## COMPUTATIONAL ASPECTS OF SUB-INDEX AND SUB-FACTORS OF GROUPS

In order to study the upper periodic subsets and some functional equations on algebraic structures, we studied factor subsets of magmas, semigroups and groups, and direct product of two subsets. Then, we arrived at a challenging problem about factorization of (arbitrary) groups by subsets (Kourovka Notebook). Regarding right and left factor subsets of groups, we found that the index concept of subgroups can be extended for factors and then arbitrary subsets. In line with that idea, we correspond to every subset A of a group G the left and right sub-factors and also four sub-indices  $|G:A|^{\pm}$ ,  $|G:A|_{\pm}$ . We call A index stable if all of these sub-indices are equal (e.g., all subgroups and normal sub-semigroups). The topic has interesting applications for studying subsets of groups and it has some interactions to additive combinatorics and number theory. For defining them, we need to recall some concepts and notations from our paper.

We use G or  $(G, \cdot)$  for a group, A and B for subsets, and  $A^{-1}$  for the set  $\{a^{-1} : a \in A\}$ . Also, A is called symmetric if  $A = A^{-1}$ , and it is obvious that a non-empty subset is a subgroup if and only if it is a symmetric sub-semigroup.

The product AB is called direct and it is denoted by  $A \cdot B$  if the representation of each element xof AB as x = ab,  $a \in A$ ,  $b \in B$  is unique (we use A + B for additive notation that is direct sum of A and B). By the notation  $G = A \cdot B$  we mean G = AB so that the product AB is direct (a factorization of G by two subsets), and call A (resp. B) a left (resp. right) factor of G related to B (resp. A). We call A a factor (resp. two-sided factor) if it is a left or (resp. and) right factor. For example, every subgroup is a two-sided factor. A sub-semigroup of G is a factor if and only if it is a subgroup. Hence  $\mathbb{Z}$ ,  $\mathbb{Q}$  are factors of the additive group  $(\mathbb{R},+)$  (as the sense of factorization by subsets), and  $\mathbb{N}$ ,  $\mathbb{Q}^+$  are not its factors. Now, we define the left and right differences of A as follows:  $Dif_{\ell}(A) := A^{-1}A$ ,  $Dif_{r}(A) := AA^{-1}$ . Both  $Dif_{\ell}(A)$  and  $Dif_{r}(A)$  are symmetric and it is obvious that  $A \neq \emptyset$  is a subgroup if and only if  $Dif_{\ell}(A) = A$  (equivalently  $Dif_{r}(A) = A$ ). We call a subset A a left (resp. right) difference-generating set of G if  $Dif_{\ell}(A) = G$  (resp.  $Dif_{r}(A) = G$ ). It is clear that every left (and right) difference-generating set is a generating set (but the converse is not true). In general, if A is a left or right difference-generating subset, then both  $Dif_{\ell}(A)$  and  $Dif_r(A)$  are left and right difference-generating subsets. If  $Dif_\ell(A) = Dif_r(A)$ , then we denote it by Dif(A). For example, if A is symmetric, normal (i.e., gA = Ag for all  $g \in G$ ) or  $A^{-1} \subseteq N_G(A)$ , then  $Dif(A) = A^{-1}A = AA^{-1}$  (hence Dif(A) = A - A, if G is abelian). In particular, if A is a normal sub-semigroup of G, then Dif(A) is a subgroup. There are close relations between direct product of subsets and their differences. It is easy to see that the following statements are equivalent:

- (i)  $AB = A \cdot B$ , (ii)  $aB \cap a'B = \emptyset$ ; for all distinct elements  $a, a' \in A$ ,
- (iii)  $Dif_{\ell}(A) \cap Dif_{r}(B) = \{1\}$ , (iv)  $Ab \cap Ab' = \emptyset$ ; for all distinct elements  $b, b' \in B$ .

If G is finite, then the property |AB| = |A||B| is equivalent to the each of the above conditions.

