

Non-Linear Assignment

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Introduction

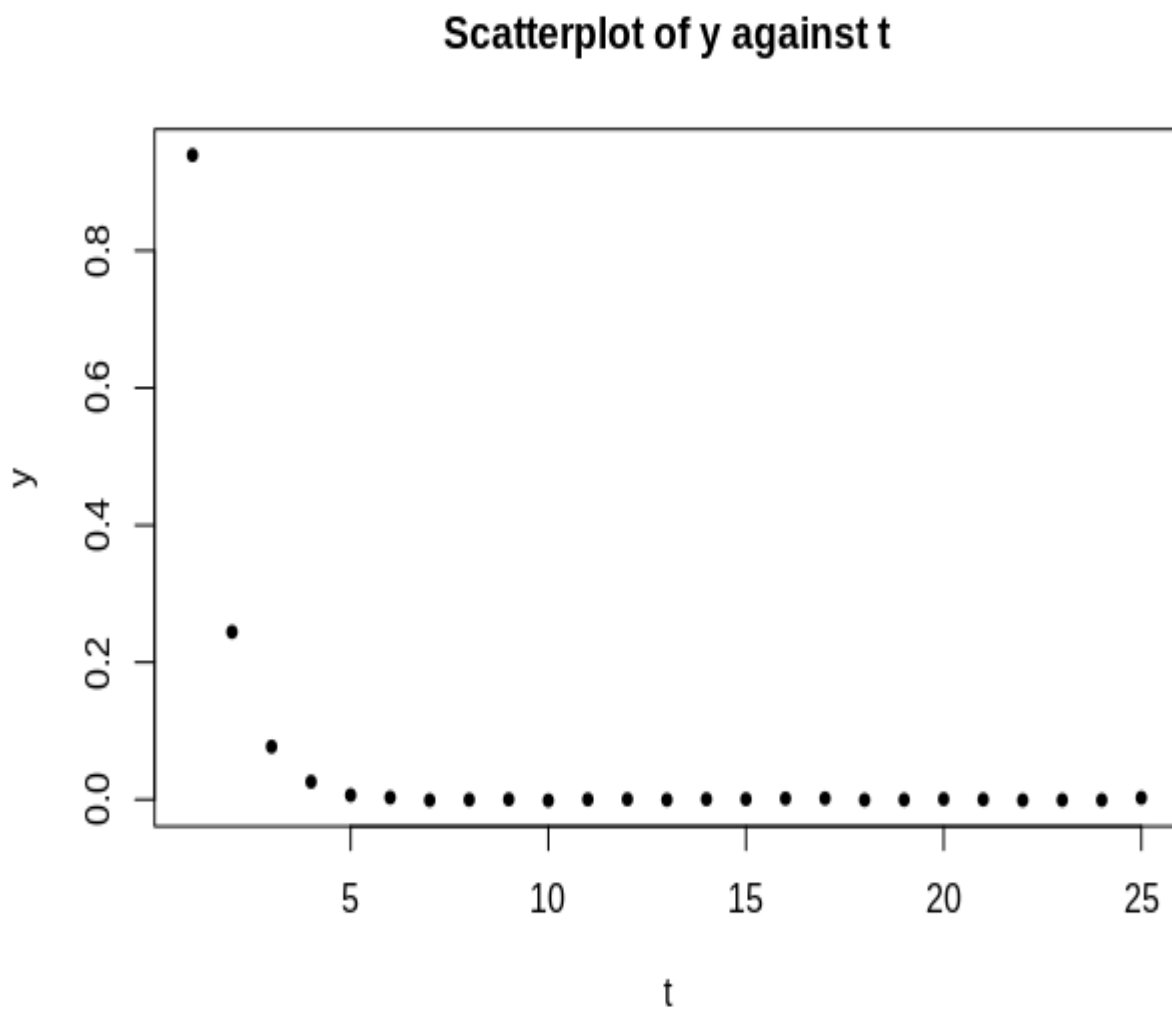
We were given 25 observations on the variable y . We are supposed to fit the model :

$$y_t = \alpha_1 e^{\beta_1 t} + \alpha_2 e^{\beta_2 t} + \varepsilon_t$$

Here ε_t is a sequence of i.i.d. random variable with mean zero and finite variance.

Part-(a)

We plot the data against t and obtain the following plot:



Part-(b)

We are to use the Prony's method to check whether the roots that we obtain are real or not.

