

Physics of socio-economic phenomena

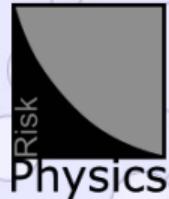
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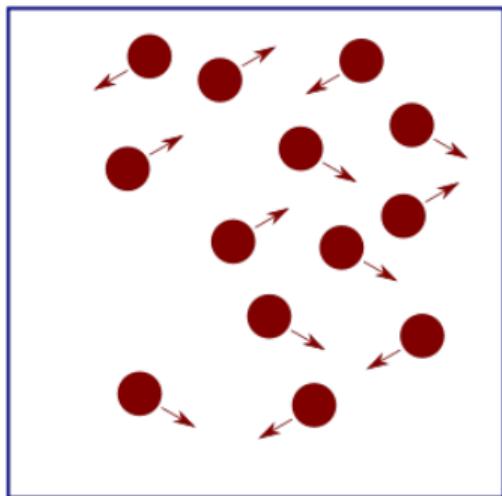
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Faculty of
Physics



Complex Physical and Social Systems group



Areas of interest: nonlinear dynamics, synchronization, long-range memory, stochastic processes, physics of socio-economic systems.

Physics of Risk blog

Physics of Risk

About

Students

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Adaptive strategy in Colonel Blotto game

February 25, 2025

Aleksiejus Kononovicius

#interactive

#game theory

#conflicts

#Colonel Blotto game

Last week I have shared a story about [Colonel Blotto](#) tournament I held back when I still used to teach [Matlab](#). This tournament is interesting from the perspective of Physics of Risk, because it was designed to encourage adaptive strategy. Admittedly, only few students actually did that, but...

Anyway, let us build an adaptive strategy for one of the variations of the [Colonel Blotto game](#) we have explored recently. Let us revisit [Colonel Blotto game with varied castles!](#)

The game

As in an [earlier post](#):

oops.

ags raised above its battlements. These flags represent the value of the castle. Thus, to win the war (game) 5 flags (points) are sufficient.

puter-controlled. "CPU" warlord will use simple fixed or random strategies (you will be able to choose). "ADA" warlord will use an adaptive strategy (i.e., this strategy allocates troops based on previous battle locations).

strategy work?

In the aforementioned tournament against my students, aims to discover the value

Physics of risk, complexity and socio-economic systems.

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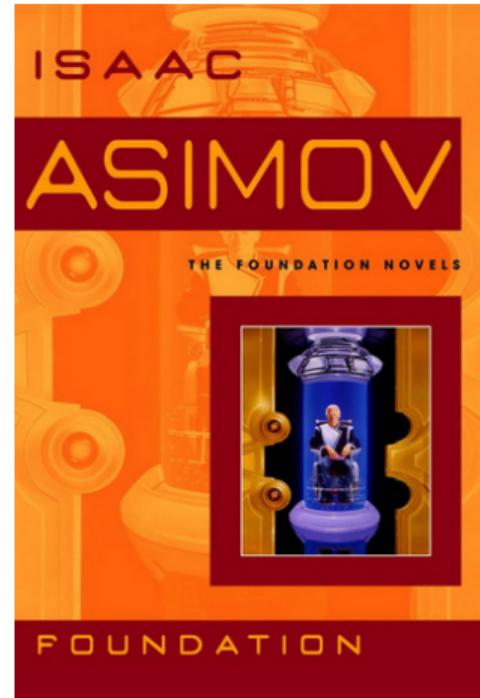
COST P10 meeting in Vilnius

<https://rf.mokslasplius.lt>

3/63

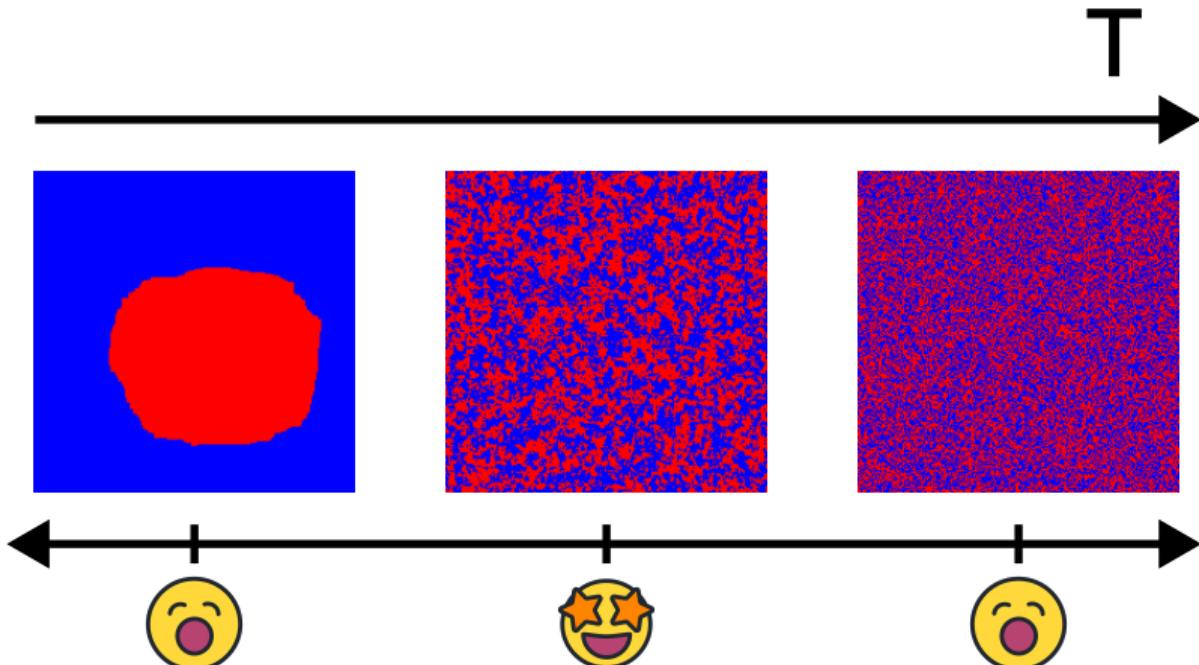
The plan

- ① Society as a complex matter
- ② Wealth and ideal gasses
- ③ Rational agents and game theory
- ④ Network science
- ⑤ Opinion dynamics
- ⑥ Financial markets



Society as a complex matter

Complex matters



$$m \sim \left| \frac{T - T_c}{T_c} \right|^\beta,$$
$$\xi \sim \left| \frac{T - T_c}{T_c} \right|^{-\nu}.$$

☺ flaticon.com; Pun intended: [Ball (2012)]; Ising model app: Physics of Risk

Sense of scale

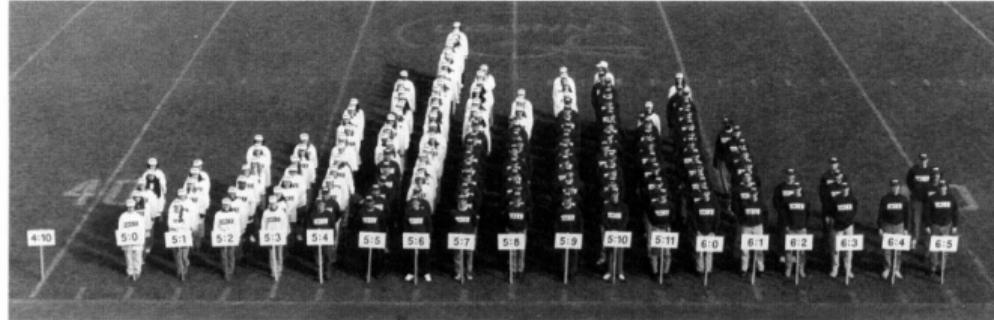


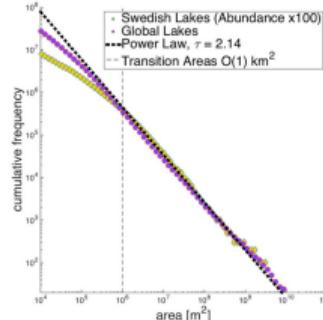
Figure 7. Living histogram of 143 student heights at University of Connecticut.

Figure 1: Globally, there are many small lakes, but only a small number of large lakes.



The asymmetry between lake size and abundance is clearly visible in this image of the Turtle Mountains, a lake district in North Dakota (USA). Image courtesy NASA.

Figure 2: Abundance (cumulative frequency)-area plots of global and Swedish lakes illustrate the asymmetry between lake size and abundance.



Large lakes are power-law distributed and the tail exponents for both datasets ($\tau=2.13$, $\tau=2.54$) are

Most people come from the “normal” distribution.

Many small lakes, while few are quite large.

[Schilling et al.(2012)], [Cael and Seekell (2016)]

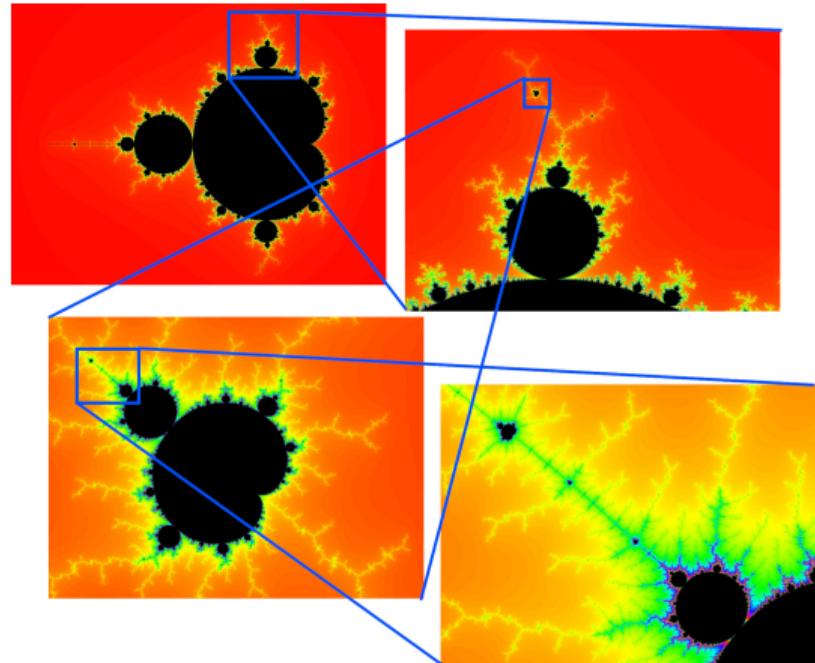
Free of scale

$f(x)$ is scale invariant if:

$$f(bx) = g(b) \cdot f(x).$$

Only solution:

$$f(x) = Cx^{-\alpha}.$$



Zooming into the Mandelbrot set.

