

# Scrutinizing the linear variable importance of local explanations of non-linear models with animated linear projections

## Abstract

Artificial Intelligence (AI) has seen a revitalization in recent years from the use of increasingly hard-to-interpret black-box models. In such models, increased predictive power comes at the cost of opaque factor analysis, which has led to the field of eXplainable AI (XAI). XAI attempts to shed light on these models. One such approach is *local explanations*. A local explanation of a model gives a point-estimate of linear variable importance in the vicinity of one observation. We extract explanations for each observation and approximate data, and this attribution space side-by-side with linked brushing. After identifying an observation of interest, its local explanation is used as a 1D projection basis. We then manipulate the magnitude of the variable contributions with the *tour* technique. The tour animates many projections over small changes in the projection basis as it changes the contribution of one variable. Doing so allows a user to visually explore the data space through the lens of this local explanation and test its support. The implementation of our framework is available as an **R** package **cheem** available on CRAN.

## 1 Introduction

Mathematically rigorous approaches to predictive modeling are attributed to the least-squares method, over two centuries ago by Legendre and Gauss in 1805 and 1809, respectively. In 1886 Francis Galton coined the term *regression* to refer to continuous, quantitative predictions. While *classification* refers to discrete predictions as introduced by Fisher in 1936.

Breiman and Shmueli (Breiman 2001; Shmueli 2010) introduce the idea of distinguishing modeling based on its purpose; *explanatory* modeling is done for some inferential purpose such as hypothesis testing, while *predictive* modeling predicts new, out-of-sample, observations. This distinction draws attention to the divide between interpretable models and black-box models. The intended use has important implications for model selection and development. In explanatory modeling, interpretability is vital for drawing inferential conclusions. While predictive modeling may opt for more accurate non-linear models, the additional hindrance to interpretation should not be taken lightly.

Interpretability aside, black-box models are becoming increasingly common, but not without their share of controversy (O’neil 2016; Kodyan 2019). Black-box models have been known to reflect common biases, including sex (Dastin 2018; Duffy 2019), race (Larson et al. 2016), and age (Díaz et al. 2018). Such issues occur when biases existent in the training data, the model picks up on this influence on the response variable, which is then built into the model. Another issue is data drift when new data is outside the support of latent or exogenous explanatory variables. Data drift can lead to worse predictions (Lazer et al. 2014; Salzberg 2014). While typically more resistant to data drift, linear models will similarly find biases in the data. However, their transparency goes a long way into exploring and mitigating the biases. Such cases highlight the need to make models fair, accountable, ethical, and transparent, which has led to the movement of XAI (Adadi and Berrada 2018; Arrieta et al. 2020).

One branch of XAI is local explanations, which take a variable attribution approach to bring transparency to a model. Local explanations attempt to approximate linear variable importance at the location of one observation. There are many such local explanations.

In multivariate data visualization, a *tour* (Asimov 1985; Buja and Asimov 1986; S. Lee et al. 2021) is a sequence of linear projections of data onto a lower-dimensional space, typically 1-3D. Tours are viewed as an animation over minor changes to the projection basis. Structure in a projection can then be explored visually to see which variables contribute to the formation of that structure. The intuition is similar to watching

the shadow of a hidden 3D object change as the object is rotated; watching the shape of the shadow change conveys information of the structure and features of the object.

There are various types of tours distinguished by the generation of projection bases. In a *manual* tour (Cook and Buja 1997; Spyrisson and Cook 2020), the path is defined by changing the contribution of a selected variable. Applying tours to models has been done in a couple of contexts. Specifically for exploring various statistical model fits and classification boundaries (Wickham, Cook, and Hofmann 2015), and using tree- and forest-based approaches as a projection pursuit index to generate a tour basis path (Y. D. Lee et al. 2013; Silva, Cook, and Lee 2021).

The proposed approach uses the radial, manual tour to scrutinize a local explanation. After identifying an observation of interest, its explanation can be evaluated by testing the support of the structure identified by the explanation as the contributions of the variables are varied with the radial tour. We provide a free and open-source R package **cheem** with an interactive application to facilitate analysis. We provide toy and modern datasets case studies for both classification and regression tasks.

The change in the projection basis might feel similar to counterfactual, what-if analysis, such as *ceteris paribus* (Biecek 2020). This phrase, Latin for “other things held constant” or “all else unchanged,” shows how an observation’s prediction would change from a marginal change in one explanatory variable given that other variables are held constant. It ignores correlations of the variables and imagines a case that was not observed. In contrast, our approach is a geometric explanation of the factual; it varies contributions of the variables by rotating the basis, a reorientation of the data object. Another difference is that the basis must remain orthonormal. That is to say, when the contribution of one variable decreases, the contributions of others necessarily increase such that there is a complete component in that direction.

The remainder of this paper is organized as follows. The following section, **Local explanation statistics**, covers the background of the local explanation, SHAP, and the traditional visuals produced from it. **Tours and the radial tour** digs deeper into these animations of continuous linear projections. The section **Application Design** discusses the visual layouts, how they facilitates analysis, data preprocessing, and package infrastructure. The section **Case Studies** illustrates several applications of this method. We conclude with a **Discussion** of the insights we draw from classification and regression tasks.

## 2 Local explanation statistics

Consider a highly non-linear model. At face value, it is hard to say which variable(s) are sensitive to crossing a classification boundary or identify which variables caused an observation to have a relatively extreme residual. Local explanations shed light on these cases by approximating linear variable importance in the vicinity of one observation.

Figure six of Arrieta et al. (2020) gives comprehensive summarization of the taxonomy and literature of explanation techniques. The figure includes a large number of model-specific explanations such as deepLIFT, (Shrikumar et al. 2016; Shrikumar, Greenside, and Kundaje 2017) a popular recursive method for estimating importance in neural networks. There are fewer model-agnostic explanations, of which LIME, (Ribeiro, Singh, and Guestrin 2016) SHAP, (S. Lundberg and Lee 2017) and their variants are popular.

These instance-level explanations are used in various ways depending on the data. In images, saliency maps overlay or offset a heatmap indicating which pixels were necessary (Simonyan, Vedaldi, and Zisserman 2014). For instance, snow may be highlighted when distinguishing if a picture contains a wolf or husky. In text analysis, word-level contextual sentiment analysis can be used to highlight the sentiment and magnitude of influential words (Vanni et al. 2018). In the case of numeric regression, they are used to explain variable additive contributions from the model intercept to the observation’s prediction (Ribeiro, Singh, and Guestrin 2016).

### 2.1 SHAP and tree SHAP

SHaply Additive exPlanations (SHAP) approximates the variable importance in the vicinity of one observation by taking the median importance of a subset of permutations in the explanatory variables. This idea stems

from the field of game theory, where Shapley (1953) devised a method to evaluate an individual’s contribution to cooperative games by permuting the players that contribute to the score.