Since  $Dif_{\ell}: 2^G \to 2^G$  is a function which maps each  $A \subseteq G$  to  $A^{-1}A \subseteq G$ , then we have the n-iteration of  $Dif_{\ell}$  denoted by  $Dif_{\ell}^n$ . Since  $Dif_{\ell}(A)$  is symmetric and  $(2^G, \cdot)$  is a semigroup, then  $Dif_{\ell}^n(A) = Dif_{\ell}(A)^{2^{n-1}}$ , for all  $n \ge 1$ .

For more detailed information, please refer to the papers [1] and [2]. Below, you'll find tables outlining concepts and their corresponding functions in GAP-codes, which can be used as usage instructions. The source code for these functions is stored in the "./lib" directory of the package.

Table 1: Factor, sub-factors, sub-indices and index stability of group subsets

| Title   | Notation in papers  | Notation in GAP-codes  | Definition or condition   | Remarks  |
|---|---|--|---|--|
| Multiplication of subsets                                       | AB  | $\mathrm{Mul}(G,A,B)$  | $\{ab:a\in A,b\in B\}$  | -  |
| Inverse of subset   | $A^{-1}$  | $\operatorname{Inv}(G,A)$  | $\{a^{-1}: a \in A\}$   | -  |
| Right, left<br>differences<br>of subsets                        | $Dif_r(A)$ , $Dif_\ell(A)$  | RD(G, A), $LD(G, A)$   | $A \operatorname{Inv}(G, A)$ , $\operatorname{Inv}(G, A)A$  | -  |
| Right, left<br>compli-<br>ments of<br>differences<br>of subsets | $\mathcal{C}_r(A) \; , \ \mathcal{C}_\ell(A)$   | RC(G, A) , $LC(G, A)$  | $G \setminus RD(G, A)$ , $G \setminus LD(G, A)$   | -  |
| Direct product of subsets                                       | $A \cdot B$   | $\operatorname{IsDirect}(G, A, B)$   | $=AB \text{ with }$ $\mathrm{LD}(G,A)\cap\mathrm{RD}(G,B)=\{1\}$  | equivalently $ AB  =  A  B $   |
| Factoriza-<br>tion by two<br>subsets                            | $G = A \cdot B$   | $\operatorname{IsFactorization}(G,A,B)$                                      | $G = AB$ with $LD(G, A) \cap RD(G, B) = \{1\}$  | A (B) is a left<br>(right) factor of G<br>related to B (A)   |
| The set of right, left factors of $G$ related to $A$            | $\operatorname{Fac}_r(G:A)$ , $\operatorname{Fac}_\ell(G:A)$  | $\operatorname{RF}(G,A)\;,$ $\operatorname{LF}(G,A)\;$                       | $\{B\subseteq G\ :\ G=A\cdot B\}\ ,$ $\{B\subseteq G\ :\ G=B\cdot A\}$  | The set of all $B \subseteq G$<br>s.t. $G = AB$ and $LD(G, A) \cap$<br>$RD(G, B) = \{1\}$  |
| The set of right, left sub-factors of $G$ related to $A$        | $\operatorname{SubF}_r(G:A),$<br>$\operatorname{SubF}_\ell(G:A),$<br>$\operatorname{SubF}_r^1(G:A)$ | $RSF(G, A) \text{ or}^*$ $RBSF(G, A)$ , $LSF(G, A)$ , $RSF1(G : A)$          | $\left\{B \subseteq G : \mathrm{LD}(G, A) \cap \mathrm{RD}(G, B) = \\ \{1\}, G = \mathrm{LD}(G, A)B\right\},$ $\left\{B \subseteq G : \mathrm{LD}(G, B) \cap \mathrm{RD}(G, A) = \\ \{1\}, G = B \ \mathrm{RD}(G, A)\right\},$ $\left\{B_1 \in \mathrm{SubF}_r(G, A) : 1 \in B_1\right\}$ | The set of all $B \subseteq G$<br>s.t. $G=LD(G,A)$ B<br>and $LD(G,A) \cap$<br>$RD(G,B) = \{1\}$<br>* The functions $RSF(A)$<br>and $RBSF(A)$ utilize<br>different algorithms |
| Right upper and lower index of $A$ in $G$                       | $ G:A ^+$ , $ G:A ^-$   | $\mathrm{RidPlus}(G,A)\;,$ $\mathrm{RidMinus}(G,A)\;,$ $\mathrm{RidPM}(G:A)$ | $\max\{ B  : B \in RSF(G, A)\},$<br>$\min\{ B  : B \in RSF(G, A)\},$<br>$( G : A ^{-},  G : A ^{+})$  | equivalently $ \text{RidPlus}(A) = \\ \max\{ B : \operatorname{LD}(G,A) \cap \\ \operatorname{RD}(G,B) = \{1\}\} \\ \text{(only for right upper index)} $                    |

