# Time Series Modeling using Neural Networks

Dušan Fedorčák 11/2021 – RBI



### Background

- Ph.D. in computer science at VŠB-TU Ostrava
  - Neural networks & unsupervised self-organization
- Experienced in simulations
  - flood prediction system for MSK
  - traffic monitoring & prediction systems
- Experienced in computer graphics & scientific visualization
  - GIS related real-time 3D visualizations
- 5+ years in applied ML and artificial intelligence
  - Lead researcher in GoodAI general artificial intelligence
  - CTO in Neuron Soundware sound processing via Deep Learning
  - Lead ML in Merlon Intelligence Inc. natural language processing



#### Content

#### DAY 1

#### Classical time series analysis

- Decomposition of time series
- ARIMA models family
- State space models generalization

#### Theoretical window

- Neural Networks & Recurrent NNs
- Time series specifics

#### Practical examples

- Simple regression toy example
- Rainfall-runoff simulation regression

#### lunch break –

#### Practical examples

- Trampoline jumping classification
- Local Weather Forecast regression

#### DAY 2

#### Product Design & ML

- Integration of ML models into products
- Tips & tricks for debuging NNs

#### Practical Examples (in random order)

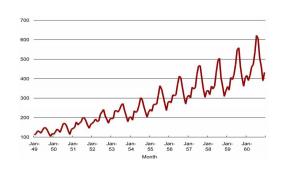
- Exoplanets Hunting
- Mobile Motion Sensing

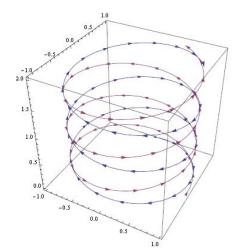
#### lunch break -

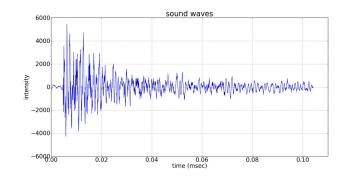
- Manufacturing Process Modeling
- Financial distress prediction
- Google Drive Folder with data
- GitHub repository with example sources



### Time series – example data



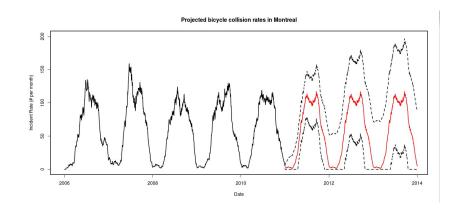


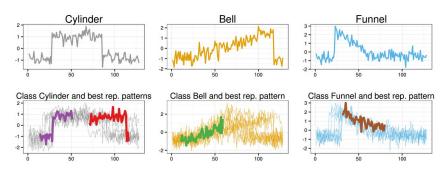


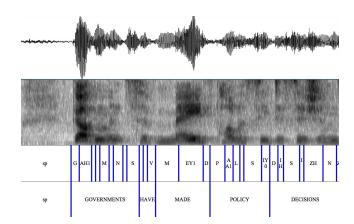


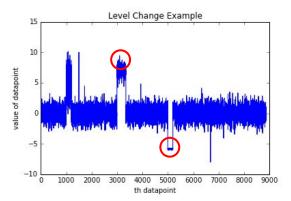


# Time series – example tasks





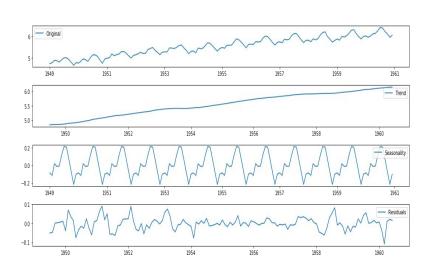


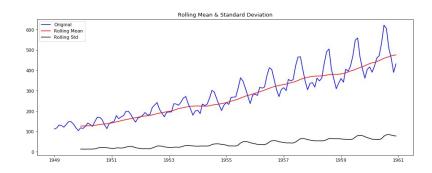


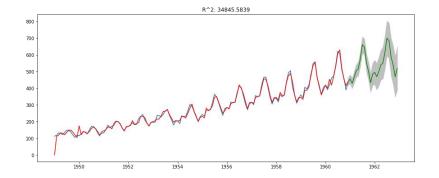


### Time Series – classical analysis & modeling

- Time Series Decomposition
  - Inflation, trend, seasonality, differencing
- ARIMA models
  - http://people.duke.edu/~rnau/411home.htm









### **State Space Models**

- State Space Models
  - A dynamic system that evolves over time
  - Knowing the current state of the model is enough to predict the future
  - The true state of the system might **not** be **directly observable**
- Model Description
  - State
  - State Equation
    - $\mathbf{x}_{t} = \mathbf{F}\mathbf{x}_{t-1} + N(0, \mathbf{Q})$  sometimes without noise
  - Observation Equation

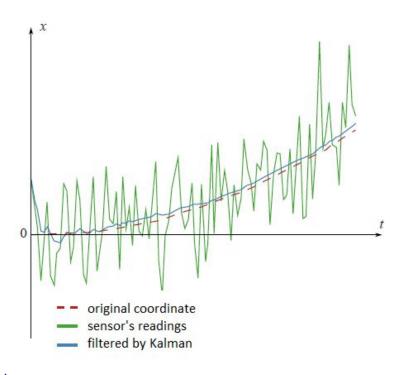


#### Kalman Filter

- Evolve state
  - $x'_t = Fx_{t-1}$   $P'_t = FP_{t-1}F^T + Q$
- Integrate observation

$$\circ \quad \mathbf{P_t} = (\mathbf{I} - \mathbf{K_t} \mathbf{H}) \; \mathbf{P'_t}$$

- Kalman Gain
  - $\circ K_t = P'_t H^T (HP'_t H^T + R)^{-1}$
- ARIMA and Kalman Filter
  - ARIMA can be viewed as a state space model
  - ARIMA can be fitted with MLE via Kalman Filter
  - o <a href="https://bookdown.org/rdpeng/timeseriesbook/maximum-likelihood-with-the-kalman-filter.html">https://bookdown.org/rdpeng/timeseriesbook/maximum-likelihood-with-the-kalman-filter.html</a>
  - https://towardsdatascience.com/the-kalman-filter-and-maximum-likelihood-9861666f6742





#### Hidden Markov Model

- Model Description
  - $\circ$  HMM ( $\lambda$ ) can be viewed as a state space model
  - Finite set of hidden states

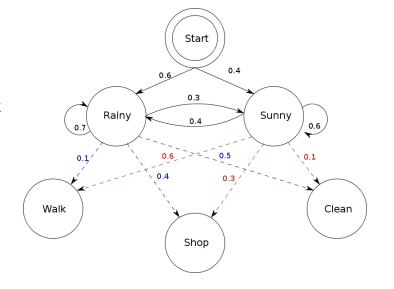
• 
$$\mathbf{Q} = \{q_1, q_2, ..., q_n\}, \ \boldsymbol{\pi} = \{\pi_1, \pi_2, ..., \pi_n\} - \text{init}$$

- $\mathbf{n}$  number of states (hyperparameter)
- Set of observations

$$\mathbf{O}_{i} = (o^{1}, o^{2}, o^{3}, ..., o^{T})$$

Transition probability matrix & emissions

■ 
$$A = (a_{00}, ..., a_{nn}), B = q_i \rightarrow 0$$



- Model Capabilities
  - $\circ$   $P(O|\lambda)$  Give prob. of **O** being produced by  $\lambda$  forward-backward alg.
  - $\circ$   $P(\mathbf{q}_1, ..., \mathbf{q}_t | \mathbf{O}, \lambda)$  Give most likely sequence of states for given  $\mathbf{O}$  Viterbi alg.
  - $\mathbf{O} \Rightarrow \lambda$  Model must be trainable with  $\mathbf{O}$  Baum-Welch alg.



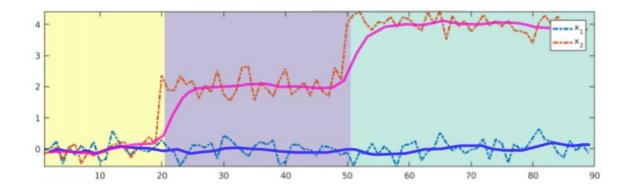
#### Kalman Filter vs. Hidden Markov Model

#### Kalman Filter

- Continuous state
- Generic state & observation equation
- Linear dynamic system
- Fusion of sensor readings and controls
- ARMA models implementation

#### Hidden Markov Model

- Discrete set of states
- N-states hyperparameter
- Emission & Transition tables
- Speech recognition
- Time series segmentation





### Time Series – goal in classical terminology

#### Forecasting

Given the past and the present observation, what will the future look like?

#### Time scale analysis

 Given the observations, what time scales dominate when observing temporal variation in the data

#### Filtering

Given the past and the present observation, how should I update my estimate of the true state of nature?

#### Smoothing

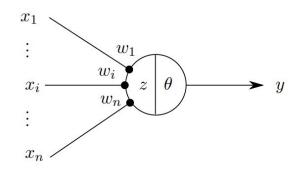
 Given a complete dataset, what can I infer about the true state of nature in the past?

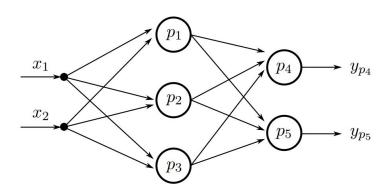
#### Regression

Given a time series of two phenomena, what is the association between them?



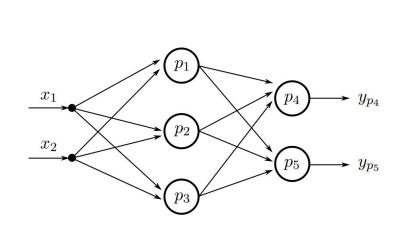
#### **Neural networks**

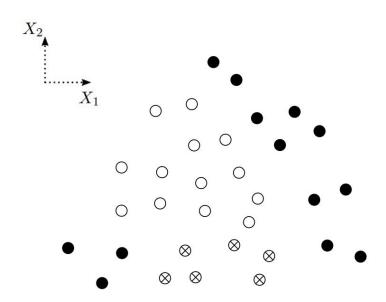




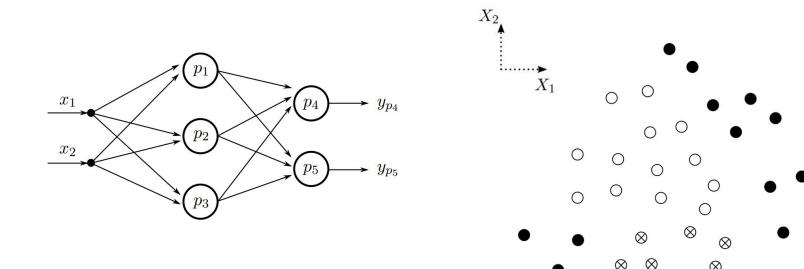
- Artificial Neural Cells
  - Linear combination of inputs
  - Non-linear activation function
- Connected Neurons
  - Directed graph
  - Layered structure
    - Dense connections
    - Convolutions & pooling
    - Recurrency, signal gates
    - Masking & attention heads
- Universal function approximator
  - Trainable with data
  - Backpropagation
  - Deep vs. shallow architecture





