# PAT: finite element solver for the heat transfer analysis of infrastructures subjected to environmental actions

# Input data file and verification examples

#### Noemi Schclar Leitão

Laboratório Nacional de Engenharia Civil Lisbon, Portugal nschclar@lnec.pt

#### Eloísa Castilho

Instituto Superior Técnico Lisbon, Portugal eloisa.castilho@tecnico.ulisboa.pt

## 1 Input data file

To run PAT, an input data file is required. The input data file must be a text-format file. This file describes the finite element model, including the node coordinates, elements and connectivity, boundary and initial conditions, etc. In case of using discrete data of environmental actions, an extra data file must be supplied. All entries are in free form format, which provides some flexibility, but requires that all input variables, even null values, must be given.

The name of the input data file (without extension) is read from the command line and set to filename. The program assumes that the data file has a file extension \*.dat. The program will assign the same file name to the output files.

### 1.1 Management data

The first group of data defines the main characteristics of the FEM and FDM adopted schemes and allow to allocate memory and initialise several general arrays.

The first line of data identifies the type of element used for the modelling element, the number of nodes per element nod, the number of elements nels, the number of nodes in the mesh nn, the number of integration points nip, the number of dimensions ndim, the calculation time step dtim and the time integration parameter theta.

The next two lines of data refer to the period of analysis given by the initial and final date and time, jdate and jhour. These dates must be given in the format yyyymmdd hhmm.

Although PAT contains all the element type library defined in [1] it is supposed to use only quadrilateral and hexahedron, Figure 1. For other element types it is necessary to implement the corresponding associated element to allow the use of prescribed flux or convection boundary conditions. This implementation is straightforward.

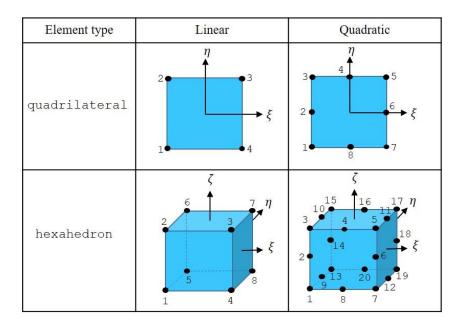


Figure 1 – Type of elements

It is also important to mention that PAT does not support different element types in the same mesh. However, unlike the extension of element types, this shortcoming is difficult to overcome since it implies a major modification of the program structure.

#### 1.2 Units

The use of the Julian day numbering scheme solves in an efficient way the dependency of the environmental actions on date and time. However, it introduces the shortcoming of fixing a priori the unit of time in days. To address this constraint, the program reads the unit of time chosen for the analysis in order to define the appropriate conversion factor. This is done through the input variable utemp by setting "s" for seconds, "h" for hours or "d" for days.

The program does not assume another unit. The only exception can be seen in 1.6.2.

#### 1.3 Mesh orientation

The general geographic orientation of the global axis is read as the latitude and azimuth angles, phi and azimuth, expressed in decimal degrees.

The latitude is the angular coordinate of the location in question in reference to the equator with positive values in the north.

The azimuth is defined as the angle between the South and the normal to the surface measured clockwise around the surface's horizon. In order to define the azimuth in an unambiguous way, the global axis orientation should observe the following rules: in 2D problems the y axis must point to the Zenith and the global azimuth is measured with respect to the normal vector pointing outwards from the plane, in 3D problems the z axis must point to the Zenith and the global azimuth is measured with respect to the y axis.

#### 1.4 Material data

The number of properties  $np\_types$  precedes the introduction of the thermal properties values. If there is only one property type  $(np\_types=1)$  then the properties are read and automatically allocated to all elements. If there is more than one property type then the properties are read, followed by the reading of an integer vector etype which holds information on which properties are assigned to each element. The properties are stored in the matrix prop, and refer to the thermal conductivities  $k_x$  and  $k_y$  in 2D problems or  $k_x$ ,  $k_y$  and  $k_z$  for 3D problems, the material density  $\rho$ , the specific heat c, the total thermal transmission coefficient  $h_t$  and the absorption coefficient a. These parameters must be provided in consistent units.

#### 1.5 Mesh data

The mesh is defined by the nodal geometry g\_coord and connectivity g\_num details. The local numbering of the elements is given in Figure 1.