| Left upper and lower index of $A$ in $G$      | $ G:A _+$ , $ G:A $                       | $\operatorname{LidPlus}(G,A)\;, \ \operatorname{LidMinus}(G,A)\;, \ \operatorname{LidPM}(G,A)\;$ | $\max\{ B  : B \in LSF(G, A)\},$<br>$\min\{ B  : B \in LSF(G, A)\},$<br>$( G : A _{-},  G : A _{+})$  | equivalently $ \text{RidPlus}(A) = \\ \max\{ B : \text{LD}(G,B) \cap \\ \text{RD}(G,A) = \{1\}\} \\ \text{(only for left upper index)} $ |
|---|---|--|---|--|
| Right (resp. left) index stable subsets       | $ G:A _r$ (resp. $ G:A _\ell$ )           | $\operatorname{Rid}(G,A)$ (resp. $\operatorname{Lid}(G,A)$ )                                     | $ (resp. \\ LidPlus(G, A) = RidMinus(G, A) \\ (resp. \\ LidPlus(G, A) = LidMinus(G, A)) \\ and denote it by Rid(G, A) (resp. Lid(G, A))$  | we say " $A$ is right (resp. left) index stable" in $G$  |
| Index<br>stable<br>subsets and<br>their index | G:A                                       | $\mathrm{Id}(G,A)$   | if $\operatorname{Rid}(A) = \operatorname{Lid}(G, A)$ and denote it by $\operatorname{Id}(G, A)$ i.e., all sub-indices are equal  | we say " $A$ is index stable" in $G$   |
| Upper (resp. lower) index stable subsets      | -   | IdPlus(G, A) (resp. $IdMinus(G, A)$ )  | $ \text{if } \operatorname{RidPlus}(G,A) = \operatorname{LidPlus}(G,A) \\ \text{(resp.} \\ \operatorname{RidMinus}(G,A) = \operatorname{LidMinus}(G,A)) \\ \text{and denote it by } \operatorname{IdPlus}(G,A) \\ \text{(resp. } \operatorname{IdMinus}(G,A)) $ | we say " $A$ is upper<br>(resp. lower) index<br>stable" in $G$<br>for example all<br>subsets of abelian<br>groups                        |
| Right (resp. left) k-index stable groups      | G is right (resp. left) $k$ -index stable | ${\it IsRightkIndexStable}(G,k)$   | if all subsets $A \subseteq G$ with $ A  = k$ are right (resp. left) index stable   | Note that a group is right k-index (resp. index) stable if and only if it is left k-index (resp. index) stable                           |
| k-index<br>stable<br>groups                   | G is $k$ -index stable                    | ${\bf IskIndexStable}(G,k)$  | $\mbox{if all subsets } A \subseteq G \mbox{ with }  A  = k$ are index stable   | -  |
| Right (resp. left) index stable groups        | G is right (resp. left) index stable      | ${\it Is} {\it RightIndexStable}(G)$   | A group $G$ is called right (resp. left) index stable if all its subsets are right (resp. left) index stable.   | It has been proved<br>that right and left<br>index stabilities are<br>equivalent   |
| Index<br>stable<br>groups                     | G is index stable                         | ${\it IsIndexStable}(G)$   | A group $G$ is called index stable if all its subsets are index stable.   | All (right) index<br>stable finite groups<br>have been<br>characterized  |