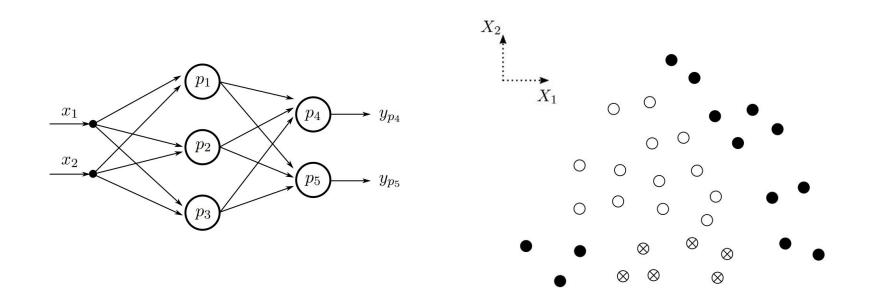






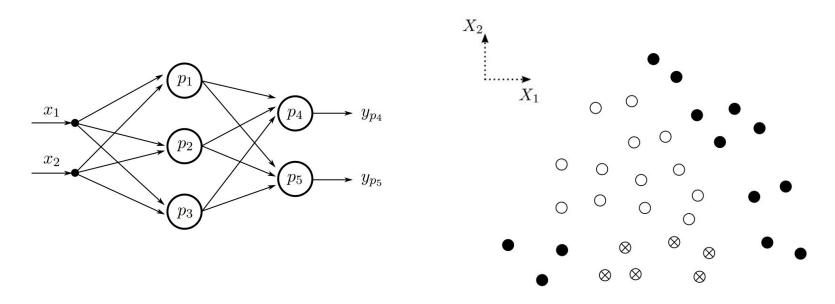
$$y = s(\sum w_i x_i - \theta)$$





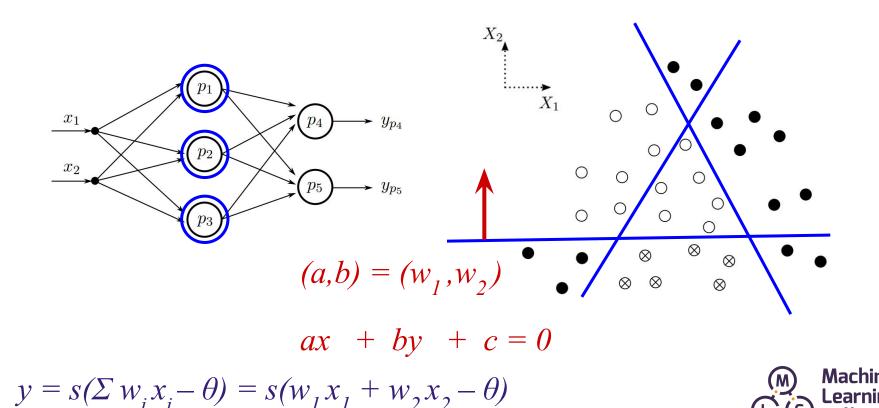
$$y = s(\Sigma w_i x_i - \theta) = s(w_1 x_1 + w_2 x_2 - \theta)$$

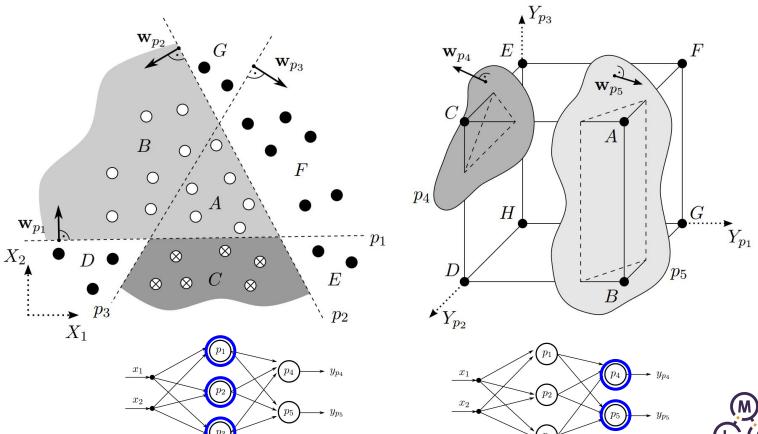




$$ax + by + c = 0$$
$$y = s(\sum w_{i}x_{i} - \theta) = s(w_{1}x_{1} + w_{2}x_{2} - \theta)$$

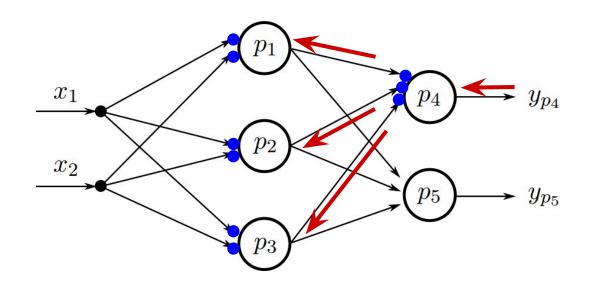






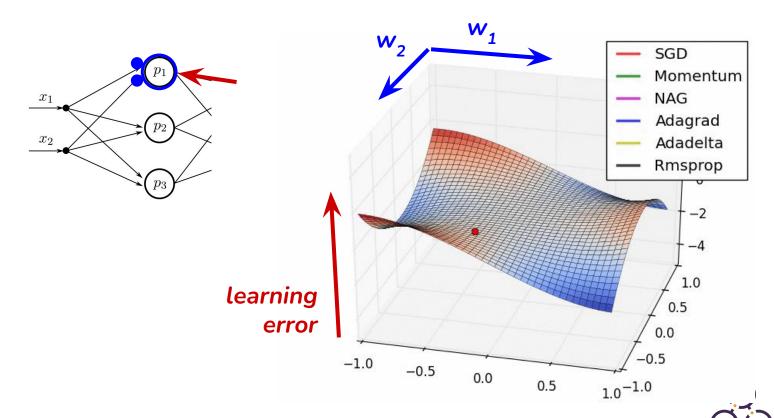
Machine

### Neural networks – Backpropagation





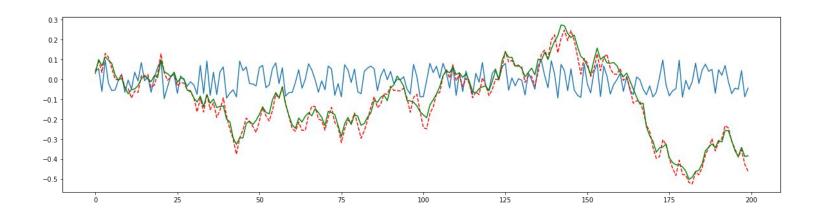
### Neural networks - Backpropagation



Machine

Learning College

#### Time Series with Neural Networks

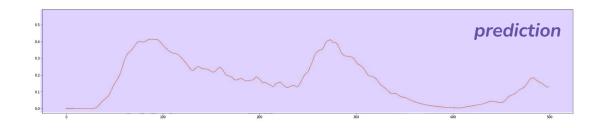


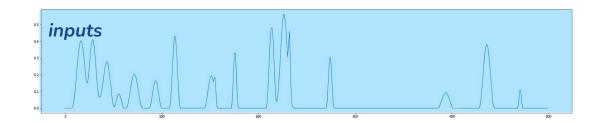
#### Neural Networks

- How to express time domain
- How to prepare training data
- How to design the model
- How to train & test the model