Scale-free distribution

Let x follow a power-law PDF:

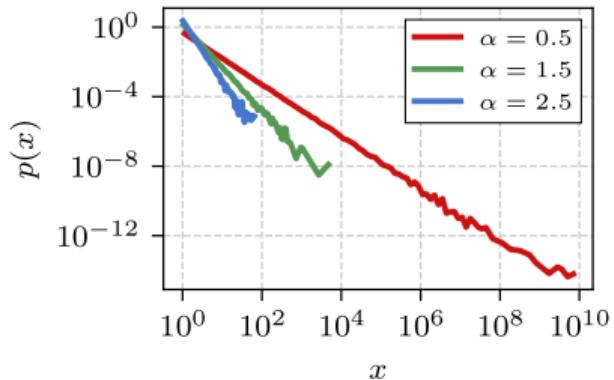
$$p(x) = (\alpha - 1) x^{-\alpha},$$

with $x \geq 1$.

Raw moments:

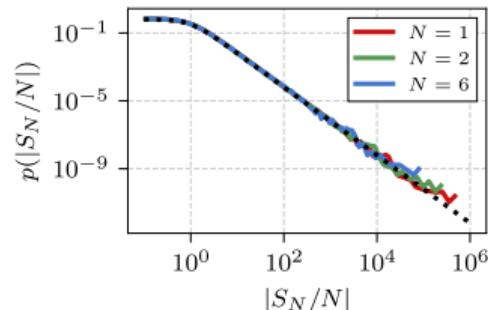
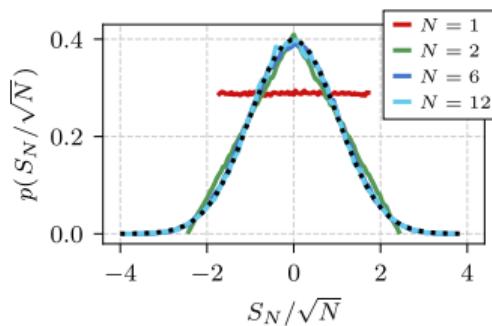
$$\langle x^m \rangle = (\alpha - 1) \int_1^\infty x^{m-\alpha} dx = \left. \frac{(\alpha - 1) x^{m+1-\alpha}}{m + 1 - \alpha} \right|_1^\infty.$$

For m -th moment to be finite, we need $\alpha > 1 + m$.



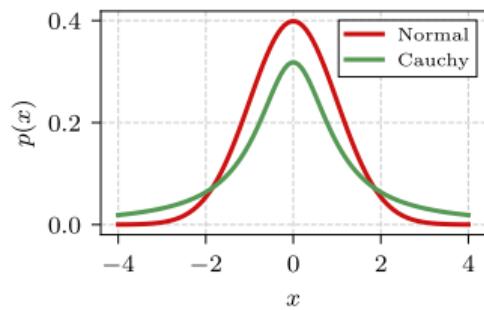
Central limit theorem?

Consider $S_k = \sum_{i=1}^k X_i$.



$$X_i \sim \mathcal{U}(-\sqrt{3}, \sqrt{3})$$

$$X_i \sim \text{Cauchy}(0, 1)$$



Comparison

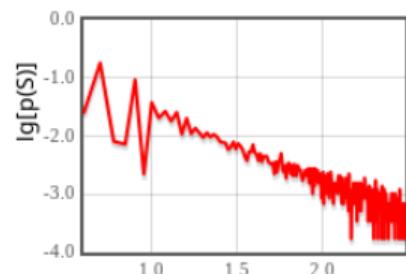
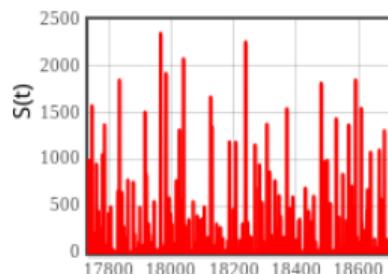
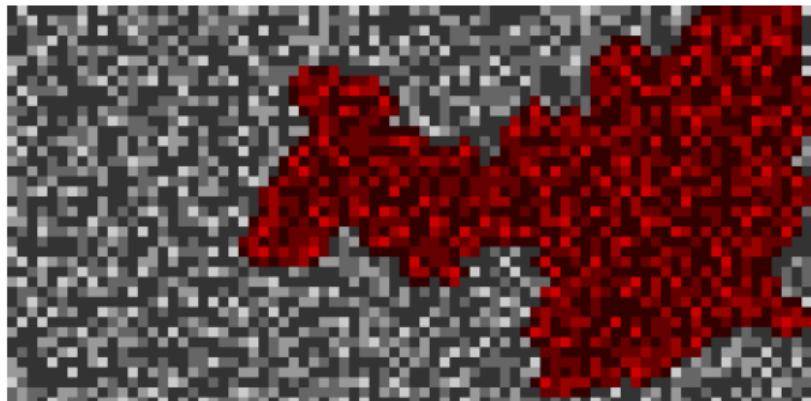
Complexity is about emergence

You can have power-law distribution without complexity! Let:

$$y \sim \text{Exp}(1), \\ x = \exp(y).$$

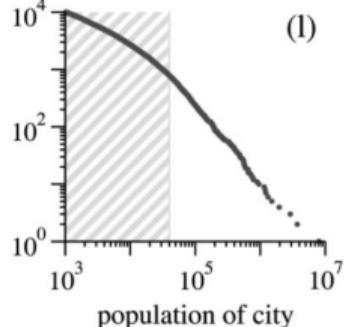
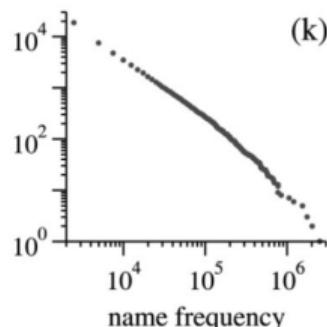
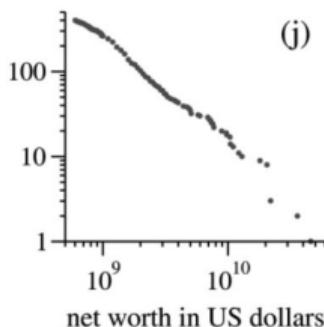
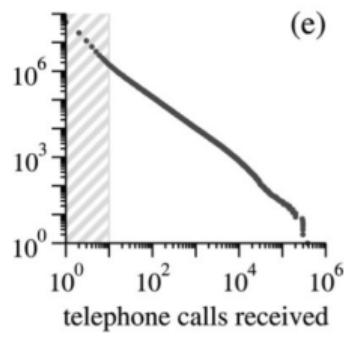
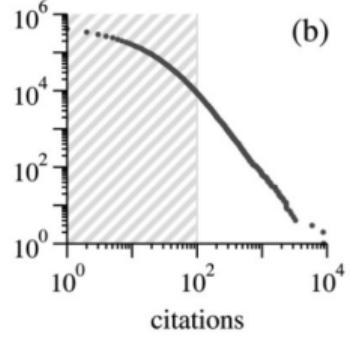
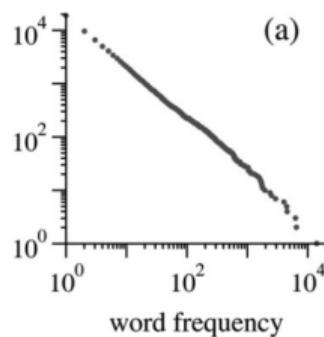
Then:

$$p_x(x) = p_y(\ln(x)) \left| \frac{dy}{dx} \right| = x^{-2}.$$



[Newman (2005)], [Bak et al.(1987)]; Sandpile model app: Physics of Risk

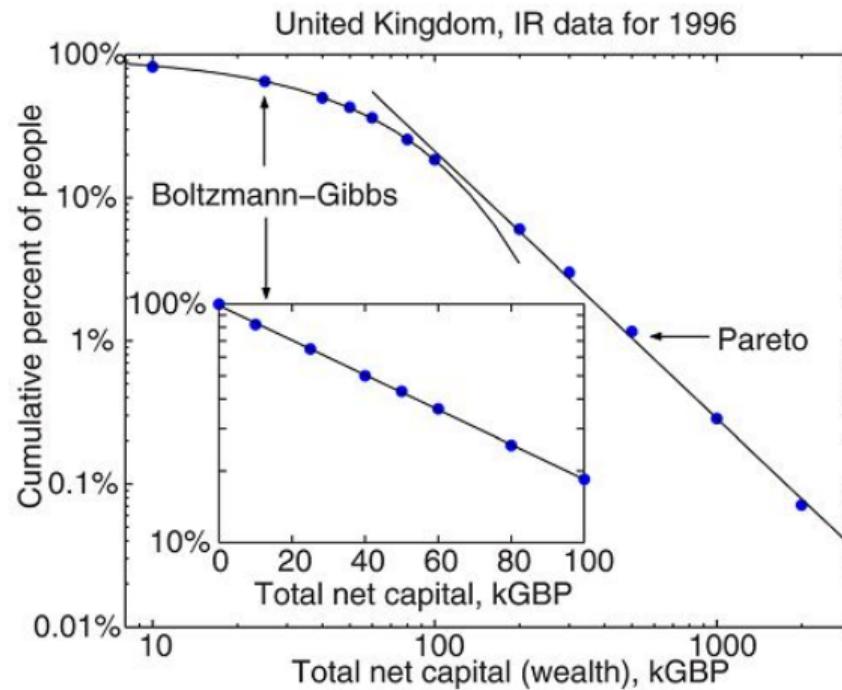
Social complexity



[Newman (2005)], Wolfgang Eckert (pixabay.com); Interactive app: Stop-and-go waves (Physics of Risk)