To illustrate SHAP and its original use, explaining the difference between the intercept and an observation’s prediction, we use soccer data from FIFA 2020 season (Leone 2020). We have 5000 observations of nine skill measures (after aggregating highly correlated variables). A random forest model is fit to regress the log wages, in 2020 Euros, from the skill measures. We then extract the SHAP values of a star offensive player (L. Messi) and defensive player (V. van Dijk). We expect to see a difference in the attribution of the variable importance across the two positions of the players.

Figure 1 shows the SHAP values of these players. Panel a) shows these players receive a sizable difference in wages. Panel b) shows the underlying distribution of the SHAP attributions while permuting the explanatory variables, with the medians being the SHAP values. In the light of the player position, the difference in the variable importance makes sense; offense and movement skills are more important for the offensive player, while defensive and power skills are more informative to the model for explaining the prediction of the defensive player. We would likewise expect the profile of variable importance to be unique for star players of other positions, such as goalkeepers or middle fielders. Panel b) shows a simplified break-down plot (Gosiewska and Biecek 2019), where a local explanation is used to additively explain the difference from the intercept to the observation’s prediction. Such additive approaches will show asymmetry in the variable ordering, so we opt to fix the order to panel a), by decreasing sum of the SHAP values.

In summary, this figure highlights how local explanations bring interpretability to a model, at least in the vicinity of their observations. In this instance, two players with different positions receive different profiles of variable importance to explain the prediction of their wages. In application we apply *tree SHAP*, a variant of SHAP that enjoys a lower computational complexity (S. M. Lundberg, Erion, and Lee 2018). Tree SHAP only compatible with tree-based models; we illustrate on random forests. In the following section, we will use normalized explanations as the starting projection basis to further scrutinize the explanation.

### 3 Tours and the radial tour

A data visualization *tour* animates many linear projections over small changes in the basis. One of the critical features of the tour is the object permanence of the data points; one can track the relative changes of observations as the basis moves, as opposed to discretely jumping to an orthogonal view with no intermediate information. There are various types of tours that are distinguished by selecting their basis paths (S. Lee et al. 2021; Cook et al. 2008).

#### 3.1 Manual tours and its radial case

The manual tour (Cook and Buja 1997) defines its basis path by manipulating a selected variable’s basis contribution. A manipulation dimension is appended onto the projection plane, giving a full contribution to the chosen variable. The bases are then selected based on rotating this newly created manipulation space. A crucial feature of the manual tour is that it allows users to control the variable contributions of the basis. Such manipulations can be selected and queued in advance or selected on the spot for human-in-the-loop analysis (Karwowski 2006). However, this navigation is relatively time-consuming due to the vast volume of the display-space. It is advisable to use this method to explore the sensitivity of the variable contribution to a previously identified feature of interest. In this case, the projection of the normalized explanations is the feature of interest.

More generally, the manual tour can change the contribution of a variable to the display dimensions. We will apply a more directed interaction, namely, a *radial* tour. In a radial tour, the selected variable is allowed to change its magnitude of contribution but not its angle; it must move along the direction of its original contribution.

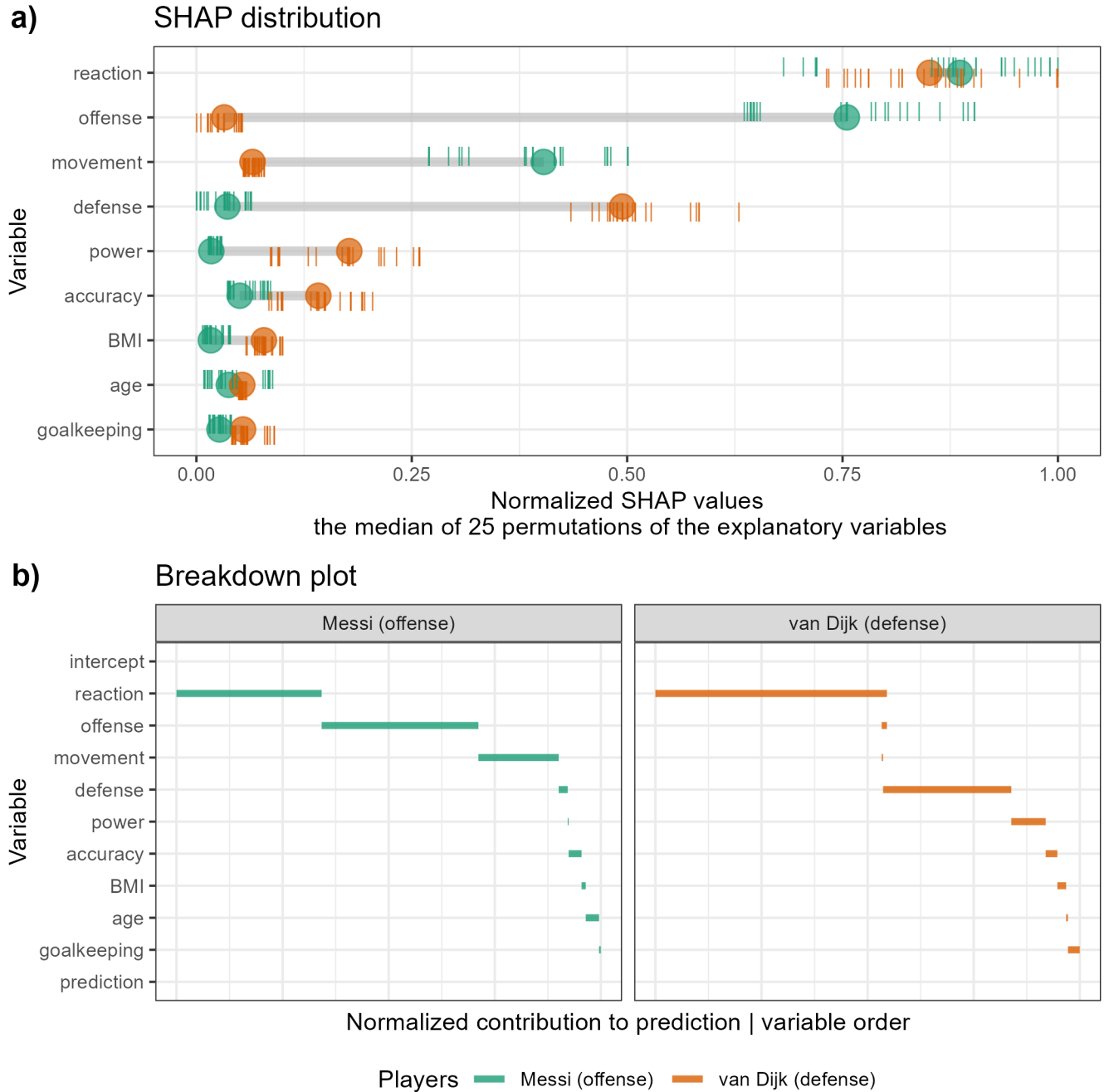


Figure 1: Illustration of the distribution of SHAP attributions and a break-down plot. From FIFA 2020 data, a random forest model regresses wages from nine skill attributes for a star offensive and defensive player. The players have very different salaries, but a) shows the distributions of 25 permutations in the explanatory variables. The medians of these distributions are the final SHAP values. The variable importance differs across the exogenous information of player position. These explanations make sense; the variable importances seem realistic given the player's positions. b) Break-down plots of the observations using their explanations to additively cover the difference between the model intercept and the observation predictions.