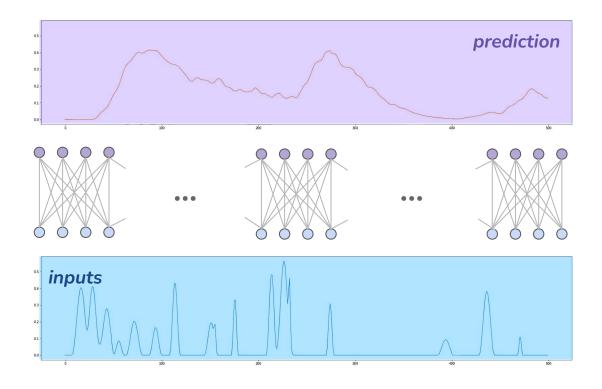


#### How neural network fits?

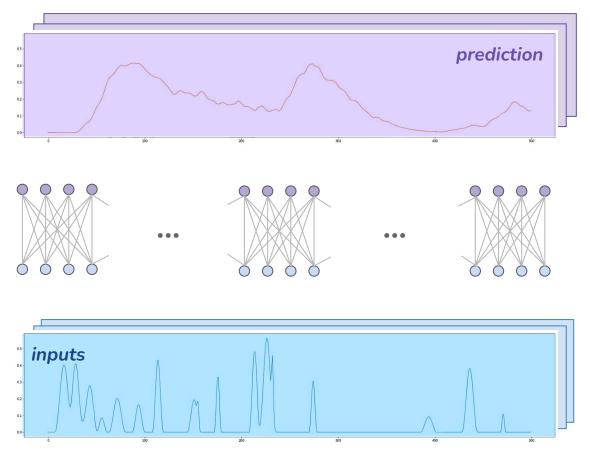




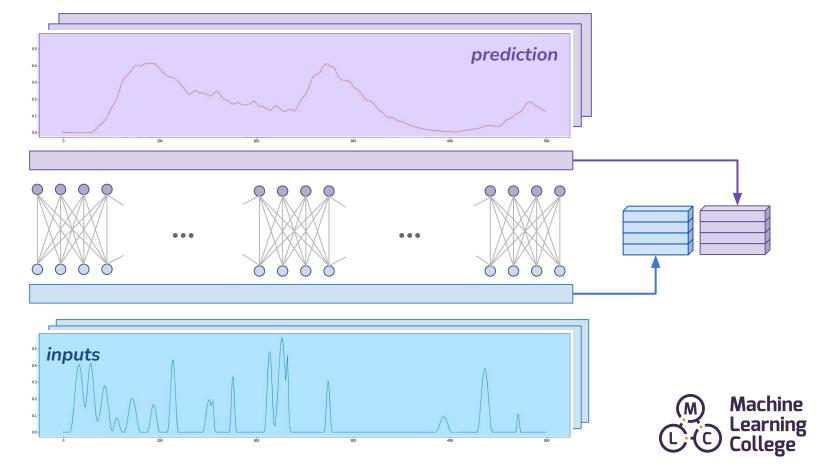


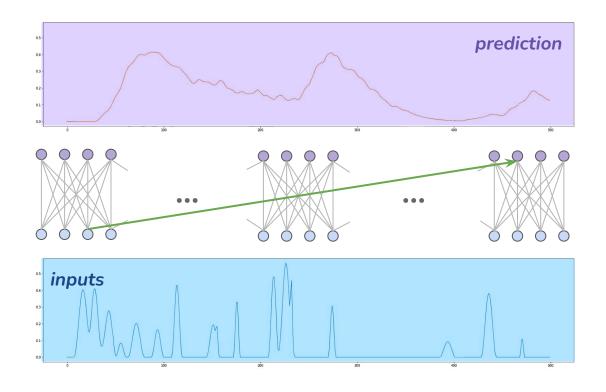




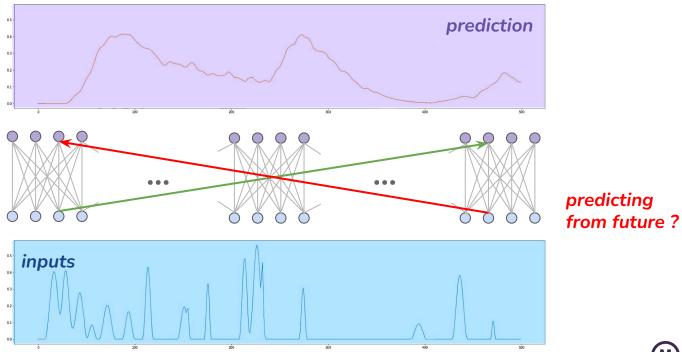




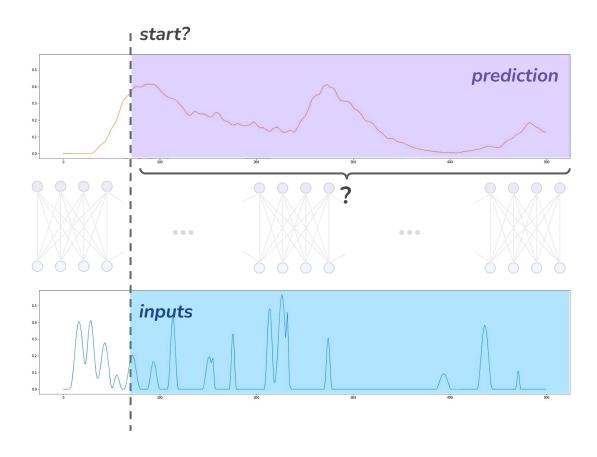




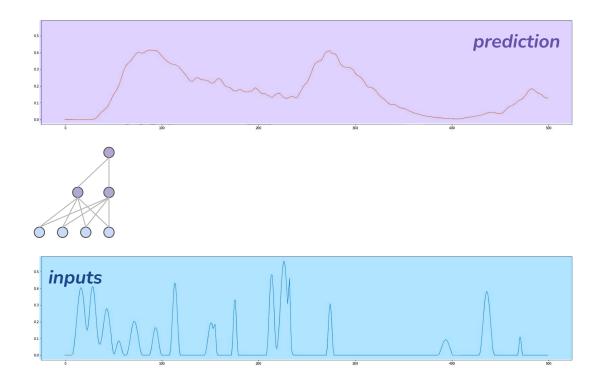




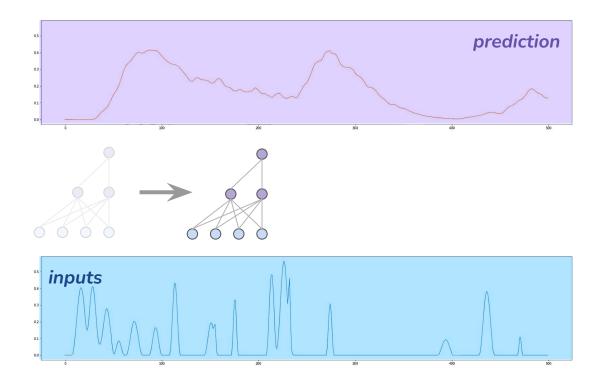




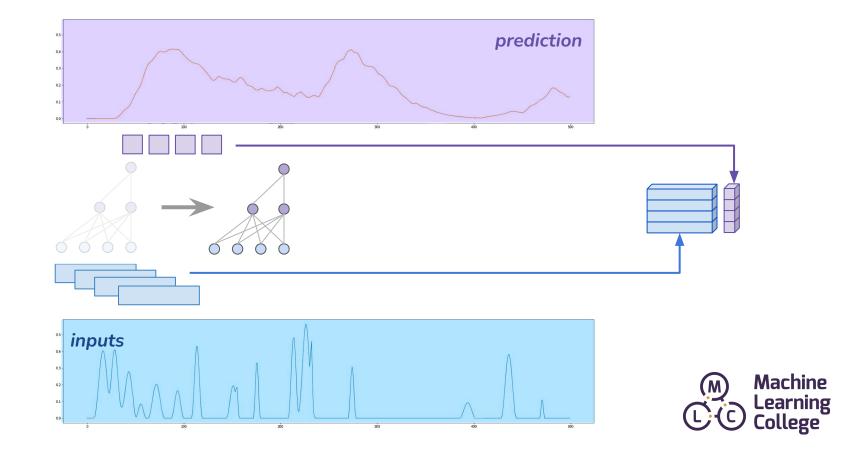


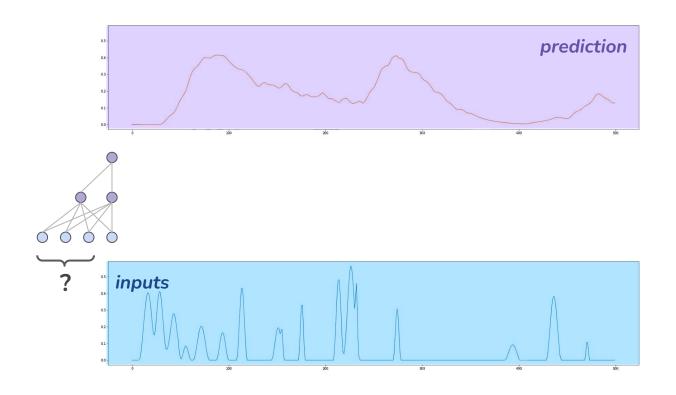




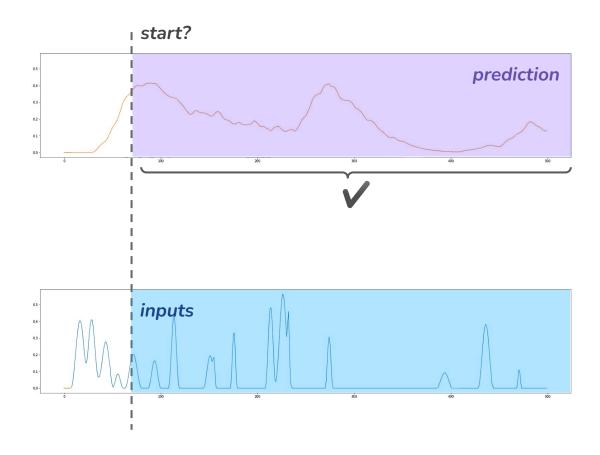




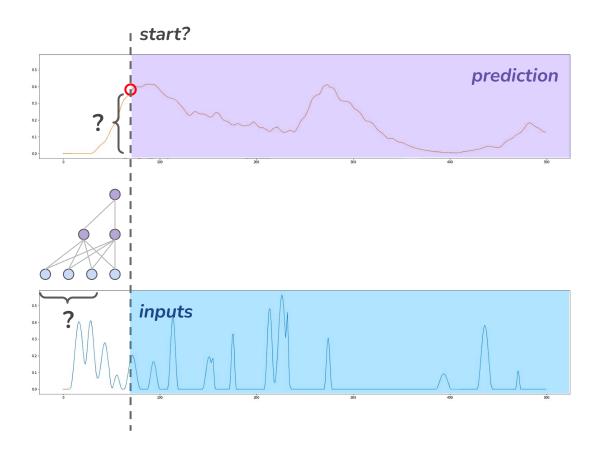






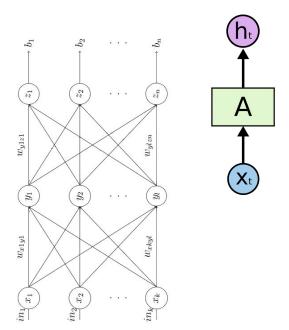


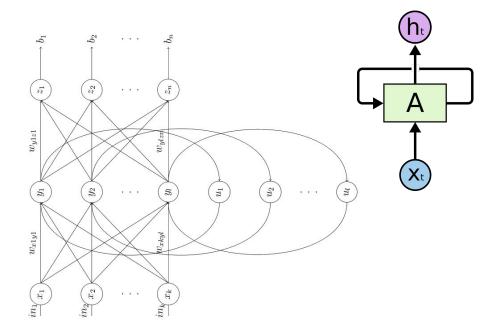






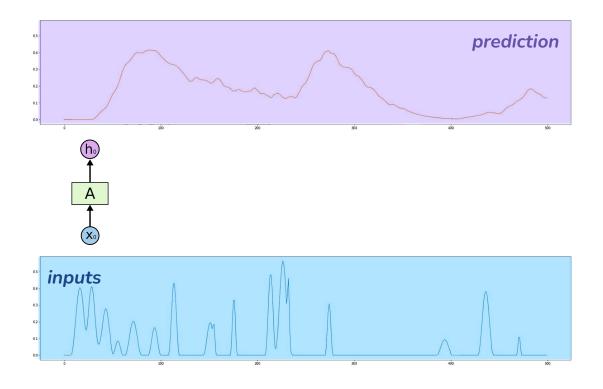
#### **Recurrent Neural Networks**







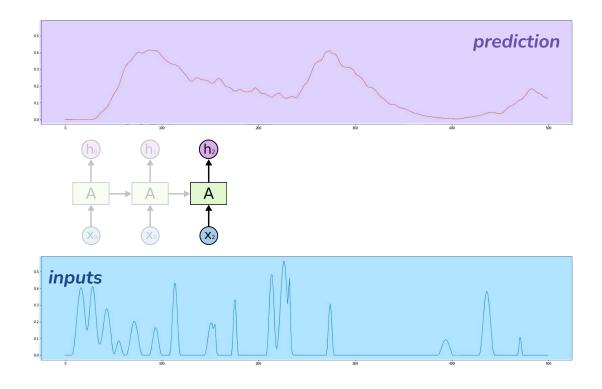
# **RNN** for time series prediction



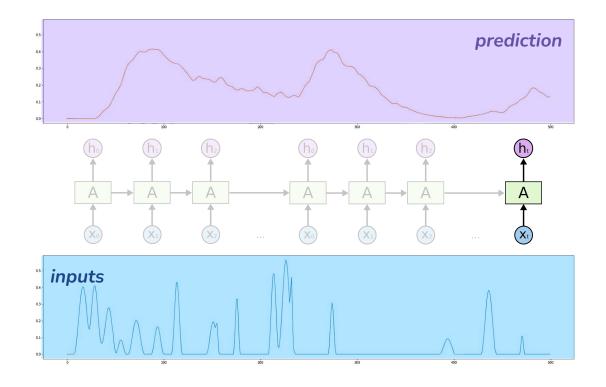




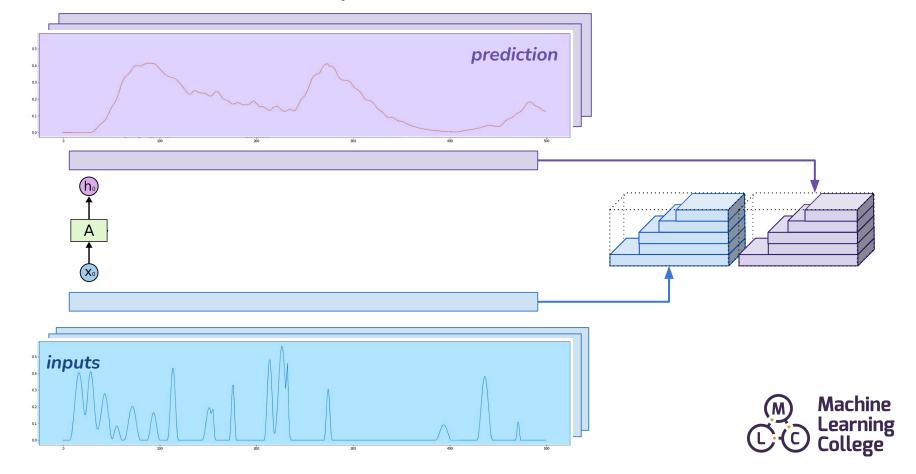


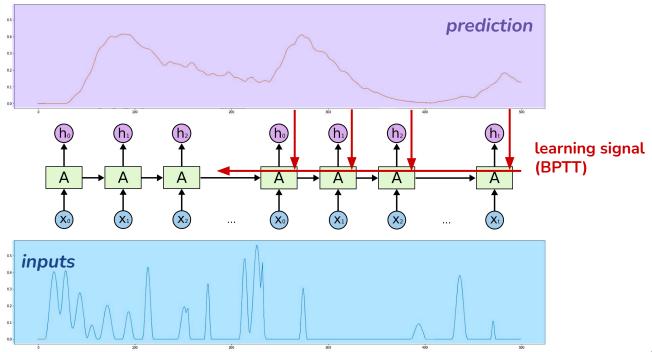






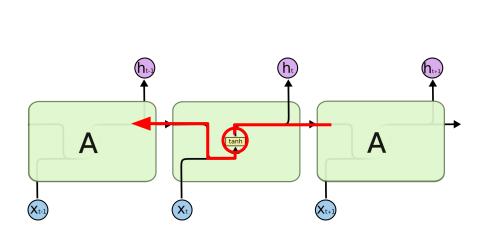


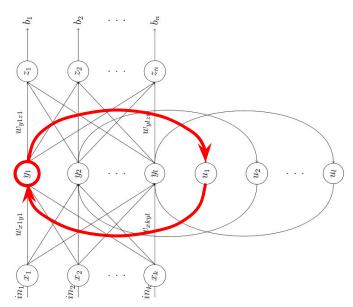






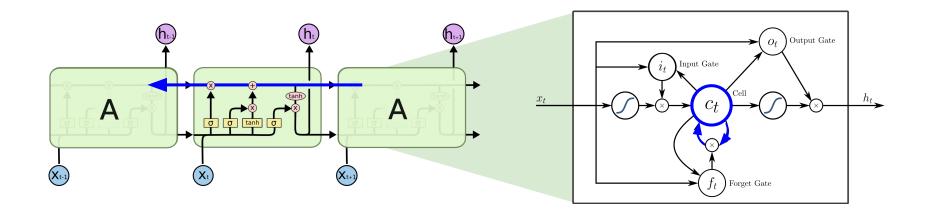
# RNN – Vanishing gradients





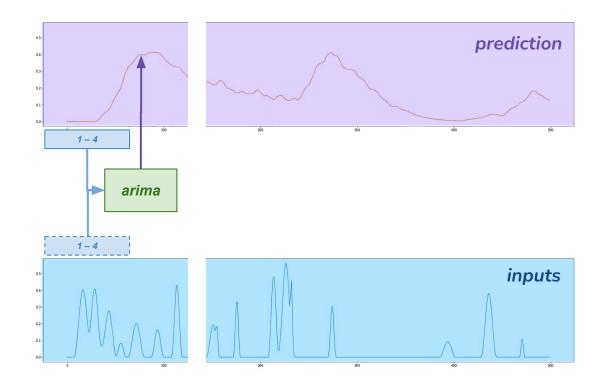