Wealth and ideal gasses

Empirical wealth data



Kinetic exchange framework

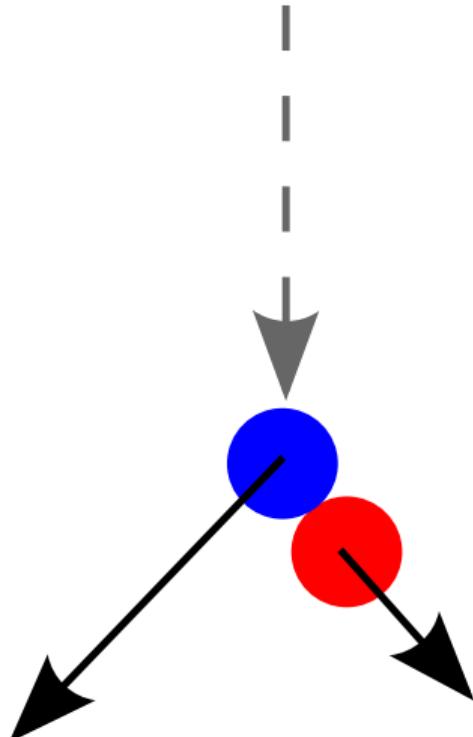
- ① Two particles i and j collide.
- ② Δw_{ij} energy is transferred:

$$\Delta w_{ij} = r_i w_i - r_j w_j.$$

- ③ Update particle energies:

$$w_i(t+1) = w_i(t) - \Delta w_{ij},$$

$$w_j(t+1) = w_j(t) + \Delta w_{ij}.$$



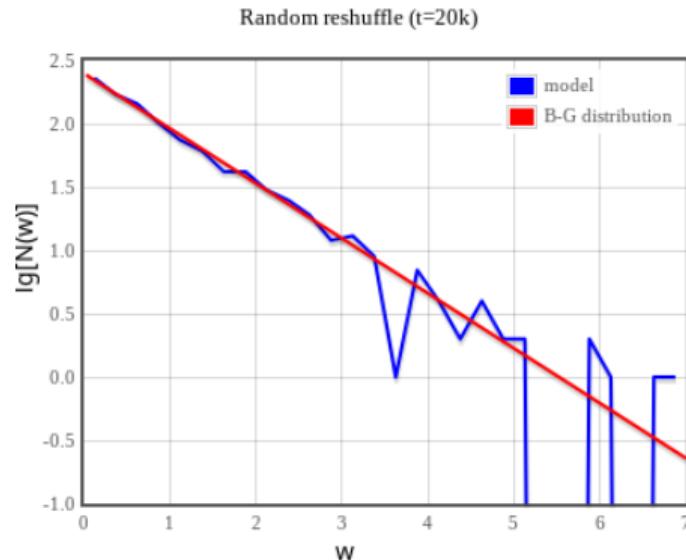
Simplest model

- ① Two agents i and j meet.
- ② Wealth is split randomly,

$$\Delta w_{ij} = (1 - \varepsilon) w_i - \varepsilon w_j,$$

with $\varepsilon \sim \mathcal{U}(0, 1)$.

- ③ Update agent wealth.



[Patriarca and Chakraborti (2013)]; Interactive app: Physics of Risk

Analytical approach to the model

The master equation:

$$\frac{\partial p(w, t)}{\partial t} = \frac{\partial N^+(w, t)}{\partial t} - \frac{\partial N^-(w, t)}{\partial t}$$

We care about stationary distribution:

$$\frac{\partial p_\infty(w)}{\partial t} = 0 \quad \Rightarrow \quad \frac{\partial N^-(w, t)}{\partial t} = \frac{\partial N^+(w, t)}{\partial t} \quad \Rightarrow$$

$$p_\infty(w) = \int_w^\infty \frac{1}{U} \left[\int_0^U p_\infty(u_i) p_\infty(U - u_i) du_i \right] dU \quad \Rightarrow \quad p_\infty(w) = \frac{1}{\langle w \rangle} \exp\left(-\frac{w}{\langle w \rangle}\right).$$

[Calbet *et al.*(2011)]

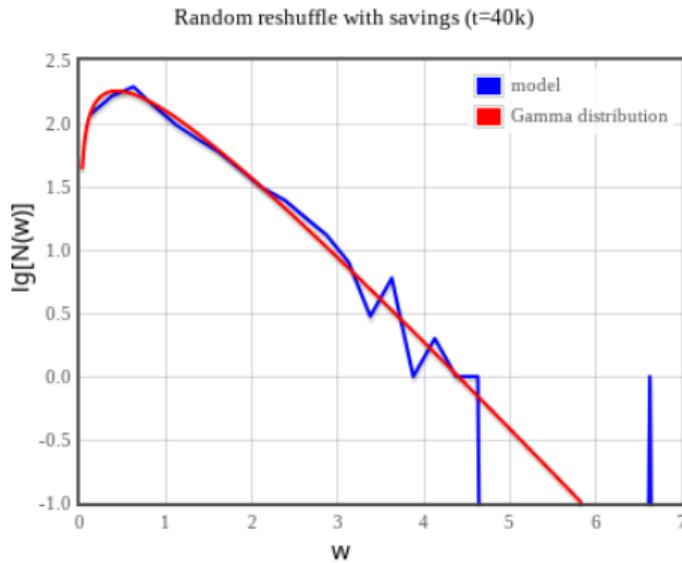
Introducing saving propensity

- ① Two agents i and j meet.
- ② Both reserve κ fraction of their wealth.
Remaining wealth is split randomly,

$$\Delta w_{ij} = (1 - \kappa) [(1 - \varepsilon) w_i - \varepsilon w_j].$$

with $\varepsilon \sim \mathcal{U}(0, 1)$.

- ③ Update agent wealth.



$\kappa = 0.2$

[Patriarca and Chakraborti (2013)]; Interactive app: Physics of Risk

Deriving moments

By definition, lhs and rhs should be equal in distribution:

$$w_i(t+1) \stackrel{d}{=} \kappa w_i(t) + \varepsilon(1-\kappa)[w_i(t) + w_j(t)]$$

Thus, for the m -th raw moment of a stationary distribution:

$$\langle w^m \rangle = \langle \{\kappa w_i + \varepsilon(1-\kappa)[w_i + w_j]\}^m \rangle.$$

Needs to be solved recurrently:

$$\langle w^1 \rangle = 1,$$

$$\langle w^2 \rangle = \frac{\kappa + 2}{1 + 2\kappa},$$

$$\langle w^3 \rangle = \frac{3(\kappa + 2)}{(1 + 2\kappa)^2},$$

$$\langle w^4 \rangle = \frac{72 + 12\kappa - 2\kappa^2 + 9\kappa^3 - \kappa^5}{(1 + 2\kappa)^2 (3 + 6\kappa - \kappa^2 + 2\kappa^3)}.$$

Suggested approximation

$$p(w) \sim w^{n-1} \exp(-nw),$$

$$\text{with } n = 1 + \frac{3\kappa}{1-\kappa}.$$

How to construct power-law distribution?

Start with:

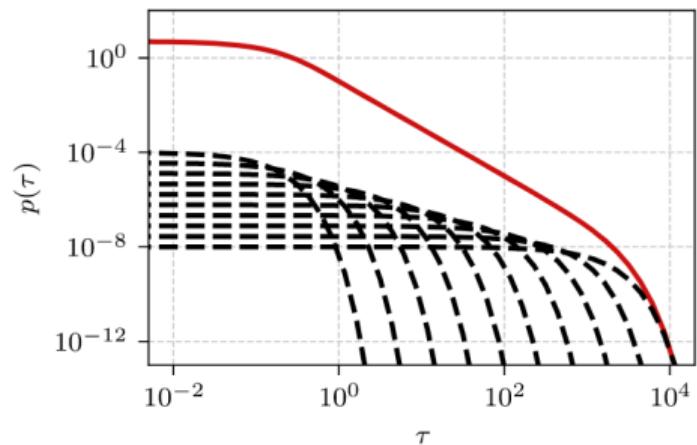
$$p(\tau|\gamma) = \gamma \exp(-\gamma\tau).$$

Assume that for $\gamma_{\min} < \gamma < \gamma_{\max}$:

$$p(\gamma) \propto \frac{1}{\gamma^\alpha}.$$

Combine:

$$p(\tau) = \int_{\gamma_{\min}}^{\gamma_{\max}} p(\gamma) p(\tau|\gamma) d\gamma \propto \frac{1}{\tau^{2-\alpha}}.$$



What about the saving propensity model?

Note that:

$$\begin{aligned} w^{n-1} \exp(-nw) &= \exp[(n-1)\ln(w) - nw] \approx \\ &\approx \exp(-nw) \end{aligned}$$

So assume that $\kappa \sim \mathcal{U}(0, 1)$.

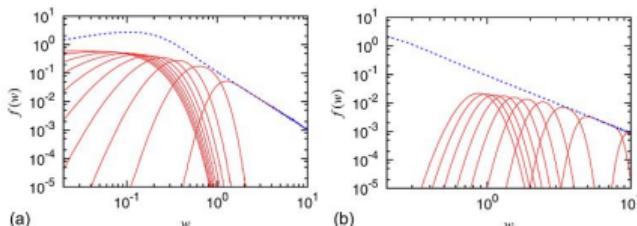
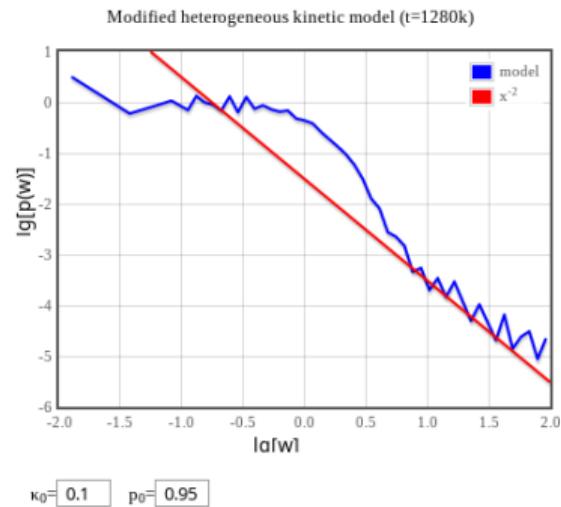


Fig. 3. (Color online) Wealth distribution $f(w)$ for uniformly distributed κ_i (or λ_i) in the interval $(0,1)$; $f(w)$ is decomposed into partial distributions $f_i(w)$, where each $f_i(w)$ is obtained by counting the statistics of those agents with parameter λ_i in a specific sub-interval (from Ref. 36). The left panel shows the decomposition of $f(w)$ into ten partial distributions in the λ -subintervals $(0, 0.1), (0.1, 0.2), \dots, (0.9, 1)$. The right panel decomposes the final partial distribution in the λ -interval $(0.9, 1)$ into partial distributions obtained by counting the statistics of agents with λ -subintervals $(0.9, 0.91), (0.91, 0.92), \dots, (0.99, 1)$. Note how the power law appears as a consequence of the superposition of the partial distributions.



Delving deeper

Wealth / income:

- Compatibility with Economics
- Skills and luck
- Temporal dynamics
- Realistic income mechanisms



But not only wealth / income:

- Opinion dynamics
(Biswas-Chatterjee-Sen model)
- Designing ranking systems (ELO)
- Epidemiological models
- Alcohol consumption

Recommendations: [Patriarca and Chakraborti (2013)], [Toscani *et al.* (2022)]

Rational agents and game theory

Game theory

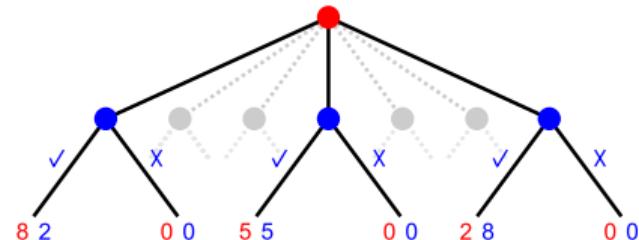
Explores interactions between rational and self-interested agents.

