

Seminar 3

1

$$\Delta_0(t) = -1 \quad (H_0)$$

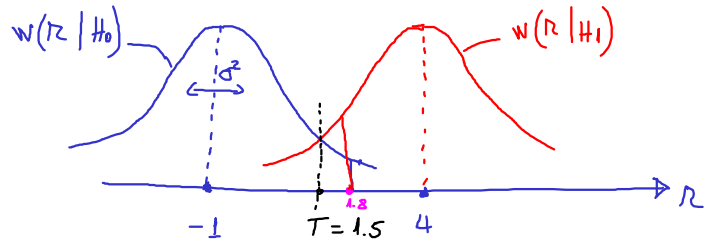
$$\Delta_1(t) = 4 \quad (H_1)$$

$$\mathcal{N}(\mu=0, \sigma^2=4)$$

$$t_0 = 0.75$$

$$r = 1.8$$

a)



$$w(r|H_0) = \frac{1}{2\sqrt{2\pi}} \cdot e^{-\frac{(r+1)^2}{8}}$$

$$w(r|H_1) = \frac{1}{2\sqrt{2\pi}} \cdot e^{-\frac{(r-4)^2}{2\sigma^2}}$$

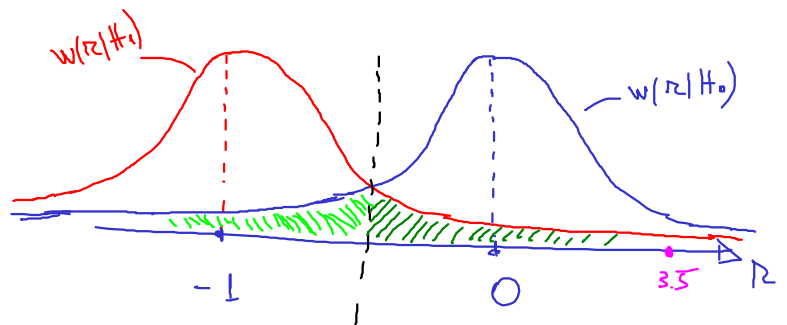
b. $T = \frac{-1+4}{2} = 1.5$

$$r > T \Rightarrow \Delta_1$$

OR

ML, gaussian noise

1.8 closer to 4 than to -1 $\Rightarrow \Delta_1$



2

$$\Delta_0(t) = \cos(2\pi t) \quad (H_0)$$

$$\Delta_1(t) = \sin(2\pi t) \quad (H_1)$$

$$\mathcal{N}(\mu=0, \sigma^2=4)$$

$$t_0 = 0.75, r = 3.5$$



$$\Delta_0(t_0) = \cos(2\pi \cdot 0.75) = 0$$

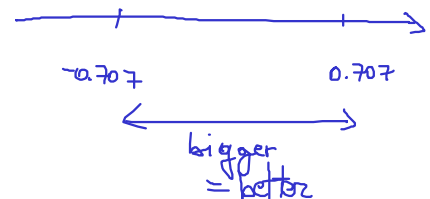
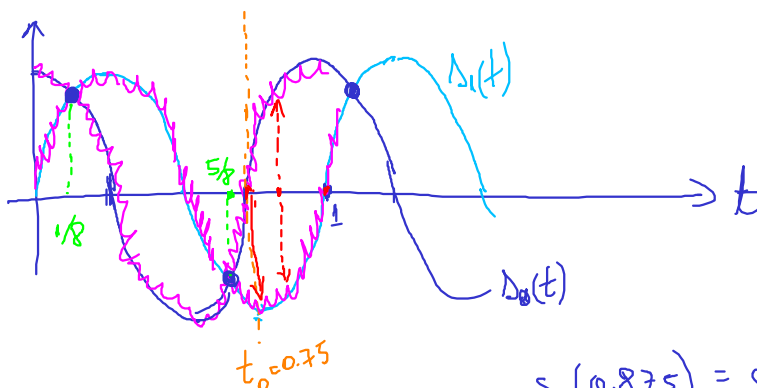
$$\Delta_1(t_0) = \sin(2\pi \cdot 0.75) = -1$$

$$w(r|H_0) = \frac{1}{2\sqrt{2\pi}} e^{-\frac{(r-0)^2}{8}}$$

$$w(r|H_1) = \frac{1}{2\sqrt{2\pi}} e^{-\frac{(r+1)^2}{8}}$$

b. For $r = 3.5$, $w(r|H_0) > w(r|H_1) \Rightarrow \boxed{\Delta_0}$

c.