## 4 cheem viewer

Below we illustrate the two primary displays of the cheem viewer application: the global view and the tour view. Then we cover what we take away from the classification and regression tasks. Lastly, we discuss the preprocessing the data before application runtime.

### 4.1 Global view

The global view provides an essential context of all observations and facilitates the exploration of the separability of the data- and attribution-spaces. While comparison of these spaces is interesting, the global view’s purpose is to facilitate the selection of observations. The local explanation of these points will be explored in more detail.

An approximation of these spaces is given as the first two principal components of their respective spaces. Model information, observed response by its prediction, is also provided. The orientation and magnitude of the variables are inscribed on a unit circle. Misclassified observations are circled in red if applicable. Linked brushing between the plots and tabular display of select points facilitates exploration of the spaces and the model. A single 2D projection will not encompass all of the structure of higher-dimensional space. However, it is a reasonable summarization given the real task at hand; the selection of observations to explore further.

### 4.2 Radial cheem tour

The global view facilitated the selection of a primary and optional comparison observation. The variable-level attribution of the primary observation is normalized and used as the initial 1D basis in a radial tour. This is an approximation of the contributions of the linear variables that best explain the difference between the model intercept and an observation’s prediction, not the local shape of the model surface.

The initial frame is the normalized SHAP values of the primary observation. The current projection basis is depicted as the width of a bar, the variable’s contribution to the horizontal axis. The normalized values of all observations are shown as vertical parallel coordinate plots.

The radial tour creates a basis path by varying the contribution of a selected variable, fully into and out of a projection frame. Doing so tests an individual variable’s sensitivity to the structure identified by the local explanation. The default variable selected has the largest discrepancy between the attribution of primary and comparison observations. The following sections elaborate on the takeaways we draw from applying this approach in classification and regression tasks, respectively. Now that we have introduced the global view and corresponding cheem radial tour let us discuss the differences between the classification and regression cases.

### 4.3 Classification task

What information do we glean from using this method on a classification task? Typically we select a misclassified observation compared to a correctly classified point nearby in data space. The initial frame is the linear attribution of that observation’s local explanation. By default, the manual tour varies the contribution of the variable with the largest difference between the primary and comparison observation. That is, we can test the sensitivity of each variable to structure identified by the local explanation; we are exploring the support of the explanation, evaluating the support or robustness of the prediction.

### 4.4 Regression task

In the regression case, the global view can be colored on a statistic to highlight the structure in the explanation space, including residuals, log Mahalanobis distance of data space (a measure of outlyingness), and the correlation of the attribution projection with the observed response. In the radial tour, the horizontal positions are the same, the basis projection of the radial tour. The vertical position is fixed to the observed response variable and residuals in the middle and right panels, respectively. Correspondingly, the display changes from univariate density to 2D scatterplot. The basis is still one component (horizontal) independent of the vertical position.



Figure 2: Display illustrating the classification case. Plots are colored on predicted class and red circles indicate misclassified observations. The radial tour is a 1D projection starting at the normalized tree SHAP values of the primary point. The first frame is the linear-variable importances that best describe the difference from model intercept to this observation's prediction. We probe the support of the variable contributions by selecting a variable to vary the contribution.



Figure 3: Display of the regression task. The global view can be colored on the correlation of the attribution projection and observed response. In the tour, the horizontal values are the same as the classification case; the projection through the basis. The vertical position is now mapped to the observed  $y$  and residuals.

## 4.5 Interactive features

The application has several reactive inputs that affect the data used, aesthetic display, and tour manipulation. These reactive inputs make the software flexible and extensible. The application also has more exploratory interactions to help link points in the data and extract other information not on plot axes.

A tooltip displays observation number/name and classification information while the cursor hovers over a point. Linked brushing allows the selection of points (left click and drag) where those points will be highlighted across plots. The information corresponding to the selected points is populated on a dynamic table. These interactions aid exploration of the spaces and, finally, identification of a primary and comparison observation.

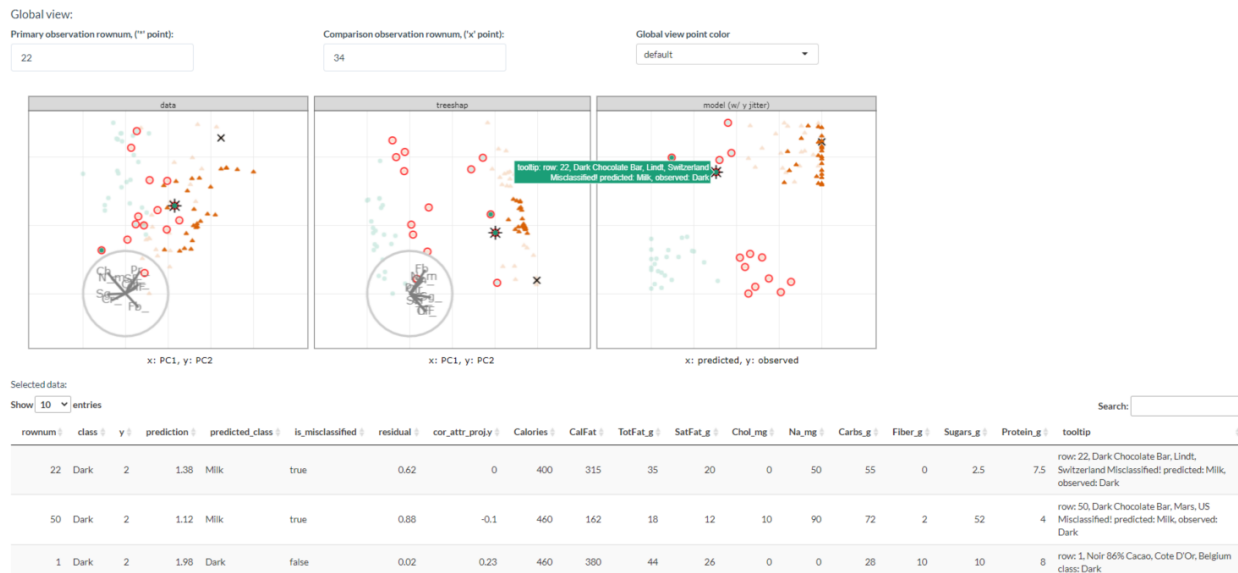


Figure 4: Illustration of data explorations interactions in the global view. This view has linked brushing of the points where observations selected in one facet are highlighted in the other facets and populate an interactive tabular display below. Tooltips display when hovering over an observation.