Games:

- cooperative or competitive
- (non-)zero sum
- (a)symmetric
- (a)synchronous
- (in)finite
- ...

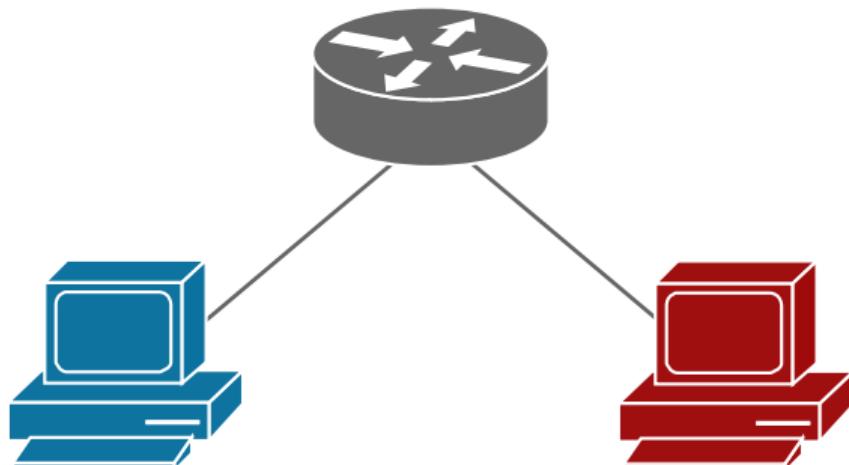
	R	P	S
Rock	0, 0	-1, 1	1, -1
Paper	1, -1	0, 0	-1, 1
Scissors	-1, 1	1, -1	0, 0

Payoff matrix for a r-p-s game



Decision tree of an ultimatum game

Pure strategies (in the TCP backoff game)



	B	C
Back-off	-1, -1	-4, 0
Continue	0, -4	-3, -3

- What is desirable?
- What do we get?

Some games have no pure strategy...

GK \ Taker	L	R
Left	1, 0	0, 1
Right	0, 1	1, 0

Matching pennies game



But there might be a mixed strategy. To find it you need to make your opponent not care about their action.

A practical problem for a football manager...

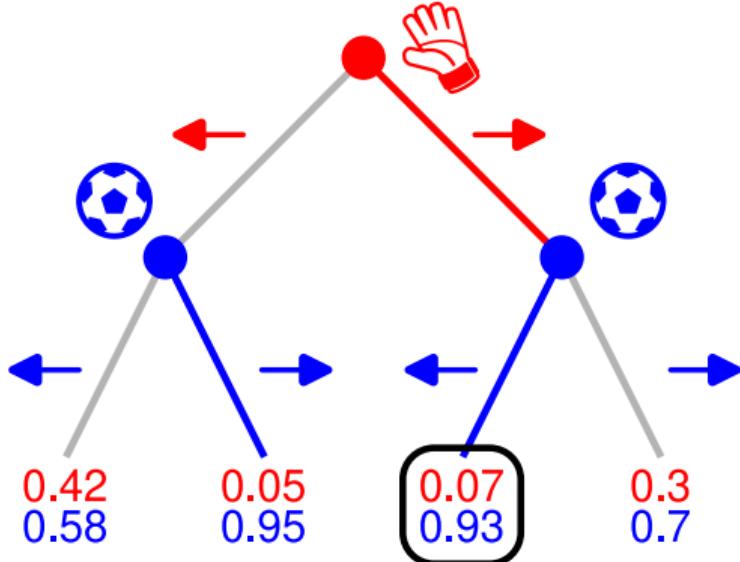
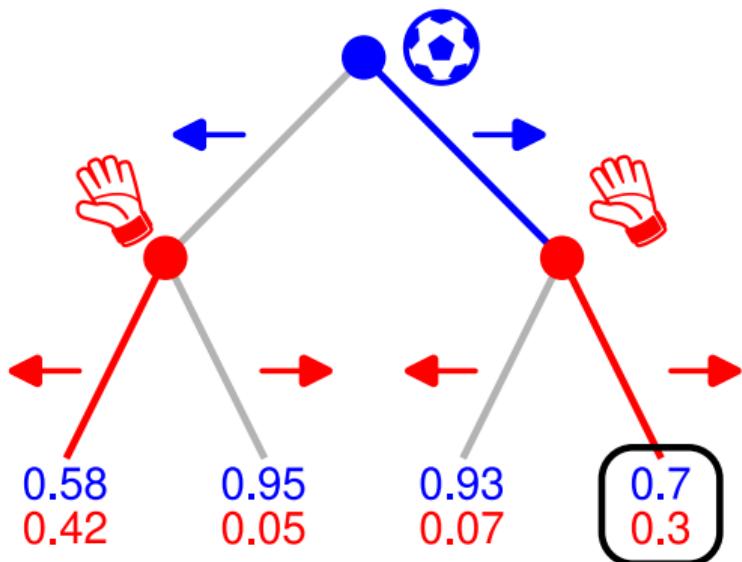


GK \ Taker	L	R
Left	0.42, 0.58	0.07, 0.93
Right	0.05, 0.95	0.3, 0.7

- ① Should GK jump left? (Answer: $p_{GK} \approx 0.42$)
- ② Should penalty taker shoot left? (Answer: $p_T \approx 0.38$)
- ③ Expected outcome? (Answer: $U_{GK} \approx 0.2$)

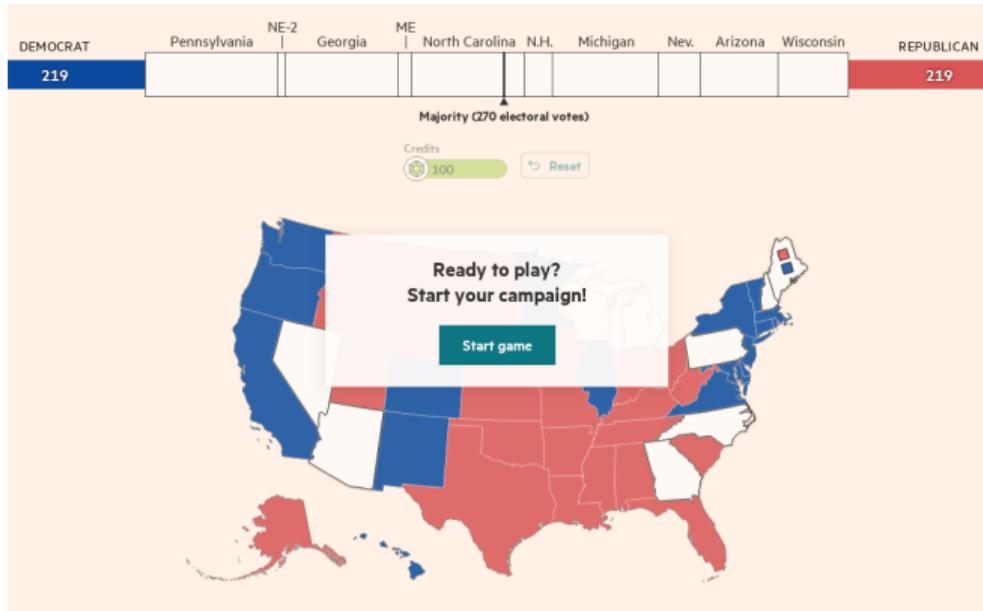
[Palacios-Huerta (2003)]; sportingnews.com

Solution: rig the game



Quick GK (left) or quick taker (right).

A really important game...



- 100 credits.
- Assign credits to states.
- Outspend to get votes.



US elections app: [Financial Times](#); Colonel Blotto apps: [Physics of Risk](#)

Delving deeper

- More actions
- More players
- Consecutive games
- Random games
- Behavioral rationality



Designing:

- Auctions
- Voting
- Board games ("prof." Reiner Knizia)

Resilience:

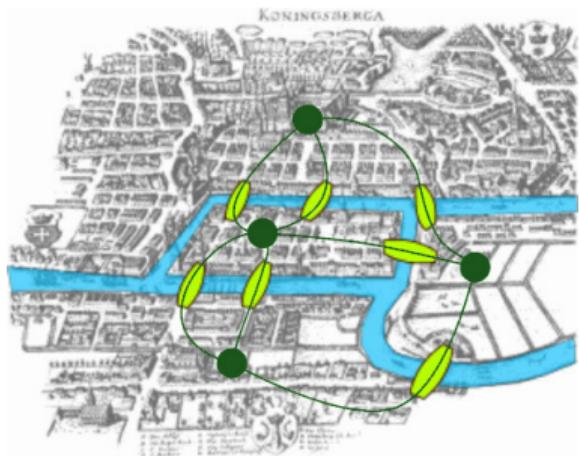
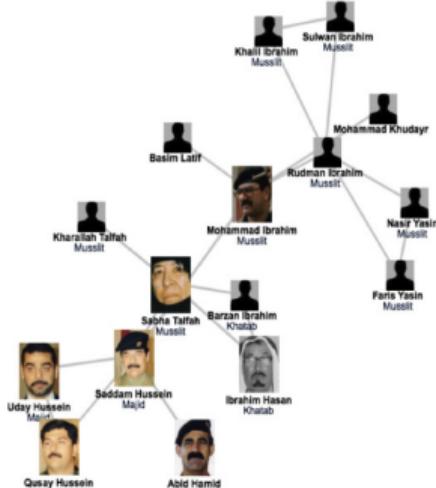
- Errors
- Manipulations

Recommendation: "Game Theory" course (Coursera and Youtube)

Greg Montani (pixabay.com); Veritasium: Why Democracy Is Mathematically Impossible

Network science

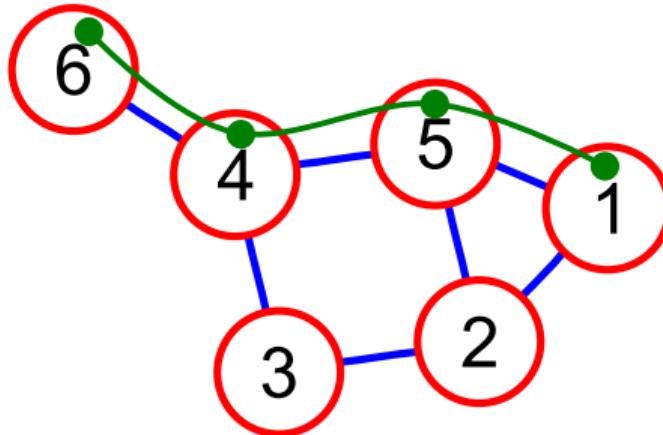
Connections



[Lynn and Bassett (2019)], slate.com, Wikimedia.