# **Long short-term memory – LSTM**



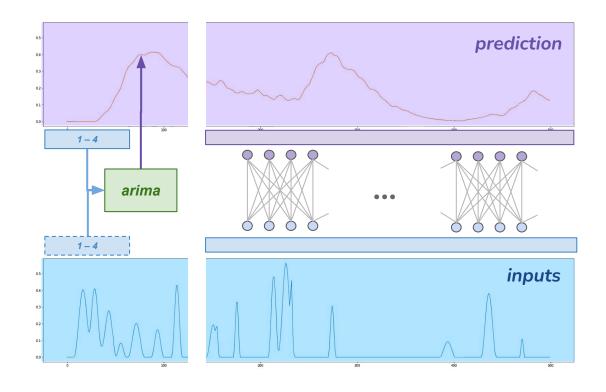


## Classical model vs. neural network



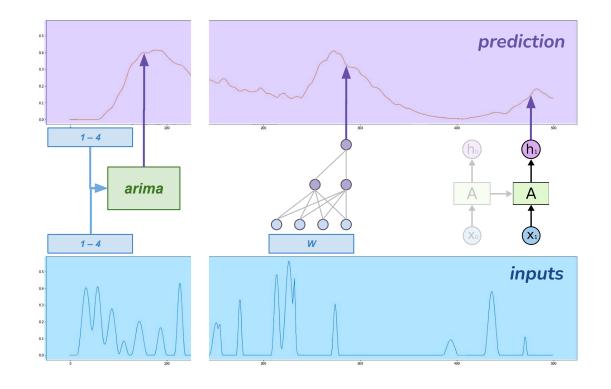


## Classical model vs. neutal network



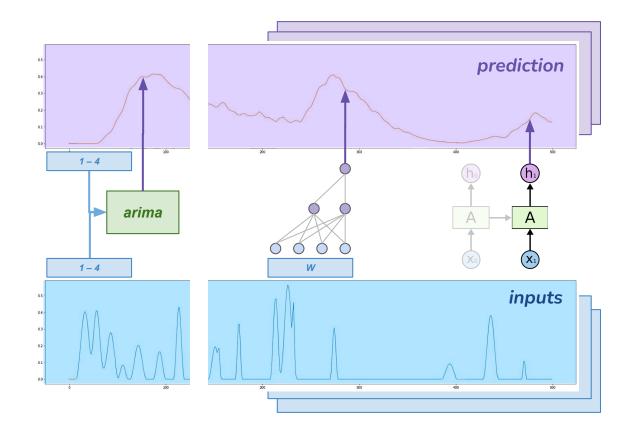


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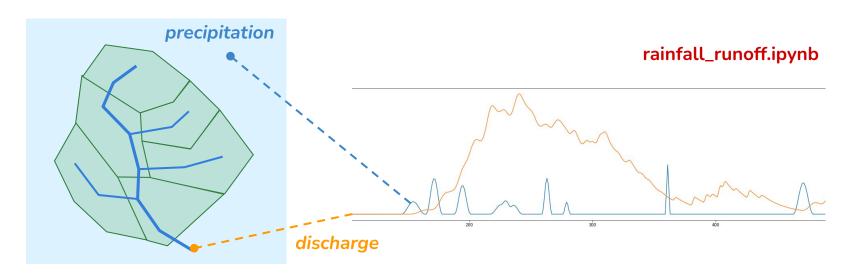


## Classical model vs. neutal network





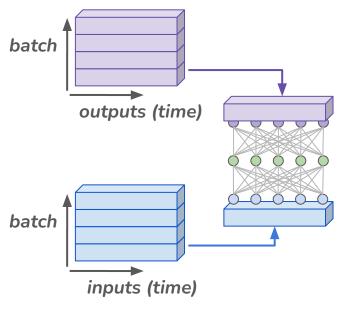
## Rainfall-runoff example



- Test out neural networks on simple generated rainfall-runoff dataset
  - Simulated long-time dependencies in data
  - Test various neural network architectures
    - Flat feed-forward network
    - LSTM



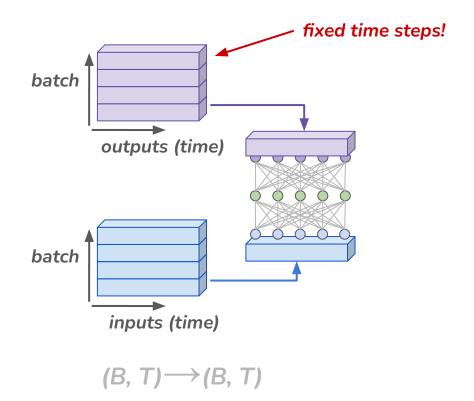
Flat NN = 2D training data





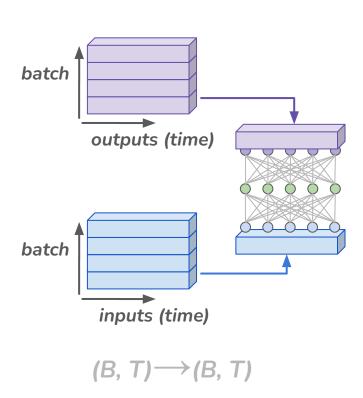


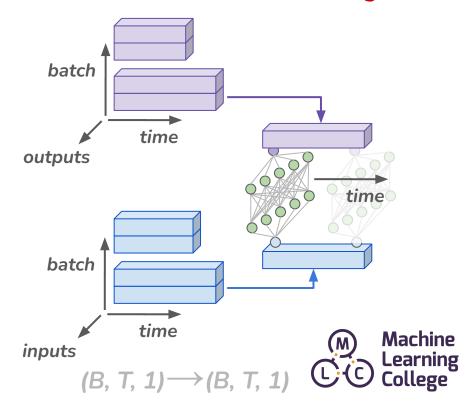
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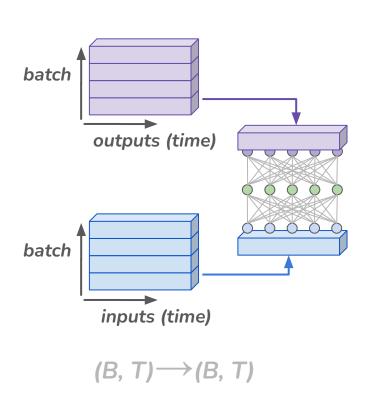


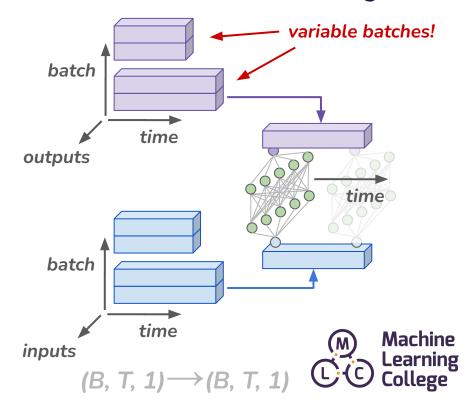
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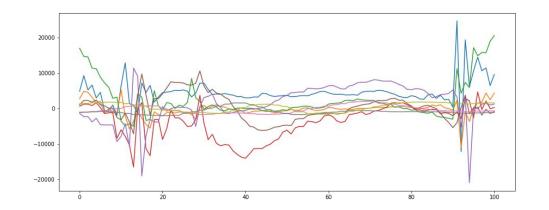
#### Flat NN = 2D training data