We define a matrix $\mathbf{Z} = \begin{bmatrix} y_1 & y_2 & \cdots & y_{k+1} \\ y_2 & & & y_{k+2} \\ \vdots & & & \vdots \\ y_{n-k} & y_{n-k+1} & \cdots & y_n \end{bmatrix}$

Here, $k=2$ and $n=25$.

After that we find the eigen vector which has the smallest eigen value of $V = Z^T Z$, that is, we select \hat{a} as $V^* \hat{a} \approx 0$

Here, we obtain $\hat{a} = (0.0171, 0.3601, 0.9328)^T$

Then we solve the equation:

$$0.0171 + 0.3601x + 0.9328x^2 = 0 \quad \text{.....\#1}$$

The solution of this equation are the estimates of e^{β_1} and e^{β_2} .

The solutions of the equation #1 are : 0.055 and 0.331

Thus, $\hat{\beta}_1 = -2.894$ and $\hat{\beta}_2 = -1.107$

To obtain the estimates of other parameters we define the matrix:

$$\mathbf{X} = \begin{bmatrix} e^{\beta_1} & e^{\beta_2} \\ \vdots & \vdots \\ e^{n\beta_1} & e^{n\beta_2} \end{bmatrix}$$

$$\hat{\alpha} = (X^T X)^{-1} X^T Y$$

The estimates are obtained as:

$$\hat{\alpha}_1 = 4.340 \quad \text{and} \quad \hat{\alpha}_2 = 2.114$$

Therefore, we can obtain real estimates of the parameters using Prony's Method.

Part-(c)

After that we plot the contours. We vary both β_1 and β_2 from -3 to 0.1 at intervals of 0.1 and find the Partial Least Square estimate of α_1 and α_2 using the equation:

$$\hat{\alpha} = (X^T X)^{-1} X Y$$

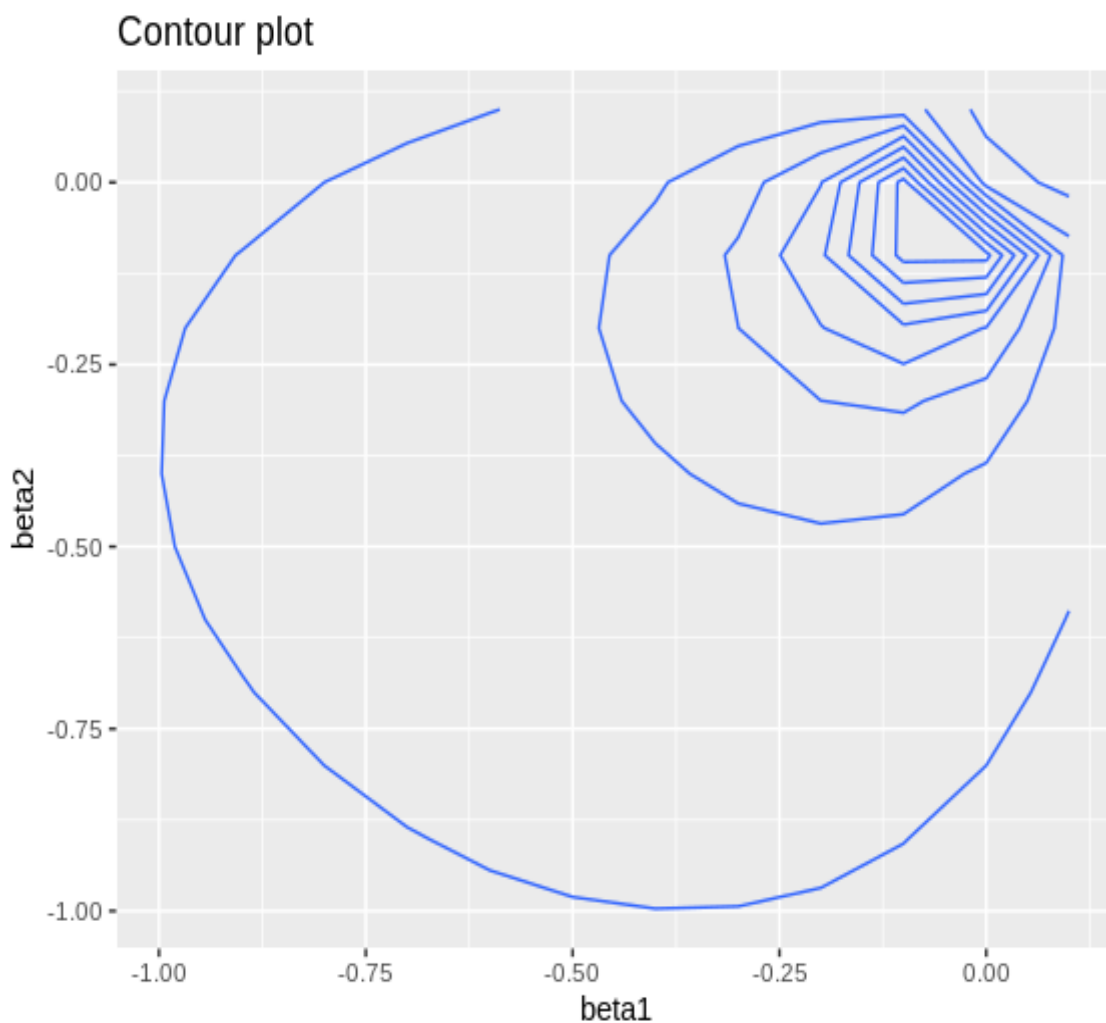
We then obtain the predicted values of y as:

