18,335/6-7310 Introduction to Numerical Methods

Course Overview

- · handouts, syllabus, psets, etc.
 - · Canvas + Piatta + Grade scope
 - · github.com/mitmath/18335
- · Optional Julia tutorial this Friday (Feb. 7) 4-5:30 pm@2-190
- · Parallel courses this semester (by Prof. Johnson)
 : 18. S190 Interdisciplinary Numerical Methods

Numerical analysis:

Fast algorithms for approximately solving 3 math + time + accuracy the groblem of continuous math"

Example: nonlinear equations

 $f: \mathbb{R} \to \mathbb{R}$, f is confinuous

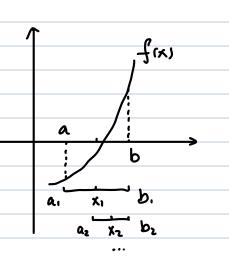
Find f(x) = 0

· f is a general polynomial of degree >5:

no root formula using +, -, x, +, "

- · Goal: approximately find the root using only + . . x . +
- · Naive method: Bisection method

$$x_n = \frac{a_n + b_n}{2}$$
if sign(f(xn)) = sign(f(a_n))
$$a_{n+1} = x_n , b_{n+1} = b_n$$
otherwise and = an, b_{n+1} = x_n



Error analysis:

$$e_n:=|\chi_n-\chi^*|\leq \frac{1}{2}(b_n-a_n)=\frac{b-a}{2^n} \rightarrow 0$$
 as $n\rightarrow +\infty$

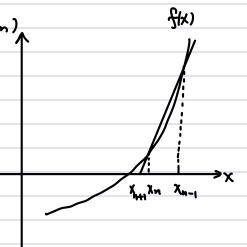
Can we do it faster? (Have only access to fix) Yes. One possible method:

· Secunt method

$$f(x) \approx f(x_n) + f'(x_n) (x - x_n)$$

$$\approx f(x_n) + \frac{f(x_n) - f(x_{n-1})}{x_n - x_{n-1}} (x - x_n)$$

$$\chi_{n+1} = \chi_n - \frac{f(\chi_n)(\chi_{n-1}\chi_{n-1})}{f(\chi_n) - f(\chi_{n-1})}$$



Error analysis:

$$= e_{n} - \frac{f(x_{n}) (e_{n} - e_{n-1})}{f(x_{n}) - f(x_{n-1})}$$

$$= \frac{f(x_{n}) e_{n-1} - f(x_{n-1}) e_{n}}{f(x_{n}) - f(x_{n-1})}$$

$$= \frac{f(x_{n}) e_{n}^{-1} - f(x_{n-1})}{f(x_{n}) - f(x_{n-1})}$$

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$$= \frac{f(x_{n}) e_{n}^{-1} - f(x_{n-1})}{f(x_{n}) - f(x_{n-1})} e_{n} e_{n-1}$$

$$= \frac{f(x_{n}) e_{n}^{-1} - f(x_{n-1})}{f(x_{n}) - f(x_{n-1})} e_{n}^{-1} + \frac{1}{2} \int_{0}^{\infty} f(x_{n}^{*}) e_{n}^{-1} - f(x_{n-1}) e_{n-1}^{-1}}{f(x_{n}) - f(x_{n-1})} e_{n}^{-1} + \frac{1}{2} \int_{0}^{\infty} f(x_{n}^{*}) e_{n}^{-1} - f(x_{n-1}) e_{n-1}^{-1}}{f(x_{n}) - f(x_{n-1})} e_{n}^{-1} + \frac{1}{2} \int_{0}^{\infty} f(x_{n}^{*}) e_{n}^{-1} - f(x_{n-1}) e_{n-1}^{-1}}{f(x_{n}) - f(x_{n-1})} e_{n}^{-1} + \frac{1}{2} \int_{0}^{\infty} f(x_{n}^{*}) e_{n}^{-1} - f(x_{n-1}) e_{n-1}^{-1}}{f(x_{n}) - f(x_{n-1})} e_{n}^{-1} + \frac{1}{2} \int_{0}^{\infty} f(x_{n}^{*}) e_{n}^{-1} - f(x_{n-1}) e_{n-1}^{-1}}{f(x_{n}) - f(x_{n-1})} e_{n}^{-1} + \frac{1}{2} \int_{0}^{\infty} f(x_{n}^{*}) e_{n}^{-1} - f(x_{n-1}) e_{n}^{-1}}{f(x_{n}) - f(x_{n-1})} e_{n}^{-1} + \frac{1}{2} \int_{0}^{\infty} f(x_{n}^{*}) e_{n}^{-1} - f(x_{n-1}) e_{n}^{-1}}{f(x_{n}) - f(x_{n-1})} e_{n}^{-1} + \frac{1}{2} \int_{0}^{\infty} f(x_{n}^{*}) e_{n}^{-1} - f(x_{n-1}) e_{n}^{-1}}{f(x_{n}) - f(x_{n-1})} e_{n}^{-1} - f(x_{n-1}) e_{n}^{-1}$$

