Delta)$$

$$x_k = \hat{x}_k / \|\hat{x}_k\|_2$$

$$m_k = R(x_k)$$

Thm For general $A \in \mathbb{C}^{n \times n}$, with $|\lambda_1| > |\lambda_2| \geq \dots \geq |\lambda_n|$
 v_1, v_2, \dots, v_n
the iteration (4) satisfies

$$|m_k - \lambda_1| = O\left(\left|\frac{\lambda_2}{\lambda_1}\right|^k\right)$$

$$\|x_k - \pm v_1\| = O\left(\left|\frac{\lambda_2}{\lambda_1}\right|^k\right)$$

Furthermore, when A is normal, we have

$$|m_k - \lambda_1| = O\left(\left|\frac{\lambda_2}{\lambda_1}\right|^{2k}\right)$$

Pf: $m_k = R(x_k) = \frac{(A^k x_0)^* A^{k+1} x_0}{(A^k x_0)^* A^k x_0}$

$$= \frac{\left(\sum_{i=1}^n \lambda_i^k a_i v_i\right)^* \left(\sum_{i=1}^n \lambda_i^{k+1} a_i v_i\right)}{\left(\sum_{i=1}^n \lambda_i^k a_i v_i\right)^* \left(\sum_{i=1}^n \lambda_i^k a_i v_i\right)}$$

Assume $A^* = A$
when $A^* \neq A$ →

orthonormality
of v_1, \dots, v_n

$$\frac{\sum_{i=1}^n |\lambda_i|^{2k} \lambda_i |a_i|^2}{\sum_{i=1}^n |\lambda_i|^{2k} |a_i|^2}$$

$$= \lambda_1 \left[1 + O\left(\left|\frac{\lambda_2}{\lambda_1}\right|^{2k}\right) \right]$$

□

Note that in shifted inverse power iteration, the linear

convergence rate is $\max_{i \neq j} \left| \frac{\lambda_j - \mu}{\lambda_i - \mu} \right|$. If we update μ

whenever we get a better estimate of λ_j , the convergence factor will decrease during iteration. ← there is a hope for superlinear convergence

Method: Rayleigh Quotient Iteration

Given $x_0 \in \mathbb{C}^n$,

For $k = 1, 2, \dots, n, \dots$

$$m_k = R(x_{k-1}) \quad (\text{RQI})$$

$$\text{Solve } (A - m_k I) \hat{x}_k = x_{k-1}$$

$$x_k = \hat{x}_k / \|\hat{x}_k\|_2$$

In practice, RQI doesn't suffer from

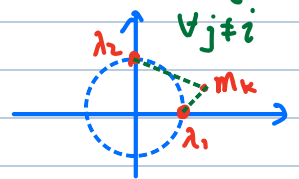
eig. vals of the same magnitude b.c. the shifting \rightarrow

Pick a random m_k .

"Almost surely" that
 $\exists i, s.t.$

$$|\lambda_i - m_k| < |\lambda_j - m_k|$$

$\forall j \neq i$



(RQI) almost always converges when it does (for good initial guess)

for general A , (RQI) converges locally quadratically

$$|m_k - \lambda_j| = O(|m_{k-1} - \lambda_j|^2)$$

$$\|x_k - \pm v_j\| = O(\|x_{k-1} - \pm v_j\|^2)$$

See Trefethen/Bau for an
illustrative proof

for Hermitian A , (RQI) converges globally, and locally cubically

$$|m_k - \lambda_j| = O(|m_{k-1} - \lambda_j|^3)$$

$$\|x_k - \pm v_j\| = O(\|x_{k-1} - \pm v_j\|^3)$$

• Simultaneous Power Iteration

How to get all $\lambda_1, \dots, \lambda_n$, and v_1, \dots, v_n ?

Idea: run power iteration on multiple vectors simultaneously

Given $Q_0 \in \mathbb{C}^{n \times n}$

For $k = 1, 2, \dots, n$

$$X_k = A Q_{k-1}$$

← power iteration

$$QR \text{ fact. } X_k = Q_k R_k$$

← orthonormalize vectors

$$T_k = Q_k^* A Q_k$$

← generalized Rayleigh Quotient

If the iteration "converges (e.g. $Q_k \rightarrow Q$ as $k \rightarrow +\infty$)"

$$\text{then } T := Q^* A Q \approx Q_k^* A Q_{k-1} = Q_k^* X_k = R_k \leftarrow \text{upper } \Delta$$

it is expected that T_k converges to the Schur form of A

This is guaranteed by the following theorem

Thm Suppose that $|\lambda_1| > |\lambda_2| > \dots > |\lambda_n|$

and $Q^* A Q = T$ be Schur fact. of A

assume that Q_0 satisfies some non-deficiency conditions

(the leading principal minors of $Q_0^* Q_0$ are all nonzero)

$$\text{then } T_k \xrightarrow{k \rightarrow +\infty} T$$

In particular, when A is normal, $T_k \rightarrow \text{diag}(\lambda_1, \dots, \lambda_n)$

Let $\lambda_i^{(k)}$ be the i^{th} eig. val. of T_k . then

$$|\lambda_i^{(k)} - \lambda_i| \approx \left| \frac{\lambda_{i+1}}{\lambda_i} \right|^k, \forall i$$

See Golub - Van Loan
Matrix computations
Section 7.3.3 for a proof

lower Δ entries $\rightarrow |T_k|_{ij} \approx \frac{|\lambda_{j+1}|}{|\lambda_j|}, \forall i > j$

We can reformulate simultaneously power iteration

to get a clean form with T_k computed directly

$$\text{Note that } T_{k-1} = Q_{k-1}^* A Q_{k-1} = Q_{k-1}^* (A Q_{k-1}) = \underline{(Q_{k-1}^* Q_k)} \underline{R_k}$$

$$T_k = Q_k^* A Q_k = (Q_k^* A Q_{k-1}) (Q_{k-1}^* Q_k)$$

$$= \underline{R_k} \underline{(Q_{k-1}^* Q_k)}$$

that is, T_k is obtained from T_{k-1} by computing the QR of T_{k-1} and multiplying the factors together in reverse order.

• QR iteration:

Given $A \in \mathbb{C}^{n \times n}$, unitary $Q \in \mathbb{C}^{n \times n}$

$$T_0 = Q_0^* A Q_0$$

for $k=1, 2, \dots$

$$\text{QR fact. } T_{k-1} = Q_k R_k$$

$$T_k = R_k Q_k$$

Output T_k

Remark: 1) A single QR iteration cost $O(n^3)$ calculation for dense A
 2) Convergence is linear (when it exists).
 3) If eigenvalues are not distinct, QR iteration

Pure QR is prohibitively expensive

converges to block upper triangular form, where each block corresponds to a group of eigenvalues sharing the same magnitude, with its size equal to the number of such eigenvalues.

$$|\lambda_1| = |\lambda_2| = |\lambda_3| > |\lambda_4| = |\lambda_5| > |\lambda_6|$$

$$T_k \approx \begin{bmatrix} A_1^{(k)} & & \\ & A_2^{(k)*} & \\ & & \lambda_6 \end{bmatrix} \quad \text{when } k \gg 1$$

where $A_1^{(k)} \in \mathbb{C}^{3 \times 3}$, $A_2^{(k)} \in \mathbb{C}^{2 \times 2}$ neither converges