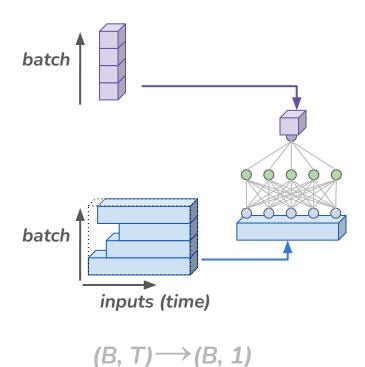
## Trampoline jumping example

- Data preparation
  - Dataset normalization
  - Sequence padding
- Binary classification task
  - Target values & dimensions
  - Loss functions
- Training & evaluation
  - Inference visualization
  - Evaluation metrics





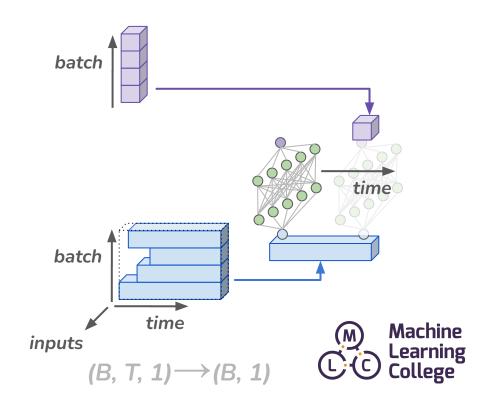
Flat NN = 2D training data





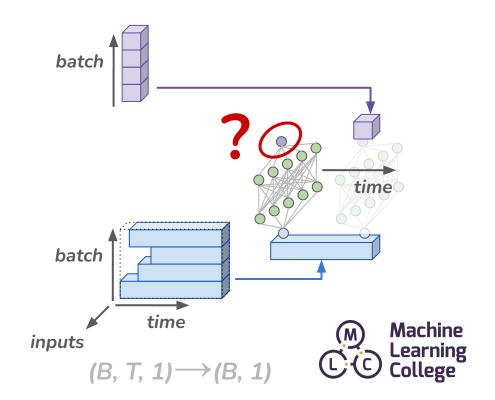
Flat NN = 2D training data

batch batch inputs (time)



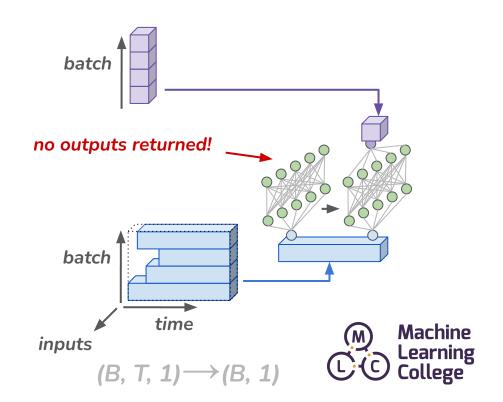
Flat NN = 2D training data

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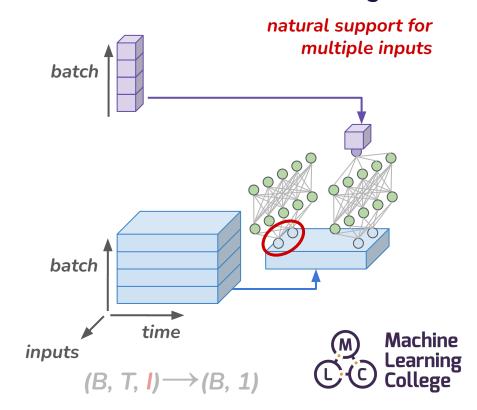
batch batch inputs (time)



## Tensors & dimentions – multivariate b. classification

Flat NN = 2D training data

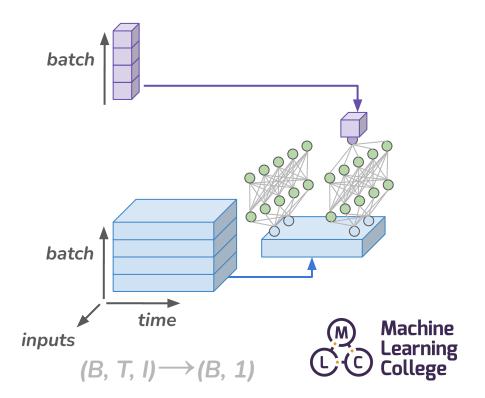
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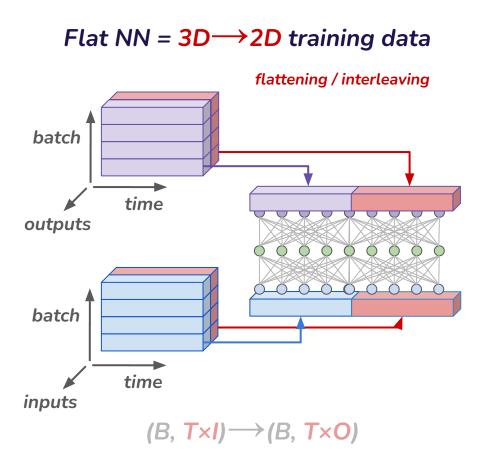


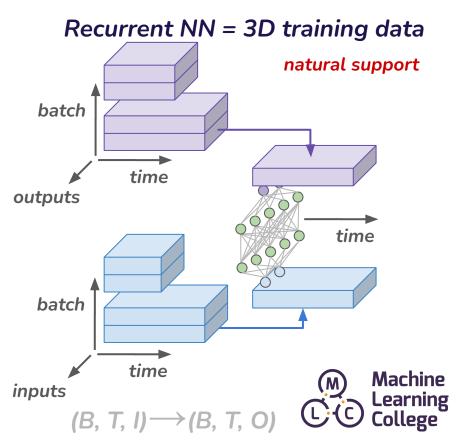
## Tensors & dimentions – multivariate b. classification

Flat  $NN = 3D \rightarrow 2D$  training data

flattening / interleaving batch outputs batch time inputs  $(B, \mathsf{T} \times \mathsf{I}) \longrightarrow (B, \mathsf{T} \times \mathsf{O})$ 







# Time Series Modeling using Neural Networks – DAY 2

Dušan Fedorčák 11/2021 – RBI



### Content

#### DAY 1

- Classical time series analysis
  - Decomposition of time series
  - ARIMA models family
  - State space models generalization
- Theoretical window
  - Neural Networks & Recurrent NNs
  - Time series specifics
- Practical examples
  - Simple regression toy example
  - Rainfall-runoff simulation regression
  - lunch break –
- Practical examples
  - Trampoline jumping classification
  - Local Weather Forecast regression

#### DAY 2

- Product Design & ML
  - Integration of ML models into products
- Practical Examples (in random order)
  - Exoplanets Hunting
  - Mobile Motion Sensing
  - lunch break –
- Tips & tricks for debuging NNs
- Practical Examples
  - Manufacturing Process Modeling
  - Financial distress prediction



## ML & Product Design – problems & decisions

- ML should solve problems
  - Al is cool ⇒ let's use it in the product! \*
  - We need to solve this problem  $\Rightarrow$  can we apply ML?  $\checkmark$
  - Q: What other means of solving the problem are available?



## ML & Product Design – problems & decisions

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- Problems vary in difficulty
  - $\circ$  Easily solvable by human  $\Rightarrow$  ML helps to scale up & automate
    - spam filter, face recognition, driving a car
  - $\circ$  Not easily solvable by human  $\Rightarrow$  ML can bring some solution
    - weather forecast, stock market prediction
  - Q: What are we optimizing for? (costs, risk reduction, better service, ...)



## ML & Product Design – problems & decisions

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  - Q: What are we optimizing for? (costs, risk reduction, better service, ... )
- Problems boils down to decisions
  - ML can assist with decisions
  - ML can automate decisions
  - Q: Could assistance model work for us or full automation is needed?



## ML & Product Design – automation

- ML solutions are imperfect
  - Expectation control & automation bias ⇒ trust issues
  - Scaling up implerfect models ⇒ quality issues
  - Right evaluation metrics model evaluation vs. UX evaluation
  - Q: Do all involved parties understand the problem & solution?
  - Q: Is there an evaluation metric everybody understands and agrees with?



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  - Q: Do all involved parties understand the problem & solution?
  - Q: Is there an evaluation metric everybody understands and agrees with?
- Black-box models are tricky
  - Black-box model + automation ⇒ trust issues
  - Expensive configurability & finetuning
  - Q: Can we build an understandable stress-test evaluation dataset?
  - Q: What tools or probes are avaiable for analysis of our learned black-box model?



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  - Right evaluation metrics model evaluation vs. UX evaluation
  - Q: Do all involved parties understand the problem & solution?
  - Q: Is there an evaluation metric everybody understands and agrees with?
- Black-box models are tricky
  - Black-box model + automation ⇒ trust issues
  - Expensive configurability & finetuning
  - Q: Can we build an understandable stress-test evaluation dataset?
  - Q: What tools or probes are avaiable for analysis of our learned black-box model?
- Assistance 
   ⇔ Automation there is a spectrum
  - 1. No automation
  - 2. Scored set of possible decisions
  - 3. Narrowed set of decision to approve
  - 4. Veto before automatic execution
  - 5. Full automation
  - Q: What is the lowest level of automation that brings value



## ML & Product Design – data analysis

- ML solutions depends on data
  - More complex models ⇒ more data required
  - Constant battle agaings overfitting
  - Distributions shift over time
  - Q: What data is available and will be available in the future



## ML & Product Design – data analysis

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  - Q: What data is available and will be available in the future
- Base rates in data influences products
  - Base rates can have unintuitive effects on the product
  - Sampling reality often produces imbalanced data
  - Q: What would be the performace of near-perfect model given the base rates



## ML & Product Design – data analysis

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#### Base rates in data influences products

- Base rates can have unintuitive effects on the product
- Sampling reality often produces imbalanced data
- Q: What would be the performace of near-perfect model given the base rates

#### All datasets are biased

- Inconsistency between data sampling and model goals
- Biased evaluation sets
- Q: Does our historical data reliably capture the goal of the model