$$\hat{y}_t = \alpha_1 e^{\beta_1 t} + \alpha_2 e^{\beta_2 t}$$

We then find the Residual Sum of Squares (RSS) = $\sum_{i=1}^n (y_i - \hat{y}_i)^2$

We find RSS for all combinations of the parameters in the given range and then plot the contour plot to obtain the following:

We obtain the following contour plots:



Part-(d)

We estimate the unknown parameters using the Gauss-Newton method.
Here we define a matrix:

$$\dot{F}(\theta) = (\partial f_i(\theta) / \partial \theta_j) \quad \text{where } f_i \text{ denotes the functional form for } y_i$$

where $\theta = (\alpha_1, \beta_1, \alpha_2, \beta_2)$ and j varies from 1 to 4.

We then set the approximate value of the parameters say θ^a to the estimates obtained from the Prony's method.

After that we obtain the next iterative value of the parameters as:

$$\theta^{a+1} = \theta^a + \delta^a \quad \text{where:}$$

$$\delta^a = (\dot{F}(\theta^a)^T * \dot{F}(\theta^a))^{-1} \dot{F}(\theta^a)(y - f(\theta^a))$$

Thus we can iteratively obtain the values of parameters with the stopping rule as:

$$|\theta^{a+1} - \theta^a| < 0.0005$$

Thus the estimates are obtained as:

$$\hat{\alpha}_1 = 10.474; \hat{\beta}_1 = -4.021; \hat{\alpha}_2 = 2.343; \hat{\beta}_2 = -1.137$$

Part-(e)

We are now to estimate the values of the parameters using Osborne's Algorithm:

We need to find the eigen vector of the matrix $B(g)$ corresponding to the smallest eigen vector.

The matrix $B(g)$ is defined as $((b_{kj}))$ where:

$$b_{kj} = (y^T U_k (G(g)^T G(g))^{-1} U_j^T y) + (y^T U_j (G(g)^T G(g))^{-1} U_k^T y) - y^T G(g) (G(g)^T G(g))^{-1} (U_k^T U_j + U_j^T U_k) (G(g)^T G(g))^{-1} G(g) y$$

We start with an estimate of $g^{(0)} = (0.01707969, -0.36000500, 0.93279402)^T$ which was obtained from the Prony's Method.

From this we obtain the value of $B(g^0)$ and then calculate the eigen vector corresponding to the smallest eigen value say $g^{(1)}$. From that we find $B(g^{(1)})$.

We repeat the procedure till the stopping criteria is satisfied which is:

$$|g^{(a+1)} - g^{(a)}| < 0.005$$

Here,

$$G^T(g) = \begin{bmatrix} g_0 & g_1 & \cdots & g_k & 0 & 0 & \cdots & 0 \\ 0 & g_0 & & \vdots & g_k & 0 & \cdots & 0 \\ \vdots & \vdots & & \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & 0 & g_0 & g_1 & \cdots & g_k \end{bmatrix}$$