## 4.6 Preprocessing

It is vital to mitigate the render time of visuals, especially when users may want to iterate many times. In order to keep render time low all of the computational operations should be prepared before runtime. The work remaining at runtime is solely reacting to inputs and rendering of visuals and tables. Below we discuss the steps and details of the preprocessing.

- **Data:** a complete numerical matrix; explanatory and response variable. An optional categorical variable can be mapped to the color and shape of observations. Explanatory variables are scaled in visualization after modeling or creating local explanations.
- **Model:** any model can be used with this method. Currently, we apply random forest models via the package **randomForest** [Liaw and Wiener (2002)] for compatibility with the local explanation, which requires tree-based models.
- **Local explanation:** any model-compatible linear explanation could be used. We apply tree SHAP, a more computationally efficient variant of SHAP, compatible with tree-based models. Tree SHAP was calculated with the package **treeshap** [Kominsarczyk et al. (2021), hosted on GitHub only]. The global view shows all observations in attribution space, requiring the variable importance from *all* observations rather than just one.



The time to preprocess the data will vary significantly with the model and local explanation. For reference, the FIFA data, 5000 observations of nine explanatory variables, took 2.9 seconds to fit a random forest model of modest hyperparameters. Extracting the tree SHAP values of each observation took 254 seconds combined. PCA and statistics of the variables and attributions took 0.6 seconds. These runtimes were from a non-parallelized R session on a modern laptop, but suffice to say that the bulk of the time will be spent on the local attribution. An increased of model complexity or data dimensionality will quickly become an obstacle. This makes tree SHAP, with its reduced computational complexity, a good candidate to start with. Alternatively, the package **fastshap** (Greenwell 2020) claims extremely low runtimes, which are attributed to fewer calls to the prediction function, partial implementation in C++, and efficient use of logical subsetting.

## 4.7 Package infrastructure

The above-described method and application are implemented as an open-source **R** package, **cheem** available on [CRAN](#). Preprocessing was facilitated with models created via **randomForest** (Liaw and Wiener 2002), and explanations calculated with **treeshap** (Kominsarczyk et al. 2021). The application was made with **shiny** (Chang et al. 2021). The tour visual is built with **spinifex** (Spyrison and Cook 2020). Both views are created first with first with **ggplot2** (Wickham 2016) and then rendered as interactive HTML widgets with **plotly** (Sievert 2020). **DALEX** (Biecek 2018) and the free ebook, *Explanatory Model Analysis* (Biecek and Burzykowski 2021) were a huge boon to understanding local explanations and how to apply them.

## 4.8 Installation and getting started

The following **R** code will help getting up and running:

```
## Download the package
install.packages("cheem", dependencies = TRUE)
## Restart the R session so the IDE has the correct directory structure
restartSession()
## Load cheem into session
library("cheem")
## Try the app
run_app()

# Processing your data
## Install treeshap from github, to use as a local explainer
remotes::install_github('ModelOriented/treeshap') ## Local
## Follow the examples in cheem_ls()
?cheem_ls
```

# 5 Case studies

To illustrate the use of the cheem method, we apply it to modern datasets, two classification examples and then two of regression.

## 5.1 1) Penguin, species classification

Palmer penguins data (Gorman, Williams, and Fraser 2014; Horst, Hill, and Gorman 2020) consist of 330 observations across four physical measurements of three species of penguins foraging near Palmer Station, Antarctica. A random forest model was fit, classifying the species of the penguin given the physical measurements.

In figure 5, a misclassified point is contrasted with a correctly classified point of its observed class nearby in data-space. The attribution space from the tree SHAP local explanations is a more separable space, where the comparison is squarely in the middle of the orange distribution. The primary observation is between the predicted and observed clusters, a sign of uncertainty in the prediction. The tour varies the contribution of bill

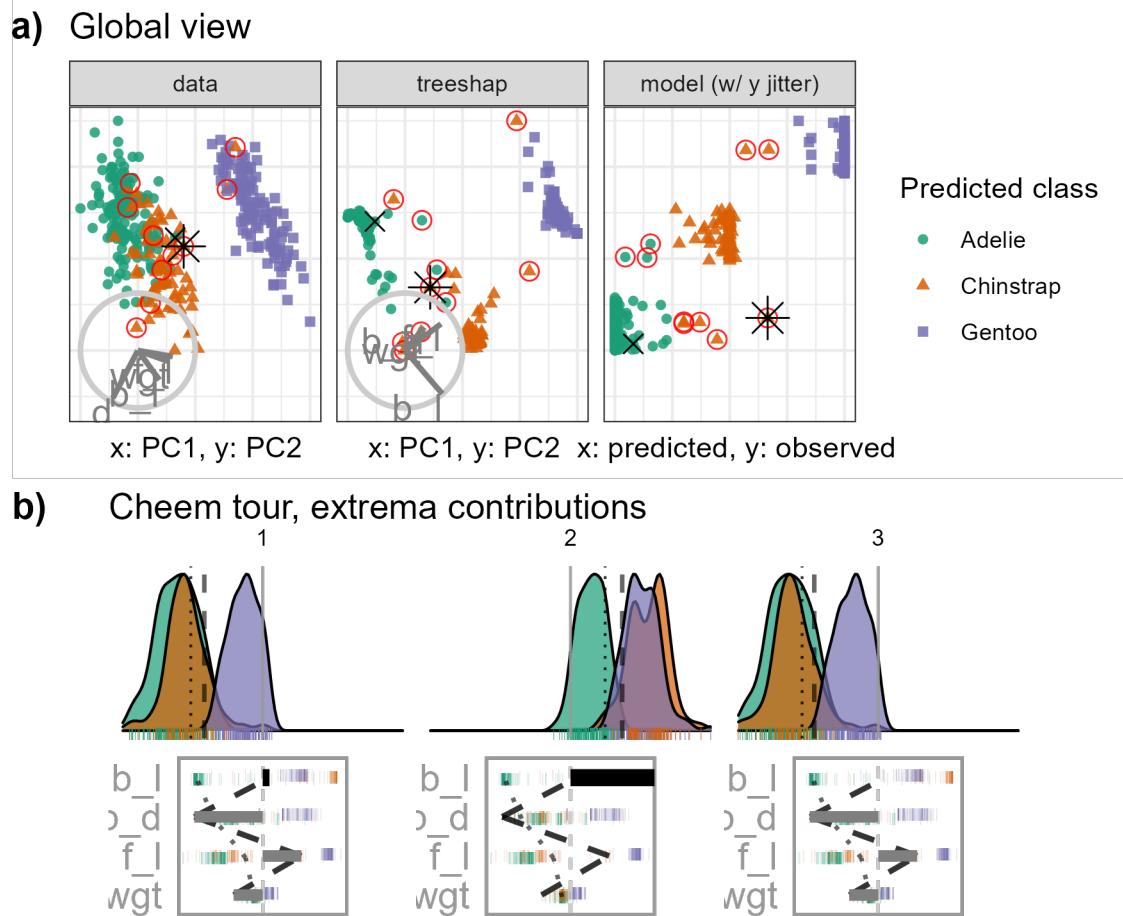


Figure 5: Species classification of Palmer penguin data.