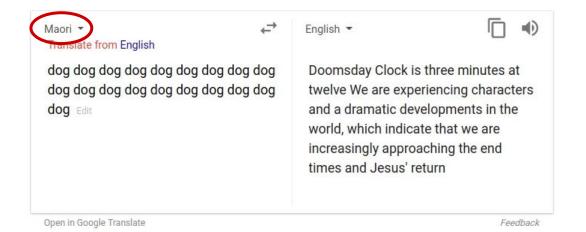


# Dataset issues – insufficient number of samples

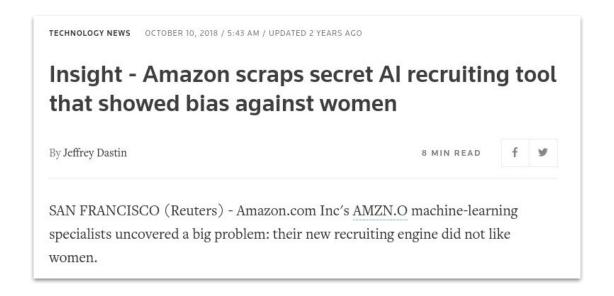




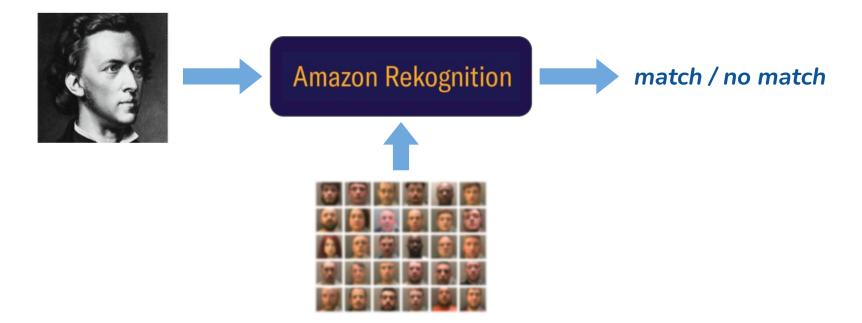
## Dataset issues – insufficient number of samples







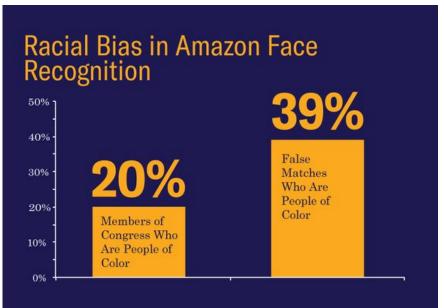














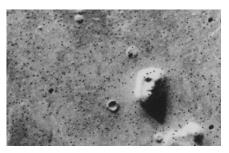
# **Human perception – overfitted to faces**











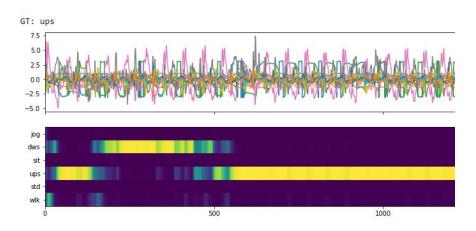






## Motion sensing example

- Data preparation
  - Dataset normalization
  - Slicing long sequences
- Categorical classification task
  - Predict activity type
  - Use correct activation & loss function
- Training & evaluation
  - Try different architectures
  - Evaluate resuslt with standard metrics
- Secondary task
  - Subject identification







- Known your data
  - Visualize everything you can
  - Try to find patterns ⇒ become the model yourself
  - Look for noisy labels / missing data
  - Make sure your preprocessing is correct (especially vectorized code)



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### • Simple models first

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- Build baseline models for comparison ⇒ even simple heuristics are useful



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#### Train iteratively

- Train without inputs ⇒ yields another baseline model
- Overfit one batch ⇒ something is off if you can't get zero loss
- Overfit the training set as far as you can



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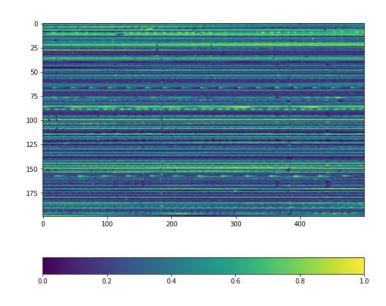
### Regularize

- Early stopping ⇒ best evaluation loss
- Make the model smaller ⇒ less space for overfitting
- Get more training data ⇒ more labels, data augmentation, pre-training



### **Exoplanets hunting example**

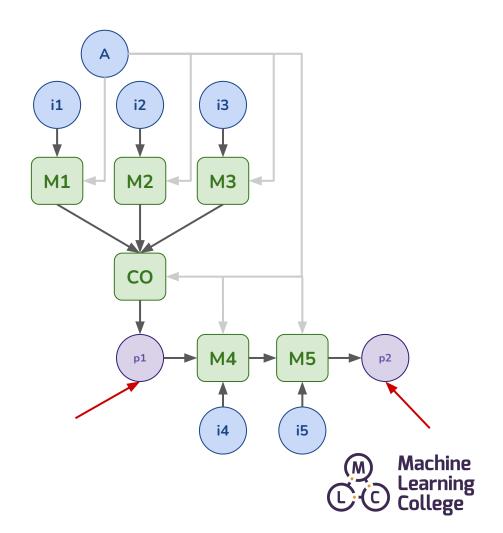
- Data preparation
  - Dataset normalization
  - Highly imbalanced dataset
- Binary classification/detection task
  - Detect starts with planets
- Model architecture
  - Dense, LSTM, Bidir. LSTM, CNN
- Training & evaluation
  - Use right evaluation metrics for imbalanced datasets



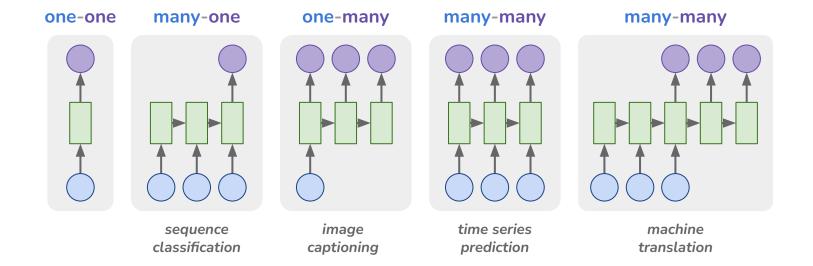


## Factory process example

- Data preparation
  - Dealing with missing values
  - Dataset normalization
  - Slicing long sequences
- Regression task
  - Predict target variables in future
- Model architecture
  - Model architecture mimics the process
- Training & evaluation
  - Masking out missing labels with custom loss function

