NICK WALKER

Ph.D. Student in Computer Science

nswalker@cs.uw.edu nickwalker.us

EDUCATION

2018— University of Washington – Seattle, WA

• Ph.D. Computer Science

• Advisor: Maya Cakmak

2018–20 University of Washington – Seattle, WA

• M.S. Computer Science

2014–18 The University of Texas – Austin, TX

• B.S.A. Computer Science

• Polymathic Scholar (Interdisciplinary Honors)

CONFERENCE

- [c8] "Influencing Behavioral Attributions to Robot Motion During Task Execution." N. Walker, C. Mavrogiannis, S. Srinivasa, M. Cakmak. Conf. Robot Learning. London, UK, Nov. 2021
- [c7] "Learning Backchanneling Behaviors for a Social Robot via Data Augmentation from Human-Human Conversations." M. Murray, N. Walker, A. Nanavati, P. Alves-Oliveira, N. Filippov, A. Sauppe, B. Mutlu, M. Cakmak. Conf. Robot Learning. London, UK, Nov. 2021
- [c6] "Human Perceptions of a Curious Robot that Performs Off-Task Actions." N. Walker, K. Weatherwax, J. Alchin, L. Takayama, M. Cakmak. ACM/IEEE Int. Conf. Human-Robot Interaction. Oxford, UK, Mar. 2020
- [c5] "Open-World Reasoning for Service Robots." Y. Jiang*, N. Walker*, J. Hart, P. Stone. Proc. 29th Int. Conf. Automated Planning Scheduling. Berkeley, Jul. 2019
- [c4] "Improving Grounded Natural Language Understanding through Human-Robot Dialog."
 J. Thomason, A. Padmakumar, J. Sinapov, N. Walker, Y. Jiang, H. Yedidsion, J. Hart, P. Stone,
 R. J. Mooney. Int. Conf. Robotics Automation. Montreal, May 2019
- [c3] "PRISM: Pose Registration for Integrated Semantic Mapping." J. W. Hart, R. Shah, S. Kirmani, N. Walker, K. Baldauf, N. John, P. Stone. 2018 IEEE/RSJ Int. Conf. Intelligent Robots Systems.

 Madrid, Spain, Oct. 2018
- [c2] "Automatic Curriculum Graph Generation for Reinforcement Learning Agents." M. Svetlik, M. Leonetti, J. Sinapov, R. Shah, <u>N. Walker</u>, P. Stone. *Proc. Thirty-First AAAI Conf. Artificial* Intelligence. San Francisco, Feb. 2017
- [c1] "Wearable ear EEG for brain interfacing." E. D. Schroeder, N. Walker, A. S. Danko. *Proc. of SPIE 10051, Neural Imaging Sensing.* San Francisco, Feb. 2017

JOURNAL

[j1] "Jointly Improving Parsing and Perception for Natural Language Commands through Human-Robot Dialog." J. Thomason, A. Padmakumar, J. Sinapov, N. Walker, Y. Jiang, H. Yedidsion, J. Hart, P. Stone, R. J. Mooney. *Journal of Artificial Intelligence Research*. Feb. 2020

REFEREED SYMPOSIUM, WORKSHOP

[w5] "Influencing Behavioral Attributions to Robot Motion During Task Execution." N. Walker, C. Mavrogiannis, S. Srinivasa, M. Cakmak. Proc. 2021 ICRA Workshop Modern Approaches for Intrinsically-Motivated Intelligent Behavior. Xi'an, China, Jun. 2021