Here, $k=2$

$$U_1^T = \begin{bmatrix} 1 & 0 & \cdots & 0 & 0 & 0 \\ 0 & 1 & & \vdots & \vdots & \vdots \\ \vdots & \vdots & & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 & 0 \end{bmatrix}$$

$$U_2^T = \begin{bmatrix} 0 & 1 & \cdots & 0 & 0 & 0 \\ 0 & 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & 1 & 0 \end{bmatrix}$$

$$U_3^T = \begin{bmatrix} 0 & 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & 0 & 1 \end{bmatrix}$$

$$G^T(g) = g_0 U_1^T + g_1 U_2^T + g_2 U_3^T$$

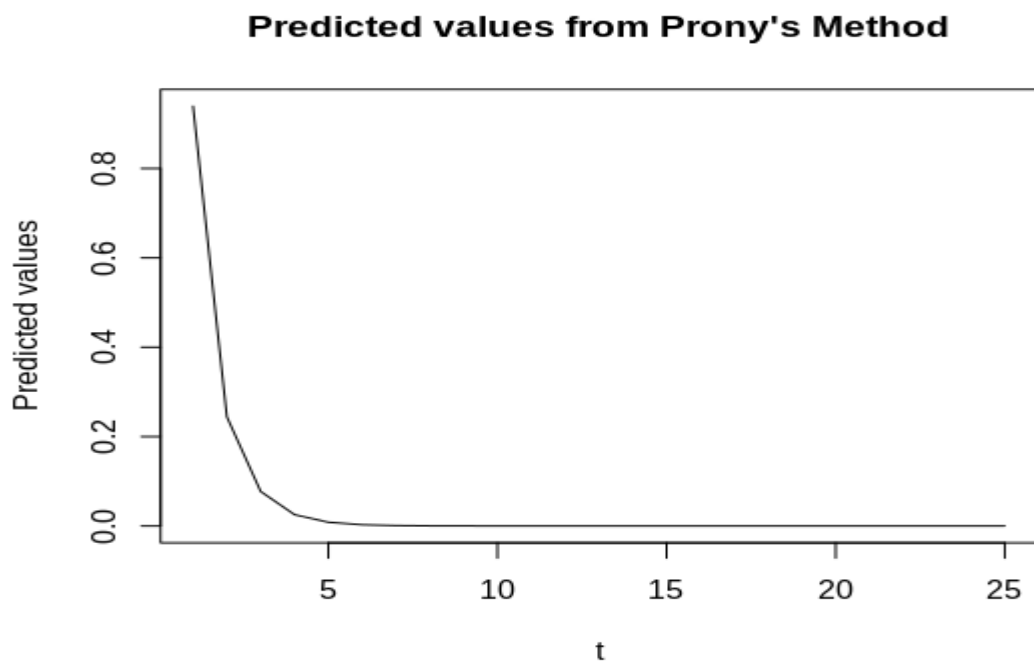
We run the procedure iteratively and obtain the estimates of the parameters as:

$$\hat{\alpha}_1 = 5.394; \hat{\beta}_1 = -3.222; \hat{\alpha}_2 = 2.225; \hat{\beta}_2 = -1.122$$

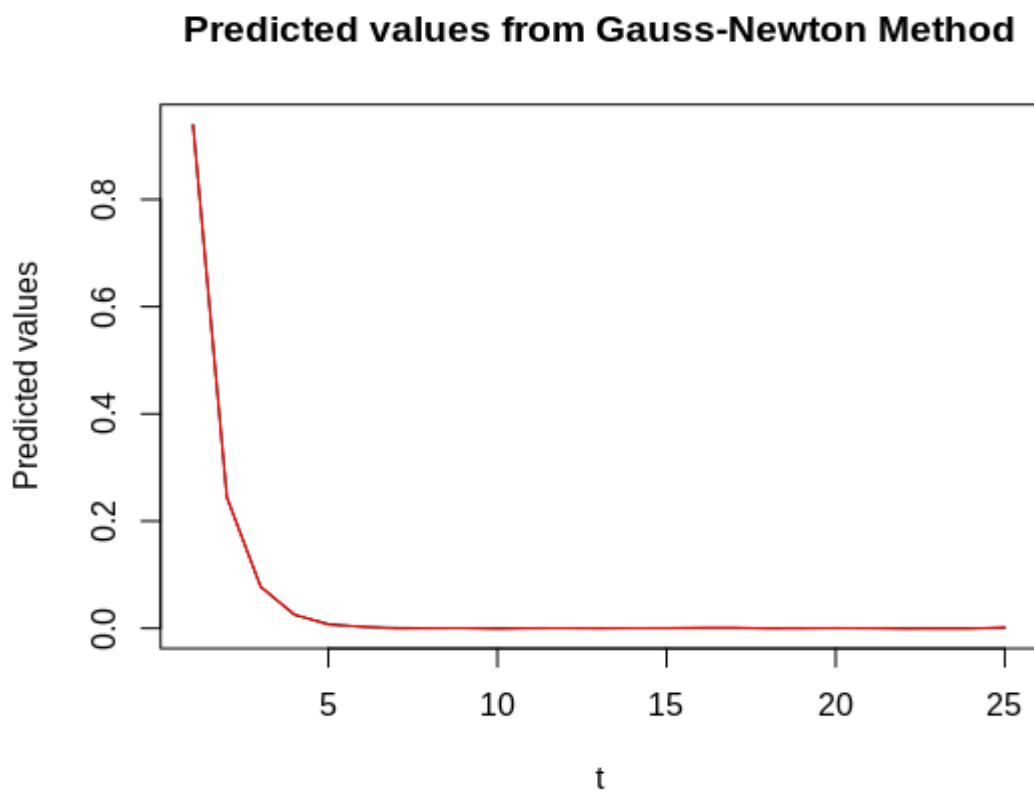
Part-(f)

