

PID Controllers

BY LUKE MCGILL



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Introduction

- A control system is a set of mechanical or electronic devices that regulates other devices or systems by way of control loops.
- Control systems are used to enhance production, efficiency and safety
- PID is type of closed loop controller



History

- 9 1922
 - Nicolas Minorsky
 - Theoretical analysis and first proposed application
- 9 1933
 - Taylor Instrument Company
 - First pneumatic controller with a fully tunable proportional component
- 940
 - Taylor Instrument Company
 - Developed the first PID pneumatic controller with a derivative action
- 942
 - Ziegler and Nichols tuning rules were introduced so that engineers were able to find and set the appropriate parameters of PID controllers





History cont.

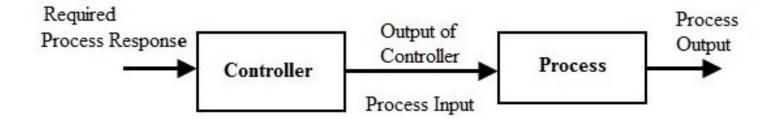
- 950s
 - Automatic PID controllers were widely adopted for industrial use





Theory

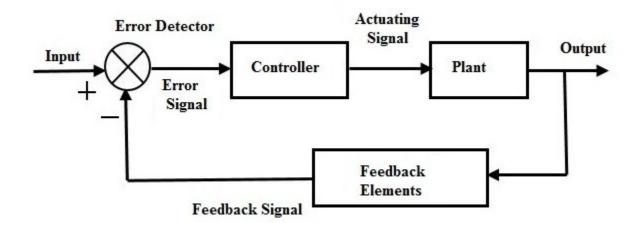
Open loop control system





Theory cont.

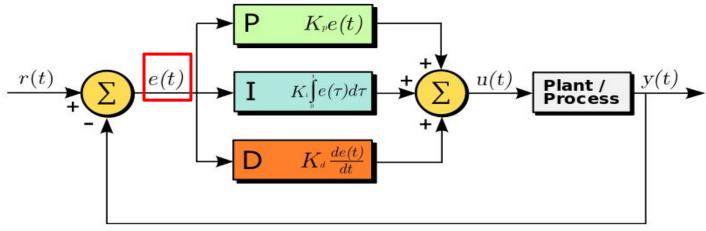
Closed loop control system



Theory cont.



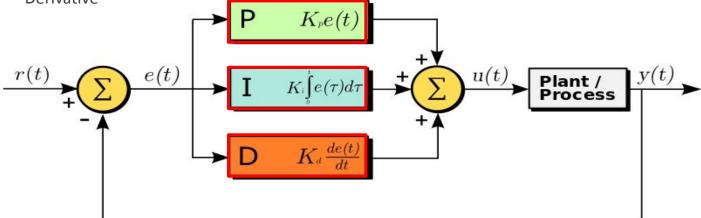
- The PID compares desired output with measured output
- e(t) is called the error signal



Theory cont.



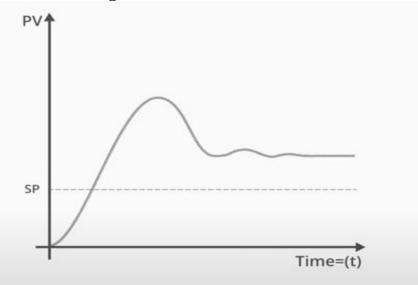
- PID has three terms
 - Proportional
 - Integral
 - Derivative