Main terminology

Network is a collection of **nodes** and **links**. Mathematicians prefer terms **graph**, **vertex** and **edge**.



- **Neighboring** nodes - connected by edges.
- Node's **degree** - a number of its neighbors.
- **Path** - sequence of neighboring nodes.
- **Geodesic** - shortest $i \rightarrow j$ path.
- **Diameter** - longest geodesic in a network.
- ...

Adjacency matrix

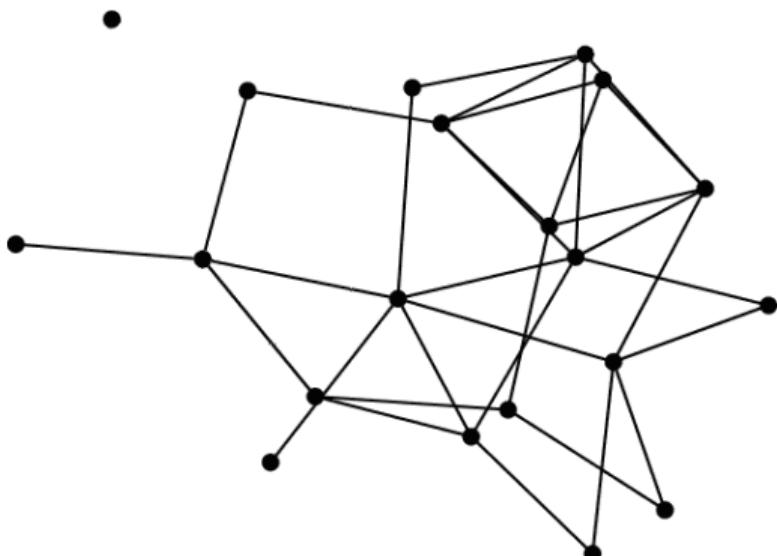
$$\mathbf{A} = \begin{pmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \end{pmatrix}$$

- If $A_{ij} \neq 0$, then there exists an edge pointing from j to i .
- Node degree:
 $k_i = \sum_{j=1}^N \mathbf{1}_{A_{ij} \neq 0} = \sum_{j=1}^N \mathbf{1}_{A_{ji} \neq 0}$.
- $(\mathbf{A}^m)_{ij}$ counts all $j \rightarrow i$ paths.

Specific links can be

- **looping**, if $A_{ii} = 1$.
- **directional**, if $A_{ij} \neq A_{ji}$.
- **multiple**, if $A_{ij} \in \mathbb{N}_0$.
- **weighted**, if $A_{ij} \in \mathbb{R}$.

Erdos-Renyi (random) network



- ① Start with N nodes and $L = 0$ edges.
- ② Iterate over all possible pairs. Add edge with probability p .

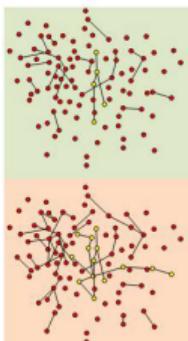
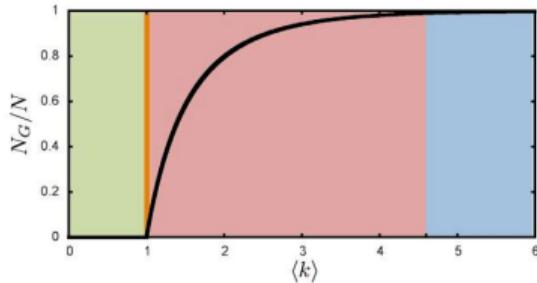
Edges on average:

$$\langle L \rangle = pN(N - 1)/2.$$

Average degree:

$$\langle k \rangle = 2L/N = p(N - 1).$$

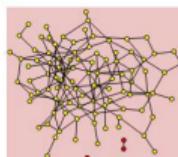
Phase transition in E-R network



$\langle k \rangle < 1$

Subcritical regime

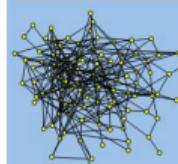
- No giant component.
- Cluster size distribution: $P(s) \sim e^{-\alpha s}$
- The size of the largest cluster: $N_G \sim \ln N$
- The clusters are trees.



$\langle k \rangle > 1$

Supercritical regime

- Single giant component.
- Cluster size distribution: $P(s) \sim e^{-\alpha s}$
- Size of the giant component: $N_G \sim (p - p_c)N$
- The small clusters are trees. GC has loops.



$\langle k \rangle \geq \ln N$

Fully connected regime

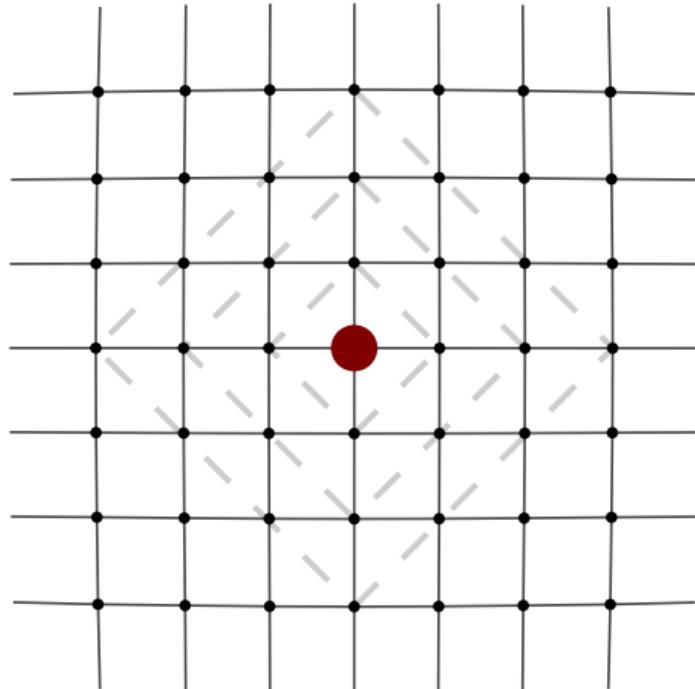
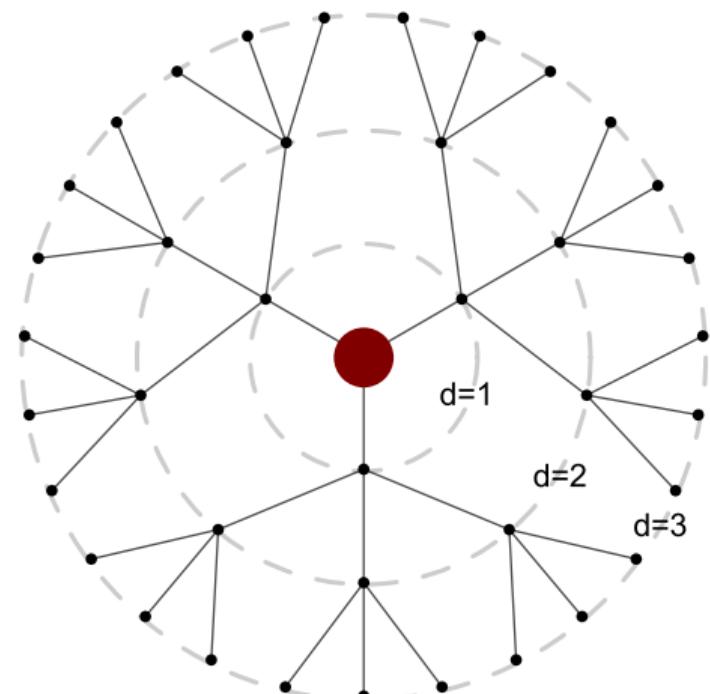
- Single giant component.
- No isolated nodes or clusters.
- Size of the giant component: $N_G = N$
- GC has many loops.

Probability to not be in g.c.:

$$u = [(1 - p) + up]^{N-1},$$

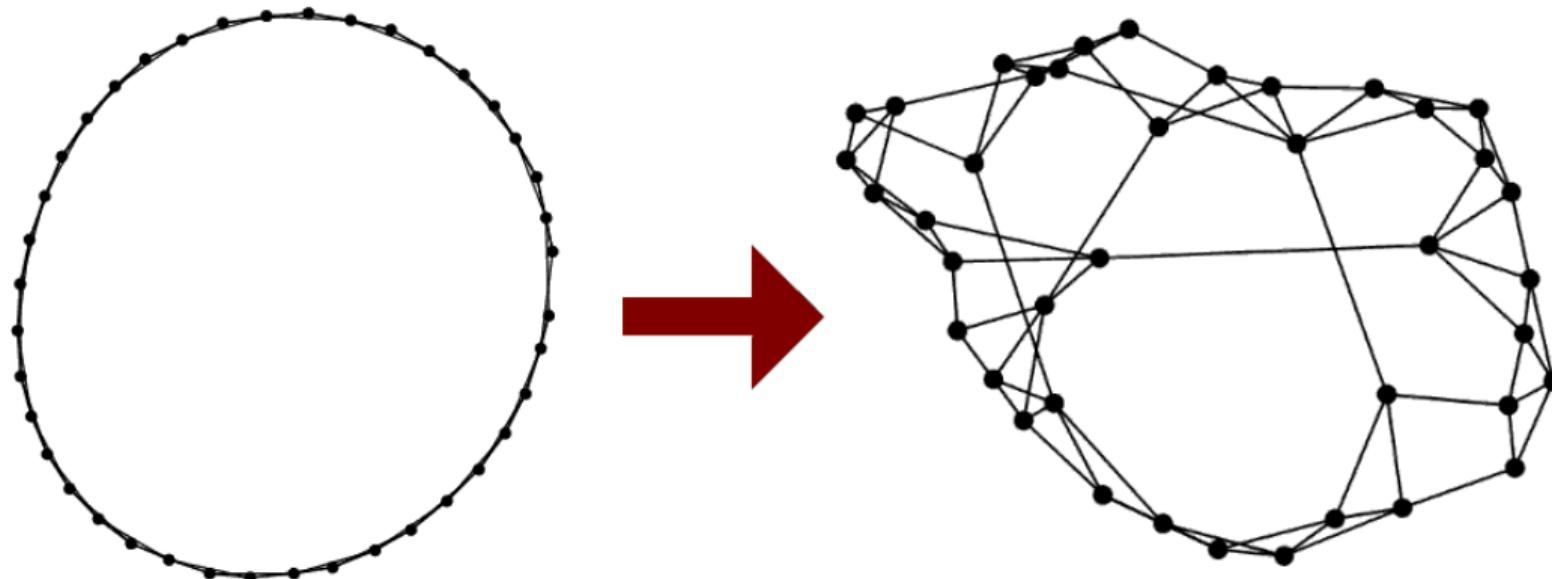
$$\frac{N_G}{N} = 1 - \exp \left[-\langle k \rangle \frac{N_G}{N} \right].$$

Randomness enhances reach



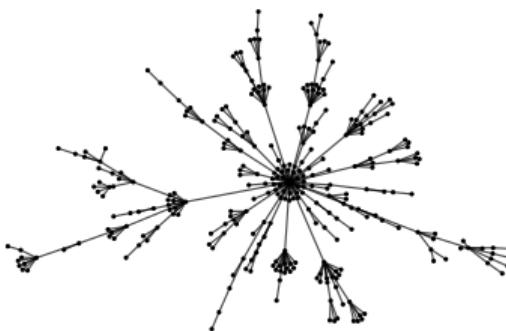
Nodes reached: 3^d (left) and $4d$ (right).