## 1.6 Boundary conditions

The boundary conditions must be given in the following order: prescribed temperature, prescribed flux and convection boundary condition.

## 1.6.1 Prescribed temperature

The prescribed temperature can be given as reservoir water temperature, fixed\_freedom\_1, or as constant or discrete values, fixed\_freedom\_2.

The variable fixed\_freedom\_1 indicates the number of nodes in contact with the reservoir water. If there are no nodes with this conditions, fixed\_freedom\_1 must be set to 0 and the data input follows with fixed\_freedom\_2 boundary condition. Otherwise, the following line must input the parameters of the water temperature equation given by Bofang ([2] §2.5)

$$T(y,d) = T_m(y) - A(y)\cos\left\{\frac{2\pi}{365}[d - \tau_o - d_o(y)]\right\}$$
 (1)

with

$$T_m(y) = c + (T_s - c) \exp(-e_1 y)$$
 (2)

$$A(y) = A_o \exp(-e_2 y) \tag{3}$$

$$d_o(y) = [e_3 - e_4 \exp(-e_5 y)] \frac{365}{12}$$
 [days] (4)

where y is the depth of the water, d is the fractional day of the year,  $T_m(y)$ , A(y) and  $t_o(y)$  are the annual mean temperature, the amplitude of annual variation and the phase difference of water temperature at depth y,  $\tau_o$  is the time for maximum air temperature, and  $T_s$ ,  $A_o$ , c and  $e_1$  to  $e_5$  are obtained through the monitored temperatures.

The depth of the water y is calculated as the difference between an adopted reference level of the reservoir wl and the vertical coordinate of the node.

The data to input are the adopted reference level of de reservoir followed for  $T_s$ ,  $A_o$ ,  $\tau_o$ , c and  $e_1$  to  $e_5$ , that is w1, ts, ao, tauo, ce, e1, e2, e3, e4 and e5, respectively.

The variable fixed\_freedom\_2 indicates the number of nodes with prescribed temperature equal to constant or discrete values. As before, if this boundary condition is not assigned to any node, fixed\_freedom\_2 must be set to 0 and follow with the next boundary condition. If fixed\_freedom\_2 is not equal to 0, the following line indicates which of the two options for fixed temperatures will be used, variable tempin.

If tempin=1 constant temperatures are assigned to each fixed\_freedom\_2 nodes. Therefore, the following piece of data must indicate for each fixed\_freedom\_2 the node and the value.

If tempin=2 the temperatures are given as function of time through a table of discrete values. Each line of the tables must indicate date, time and temperature value. The date and time must be given in yyyymmdd hhmm format. This data must be provided in a separate text-format file. The file name, including file extension, corresponds to the next line of the input file followed by the number of nodes with these prescribed temperatures.

#### 1.6.2 Prescribed flux

The prescribed flux corresponds in PAT to the solar radiation boundary conditions and is given by the variable hfbc. If there is no prescribed flux, hfbc must be set to 0, otherwise hfbc indicates the number of boundaries with prescribed flux. The solar irradiation data can be introduced as an exponential function, fluxin=1, or as discrete values, fluxin=3. There is also the possibility of computing the beam and diffuse irradiations internally by the Kumar's model, fluxin=2.

If fluxin=1, the irradiance is computed through the function

$$\frac{I_b}{\cos Z} = I_o \exp(A + B \cos Z) \tag{5}$$

where  $I_o$  is the solar constant (1367 W/m<sup>2</sup>), and A and B must be given by the user. It is important to note that the program only converts units of time. If the unit of length is different from meter,

or the unit of energy is different from joule, the user must modify the constant  $I_o$  in subroutine radiation parameters.

If fluxin=3, the beam and diffuse irradiance are given as a function of time through a table of discrete values. Each line of the table must indicate date, time, value of beam irradiation and value of diffuse irradiation. The date and time must be given in the form yyyymmdd hhmm. The data table must be provided in a separate text-format file, which name, including file extension, must be given following fluxin.

If fluxin=2, the beam and diffuse irradiance are computed internally by Kumar's model and no extra data is necessary. The subroutine Kumar\_model works with a fixed  $I_o$ = 1367 W/m<sup>2</sup>, and no conversion unit is addressed.

Whatever the value of fluxin, the radiation boundary conditions end with the indication for each hfbc boundary condition of the number of the parent element and the number of the side with solar radiation following Figure 2.