$$s_0(0.875) = \cos(2\pi \cdot 0.875) = 0.707 = \frac{\sqrt{2}}{2}$$

$$s_1(0.875) = \sin(2\pi \cdot 0.875) = -0.707 = -\frac{\sqrt{2}}{2}$$

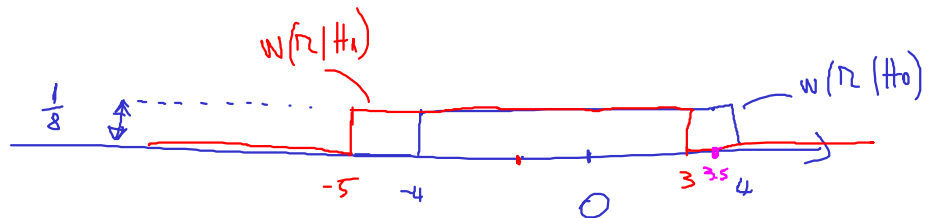
$$t_1 = 0.75 + \frac{0.25}{2} = 0.875$$

d). Worst moment : when $\Delta_0(t) = \Delta_1(t)$

$$\cos(2\pi t) = \sin(2\pi t)$$

$$\Leftrightarrow \text{when } 2\pi t = \pi/4 \Rightarrow t = \frac{1}{8}$$

e) $\mathcal{U}[-4, 4]$



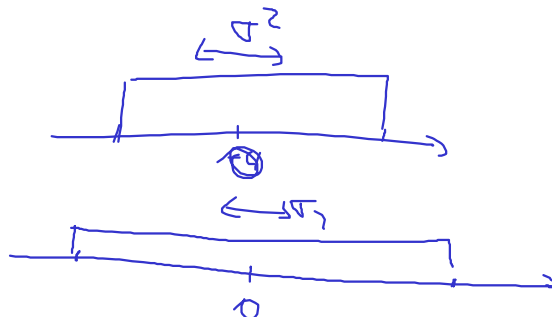
$$r = 3.5 \Rightarrow w(r|H_0) = \frac{1}{8}$$

$$w(r|H_1) = 0$$

$$\Rightarrow \boxed{\Delta_0}$$

$r = 1.2 \Rightarrow$ Indecision because $w(r|H_0) = w(r|H_1)$

f). $\mathcal{U}[-4, 4]$



Max noise is $\mathcal{U}[-4.5, 4.5]$
-4.4999 4.4999



Max. variance is for noise $\mathcal{U}[-4.5, 4.5]$

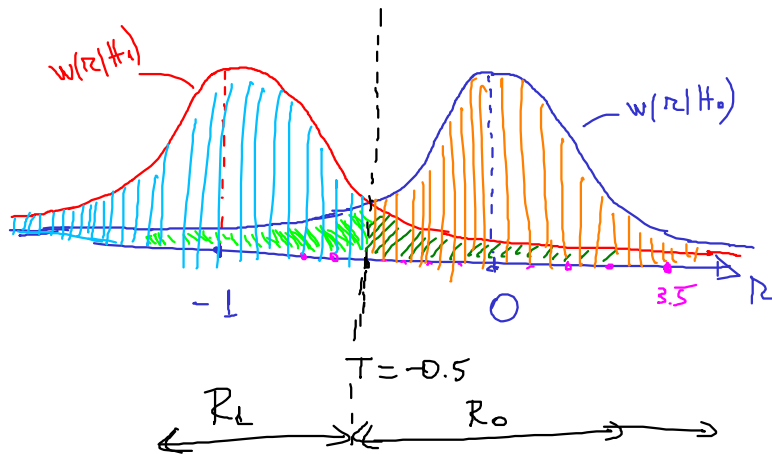
$$\sigma_{\max}^2 = \overline{x^2} - \mu^2 = \overline{x^2} = \int_{-4.5}^{4.5} x^2 \cdot \frac{1}{9} dx = \frac{1}{9} \cdot \frac{x^3}{3} \Big|_{-4.5}^{4.5} = \dots$$

g).

$$P(D_0 | H_0) = \int_{-0.5}^{\infty} w(r|H_0) =$$

miss
correct
rej.

$$= \underbrace{F(\infty)}_1 - \underbrace{F(-0.5)}_{\frac{1}{2}(1 + \operatorname{erf}(\frac{-0.5-0}{2\sqrt{2}})) = 0.4} = 0.6$$



$$F(x) = \frac{1}{2} \left(1 + \operatorname{erf} \left(\frac{x-\mu}{\sqrt{2}\sigma} \right) \right)$$

$$P(D_1 | H_0) = \int_{-\infty}^{-0.5} w(r|H_0) = \underbrace{F(-0.5)}_{0.4} - \underbrace{F(-\infty)}_0 = 0.4$$

false
alarm

$$P(D_0 | H_1) = \int_{-0.5}^{\infty} w(r|H_1) = \underbrace{F(\infty)}_1 - \underbrace{F(-0.5)}_{\frac{1}{2}(1 + \operatorname{erf}(\frac{-0.5+1}{2\sqrt{2}})) = 0.6} = 0.4$$

miss

$$P(D_1 | H_1) = \int_{-\infty}^{-0.5} w(r|H_1) = \underbrace{F(-0.5)}_{0.6} - \underbrace{F(-\infty)}_0 = 0.6$$

correct
detection