Watts-Strogatz network

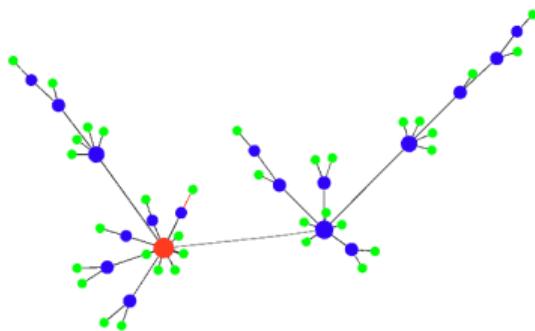


Idea: Introduce random edges into a regular structure.

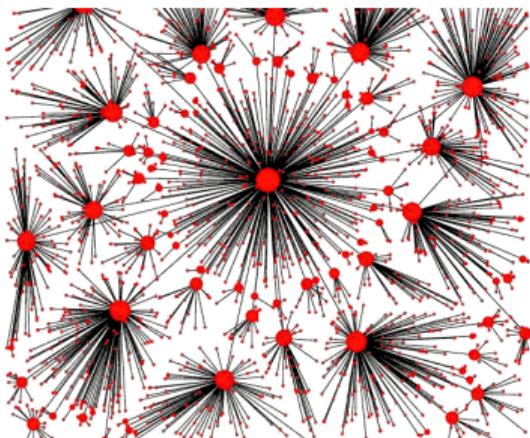
Scale-free networks



Barabasi-Albert



Edge redirection



Luck-and-reason

Interactive apps: [Barabasi-Albert](#), [Edge redirection](#),
[Luck-and-reason](#) (Physics of Risk)

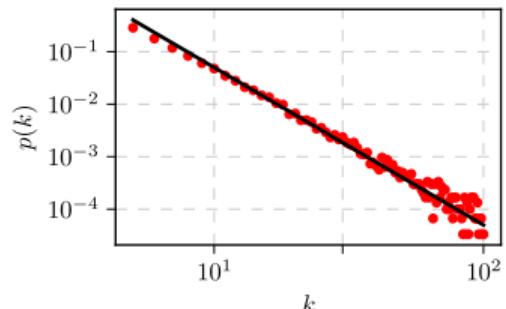
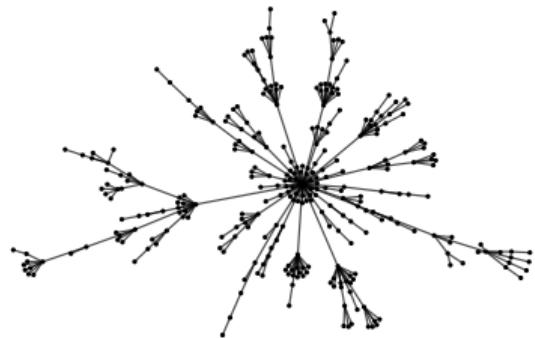
Continuum approach to B-A network

Expected degree of j -th node,

$$\frac{dk_j}{dt} = mp(t \rightarrow j) = \frac{k_j}{2t}, \quad \Rightarrow \quad k_j(t) = m\sqrt{\frac{t}{t_j}}.$$

Looking for “younger” nodes is the same as looking for lower degree nodes. Thus:

$$P(t_j > T) = P(k_j < k) \propto k^{-2},$$
$$p(k) \propto k^{-3}.$$



[Barabasi et al.(1999)]

Delving deeper

Further general topics:

- Degree correlations
 - Clustering
 - Centrality and influence
 - Strategic network formation



Recent research directions:

- Community detection
 - Evolving networks
 - Multi-layer networks
 - Hyper-graphs
 - Higher-order networks
 - Predicting missing edges
 - Reconstructing processes

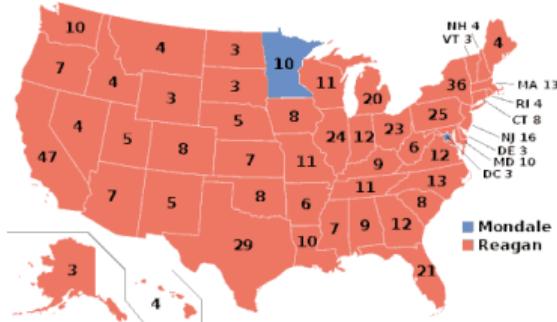
Recommendations: Barabasi "Network Science", "Social and Economic Networks" course (Coursera and Youtube)

 Generated by Copilot

Opinion dynamics

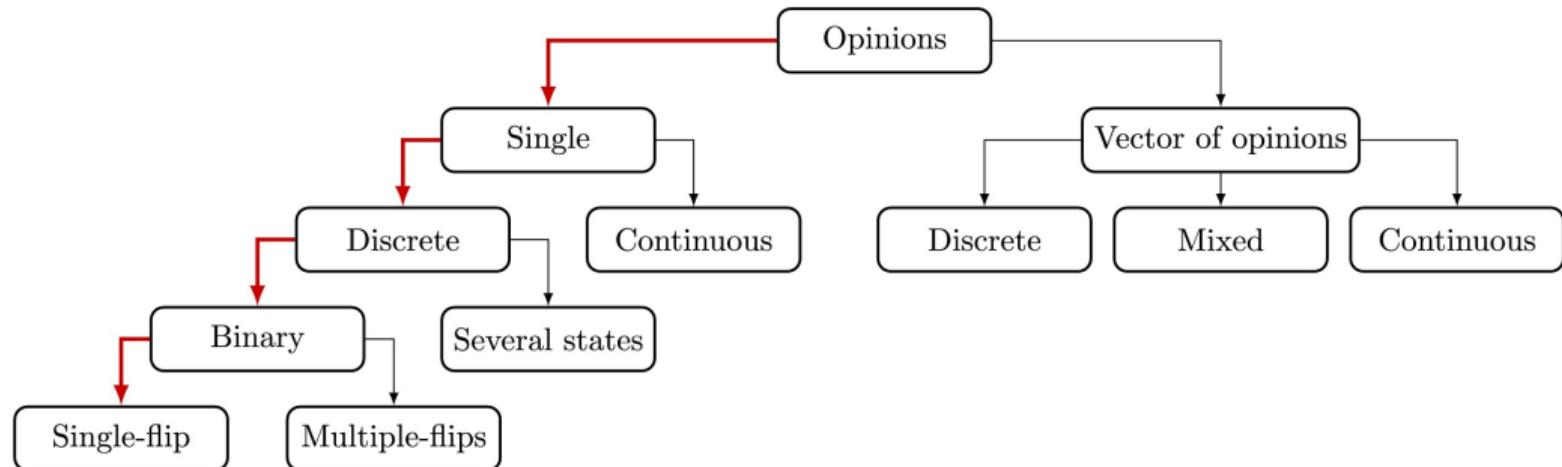
Diverse research direction

- Elections, polls, census data
- Online discussion
- Collective behavior
- Laboratory experiments



Gizmodo, Wikimedia, Wikimedia

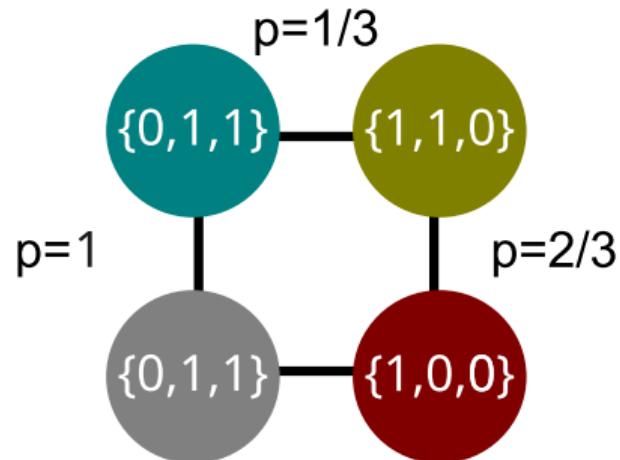
Model taxonomy



[Jedrzejewski and Sznajd-Weron (2019)]

Axelrod model

- Opinion is given by d -dimensional **vector**.
 - Each component may take q distinct values.
- ① Choose a random agent i .
 - ② Choose a random neighbor j .
 - ③ Interaction probability is proportional to the number of shared components.
 - ④ During interaction i copies a single component from j .



[Axelrod (1997)]; Interactive app: [Physics of Risk](#)

Bounded confidence models

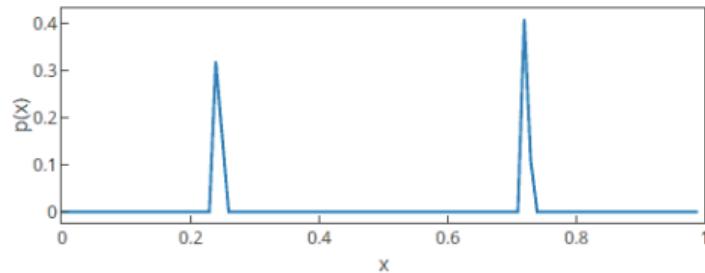
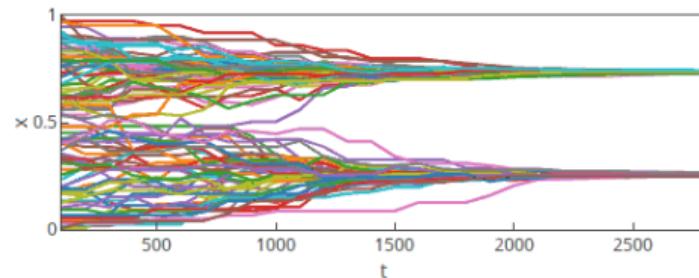
- Agents have **continuous opinion** x_i .
- There exists a “trust” threshold ε .