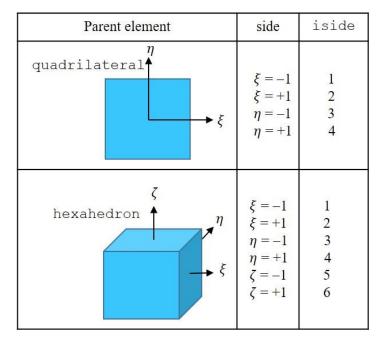


Figure 2 - Boundary identification

#### 1.6.3 Convection boundary condition

The convection boundary condition is indicated by the variable htbc. If there is no convection boundary condition, htbc must be set to 0, otherwise htbc indicates the number of boundaries with convection heat transfer. The air temperature can be introduced as a harmonic function, airin=1, or as a table of discrete values, airin=2.

If airin=1, the daily air temperature is represented as the superposition of two harmonic functions, one of annual period and another with a one day period

$$T(d) = T_m + T_o^a \cos\left[\frac{2\pi}{365} (d - t_o^a)\right] + \frac{A(d)}{2} \cos[2\pi (d - t_o^d)]$$
 (6)

with

$$A(d) = A_m + A_o^a \cos \left[ \frac{2\pi}{365} (d - \theta_o^a) \right]$$
 (7)

where d is the fractional day of the year,  $T_m$  is the yearly mean temperature,  $T_o^a$  is the amplitude of annual variation,  $t_o^a$  is the yearly phase difference, A(d) is the yearly variation of the daily amplitude defined by the mean amplitude  $A_m$ , amplitude  $A_o^a$  and the phase difference  $\theta_o^a$ , and  $t_o^d$  is the daily phase difference.

The parameters must be given in the following order:  $T_m$ ,  $T_o^a$ ,  $t_o^a$ ,  $A_m$ ,  $A_o^a$ ,  $\theta_o^a$  and  $t_o^d$  which are attributed to the variables t\_m1, t\_p1, delay\_1, t\_m2, t\_p2, delay\_2 and delay\_3, respectively.

If airin=2, the air temperature and the total thermal transmission coefficient are both introduced as a function of time through a table of discrete values. Each line of the table must contain date, time, air temperature and total thermal transmission coefficient. The date and time must be given in the form yyyymmdd hhmm. These data are given in a separate text-format file, which name, including file extension, must be given in the input file. The program provides the possibility of introducing two different groups of convection boundary conditions (air temperature and total thermal transmission coefficient), so after airin, it is necessary to indicate 1 or 2 followed by the name(s) of the file(s).

The convection boundary condition ends with the indication for each htbc boundary condition of the number of the element and the number of the side of the element with convection. In the case that there are two tables of discrete data, it must be given also the number of the group (1 or 2).

It is worth noting that in case of airin=2 the total thermal transmission coefficient given in matrix prop is not used.

#### 1.7 Initial conditions

After the boundary conditions, the program reads the initial temperature indicator indic. If indic=0, the program assigns an initial constant temperature to all the nodes of value val0. Otherwise indic must be set to the number of nodes with initial value different from 0, followed by the indic number of node and temperature value.

## 1.8 Output data

The final part of the data file refers to the outputs. The npri variable indicates that the results will be printed every npri time steps. The output files will be called filename yyyymmddhhmmss.res.

If the user wants results in some specific points inside the mesh, the variable nsensors must be set to the number of points to be computed, otherwise this variable must be set to 0. For each point, it must be provided a name to identify the point and its global coordinates. The output files will be called filename name.res.

# 2 Verification examples

# 2.1 One-dimensional heat conduction through a plane wall with one side at prescribed periodic temperature and the other at 0°C

Consider the one-dimensional heat transfer through a plane wall with thickness L, constant thermal diffusivity  $h^2$  and uniform initial temperature  $T_i$  with the boundary conditions given by

$$T(0,t) = -T_o \cos\left[\frac{2\pi}{P} \left(t - t_o\right)\right] \tag{8}$$

$$T(L,t) = 0 (9)$$

as shown in Figure 3.