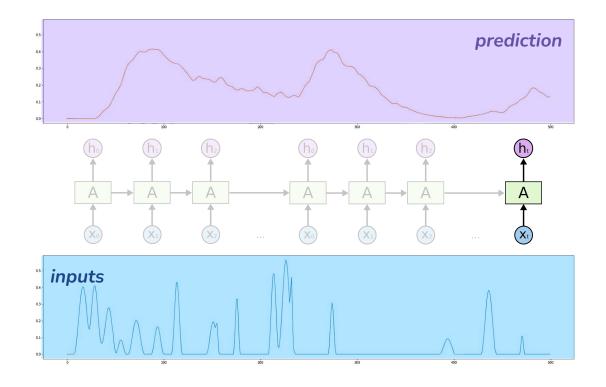


## RNN and sequence data



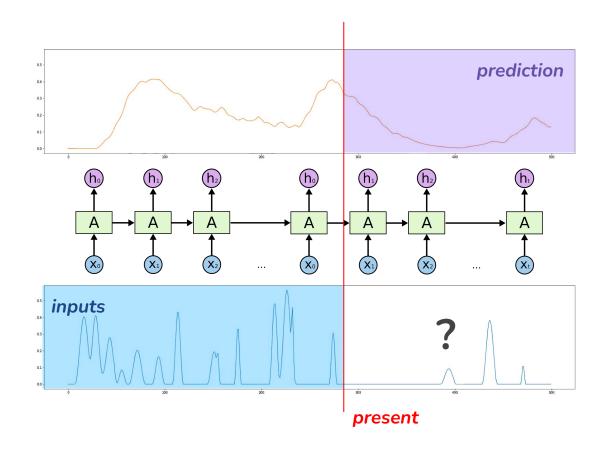


# RNN for time series prediction



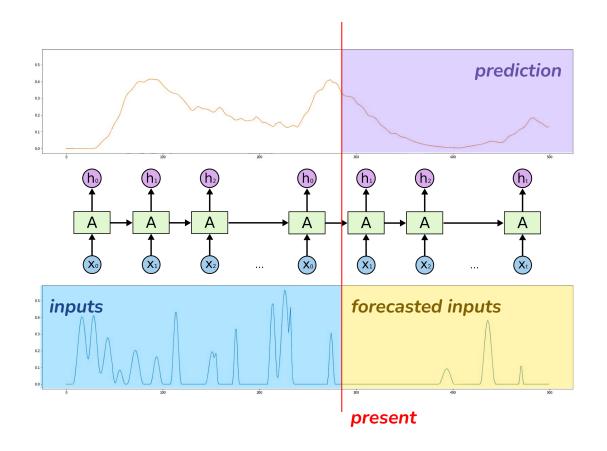


# Forecasting from input variables



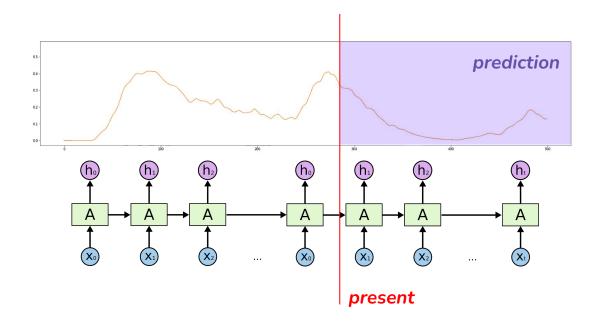


# Forecasting from input variables



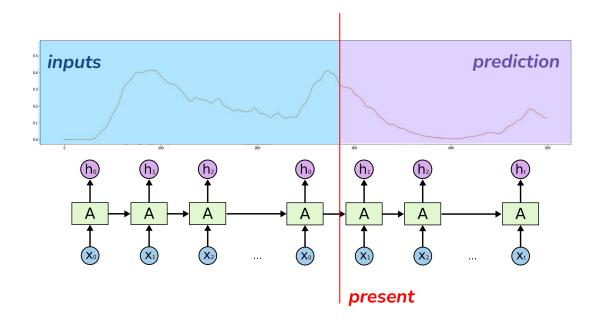


## Forecasting from historical values



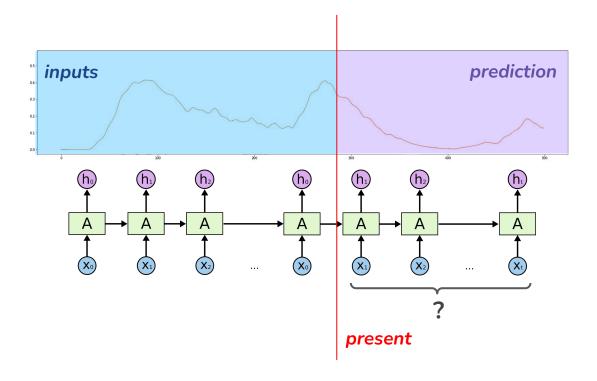


## Forecasting from historical values



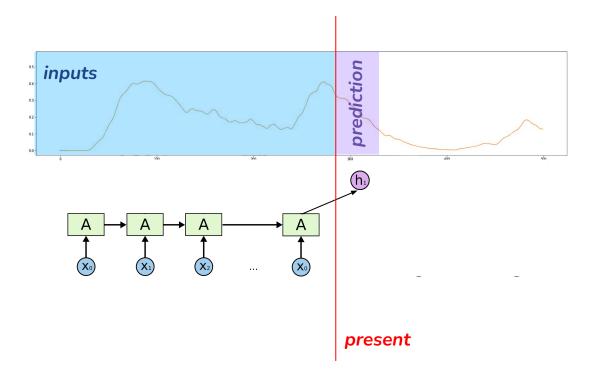


# Forecasting from historical values



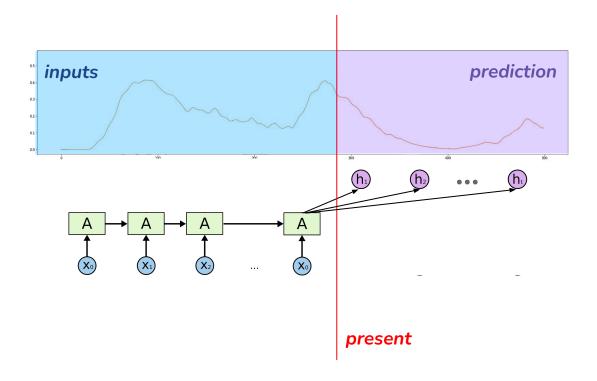


# Forecasting – one step ahead



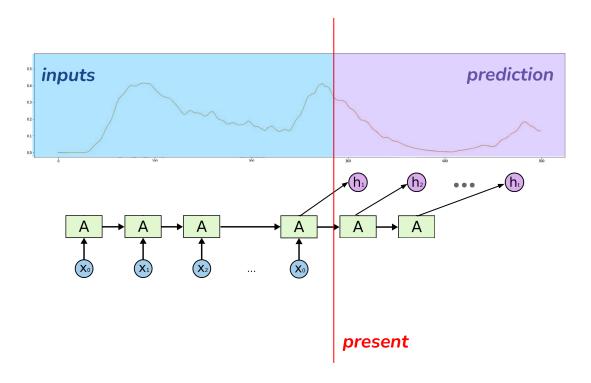


## Forecasting – flat multi-step prediction



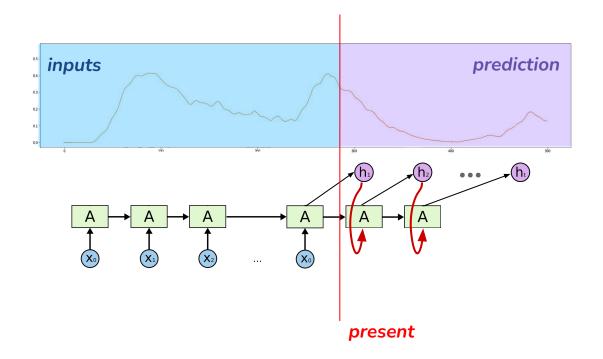


## Forecasting – developed multi-step predition



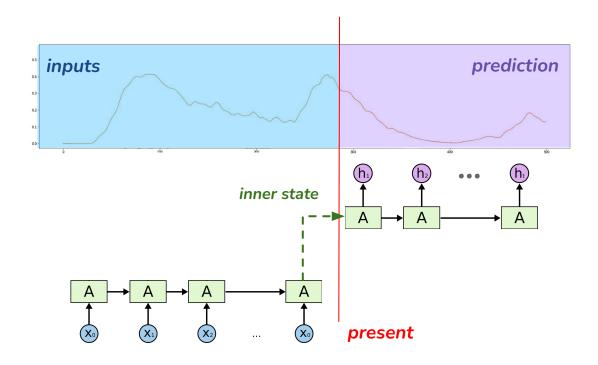


# Forecasting – developed multi-step predition

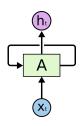


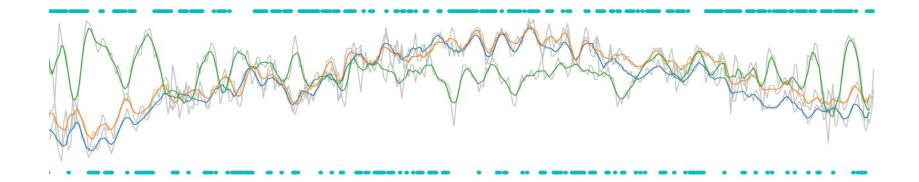


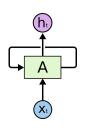
# Forecasting – encoder & decoder



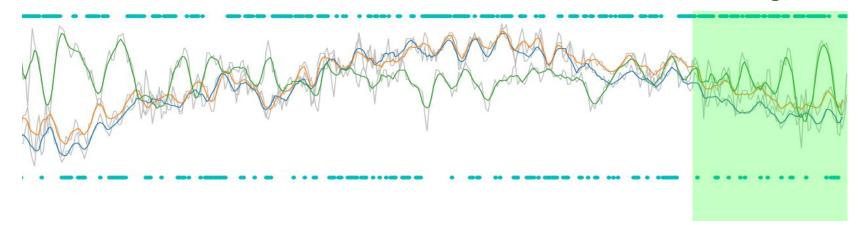


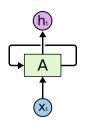




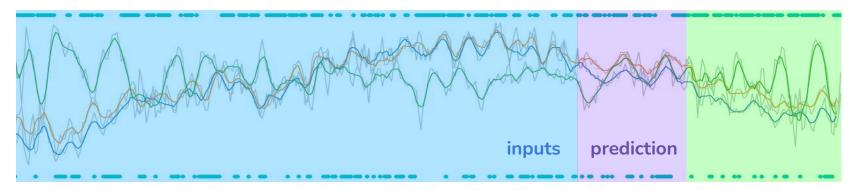


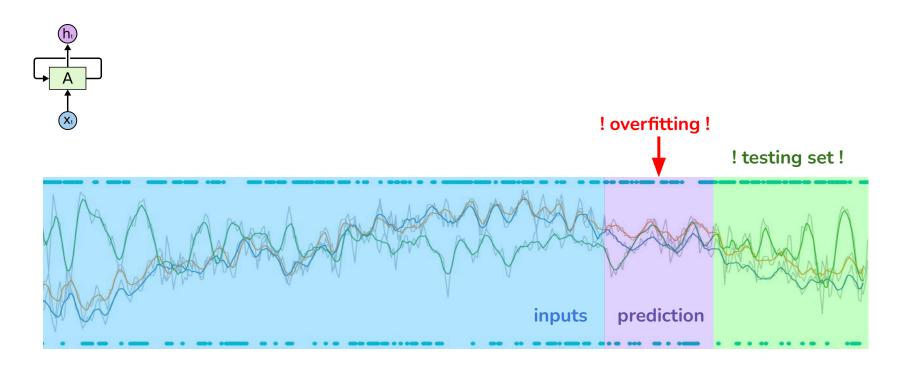
! testing set!

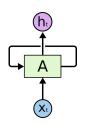




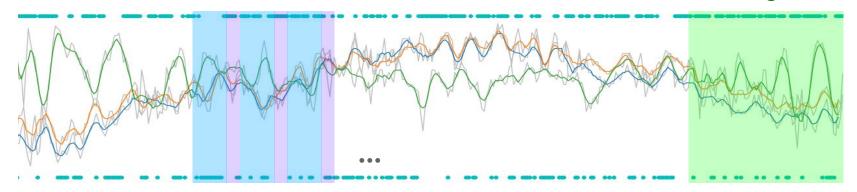
! testing set!

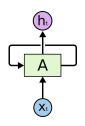




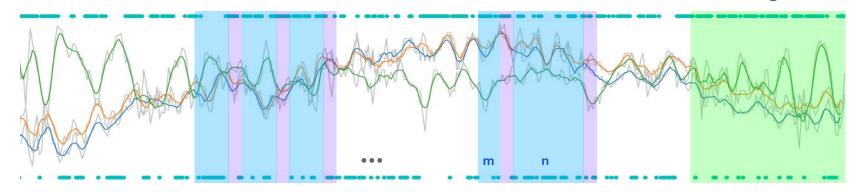


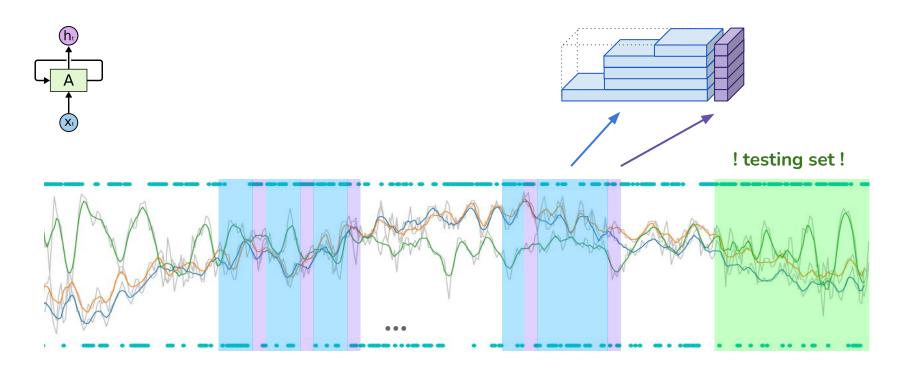
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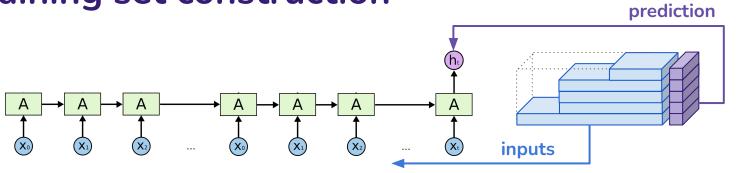




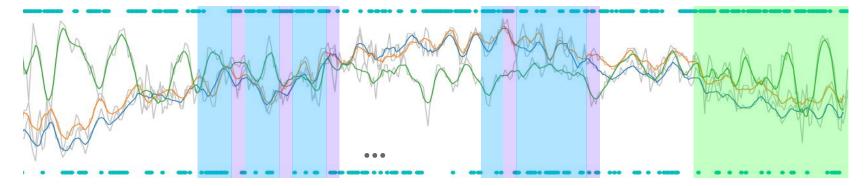
! testing set!



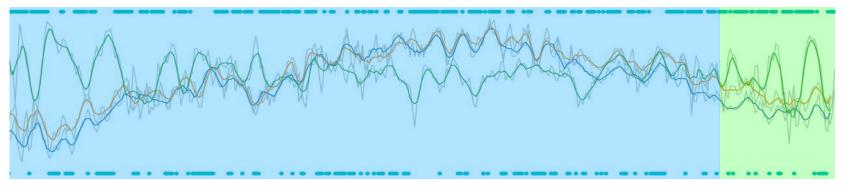


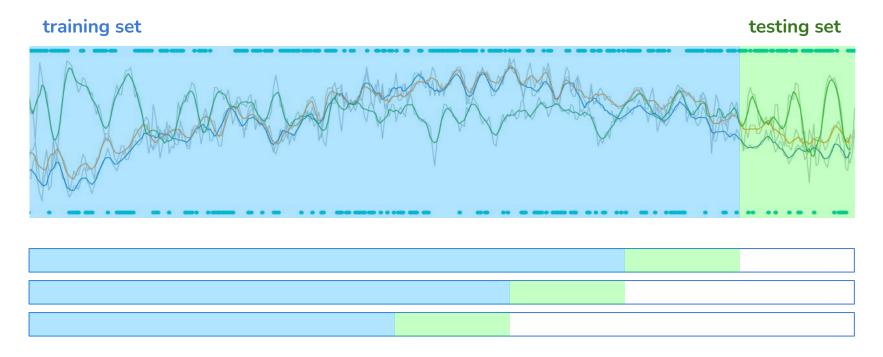


! testing set!