- Proportional term K_p
 - Proportional to magnitude of the error signal

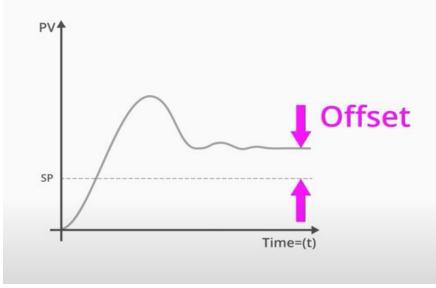
$$K_p \times e(t)$$





- Proportional term K_p
 - Proportional to magnitude of the error signal

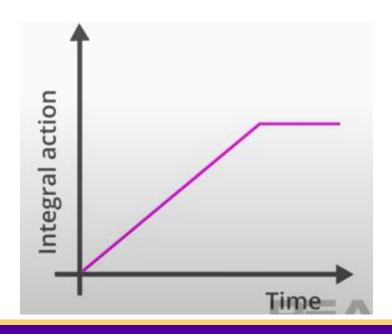
$$K_p \times e(t)$$





Integral term K_i

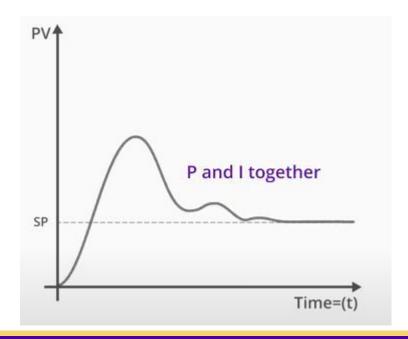
$$K_i \int_0^t e(\tau) d\tau$$





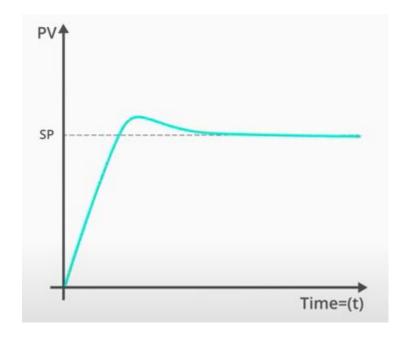
Integral term K_i

$$K_i \int_0^t e(\tau) d\tau$$





Derivative K_d



$$K_d \frac{de(t)}{dt}$$

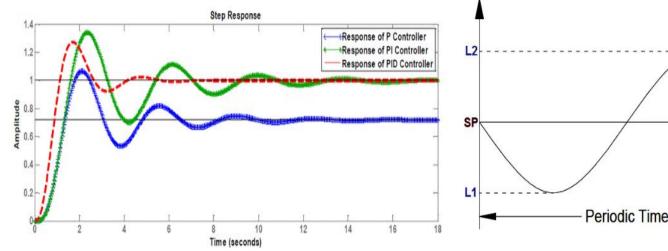
Tuning

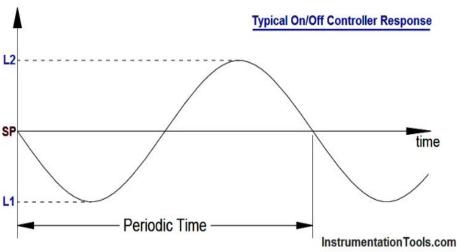
- Adjust constants K_p, K_i, K_d
- PID term tuning can differ vastly between processes and applications
- Can be tuned by trial and error, observing output response
 - Can be time consuming and impractical
- Some modern PID controllers have autotuning functionality
 - Sometimes additional tweaking required



Why choose a PID controller?

Typical PID Controller Response







Variations

- PID not always necessary
 - P controller
 - PI controller
- Why make a simpler controller?
 - Easy to implement
 - Easy to test and troubleshoot
 - Easy to understand
 - Can save time and money



Utilization

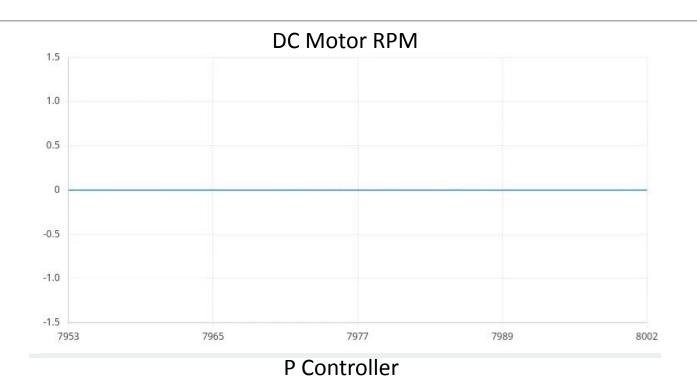
- Widely used in industry, automation, and manufacturing
- Usually digital
- Typically integrated in a PLC or DCS
 - Can still be stand alone devices





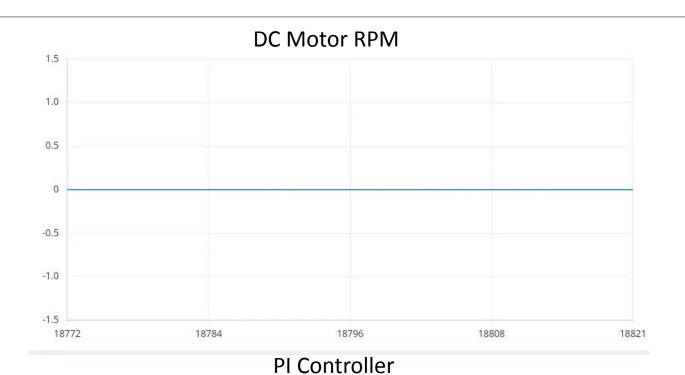


Using PID in Capstone



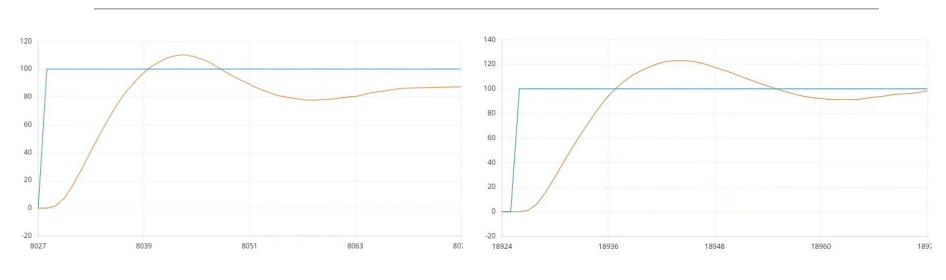


Using PID in Capstone





Using PID in Capstone



P Controller PI Controller



Conclusion

- PID controllers are widely used control method
- Three terms P, I, D
- Can be simple or more sophisticated depending on application
- Used heavily in industry, automation, and manufacturing



Works Cited

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Questions?