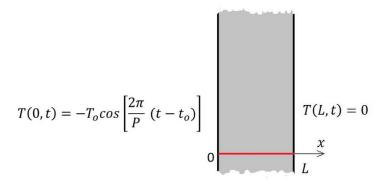


Figure 3 - One dimensional heat conduction through a plane wall with periodic boundary conditions on one side and 0°C in the other

If the surface oscillation of temperature T(0,t) has been going on for so long that the steady periodic conditions are established and the influence of the initial temperature has disappeared, temperature development through the thickness of the wall at time t can be calculated based on Puppini's formula [3] and using trigonometric relationships

$$T(x,t) = -T_o \left\{ \cos \left( \frac{2\pi t_o}{P} \right) \left[ A_x \cos \left( \frac{2\pi t}{P} \right) + B_x \sin \left( \frac{2\pi t}{P} \right) \right] + \sin \left( \frac{2\pi t_o}{P} \right) \left[ A_x \sin \left( \frac{2\pi t}{P} \right) - B_x \cos \left( \frac{2\pi t}{P} \right) \right] \right\}$$

$$(10)$$

with

$$A_x = -2M \sinh z \cos z - 2N \cosh z \sin z + e^z \cos z \tag{11}$$

$$B_x = 2M \cosh z \sin z - 2N \sinh z \cos z - e^z \sin z \tag{12}$$

and

$$M = \frac{e^{2z_o} - \cos 2z_o}{2(\cosh 2z_o - \cos 2z_o)}$$
 (13)

$$N = \frac{\sin 2z_o}{2(\cosh 2z_o - \cos 2z_o)} \tag{14}$$

$$z_o = \sqrt{\frac{\pi}{P h^2}} L \tag{15}$$

$$z = \sqrt{\frac{\pi}{P h^2}} x \tag{16}$$

Since the model is infinitely long in one direction, the model is essentially one-dimensional, and horizontal boundaries may be represented as adiabatic boundaries, Figure 4.

In this example the thermal diffusivity  $h^2 = k/(\rho C)$  was set to 1 m<sup>2</sup>/day, the period P to 365 days, and the periodic parameters  $T_o$  to 40°C and  $t_o$  to 73 days.

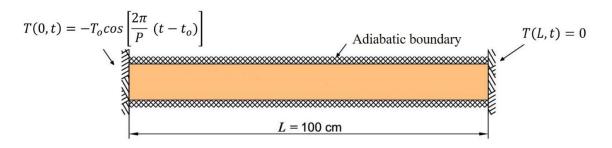


Figure 4 – Idealization of the plane wall

The wall was divided into a row of 8 quadratic quadrilateral elements. Figure 5 shows the mesh and data used for the analysis. It is worth noting that the words in bold of Figure 5 are just explanatory text, they do not form part of the input file.

The input file begins with the general data of the adopted mesh. Since the problem must be run until it reaches a steady temperature variation, a long period between 2001/01/01 and 2019/01/01 was chosen. In this example the orientation of the mesh is not necessary, therefore the angles phi and azimuth can be set to any value.

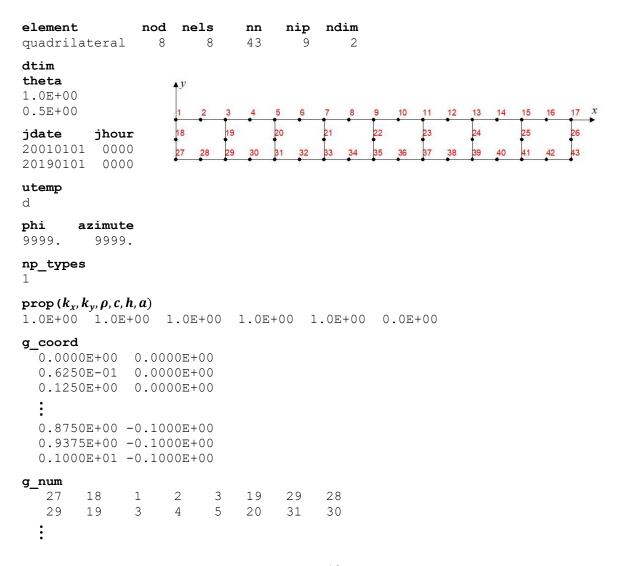
As it was mentioned above, prescribed temperature boundary conditions are applied to the two sides of the wall and adiabatic boundary conditions to the horizontal boundaries.