length (b\_l) as this variable differs most from the contribution of the comparison observation. Downplaying the contribution of bill length is crucial to the linear explanation of this observation being misclassified.

## 5.2 2) Chocolates, milk/dark chocolate classification

The chocolates dataset consists of 88 observations of 10 nutritional measurements from their labels. Each of which was labeled as being either milk or dark chocolates. With this data, we can see if a manufacturer accurately portrays the chocolate. We are curious to see if there are chocolates that nutritionally look like milk chocolates labeled as dark chocolates, which may hold a higher market value. We should note that not all chocolates consist wholly of chocolate. The addition of other ingredients will decrease the predictive power of the model nutritional explanatory variable. A random forest model is fit classifying the type of chocolate. We selected a chocolate labeled dark, through predicted to be milk chocolate compared with a chocolate labeled 85% cocoa.

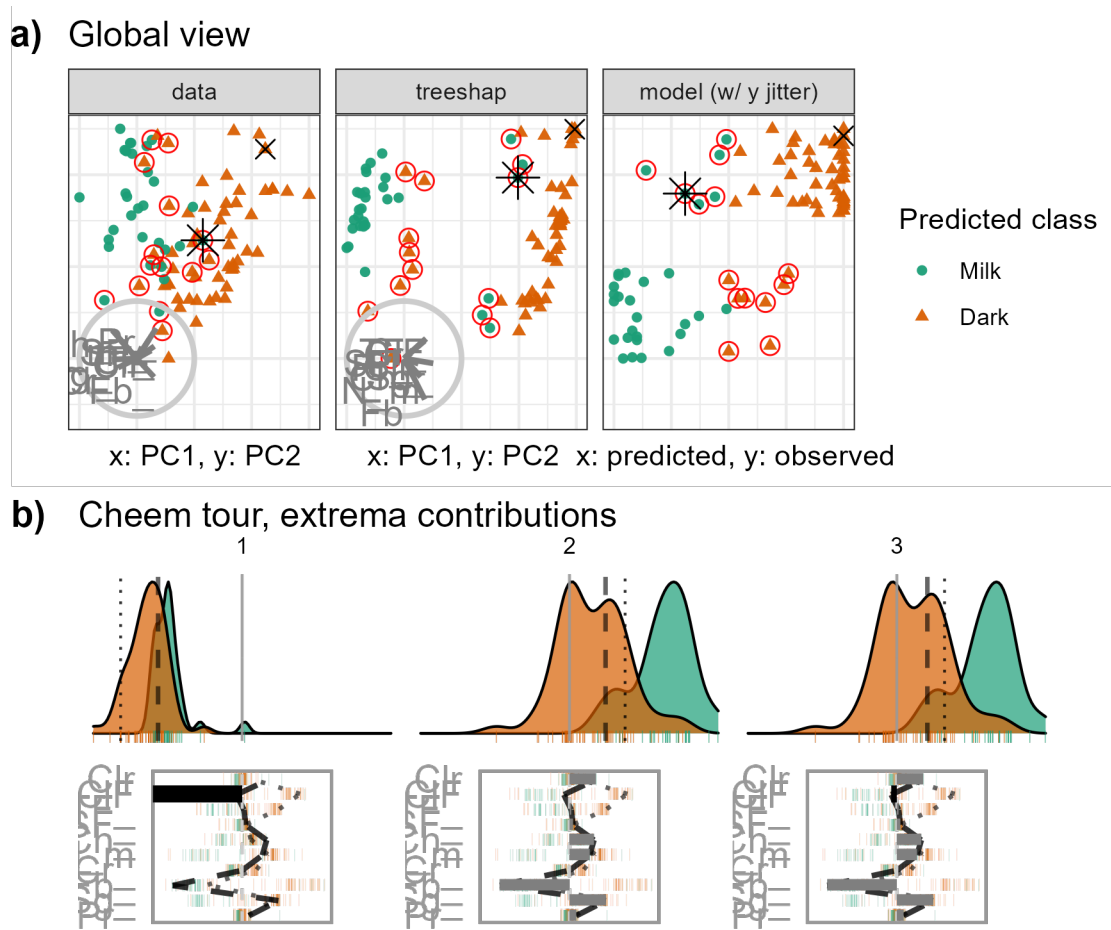


Figure 6: Chocolates data type classification (milk or dark).

In figure 6, we similarly see that attribution space is more separable than data-space. Interestingly, the class imbalance that we suspected was not observed; there are only six chocolates labeled as dark and predicted as milk, while eight of the inverse case. Calories from fat is the variable with the largest difference in treeshap attribution between these points.

### 5.3 3) FIFA, wage regression

The 2020 season FIFA data (Leone 2020; Biecek 2018) contains many skill measurements of soccer/football players and wage information. After aggregation of the skill measurements, we regress the log wages [2020 euros] given just the skill aggregates. The model was fit from 5000 observations of the nine skill aggregates before being thinned to 500 players to mitigate occlusion and render time. We compare a leading offensive fielder (L. Messi) with that of a top defensive fielder (V. van Dijk), the same observations were used in figure 1.

With figure 7, we will test the premise of the local explanation. If we remove reaction and movement skills from the basis, then offense skills have almost singular importance for explaining the offensive player. We vary the contribution of offensive skills. In the tour (panel b, frame 3), offensive skills are removed, and Messi is no longer separated from the group. We also notice that accuracy has rotated into the frame, maintaining some separability.

### 5.4 4) Ames housing 2018, sales price regression

Ames 2018, housing data was subset to North Ames (the neighborhood with the most house sales). The remaining are 338 house sales across nine variables. Using interaction from the global view, we select a house with an extreme negative residual and an accurate observation close to it in the data.