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[w4]	"Desiderata for Planning Systems in General-Purpose Service Robots." N. Walker*, Y. Ji-					
[1 1	ang*, M. Cakmak, P. Stone. <i>Proc. of 2019 ICAPS Workshop Planning Robotics</i> . Berkeley, Jul. 2019					
[w3]						
[vv3]	"Neural Semantic Parsing with Anonymization for Command Understanding in Gen-					
	eral-Purpose Service Robots." <u>N. Walker</u> , YT. Peng, M. Cakmak. RoboCup 2019: Robot Soccer					
	World Cup XXIII. Sydney, Jul. 2019					
[w2]	"LAAIR: A Layered Architecture for Autonomous Interactive Robots." Y. Jiang*, <u>N. Walker</u> *,					
	M. Kim, N. Brissonneau, D. S. Brown, J. W. Hart, S. Niekum, L. Sentis, P. Stone. AAAI Fall Symp.					
	Reasoning Learning in Real-World Systems for Long-Term Autonomy. Arlington, Oct. 2018					
[w1]	"Interaction and Autonomy in RoboCup@Home and Building-Wide Intelligence." J. Hart,					
	H. Yedidsion, Y. Jiang, N. Walker, R. Shah, J. Thomason, A. Padmakumar, R. Fernandez,					
	J. Sinapov, R. Mooney, P. Stone. AAAI Fall Symp. Artificial Intelligence Human-Robot Interaction.					
	Arlington, Oct. 2018					
RECOGNITION						
2020—	Graduate Research Fellowship – National Science Foundation					
2018-19	Computer Science & Engineering Research Fellowship – Allen School, UW					
2018	Best Poster, with UT Austin Villa – RoboCup@Home DSPL					
2018	Commencement Student Speaker – College of Natural Sciences, UT					
2018	GRFP Honorable Mention – National Science Foundation					
2018	Dean's Honored Graduate – College of Natural Sciences, UT					
2018	Outstanding Undergraduate Researcher Award Honorable Mention – Computing Research					
2010	Association					
2017						
	TIDES Fellowship – Texas Institute for Discovery Education in Science, UT					
2014–18	College of Natural Sciences Scholarship – College of Natural Sciences, UT					
Outreach	Ţ					
2019	Demo Assistant – UW Engineering Discovery Days					
2017	Organized and helped run an exhibit demonstrating our lab's research					
2019	Program Assistant – UTCS Robotics Camp					
2019	·					
0045 0040	Helped high school students assemble robot kit, program intelligent behaviors					
2017, 2018	,					
	• Ran demos on our robots and explained lab's research to community members					
2017, 2018	Workshop Assistant – UT Introduce a Girl to Engineering Day					
	 Taught grade school girls about electricity using Play-Doh and LEDs 					
2017, 2018	Workshop Instructor – UT Computer Science, Code Longhorn & First Bytes Camps					
	• Taught high school students from underrepresented groups about web technologies					
2016-18	Peer Mentor – Freshman Research Initiative					
	• Helped first- and second-year students formulate their research projects					
SERVICE						
2020	NSF GRFP Seminar Coordinator – Allen School Graduate Student Committee, UW					
2020	Organizer – Practical Service Robots Workshop, RSS					
2020	Organizer – Imitation Learning Workshop, RSS					
2019-20	Technical Committee – RoboCup@Home					
2019_21	019–21 Peer Mentor – Allen School First Year Graduate Student Mentoring, UW					
2017 21	reel Mellol – Allen School First Lear Graduate Student Mentoring, O W					

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2018 Reader – Allen School Ph.D. Admissions Committee, UW

REVIEWING

ICRA	2021, 2019	RSS	2021	TCDS	2020
IROS	2021	SSRR	2021	THRI	2020
RA-L	2021	TAFFC	2020		

WORK AND TEACHING EXPERIENCE

2021 Sp. Teaching Assistant – UW CSE 478 (Robotics)

• Updated assignments based on an autonomous race-car platform

2019 Wi. Teaching Assistant – UW CSE 481C (Robotics Capstone)

• Developed assignments and supported undergraduates using the Kuri robot

2016 Su. Research Engineer Intern – USAA

 $\bullet \ Developed\ experimental\ brain-computer\ interface\ software\ and\ hardware$

• Work contributed to a SPIE conference publication

2015 Su. Research Engineer Intern – USAA

• Characterized the performance of automated speech transcription vendors

• Developed evaluation methodology that led to a patent application

SKILLS

- Experienced with robotics software ROS, C++, Python
- Experienced with robotics platforms Stretch, Fetch, Kuri, HSR
- Proficient with user research Study Design, Hypothesis Testing, Amazon Mechanical Turk
- Proficient with machine learning techniques, tools PyTorch, Numpy, Pandas
- Proficient with web technologies PHP, Typescript, HTML, CSS
- Handy with digital media Premiere, Photoshop, Illustrator, InDesign

PERSONAL

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