The periodic temperature is introduced as reservoir water temperature in nodes 1, 18 and 27, thus fixed\_freedom\_1=3. In order to adapt expression (1) to expression (8)  $A_o$  was set to 40°C,  $\tau_o$  to 73 days and the rest of the parameters to zero. To indicate that the model is submerged it was set w1=10.

On the right side, the prescribed temperature is introduced as a fixed temperature in nodes 17, 26 and 43, that is fixed freedom 2=3 and tempin=1.

The adiabatic boundary condition is simulated as a prescribed flux boundary condition with  $q_r = 0$ . However, as  $q_r = 0$  does not contribute to the heat load vector, it is not necessary to specify this boundary conditions. In other words, the adiabatic boundary condition is the default boundary condition.

The last part of the input file refers to the output selection. In this case it was chosen to print node temperatures every 365 time steps by setting npri=365, and to print the whole temperature history of node 22 in order to control the convergence of the results to steady periodic variation.



```
39
       24 13 14 15 25
                               41
                                     40
       25
            15
                     17 26 43
   41
                  16
                                      42
fixed freedoms 1
                               tauo
                                                e1
                                                        e2
                                                                23
                       ao
                                         ce
10.0E+00 0.0E+00 40.0E+00 73.0E+00 0.0E+00 0.0E+00 0.0E+00 0.0E+00 0.0E+00
e5
0.0E+00
(node_1(i),i=1,fixed_freedoms_1)
1 18 27
fixed_freedoms_2
tempin
1
(node_2(i),value_2(i),i=1,fixed_freedoms_2)
17 0.0E+00 26 0.0E+00 43 0.0E+00
hfbc
 0
htbc
 0
indic
 0
val0
0.0E+00
npri
365
nsensors
1
ifile
         sensors(j,:)
         0.5000E+00 -0.5000E-01
Node_22
```

Figure 5 - Mesh and data for the plane wall

In Table 1 the comparison of the last 15 days are shown. As the FEM model computes the temperature at the beginning of each day, the corresponding analytical solution must be computed at day (d-1).

Table 1 - Comparison of FEM with analytical solution

Analytical		FEM	
d	T [°C]	date	T [°C]
351	-1,419	18/12/2019 00:00	-1,419
352	-1,762	19/12/2019 00:00	-1,762
353	-2,105	20/12/2019 00:00	-2,105
354	-2,447	21/12/2019 00:00	-2,447
355	-2,788	22/12/2019 00:00	-2,788
356	-3,129	23/12/2019 00:00	-3,129
357	-3,468	24/12/2019 00:00	-3,468
358	-3,807	25/12/2019 00:00	-3,807
359	-4,144	26/12/2019 00:00	-4,144
360	-4,480	27/12/2019 00:00	-4,480
361	-4,815	28/12/2019 00:00	-4,815
362	-5,149	29/12/2019 00:00	-5,149
363	-5,481	30/12/2019 00:00	-5,481
364	-5,811	31/12/2019 00:00	-5,811
365	-6,139	01/01/2020 00:00	-6,139

## 2.2 Steady-state temperature distribution along a rectangular fin

This example corresponds to a one-dimensional fin exposed to a surrounding fluid at a temperature  $T_{\infty}$  as shown in Figure 6. The temperature of the base of the fin is  $T_o$ .

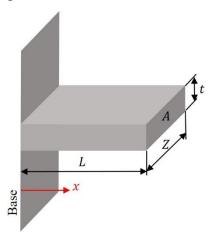


Figure 6 – One-dimensional conduction and convection through a rectangular fin

The solution is given by Holman ([4] §2.9)

$$\frac{T - T_{\infty}}{T_o - T_{\infty}} = \frac{\cosh[m(L - x)] + \left(\frac{h}{mk}\right) \sinh[m(L - x)]}{\cosh(mL) + \left(\frac{h}{mk}\right) \sinh(mL)}$$
(17)

with  $m = \sqrt[2]{h_c P/kA}$  and where P is the perimeter.

It was assumed that the fin is 8.33 cm high, 33.33 cm wide and infinitely long. It is attached to a wall maintained at  $1100^{\circ}$ C, and is immersed in a fluid maintained at  $100^{\circ}$ C. The fin has thermal conductivity of 15 W/(m°C) and a heat convection coefficient of 15 W/(m² °C). These data are similar to the verification problem given in ([5] §3.2.2.2). Figure 7 shows the idealisation of the problem.