We then the predicted curve that we have obtained from the three procedures:

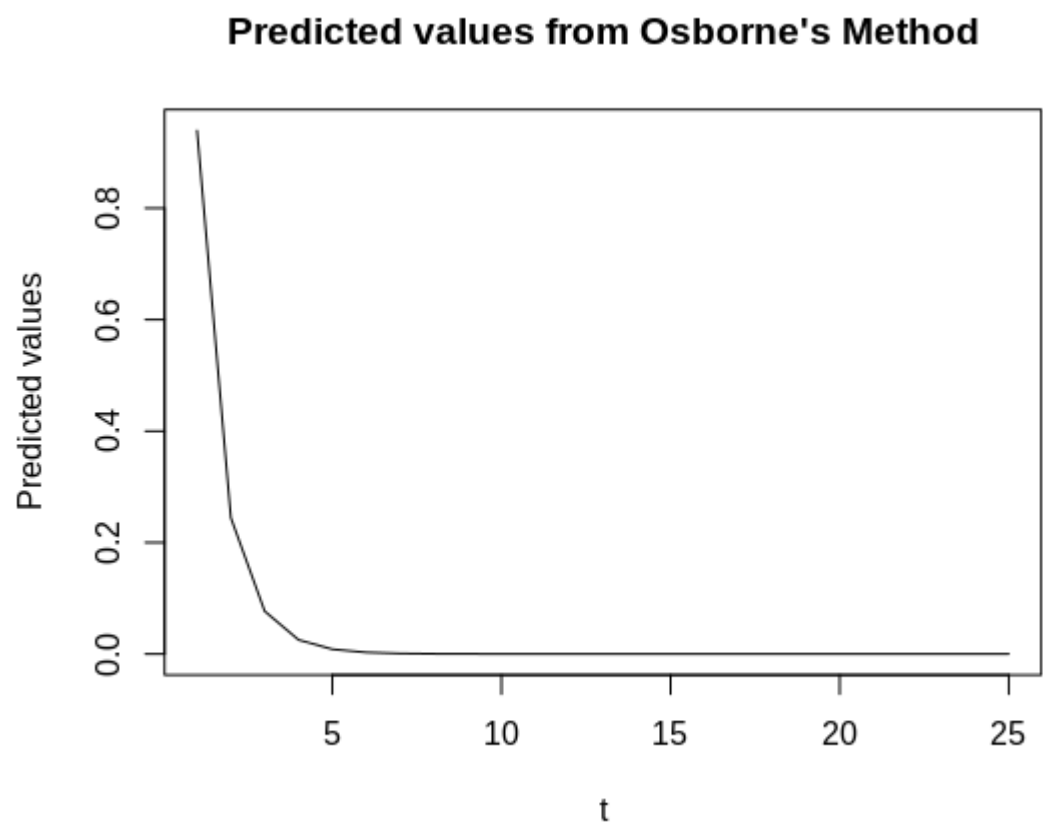
Prony's Method:



Gauss-Newton Method:



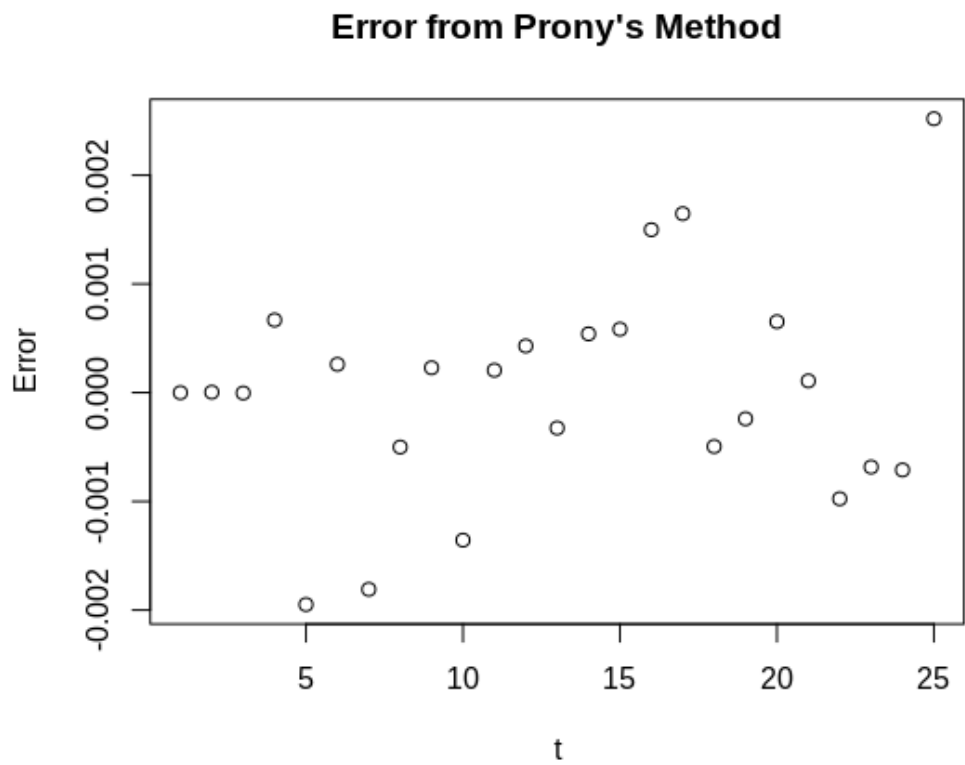
Osborne’s Method



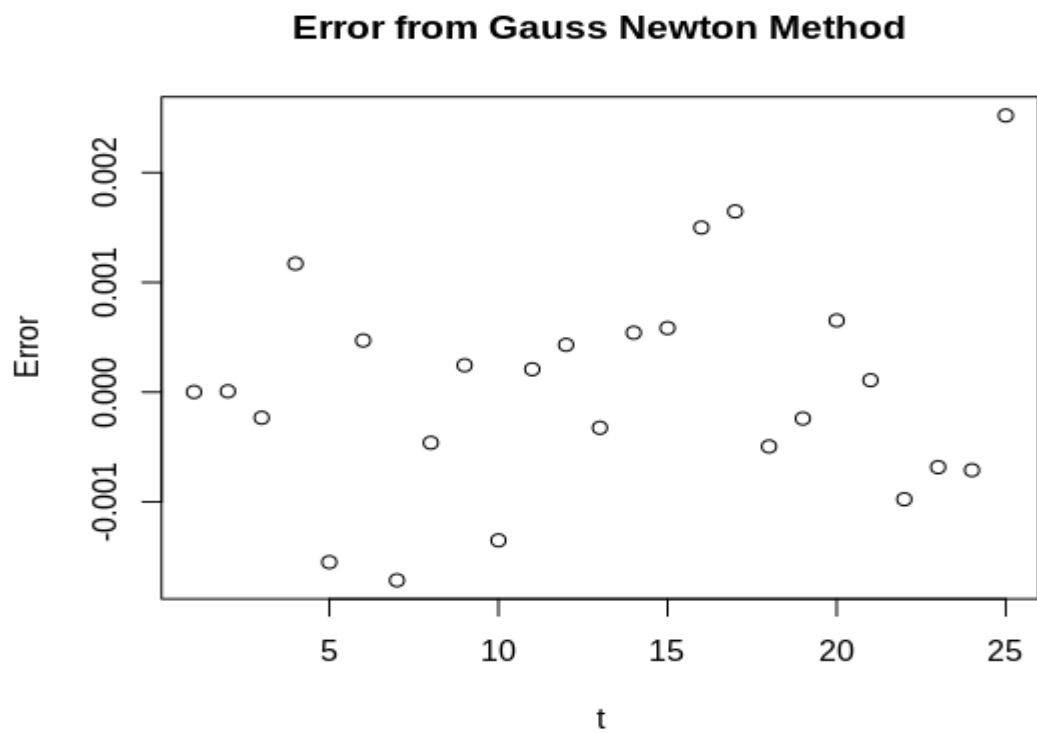
Part-(g)

We then continue to plot the errors associated in predicting the values of y in case of the three algorithms.