- ① Choose random agents i and j .
- ② Check if i trusts j :

$$|x_j(t) - x_i(t)| < \varepsilon.$$

- ③ If yes, update agent's i opinion:

$$x_i(t+1) = x_i(t) + \mu [x_j(t) - x_i(t)].$$

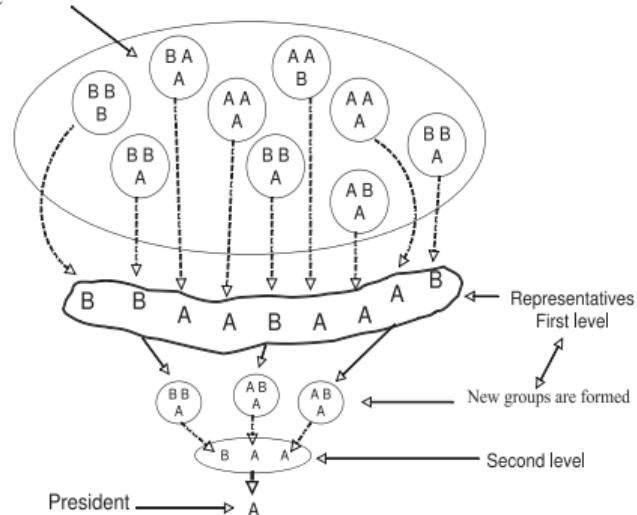


[Flache *et al.*(2017)]; Interactive app: [Physics of Risk](#)

Galam models

- Each agent has **discrete opinion**.
- Interactions occur in groups imposed by hierarchy, or in randomized groups.
- Agents may elect their representative, or they may align their opinions.
- Consider *status quo* effects.

Agents are randomly selected from the population to form the ground people

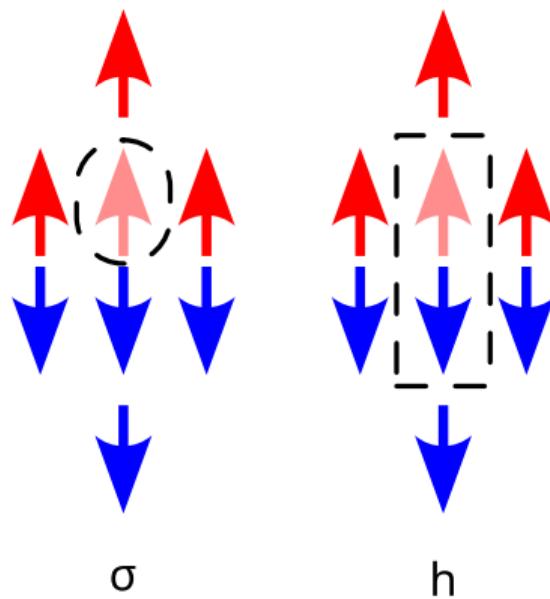


Interactive apps: [Hierarchical voting model](#), [Referendum model](#) (Physics of Risk).

[Galam (2008)]

Noisy voter model

- Discrete binary opinions
- Agents may change their opinion independently, rate σ
- Agents may change their opinion by imitating their peers, rate $\propto h$
- Interactions may occur on a complete network or other arbitrary network



Recommendations: [Redner (2019)], [Jedrzejewski and Sznajd-Weron (2019)]
Interactive voter model apps: Physics of Risk

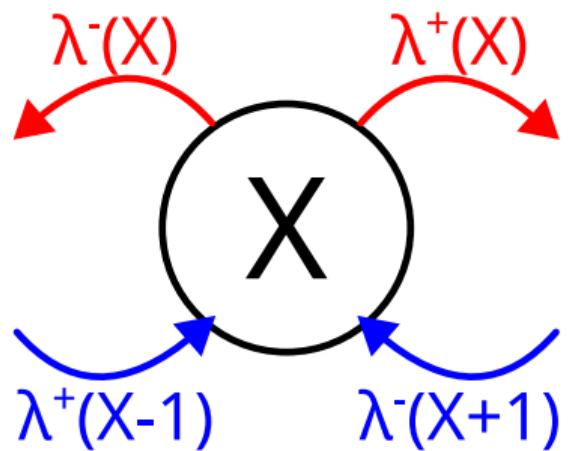
Master equation

We can formalize NVM using birth and death rates:

$$\lambda^+(X) = (N - X) [\sigma^+ + hX], \quad \lambda^-(X) = X [\sigma^- + h(N - X)].$$

Master equation:

$$\begin{aligned} \frac{\Delta p(X, t)}{\Delta t} = & -\lambda^+(X)p(X, t) - \lambda^-(X)p(X, t) + \\ & + \lambda^+(X-1)p(X-1, t) + \\ & + \lambda^-(X+1)p(X+1, t). \end{aligned}$$



[van Kampen (2007)], [Anderson (2007)]

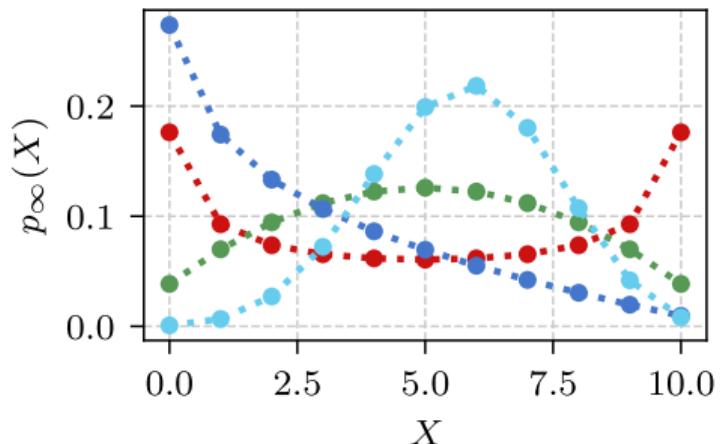
Deriving stationary distribution

Detailed balance:

$$\lambda^-(X)p_\infty(X) = \lambda^+(X-1)p_\infty(X-1).$$

Getting rid of recursion:

$$\begin{aligned} p_\infty(X) &= p_\infty(0) \cdot \frac{\prod_{i=1}^X \lambda^+(i-1)}{\prod_{k=1}^X \lambda^-(k)} = \\ &= p_\infty(0) \cdot \frac{N!}{X!(N-X)!} \cdot \\ &\quad \cdot \frac{B\left(\frac{\sigma^+}{h} + X, \frac{\sigma^-}{h} + N - X\right)}{B\left(\frac{\sigma^+}{h}, \frac{\sigma^-}{h} + N\right)} \end{aligned}$$



Continuous ($N \rightarrow \infty$) limit

Rewrite the rates:

$$\lambda_s^+(x) = N^2 \cdot (1-x) \left[\frac{\varepsilon^+}{N} + x \right], \quad \lambda_s^-(x) = N^2 \cdot x \left[\frac{\varepsilon^-}{N} + (1-x) \right].$$

Master equation:

$$\begin{aligned} \frac{\Delta p(x, t)}{\Delta t} &= -\lambda_s^+(x)p(x, t) - \lambda_s^-(x)p(x, t) \\ &\quad + \lambda_s^+(x - \Delta x)p(x - \Delta x, t) + \lambda_s^-(x + \Delta x)p(x + \Delta x, t) = \\ &= (\mathbf{E}^+ - 1) [\lambda_s^-(x)p(x, t)] + (\mathbf{E}^- - 1) [\lambda_s^+(x)p(x, t)]. \end{aligned}$$

Here: $\mathbf{E}^\pm f(x) = f(x \pm \Delta x) \approx f(x) \pm \Delta x f'(x) + \frac{(\Delta x)^2}{2} f''(x)$.

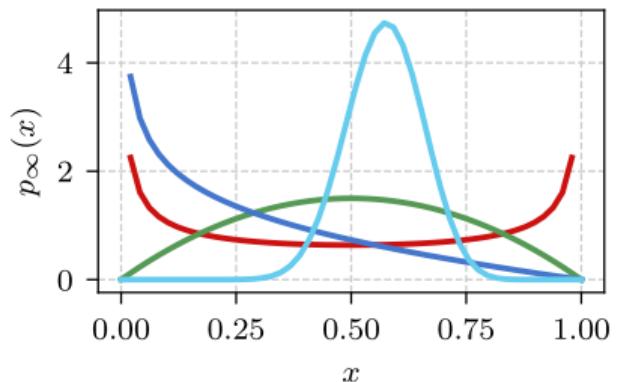
Fokker-Planck equation

$$\frac{\partial p(x, t)}{\partial t} \approx -\frac{\partial}{\partial x} \left[\frac{\lambda_s^+(x) - \lambda_s^-(x)}{N} p(x, t) \right] + \frac{1}{2} \frac{\partial^2}{\partial x^2} \left[\frac{\lambda_s^+(x) + \lambda_s^-(x)}{N^2} p(x, t) \right]$$

Stationary distribution:

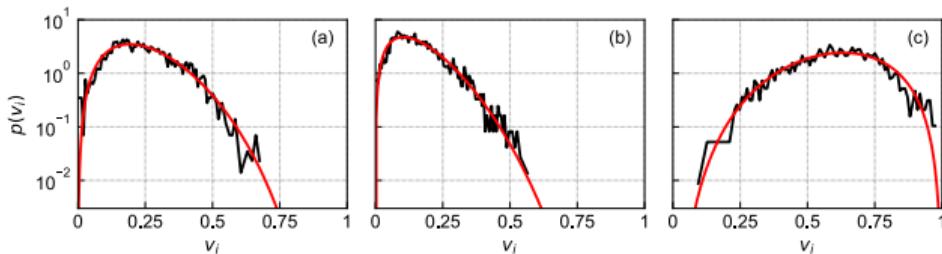
$$0 = -\{\varepsilon^+ (1-x) - \varepsilon^- x\} p_\infty(x) + \\ + \frac{d}{dx} [x(1-x) p_\infty(x)],$$

$$p_\infty(x) = C_N \cdot x^{\varepsilon^+-1} (1-x)^{\varepsilon^--1}.$$



[Risken (1996)]

Empirical fitness



Party (SK) (a), LKDP (b) and LDDP (c) vote shares
in Lithuanian 1992 parliamentary election.

PHYSICAL REVIEW LETTERS

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Featured in Physics Editors' Suggestion

Is the Voter Model a Model for Voters?

Juan Fernández-Gracia, Krzysztof Suchecki, José J. Ramasco, Maxi San Miguel, and Victor M. Eguíluz
Phys. Rev. Lett. **112**, 158701 – Published 18 April 2014; Erratum Phys. Rev. Lett. **113**, 089903 (2014)



Lithuanian 2022 municipality
election results map.