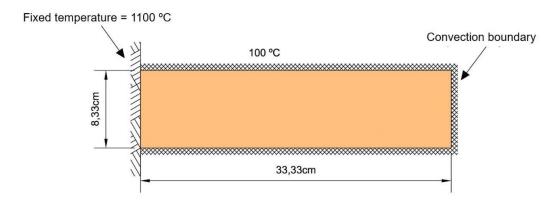


Figure 7 – Idealization of the fin

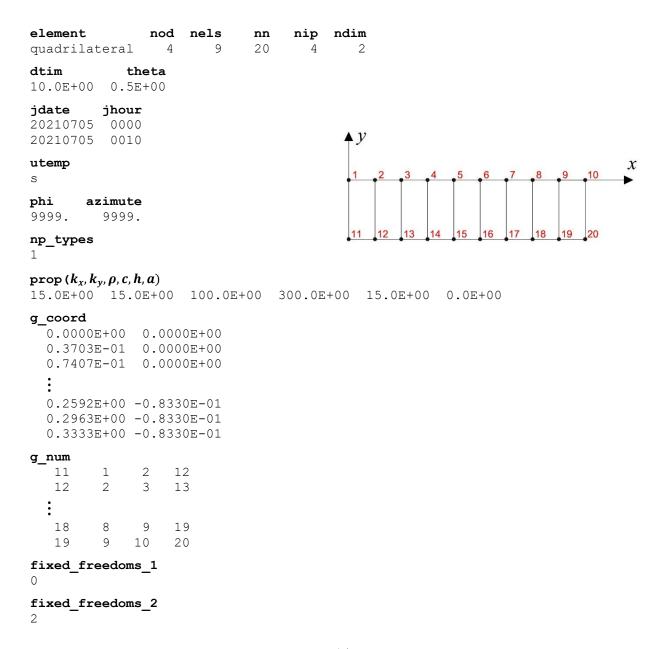
As the fin is infinitely long in the plane perpendicular to the analysed section, the problem can be solved as a 2D problem. In this case, P/A goes to 24 and M has a value of  $\sqrt[2]{24}$ .

For the numerical model, the fin is divided into a row of 9 linear quadrilateral elements. Figure 8 shows the mesh and data used for the analysis.

The fluid temperature is introduced by expression (6), assigned the value of  $100^{\circ}$ C to  $T_m$  and zero to the rest of the parameters.

The problem must be run to reach a steady-state temperature. The history of the temperature of node 3 is used to control the convergence of the problem to a steady-state temperature, and the results are printed only once setting npri=60.

Table 2 shows the comparison between the obtained results and analytical solution.



```
tempin
(node_2(i), value_2(i), i=1, fixed_freedoms_2)
hfbc
htbc
19
airin
1

        t_m1
        t_p1
        delay_1
        t_m2
        t_p2
        delay_2
        delay_3

        100.0E+00
        0.0E+00
        0.0E+00
        0.0E+00
        0.0E+00
        0.0E+00
        0.0E+00

((itrans(i,j),j=1,2),i=1,htbc)
1 4
2 4
3 4
8 3
9 3
9 2
indic
0
val0
0.0E+00
npri
60
nsensors
1
ifile sensors(j,:)
Node 3 0.7407E-01 -0.4165E-01
                                    Figure 8 – Mesh and data for the fin
```

riguic 6 – Wesii and data for the fin

Table 2 – Comparison of FEM with analytical solution

n / I	<i>T</i> [°C]		
x/L	Analytical	FEM	
0.00	1100.0	1100.0	
0.11	943.1	942.8	
0.22	813.9	813.5	
0.33	708.4	707.8	
0.44	622.9	622.3	
0.56	554.7	554.0	
0.67	501.5	500.8	
0.78	461.6	460.9	
0.89	433.5	432.8	
1.00	416.5	415.8	

## 2.3 Conduction through a composite plane wall

An infinite wall consisting of two distinct layers is exposed to an atmosphere at high temperature on one side and low temperature on the other. The wall eventually reaches an equilibrium where it passes a constant flux and the temperature distribution is unchanging ([5] §3.2.2.1).

Figure 9 shows the wall geometry and boundary conditions. The values adopted for the example were thermal conductivities  $k_1 = 1.6$  W/(m °C),  $k_2 = 0.2$  W/(m °C), thickness  $d_1 = 25$  cm,  $d_2 = 15$  cm, convection coefficients  $h_1 = 100$  W/(m² °C),  $h_2 = 15$  W/(m² °C) and temperatures  $T_1 = 3000$  °C,  $T_1 = 25$  °C.

