

Frame **

Pulse

$$S_R(n) = W1_D(n - N_F) + \left(X0_D - \frac{1}{2}N_SW1_D\right) \quad N_F < n \le N_F + N_R + N_S$$

$$S_F(n) = \frac{X2_D}{2\pi} \left[W2_D n - \sin(W2_D n) \right] + W1_D n + X_{Start_D} \quad 0 < n \le N_F$$

n_S = Number of points between stationary point and linear ramp

$$= \frac{1}{W2_{D}} \left[\cos^{-1} \left(\frac{2\pi W 1_{D}}{X 2_{D} W 2_{D}} + 1 \right) \right]$$

N_S = Number of points in step response of galvanometer

 N_F = Number of points in flyback

N_R = Number of points in linear ramp

The line delay has an additional pixel delay and the line pulse has a reduction of a pixel delay, to ensure the unison of rising and falling edges.

Frame **

Delay

$$\label{eq:line_pulse} \begin{split} LinePulse = & \left[Width \times \left(PixelDelay + PixelPulse \right) \right] - PixelDelay \\ LineDelay = & \left[n \times \left(PixelDelay + PixelPulse \right) \right] + PixelDelay \end{split}$$

** The frame delay has an additional line delay and the frame pulse has a reduction of a line delay, to ensure the unison of rising and falling edges.

$$FramePulse = \Big[Height \times \big(LineDelay + LinePulse \big) \Big] - LineDelay$$

$$FrameDelay = \Big[n \times \big(LineDelay + LinePulse \big) \Big] + LineDelay$$