[Kononovicius (2017)], [Fernandez-Gracia *et al.*(2014)]

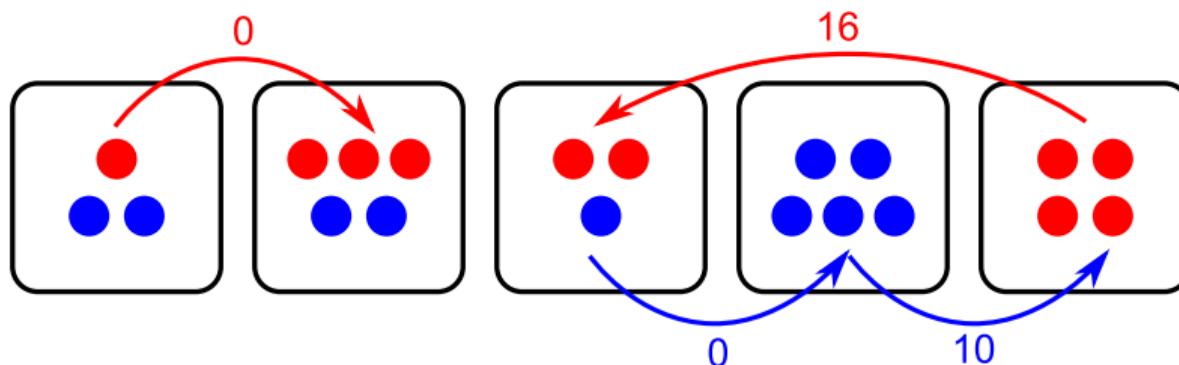
✉ rinkimai.maps.lt

It might be more about exchange...

Let the exchange rate between the spatial units be:

$$\lambda_{(k)}^{i \rightarrow j} = \begin{cases} X_i^{(k)} \left(\varepsilon^{(k)} + X_j^{(k)} \right) & \text{if } i \neq j \text{ and } \sum_k X_j^{(k)} < C, \\ 0 & \text{otherwise,} \end{cases}$$

N=20, T=2, M=5, C=5, $\varepsilon=2$



Delving deeper

- *q*-voter model
- Non-Markovian dynamics
- Dynamics on networks
- Polarization (physicsworld.com)
- Detecting election fraud
- Compatibility with social sciences



Recommendations: [[Castelano et al.\(2009\)](#)], [[Flache et al.\(2017\)](#)], [[Peralta et al.\(2023\)](#)]

Recent: [[Pal et al.\(2025\)](#)]

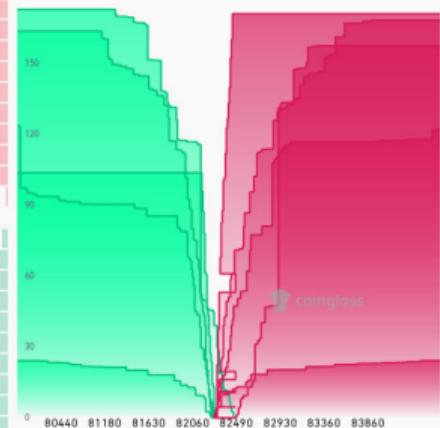
 (unknown), "spinon"

Financial markets

The big picture



Exchanges	Price(USD)	Quantity(BTC)	Total(BTC)
Binance	82370	8.6459	141
Binance	82360	28	132
Binance	82350	7.8037	104
Binance	82340	11	96
Binance	82330	23	85
Binance	82320	25	62
Binance	82310	26	37
Binance	82300	5.4237	11
Binance	82290	4.0282	5.3126
Binance	82280	1.2564	1.2844
Binance	82270	0.0281	0.0281
Uniswap	82480	0.7602	0.7602
Uniswap	82470	1.6385	2.3981
Uniswap	82460	0.3926	2.7912
Uniswap	82450	1.7589	4.5503
Uniswap	82440	2.2458	6.7951
Uniswap	82430	3.1423	9.9383
Uniswap	82420	1.5262	11
Uniswap	82410	0.0134	11
Uniswap	82400	0.1281	12
Uniswap	82390	0.4015	12



 finance.yahoo.com, coinglass.com, imgflip.com

Some statistical facts

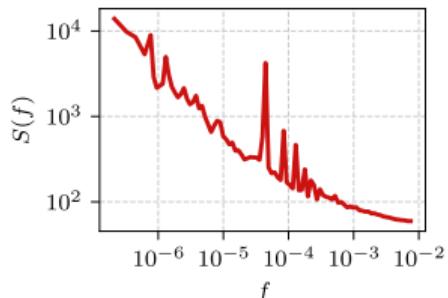
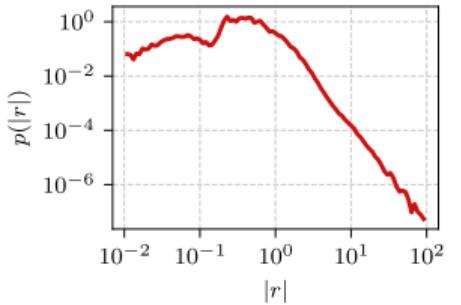
Let us introduce return:

$$r(t, \Delta t) = \ln \frac{P(t)}{P(t - \Delta t)}.$$

If we look at high frequency data ($\Delta t < 24\text{h}$). We find that:

- r has power-law tails
- r is mostly not correlated
- $|r|$ is correlated

(right) PDF and PSD of $|r|$ ($\Delta t = 60\text{ s}$; NYSE 2005–2007 data)



[Cont (2001)], [Gontis et al. (2010)]

Just some opinion dynamics?



Let there be two type of traders:

- Chartists bet on their mood:

$$D_c(t) = -r_0 X_c(t) \xi(t).$$

- Fundamentalists follow strategy:

$$D_f(t) = X_f(t) \ln \left[\frac{P_f}{P(t)} \right].$$

[Kononovicius and Gontis (2012)]; Jeff Parker (cagle.com)

Stochastic differential equations

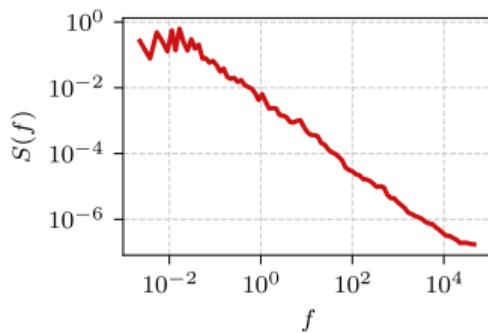
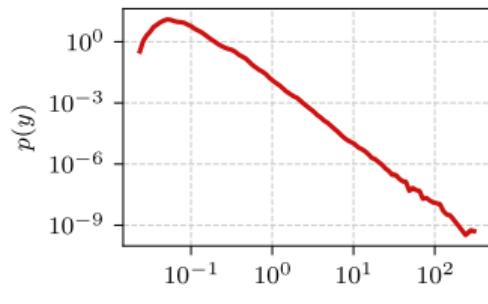
Stochastic differential equation (Ito sense) for the noisy voter model:

$$dx = [\varepsilon^+ (1 - x) - \varepsilon^- x] dt + \sqrt{2x(1-x)} dW.$$

For long-term return, $y = \frac{x}{1-x}$:

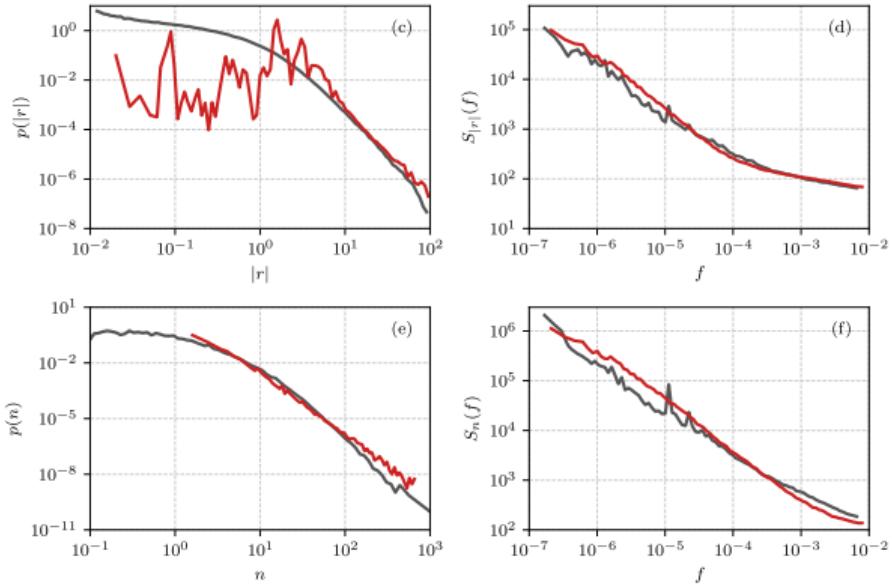
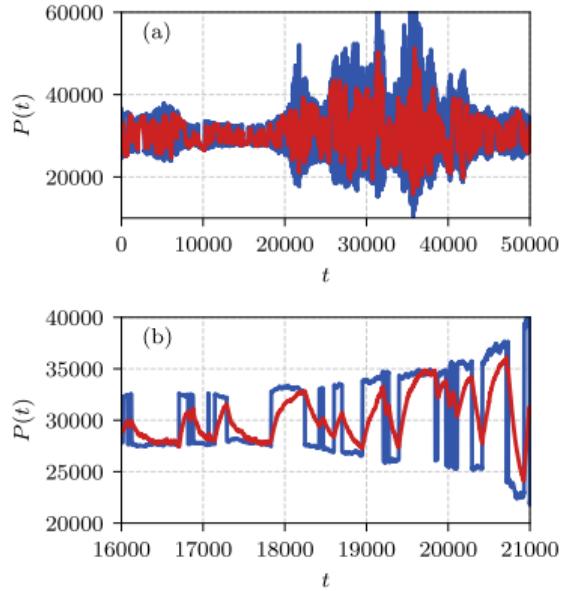
$$dy = \left[\varepsilon^+ + (2 - \varepsilon^-) \frac{y}{\tau(y)} \right] (1+y) dt + \sqrt{\frac{2y}{\tau(y)}} (1+y) dW,$$

with $\tau(y) = y^{-\alpha}$.



[Kononovicius and Gontis (2012)]; Interactive app: [Physics of Risk](#)

Order book model



Incorporation of new information through order book takes time.

Delving deeper



- Stock cross-correlation
- Multi-scaling behavior
- Bayesian inference
- Portfolio optimization
- Option pricing problem
- Risk estimation
- Bubble detection
- Market efficiency, maturity
- Deep forecasting

Recommendations: [Mantegna and Stanley (1999)], [Slanina (2014)]

Generated by Copilot; Veritasium: The Trillion Dollar Equation

Thank you!

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🔗 kononovicius.lt, rf.mokslasplius.lt



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