Figure 8 shows the global view and extrema of the tour. The horizontal distance in the tour didn't show a significant disparity between our selected points. This is not particularly surprising as most variables have a sizable contribution. Rotating any one variable out of the frame will rotate other vital variables into the frame, preserving most of the distance from intercept to prediction. However, the tour has revealed an interesting feature worth discussing. Notice that the observations pivot about the origin, the basis roughly halfway between bases in frames one and two of panel b) the data is near a singular profile. This means that there is a basis orthogonal to this point that describes sizable variation. Knowing these singular bases can point toward others with meaningful data variation.

## 6 Discussion

The need to maintain the interpretability of black-box models is evident. One aspect uses local explanations of the model in the vicinity of an observation. Local explanations approximate the linear variable importance to the model. Our contribution is to assess explanations by examining the support by varying the contributions with a radial tour. First, a global view visualizes approximations of the data and explanation spaces side-by-side, using dynamic interaction to compare and contrast and, identify primary and comparison observations of interest. The normalized linear importance from the explanation of the primary observation becomes the feature of interest to further explore with radial tour. The variable sensitivity to the structure identified in the explanation is explored by the tours.

We have illustrated this method on random forest models using the tree SHAP local explanation, while it could be generally used with any compatible model-explanation pairing. We apply it to the classification and regression tasks. We have created an open-source **R** package **cheem**, available on [CRAN](#), to facilitate preprocessing and exploration with the described interactive application. Toy and real data are provided, or upload your data after preprocessing.

## 7 Acknowledgments

We would like to thank Professor Przemyslaw Biecek for his input early in the project and to the broader MI<sup>2</sup> lab group for the **DALEX** ecosystem of **R** and **Python** packages. This research was supported by Australian Government Research Training Program (RTP) scholarships. Thanks to Jieyang Chong for helping proofread this piece.

The namesake, Cheem, refers to a fictional race of humanoid trees from Doctor Who lore. **DALEX** pulls on from that universe, and we initially apply tree SHAP explanations specific to tree-based models.

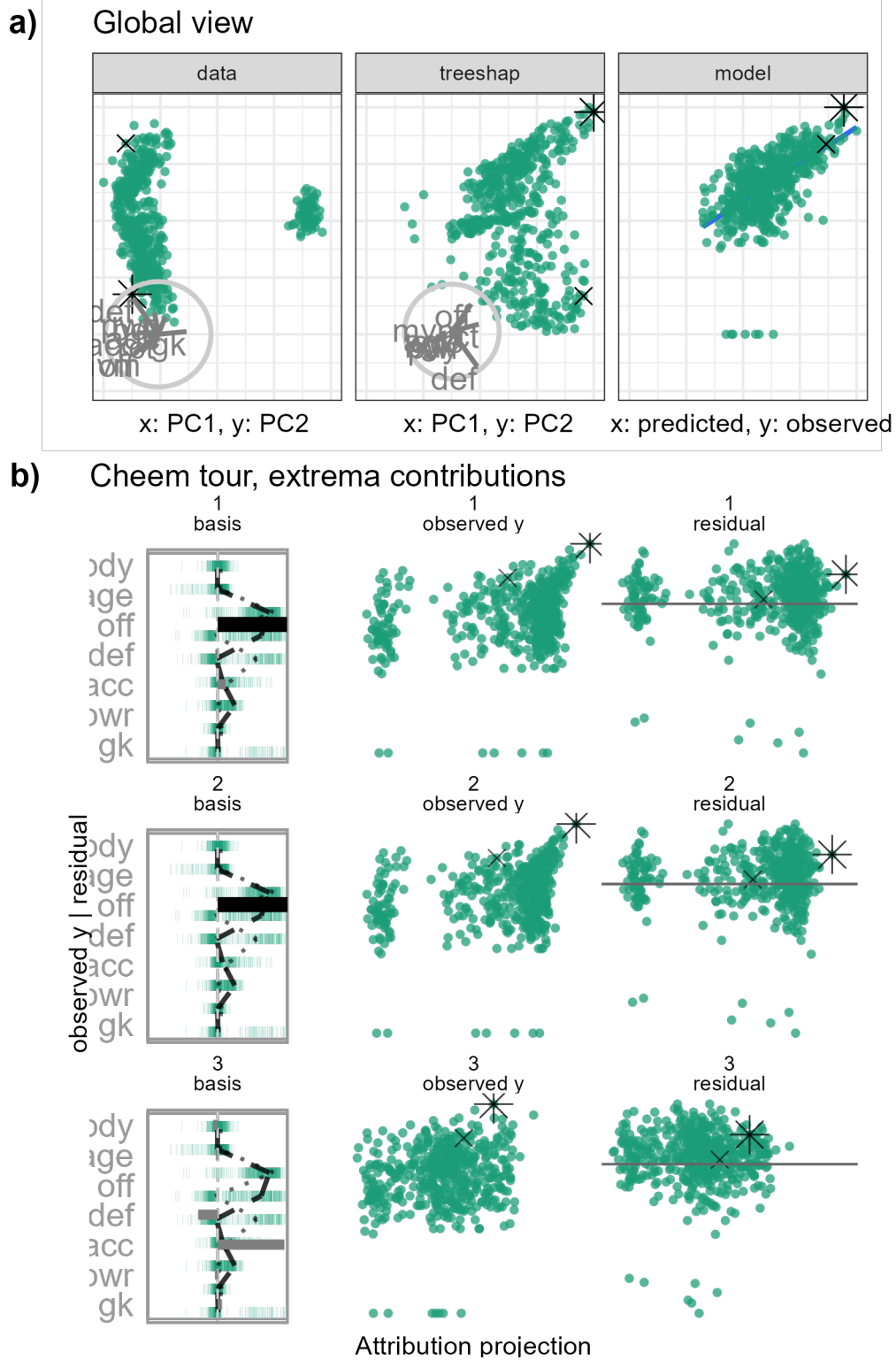
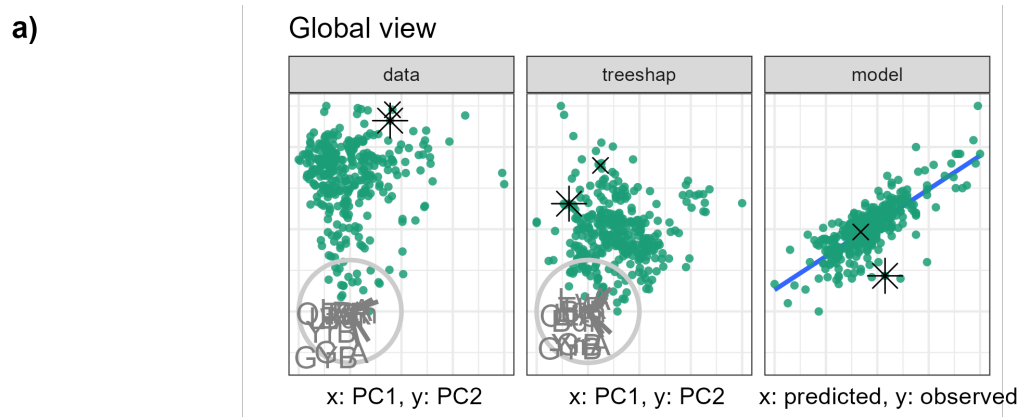