Table 2. Infinite differences and difference length of subsets

| Title          | Notation in              | Notation in | Definition or condition                    | Remarks                   |
|----------------|--------------------------|-------------|--|---------------------------|
|                | papers                   | GAP-codes   |  |                           |
| Iterated       | $Dif_r^n(A)$ ,           | RD(G, n, A) | $RD(G, A)RD(G, A) \cdots RD(G, A);$        | for $n = 0$ define        |
| right, left    | $Dif_{\ell}^{n}(A)$      | ,           | $2^{n-1}$ -times,                          | RD(0, G, A) =             |
| differences of |                          | LD(G, n, A) | $LD(G, A)LD(G, A) \cdots LD(G, A);$        | LD(0, G, A) = A           |
| subsets        |                          |             | $2^{n-1}$ -times                           |                           |
| Right , left   | $dl_r^{\infty}(A)$ ,     | Rdl(G,A),   | $\min\{n \ge 0 : \mathrm{RD}(G, n, A) =$   | equivalently              |
| infinite       | $dl_{\ell}^{\infty}(A)$  | Ldl(G, A)   | RD(G, n+1, A),                             | $\min\{n\geq 0:$          |
| difference     |                          |             | $\min\{n \geq 0 : \mathrm{LD}(G, n, A) =$  | $RD(G, n, A) \leq G $ ,   |
| length of      |                          |             | LD(G, n+1, A)                              | $\min\{n\geq 0:$          |
| subsets        |                          |             |  | $LD(G, n, A) \leqslant G$ |
| Limit of       | $Dif_r^{\infty}(A)$ ,    | RDD(G, A)   | RD(G, Rdl(G, A), A),                       | they are subgroups of $G$ |
| iterated       | $Dif_{\ell}^{\infty}(A)$ | ,           | LD(G, Ldl(G, A), A)                        | if $A \neq \emptyset$     |
| differences of |                          | LDD(G, A)   |  |                           |
| subsets        |                          |             |  |                           |
| Right , left   | -                        | Rlag(G, A)  | Size of $\{1 \le n \le \text{Rdl}(G, A) :$ | -                         |
| Lagrange       |                          | ,           | RD(G, n, A)  divides $ G $ ,               |                           |
| difference     |                          | Llag(G, A)  | Size of $\{1 \le n \le \text{Rdl}(G, A) :$ |                           |
| length of      |                          |             | RD(G, n, A)  divides $ G $                 |                           |
| subsets        |                          |             |  |                           |