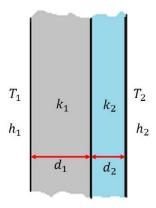


Figure 9 – Composite wall

The solution to this problem is T(0) = 2970 °C,  $T(d_1) = 2497$  °C and  $T(d_1 + d_2) = 226.7$  °C with a linear variation between them.

Since the model is infinitely long in one direction, the model is essentially one-dimensional, and the horizontal boundaries may be represented as adiabatic boundaries. Figure 10 shows the idealization of the wall.

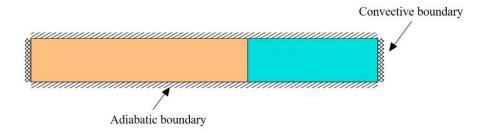


Figure 10 – Idealization of the composite wall

For the numerical model, the wall is divided into two rows of 16 linear quadrilateral elements. Figure 8 shows the mesh and data used for the analysis.

```
nod nels
                             nip ndim
element
                         nn
              4
                    32
                         51
                                4
quadrilateral
           theta
dtim
1.0E+00
         0.5E+00
jdate
        jhour
20200101 0000
                 \triangle y
20200101 0001
                                                                      x
utemp
                                              10
                                                 11
                                                    12
S
phi
      azimute
9999.
        9999.
np_types
prop(k_x, k_y, \rho, c, h, a)
1.6E+00 1.6E+00 1.0E+00 1.0E+00 100.0E+00 0.0E+00
 0.2E+00 0.2E+00 1.0E+00 1.0E+00 15.0E+00 0.0E+00
etype
g coord
 0.0000E+00 0.0000E+00
 0.2500E-01 0.0000E+00
 0.5000E-01 0.0000E+00
 0.3500E+00 -0.5000E-01
 0.3750E+00 -0.5000E-01
 0.4000E+00 -0.5000E-01
g num
  18
       1
             2
                19
  19
        2
            3
                20
                49
  48
       31
            32
  49
       32
            33
                50
  50
       33
            34
                51
fixed freedoms 1
fixed freedoms 2
hfbc
0
htbc
4
airin
 2
nfiles
 2
ifile
```

left.dat

Since there are two different convection boundary conditions, the data is introduced through two files, left.dat and right.dat, shown in Figure 12 and Figure 13, respectively. The values of the temperature and convection coefficient for each time step are then obtained by means of a linear interpolation, therefore, only the extreme values were introduced.

```
20200101 0000 3000.0E+00 100.0E+00
20200101 0001 3000.0E+00 100.0E+00

Figure 12 - File left.dat

20200101 0000 25.0E+00 15.0E+00
20200101 0001 25.0E+00 15.0E+00
Figure 13 - File right.dat
```

Figure 14 shows a graphical representation of the steady-state temperature distribution.

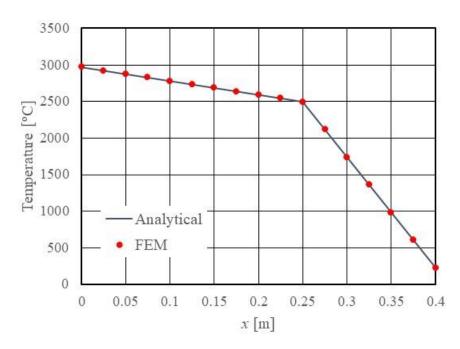


Figure 14 – Composite wall: comparison between FEM and analytical solution

## References

- [1] I.M. Smith, D.V. Griffiths. Programming the finite element method, 4th ed. John Wiley & Sons, Ltd, 2005.
- [2] Z. Bofang. Thermal stresses and temperature control of mass concrete. Elsevier, 2014.
- [3] U. Puppini. Variazioni di temperatura entro masse murarie. Bollettino della Unione Matematica Italiana. Anno 1-N. 1, 1922, pp. 53-57. https://archive.org/details/bollettinodellau01unio
- [4] J.P. Holman. Heat transfer, 10th ed. Mc Graw Hill, 2010.
- [5] Itasca. FLAC Version 2.2, Verification, examples and benchmark problems. 1989.