Figure 7: FIFA 2020, regressing log wages [2020 Euros] from aggregations of skill measurements. The primary observation is a star offensive player (L. Messi) compared with a top defensive player (V. van Dijk).



b)

Cheem tour, select frames

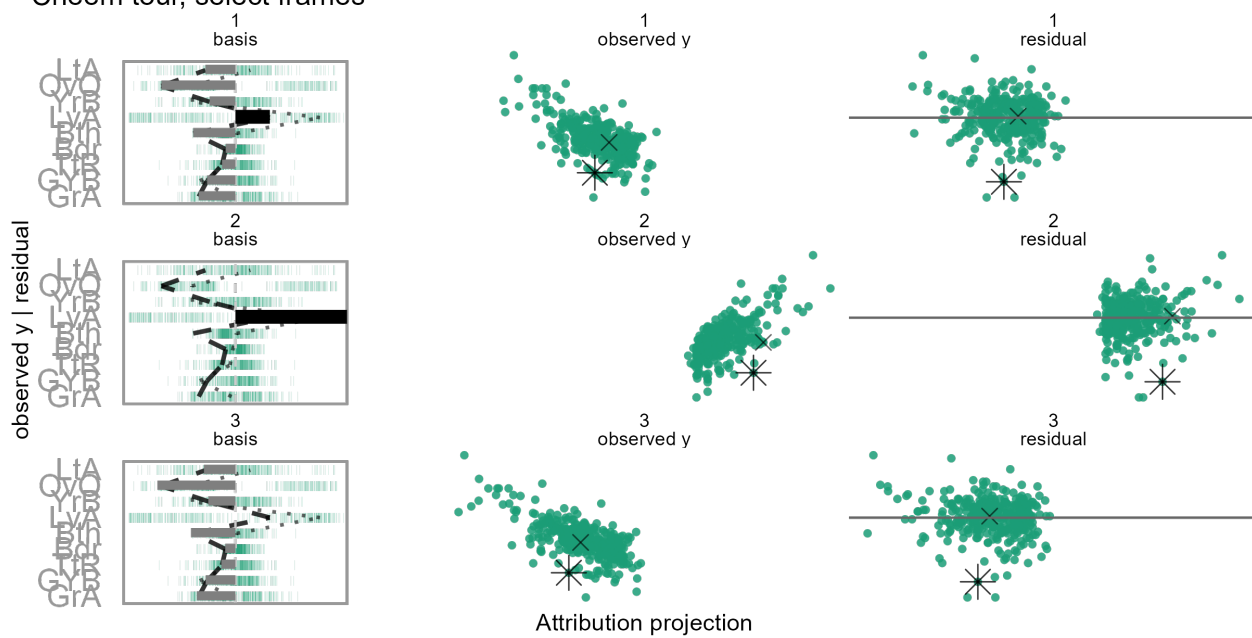


Figure 8: Ames housing 2018 regressing log sales price [2018 USD].

## References

- Adadi, Amina, and Mohammed Berrada. 2018. “Peeking Inside the Black-Box: A Survey on Explainable Artificial Intelligence (XAI).” *IEEE Access* 6: 52138–60.
- Arrieta, Alejandro Barredo, Natalia Díaz-Rodríguez, Javier Del Ser, Adrien Bennetot, Siham Tabik, Alberto Barbado, Salvador García, Sergio Gil-López, Daniel Molina, and Richard Benjamins. 2020. “Explainable Artificial Intelligence (XAI): Concepts, Taxonomies, Opportunities and Challenges Toward Responsible AI.” *Information Fusion* 58: 82–115.
- Asimov, Daniel. 1985. “The Grand Tour: A Tool for Viewing Multidimensional Data.” *SIAM Journal on Scientific and Statistical Computing* 6 (1): 128–43. <https://doi.org/https://doi.org/10.1137/0906011>.
- Biecek, Przemyslaw. 2018. “DALEX: Explainers for Complex Predictive Models in R.” *The Journal of Machine Learning Research* 19 (1): 3245–49.
- . 2020. *ceterisParibus: Ceteris Paribus Profiles*. <https://CRAN.R-project.org/package=ceterisParibus>.
- Biecek, Przemyslaw, and Tomasz Burzykowski. 2021. *Explanatory Model Analysis: Explore, Explain, and Examine Predictive Models*. CRC Press.
- Breiman, Leo. 2001. “Statistical Modeling: The Two Cultures (with Comments and a Rejoinder by the Author).” *Statistical Science* 16 (3): 199–231.
- Buja, Andreas, and Daniel Asimov. 1986. “Grand Tour Methods: An Outline.” In *Proceedings of the Seventeenth Symposium on the Interface of Computer Sciences and Statistics on Computer Science and Statistics*, 63–67. New York, NY, USA: Elsevier North-Holland, Inc. <http://dl.acm.org/citation.cfm?id=26036.26046>.
- Chang, Winston, Joe Cheng, JJ Allaire, Carson Sievert, Barret Schloerke, Yihui Xie, Jeff Allen, Jonathan McPherson, Alan Dipert, and Barbara Borges. 2021. *Shiny: Web Application Framework for r*. <https://CRAN.R-project.org/package=shiny>.
- Cook, Dianne, and Andreas Buja. 1997. “Manual Controls for High-Dimensional Data Projections.” *Journal of Computational and Graphical Statistics* 6 (4): 464–80. <https://doi.org/10.2307/1390747>.
- Cook, Dianne, Andreas Buja, Eun-Kyung Lee, and Hadley Wickham. 2008. “Grand Tours, Projection Pursuit Guided Tours, and Manual Controls.” In *Handbook of Data Visualization*, 295–314. Berlin, Heidelberg: Springer Berlin Heidelberg. [https://doi.org/10.1007/978-3-540-33037-0\\_13](https://doi.org/10.1007/978-3-540-33037-0_13).
- Dastin, Jeffrey. 2018. “Amazon Scraps Secret AI Recruiting Tool That Showed Bias Against Women.” *Reuters*, October. <https://www.reuters.com/article/us-amazon-com-jobs-automation-insight-idUSKCN1MK08G>.
- Díaz, Mark, Isaac Johnson, Amanda Lazar, Anne Marie Piper, and Darren Gergle. 2018. “Addressing Age-Related Bias in Sentiment Analysis.” In *Proceedings of the 2018 Chi Conference on Human Factors in Computing Systems*, 1–14.
- Duffy, Claire. 2019. “Apple Co-Founder Steve Wozniak Says Apple Card Discriminated Against His Wife.” *CNN*, November. <https://www.cnn.com/2019/11/10/business/goldman-sachs-apple-card-discrimination/index.html>.
- Gorman, Kristen B., Tony D. Williams, and William R. Fraser. 2014. “Ecological Sexual Dimorphism and Environmental Variability Within a Community of Antarctic Penguins (Genus *Pygoscelis*).” *PloS One* 9 (3): e90081.
- Gosiewska, Alicja, and Przemyslaw Biecek. 2019. “IBreakDown: Uncertainty of Model Explanations for Non-Additive Predictive Models.” *arXiv Preprint arXiv:1903.11420*.
- Greenwell, Brandon. 2020. *Fastshap: Fast Approximate Shapley Values*. <https://CRAN.R-project.org/package=fastshap>.
- Horst, Allison Marie, Alison Presmanes Hill, and Kristen B. Gorman. 2020. “Palmerpenguins: Palmer Archipelago (Antarctica) Penguin Data.” <https://allisonhorst.github.io/palmerpenguins/>.