Table 3: Index and sub-index pervasive properties for groups

| Title   | Notation in  | Notation in  | Definition or condition  | Remarks  |  |
|---|--|--|--|--|--|
| 11010   | papers   |  | Deminion of condition  | Itemarks   |  |
| The set of all right (resp. left) index stable subsets of $G$ | $\iota\sigma_r(G)$ (resp. $\iota\sigma_l(G)$ )   | RISS(G)  (resp. $LISS(G))$   | $ \{A \subseteq G : \\ \operatorname{RidPlus}(G,A) = \operatorname{RidMinus}(G,A) \} $ $ (\operatorname{resp.} \ \{A \subseteq G : \\ \operatorname{LidPlus}(G,A) = \operatorname{LidMinus}(G,A) \} ) $  | i.e. $\{A \subseteq G :$ A is right index stable}  (resp. $\{A \subseteq G :$ A is left index stable}) |  |
| All index stable subsets of $G$                               | $\iota\sigma(G)$   | $\mathrm{ISS}(G)$  | $ \{A \subseteq G : \operatorname{RidPlus}(G, A) = \\ \operatorname{RidMinus}(G, A) = \\ \operatorname{LidPlus}(G, A) = \operatorname{LidMinus}(A) \} $  | i.e. $\{A \subseteq G : A \text{ is index stable}\}$   |  |
| The set of all right (resp. left) indices of $G$              | $ \operatorname{Num}_{\iota_r}(G) \\ (\text{resp.} \\ \operatorname{Num}_{\iota_l}(G)) $ | $\operatorname{IndR}(G)$ (resp. $\operatorname{IndL}(G)$ )   | $\{ \operatorname{Rid}(G,A) : A \text{ is right index stable} \}$ $\{ \operatorname{resp.} \{ \operatorname{Lid}(G,A) : A \text{ is left index stable} \} \}$  | i.e. $\{ G:A _r:A\in\iota\sigma_r(G)\}$<br>(resp. $\{ G:A _l:A\in\iota\sigma_l(G)\}$                   |  |
| The set of all right (resp. left) sub-indices of $G$          | $\operatorname{Num}_{s\iota_r}(G)$ (resp. $\operatorname{Num}_{s\iota_l}(G))$            | $ \begin{aligned} \operatorname{IndslR}(G) \\ (\operatorname{resp.} \\ \operatorname{IndslL}(G)) \end{aligned} $ | $ \{ \operatorname{RidMinus}(G,A) : A \subseteq G \} \cup $ $ \{ \operatorname{RidPlus}(G,A) : A \subseteq G \} \text{ (resp.} $ $ \{ \operatorname{LidMinus}(G,A) : A \subseteq G \} \cup $ $ \{ \operatorname{LidPlus}(G,A) : A \subseteq G \} \text{ )} $ | i.e $\{ G:A ^{\pm}: A \in P(G)\}$<br>(resp. $\{ G:A _{\pm}: A \in P(G)\}$ )                            |  |
| The set of all indices of subsets of $G$                      | $\operatorname{Ind}(G)$  | $\operatorname{Ind}(G)$  | $\{ \mathrm{Id}(A) : A \text{ is index stable} \}$   | i.e $\{ G:A :A\in\iota\sigma(G)\}$   |  |

| The set of all sub-indices of subsets of $G$ | $\operatorname{Num}_{s\iota}(G)$        | $\operatorname{Indsl}(G)$  | $\mathrm{IndslR}(G) \cup \\ \mathrm{IndslL}(G)$          | i.e. $\{ G:A _\pm^\pm:A\in P(G)\}$ |
|--|---|--|--|------------------------------------|
| Possible<br>numbers for<br>sub-indices       | $\operatorname{Num}_{\frac{1}{2}}(G)$   | $\operatorname{Num}(G)$  | $\{1,\cdots,\lfloor \frac{ G }{2}\rfloor\} \cup \{ G \}$ | -                                  |
| Right (resp. left) index pervasive groups    | G is right (resp. left) index pervasive | $ \begin{split} \text{IsRightIndex} \\ \text{Pervasive}(G) \\ \text{(resp.} \\ \text{IsLeftIndex} \\ \text{Pervasive}(G) \ ) \end{split} $ | if $RInd(G) = Num(G)$ (resp. $RInd(G) = Num(G)$ )        | -                                  |
| Index pervasive groups                       | G is index pervasive                    | $\begin{array}{c} \text{IsIndex} \\ \text{Pervasive}(G) \end{array}$   | $\mathrm{if}\;\mathrm{Ind}(G)=\mathrm{Num}(G)$           | -                                  |
| Sub-index<br>pervasive<br>groups             | G is sub-index pervasive                | $\begin{array}{c} \text{IsSubIndex} \\ \text{Pervasive}(G) \end{array}$  | $\mathrm{if}\;\mathrm{SInd}(G)=\mathrm{Num}(G)$          | -                                  |

## References

<sup>[1]</sup> M.H. Hooshmand, Index, sub-index and sub-factor of groups with interactions to number theory, J. Alg. Appl., 19:6(2020), 1-23.

<sup>[2]</sup> M.H. Hooshmand, Subindices and subfactors of finite groups, Commun. Algebra, 51:6(2023), 2644-2657.