We arrive at

$$e_{n+1} = e_{n} e_{n} - e_{n}$$

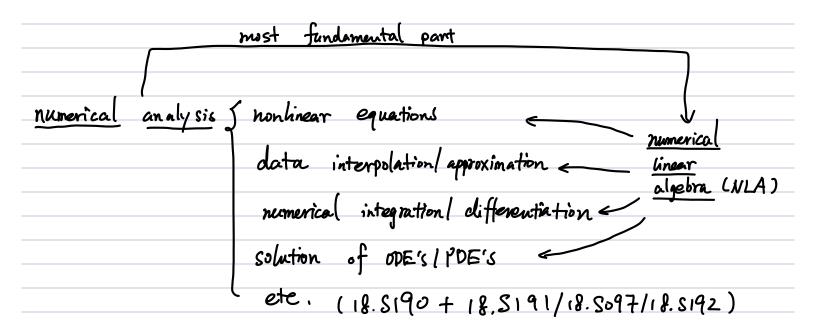
$$e_{n} = e_{n} e_{n} - f(x_{n}) - f(x_{n}) - f(x_{n}) e_{n}^{-1} - f(x_{n-1}) e_{n}^{-1}$$

$$e_{n} = e_{n} - f(x_{n}) - f(x_{n}) - f(x_{n}) e_{n}^{-1} - f(x_{n-1}) e_{n}^{-1}$$

We arrive at

$$e_{n+1} = e_{n} e_{n} - f(x_{n}) - f(x_{n}) e_{n}^{-1} - f(x_{n-1}) e_{n}^{-1} - f(x_{n-1}) e_{n}^{-1}$$

$$e_{n} = e_{n} - e_{n} - f(x_{n}) - f(x_{n}) - f(x_{n}) e_{n}^{-1} - f(x_{n-1}) e_{n}^{-1} - f(x_{n-1$$



Example: Numerical methods for PDEs

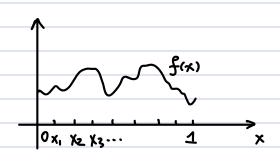
a) Poisson equations

$$\int \Delta u := \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f$$

$$u \partial \Omega = 0$$

In 1D,
$$\frac{d^2u}{dx^2} = f$$

$$u(o) = u(-i) = 0$$



Discretization:

$$u(x_i) \approx u_i$$

$$f(x_i) \approx f_i$$

$$h = x_{i+1} - x_i$$

$$\frac{d^2 u}{dx^2}(x_i) \approx \frac{u_{i+1} - 2u_i + u_{i-1}}{h^2}$$

$$\begin{bmatrix} -2 & 1 & & & \\ 1 & -2 & 1 & & \\ & & \ddots & & \\ & & & 1 & -2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} = h^2 \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_n \end{bmatrix}$$

Solve large linear system Au = f

$$-\Delta u + Vu = Eu$$

u: Wave function

V: potential

E: Quantized energy (eigenvalues)

· Discretization :

$$\frac{1}{h^{2}} \begin{bmatrix} 2+V_{1}h^{2} & -1 & & & \\ -1 & 2+V_{2}h^{2} & & & \\ & & & \\ & & & -1 & \\ & & & -1 & 2+V_{0}h^{2} \end{bmatrix} \begin{bmatrix} u_{1} \\ u_{2} \\ \vdots \\ u_{n} \end{bmatrix} = \begin{bmatrix} u_{1} \\ u_{2} \\ \vdots \\ u_{n} \end{bmatrix}$$

Solve large eigenvalue problems

Au= Eu

Dutline

fundamentals of numerical analysis

NLA

Given AER^{nxm} be R"

Solve Ax= b

Given A & Rnxn

Find all (1, x) s.t. Ax = //x

Krylov subspace methods

Other topics:

Nonlinear optimization Numerical integration FFT etc