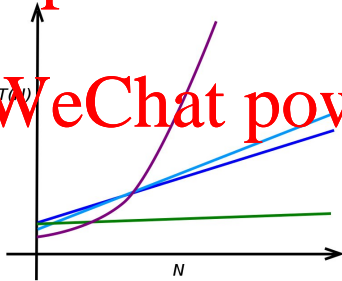


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D. Timothy Kimber

January 2018
<https://powcoder.com>

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Course Outline

The lecturer

- PhD in Computational Logic (Imperial)
- 5 years as Teaching Fellow/Senior Teaching Fellow
- Also teach Prolog to the MAC and Specialism classes

The structure

- 28 hours of interactive lectures (weeks 2–9)
- Sessions include unassessed group and individual exercises
- Two assessed exercises (one in Java) (10%)
- A 2-hour written examination *next term* (90%)

Books

- *Introduction to Algorithms*, Cormen et al., 3rd edn, 2009.
- *Algorithms*, Sedgewick & Wayne 4th edn, 2011.

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Intended Learning Outcomes

At the end of this module YOU will be better able to ...

- 1 Communicate with other engineers about how to solve a computational problem*.
- 2 Organise and manage computational resources.
- 3 Deploy known solutions to common problems.
- 4 Create original solutions to problems using sound general approaches.
- 5 Design appropriate data structures.
- 6 Explain properties of a solution, existing or original, to customers.
- 7 Analyse performance of code using established engineering techniques and terminology.

*e.g. at an interview

Course Summary

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This course: [How To Write Good Programs](#)

A [good](#) program...

- Always gives some output (terminates)
- Always gives a correct output (sound)
- Gives an output for every possible input (complete)
- Uses as few [resources](#) as possible

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Aims

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This course is concerned with the resources consumed by your programs, principally **space** and **time**.

Questions To Answer

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- How much time/space does a program use?
- What kind of program uses least time/space?

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These questions are a bit harder to answer for time, but that is what we are usually most interested in, so that is where we will start.

An Algorithm

Example (Sequence Search)

Input: a sequence $L = \langle a_1, \dots, a_N \rangle$ of N integers, and an integer k

Output: *True* if k is in L , *False* otherwise

Simplification: assume L is ordered

Procedure: SimpleSearch (Input: seq L , int k)

```
1 for each  $e$  in  $L$ 
2   if  $e == k$ 
3     return True
4 return False
```

Input Cases

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When analysing an algorithm's performance it is essential to be clear what input cases are being considered. Most often this will be one of

- Best case (least possible time/space consumed)
- Worst case (greatest possible time/space consumed)
- Average case (see later)

Later, you will see how to combine these analyses to describe performance for any input.

Formal Analysis (Worst Case)

- The input has N elements
- The cost (time taken) for line i is represented by c_i .
- We know exactly how many times each instruction happens (only worst case considered)

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Simple Search (Input: seq L and int k)

	Cost	Times
1 for each e in L	c_1	$N+1$
2 if $e == k$	c_2	N
3 return True	c_3	0
4 return False	c_4	1

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Simple Search (Worst Case)

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- So the running time, or **time complexity** for a worst case input of size N is

$$T(N) = c_1 + Nc_1 + Nc_2 + c_4$$

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$$T(N) = (c_1 + c_4) + (c_1 + c_2)N$$

- so,

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$$T(N) = aN + b$$

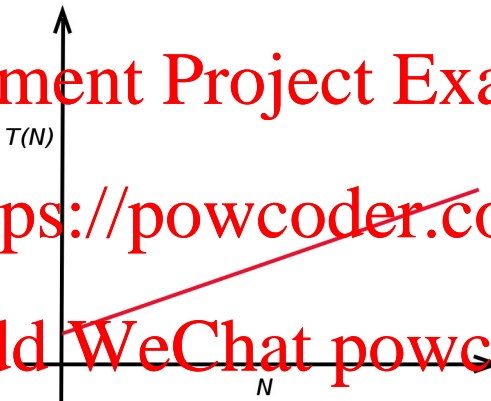
- There is a chunk of time a that is used for each element of L
- There is a chunk of time b that is used just once

Simple Search (Worst Case) Time Complexity

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- Longer sequences take more time
- The increase is linear
- a and b will differ with language, hardware, load etc.

Comparing Algorithms

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Given an input of size N , the worst-case time complexity for a range of algorithms that all solve Problem X is

- (A) $T(N) = a_1 N + a_2$
- (B) $T(N) = b_1 N$
- (C) $T(N) = c_1 N^2 + c_2 N + c_3$
- (D) $T(N) = d_1 N^3 + d_2$

where a_1, b_1, c_1 and d_1 are positive. In terms of time, which is:

- the **best** algorithm? (why?)
- the **worst** algorithm? (why?)

Highest Order Terms

For large N functions are dominated by their highest order N term

- Polylogarithmic functions include a term of the form $(\log_b N)$
- Any degree d positive polynomial grows faster than any polynomial of degree less than d , and any polylogarithm

Definition (Polynomial)

A polynomial of degree d (for $d \geq 1$) is a function $p(N)$ of the form

$$p(N) = a_0 + a_1N + a_2N^2 + \dots + a_dN^d$$

in which $a_d \neq 0$. The polynomial is asymptotically positive iff $a_d > 0$.

Exponential functions include a term of the form a^N

- If $a > 1$ then the function grows faster than any polynomial

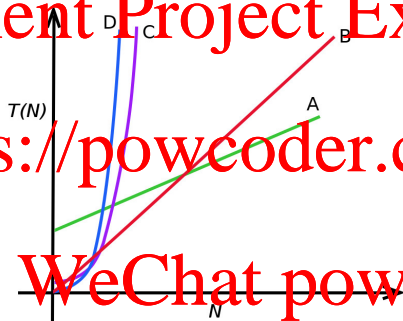
Comparing Algorithms

Depending on the constants, the time complexities might look like this ...

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- Regardless of constant factors, D will take longest for large N
- “Large N ” is usually small enough that we don’t want C or D

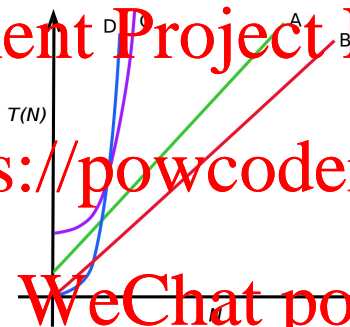
Comparing Algorithms

Or like this ...

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- A and B are, in a sense, indistinguishable (constant factors)
- The value of large N , and if it exists, for A and B needs to be considered

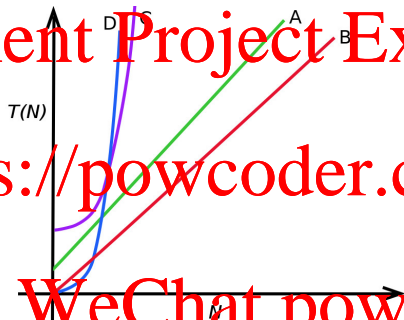
Comparing Algorithms

So, we have clear(ish) goals

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- Any " N^3 algorithm" is worse than any " N^2 algorithm"
- Any " N^2 algorithm" is worse than any " N algorithm"
- Unless we have big constants*, or small N
- *Normally, we don't