

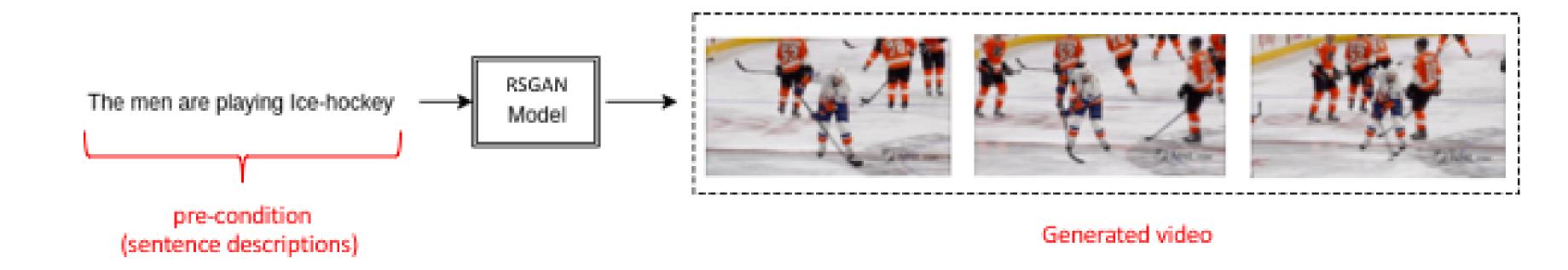
# RSGAN: RECURSIVE STACKED GENERATIVE ADVERSARIAL NETWORK FOR CONDITIONAL VIDEO GENERATION

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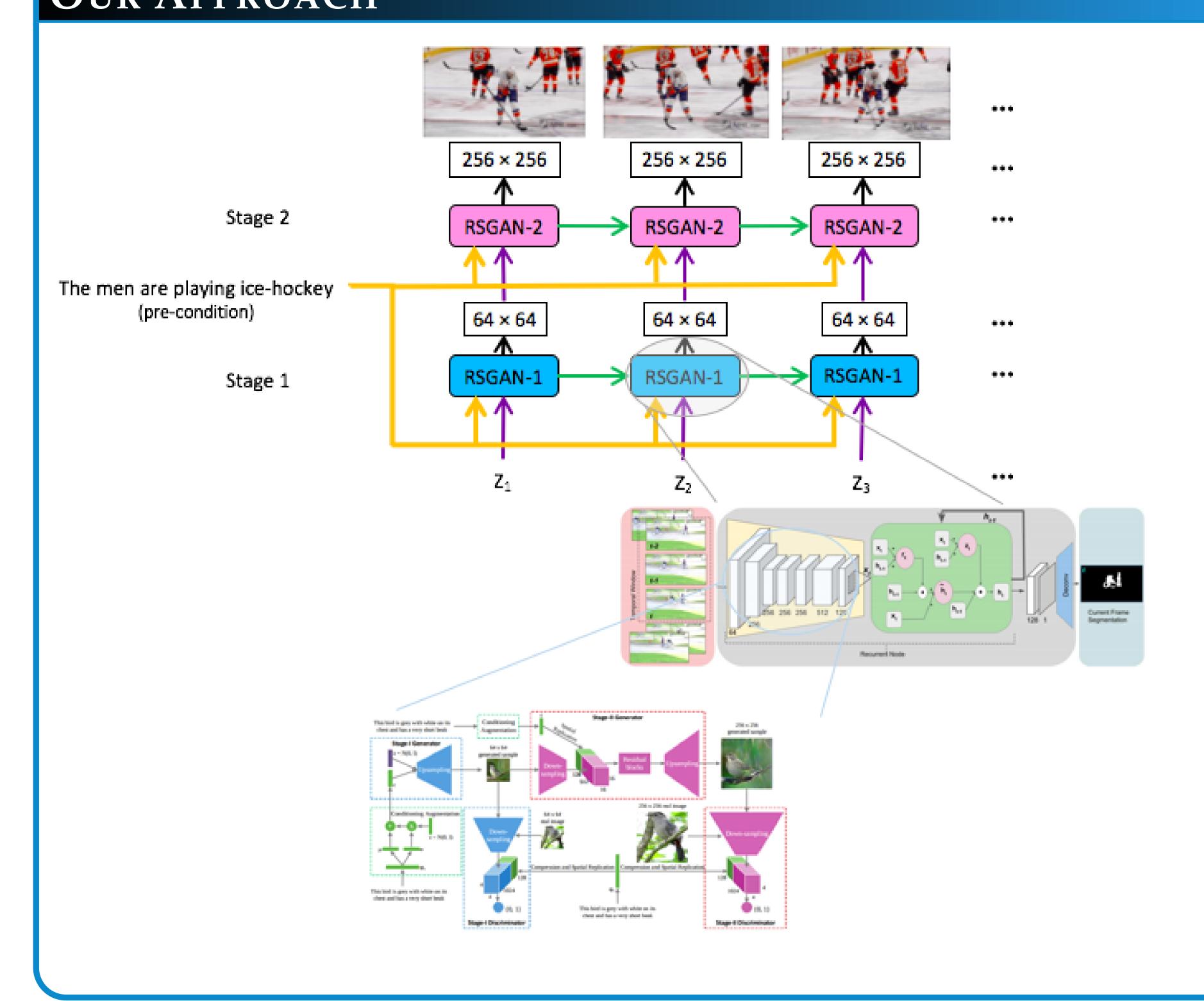
## INTRODUCTION