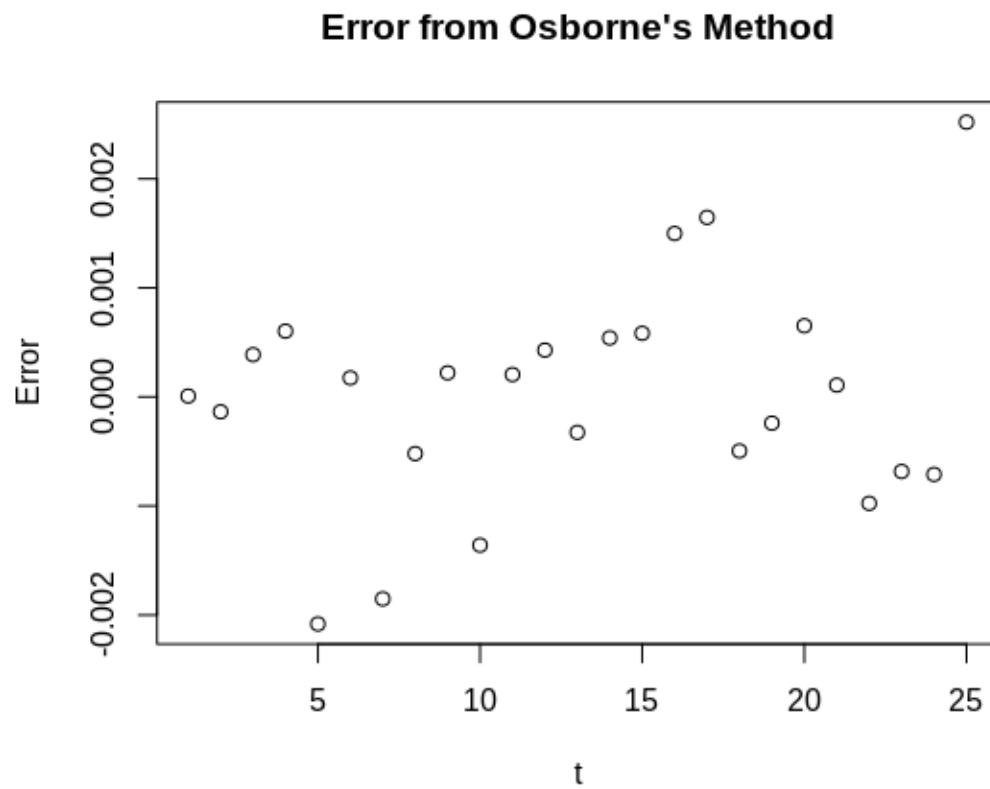
Prony's Method



Gauss-Newton Method:



Osborne's Method:



From all the three graphs above it is clear that the error term is scattered around the point without displaying any particular pattern.

Part-(h)

We need to find the number of components using the cross-validation approach.

For this we consider models of the form:

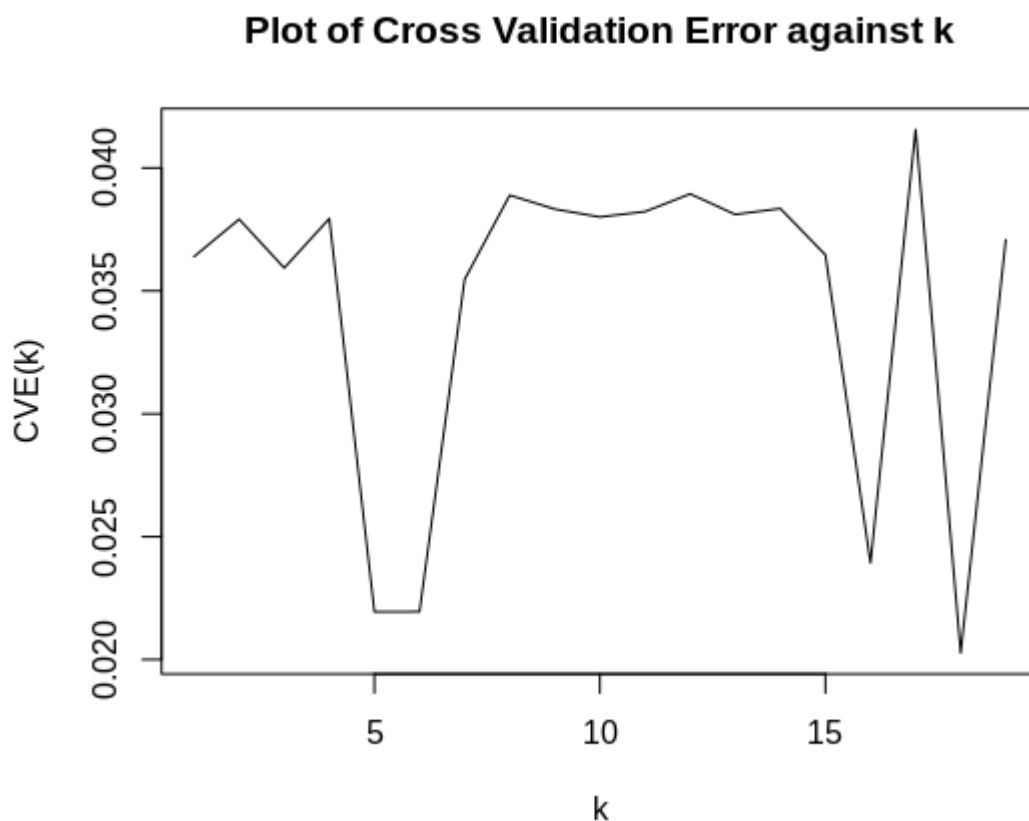
$$y_t = \alpha_1 e^{\beta_1 t} + \alpha_2 e^{\beta_2 t} + \dots + \alpha_k e^{\beta_k t} + \varepsilon_t$$

Then for this model we consider the data y_{it} where i th observation is removed and the above compartment model is considered for the data y_{it} estimates of the parameters are obtained using Prony's Method. Then for a $k \geq 2$ we calculate the Cross-Validation Error for order k [CVE(k)] as:

$$CVE(k) = \left(\sum_{i=1}^n (y_i - \hat{y}_i)^2 \right) / n$$

where y_i is the observation that is left out and its value is predicted using the estimates of the Prony's Algorithm from the rest 24 observations.

The procedure is repeated for $k=2, \dots, 20$ and the following graph is obtained:



From the graph it is clear that the CVE(k) reduces for $k=5,6$ and against goes up as k increases and finally for $k=18$ CVE(k) sees a sharp fall in the value of CVE(k).

We need to consider a trade-off as for large values of k the model becomes very complex and the parameters cannot be estimated with high precision. Therefore, for this dataset and the given compartment model the value of k can be considered to be 5 or 6 as the CVE(k) decreases and the number of parameters is not very high.

Next we need to find an confidence interval for the parameters.

$$\sqrt{(n)}(\theta - \hat{\theta}) \rightarrow N_p(0, \sigma^2 n * (\hat{F}(\theta)^T \hat{F}(\theta))^{-1})$$

where the matrix F is same as defined above.

We evaluate the matrix F at the estimates obtained from the Prony's Algorithm.

An estimate of the variance is MSE.

$$\hat{\sigma} = MSE = SSE / (n - k)$$

We obtain MSE = 1.67×10^{-6}

From the above multivariate normal distribution we can find the marginal distributions of the parameters which will follow univariate normal distributions from which we can construct the 100(1- α)% confidence interval using the below formula:

$$(\hat{\theta} - t_{\alpha/2} \hat{\sigma} / \sqrt{(n)}, \hat{\theta} + t_{\alpha/2} \hat{\sigma} / \sqrt{(n)})$$

where $t_{\alpha/2}$ denotes the upper $\alpha/2\%$ point of a t_{n-1} distribution [Here n=25]. The estimates of the parameters is obtained from the Prony's Algorithm.

Hence the 95% Confidence Intervals of the parameters is given as:-

$$\hat{\alpha}_1 \in (-1.382, 10.533); \hat{\beta}_1 \in (-4.913, -1.041); \hat{\alpha}_2 \in (1.150, 2.780); \hat{\beta}_2 \in (-1.194, -1.028)$$

Thus we obtain the individual 95% CI for the parameters.