- Karwowski, Waldemar. 2006. *International Encyclopedia of Ergonomics and Human Factors*, -3 Volume Set. CRC Press.
- Kodiyan, Akhil Alfons. 2019. “An Overview of Ethical Issues in Using AI Systems in Hiring with a Case Study of Amazon’s AI Based Hiring Tool.” *Researchgate Preprint*.
- Kominsarczyk, Konrad, Pawel Kozminski, Szymon Maksymiuk, and Przemyslaw Biecek. 2021. “Treeshap.” Model Oriented. <https://github.com/ModelOriented/treeshap>.
- Larson, Jeff, Surya Mattu, Lauren Kirchner, and Julia Angwin. 2016. “How We Analyzed the COMPAS Recidivism Algorithm.” *ProPublica*, May. [https://www.propublica.org/article/how-we-analyzed-the-compas-recidivism-algorithm?token=RPR1E2qtzJlftJ0tS-gB\\_41kmfoWZAu4](https://www.propublica.org/article/how-we-analyzed-the-compas-recidivism-algorithm?token=RPR1E2qtzJlftJ0tS-gB_41kmfoWZAu4).
- Lazer, David, Ryan Kennedy, Gary King, and Alessandro Vespignani. 2014. “The Parable of Google Flu: Traps in Big Data Analysis.” *Science* 343 (6176): 1203–5.
- Lee, Stuart, Dianne Cook, Natalia da Silva, Ursula Laa, Nicholas Spyrisson, Earo Wang, and H. Sherry Zhang. 2021. “The State-of-the-Art on Tours for Dynamic Visualization of High-Dimensional Data.” *WIREs Computational Statistics* n/a (n/a): e1573. <https://doi.org/10.1002/wics.1573>.
- Lee, Yoon Dong, Dianne Cook, Ji-won Park, and Eun-Kyung Lee. 2013. “PPtree: Projection Pursuit Classification Tree.” *Electronic Journal of Statistics* 7: 1369–86.
- Leone, Stefano. 2020. “FIFA 20 Complete Player Dataset.” <https://kaggle.com/stefanoleone992/fifa-20-complete-player-dataset>.
- Liaw, Andy, and Matthew Wiener. 2002. “Classification and Regression by randomForest.” *R News* 2 (3): 18–22.
- Lundberg, Scott M., Gabriel G. Erion, and Su-In Lee. 2018. “Consistent Individualized Feature Attribution for Tree Ensembles.” *arXiv Preprint arXiv:1802.03888*.
- Lundberg, Scott, and Su-In Lee. 2017. “A Unified Approach to Interpreting Model Predictions.” *arXiv Preprint arXiv:1705.07874*.
- O’neil, Cathy. 2016. *Weapons of Math Destruction: How Big Data Increases Inequality and Threatens Democracy*. Crown.
- Ribeiro, Marco Tulio, Sameer Singh, and Carlos Guestrin. 2016. “‘Why Should I Trust You?’: Explaining the Predictions of Any Classifier.” *arXiv:1602.04938 [Cs, Stat]*, February. <http://arxiv.org/abs/1602.04938>.
- Salzberg, Steven. 2014. “Why Google Flu Is A Failure.” *Forbes*, March. <https://www.forbes.com/sites/stevensalzberg/2014/03/23/why-google-flu-is-a-failure/>.
- Shapley, Lloyd S. 1953. *A Value for n-Person Games*. Princeton University Press.
- Shmueli, Galit. 2010. “To Explain or to Predict?” *Statistical Science* 25 (3): 289–310.
- Shrikumar, Avanti, Peyton Greenside, and Anshul Kundaje. 2017. “Learning Important Features Through Propagating Activation Differences.” In *International Conference on Machine Learning*, 3145–53. PMLR.
- Shrikumar, Avanti, Peyton Greenside, Anna Shcherbina, and Anshul Kundaje. 2016. “Not Just a Black Box: Learning Important Features Through Propagating Activation Differences.” *arXiv Preprint arXiv:1605.01713*.
- Sievert, Carson. 2020. *Interactive Web-Based Data Visualization with R, Plotly, and Shiny*. Chapman; Hall/CRC. <https://plotly-r.com>.
- Silva, Natalia da, Dianne Cook, and Eun-Kyung Lee. 2021. “A Projection Pursuit Forest Algorithm for Supervised Classification.” *Journal of Computational and Graphical Statistics*, 1–21.
- Simonyan, Karen, Andrea Vedaldi, and Andrew Zisserman. 2014. “Deep Inside Convolutional Networks: Visualising Image Classification Models and Saliency Maps.” In *In Workshop at International Conference on Learning Representations*. Citeseer.



- Spyrison, Nicholas, and Dianne Cook. 2020. “Spinifex: An R Package for Creating a Manual Tour of Low-Dimensional Projections of Multivariate Data.” *The R Journal* 12 (1): 243. <https://doi.org/10.32614/RJ-2020-027>.
- Vanni, Laurent, Mélanie Ducoffe, Carlos Aguilar, Frédéric Precioso, and Damon Mayaffre. 2018. “Textual Deconvolution Saliency (TDS): A Deep Tool Box for Linguistic Analysis.” In *Proceedings of the 56th Annual Meeting of the Association for Computational Linguistics (Volume 1: Long Papers)*, 548–57.
- Wickham, Hadley. 2016. *Ggplot2: Elegant Graphics for Data Analysis*. Springer-Verlag New York. <https://ggplot2.tidyverse.org>.
- Wickham, Hadley, Dianne Cook, and Heike Hofmann. 2015. “Visualizing Statistical Models: Removing the Blindfold.” *Statistical Analysis and Data Mining: The ASA Data Science Journal* 8 (4): 203–25. <https://doi.org/10.1002/sam.11271>.