Generating video frames based on a pre-condition is a challenging problem and requires understanding of per frame contents and visual dynamics and their relevacies to the pre-condition. In this project, we propose a novel Recurrent Stacked Generative Adversarial Network (RSGAN) based model to generate video frames based on a given pre-condition. In our knowledge, this is the first work to address the problem of conditional video generation using adversarial network. We can address the problem of generating videos based on pre-conditions such as,

- 1. action classest
- 2. fMRI signals
- 3. sentence descriptions



# OUR APPROACH



# OBJECTIVE FUNCTION

Conditioned on Gaussian latent variables  $c_0$ , Stage-I RSGAN trains discriminator  $D_0$  and generator  $G_0$  by alternatively maximizing  $\mathcal{L}_{D_0}$  and minimizing  $\mathcal{L}_{G_0}$ .

#### Stage-I RSGAN:

$$\mathcal{L}_{D_o} = \mathbb{E}_{(I_o,t) \sim p_{data}} [log D_0(I_0,\varphi_t)] + \mathbb{E}_{z \sim p_z,t \sim p_{data}} [log (1 - D_0(G_0(z,c_0),\varphi_t))]$$

$$\mathcal{L}_{G_o} = \mathbb{E}_{z \sim p_z,t \sim p_{data}} [log (1 - D_0(G_0(z,c_0),\varphi_t))] + \lambda D_{KL}(\mathcal{N}(\mu_0(\varphi_t),\sum_0(\varphi_t))||\mathcal{N}(0,I))$$

Conditioned on the low resulation sample  $s_0$  and Gaussian latent variables c, discriminator D and generator G in Stage-II RSGAN is trained by alternatively maximizing  $\mathcal{L}_D$  and minimizing  $\mathcal{L}_G$ .

#### Stage-II RSGAN:

$$\mathcal{L}_{D} = \mathbb{E}_{(I,t) \sim p_{data}}[logD(I,\varphi_{t})] + \mathbb{E}_{s_{o} \sim p_{G_{o}}, t \sim p_{data}}[log(1 - D(G(s_{o},c),\varphi_{t}))]$$

$$\mathcal{L}_{G} = \mathbb{E}_{s_{o} \sim p_{G_{o}}, t \sim p_{data}}[log(1 - D(G(s_{o},c),\varphi_{t}))] + \lambda D_{KL}(\mathcal{N}(\mu(\varphi_{t}), \sum(\varphi_{t}))||\mathcal{N}(0,I))$$

### RESULT

- Right now, we are trying to generate video with simple details. That's why we are using Kinect skeleton video as dataset.
- Due to two stage adversial network systems, it takes around 3days to train each stages in Future System of IU.

## FUTURE RESEARCH

- Generate video with complex details and multiple moving objects.
- Use fMRI dataset of human brain, to generate video.

# REFERENCES

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