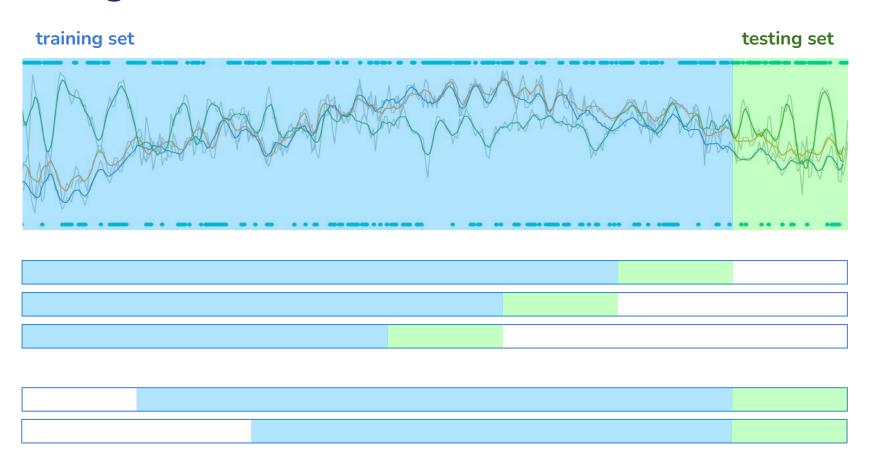






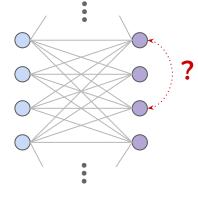


# Training set construction

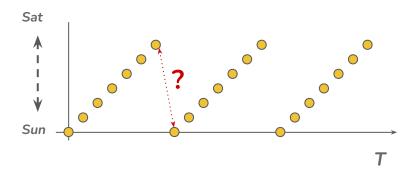


## Feature Encoding – Seasonal dummy variables

0	0	0	0
1	0	0	0
0	1	0	0
0	0	1	0
0	0	0	1
0	0	0	0
0	0	0	0
	1 0 0 0	1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	1 0 0   0 1 0   0 0 1   0 0 0   0 0 0

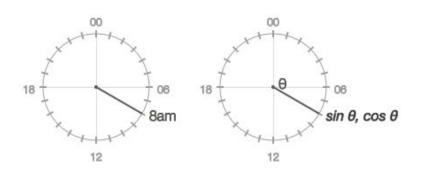


- (hour of day, day of week, ...)
- Numerical variables
- One-hot encoding

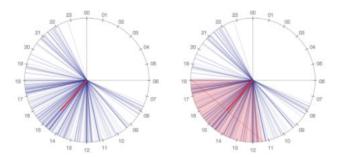


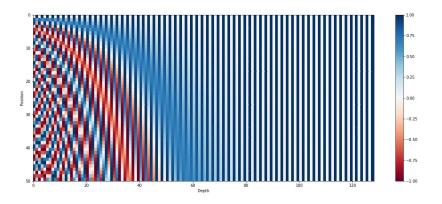
https://medium.com/life-at-hopper/ai-in-travel-part-2-representing-cyclic-and-geographic-features-4ada33dd0b22 https://kazemnejad.com/blog/transformer\_architecture\_positional\_encoding/

## Feature Encoding – Seasonal dummy variables



- Circular encoding
- Positional embedding (transformers)

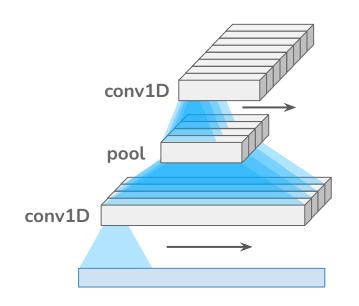


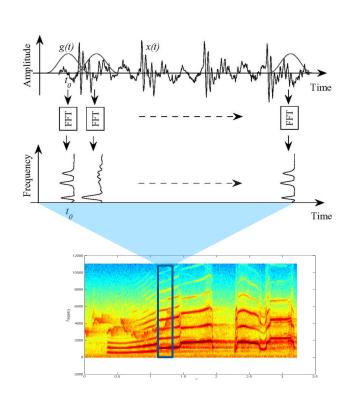


https://medium.com/life-at-hopper/ai-in-travel-part-2-representing-cyclic-and-geographic-features-4ada33dd0b22 https://kazemnejad.com/blog/transformer\_architecture\_positional\_encoding/

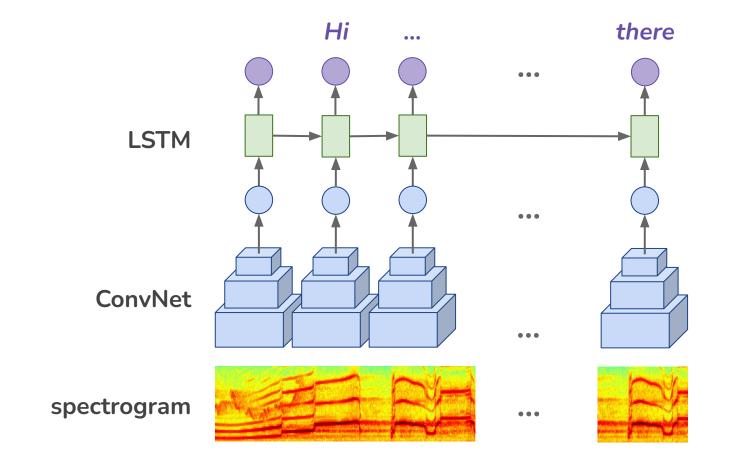
## Feature Encoding II

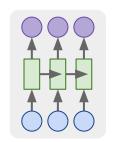
- Exchange for extra dimension
  - 1D Convolution & pooling
  - Short-Time Fourier Transform





### Advanced architectures







### ML Tips & Tricks

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### Additional learning materials

#### Classical time series

- <u>Time series course</u> a book-like explanation of basic principles of time-series and classical analysis
- Statistical forecasting detailed notes on classical time series analysis and ARIMA models

#### Keras

- Guides code examples for most of the basics in Keras
- <u>Examples</u> huge selection of code examples from different areas (time series, vision, ...)
- Blog good selection of advanced application of Keras on practical problems

### Interesting blogs

- Adam Geitgey Machine learning is fun great selection of simple examples from various areas
- Christopher Olah very well-described principles of neural networsk (with a lot of visual insights)
- Andrej Karpathy some very interesting insights (including the debug recipes for NNs)
- <u>Distill</u> Chris Olah and Shan Carter collaboration open problems in deep learning & advanced topics

### Tech companies blogs

- <u>DeepMind (Google)</u> top research in artificial intelligence usually acompanied with science papers
- OpenAl started as non-commercial research group / answer to Deepmind
- Facebook many interesting projects sometimes with free-to-use pre-learned models
- Amazon many interesting machine learning articles sometimes with detailed papers



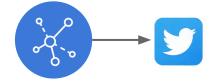
# Time series prediction from textual data





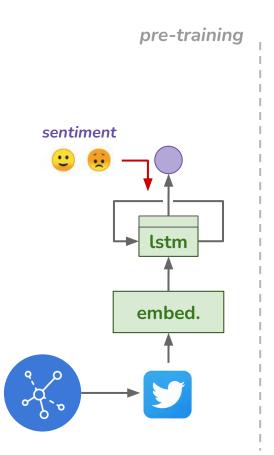
# Time series prediction from textual data







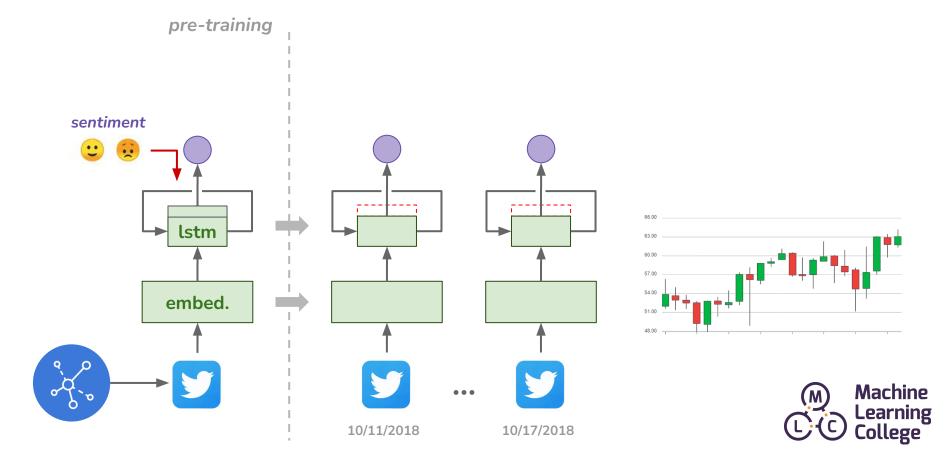
# Pre-training with additional data



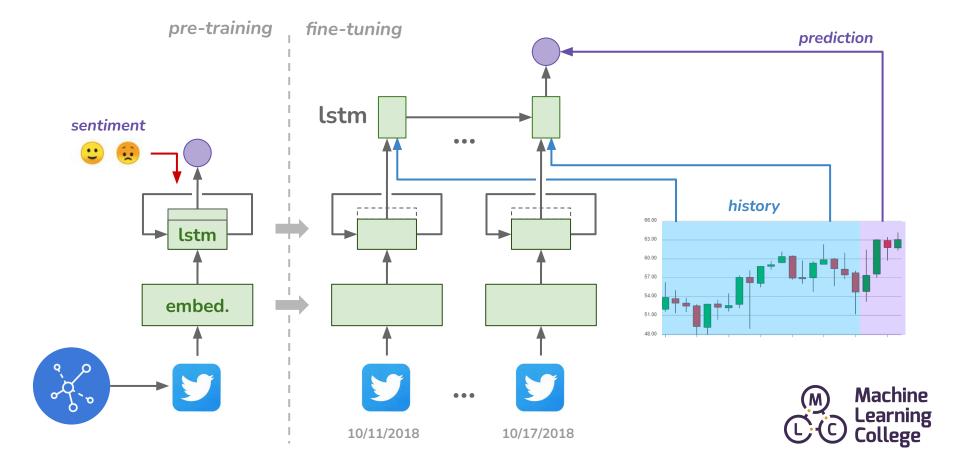




# Transfering model & exposing feature layer



# Fine-tuning with time series target data



# Fine-tuning with time series target data

